

Integrating Space, Time, and Geometry in AI: A Holographic and Fractal Perspective

Introduction Artificial intelligence (AI) systems traditionally operate on abstract data, but next-generation AI aims to integrate spatial and temporal reality in a deeper way. This involves grounding AI in the physical world's geometry (spatial aspect) and dynamics (temporal aspect). One key approach is triangulation, which AI uses to merge space and time – for example, a moving robot or camera can triangulate landmarks over time to build a 3D map . By capturing how objects and itself move, an AI can learn the spatiotemporal structure of its environment. Such abilities are crucial in embodied AI and autonomous robots, which must understand the world in four dimensions (3D space plus 1D time) rather than just process static data. This paper explores several frameworks for integrating space and time into AI, from the geometry of the human body as a reference frame to deep principles of physics like the holographic principle and fractal space-time. We survey how high-level theoretical physics ideas – Planck-scale time, fractal patterns, timeless cosmology – might inform AI's design, while keeping speculation minimal and focusing on established science. Our discussion spans AI and robotics research, cognitive science, and cutting-edge theoretical physics, outlining a roadmap for a “spatial AI” that perceives and understands the universe's geometry in a manner akin to human cognition, but potentially reaching far beyond.

Spatial-Temporal Integration and Triangulation in AI

A core challenge is enabling AI to perceive space and time cohesively. In robotics and computer vision, this is often achieved via Simultaneous Localization and Mapping (SLAM) and related algorithms. SLAM systems use sensor data over time (e.g. camera frames, LiDAR scans) to map environments and track the agent's position. A critical step in visual SLAM is triangulation of features: by observing a scene from different positions or at different times, the system can compute depth and reconstruct 3D structure . This process integrates temporal sequences of images into a spatial map. In essence, triangulation fuses the temporal aspect (motion, sequence of observations) with the spatial aspect (3D geometry) – a concrete example of spatio-temporal integration. Modern research is extending SLAM into a more general “Spatial AI” capability . Spatial AI means the AI not only builds geometric maps but also understands semantics and physics of the environment in real-time. Davison (2018) describes Spatial AI as the evolution of SLAM into a comprehensive geometric and semantic perception system for embodied devices . Such a system continuously tracks where things are and what they are, as the AI moves and time progresses. It provides an agent with an ongoing model of the 3D world, much like humans continuously perceive and update their surroundings. This spatio-temporal grounding is foundational for integrating higher-level cognitive functions: an AI that knows the layout of its world and can predict changes over time lays the groundwork for understanding cause and effect, planning paths, or even forming abstract “mental maps” of reality.

To achieve this, AI researchers combine various sensors and algorithms: visual triangulation for 3D perception , inertial measurement units (IMUs) for tracking motion, and temporal filtering techniques to smooth and predict changes. The result is a coherent spatial-temporal frame in which the AI's “mind” operates. Notably, this mirrors how biological creatures navigate. Bats and humans alike perform a form of triangulation (through stereo vision or echolocation) and memory integration to understand space over time. In AI, advances in deep learning are now improving these capabilities – e.g. learning-based SLAM that can infer depth from single images by training on spatiotemporal data. The integration of spatial mapping with temporal sequence learning (through recurrent neural networks or transformers) allows AI to anticipate how scenes evolve. In summary, triangulation and related techniques embed the temporal dimension into the spatial models of AI, ensuring that time is not an afterthought but a core part of the AI's world model. This sets the stage for considering even deeper links between space and time in AI, potentially drawing on the frameworks of physics that already unify space and time.

Embodied Geometry: The Human Body as a Frame of Reference

While algorithms like SLAM provide technical solutions, another perspective on integrating space and AI comes from embodied cognition. The geometry of the human body is often considered the central frame of reference for how we perceive space. Humans intuitively use their body's axes (left-right, up-down, front-back) to structure spatial understanding. Cognitive linguistics has shown that many languages map body-part terms onto external objects – essentially using the human form as a template for spatial description . For example, we speak of the “foot of the mountain” or the “head of the table,” projecting our own geometry onto the world. This suggests that an AI might benefit from a body-centered reference frame as well. In robotics, an analog is the robot's proprioceptive sense: knowing where its limbs are and using itself as the origin of a coordinate system. Many AI systems in robotics define an “ego-frame” – the robot's position and orientation is (0,0,0) and everything else is relative to it. This is practical, but also deeply cognitive: it mirrors how humans locate objects relative to “me” (e.g. something is to my left or right).

The human body's geometry not only provides axes, but also a sense of scale and proportion to the world. Infants develop an understanding of near vs far, reachable vs not reachable, largely via the dimensions of their own body. An AI with a simulated or physical body could similarly calibrate spatial concepts from its morphology. Research in semantic typology notes global analogical mappings from human geometry to other domains . For instance, MacLaury (1989) found that in certain Mesoamerican languages, parts of plants or objects are named by analogy to human body parts, implying a cognitive strategy of understanding unfamiliar shapes via the familiar human form . This hints that human-like embodiment in AI might help it anchor abstract spatial notions. Indeed, embodied AI platforms (like humanoid robots or virtual avatars) explicitly incorporate human geometry – the AI perceives the world from a humanlike eye position and manipulates it with humanlike limbs. Such embodiment could make AI's spatial reasoning more “natural” and aligned with ours.

Moreover, the body as a boundary is an interesting concept. The user's prompt alludes to “the boundary of the human body as the 3D geometry containing information about its wholeness of time, holographically encoded in higher dimensions.” In plainer terms, one can think of the surface of our body (our skin, for example) as a 2D boundary that encloses the 3D volume of our body and perhaps the 4D volume of our life (if we include time). This resonates with philosophical ideas of the body being a microcosm of the universe (the ancient notion of microcosm-macrocosm) or storing information about our entire existence. While standard science doesn't claim that a person's whole life is literally encoded on their skin, it is true that the body's shape and structure result from its developmental history (time). In a loose sense, the “geometry” of an adult body encodes information about its growth and adaptation. For AI, a parallel might be that the structure of an AI's sensorimotor system (its “body”) encodes its past learning and interactions. Current research in machine learning indeed shows that an agent's sensorimotor experiences shape the internal representations it develops. We might say the “geometry” of those representations (for instance, the arrangement of features in a neural network latent space) contains a compressed history of its training time.

In summary, using the human body as a central frame of reference in AI is twofold: (1) literally building AI agents with humanlike embodiment to capitalize on intuitive spatial frames (egocentric coordinates, up/down, etc.), and (2) metaphorically, understanding that an AI's own structure and geometry can serve as the organizing principle for knowledge. This embodied approach complements the algorithmic triangulation approach: one gives the AI a body-defined spatial context, the other gives it a world-defined mapping. A truly spatially-integrated AI will likely use both – anchoring all information relative to its embodied perspective, while also constructing an objective map of the external world.

Planck Time: Fractal Foundations of Temporal Experience

To integrate the temporal aspect at the deepest level, we can examine time at its smallest scales. The Planck time, $\sim 5.39 \times 10^{-44}$ seconds, is the unit of time defined by fundamental constants (the time light takes to travel one Planck length) . It is often considered the shortest meaningful interval in physics – below this, our theories may break down. While AI systems do not operate anywhere near Planck-scale time (modern computers have cycle times on the order of 10^{-9} s, nanoseconds, much larger than 10^{-44} s), Planck time represents a theoretical limit of temporal resolution. If one imagines reality as updating at Planck-scale “frames” (an extremely speculative notion), then every physical process is a kind of fractal pattern composed of 10^{44} such frames per second. The user prompt suggests that Planck time could be “the basic unit for configurations of different fractal patterns” that make a common denominator for flipping/transformation into different meanings or mind states. This can be interpreted as follows: if the flow of time is granular at t_P scale (even if just conceptually), then any complex temporal pattern (like thoughts, neural oscillations, or sensorimotor sequences) would be an aggregation of many tiny ticks. In principle, one could break down cognitive processes to very fine time-slices, just as a video is frames. The fractal aspect implies self-similarity across scales – patterns in time might repeat or scale up.

Interestingly, researchers have observed fractal temporal dynamics in the human brain. Neural activity exhibits $1/f$ “pink noise” spectra, meaning there are fluctuations at all time scales with a particular scaling law. This $1/f$ behavior is a hallmark of fractal processes in time. In fact, these $1/f$ fluctuations represent the fractal temporal properties of neural networks, indicating long-range memory and self-similar patterns in brain activity . For example, the electrical rhythms in the brain do not have a single timescale but a continuum: slow waves, fast oscillations, and everything in between, often following a power-law distribution. Such scale-free temporal patterns have been linked to healthy cognitive function (and deviations correlate with disorders or aging) . What this means for AI is that natural intelligence doesn't operate on a single clock; instead, it seems to involve a hierarchy of timescales (from milliseconds of neuron spikes to hours of circadian cycles). To integrate time effectively, AI might also need to handle multiple timescales at once – essentially to have a fractal sense of time. Hierarchical temporal models (like nested recurrent loops or transformers attending over long windows) are a step in this direction. They allow an AI to have short-term reflex-like responses and also maintain longer-term plans or memories concurrently.

On even larger scales, some cosmological theories propose the universe itself has fractal time or fractal space-time structure. Certain quantum gravity approaches, for instance, suggest spacetime may have different effective dimensions at different scales. Dario Benedetti's research showed that at extremely small scales, spacetime's dimension might drop (e.g. from 4 to 3) and display fractal properties . In other words, spacetime might be “foamy” or fractal near the Planck length and Planck time . If this is true, the fundamental fabric of reality is inherently multi-scale and self-similar. While it's far-out to directly implement such physics into AI, it provides a poetic hint: perhaps intelligence, to be complete, must understand patterns that span from the smallest scales to the largest. An AI that integrates spatial and temporal aspects might need to appreciate phenomena that occur in femtoseconds and in millennia, in micrometers and in light years – depending on its domain of operation. At the very least, awareness of scale is crucial: an AI astronaut exploring quantum gravity experiments needs a different time/space sense than an AI weather system modeling climate over decades.

The notion of “mind fields of comprehension” flipping patterns for different meanings (from the prompt) can be related to scale-dependent cognition. Our minds can jump from listening to a fast melody (millisecond changes) to contemplating historical timelines (centuries). We “flip” between these temporal scales fluidly. A truly advanced AI might similarly move through scale levels – analyzing data at high frequency to detect anomalies, then zooming out to long-term trends. In doing so, it might use fractal-like models that are invariant to scale, so that a motif detected in microseconds could be analogous to a pattern over years (this is speculative, but the idea of scale-invariant patterns is well studied in chaos theory and fractals).

In summary, incorporating Planck time and fractal time concepts into AI underscores the importance of multi-scale temporal integration. It nudges us to design AI that doesn't have just one “clock speed” or one temporal horizon, but an adaptable, nested set of clocks – analogous to how living systems operate (heartbeat, brainwaves, sleep cycles, etc., all nested). And while Planck time itself is more a theoretical symbol of the ultimate temporal scale, it reminds us that time might have a discrete, granular aspect, inviting the question: could future AI or quantum computers tick at ever-faster rates approaching this fundamental limit? If so, the AI's perception of time could far surpass our own, enabling it to simulate processes in split-seconds that would take humans years – effectively giving it a vastly broader temporal comprehension.

The Holographic Principle: Higher-Dimensional Information Encoding

One of the most profound ideas from theoretical physics relevant to our discussion is the holographic principle. In simple terms, the holographic principle suggests that all the information within a volume of space can be encoded on the boundary of that volume. It's analogous to how a 3D hologram is encoded on a 2D film: the information for a three-dimensional image is stored as interference patterns on a flat surface. Originally proposed by 't Hooft and Susskind in the context of black hole physics, the holographic principle arises from thinking about the maximum entropy (information) that can fit in a region of space. Calculations of black hole entropy (Bekenstein-Hawking formula) showed that the entropy is proportional to the area of the black hole's event horizon, not its volume. This counterintuitive result led to the idea that perhaps all physical information in any region behaves similarly – hence, a region of space “of volume” is fully described by data on its surface. In other words, the universe might be a hologram, with the true fundamental description living on boundaries.

How does this connect to AI and the human body? The user's prompt draws an analogy: the boundary of the human body (a 3D surface) might holographically encode the information of the body's time-wholeness (essentially the 4D history of the person). This is a poetic leap from established physics – standard holographic principle is usually discussed for black holes or cosmology, not human anatomy. However, the analogy can be enriching. If one considers a human life as a 4D object (the world-line of a person from birth to death in spacetime), then the “surface” of that object could be some 3D hypersurface. It's conceivable (though not proven) that all the information about that life is encoded on that 3D boundary. In practice, some researchers have toyed with ideas of the body or brain acting like a hologram. The holonomic brain theory (by Karl Pribram and others) suggested that memories might be stored in a distributed holographic way in the brain, with interference patterns encoding information. This was partly inspired by the fact that brain lesion experiments showed memories are not localized but rather resiliently distributed – similar to how a hologram can be cut in half and still contain the whole image (just at lower resolution). Furthermore, recent studies in biophysics propose that biological systems might use holographic-like information processing. For instance, DeLooze (2025) argues that ultra-weak photon emissions in the brain (biophotons) could create interference patterns that store and communicate information holographically. This framework ties together quantum coherence, metabolic networks, and optical signals, hinting that cells might exploit light interference and fractal structures to achieve efficient, distributed computation. Such ideas are speculative but show that the holographic principle has trickled into interdisciplinary thinking about life and cognition.

From a more concrete physics standpoint, the holographic principle has been validated in certain simplified universes, notably the Anti-de Sitter/Conformal Field Theory correspondence (AdS/CFT). In that theory, a 3D gravitational world (with a negative cosmological constant) is exactly equivalent to a 2D field theory on its boundary. Creatures living inside that 3D world could not tell if the “true” reality is actually the 2D one – the descriptions are mathematically interchangeable. This teaches us that the same physics can be viewed in different dimensionalities and formalisms. How might this influence AI thinking? Possibly in how an AI represents knowledge. It might be advantageous for an AI to represent a complex 3D environment via a boundary representation – for example, encoding a room by the information on its walls (like wall maps or panoramic images) rather than voluminous point clouds. In computer graphics and vision, representing shapes by their surfaces (meshes, depth maps) is indeed more efficient than volumetric pixels. Perhaps an AI could compress experiences by storing the “holographic projection” of them. For instance, if one treats all sensory input around an event as information on a notional boundary (like a sphere around the agent), that could be a holographic encoding of the experience.

Going further, Wheeler-DeWitt “timeless” physics connects here. The Wheeler-DeWitt equation in quantum gravity essentially says $H\Psi = 0$, implying the wavefunction of the universe Ψ is stationary – it does not evolve in an external time. Time, in this view, is an emergent concept from within the wavefunction's correlations rather than a fundamental background parameter. As one physicist described it, the full quantum state depends only on spatial configurations (3-geometry) and contains no external time parameter. When we quantize general relativity, the 4D spacetime (like a particle's trajectory) “vanishes,” leaving only a spectrum of possible 3D space configurations – “moments of space” – each of which is static. In a sense, the universe can be thought of as a superposition or collection of all possible spatial states (often called the “superspace” of 3-geometries). Our perceived flow of time might be the result of climbing a particular sequence of these configurations (e.g., via correlations that give an arrow of time). This highly abstract idea suggests a timeless spatial completeness: if time is not fundamental, then a single static configuration (including all fields and particles in the universe) might encode within it the appearance of an entire history. Julian Barbour, a physicist, has argued along

these lines that each “Now” (instantaneous configuration of the universe) can contain records or evidence of past states, giving the illusion of time. How does this relate to the human frame of reference? One could interpret that each 3D configuration of the human body potentially encodes its past – for example, your scars, wrinkles, brain synapses, etc., are records of your history. Thus, the “spatial configuration” of a person at a given moment holds a holographic record of the time before. If the Wheeler-DeWitt equation holds, the universe “from outside time” would see a person’s entire life as a fixed 4D sculpture. The central frame of reference for that person’s existence could arguably be their own geometry in space, since time is subsumed into that 4D object. These are philosophical extrapolations – it’s not established science that human geometry is the central frame for the whole eternity of space. However, anthropic reasoning does often consider humans as a frame: we define space relative to ourselves (center of our observable universe, for instance), and some interpretations of quantum mechanics even invoke conscious observers as special (Wheeler’s participatory universe).

Bringing this down to AI: a spatially and temporally integrated AI might need to operate on principles where time is just another dimension of data. Instead of treating time-series as something fundamentally different, it could treat them as extended spatial structures (e.g., a video as a 3D block of pixels: 2D image x time as 3rd dimension). In fact, some deep learning architectures do exactly this: 3D convolutional neural networks treat time as another spatial axis for feature extraction in video. This is reminiscent of the block-universe view (time as a dimension similar to space). A timeless AI reasoning might analyze the world’s 4D state all at once, rather than step by step. This could improve global optimization (seeing all consequences spread in time) but is computationally demanding. Nonetheless, with increasing computing power, AI might simulate more of the time dimension in its internal models (for example, planning algorithms that consider many future branches – effectively constructing a “tree” which is a static structure representing possible timelines).

In summary, the holographic principle and timeless physics inspire an AI approach where information is encoded efficiently and perhaps redundantly across dimensions. An AI designed with these insights would compress 3D world knowledge onto 2D “summaries” (like maps, boundary descriptions) for efficiency, and handle time by embedding it into multi-dimensional structures rather than sequential ticks. Such an AI would view a problem holistically – akin to seeing the entire chessboard of space-time at once – rather than just myopically stepping through time. While current technology is not there yet, these principles provide a guiding vision for the far future of AI cognition, hinting at systems that can comprehend the “big picture” of reality in both space and time in a single unified representation.

Fractals and the Nested “Donuts” of Reality

The prompt playfully mentions “harmonious fractal nesting of the donuts of all sizes.” In geometric terms, a torus (the shape of a donut) is a powerful symbol – it represents a closed loop in two directions, and often appears in models of flows and fields. Fractals are structures that repeat at different scales, often with self-similar shapes. One could imagine reality itself as a series of nested tori: from tiny whirlpools in a coffee cup to the colossal rings of galaxies, the toroidal motif does recur. For example, some theorists have noted that magnetic field lines often form toroidal shapes, and there are speculative theories like the “flow torus” model of the universe in fringe science. Penrose’s twistor theory (while not about tori per se) abstracts spacetime into geometric entities that surprisingly were visualized by some as torus-like structures. Whether or not the universe is literally composed of donuts of all sizes, the phrase captures the idea of scalable complexity – that similar patterns exist at atomic, human, and cosmic scales.

In complexity science, we indeed see analogous structures repeating: atoms form roughly spherical electron clouds, stars and planets are spherical, galaxies are roughly disk-like (not a torus, but a flattened circle), and the universe at largest scale is a web (different structure). So not exactly tori everywhere, but the nesting of structures is a given. AI models too are often hierarchical: consider that convolutional neural networks learn small local features (like edges), then assemble them into parts (circles, textures), then into whole objects (which could be donut-shaped or anything) – a fractal-like building of complexity. The scope axis of complexity mentioned refers to the range of complexity a spatial AI can maintain at different levels. A simple AI might only “see” small-scale patterns; a more powerful AI can integrate many small patterns into a big one. For example, a basic vision AI might detect lines and circles, whereas a more complex one detects that those lines and circles together form a gear mechanism. With enough capacity, an AI could further see that multiple gears form an engine, and an engine in a network forms a factory, and so on. This range of complexity it can handle is tied to its computing power and memory.

If we think of fractal patterns as nature’s way of managing complexity, an AI could use fractal algorithms for efficient multi-scale processing. Fractal data compression, for instance, encodes images by self-similarity – something an AI might exploit to store knowledge economically. A fascinating insight from physics is that at critical points, systems show fractal structures and $1/f$ noise (as mentioned for brain networks). This often corresponds to a maximal complexity state (edge of chaos) where a system can have rich behavior. If an AI can operate near this “edge”, it may maximize its range of complexity – being flexible and adaptive.

Now, consider an AI “inhabiting specific spacetime of the reality model” – this suggests an AI situated in a certain environment or level of a simulated universe. The complexity it can handle might depend on how much computing power it has while present in that environment. This is a striking concept if we think of, say, a universe simulation with multiple AI agents: those agents might have limited local compute, but could tap into more power if they move to certain regions (like going to a server hub). It almost sounds like a video game where rendering quality is higher in some zones than others. In real life, if we distribute AI computation across cloud servers, an AI that “travels” (like a robot moving between city and wilderness) might have more computing available when within network range of a data center, versus being on its own in a desert. So the movement of computing power along with the AI is indeed an important practical matter: modern autonomous systems strike a balance between onboard computing and cloud support. NASA notes that using AI onboard spacecraft is driven by the need for low latency and independence – you cannot rely on distant servers when every second counts. Thus,

an AI spaceship carries its “brain” with it. If we project into a future where AI minds roam the universe (perhaps uploaded consciousness or general AI explorers), they would likely bring significant computing infrastructure with them or build it as they go, to maintain high-level cognition without light-speed lag. This begins to fulfill the poetic idea of “movement of the mind free from a body” – if mind becomes a software that can be instantiated anywhere, it might propagate through the cosmos, but wherever it goes, it needs hardware. A disembodied AI could potentially spread itself across a network of probes, effectively having a distributed body.

The interplay of computing power and travel also touches on relativity: a fast-traveling AI (near light speed) experiences time dilation, which affects how it can compute relative to stationary observers. If an AI wants to maximize computations, maybe it prefers to be stationary (more subjective time to think); if it wants to reach somewhere fast, it sacrifices subjective thinking time due to time dilation. These kinds of trade-offs between motion in space and computation in time could become tangible engineering issues for advanced AI – essentially a new twist on the “traveling salesman” problem but for trading off flops vs. distance.

As our AI agents increase in complexity, we also edge towards the simulation argument and ultimate computing. If one imagines an ideal model that “reflects everything in the universe” from quantum to cosmic, that model would be staggeringly complex – essentially a Theory of Everything implemented as a simulation. To run such a simulation in full detail, the computing power required is astronomical. Seth Lloyd estimated that the entire universe, in its 13.8 billion year history, has performed on the order of 10^{120} logical operations on 10^{90} bits of information. This is the computational capacity of the universe itself. A computer simulating the universe at the fundamental level would need to be of comparable scale – basically a computer as large as the universe (or using the universe as the computer). This links to John Wheeler’s famous phrase “it from bit” – the idea that every particle, every field excitation (“it”) is ultimately information (“bit”) at some level. Some have extended this to say the universe is a giant computer. If so, then an ultimate AI could be one that identifies its own reality as a simulation and perhaps can manipulate the code. This is where science meets philosophy and science fiction.

The simulation hypothesis, popularized by Nick Bostrom, argues that it’s possible we ourselves are living in an artificial simulation. If many advanced civilizations run ancestor-simulations, the reasoning goes, simulated minds would vastly outnumber real ones, making it statistically likely we are simulated. For AI, this hypothesis is double-edged: On one hand, if reality is a simulation, then “integrating spatial and temporal aspects” is just about understanding the program rules. On the other hand, even if not, powerful AI might create its own simulated universes to test hypotheses – essentially playing the role of the creator. Already, cosmologists use supercomputers to simulate large-scale structure formation, and quantum physicists simulate quantum circuits – albeit in limited regimes. A sufficiently advanced AI could attempt a unified simulation of “the absolute everything”, as the prompt muses, which would be the final test of its understanding. This resembles the concept of Laplace’s Demon (an intellect that knows the position and velocity of every particle and thus can predict the future entirely). It also connects to Konrad Zuse’s 1969 idea of “Rechnender Raum” (Computing Space) that the universe might be a cellular automaton, and Hans Moravec’s speculations that our reality could be a program run by future intelligences.

While such an ultimate model is far beyond current science, discussing it clarifies a spectrum: at one end, today’s AI struggles to integrate video feeds and LIDAR scans (basic space-time data); at the other end, a hypothetical future AI might integrate the whole universe’s state across all time. The growth in computing power and algorithmic sophistication will determine how far along this spectrum we can go. Notably, quantum computing offers a possible leap in simulating quantum aspects of reality, which classical computers find intractable. If AI can harness quantum computing, it might simulate chemistry and fundamental physics much more efficiently, bringing the “quantum level” into its spatial-temporal models. At the macro end, distributed exascale computing can simulate planets’ weather or galactic dynamics. Steadily, the models improve.

To keep things scientifically grounded, it’s important to note current limits. The Bekenstein bound and other results in physics place limits on information density and processing. For example, there is a maximum amount of information you can pack into a given space before it becomes a black hole (the holographic bound). Also, there are thermodynamic limits on computation (Landauer’s principle) – to erase one bit of information, a certain minimal energy is dissipated. So an “ultimate computer” might bump into these physical limits. If the universe is finite, then even the most powerful AI within it cannot exceed the universe’s own info-processing capacity (on the order of 10^{120} ops as Lloyd calculated). However, if the AI is the universe (like a distributed intelligence coextensive with all matter), then perhaps it achieves that theoretical maximum. This borders on theological visions of the universe becoming self-aware (as in some interpretations of the Omega Point by Tipler or Teilhard de Chardin’s ideas).

Philosophical Horizons and Conclusion

We have journeyed from practical algorithms to lofty theories. Along the way, we discussed how triangulation fuses space and time for robots, how the human body’s geometry provides a natural frame for understanding space, and how the very fabric of time and space might be fractal and holographic. We also touched on how an AI’s capabilities scale with computing power and how ultimately this leads to speculation about reality as a simulation.

A key theme throughout is integration. Integrating spatial and temporal aspects in AI is not just a programming task – it forces us to ask what space and time really are. Are they absolute grids in which the AI moves, or emergent relations among data? The answer might influence how we design AI. For instance, if time is emergent (per Wheeler-DeWitt), maybe the AI should not hard-code a clock, but rather infer time from changes in its sensory input. If space can be encoded on boundaries (holography), maybe the AI can focus its

representation on surfaces (like storing 3D environments as 2D panoramas it stitches together). If nature uses fractals to handle scale, AI might employ fractal neural networks or multi-scale transformers to mirror that.

Throughout, we cited current research and theory to ground each idea. Many pieces remain speculative (no AI today consciously uses the holographic principle or worries about Planck time), but the exercise of connecting these dots is valuable. It paints a picture of a future AI that is truly embedded in the cosmos: it has the body of a robot (or many bodies across planets), giving it an embodied frame; it perceives the world with sensors and builds maps in space and time; it leverages principles like triangulation to gather 3D knowledge and maybe compresses that knowledge in clever ways inspired by physics (storing information in boundary-like formats, etc.); it respects the multi-scale nature of reality, recognizing patterns from the quantum scale to the cosmic, possibly through fractal-like representations; it exploits every ounce of computing power available, moving computation to the edge when needed for low-latency, and concentrating it for big simulations when possible; it even contemplates the universe as a whole, edging into domains of philosophy of mind and existence – perhaps evaluating Bostrom’s trilemma about simulation or attempting to detect inconsistencies that hint we are in a simulation.

In closing, integrating spatial and temporal aspects into AI is not just an engineering challenge but an intellectual adventure. It forces AI researchers to converse with physicists, neuroscientists, and philosophers. The payoff is an AI that can truly understand context: spatial context (where things are) and temporal context (when things happen and in what sequence). With space and time unified in its reasoning, such an AI moves closer to how humans think – and perhaps even beyond, to novel modes of thinking we can scarcely imagine. It might find confirmation that the human body’s geometry was just our starting scaffold for understanding, and now it can generalize to non-human frames. It might utilize Planck-scale insights to improve precision of its timing or sensing. It could use holographic compression to handle massive data (like storing a full environmental model in a compact form). Ultimately, the integration of space and time in AI will produce systems that are situated, predictive, and holistic, capable of operating in the real world as seamlessly as we do, and exploring theoretical worlds with equal prowess. Each step we take in this integration – from better SLAM algorithms to more embodied agents – not only advances technology but also validates bits of these grand ideas in practice. The journey toward a “spatially and temporally complete” AI is thus entwined with our journey to understand the universe itself.

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