

# 计算方法Final-Project

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## 1.

$$\text{记 } F = \min_{\{u_1, \dots, u_{n-1}\}} \sum_{i=1}^n \frac{1}{2} \left( \frac{u_i - u_{i-1}}{h} \right)^2 h + \sum_{i=1}^{n-1} \left( \frac{\alpha}{4} u_i^4 - f_i u_i \right) h, \quad \alpha=0 \text{ 时,}$$
$$\frac{\partial F}{\partial \mu_i} = \left( \frac{u_i - u_{i-1}}{h} \right) - \left( \frac{u_{i+1} - u_i}{h} \right) - f_i h = 0,$$

即  $2u_i - u_{i-1} - u_{i+1} - f_i h^2 = 0, \quad 1 \leq i \leq n-1, \quad u_0 = u_n = 0$ , 线性方程组  $A_h u_h = f_h$  为

$$\begin{pmatrix} \frac{2}{h^2} & -\frac{1}{h^2} & & & \\ -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} & & \\ & -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} & \\ & & \dots & \dots & \\ & & & -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} \\ & & & & -\frac{1}{h^2} & \frac{2}{h^2} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \dots \\ u_{n-1} \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ \dots \\ f_{n-1} \end{pmatrix}$$

## 2.

**Jacobi迭代法:**  $u_0$ 和 $u_1$ 两个数组循环迭代, 即当次迭代利用 $u_0[j+1]$ 和 $u_0[j-1]$ 计算 $u_1[j]$ , 下次迭代利用 $u_1[j+1]$ 和 $u_1[j-1]$ 计算 $u_0[j]$ 。

```
u1[1] = (u0[2] + f(h) * h * h) / 2.0;
for(auto j = 2; j < n - 1; j++){
    u1[j] = (u0[j+1] + u0[j-1] + f((j) * h) * h * h) / 2.0;
}
u1[n-1] = (u0[n-2] + f((n-1)*h) * h * h) / 2.0;

long double max = 0.0;
for(auto j = 1; j < n; j++){
    //cout << u1[j] << " ";
    auto distance = fabs(u1[j] - u0[j]);
    if(distance > max)
        max = distance;
}
//cout << endl;
if(max < eps){
    long double eh = 0.0;
    for(auto j = 1; j < n; j++){
        eh += (u1[j] - check(j * h)) * (u1[j] - check(j * h));
    }
    eh = sqrt(eh);
    cout << "count = " << cnt << endl;
    cout << "eh = " << eh << endl;
    break;
}
```

```
}
```

**Gauss-Seidel迭代法：** $u_0$ 和 $u_1$ 两个数组循环迭代，即当次迭代利用 $u_0[j+1]$ 和 $u_1[j-1]$ 计算 $u_1[j]$ ，下次迭代利用 $u_1[j+1]$ 和 $u_0[j-1]$ 计算 $u_0[j]$ 。

```
u1[1] = (u0[2] + f(h) * h * h) / 2.0;
for(auto j = 2; j < n - 1; j++){
    u1[j] = (u0[j+1] + u1[j-1] + f((j) * h) * h * h) / 2.0;
}
u1[n-1] = (u1[n-2] + f((n-1)*h) * h * h) / 2.0;

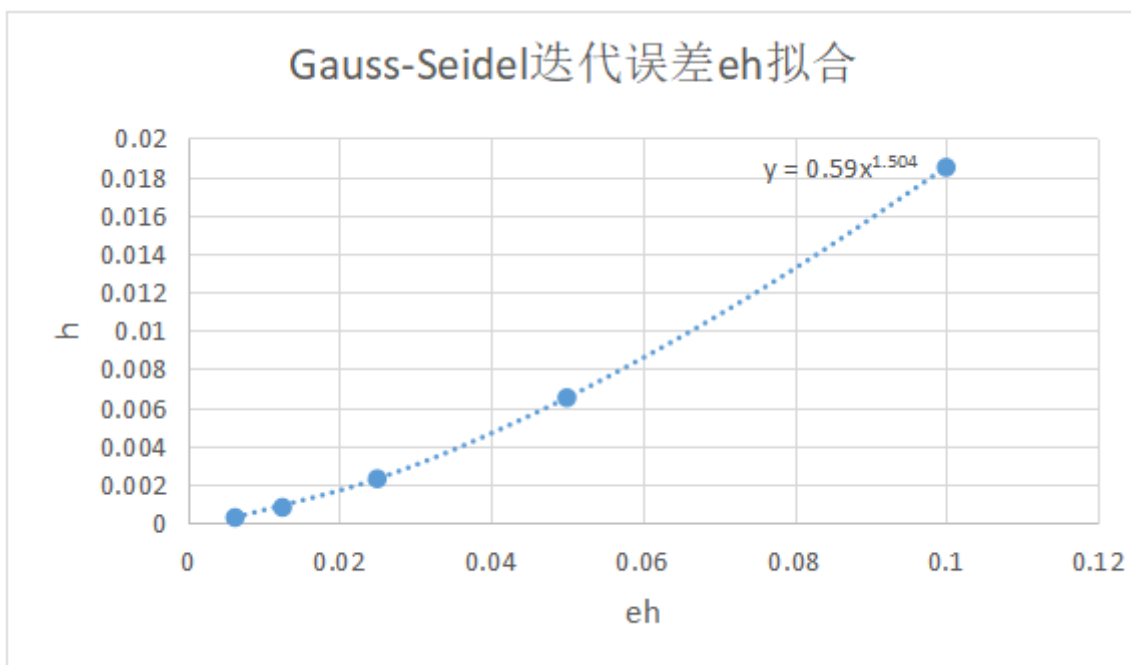
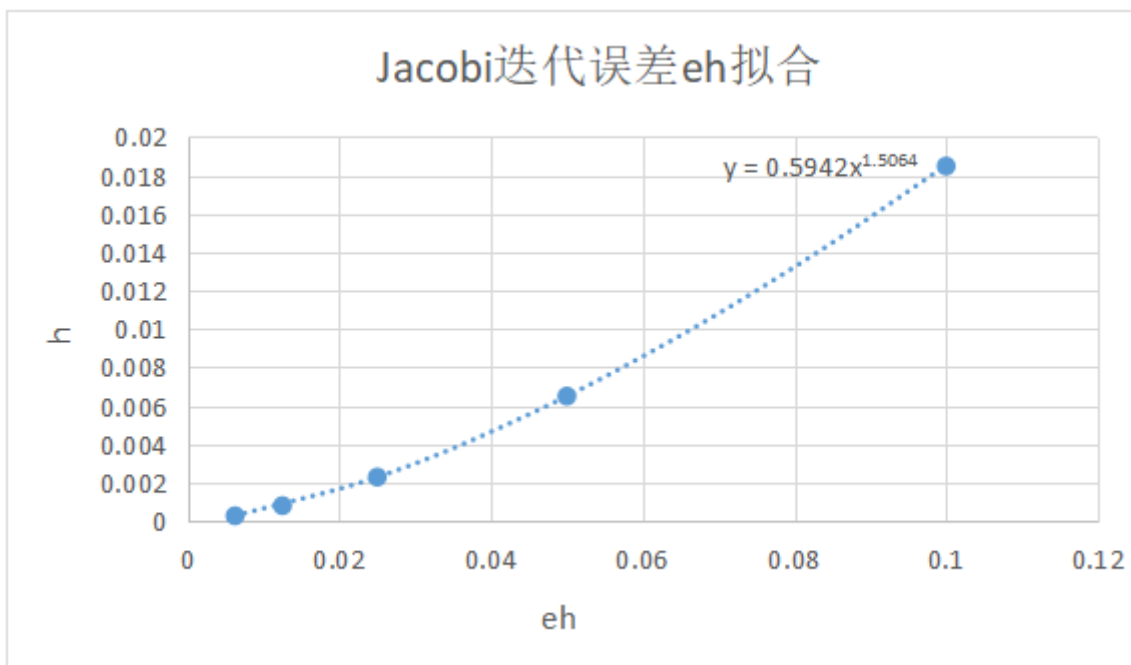
long double max = 0.0;
for(auto j = 1; j < n; j++){
    //cout << u1[j] << " ";
    auto distance = fabs(u1[j] - u0[j]);
    if(distance > max)
        max = distance;
}
//cout << endl;
if(max < eps){
    long double eh = 0.0;
    for(auto j = 1; j < n; j++)
        eh += (u1[j] - check(j * h)) * (u1[j] - check(j * h));
    eh = sqrt(eh);
    cout << "count = " << cnt << endl;
    cout << "eh = " << eh << endl;
    break;
}
```

Jacobi迭代法和Gauss-Seidel迭代法 $u_h$ 与精确解 $u_e(x) = \sin(\pi x)$ 之间的误差 $e_h = \|u_h - u_e\|_2$ ：

n	Jacobi迭代误差 $e_h$	Gauss-Seidel迭代误差 $e_h$
10	0.018482	0.018482
20	0.00651018	0.00651019
40	0.00229943	0.0022995
80	0.000812015	0.000812425
160	0.000282725	0.000285045

### 3.

利用Excel对 $e_h \sim h$ 进行最小二乘幂函数拟合，得到Jacobi迭代误差 $e_h = \Theta(\beta^{1.5064})$ ，Gauss-Seidel迭代误差 $e_h = \Theta(\beta^{1.504})$



## 4.

Jacobi迭代法和Gauss-Seidel迭代法收敛所需要的迭代次数:

n	Jacobi迭代次数	Gauss-Seidel迭代次数
10	400	208
20	1505	781
40	5587	2906
80	20563	10732
160	75071	39334

结论：从表中可以看出Jacobi迭代次数是Gauss-Seidel迭代次数1.9倍左右，此问题中Gauss-Seidel迭代法收敛速度明显快于Jacobi迭代法。

## 5.

$\alpha=1$ 时,  $\frac{\partial F}{\partial \mu_i} = \left( \frac{u_i - u_{i-1}}{h} \right) - \left( \frac{u_{i+1} - u_i}{h} \right) + (u_i^3 - f_i)h = 0$ , 非线性方程组为

$$2u_i - u_{i-1} - u_{i+1} + (u_i^3 - f_i)h^2 = 0, \quad 1 \leq i \leq n-1, \quad u_0 = u_n = 0$$

## 6.

**Newton迭代法：**每个方程对每个 $u_i, 1 \leq i \leq n-1$ 求偏导记录在系数矩阵 $A$ 中，求出 $\text{delta\_u} = A^{-1}(-f)$ ，当次迭代结果 $u += \text{delta\_u}$

```
A = np.zeros((n - 1, n - 1), dtype=np.double)
for i in range(1, n - 2):
    A[i][i - 1] += -1
    A[i][i] += (2 + 3 * h * h * u[i])
    A[i][i + 1] += -1
A[0][0] += (2 + 3 * h * h * u[0])
A[0][1] += -1
A[n - 2][n - 2] += (2 + 3 * h * h * u[n - 2])
A[n - 2][n - 3] += -1
A_inverse = np.linalg.inv(A)

f = np.zeros(n - 1, dtype=np.double)
for i in range(1, n - 2):
    f[i] = 2 * u[i] - u[i - 1] - u[i + 1] + (u[i] ** 3 - func((i + 1) * h)) * h
    * h
f[0] = 2 * u[0] - u[1] + (u[0] ** 3 - func(h)) * h * h
f[n - 2] = 2 * u[n - 2] - u[n - 3] + (u[n - 2] ** 3 - func((n - 1) * h)) * h * h

delta_u = np.dot(A_inverse, -f)
# print(delta_u, '\n')
u += delta_u
```

Newton迭代法 $u_h$ 与精确解 $u_e(x) = \sin(\pi x)$ 之间的误差 $e_h = \|u_h - u_e\|_2$ ：

n	Newton迭代误差 $e_h$
10	0.015018033484455717
20	0.005300890512751275
40	0.001873370142282602
80	0.0006622691265689797
160	0.00023414373803619495

利用Excel对 $e_h \sim h$ 进行最小二乘幂函数拟合，得到Newton迭代收敛阶为1.5007

