计算方法实验三

PB19030888张舒恒

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问题—

1. (Page186, Project10) 用 Newton 迭代法求解非线性方程组

$$\begin{cases} f(x) = x^2 + y^2 - 1 = 0 \\ g(x) = x^3 - y = 0 \end{cases}$$
 (1)

取
$$\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = \begin{pmatrix} 0.8 \\ 0.6 \end{pmatrix}$$
, 误差控制 $\max(|\Delta x_k|, |\Delta y_k|) \le 10^{-5}$. 输入: 初始点 $(x_0, y_0) = (0.8, 0.6)$, 精度控制 e , 定义函数 $f(x), g(x)$. 输出: 迭代次数 k , 第 k 步的迭代解 (x_k, y_k) .

算法过程

$$\begin{cases}
\Delta x \frac{\partial f_1(x_0, y_0)}{\partial x} + \Delta y \frac{\partial f_1(x_0, y_0)}{\partial y} = -f_1(x_0, y_0) \\
\Delta x \frac{\partial f_2(x_0, y_0)}{\partial x} + \Delta y \frac{\partial f_2(x_0, y_0)}{\partial y} = -f_2(x_0, y_0)
\end{cases} (3.7)$$

如果

$$\det(J(x_0,y_0)) = \left| egin{array}{ccc} rac{\partial f_1}{\partial x} & rac{\partial f_1}{\partial y} \\ rac{\partial f_2}{\partial x} & rac{\partial f_1}{\partial y} \\ \end{array}
ight|_{(T_0,y_0)}
eq 0$$

解出 $\Delta x, \Delta y$

$$w_1 = w_0 + \left(egin{array}{c} \Delta x \ \Delta y \end{array}
ight) = \left(egin{array}{c} x_0 + \Delta x \ y_0 + \Delta y \end{array}
ight) = \left(egin{array}{c} x_1 \ y_1 \end{array}
ight)$$

再列出方程组

$$\left\{\begin{array}{l} \displaystyle \frac{\partial f(x_1,y_1)}{\partial x}(x-x_1) + \frac{\partial f(x_1,y_1)}{\partial y}(y-y_1) = -f(x_1,y_1) \\[0.2cm] \displaystyle \frac{\partial g(x_1,y_1)}{\partial x}(x-x_1) + \frac{\partial g(x_1,y_1)}{\partial y}(y-y_1) = -g(x_1,y_1) \end{array}\right.$$

解出

$$\Delta x = x - x_1, \quad \Delta y = y - y_1$$
 $w_2 = \begin{pmatrix} x_1 + \Delta x \\ y_1 + \Delta x \end{pmatrix} = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$

继续做下去,每一次迭代都是解一个类似式 (3.7) 的方程组

$$J(x_k, y_k) \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} = \begin{pmatrix} -f(x_k, y_k) \\ -g(x_k, y_k) \end{pmatrix}$$

 $\Delta x = x_{k+1} - x_k, \quad \Delta y = y_{k+1} - y_k$

$$x_{k+1} = x_k + \Delta x, \quad y_{k+1} = y_k + \Delta y$$

直到 $\max(|\Delta x|, |\Delta y|) < \varepsilon$ 为止.

代码实现

计算delta_x, delta_y, 将其加入x[i+1], y[i+1], 输出当次迭代结果, 若max(fabs(delta_x), fabs(delta_y)小于给定误差界限,则停止迭代,否则继续迭代。

```
while(true){
    delta_x = (-f(x[i], y[i]) - g(x[i], y[i]) * 2 * y[i]) / (2 * x[i] + 6.0 *
    x[i] * x[i] * y[i]);
    delta_y = 3 * x[i] * x[i] * delta_x + g(x[i], y[i]);
    x[i+1] = x[i] + delta_x;
    y[i+1] = y[i] + delta_y;
    cout << "第" << i+1 << "次迭代: " << "(" << x[i+1] << ", " << y[i+1] << ")" <<
endl;
    i++;
    //cout << "max:" << max(delta_x, delta_y) << endl;
    if(max(fabs(delta_x), fabs(delta_y)) <= eps)
        break;
}</pre>
```

输出结果

在第3次迭代后满足精度要求,得出 $x \approx 0.826031, y \approx 0.563624$

```
运行: Al_Lab1 ×

C:\AI_Lab1\cmake-build-debug\AI_Lab1.exe
第1次迭代: (0.827049, 0.563934)
第2次迭代: (0.826032, 0.563624)
第3次迭代: (0.826031, 0.563624)
进程已结束,退出代码0
```

问题二

2. (Page187, Project21(1)) 用二阶 Rouge-Kutta 公式求解常微分方程组初值问题

$$\begin{cases} y'(x) = f(x, y) \\ y(a) = y_0 \end{cases}, a \le x \le b \tag{2}$$

(1) 求解初值问题

$$\begin{cases} y'(x) = y \sin \pi x \\ y(0) = 1 \end{cases}$$
(3)

输入: 区间剖分点数 n, 区间端点 a,b, 定义函数 y'(x) = f(x,y).

输出: y_k , k = 1, 2, ..., n.

Runge-Kutta 方法通常写成如下形式,

$$\begin{cases} y_{n+1} = y_n + h(c_1k_1 + c_2k_2) \\ k_1 = f(x_n, y_n) \\ k_2 = f(x_n + ah, y_n + bhk_1) \end{cases}$$
(7.13)

若取 $c_1 = \frac{1}{2}$, $c_2 = \frac{1}{2}$, a = 1, b = 1, 得到式 (7.14) 的二阶 Runge-Kutta 公式:

$$\begin{cases} y_{n+1} = y_n + \frac{h}{2}(k_1 + k_2) \\ k_1 = f(x_n, y_n) \\ k_2 = f(x_n + h, y_n + hk_1) \end{cases}$$
(7.14)

代码实现

计算k1, k2, y[i+1], 输出y[i+1], 若i < n则继续迭代, 否则算法终止

```
for(int i = 0; i < n; i++){
    x[i] = i * h;
    k1 = f(x[i], y[i]);
    k2 = f(x[i] + h, y[i] + h * k1);
    y[i+1] = y[i] + h / 2.0 * (k1 + k2);
    cout << "y" << i+1 << " = " << y[i+1] << end];
}</pre>
```

输出结果

这里取区间[0,1],剖分点数5进行测试,求得y1 = 1.05878,y2 = 1.23355,y3 = 1.49049,y4 = 1.73652,y5 = 1.83859

```
运行: AI_Lab1 ×

C:\AI_Lab1\cmake-build-debug\AI_Lab1.exe

0 1 5

y1 = 1.05878

y2 = 1.23355

y3 = 1.49049

y4 = 1.73652

y5 = 1.83859
```

问题三

3. (Page187, Project22) 用改进的 Euler 公式求解常微分方程组初值问题计算公式:

$$\begin{pmatrix} \bar{y}_{n+1} \\ \bar{z}_{n+1} \end{pmatrix} = \begin{pmatrix} y_n \\ z_n \end{pmatrix} + h \begin{pmatrix} f(x_n, y_n, z_n) \\ g(x_n, y_n, z_n) \end{pmatrix}$$
(4)

$$\begin{pmatrix} y_{n+1} \\ z_{n+1} \end{pmatrix} = \begin{pmatrix} y_n \\ z_n \end{pmatrix} + \frac{h}{2} \left[\begin{pmatrix} f(x_n, y_n, z_n) \\ g(x_n, y_n, z_n) \end{pmatrix} + \begin{pmatrix} f(\bar{x}_{n+1}, \bar{y}_{n+1}, \bar{z}_{n+1}) \\ g(\bar{x}_{n+1}, \bar{y}_{n+1}, \bar{z}_{n+1}) \end{pmatrix} \right]$$
(5)

输入: 区间剖分点数 N, 区间端点 a,b, 定义函数

$$y'(x) = f(x, y, z), z'(x) = g(x, y, z)$$
 (6)

输出: (y_k, z_k) , k = 1, 2, ..., N

利用上述方法,求解课本 Page156 例题 7.7:

$$\begin{cases} \frac{\mathrm{d}u}{\mathrm{d}t} = 0.09u(1 - \frac{u}{20}) - 0.45uv \\ \frac{\mathrm{d}v}{\mathrm{d}t} = 0.06v(1 - \frac{v}{15}) - 0.001uv \\ u(0) = 1.6 \\ v(0) = 1.2 \end{cases}$$
(7)

算法过程

如上图改进的Euler公式所示

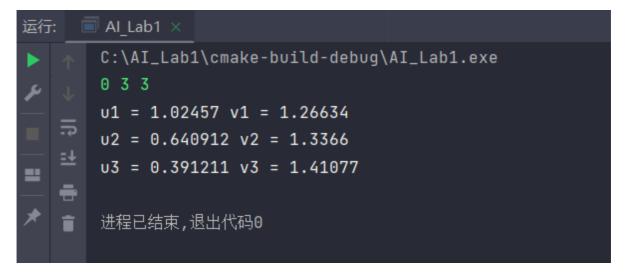
代码实现

依次计算u_[i+1], v_[i+1], u[i+1], v[i+1], 并将u[i+1], v[i+1]输出

```
for(int i = 0; i < n; i++){
    u_[i+1] = u[i] + h * f(u[i], v[i]);
    v_[i+1] = v[i] + h * g(u[i], v[i]);
    u[i+1] = u[i] + h / 2.0 * (f(u[i], v[i]) + f(u_[i+1], v_[i+1]));
    v[i+1] = v[i] + h / 2.0 * (g(u[i], v[i]) + g(u_[i+1], v_[i+1]));
    cout << "u" << i+1 << " = " << u[i+1] << " " << "v" << i+1 << " = " << v[i+1] <<
```

输出结果

输入区间[0,3],剖分点数3,计算得出u3 = 0.391211,v3 = 1.41077,即3年后这一对寄生虫数量分别为 0.391211和1.41077



实验总结

通过本次实验我基本掌握了Newton迭代法,Rouge-Kutta方法,改进的Euler公式。解决非线性方程组求解,常微分方程组初值问题。

参考资料

[1]数值计算方法与算法.第三版.张韵华,王新茂编

附录

问题—代码

```
#include <cmath>
#include "iostream"
using namespace std;
double f(double x, double y){
   return x * x + y * y - 1;
}
double g(double x, double y){
   return x * x * x - y;
}
int main(){
    double eps = 1E-5, x[100], y[100], delta_x, delta_y;
   x[0] = 0.8;
   y[0] = 0.6;
   int i = 0;
   while(true){
        delta_x = (-f(x[i], y[i]) - g(x[i], y[i]) * 2 * y[i]) / (2 * x[i] + 6.0)
* x[i] * x[i] * y[i]);
        delta_y = 3 * x[i] * x[i] * delta_x + g(x[i], y[i]);
        x[i+1] = x[i] + delta_x;
        y[i+1] = y[i] + delta_y;
        cout << "第" << i+1 << "次迭代: " << "(" << x[i+1] << ", " << y[i+1] <<
")" << end1;
        i++;
        //cout << "max:" << max(delta_x, delta_y) << endl;</pre>
        if(max(fabs(delta_x), fabs(delta_y)) <= eps)</pre>
            break;
   }
    return 0;
}
```

问题二代码

```
#include <cmath>
#include "iostream"

using namespace std;
```

```
double f(double x, double y){
   return y * sin(numbers::pi * x);
}
int main(){
   int n;
   double a, b, y[100], x[100], k1, k2;
   y[0] = 1.0;
    cin >> a >> b >> n;
    double h = (b - a)/double(n);
    for(int i = 0; i < n; i++){
        x[i] = i * h;
        k1 = f(x[i], y[i]);
        k2 = f(x[i] + h, y[i] + h * k1);
       y[i+1] = y[i] + h / 2.0 * (k1 + k2);
        cout << "y" << i+1 << " = " << y[i+1] << end];
    }
   return 0;
}
```

问题三代码

```
#include <cmath>
#include "iostream"
using namespace std;
double f(double u, double v){
   return 0.09 * u * (1 - u / 20.0) - 0.45 * u * v;
}
double g(double u, double v){
   return 0.06 * v * (1 - v / 15.0) - 0.001 * u * v;
}
int main(){
   double u[100], v[100], u_[100], v_[100], a, b;
   int n;
   u[0] = 1.6;
   v[0] = 1.2;
   cin >> a >> b >> n;
   double h = (b - a)/double(n);
   for(int i = 0; i < n; i++){
       u_{i+1} = u[i] + h * f(u[i], v[i]);
       v_{i+1} = v[i] + h * g(u[i], v[i]);
       u[i+1] = u[i] + h / 2.0 * (f(u[i], v[i]) + f(u_[i+1], v_[i+1]));
       v[i+1] = v[i] + h / 2.0 * (g(u[i], v[i]) + g(u_[i+1], v_[i+1]));
       v[i+1] \ll endl;
   }
   return 0;
}
```