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#include<iostream>
#include<queue>
#include<list>
#include<vector>
#include<fstream>
using namespace std;
class Dijkstra {
    int V; // nr de varfuri
    list<pair<int, int>>* adj;
public:
    Dijkstra(const char* file) {
        ifstream ifs(file);
        ifs >> V; //citesc din fisier numarul de varfuri
        adj = new list<pair<int, int>>[V];
        while (!ifs.eof()) {
            int u, v, w;
            ifs >> u >> v >> w;
            adj[u].push_back(make_pair(v, w));
        }
    }
    void print() {
        for (int i = 0; i < V; i++)
        {
            cout << i << "->";
            list<pair<int, int>> ::iterator j;
            for (j = adj[i].begin(); j != adj[i].end(); ++j)
                cout << "(" << (*j).first << "," << (*j).second << ")";
            cout << endl;
        }
    }
    void shortestPath(int src) {
        //initializam vectorul distantelor cu infinit
        vector<int> dist(V, INT_MAX);
        vector<int> parent(V);
        for (int i = 0; i < V; i++)
            parent[i]=i;
        //cream coada de prioritati unde se vor aduga nodurile neprocesate
        priority_queue< pair<int,int>, vector <pair<int, int>>, greater<pair<int, int>>> pq;

        pq.push(make_pair(0, src));
        dist[src] = 0;
        while (!pq.empty()) {
            int u,v;// nodul sursa, nodul destinatie

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        int w; //ponderea muchiei [uv]
        u = pq.top().second;
        w = pq.top().first;
        pq.pop();
        list<pair<int, int>> ::iterator i;
        for (i = adj[u].begin(); i != adj[u].end(); ++i) {
            v = (*i).first;
            w = (*i).second;
            if (dist[u] + w < dist[v])
            {
                dist[v] = dist[u] + w;
                pq.push(make_pair(dist[v], v));
                parent[v] = u;
            }
        }
    }

    for (int i = 0; i < V; i++)
        cout << dist[i] << ", ";
    cout << endl << "PAths:" << endl;
    for (int i = 0; i < V; i++) {
        showPath(parent, i);
        cout << endl;
    }
}

void showPath(vector<int> parent, int v) {
    if(v != parent[v])
        showPath(parent, parent[v]);
    cout << v << "->";
}

};

void main() {
    Dijkstra d("graf.txt");
    d.print();
    d.shortestPath(0);
}

```