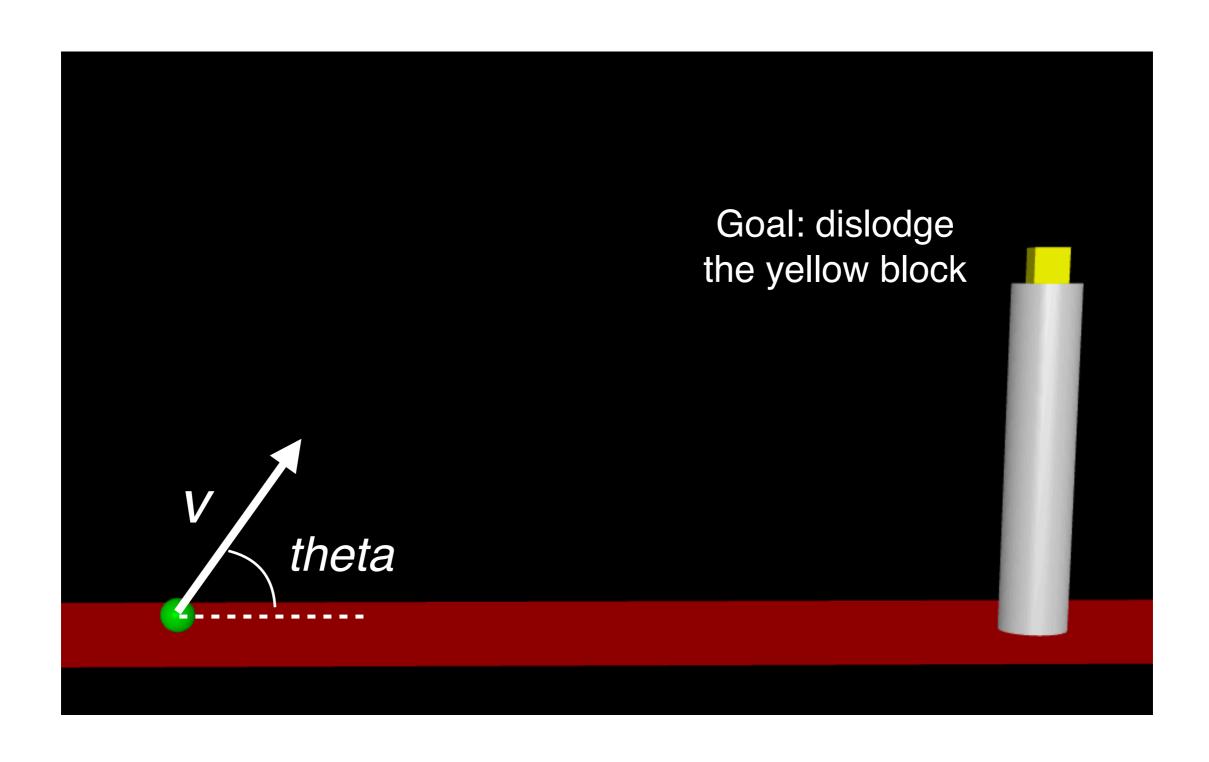
#### MuJoCo: Projectile Launch Optimization (I)

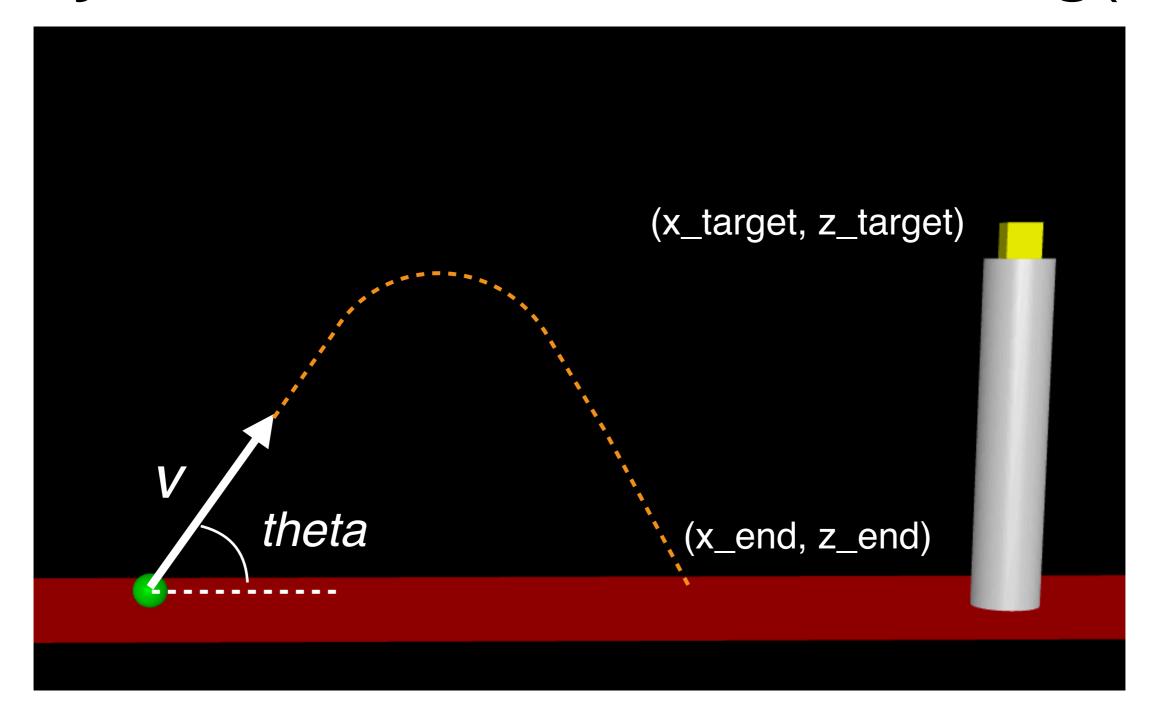


#### MuJoCo: Projectile Launch Optimization (2)\*

#### Using template\_projectile.zip to get started

- I. From <u>tiny.cc/mujoco</u> download <u>template\_projectile.zip</u> and unzip in myproject
- 2. Rename folder template\_projectile to projectile\_opt
- 3. Make these three changes
  - 1. main.c line 28, change template\_projectile/ to projectile\_opt/
  - makefile change ROOT = template\_writeData to ROOT = projectile\_opt also UNCOMMENT (del #) appropriate to your OS
  - 3. run\_unix / run\_win.bat change <template\_projectile > to < projectile\_opt >
- 4. In the shell, navigate to projectile\_opt and type ./run\_unix (unix)
- \* I don't have instructions for Windows. For Windows, use Ubuntu via Virtualbox.

## MuJoCo: Non-linear root finding(I)



Inputs: v, theta, time of flight

Outputs: x\_end, z\_end

# MuJoCo: Nonlinear root-finding (2)

$$\min_{x} f(x) = 0$$

Cost needs to defined so we set it to 0

subject to:

$$0.1 \le v \le \infty$$

$$0.1 \le \theta \le \pi/2$$

$$0.1 \le t \le \infty$$

$$x_{end} - x_{target} = 0$$

$$z_{end} - z_{target} = 0$$

### MuJoCo: Nonlinear optimization (3)

$$\min_{x} f(x) = t$$

Minimize time

subject to:

$$0.1 \le v \le \infty$$

$$0.1 \le \theta \le \pi/2$$

$$0.1 < t < \infty$$

$$x_{end} - x_{target} = 0$$

$$z_{end} - z_{target} = 0$$