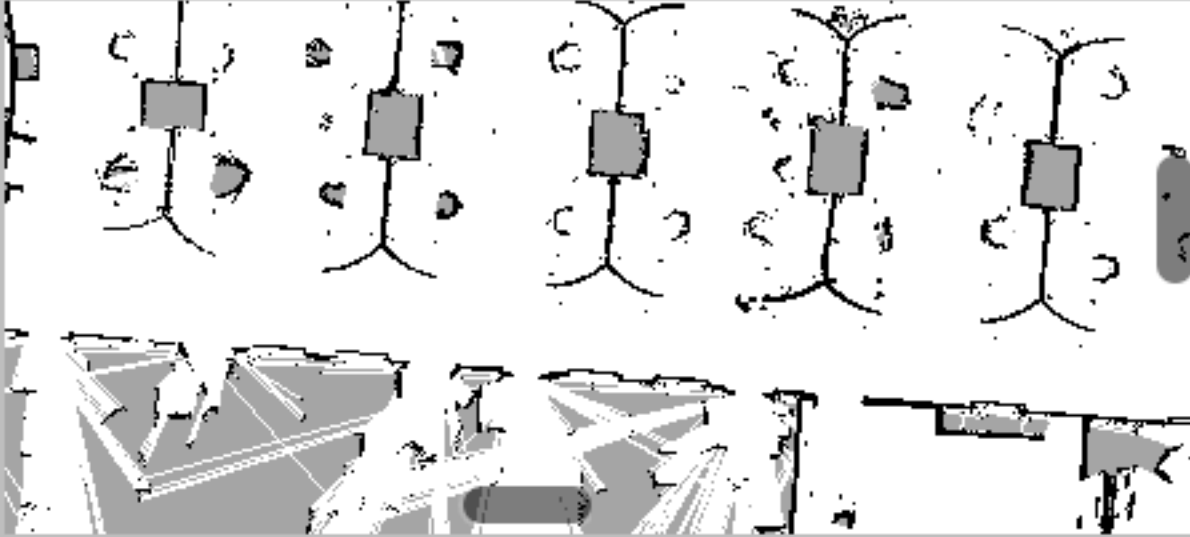


Capabilities

Map_representation



read description



X: -1.750000026077032

Y: -5.100000075995922

Vision



read description



Directional_Movement

add

read description

Imu_based_Robot_position



read description

Imu_based_Robot_speed



read description

Navigation

add

read description

Depth_Sensing



read description

ARTag_counting



read description

Program

Navigation

header.frame_id
pose.orientation.w
pose.orientation.x
pose.orientation.y
pose.orientation.z
pose.position.x
pose.position.y
pose.position.z

map

1

0

0

0

0.175

-0.487

0

remove

WHILE:

☐ NOT

ARTag_counting/total

!=



1

remove

add another condition

DO:

Directional_Movement

angular.x

angular.y

angular.z

linear.x

linear.y

linear.z

remove

remove

Run

Constructs

capability

if-then-else

while-do

repeat

no-action