



Lecture 8 slides

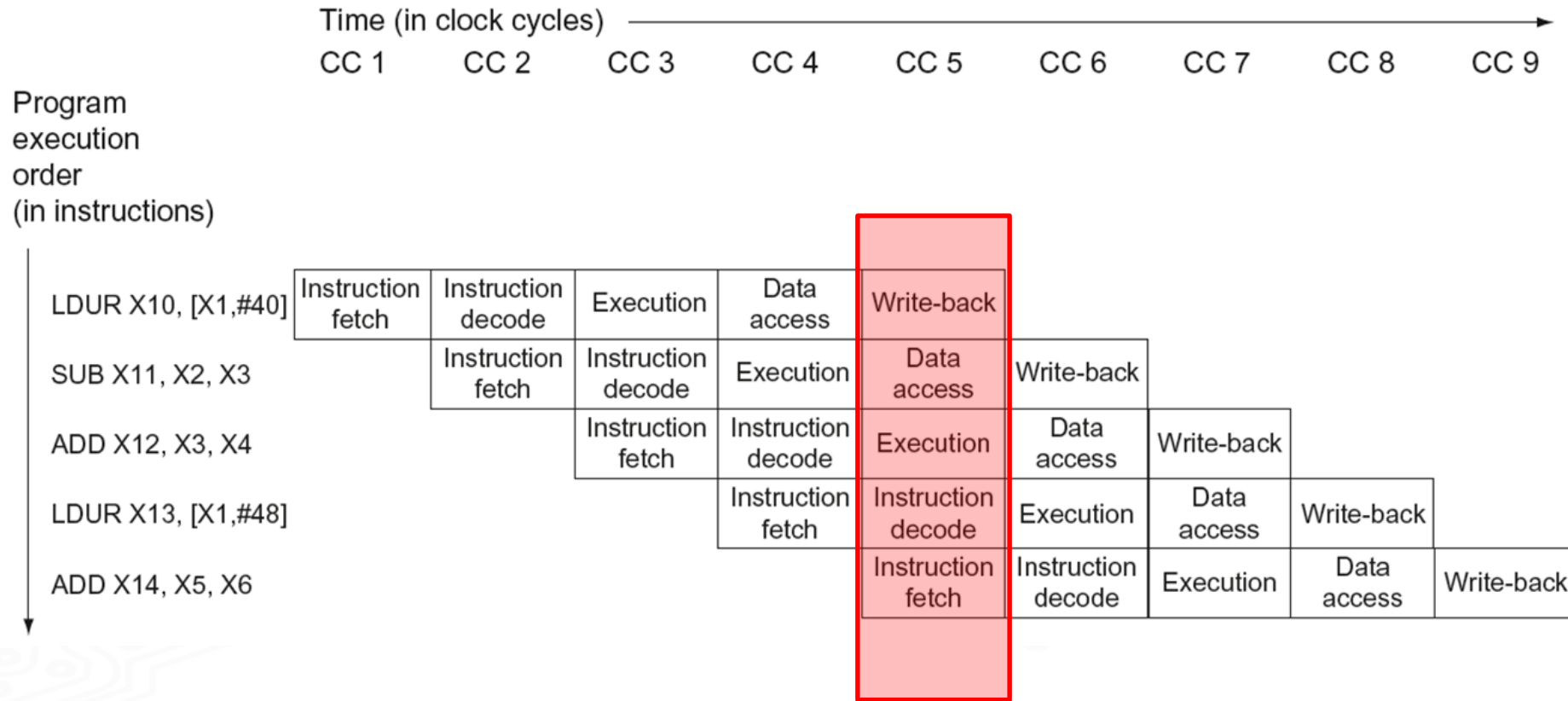
CE/CZ 3001:  
Advanced Computer Architecture  
(Module 4: Instruction Level Parallelism(ILP))

Dr Smitha K. G.  
School of Computer Science  
And Engineering

# Summary of video

- Data-dependence
- How to handle data dependencies?
  - Detect and Wait
  - Data forwarding through register
  - Detect and forward
- In order and out of order execution
- Instruction reordering and renaming
- Loop unrolling

# CPI of a pipeline without stalls



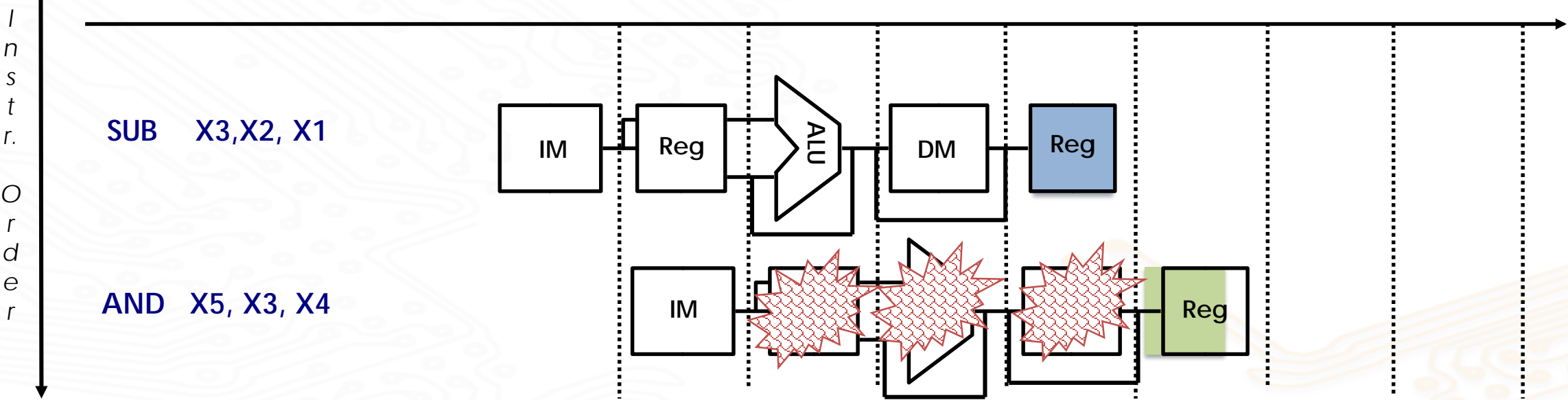
CPI= No of clock cycles/instruction

Steady state CPI = (No of instructions + no of stalls ) / No of instructions

# How to handle data dependencies

- Anti and output dependences are easier to handle
- True (Flow or RAW) dependences are more difficult to handle as they constitute true dependence on a value
  - Detect and wait until value is available in register file
    - Stall the program. (HARDWARE)
    - Compiler can also plug in the NOP instructions in between. (SOFTWARE)
  - Detect and forward / bypass data to dependent instruction

# Detect and wait



Hardware stall

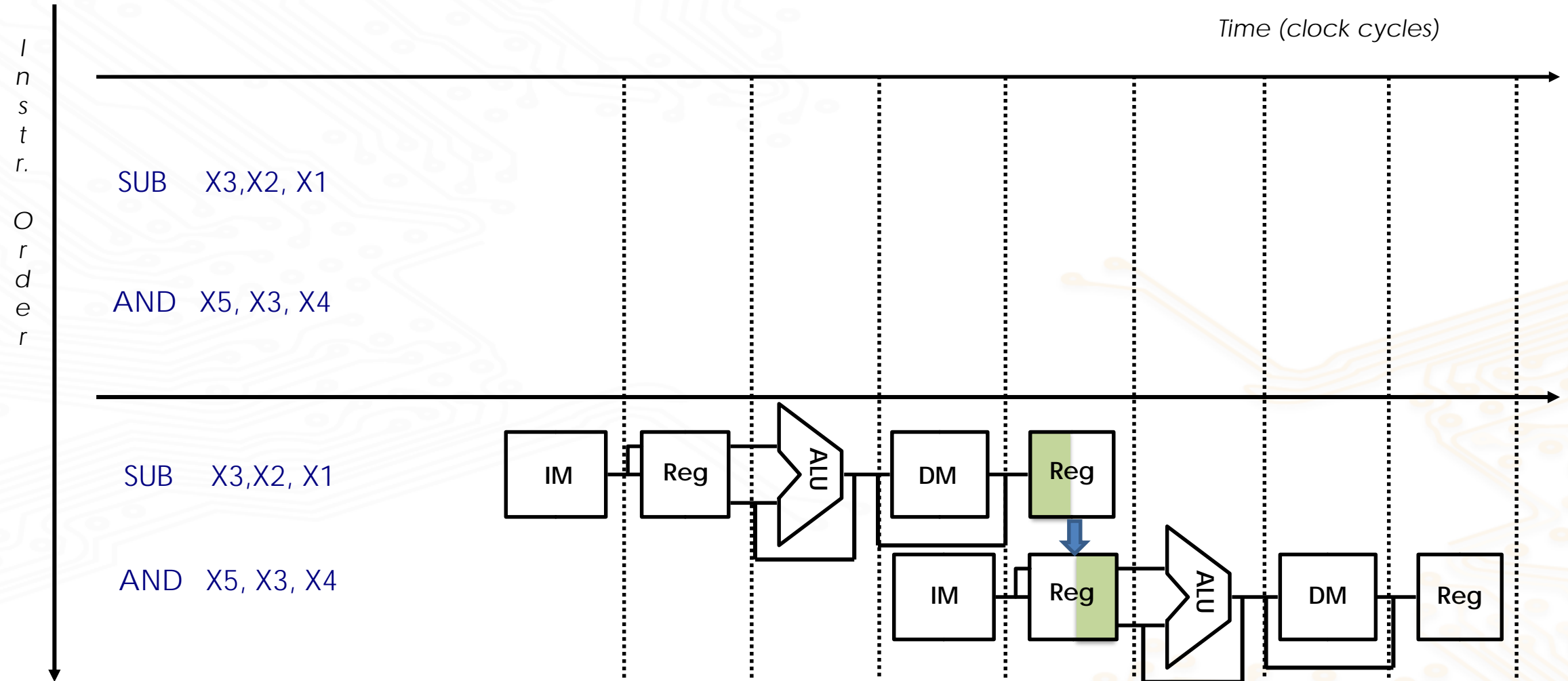
Instr.	1	2	3	4	5	6	7	8	9
I1									
I2									

Software inserting NOPs

Instr.	1	2	3	4	5	6	7	8	9
I1									
I2									



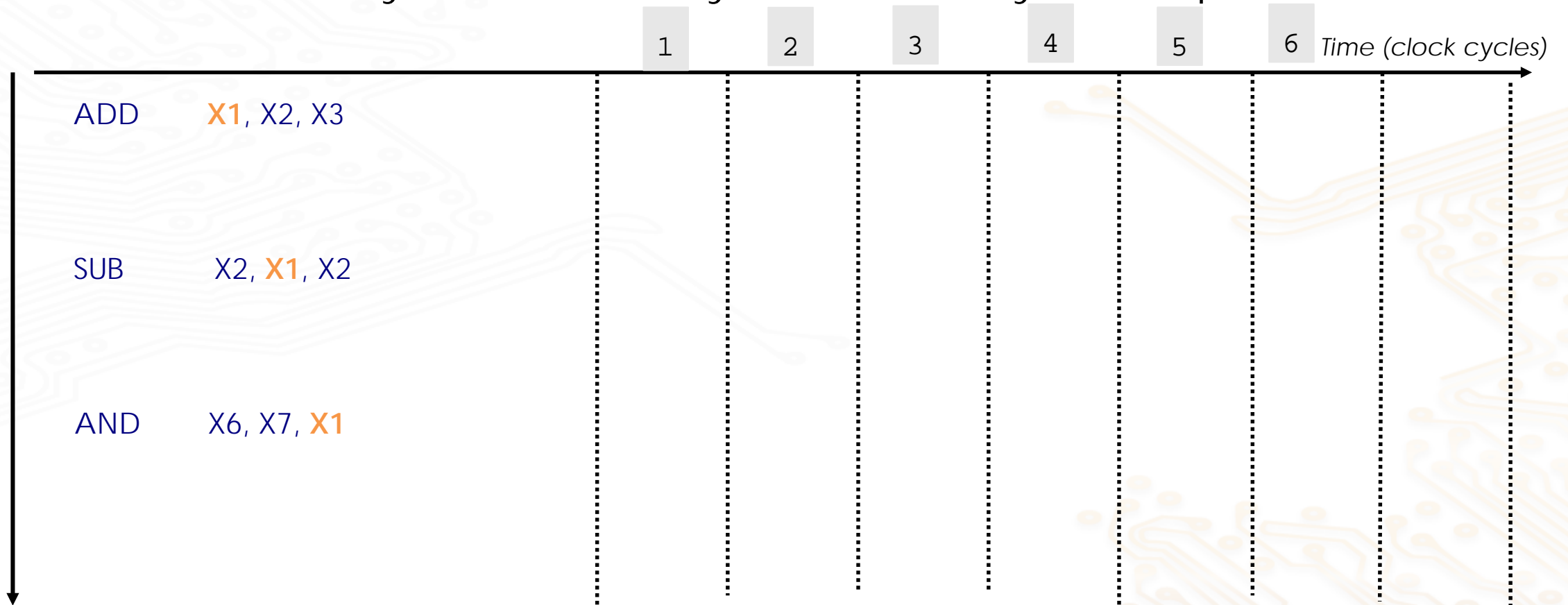
# Data Forwarding – through register



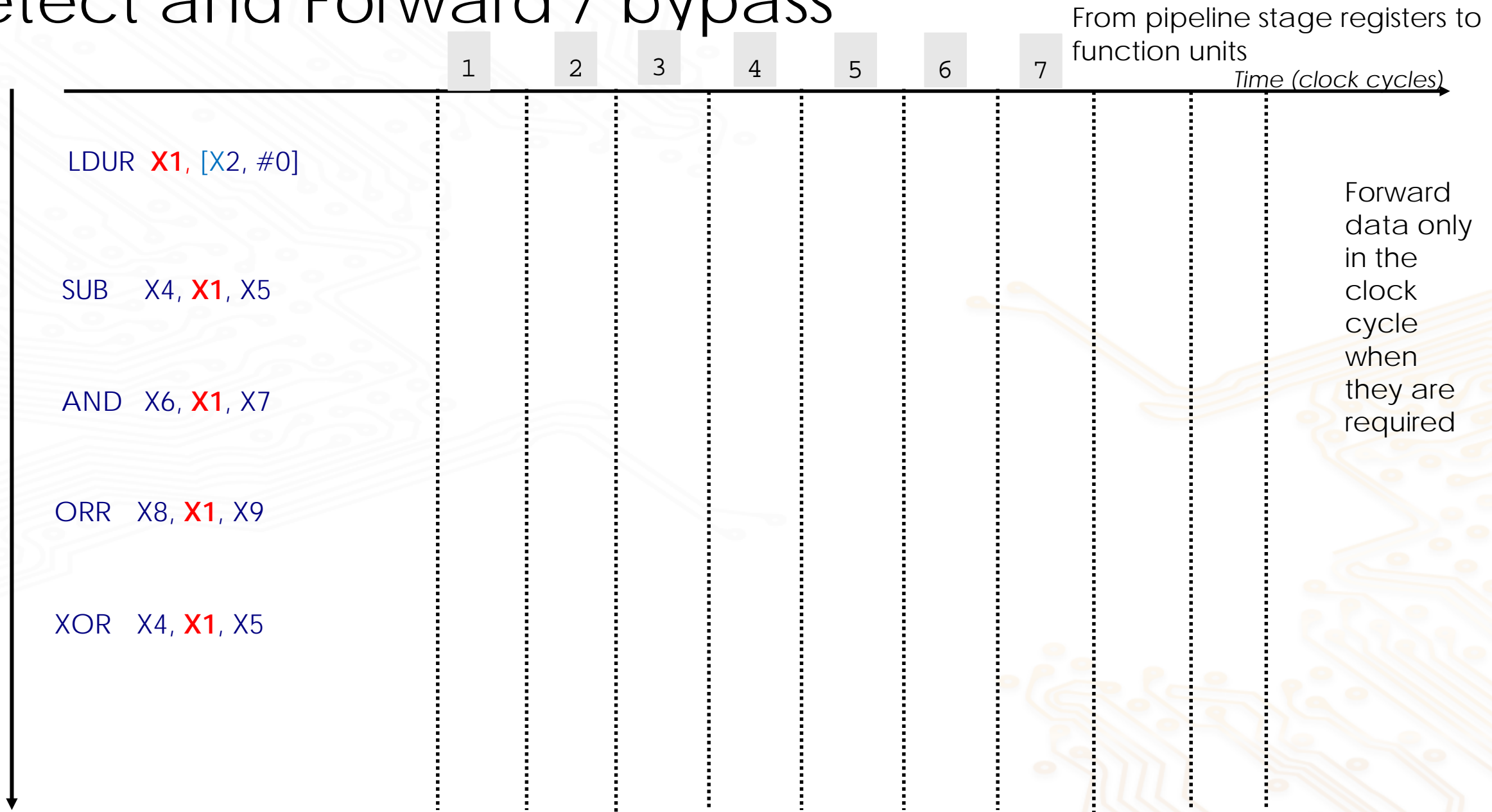
Solution: write and read in the same cycle  
Most processors have this as it is easy to implement

# Detect and Forward / bypass

- Data forwarding.
- From **pipeline stage registers** to **function units**
- Forward data only in the clock cycle when they are required



# Detect and Forward / bypass





# Data forwarding – example 2

Without forwarding

(writeback and decode can happen simultaneously)

I1: ADD **X1**, X2, X3

I2: LDUR X2, [**X1**, #0]

I3: AND X6, X7, **X1**

Clocks	1	2	3	4	5	6	7	8	9	10
I1	IF	ID	EX	M	WB					
I2		IF	S	S	ID	EX	M	WB		
I3					IF	ID	EX	M	WB	

With forwarding

Clock cycle	1	2	3	4	5	6	7
I1							
I2							
I3							

Steady state CPI = (No of instructions + no of stalls ) / No of instructions

Steady state CPI (no forwarding) =

Steady state CPI (forwarding) =

# Performance improvement using Dynamic Scheduling

Assume full data forwarding

## Out-of-order processors:

After instruction decode

- don't wait for previous instructions to execute if this instruction does not depend on them, i.e., independent ready instructions can execute before earlier instructions that are stalled

### in-order processors

LDUR **X1**, [X4, #100]

ADD X2, **X1**, X4

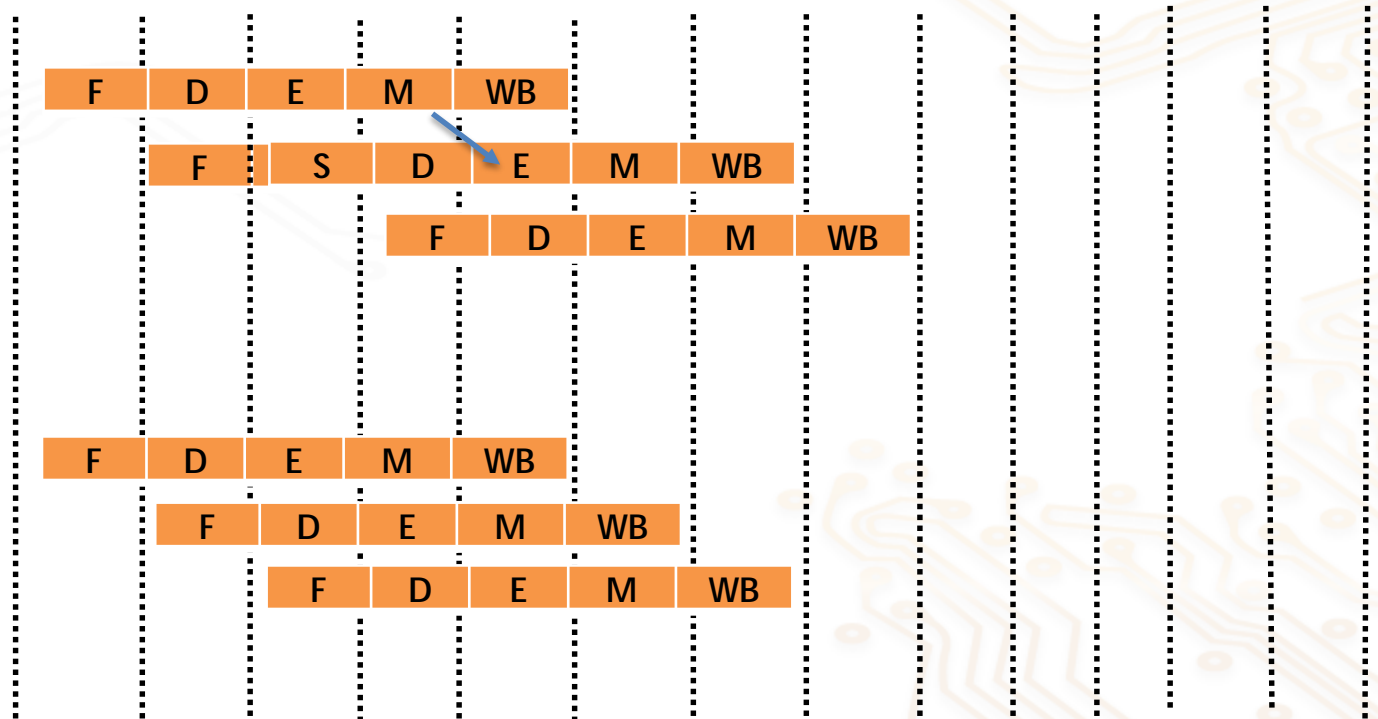
SUB X5, X6, X7

### out-of-order processors

LDUR **X1**, [X4, #100]

SUB X5, X6, X7

ADD X2, **X1**, X4(no stalls)



# Register Renaming

WAR      ADD      X4, X2, X1;       $X4 \leftarrow X2 + X1$   
          ANDI     X1, X0, #2;       $X1 \leftarrow X0 \& 2$



Rename X1 to X3

          ADD      X4, X2, X1;       $X4 \leftarrow X2 + X1$   
          AND      X3, X0, #2;       $X3 \leftarrow X0 \& 2$

WAW      ADD      X0, X2, X1;       $X0 \leftarrow X2 + X1$   
          SUB      X0, X3, X5;       $X0 \leftarrow X3 - X5$



Rename X0 to X4

          ADD      X0, X2, X1;       $X0 \leftarrow X2 + X1$   
          SUB      X4, X3, X5;       $X4 \leftarrow X3 - X5$

**More register resources will be needed**

# Loop unrolling

- loop unrolling leads to multiple replications of the loop body
  - unrolling creates longer code sequences
  - goal is to execute iterations in parallel

- Example

```
for (i=0; i < 16; i++) {  
  c[i] = a[i] + b[i];  
}
```



Unroll  
once

```
for (i=0; i < 8; i++) {  
  c[2 * i] = a[2 * i] + b[2 * i];  
  c[2 * i+1] = a[2 * i+1] + b[2 * i+1];  
}
```

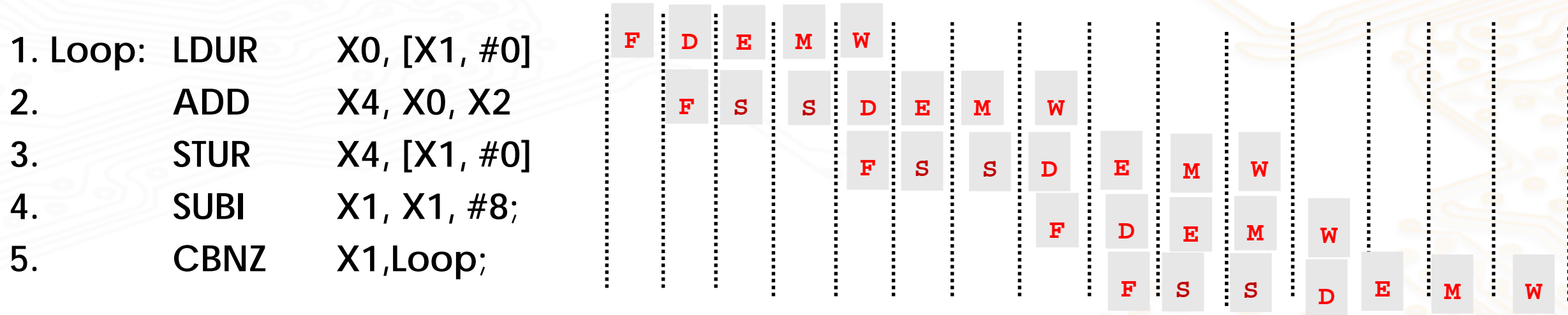
- greater demand for registers
  - higher register pressure : more concurrency demands for more resources

**How can loop unrolling help us to reduce the stalls and to improve CPI?**

# Loop unrolling example

Loop:	LDUR	<b>X0</b> , [X1, #0];	load to X0 from mem[0+X1]
	ADD	X4, <b>X0</b> , X2;	add [X0]+[X2]
	STUR	X4, [X1, #0];	store X4 to mem[0+X1]
	SUBI	X1, X1, #8;	decrement pointer 8
	CBNZ	X1, Loop;	branch X1!=zero

If data forwarding is not allowed,  
write back and decode of two  
instructions can happen  
simultaneously



$$\text{CPI} = (\text{No of instructions} + \text{no of stall}) / \text{No. of instruction} =$$

# Loop unrolling example

1	Loop:	LDUR	X0, [X1, #0]		
2		ADD	X4, X0, X2	2 stall	
3		STUR	X4, [X1, #0]	2 stall	;drop SUBI & CBNZ
4		LDUR	X6, [X1, #-8]		
5		ADD	X8, X6, X2	2 stall	
6		STUR	X8, [X1, #-8]	2 stall	;drop SUBI & BNEZ
7		LDUR	X10, [X1, #-16]		
8		ADD	X12, X10, X2	2 stall	
9		STUR	X12, [X1, #-16]	2 stall	;drop SUBI & BNEZ
10		LDUR	X14, [X1, #-24]		
11		ADD	X16, X14, X2	2 stall	
12		STUR	X16, [X1, #-24]	2 stall	
13		SUBI	X1, X1, #32		;alter to 4*8
14		CBNZ	X1, LOOP	2 stall	

STRAIGHT FORWARDED UNROLLING,  
CPI=

Rewrite loop to minimize stalls?



# Loop unrolling with reordering

Branch is not  
handled here

```
1 Loop: LDUR    X0, [X1, #0]
2      ADD     X4, X0, X2    2 stall
3      STUR    X4, [X1, #0]  2 stall
4      LDUR    X6, [X1, #-8]
5      ADD     X8, X6, X2    2 stall
6      STUR    X8, [X1, #-8] 2 stall
7      LDUR    X10, [X1, #-16]
8      ADD     X12, X10, X2  2 stall
9      STUR    X12, [X1, #-16] 2 stall
10     LDUR    X14, [X1, #-24]
11     ADD     X16, X14, X2  2 stall
12     STUR    X16, [X1, #-24] 2 stall
13     SUBI    X1, X1, #32
14     CBNZ    X1, LOOP    2 stall
```

```
1 Loop: LDUR    X0, [X1, #0]
2      LDUR    X6, [X1, #-8]
3      LDUR    X10, [X1, #-16]
4      LDUR    X14, [X1, #-24]
5      ADD     X4, X0, X2
6      ADD     X8, X6, X2
7      ADD     X12, X10, X2
8      ADD     X16, X14, X2
9      STUR    X4, [X1, 0]
10     STUR    X8, [X1, #-8]
11     STUR    X12, [X1, #-16]
12     STUR    X16, [X1, #-24]
13     SUBI    X1, X1, #32
14     CBNZ    X1, LOOP
```

2 stall here

No dataforwarding, WB and DEC  
happens simultaneously

# How data hazards can be eliminated?

## Summary

- Detect and wait (stalling unnecessarily)
- Data forwarding
- Reordering (out of order)
- Renaming (to remove WAR and WAW hazard)
- Loop unrolling and reordering