

# PLC programming

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Paolo Burgio  
[paolo.burgio@unimore.it](mailto:paolo.burgio@unimore.it)



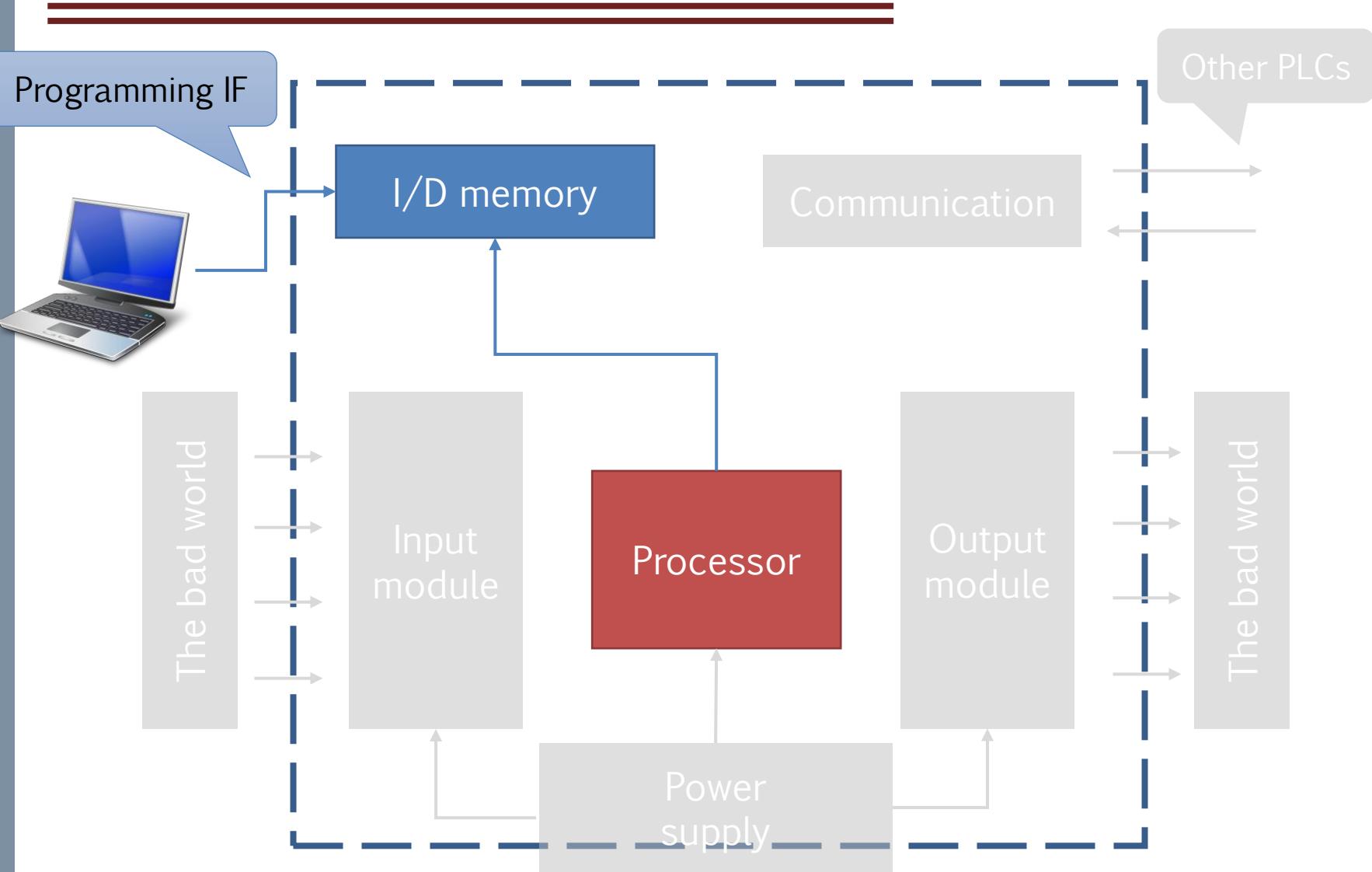
**UNIMORE**  
UNIVERSITÀ DEGLI STUDI DI  
MODENA E REGGIO EMILIA

High Performance  
Real Time **Lab**

```
while (not edge) {  
    run();  
}
```

```
do {  
    run();  
} while (not edge);
```

# Structure of a PLC





# PLC programming with IEC 61131

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First attempt of standardization => IEC 61131-3 standard

- › yr 1993, latest rev 2013
- › Before that, “the fish market” of languages
- › Still, Ladder was a prominent one...but everyone had its own variant!!

States that there are 5 “standard” ways of programming PLCs

- › **Ladder diagram**
  - Description of electrical wiring, designed for non-informatics
- › **Function Block Diagram – FBD**
  - From electronics
- › **Sequential Functional Chart – SFC**
  - Petri-net style
- › **Instruction List – IL**
  - ASM-like
- › **Structured Text – ST**
  - Similar to Pascal/VB



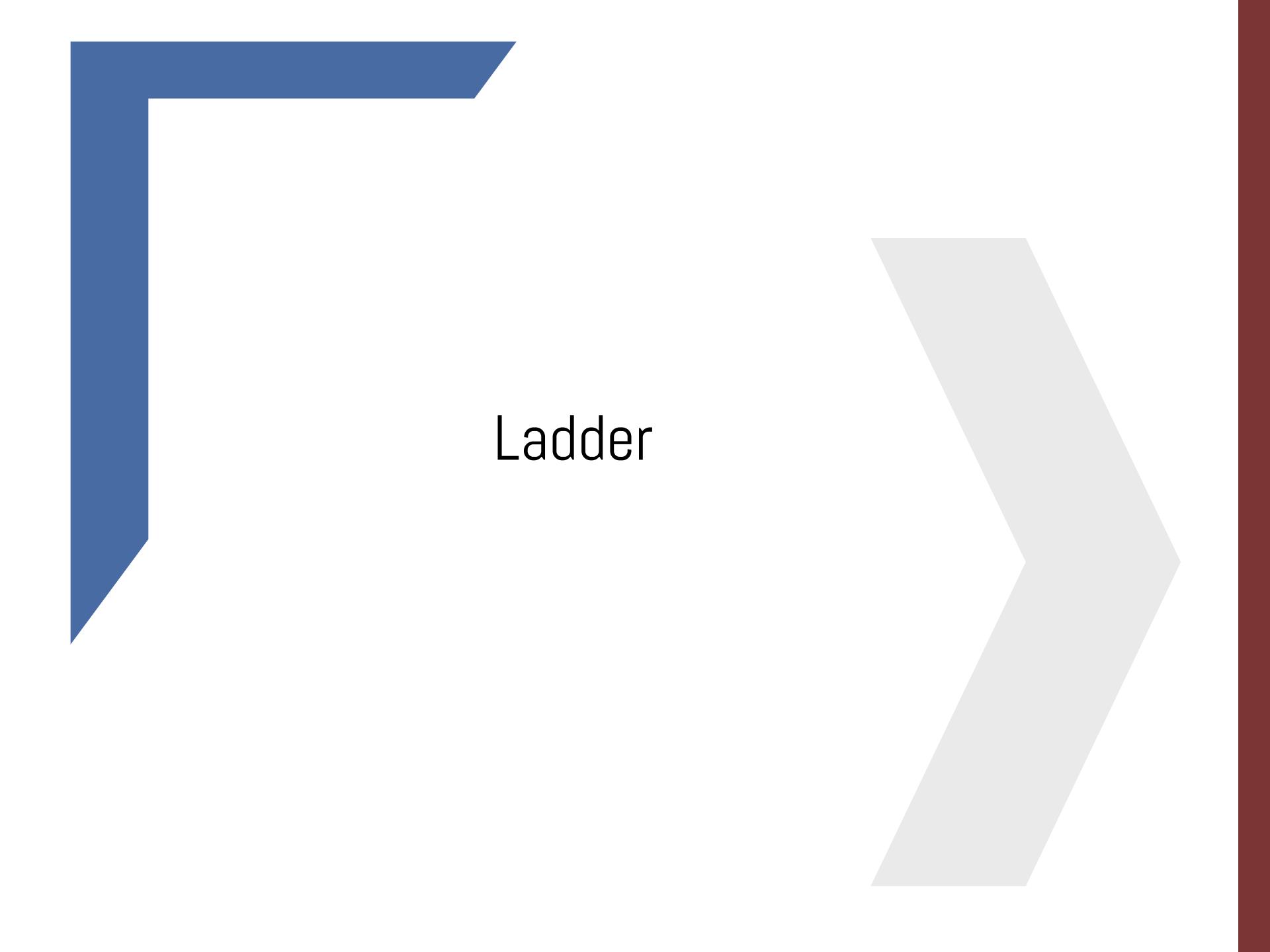
# IEC 61131

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Covers the complete lifecycle of PLC modules and ~~sw development for PLC~~ PLC programming

- › Part 1: definition of terminology and concepts
- › Part 2: electronic and mech equipment and verification/testing
- › Part 3: programming languages (5 types)
- › Part 4: how to choose, install and maintain
- › Part 5: how to communicate (MMS – Manufacturing Messaging Specification)
- › Part 6: communication via fieldbusses/other ind. standards
- › Part 7: fuzzy control (won't see this..if you don't want)
- › Part 8: sw dev guidelines

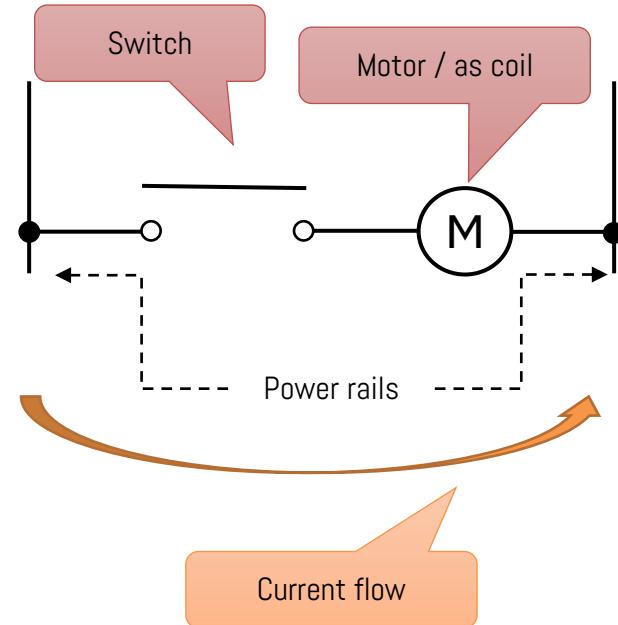
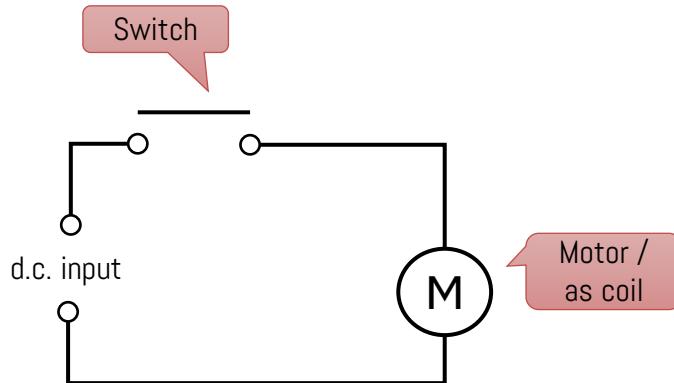


Ladder

# Ladder diagrams

Possible circuit to power on a motor

- › Left: electrical diagram; right: Ladder
- › Does it remind of something...?



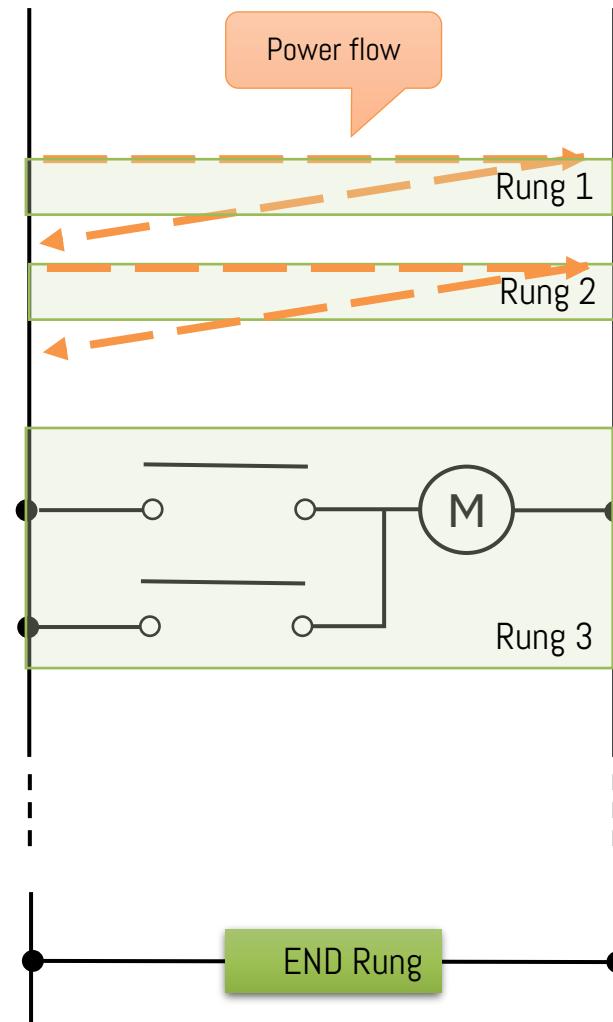
# Ladder programs

Writing a program is as easy as writing a switching circuit

- › Vertical lines are power rails, and power flows from top-left to bottom-right
  - So does “program flow”
- › Horizontal lines (rungs) connect power rails
  - Every rung starts with one or more inputs, and ends with exactly one output
- › Typical exec time: 1ms for 1k bytes of program, so usually approx 10-50ms

Program flow

- › Store input status in mem
- › Read inputs from memory, run program, store out in mem
- › Update all outputs



# Ladder symbols

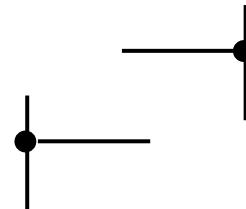
- › Power rails (Vert lines)



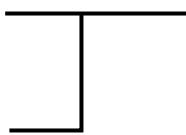
- › Rungs (Horiz lines)



- › Left/right connection between power rail and rungs



- › Dual connection



- › Normally open (NO) contact



- › Normally closed (NC) contact



- › Output coil (from a lamp, a motor...)

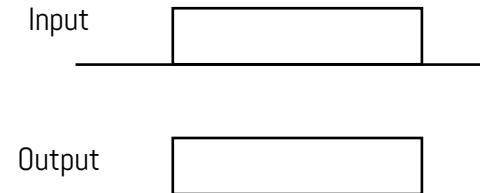
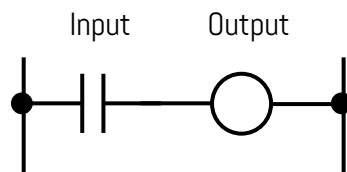


- › A switch

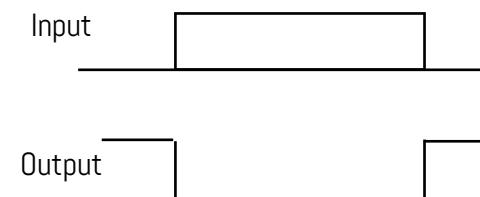
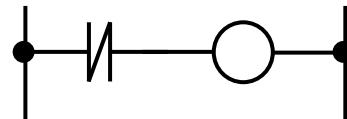


# Example: a (lamp?) switch

- When a NO contact is closed, the attached coil propagates the signal



- When a NC contact is opened, the attached coil propagates the input signal



Let's see  
this in  
action



# Structured Text



# Structured text

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- › Inspired by Pascal language, also Basic and VB programmer might find it familiar
- › Procedural language (can define Functions, or Function Blocks)
- › Or define a Program (and call it from within your Application MainTask)
  - Can have multiple programs...you must have one call for one program!

Can also comment code..

```
(* This is a comment! *)
```

```
(* This is a  
multi-line  
comment! *)
```



# Defining variables

Can also initialize them

- › Don't forget semicolon ;

IEC 61131.3 defines several datatypes

- › Few examples

```
Contact1: BOOL;
```

```
Contact2: BOOL := FALSE;
```

IEC Data Type	Format	Range
SINT	Short Integer	-128 ... 127
INT	Integer	-32768 ... 32767
DINT	Double Integer	-2^31 ... 2^31-1
UINT	Unsigned Integer	0 ... 2^16-1
BOOL	Boolean	1 bit
BYTE	Byte	8 bits
WORD	Word	16 bits
STRING	Character String	'My string'
TIME	Duration of time after an event	<b>T#</b> 10d4h38m57s12ms <b>TIME#</b> 10d4h38m
DATE	Calendar date	<b>D#</b> 1989-05-22 <b>DATE#</b> 1989-05-22
REAL	Real Numbers	±10 ^ ±38



# Variables: simple operations

- › Assigning immediate vals to variables

```
Contact1 := FALSE;  
Input1 := 11;  
Output1 := 5;
```

```
Contact1: BOOL;  
Input1: INT;  
Output1: BYTE;
```

- › Also, with operators in R-values

```
Output1 := Input1 - Output1 / ( Input6 + 3 );
```

Let's see  
this in  
action

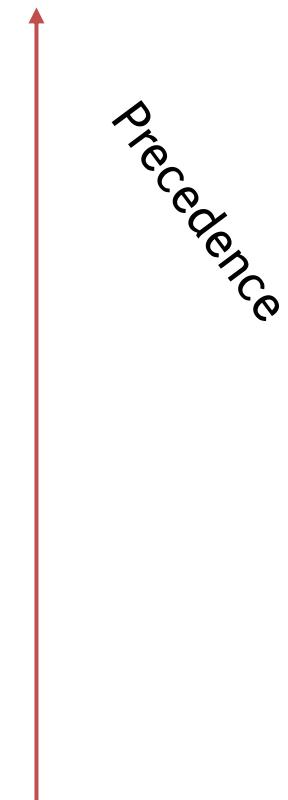




# Structured Text Operators (and their priority)

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Operators	Description
( . . . )	Parenthesized (brackets) expression
Function ( . . . )	List of parameters of a function
**	Power
- , NOT	Negation, Boolean NOT
* , / , MOD	Multiplication, division, modules operations
+ , -	Add, subtract
< , > , <= , >=	Comparison
=, <>	Comparison
AND, OR	Boolean operator
XOR	Exclusive OR
OR	Boolean OR





# Define your own datatypes

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```
(* Enum-like datatype *)
TYPE Motor_State:( Stopped, Running );
END_TYPE;
```

```
(* Analog value datatype *)
TYPE Pressure: REAL;
END_TYPE;
```

# Variables: nomenclature

- › ST is not case sensitive; in case you might want to use capital letter for clarity
- › Use the AT keyword to fix the memory location of a variable

```
Contact1: BOOL AT %MX100; (* Internal memory Bit at address 100 *)  
  
Input1: INT AT %IW200; (* Input memory Word at address 200 *)  
  
Output1: BYTE AT %OB300; (* Output memory Byte at address 300 *)
```

**Memory type**  
M - internal  
I - input  
O - output

% M X 100

Memory Address

**Data type**  
X (bit) - 1 bit  
B (byte) - 8 bit  
W (word) - 16 bits  
D (double word) - 32 bits  
L (long word) - 64 bits



# If-Then-Else

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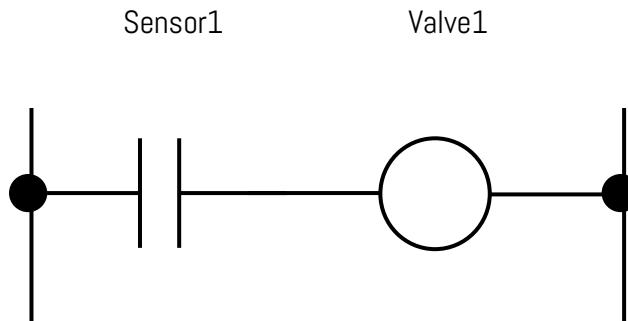
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```
IF Contact1 = TRUE THEN;  
    Coill := TRUE;  
ELSE;  
    Coill := FALSE;  
END_IF;
```

```
IF NOT Contact1 = TRUE;  
    Coill := TRUE;  
END_IF;
```

```
IF Contact1 = TRUE OR Input1 = 11;  
    Coill := TRUE;  
END_IF;
```

# Ladder vs. ST



```
Valve1 := Sensor1;  
  
IF Sensor1 THEN;  
    Valve1 := 1;  
END_IF;
```

Let's see  
this in action





# Switch-case

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- › Multiple instructions on the same line
- › Default with `ELSE` keyword
- › Can also use ranges

```
CASE (State) OF
  1: NextState := 2; ERROR := FALSE;
  2: NextState := 3; ERROR := FALSE;
ELSE
  NextState := 4; ERROR := TRUE;
END_CASE;
```

```
CASE (Temperature) OF
  0...40: Furnace_switch := ON;
  40...100: Furnace_switch := OFF;
END_CASE ;
```



# Loops

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- › For, While-Do, Repeat-Until

```
(* for (input1 = 10;
        input1 >= 0;
        input1-- *)
FOR Input1 := 10 to 0 BY -1
DO
    Output1 := Input1;
END_FOR;
```

```
(* do...
while (input1 < 3
       && input2 == 5); *)
Output1 := 0;
REPEAT
DO
    Output1 := Output1 + 1;
UNTIL Input1 < 3 AND Input2 = 5
END_REPEAT;
```

```
(* while (input1 < 3
          && input2 == 5) *)
Output1 := 0;
WHILE Input1 < 3 AND Input2 = 5
DO
    Output1 := Output1 + 1;
END WHILE;
```

# Defining Programs

- › Read (input vars) – Exec – Write (output vars) paradigm

```
(* ... *)  
VAR (* Input type, and datatype,  
implicit by memory *)  
    Temperature AT $IW100;  
END_VAR  
  
(* ... *)
```

## PROGRAM Example

```
PROGRAM Example  
  
VAR_IN (* Input *)  
    Temperature: INT;  
    Humidity: REAL;  
END_VAR;  
  
VAR_IN (* Input *)  
    Speed: INT = 50;  
END_VAR;  
  
VAR_OUT (* Outputs *)  
    Motor_speed: REAL;  
END_VAR;  
  
(* Instructions here *)  
  
END_PROGRAM;
```

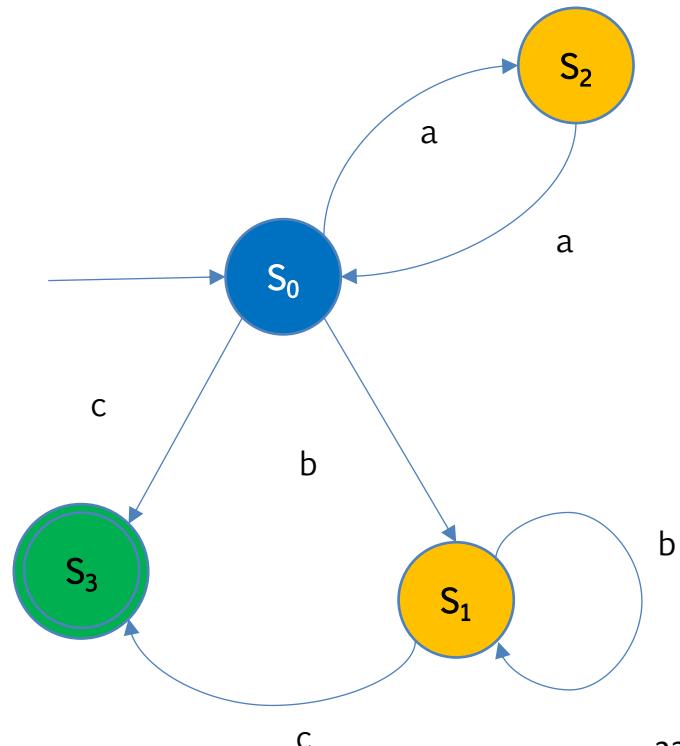
# Exercise

Let's code!

- › Implement the Moore machine of the FSM that understands whether a words is from L

*"Identify even sequences of a (even empty),  
followed by one, or more, or no, b, ended by c"*

- › ...and turns on the corresponding led color
  - Red (error state)
- › How do we give input?
  - 3 inputs => 3 "push buttons"



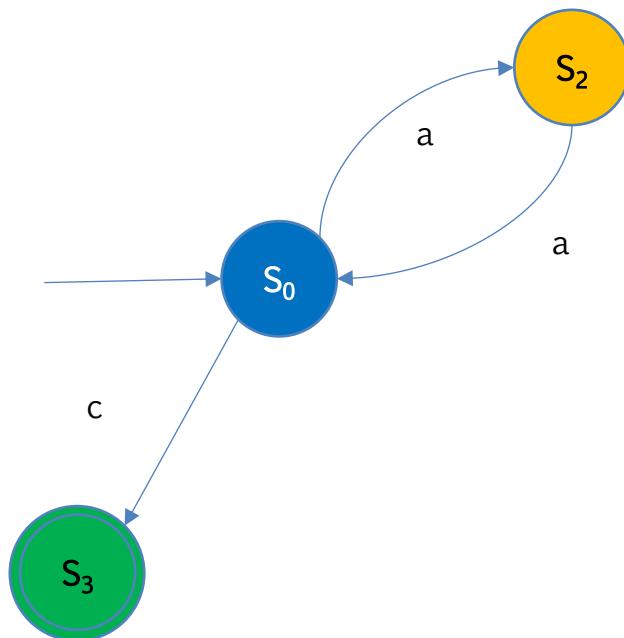
# Exercise (start from this..)

Let's code!

- › Implement the Moore machine of the FSM that understands whether a words is from L

*"Two a (or no a) followed by one c"*

- › ...and turns on the corresponding led color
  - Red (error state)
- › START EVEN SIMPLER!
  - "...that detects c"
  - "...that detects a followed by c"





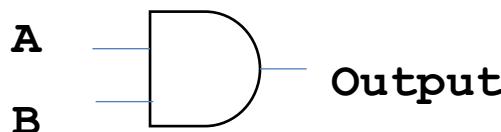
# Logic blocks

# (Unnecessary) brief recap

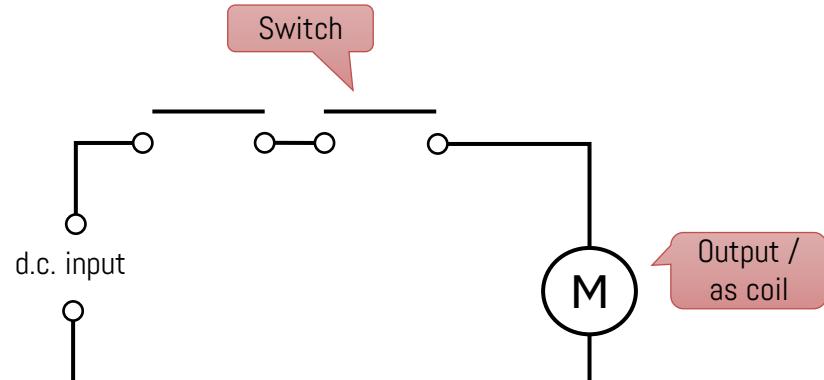
## Logic functions

- › Already seen in previous courses
- › Express Boolean logics, adders, latches, ...

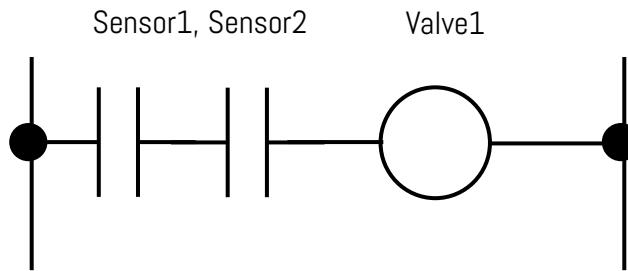
## Example: Logical AND



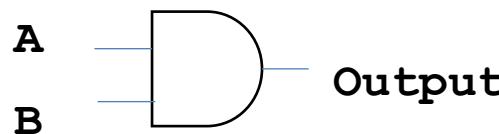
		Output
A	B	
0	0	0
0	1	0
1	1	1
1	0	0



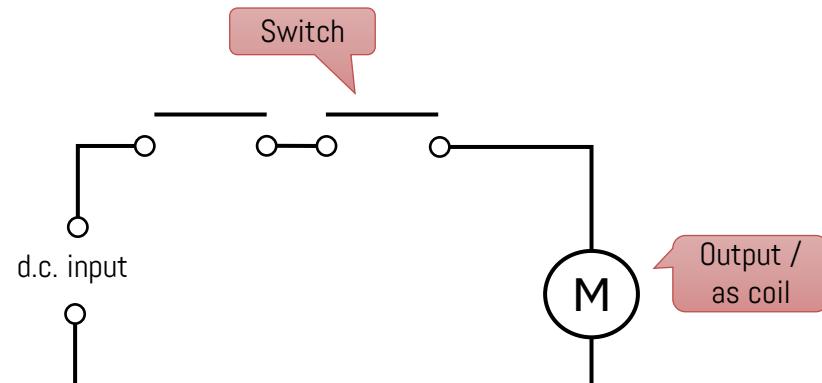
# Ladder and ST AND



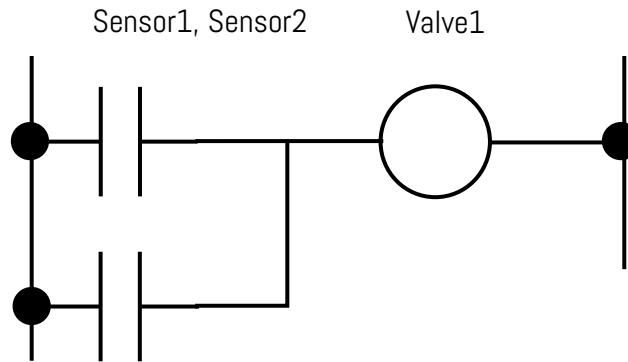
```
IF Sensor1 AND Sensor2 THEN;  
    Valve1 := TRUE;  
ELSE  
    Valve1 := FALSE;  
END_IF;
```



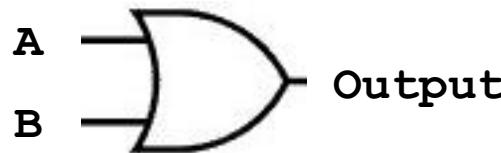
		Output
A	B	
0	0	0
0	1	0
1	1	1
1	0	0



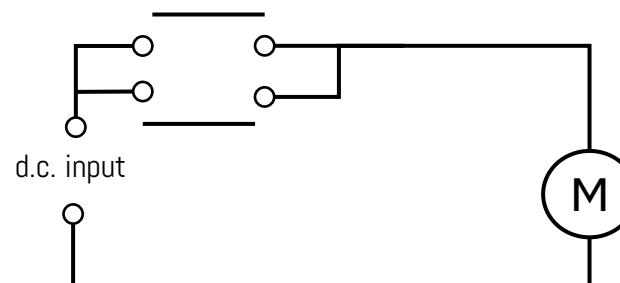
# Ladder and ST OR



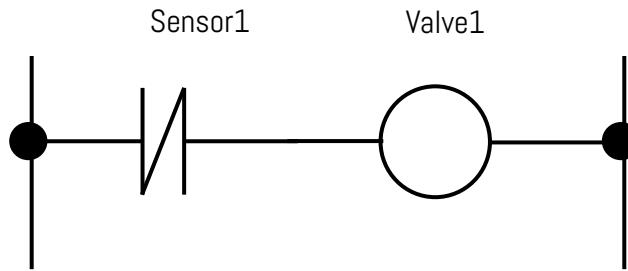
```
IF Sensor1 OR Sensor2 THEN;  
    Valve1 := TRUE;  
ELSE  
    Valve1 := FALSE;  
END_IF;
```



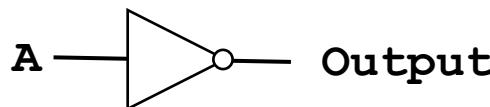
		Output
A	B	Output
0	0	0
0	1	1
1	1	1
1	0	1



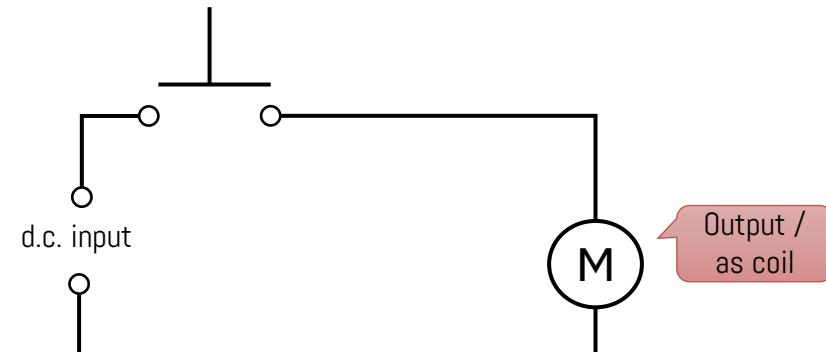
# Ladder and ST NOT



```
IF NOT Sensor1 THEN;  
    Valve1 := TRUE;  
ELSE  
    Valve1 := FALSE;  
END_IF;
```

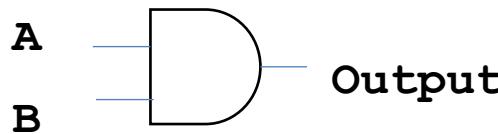


A	Output
0	1
1	0



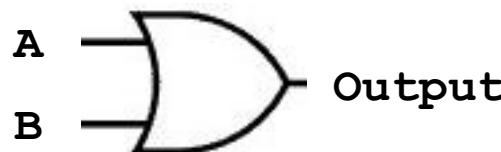
# Boolean algebra

›  $A * B = \text{Out}$

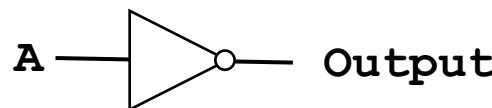


		$A * B$
A	B	
0	0	0
0	1	0
1	1	1
1	0	0

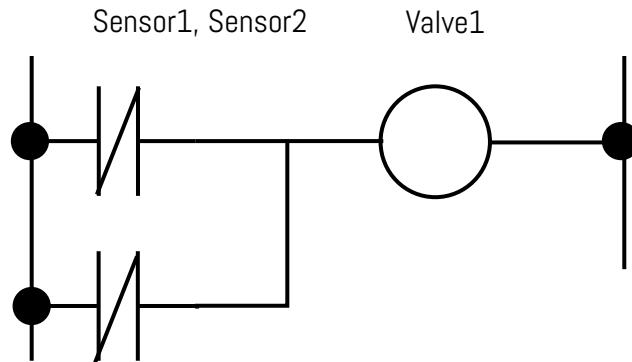
›  $A + B = \text{Out}$



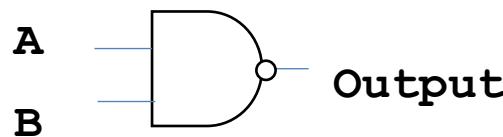
›  $\bar{A} = \text{Out}$



# Ladder and ST NAND



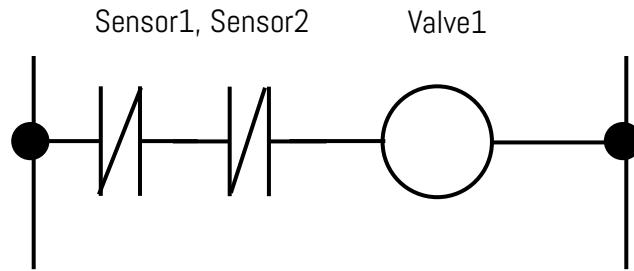
```
IF NOT Sensor1 OR NOT Sensor2 THEN;  
    Valve1 := TRUE;  
ELSE  
    Valve1 := FALSE;  
END_IF;
```



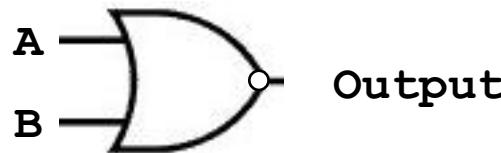
		Output
A	B	
0	0	1
0	1	1
1	1	0
1	0	1

```
IF Sensor1 AND Sensor2 THEN;  
    Valve1 := FALSE;  
ELSE  
    Valve1 := TRUE;  
END_IF;
```

# Ladder and ST NOR



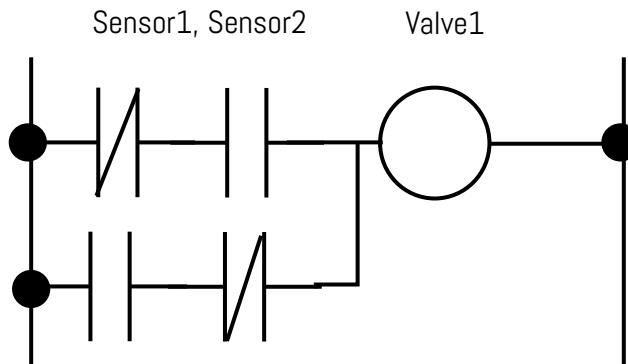
```
IF NOT Sensor1 AND NOT Sensor2 THEN;  
    Valve1 := TRUE;  
ELSE  
    Valve1 := FALSE;  
END_IF;
```



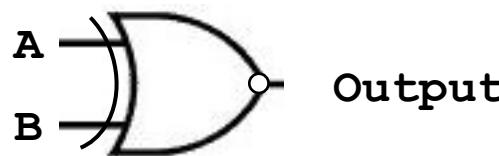
		Output
A	B	
0	0	1
0	1	0
1	1	0
1	0	0

```
IF Sensor1 OR Sensor2 THEN;  
    Valve1 := FALSE;  
ELSE  
    Valve1 := TRUE;  
END_IF;
```

# Ladder and ST XOR



```
IF (Sensor1 AND NOT Sensor2)
    OR (NOT Sensor 1 AND Sensor2)
THEN;
    Valve1 := TRUE;
ELSE
    Valve1 := FALSE;
END_IF;
```



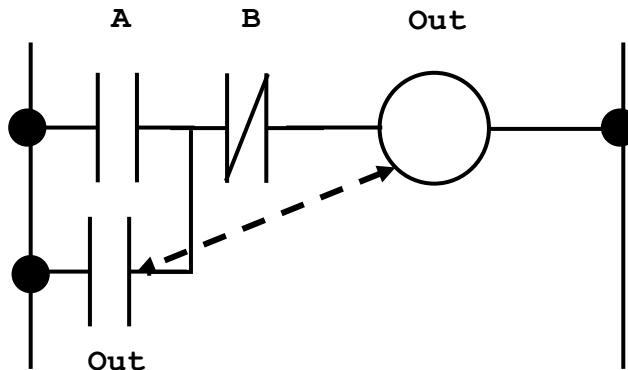
		Output
A	B	
0	0	0
0	1	1
1	1	0
1	0	1

# Latching

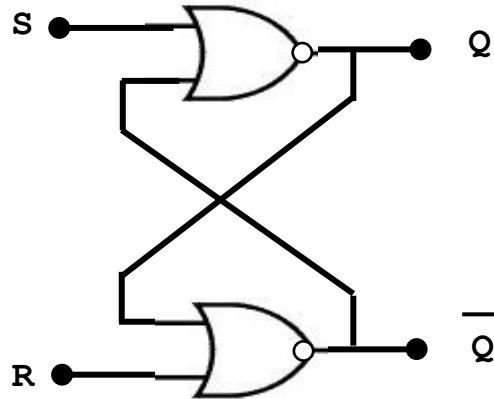
- › We often need to store in memory a value (e.g. a bit)
  - I.e., to store a **state**
- › Can implement it with NANDs, or NORs

## SR Latch circuit

- › When **A** closes ('1'), **Out** coil gets energy ('1')
- › Also, **Out** contact closes, so, even if **A** opens ('0'), the "OR" keeps the **Out** coil powered ('1')
- › Until the NC **B** contacts closes ('0'). Then the **Out** coil becomes '0'

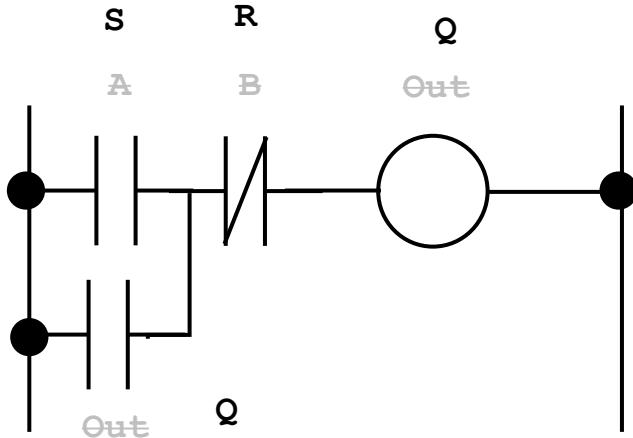


# Latch with NOR

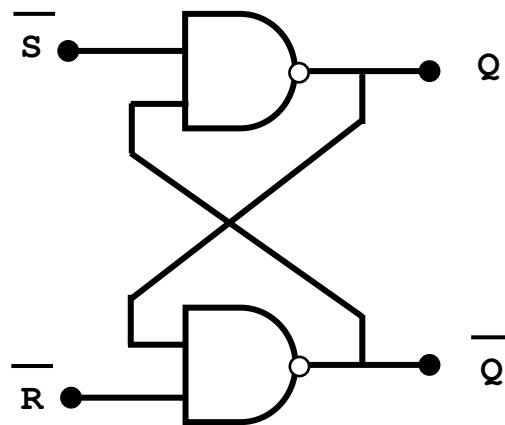


We also have the negate available for free!

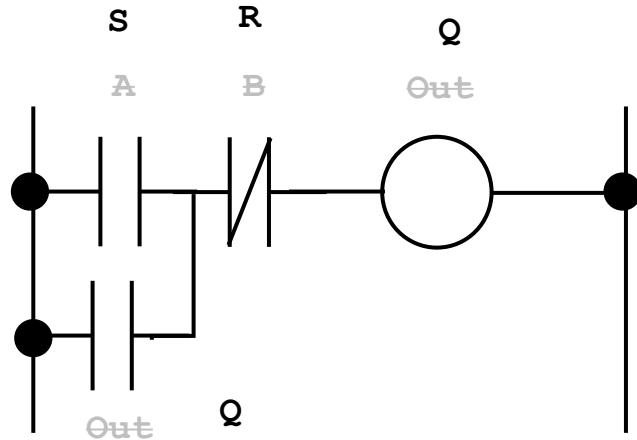
		Q	
S	R	LATCH	
0	0	0	Memory
0	1	0	Reset
1	0	1	Set
1	1	-	Not legal



# Latch with NAND



S	R	Q
0	0	-
0	1	0
1	0	1
1	1	LATCH



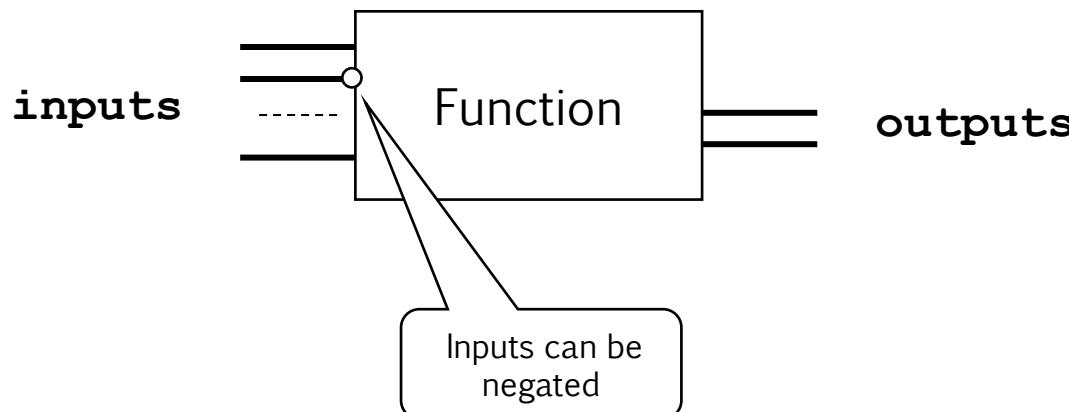
# Functional Block Diagrams

# Function blocks

Enable us grouping a functionality in a reusable elements

- › "aka": function ☺
- › Multiple inputs, multiple outputs
- › Standard-defined functions vs. user-defined functions

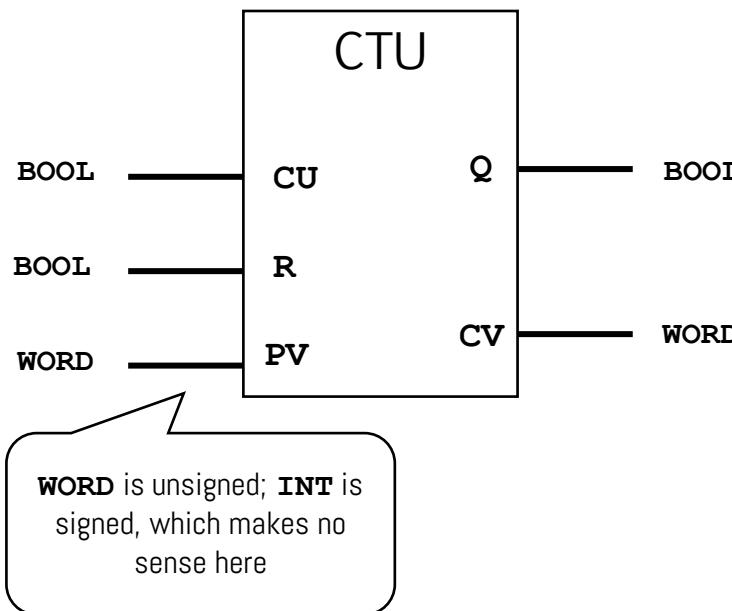
IEC 61131-3 defines them graphically as



# Standard blocks: CTU

Up counter **CTU**

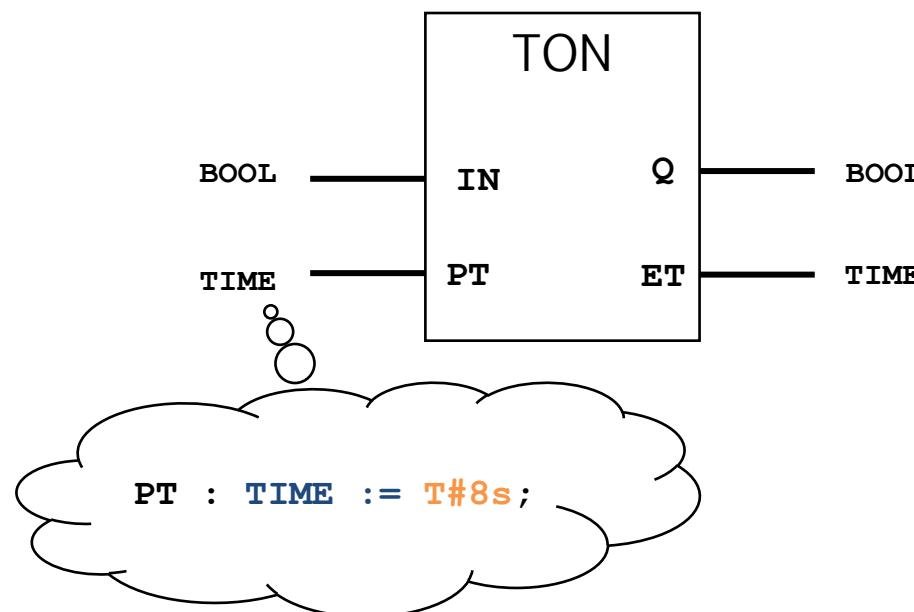
- › Gives output **Q** when *input pulse CU* reaches the *set value PV*
- › Reset input **R**
- › Also, every time **Q** is set, **CV** is incremented



# Standard blocks: TON

## Timer ON TON

- › Output **Q** has a rising edge when internal timer has value “time to pass” **PT**
- › Starts when **IN** has a rising edge, resets when **IN** has a falling edge
- › Also, *Elapsed Time* **ET** keeps trace of time



# Defining our own Function Blocks

- › Here, written in ST
- › Define function to reuse code
- › Define in, out, internal vars



```
FUNCTION_BLOCK MyFb

VAR_INPUT (* Inputs *)
(* ... *)
END_VAR;

VAR_OUTPUT (* Outputs *)
(* ... *)
END_VAR;

VAR (* Internal *)
(* ... *)
END;

(* Instructions here *)

END_FUNCTION_BLOCK;
```

# References



## Course website

- › [http://hipert.unimore.it/people/paolob/pub/Industrial\\_Informatics/index.html](http://hipert.unimore.it/people/paolob/pub/Industrial_Informatics/index.html)

## My contacts

- › [palo.burgio@unimore.it](mailto:palo.burgio@unimore.it)
- › <http://hipert.mat.unimore.it/people/paolob/>

## Resources

- › W. Bolton, "Programmable Logic Controllers", 6th edition, Newnes
- › "Industrial informatics" course by Proff. Vezzani and Pazzi @UNIMORE
- › A "small blog"
  - <http://www.google.com>