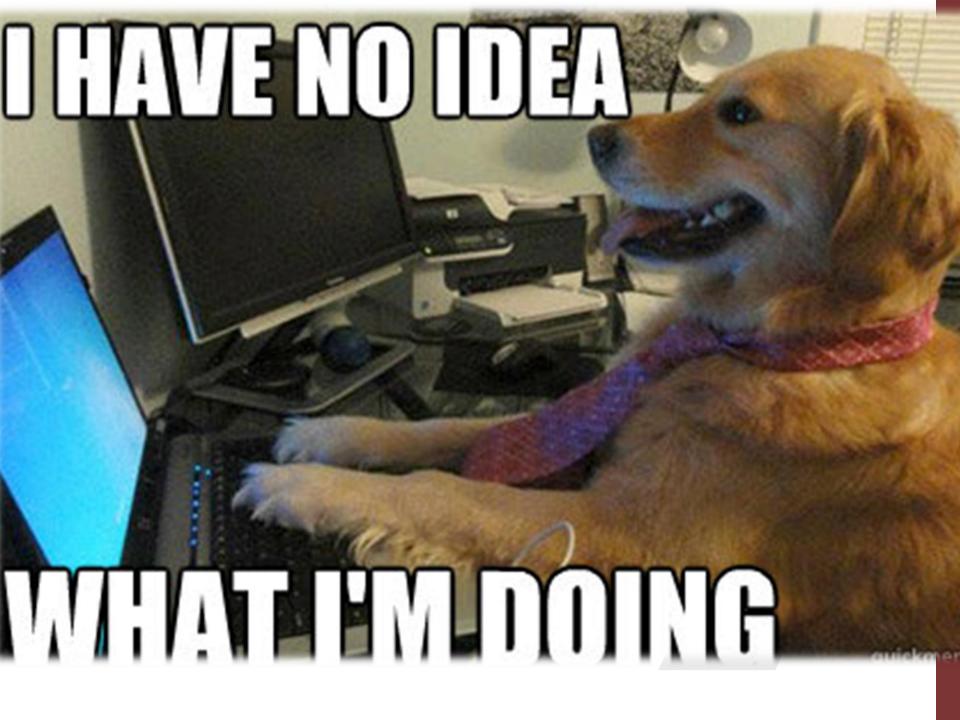
Industrial processors

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Industrial computing continuum

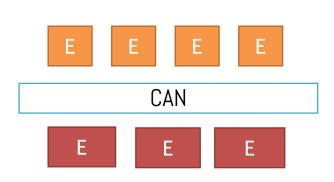
A modern design: in the past might have been different!

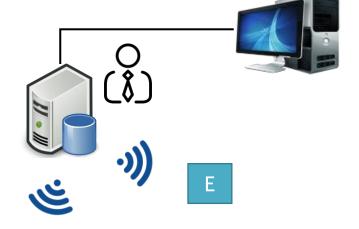
- > Embedded (edge) devices for plant control
- > Centralized aggregator or intermediate fog nodes

Connectivity via industrial standards

- > Wired: flexray, CAN (automotive), serial, (RT-)Ethernet
- > Wireless: WiFi, (soon) 4/5G due to the rise of IoT





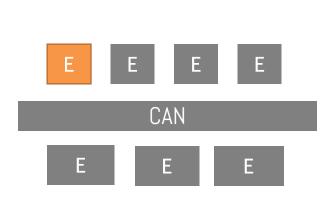


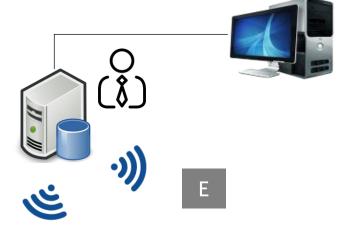


Requirements for industrial edge devices

- > Low cost and form factor might be key feature
 - ...we can trade performance for that
 - Reliability, dependability, safety, security, certifications....
 - Reduced Size, Weight and Power (SWaP)
- > Might be costly to update your plant to a new generation of processors
 - Several companies rely to old technologies (also, software tools!!)
 - Electrical/electronic/informatic engineers in 80s/90s
 - Moore's law runs fast









Families of edge processors

As opposite to GP/desktop systems, where more or less we know "who won"...

- Micro Controller Units MCUs
- > Digital Signal Processors DSPs
- > Micro Processor Units MPUs
- > Programmable Logic Controllers PLCs



More recently, heterogeneous architectures

- > Multi-core host + accelerator
- > Many-core processor, such as GPGPUs (but not only....)
- > Field-Programmable Gate Arrays FPGAs





Micro Controller Units

Lowest end that we will see

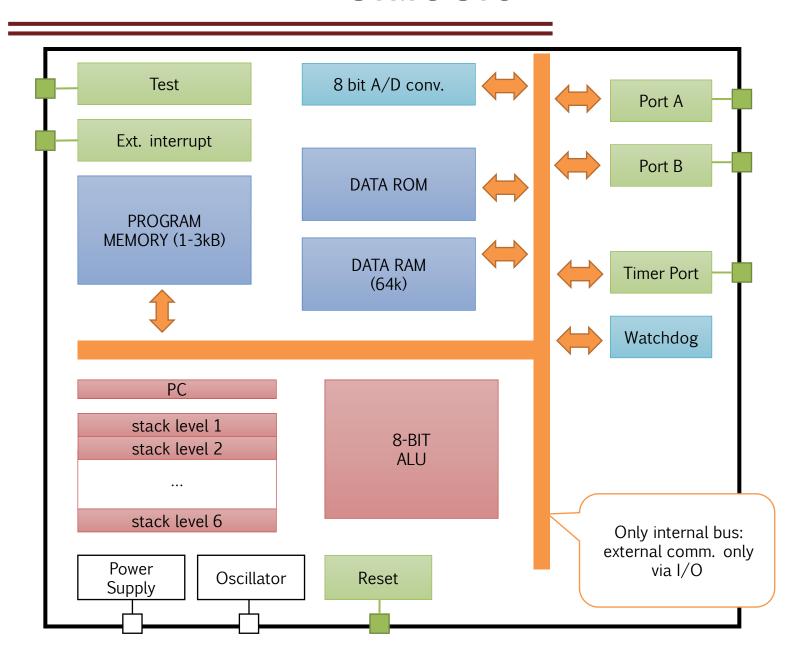
- > 8, 16, 32-bit processors, limited memory
- > Designed for I/O interaction, can poorly do more
- Also, programmability might suffer (ASM)

We will see (and play with)

- > ST Microelectronic's SC6
- > Arduino's first family
- > Expressif's ESP8266 => ESP32 (NodeMCU)
- > Raspberry PI
- > STM IoT Node



STM's ST6





Watchdog



Checks whether a program process processor is stuck, e.g., in deadlock, or infinite loop

In MCUs/single core, single thread machines it is a problem

- > A watchdog circuit is basically a x-bit counter
- > It must be manually reset every $\frac{2^x}{y \cdot 10^6}$ seconds (y = clk in Mhz) by software
- > Else, it "takes care of the situation"
 - Typically => full reset



Modern system does not actually block the full machine (SW managed) nor resets it

- > Multi-processing
- > Preemption (we'll see..)
- > OS-level controls on processes



Memory space

This is what programmers "see"

- Non-physical, here, abstracts the HW blocks
- > != virtualized ©

Program data (variables, ..) are in data RAM

- > Stack, heap (..?)
- ...if we could use high-level languages! (e.g., C)
- > Might be necessary to work in ASM

Data memory

Empty

DATA (ROM, EEPROM)

Internal registers

Data RAM

I/O ctrl registers

A/D converter Timer I/O ports NMI interrupt Reset Watchdog

Program memory

Empty

Reserved

User program (ROM, EEPROM)

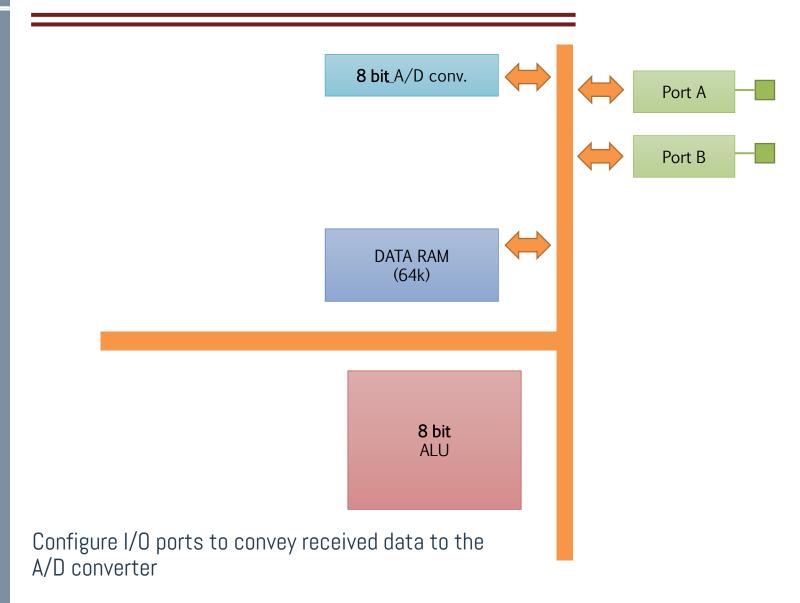
Reserved

Interrupt vectors:

A/D converter
Timer
I/O ports
NMI interrupt
Reset



A/D converter



> Use memory-mapped registers

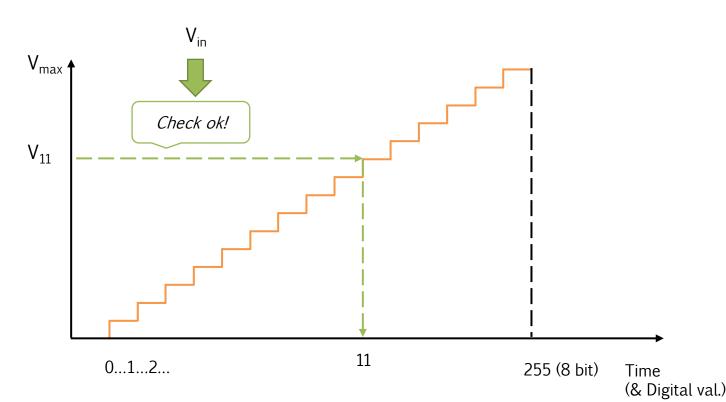


A/D conversion

8 bit A/D conv.

Using the internal wave generator of A/D module, our program

- Generate a signal with increasing V_{in} (y-axis)
- > Compare (in HW) it with the V received by the analog I/O port
- > When equals, assign the corresponding digital value (x-axis)





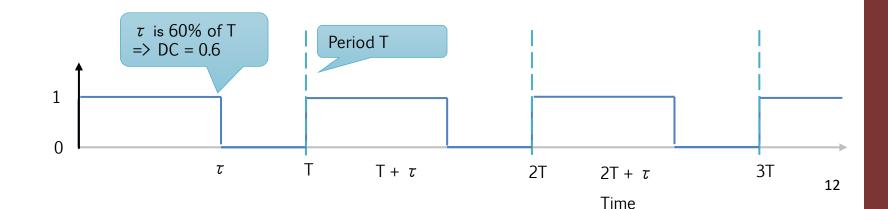
D/A conversion

Generate a tension corresponding to a digital value stored in a register

- > Not easy! Use Pulse-Width Modulation (PWM)
 - (Almost) fully implementable in SW!

How it works

- 1. Generate a periodic signal of amplitude 1 whose **duty cycle** is proportional to the digital value we want to convert
- 2. Give it to a low-pass filter, to average (such as Resistor-Capacitor RC circuit)
- 3. ..and enjoy your analog signal! ©

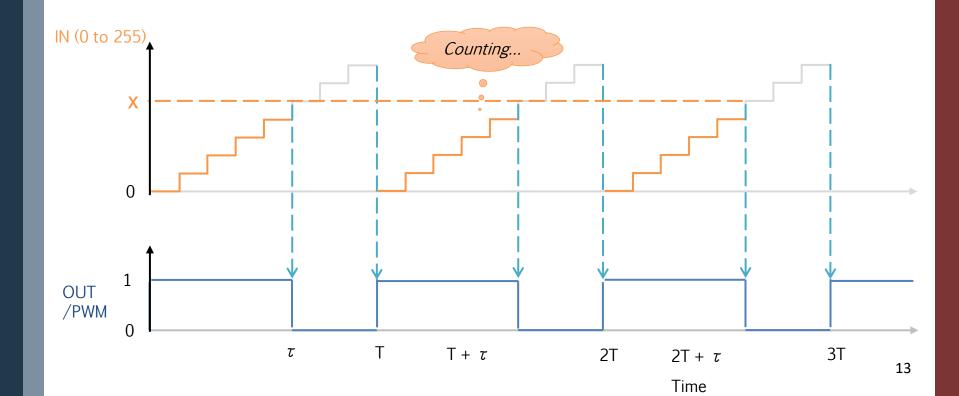




PWM - step 1

We need

- > A register that counts from 0 to 255 (8-bit)
- > An output port (bit) set to '1' and becoming '0' when input value matches the one of the register





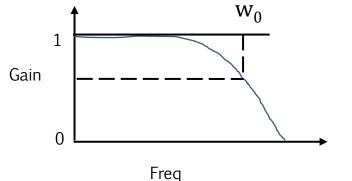
RC low-pass filter

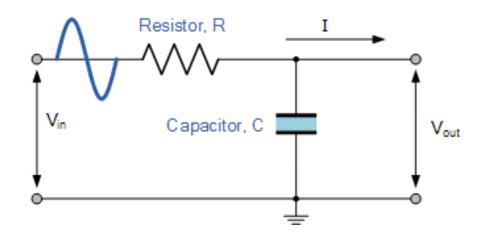
Simple electric circuit with a Capacitor and a Resistance

> "Averages" the IN value

$$|V_{out}| = |V_{in}| \times \frac{1}{\sqrt{1 + w^2 R^2 C^2}}$$







Cutoff freq
$$w_0 = \frac{1}{RC}$$

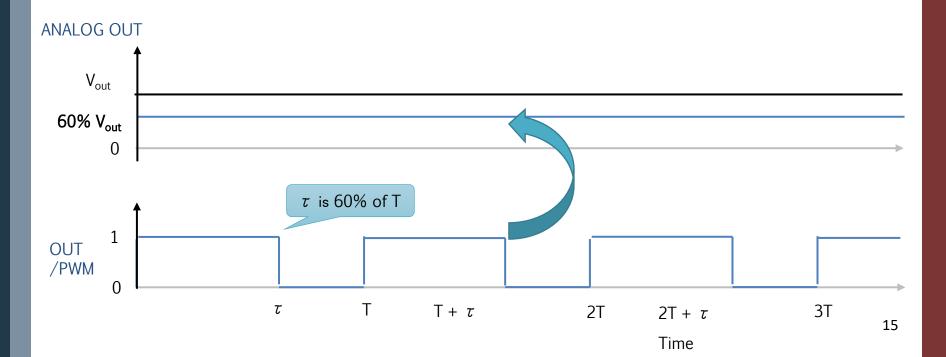


PWM - step 2

Now, compute the average for every T

- > Using a low-pass filter
- > Plug it to output port
- > Et voilà

Extremely useful in engine controls





Application-Specific HW - Digital Signal Processors

A family of MCUs explicitly designed for digital signal processing

> We have A/D converters..

Example: Digital Finite Impulse Response filter (FIR)

 \rightarrow Computes the weighted sum of N timing samples of a discrete signal x

$$y_n = a_0 \cdot x_n + a_1 \cdot x_{n-1} \dots a_N \cdot x_{n-N}$$

$$y_n = \sum_{i=0}^{N} x_{n-i} \cdot a_i$$

- > Typically, discrete time series
- > N is also called *order* and specifies "how much in the past" we go



How to implement it?

$$y_n = a_0 \cdot x_n + a_1 \cdot x_{n-1} \dots a_N \cdot x_{n-N}$$

- Assume time series...)
- > We can't accumulate multiplied values, as every sample is multiplied with a different coefficient a
- > We can keep a buffer in memory of the last N-1 samples, and slide on it (aka: sliding window)

Compute multiplications in parallel, then sum

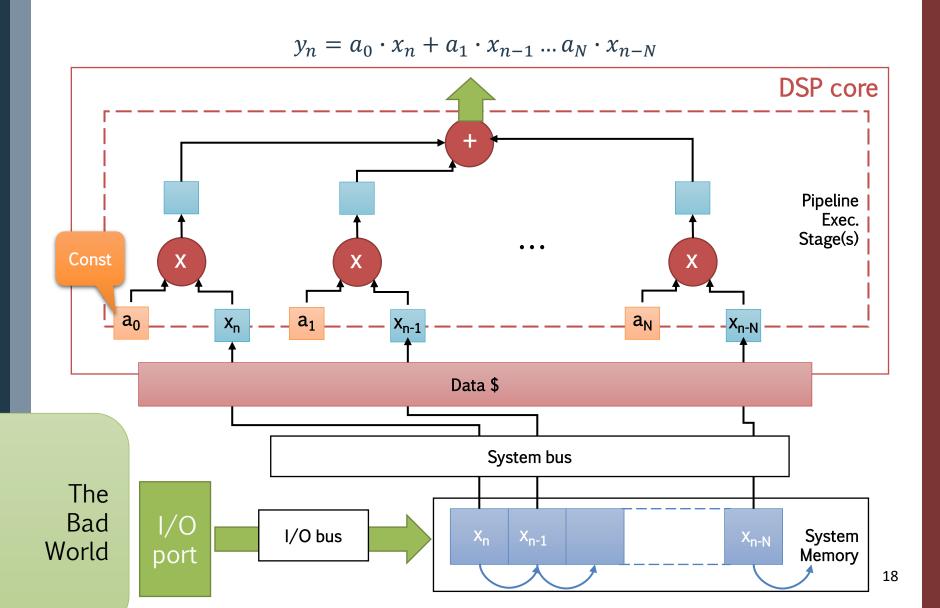
- > Parallel programming patterns: reduction, data parallelism
- The principle behind GPUs!

Assuming that

- > We have a N-wide execution pipeline
- > Our memory bandwidth can read N samples in parallel
- > Else, we create stages



Data-parallel FIR





DSP typical ingredients

Like standard MCUs...but...

- > Wide and simple pipeline for data parallelism
 - Multipliers, accumulators
- > Wide data bus to avoid staging
 - Similar problem also for exec pipeline, but it's it's much more exacerbated in busses!
- > Fast I/O and A/D, D/A conversion
 - Typically, interacts with the world Cyber-Physical System CPS

Often, problem-dependent architecture

- Clock frequency depends on how fast is input data sampling
- Register size (16, 32-bit) and data type (fixed, double) depends on the signal we want to process

A recent example: Texas Instrument's Keystone II



Limits of MCUs

As complexity of applications grows....

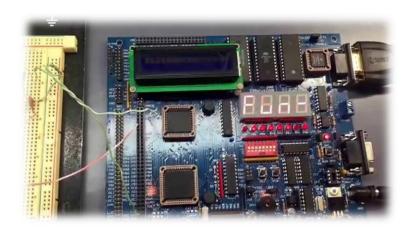
- > 8-bits might not be enough to capture wide data dynamics
- > Limited memory size
- > Poor programmability
 - In the worst case, assembly
- > Poor extendibility
- > Industry can stand more consuming, costly and bulky edge computers
 - Traded for performance



Micro Processor Units - MPUs

Motorola 68HC11

- > Embed "standard" processors
 - 16... 32... 64 bit
 - Also, Intel!
 - Advanced RISC Machines (ARM) is the big guy here
- > Desktop-like memories and programmability
 - C, C++..
- > Rich I/O and connectivity
 - A/D, D/A, watchdog..
 - Support for industrial-grade fieldbusses such as CAN
 - Traditional connectivity (ETH, Wireless..)
- > Typically, built to be mounted in racks
- > Easily extendable
 - Arduino, Raspberry Pi are very simple, low-cost samples
 - ExpressIF's ESP8266 (NodeMCU) and ESP32





Programmable Logic Controllers - PLCs

Designed for industrial controls

> Drive electricity via relays

Typically have

Central processing units

+

> Rich set of actuation interfaces the plant



PLC SIMATIC S7-1500

Used to build wide SCADA systems

> Supervisory Control And Data Acquisition



Programmable Logic Controllers - PLCs

Programmed via

- > Ladder diagram
 - Electrical diagrams
- > Structured Text ST
 - Similar to Pascal/VB
- > Function Block Diagram FBD
 - System level integration



PLC SIMATIC S7-1500

We will not see...

- > Sequential Functional Chart SFC
 - Petri-net style
- > Instruction List IL
 - ASM-like



References



Course website

http://hipert.unimore.it/people/paolob/pub/Industrial_Informatics/index.html

My contacts

- > paolo.burgio@unimore.it
- http://hipert.mat.unimore.it/people/paolob/

Resources

- > Alessandro Fantechi, «Informatica Industriale», Città Studi Edizioni
- > Giacomo Bucci, «Calcolatori elettronici: architettura e organizzazione», McGraw-Hill Education
- A "small blog"
 - http://www.google.com