PLC programming

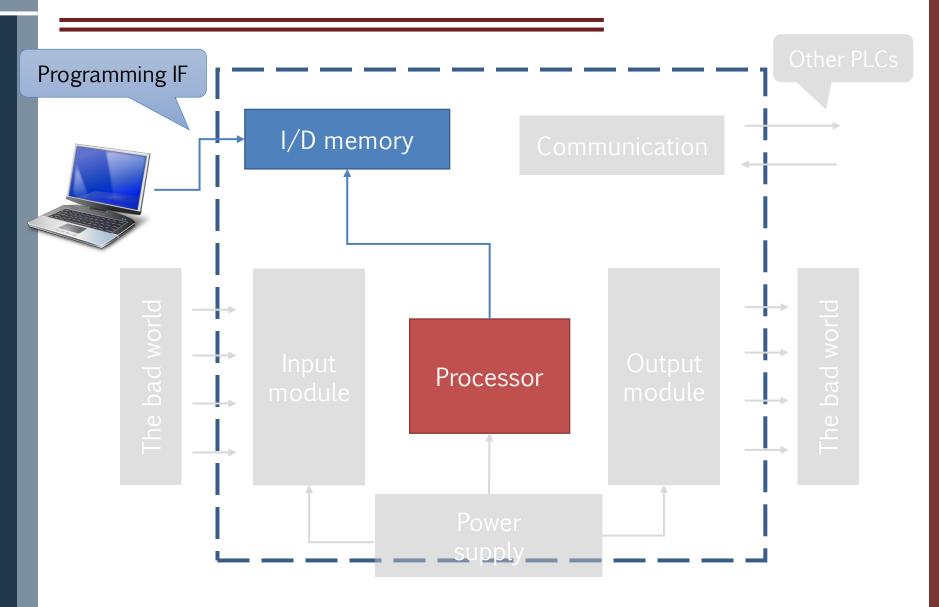
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Structure of a PLC





PLC programming with IEC 61131

First attempt of standardization => <u>IEC 61131-3 standard</u>

- > yr 1993, latest rev 2013
- > Before that, "the fish market" of languages
- > Still, Ladder was a prominent one...but everyone had its own variant!!

States that there are 5 "standard" ways of programming PLCs

- > Ladder diagram
 - Description of electrical wiring, designed for non-informatics
- > Function Block Diagram FBD
 - From electronics
- > Sequential Functional Chart SFC
 - Petri-net style
- > Instruction List IL
 - ASM-like
- > Structured Text ST
 - Similar to Pascal/VB



IEC 61131

Covers the complete lifecycle of PLC modules and sw development for PLC PLC programming

- > Part 1: Definition of <u>terminology</u> and concepts
- > Parte 2: Electronic and mech equipment and verification/testing
- > Part 3: programming languages (5 types)
- > Part 4: how to choose, install and maintain
- > Part 5: how to <u>communicate</u> (MMS Manufacturing Messaging specification)
- > Part 6: communication via fieldbusses/other ind. Standards
- > Part 7: Fuzzy control (won't see this..if you don't want)
- > Part 8: sw dev guidelines

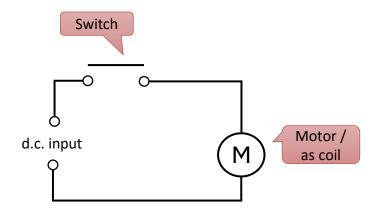
Ladder

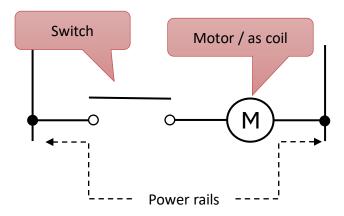


Ladder diagrams

Possible circuit to power on a motor

- > Left: electrical diagram; right: Ladder
- > Does it remind of something...?







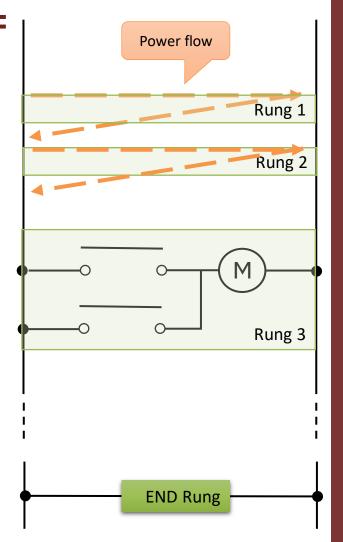
Ladder programs

Writing a program is as easy as writing a switching circuit

- Vertical lines are power rails, and power flows from top-left to bottom-right
 - So does "program flow"
- Horizontal lines (rungs) connect power rails
 - Every rung starts with one or more inputs, and ends with exactly one output
- Typical exec time: 1ms for 1k bytes of program, so usually approx 10-50ms

Program flow

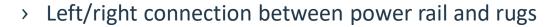
- Store input status in mem
- mem
- Read inputs from memory, run program, store out in

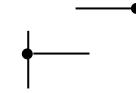




Ladder symbols

- > Power rails (Vert lines)
- > Rugs (Horiz lines)

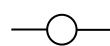




- > Dual connection
- > Normally open (NO) contact —
- > Normally closed (NC) contact



> A switch

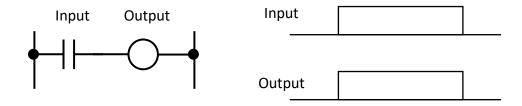




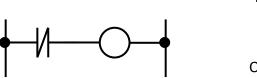


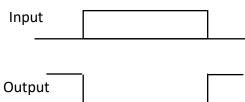
Example: a (lamp?) witch

> When a NO contact is closed, the attached coil propagates the signal



> When a NC contact is opened, the attached coil propagates the input signal







Structured Text



Structured text

- > Inspired by Pascal language, also Basic and VB programmer might find it familiar
- > Procedural language (can define Functions, and Function Blocks)
- > Or define a Program (and call it from within your Application MainTask)



Defining variables

Can also initialize them

> Don't forget semicolon;

IEC 61131.3 defines several datatypes

> Few examples

Contact1: BOOL;
Contact2: BOOL := FALSE;

IEC Data Type	Format	Range
SINT	Short Integer	-128 127
INT	Integer	-32768 32767
DINT	Double Integer	-2^31 2^31-1
UINT	Unsigned Integer	0 2^16-1
BOOL	Boolean	1 bit
BYTE	Byte	8 bits
WORD	Word	16 bits
STRING	Character String	'My string'
TIME	Duration of time after an event	T#10d4h38m57s12ms TIME#10d4h38m
DATE	Calendar date	D#1989-05-22 DATE#1989-05-22
REAL	Real Numbers	±10 ^ ±38



Variables: simple operations

Assigning variables

```
Contact1 := FALSE;
Input1 := 11;
Output1 := 5;
```

Contact1: BOOL;
Input1: INT;
Output1: BYTE;

> Also, with operators in R-values

```
Output1 := Input1 - Output1 / ( Input6 + 3);
```





Structured Text Operators (and their priority)

Operators	Description
()	Parenthesized (brackets) expression
Function ()	List of parameters of a function
**	Power
-, NOT	Negation, Boolean NOT
* , / , MOD	Multiplication, division, modules operations
+, -	Add, subract
< , > , <= , >=	Comparison
=, <>	Comparison
AND, OR	Boolean operator
XOR	Exclusive OR
OR	Boolean OR





Define your own datatypes

```
(* Enum-like datatype *)
TYPE Motor:( Stopped, Running);
END_TYPE;
```

```
(* Analog value datatype *)
TYPE Pressure: REAL ;
END_TYPE;
```



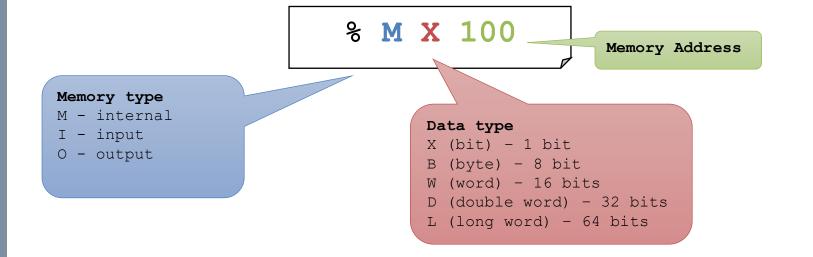
Variables: nomenclature

- > ST is not case sensitive; in case you might want to use capital letter for clarity
- > Use the AT keyword to fix the memory location of a variable

```
Contact1: BOOL AT %MX100; (* Internal memory Bit at address 100 *)

Input1: INT AT %IW200; (* Input memory Word at address 200 *)

Output1: BYTE AT %OB300; (* Output memory Byte at address 300 *)
```





If-Then-Else

```
IF Contact1 = TRUE THEN;
   Coil1 := TRUE;
ELSE;
   Coil1 := FALSE;
END_IF;
```

```
IF NOT Contact1 = TRUE;
  Coil1 := TRUE;
END_IF;
```

```
IF Contact1 = TRUE OR Input1 = 11;
  Coil1 := TRUE;
END_IF;
```



Switch-case

- > Multiple instructions on the same line
- > Default with ELSE keyword
- > Can also use ranges

```
CASE (STATE) OF
  1: NEXT_STATE := 2; ERROR := FALSE;
  2: NEXT_STATE := 3; ERROR := FALSE;

ELSE
  NEXT_STATE := 4; ERROR := TRUE;
END_CASE;
```

```
CASE (TEMPERATURE) OF
    0...40: Furnace_switch := ON;
    40...100: Furnace_switch := OFF;
END_CASE;
```



Loops

> For, While-Do, Repeat-Until

```
(* do...
    while (input1 < 3
        && input2 == 5; *)
Output1 := 0;
REPEAT
DO
    Output1 := Output1 + 1;
UNTIL Input1 < 3 AND Input2 = 5
END_REPEAT;</pre>
```



Defining Programs

Read (input vars) – Exec – Write (output vars) paradigm

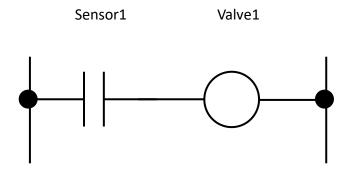
```
(* ... *)

VAR (* Input type, and datatype,
implicit by memory *)
  Temperature AT $IW100;
END_VAR;
(* ... *)
```

```
PROGRAM Example
VAR IN (* Input *)
  Temperature: INT;
END VAR;
VAR IN (* Input *)
  Speed: INT = 50;
END VARS;
VAR OUT (* Outputs *)
 Motor speed: REAL;
END VAR;
(* Instructions here *)
END PROGRAM;
```



Ladder vs. ST



```
Valve1 := Sensor1
IF Sensor1 THEN;
  Valve1 := 1;
END_IF;
```



Function Blocks

> Define function to reuse code

```
FUNCTION BLOCK ExampleFnBlk
VAR INPUT (* Input *)
(* ... *)
END VAR;
VAR OUTPUT (* Output *)
(* ... *)
END VAR;
(* Instructions here *)
END FUNCTION BLOCK;
```

Functional Block Programming

Implementing state machines into IEC 61131



References



Course website

http://hipert.unimore.it/people/paolob/pub/Industrial Informatics/index.html

My contacts

- > paolo.burgio@unimore.it
- http://hipert.mat.unimore.it/people/paolob/

Resources

- > W. Bolton, "Programmable Logic Controllers", 6th edition, Newnes
- "Industrial informatics" course by Proff. Vezzani and Pazzi @UNIMORE
- > A "small blog"
 - http://www.google.com