



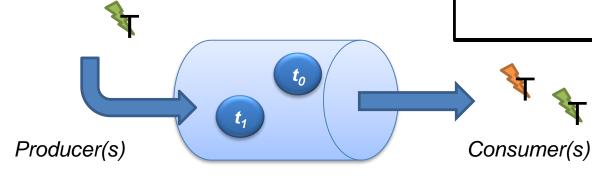
Scheduling on multiand many-cores

Paolo Burgio paolo.burgio@unimore.it



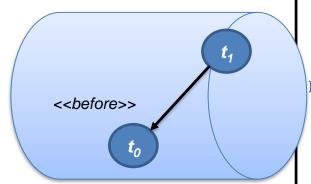
Recall: OpenMP tasks

- ✓ Work queue pool paradigm!
 - Timing de-couple
- Typically, one producer, one consumer
 - Simple
 - More manageable
- ✓ How to do this?





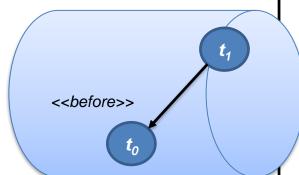
- ✓ A system with two tasks
 - t₀ created before t₁
 - t₁ must execute before t₀
 - Also on single-core system
- ✓ ...sounds familiar?



```
#pragma omp parallel
  #pragma omp single
    #pragma omp task
      t0();
    #pragma omp task
      t1();
   // bar&TSO
 // parreg end
```



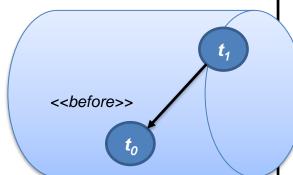
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```
/* Lock var */
omp lock t lock;
#pragma omp parallel
  #pragma omp single
    /* Init as "locked" */
    omp init lock(&lock);
    omp set lock(&lock);
    #pragma omp task
      /* Immediately wait */
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      /* Done: release */
      omp unset lock(&lock);
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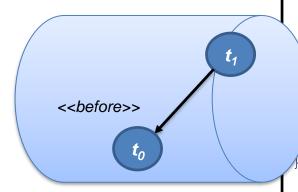
- ✓ A system with two tasks
 - t₀ created before t₁
 - t₁ must execute before t₀
 - Also on single-core system
- ✓ Thread blocked on t₀ will never work on t₁
 - Not enough parallelism in the machine



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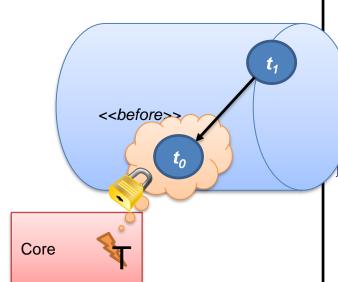
- omp_set_lock is blocking, but
 not a TSP!!
 - There can be thread switch
 - There is NO task switch!
- ✓ Thread is stuck on t0.
- In single-thread systems, deadlock!



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```



✓ omp_set_lock is blocking. but

not a TSP!!

There can be three

There is NO task

✓ Thread is stuck on t0

✓ In single-thread systems, deadlock!

Core

```
/* Wait + TSP */
while(!omp_test_lock(&lock))
{
    #pragma omp taskyeld
}

agma omp task
single
single
s "locked" */
lock(&lock);
ock(&lock);
```

/* Lock var */
omp lock t lock;

#pragma omp parallel

Immediat

```
#pragma omp task
{
    t1();
    /* Done: release */
    omp_unset_lock(&lock);
}
// bar&TSO
// parreg end
```



√ omp set lock is blocking. but

not a TSP!!

There can be three

There is NO task

✓ Thread is stuck on t0

✓ In single-thread systems, deadlock!

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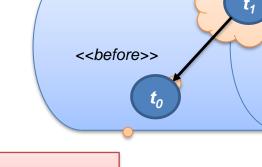
/* Lock var */
omp lock t lock;

#pragma omp parallel

```
/* Immediately wait */
   omp_set_loc. [lock);

   t0();

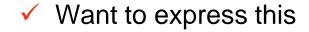
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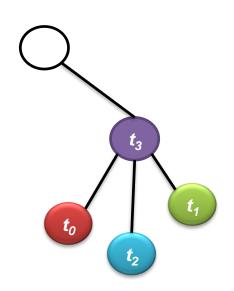


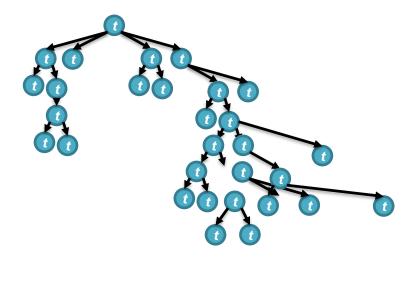


..but we want more!

✓ Instead of this...





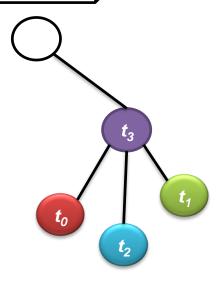


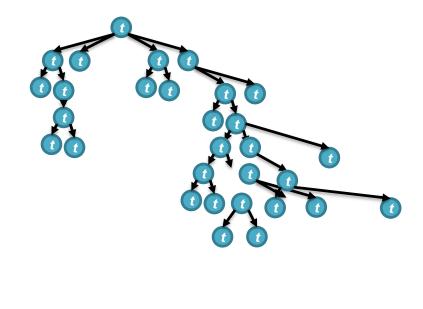


..but we want more!

✓ Instead of this...

✓ Want to express this





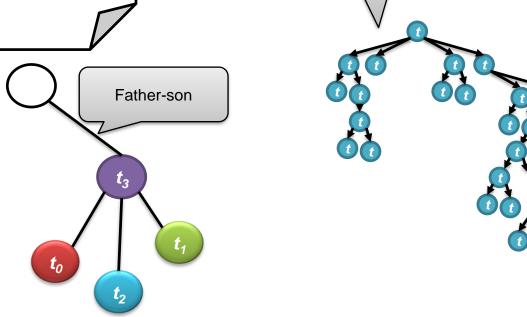


..but we want more!

✓ Instead of this...

Timing

precedence



✓ Want to express this

The depend clause

```
#pragma omp task [clause [[,] clause]...] new-line
  structured-block
Where clauses can be:
if([ task : |scalar-expression)
final(scalar-expression)
untied
default(shared | none)
mergeable
private(list)
firstprivate(list)
shared(list)
depend(dependence-type : list)
priority(priority-value)
```

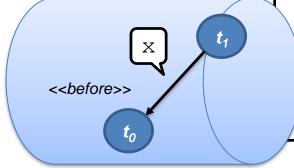
- Expresses dependencies among tasks
 - Tasks cannot proceed until the dependencies are satisfied

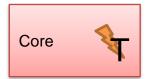


The depend clause

 Set a variable to act as placeholder for the dependency

```
#pragma omp parallel
  #pragma omp single
   // Dependency is represented as a var
   int x = 0;
   #pragma omp task depend(in:x)
      t0();
   #pragma omp task depend(out:x)
      t1();
    // bar&TSO
  // parreg end
```







OpenMP is just a language

- ✓ At the end, OpenMP can be seen as a mechanism!
 - Still, good, but let's move on!
- Use OpenMP to express complex graphs
- ✓ For the sake of completeness, i cheated a bit
 - Also an OpenMP task can be decomposed

```
#pragma omp parallel
#pragma omp single // task TO

p<sub>00</sub> (x=0; y=0;)
   // task T1
   #pragma omp task depend(out:x,y) { p<sub>1</sub> }

p<sub>01</sub>
   // task T2
   #pragma omp task depend(in:x) { P<sub>2</sub> }

p<sub>02</sub>
   // task T3
   #pragma omp task depend(in:y) { P<sub>3</sub> }

p<sub>03</sub>
```



OpenMP is just a language

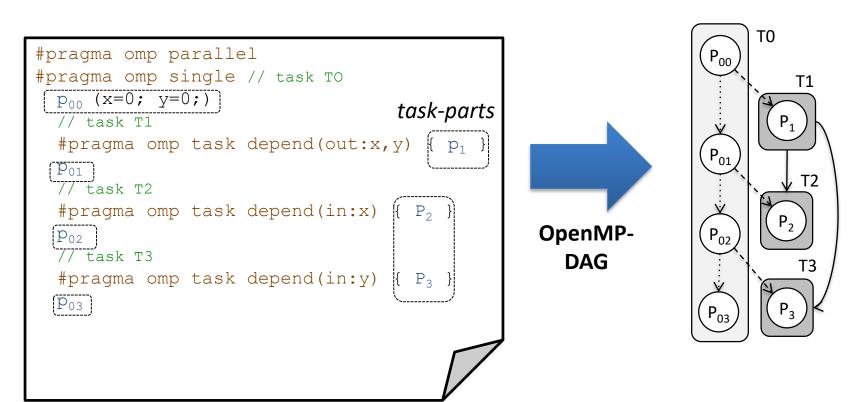
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```
#pragma omp parallel
#pragma omp single // task TO
 p_{00} (x=0; y=0;)
                                     task-parts
  // task T1
  #pragma omp task depend(out:x,y)
  // task T2
  #pragma omp task depend(in:x) { P2
  p_{02}
  // task T3
  #pragma omp task depend(in:y)
 P<sub>03</sub>
```



OpenMP is just a language

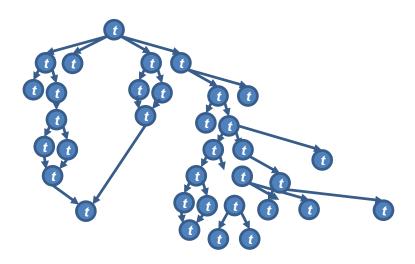
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Directed Acyclic Graphs

- ✓ Nodes are in a parent-children relationship, no cycles (back arcs)
 - No loops!
- ✓ As opposite to, program as a "full" graph
 - Basic blocks in compiler internals
- ✓ In some situations, preferrable for representing the flow of a program
 - Today, we will see mainly these





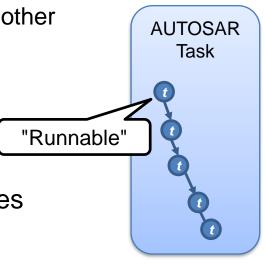
Example: AUTOSAR

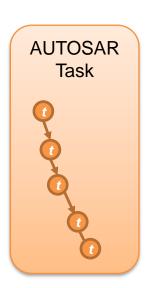


- ✓ Very-well known standard for automotive
 - Clean model
 - Composability of isolated software "AUTOSAR components"
 - Black box" approach
- ✓ AUTOSAR tasks are composed by runnables
 - Runnables are sequential one another
 - Tasks are schedulable to cores
 - A bit complex...

AUTOSAR runnable -> our "task"

AUTOSAR task -> Group of runnables









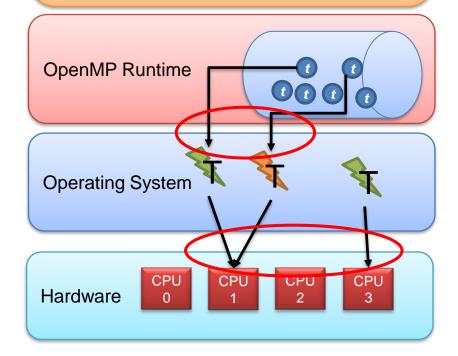


Generic parallel stack

- ✓ For instance, OpenMP lets us specifying
 - Threads in parregs
 - Tasks in a parreg
- ✓ There are two scheduling levels
 - Tasks -> Threads
 - Threads -> Cores



```
#pragma omp parallel
#pragma omp single
#pragma omp task
```

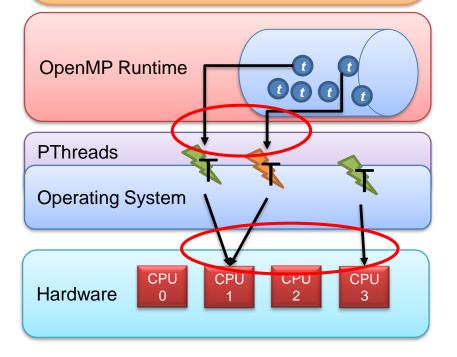




Example #1: OMP + GNU/Linux

- ✓ Example of parallel stack
 - OMP runtime (e.g., GCC-OMP)
 - GNU/Linux w/Pthreads
 - 4 cores

```
#pragma omp parallel
#pragma omp single
#pragma omp task
```

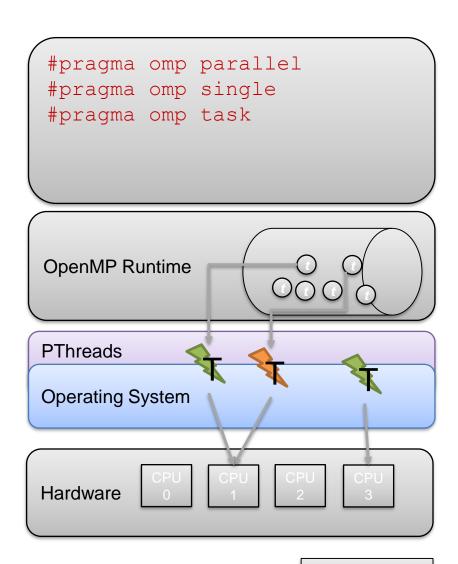




OpenMP-to-OS threading

- ✓ OpenMP runtime creates "OMP threads"
 - Leveraging on OS threads
 - E.g., Pthreads
 - OMP threads <-> Pthread

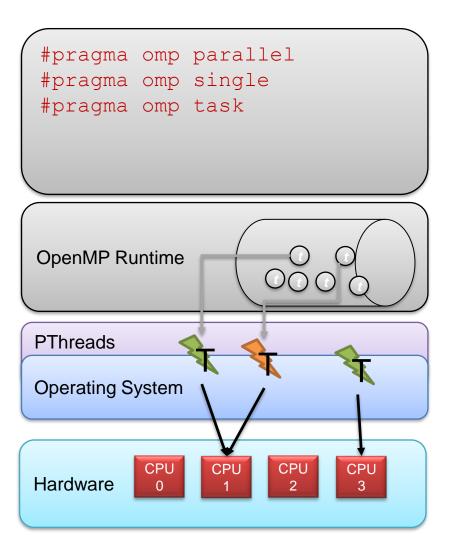
Let's see this!





Thread scheduling

- ✓ OMP threads become OS threads
 - E.g., Pthreads
- Linux has his own thread scheduling policies
- Pthreads layer adds its own!
- Runtime+App have poor control!
 - Only proc bind clause
 - NO notion of priority





Thread scheduling



Generic thread scheduling

✓ Each process (and its threads) can be in one of the following states:

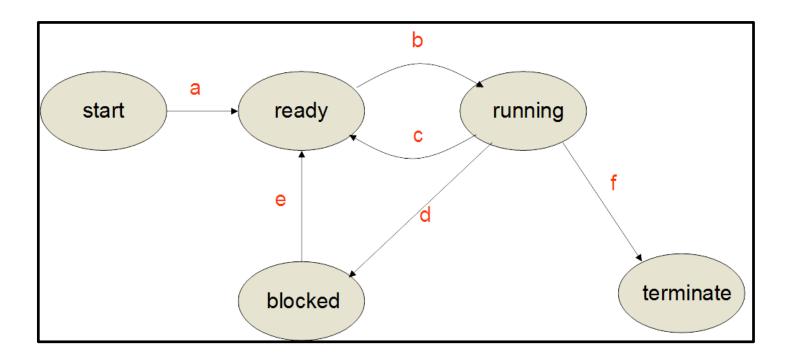
- starting being created (e.g., before main)

ready ready to be executed)

executing executing on a core

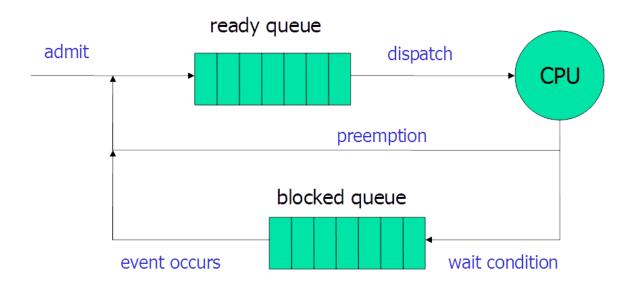
blocked waiting on a condition (e.g., a lock)

terminating about to terminate (e.g., after return)





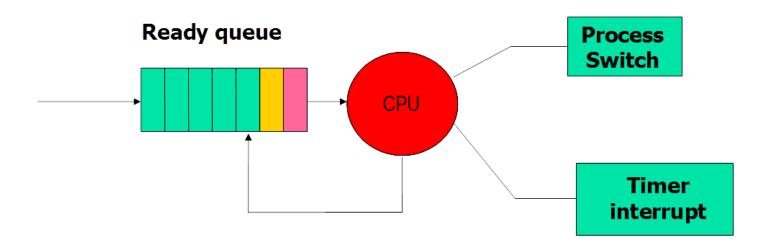
Single processor





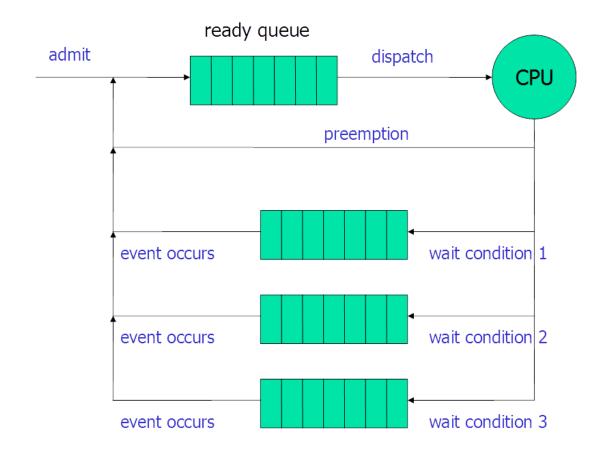
Time sharing: fairness

- ✓ Given a time T (e.g., 1 sec)
- ✓ be sure we allocate the CPU at least T/N, where N = #threads



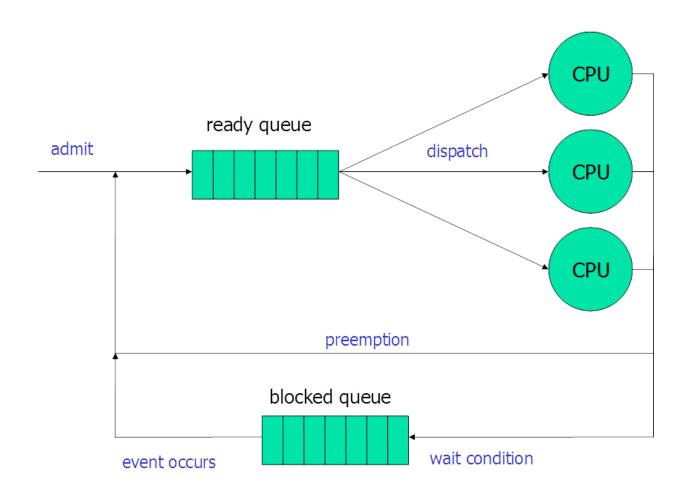


Multi-processor with multiple wait queues



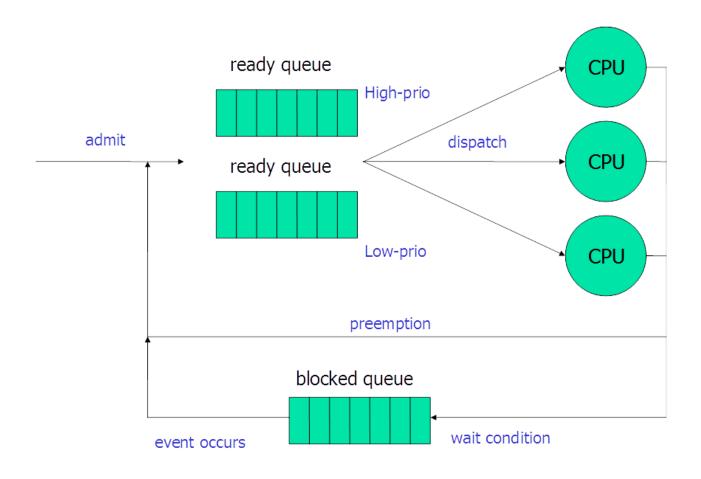


Multi-processor with migration



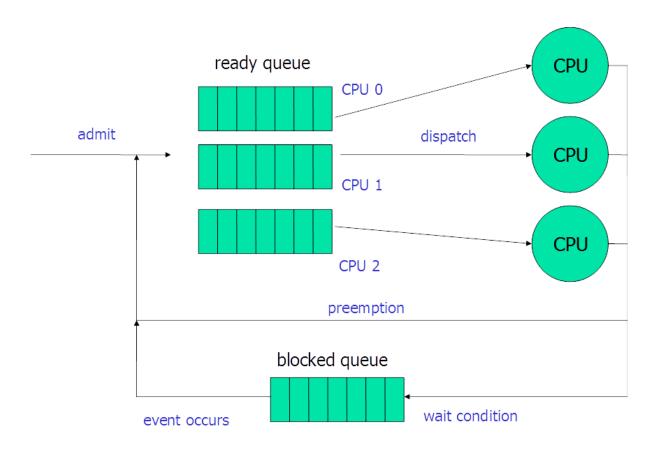


Multi-processor with priorities





Multi-processor with dedicated queues





Linux scheduling policies - recall

- ✓ FIFO
 - High vs. Low priority
- ✓ Round Robin
- ✓ CFS
 - User-space, non real-time
- ✓ BFS
 - Non-real-time
- ✓ sched deadline
 - Molto promettente
 - Real-time
 - Complesso da configurare

Thanks
Francesco
Bellei



Pthreads scheduling

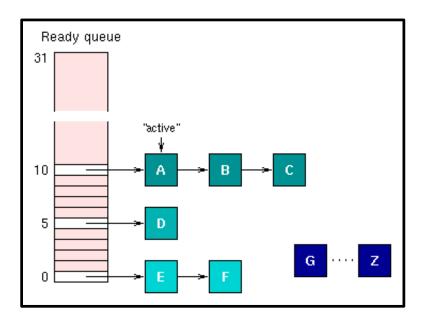
- ✓ The scheduling policy can either be SCHED_FIFO or SCHED_RR.
 - "FIFO is a first come first serve policy. RR is a round robin policy that might preempt threads. But again, the policy only effects threads that have the same priority."
- Realtime Process Scheduling
 - It is also possible to do realtime process scheduling.
 sched setscheduler() is used to set the process scheduling parameters.



Priority + FIFO scheduler

Thanks
Francesco
Bellei

- ✓ First-in first-out (FIFO) scheduling
 - Every thread has a priority
 - "When multiple threads have the same priority level, they run to completion in FIFO order."

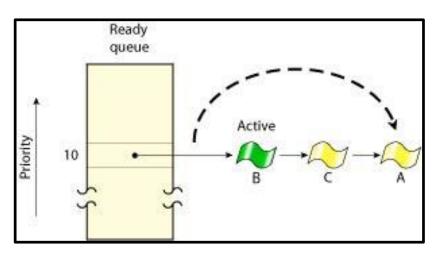




Priority + Round Robin scheduler

- Round-robin (RR) scheduling.
 - Every thread has a priority
 - ..meaning a guaranteed core BW
 - Similar to FIFO, but w/guaranteed bandwidth

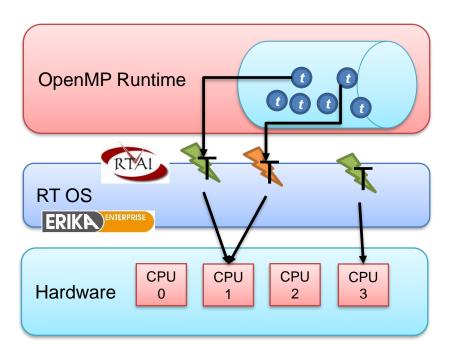
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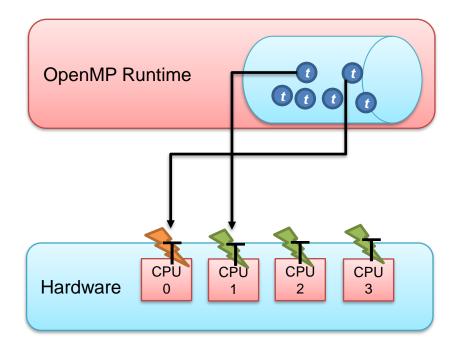




Real-time system

- Requirements: worst-case/guaranteed performance
 - Leverage on a Real-Time OS that has advanced FIFO/Priority policies for Thread-to-core mapping
 - Or..simplest solution: remove thread-to-os mapping
 - Persistent threads







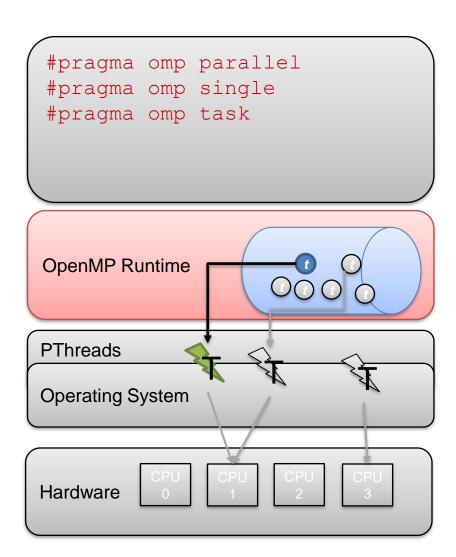
Task scheduling on multi-/many-cores





Task scheduling

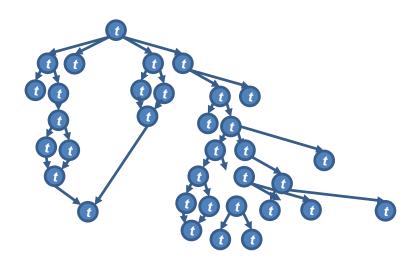
- OMP runtime schedules tasks to threads
 - Typically, every idle threads requests work
 - "Enhanced" FIFO manner
 - In case of taskwait/group,
 might want to execute children first
- Scheduling policy is at Runtime level!
- Runtime also manages task dependencies





Possible implementation

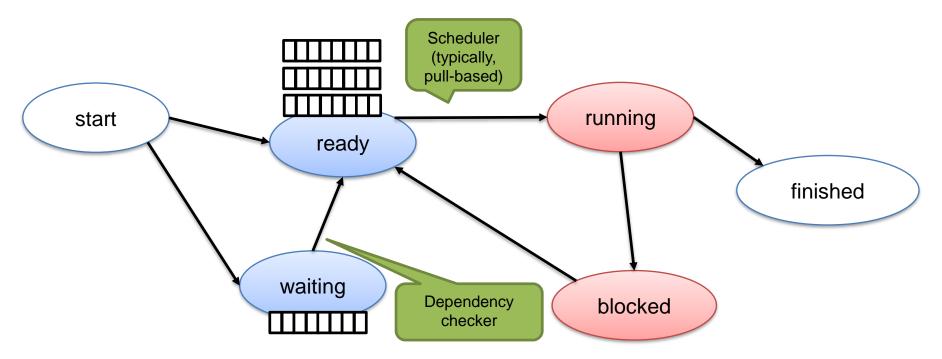
Remember that we also need to manage dependencies





Two levels of queues

- ✓ Similar to Unix threads status
- One for the "waiting" tasks, e.g., whose dependencies has not yet been satisfied
- ✓ One (or more) for the "ready" tasks, that could potentially execute

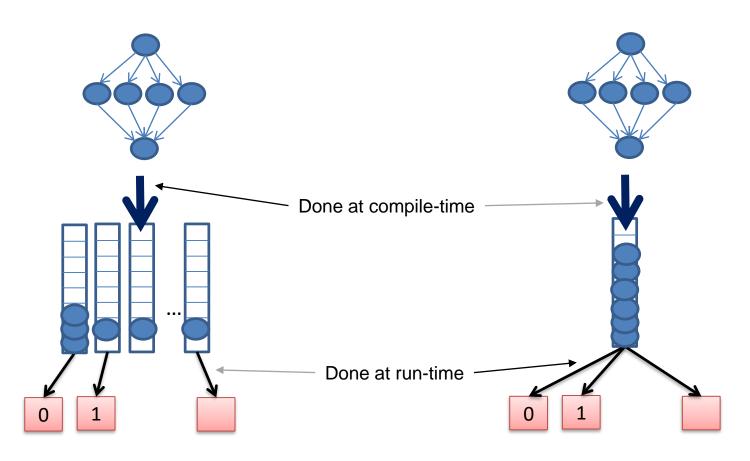




Static vs. dynamic scheduling

- Static/partitioned
 - Guaranteed performance
 - Worst avg performance
 - Real-time/critical systems

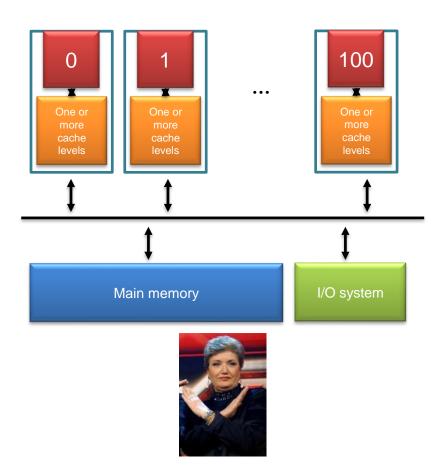
- ✓ Dynamic/global
- Best perf. thanks to work balancing
 - Poor guaranteed performance
 - Linux





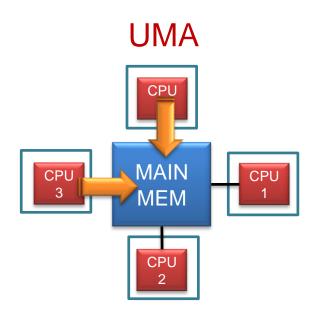
Scaling to many-core

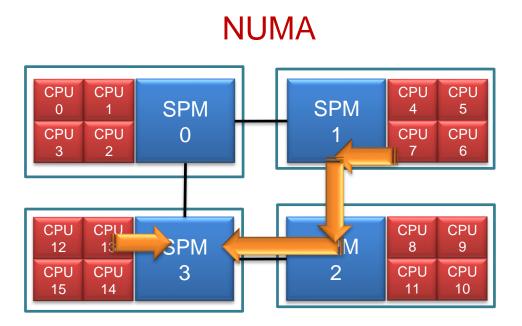
- ✓ For "physical" reasons, it is not possible to build a "flat" system made of more than 20-30 cores
- ✓ Architectural scaling via core clustering (e.g., GPUs)



UMA vs. NUMA

- ✓ Shared mem: every thread can access every memory item.
 - (Not considering security issues...)
- ✓ Uniform Memory Access (UMA) vs Non-Uniform Memory Access (NUMA)
 - Different access time for accessing different memory spaces

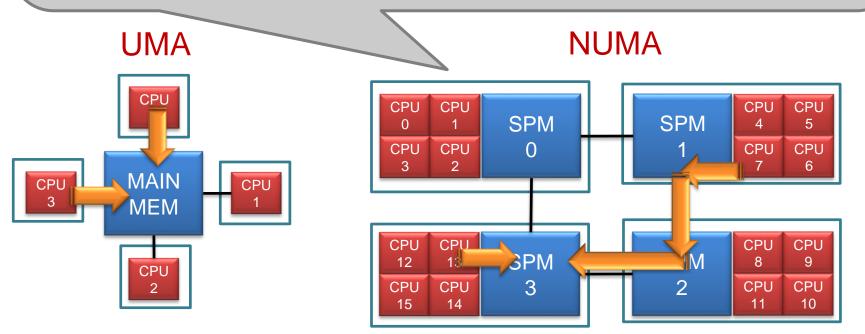






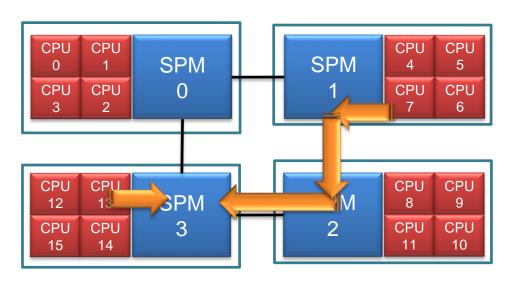
UMA vs. NUMA

Share		MEM0	MEM1	MEM2	MEM3	
– (N Unifo – Di	CPU03	0 clock	10 clock	20 clock	10 clock	/h II IB
	CPU47	10 clock	0 clock	10 clock	20 clock	ess (NUN
	CPU811	20 clock	10 clock	0 clock	10 clock	
	CPU1215	10 clock	20 clock	10 clock	00 clock	



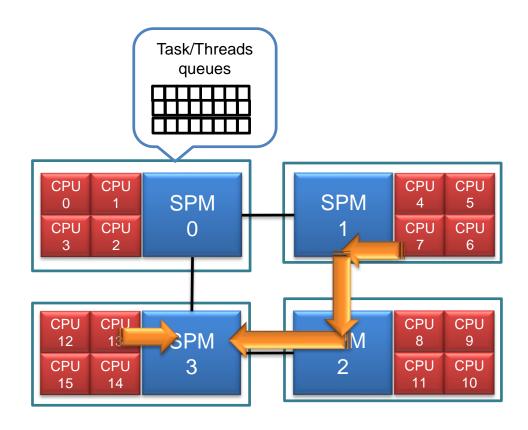


- ✓ NUMA architectures mean that we should schedule tasks(/threads as close as possible to data!
 - Or..the other way around: put (map) data where we know threads will be
 - Co-scheduling problem!



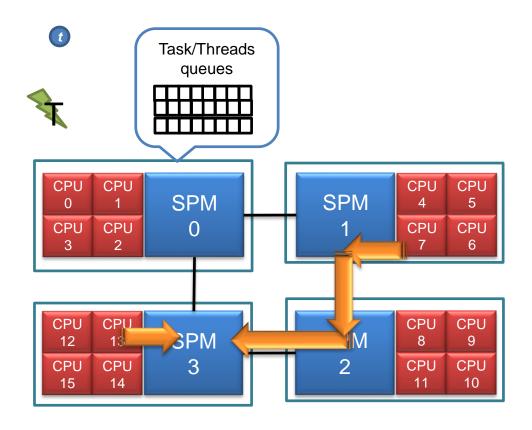


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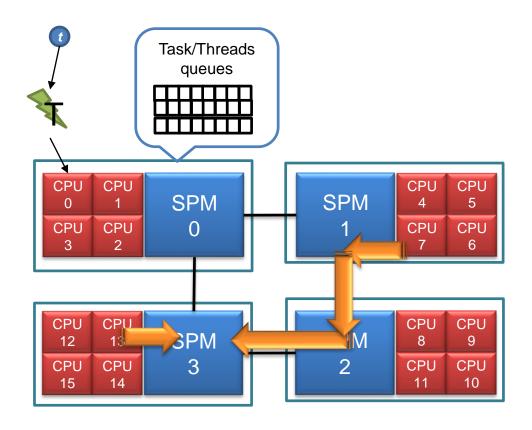


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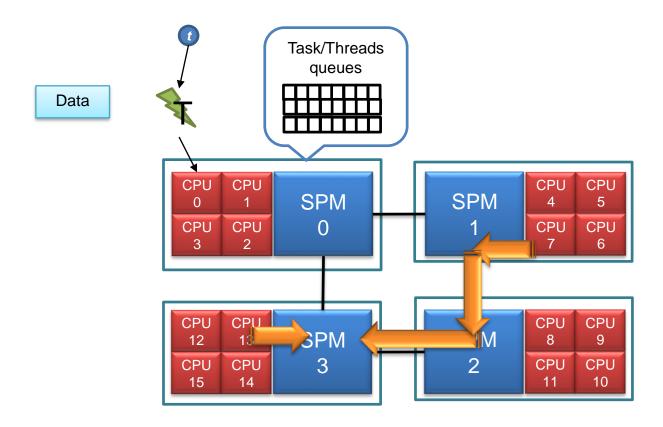


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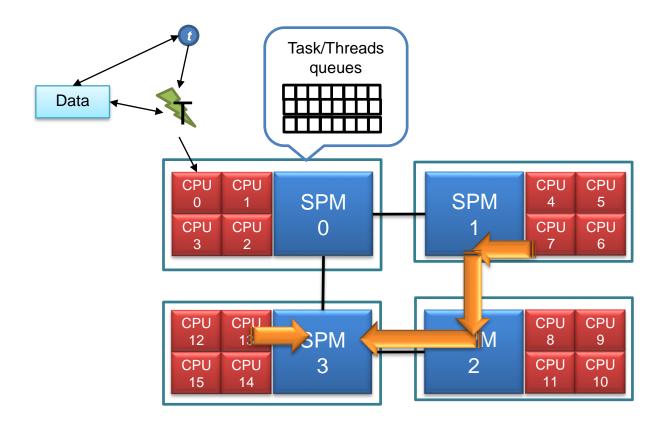


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- ✓ "Calcolo parallelo" website
 - http://hipert.unimore.it/people/paolob/pub/Calcolo_Parallelo/
- My contacts
 - paolo.burgio@unimore.it
 - http://hipert.mat.unimore.it/people/paolob/
- ✓ OpenMP
 - http://www.openmp.org
 - https://computing.llnl.gov/tutorials/openMP/