

# Vocabulary for Deep Learning (In 40 Minutes! With Pictures!)

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# Prediction Problems

Given  $x$ , predict  $y$

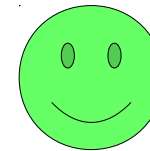
# Example: Sentiment Analysis

x

y

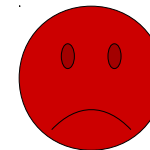
I am happy

+1



I am sad

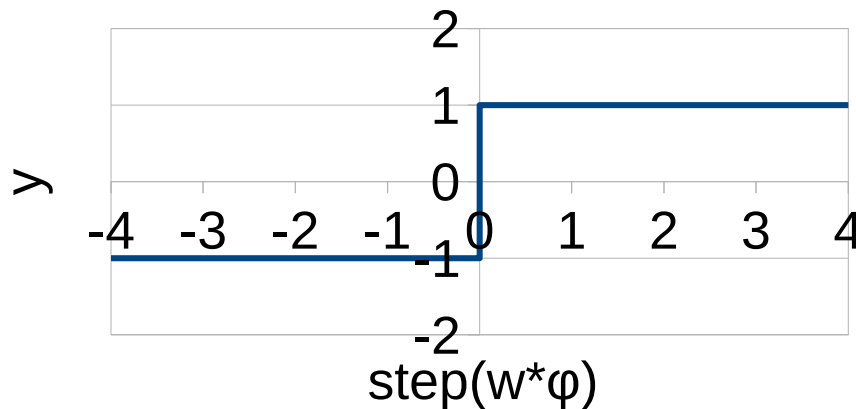
-1



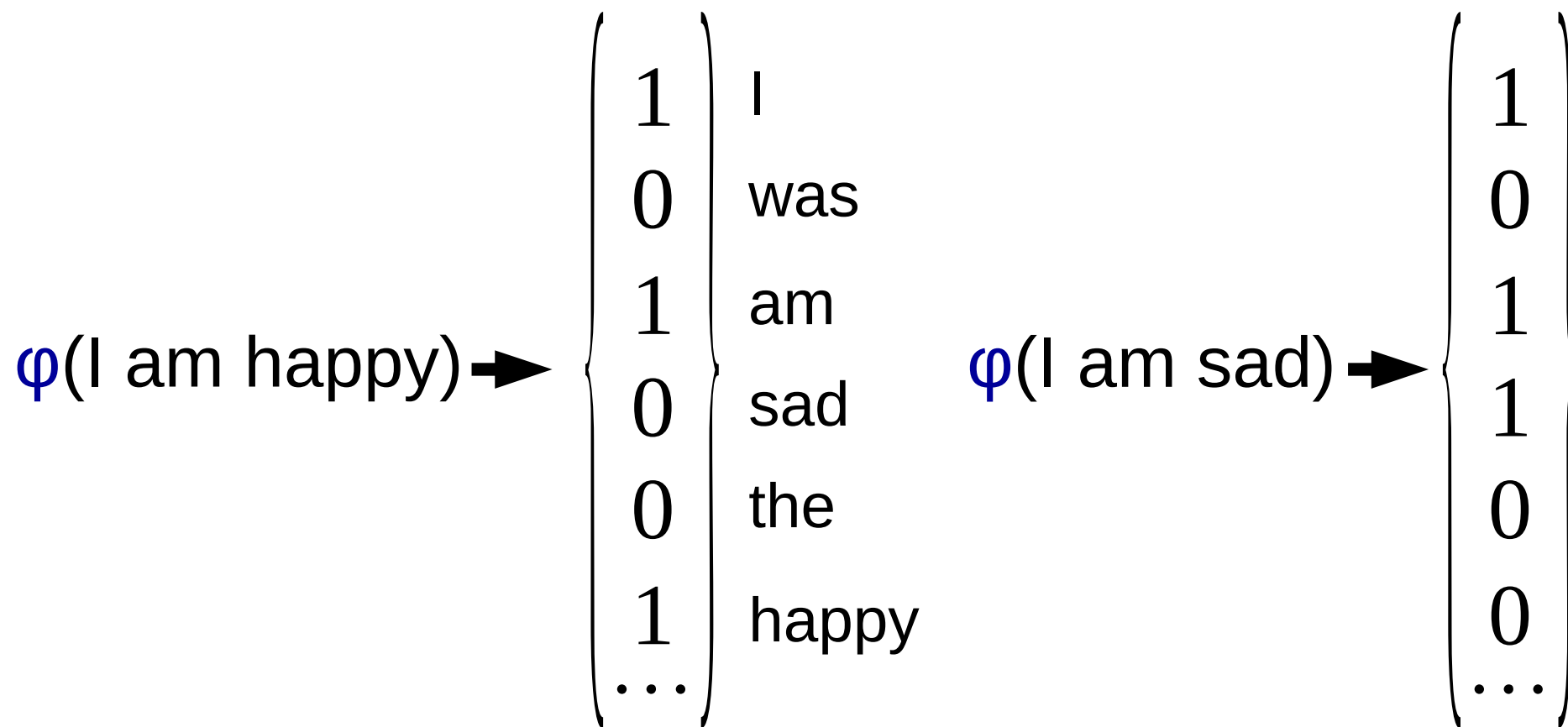
# Linear Classifiers

$$y = \text{step}(\mathbf{w}^T \boldsymbol{\varphi}(\mathbf{x}))$$

- $\mathbf{x}$ : the input
- $\boldsymbol{\varphi}(\mathbf{x})$ : vector of feature functions
- $\mathbf{w}$ : the weight vector
- $y$ : the prediction, +1 if “yes”, -1 if “no”

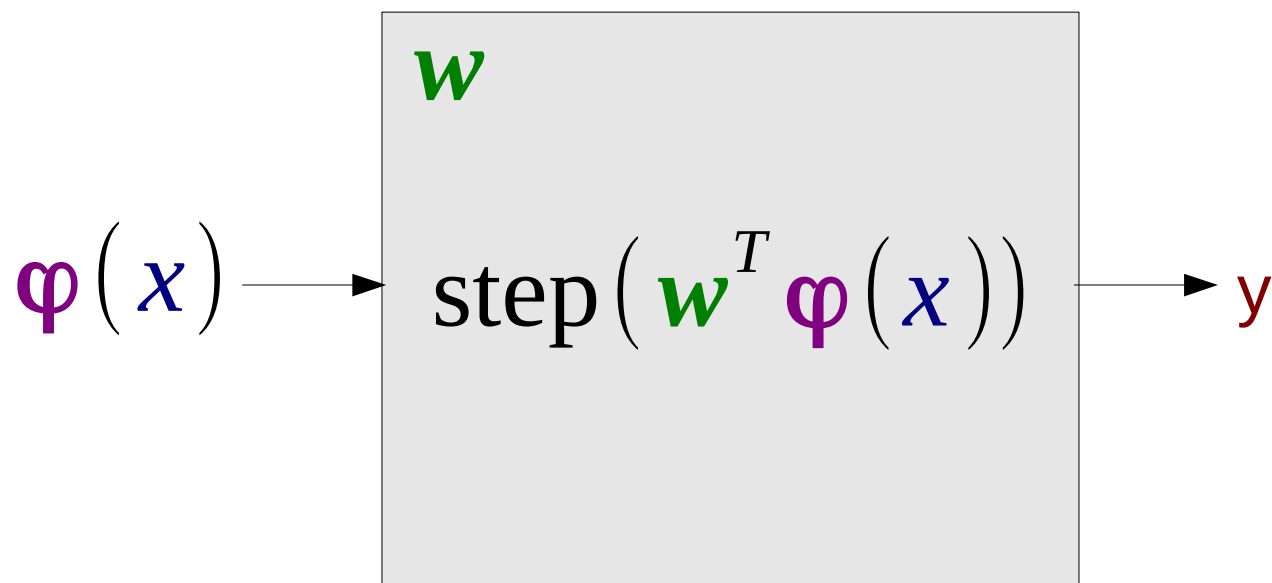


# Example Feature Functions: Unigram Features



# The Perceptron

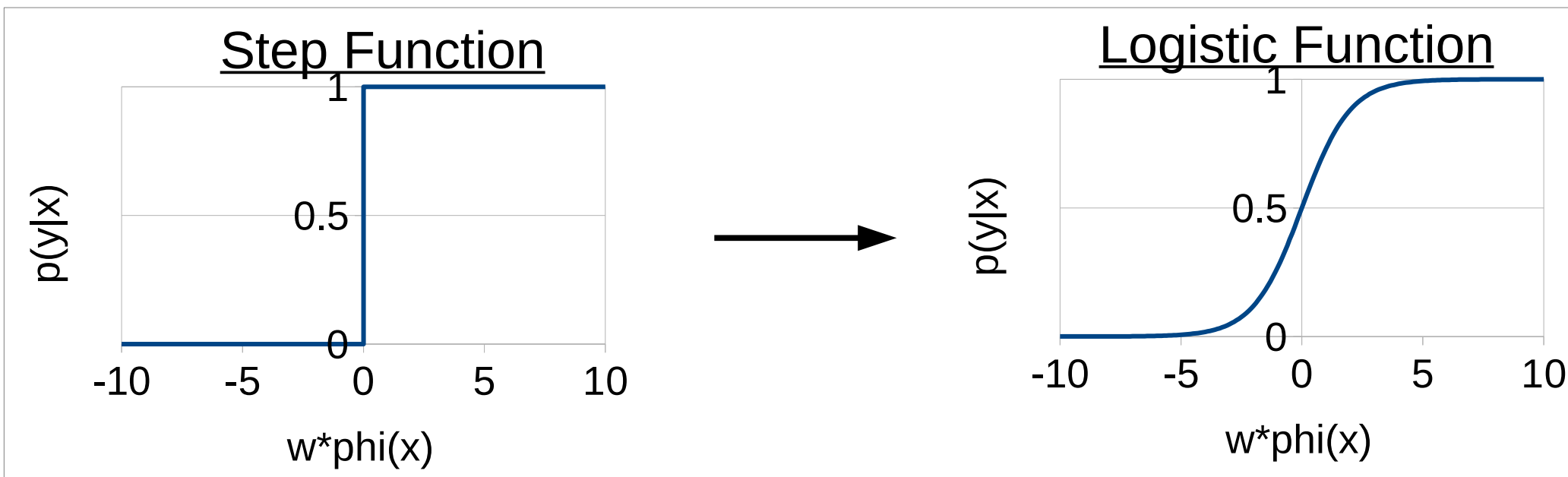
- Think of it as a “machine” to calculate a weighted sum and insert it into an activation function



# Sigmoid Function (Logistic Function)

- The **sigmoid function** is a “softened” version of the step function

$$P(y=1|x) = \frac{e^{w \cdot \varphi(x)}}{1 + e^{w \cdot \varphi(x)}}$$



- Can **account for uncertainty**
- Differentiable**

# Logistic Regression

- Train based on conditional likelihood
- Find the parameters  $\mathbf{w}$  that maximize the conditional likelihood of all answers  $y_i$  given the example  $x_i$

$$\hat{\mathbf{w}} = \underset{\mathbf{w}}{\operatorname{argmax}} \prod_i P(y_i | x_i; \mathbf{w})$$

- How do we solve this?



# Stochastic Gradient Descent

- Online training algorithm for probabilistic models (including logistic regression)

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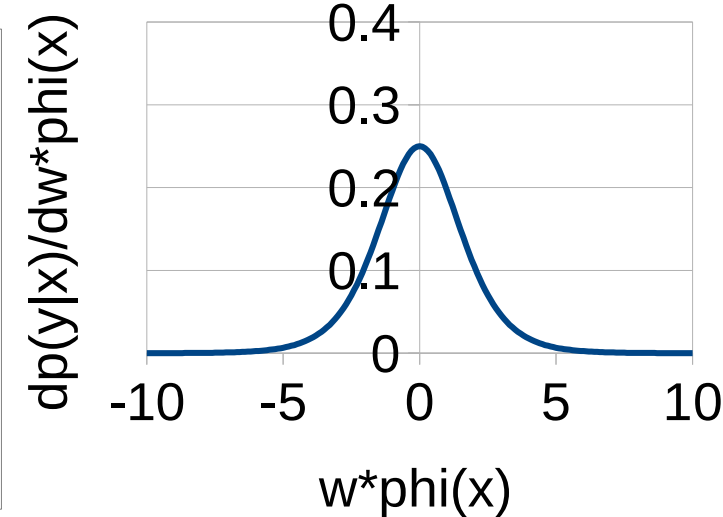
create map  $w$ 
for / iterations
    for each labeled pair  $x, y$  in the data
         $w \ += \ \alpha \ * \ dP(y|x)/dw$ 
    
```

- In other words
  - For every training example, calculate the **gradient** (the direction that will increase the probability of  $y$ )
  - **Move** in that direction, multiplied by learning rate  $\alpha$

# Gradient of the Sigmoid Function

- Take the derivative of the probability

$$\begin{aligned}\frac{d}{d \mathbf{w}} P(\mathbf{y} = 1 | \mathbf{x}) &= \frac{d}{d \mathbf{w}} \frac{e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})}}{1 + e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})}} \\ &= \boldsymbol{\varphi}(\mathbf{x}) \frac{e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})}}{(1 + e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})})^2}\end{aligned}$$

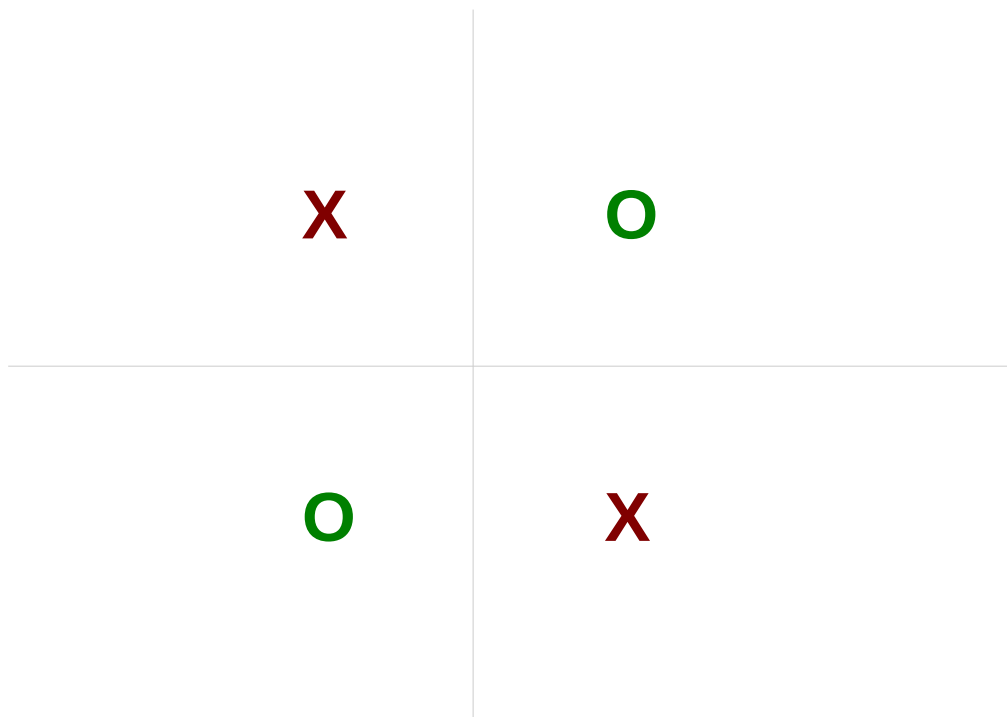


$$\begin{aligned}\frac{d}{d \mathbf{w}} P(\mathbf{y} = -1 | \mathbf{x}) &= \frac{d}{d \mathbf{w}} \left( 1 - \frac{e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})}}{1 + e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})}} \right) \\ &= -\boldsymbol{\varphi}(\mathbf{x}) \frac{e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})}}{(1 + e^{\mathbf{w} \cdot \boldsymbol{\varphi}(\mathbf{x})})^2}\end{aligned}$$

# Neural Networks

## Problem: Linear Constraint

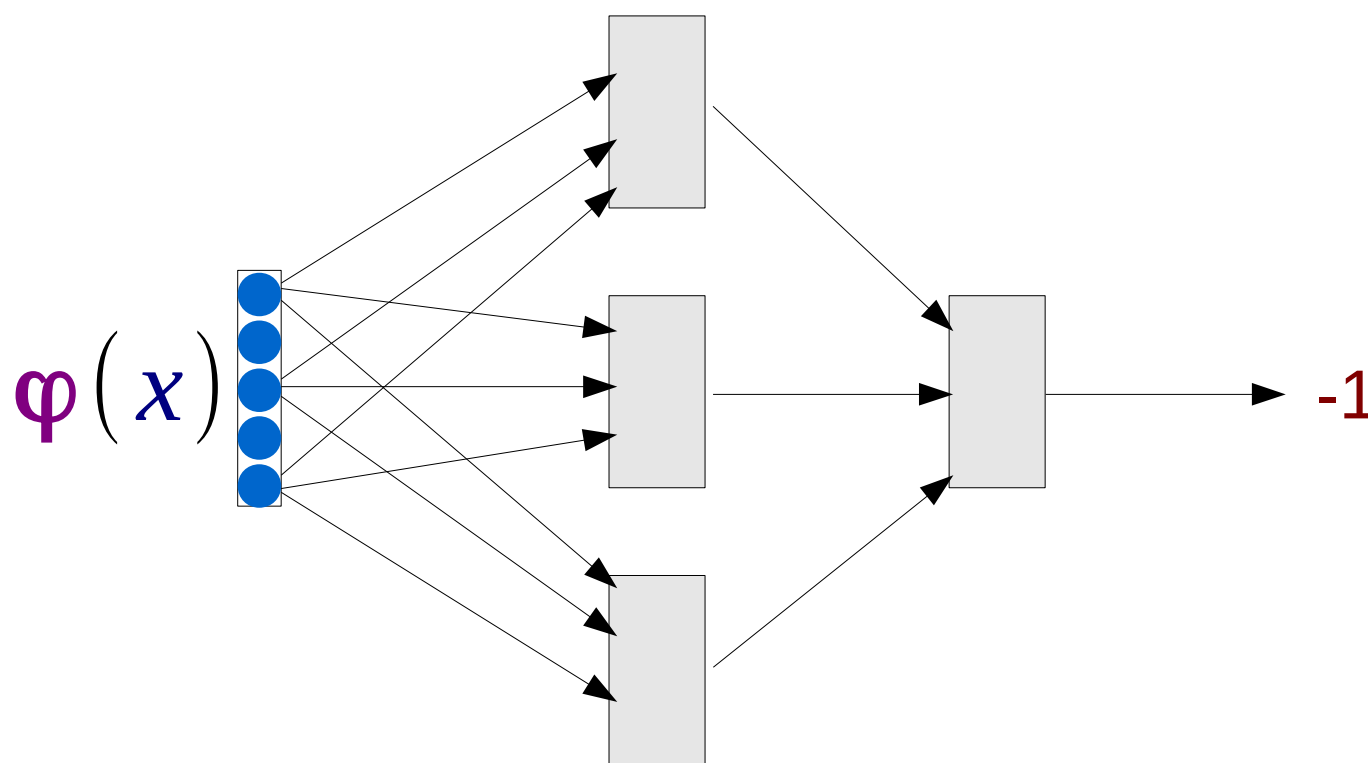
- Perceptron cannot achieve high accuracy on non-linear functions



- Example: “I am **not** happy”

# Neural Networks (Multi-Layer Perceptron)

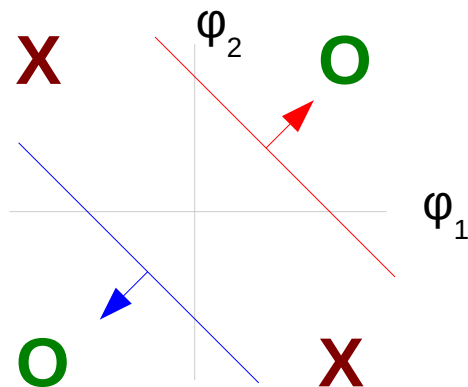
- Neural networks connect multiple perceptrons together



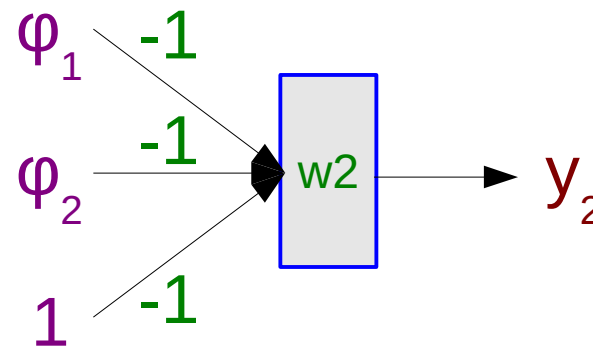
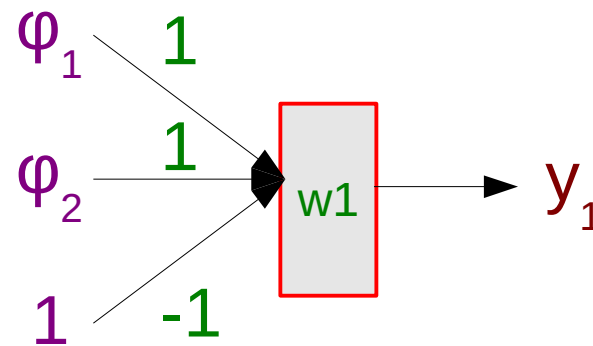
# Example:

- Build two classifiers:

$$\varphi(x_1) = \{-1, 1\} \quad \varphi(x_2) = \{1, 1\}$$

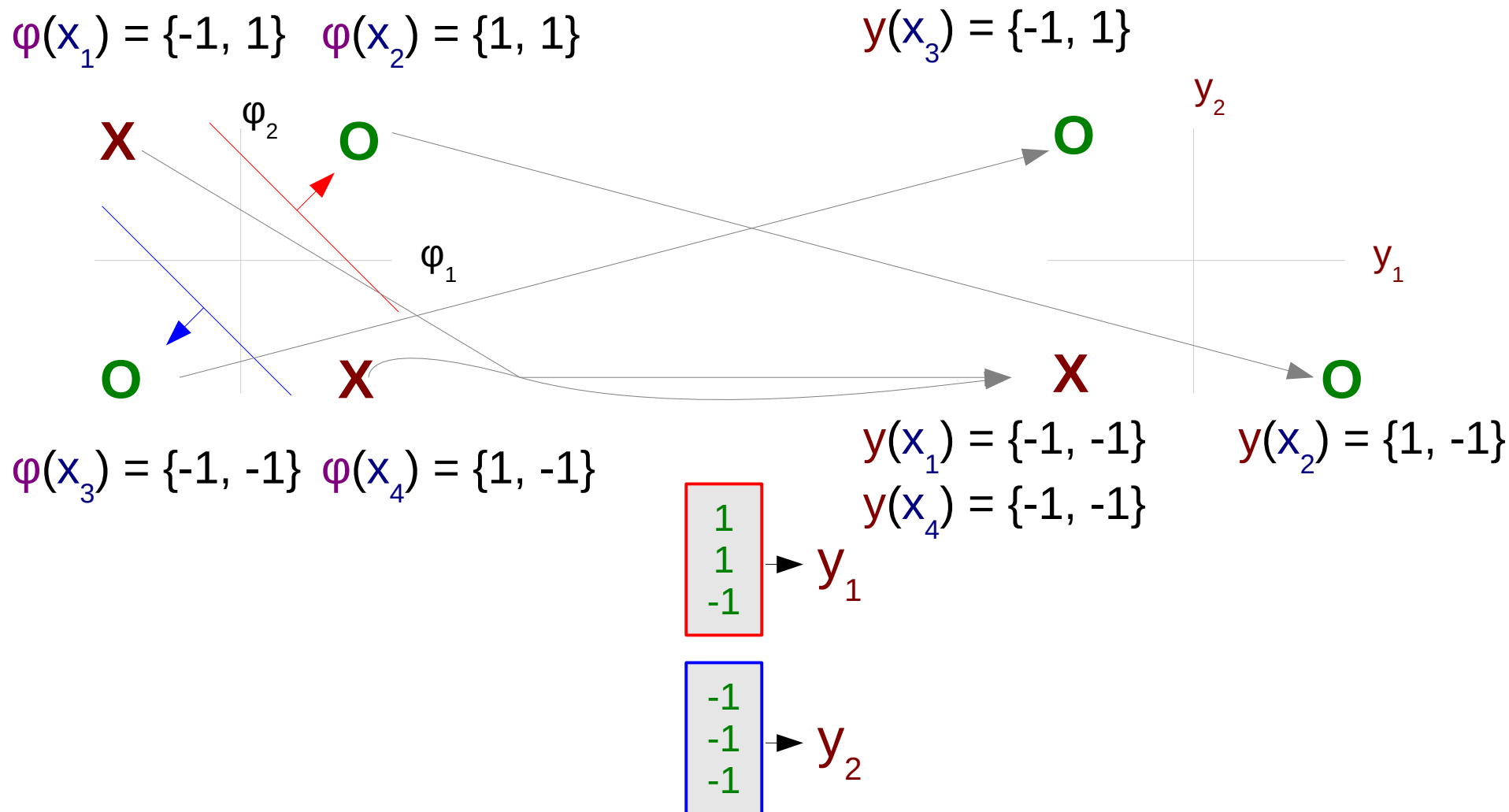


$$\varphi(x_3) = \{-1, -1\} \quad \varphi(x_4) = \{1, -1\}$$



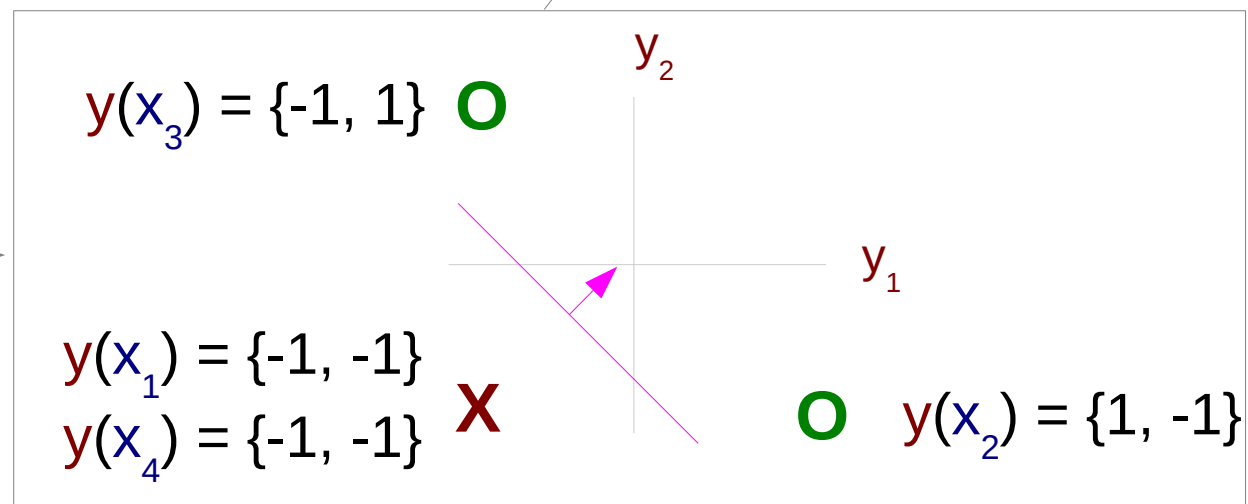
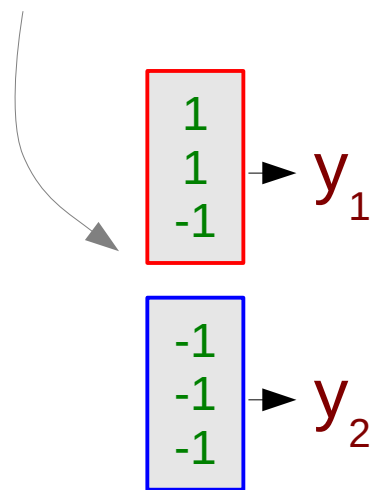
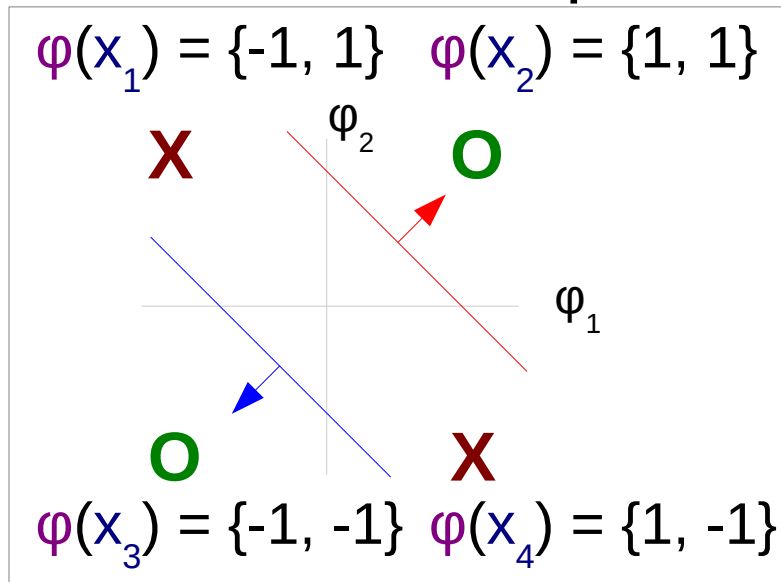
# Example:

- These classifiers map the points to a new space



# Example:

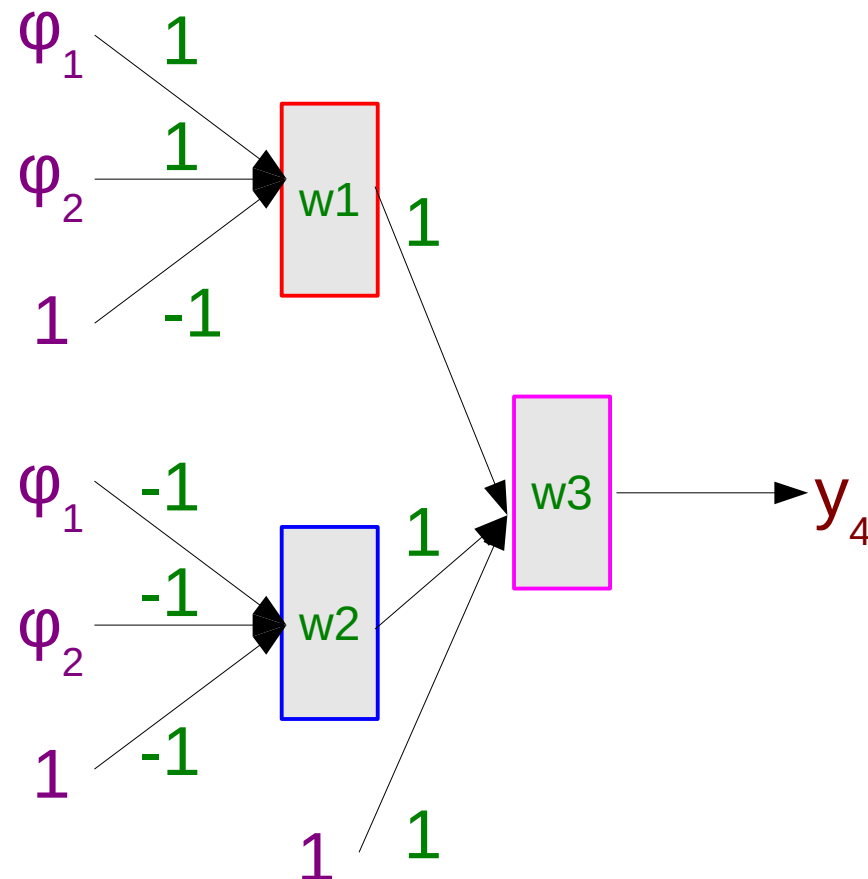
- In the new space, examples are classifiable!





# Example:

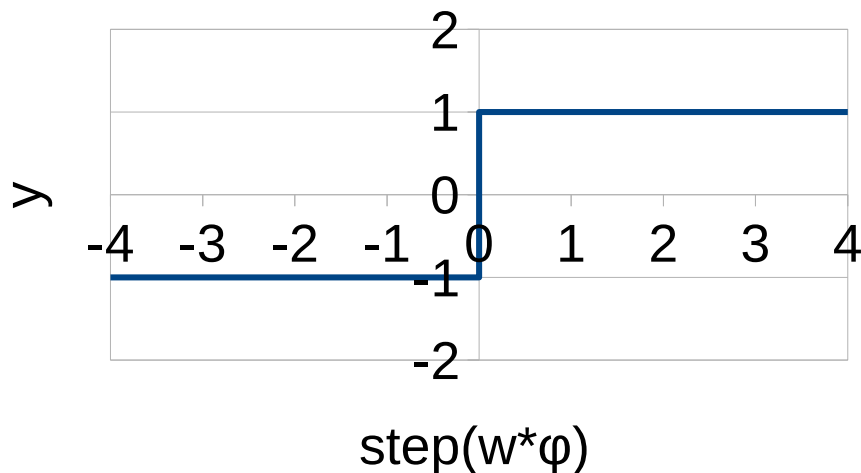
- Final neural network:



# Hidden Layer Activation Functions

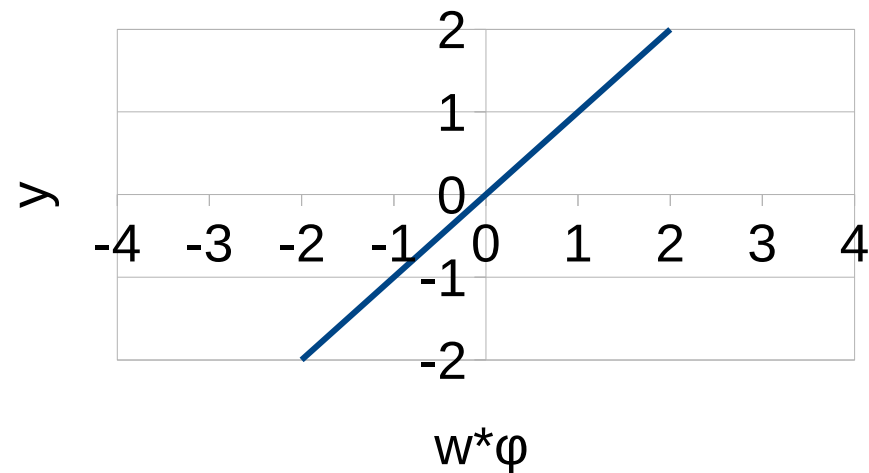
## Step Function:

- Cannot calculate gradient



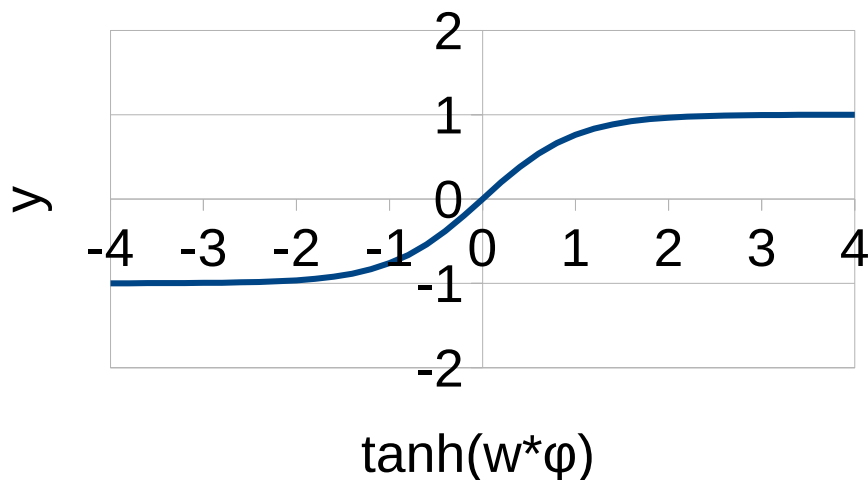
## Linear Function:

- Whole net become linear



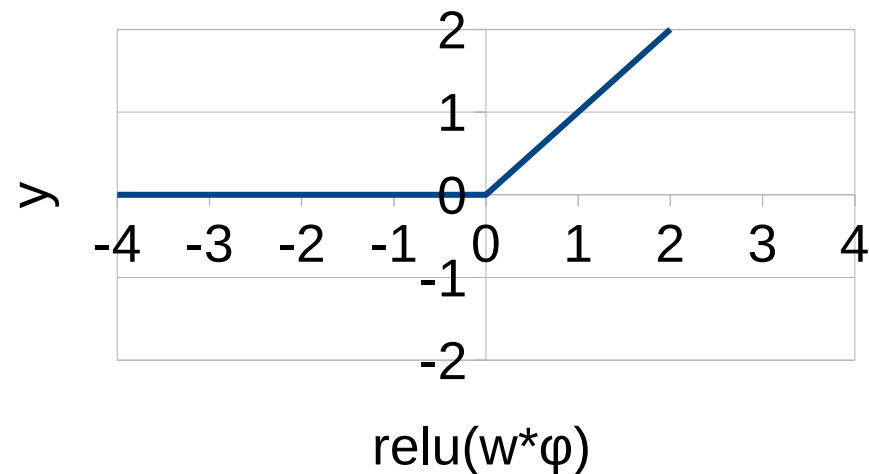
## Tanh Function:

Standard (also 0-1 sigmoid)

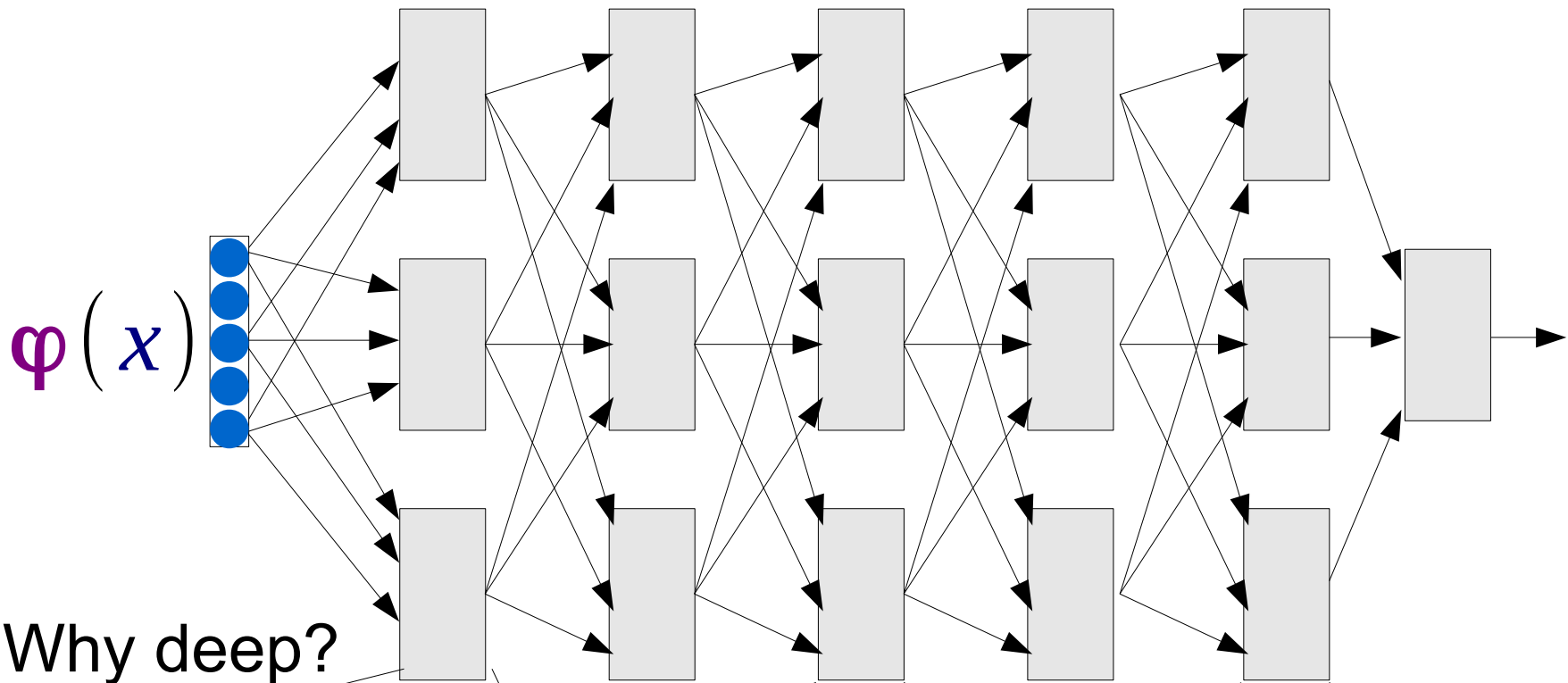


## Rectified Linear Function:

+ Gradients at large vals.



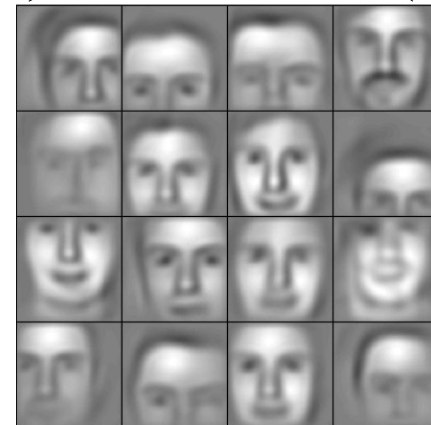
# Deep Networks



- Why deep?



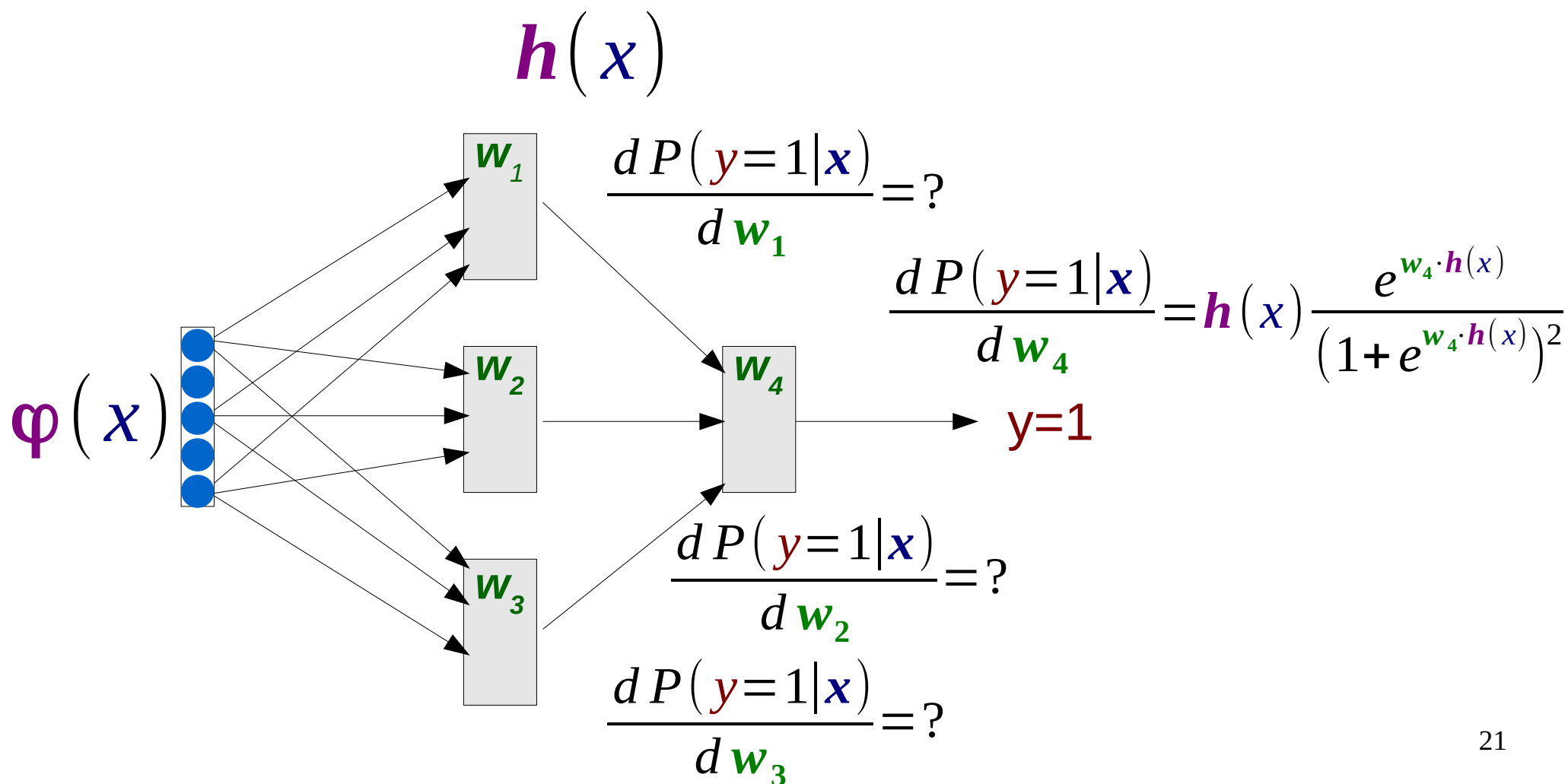
- Gradually more detailed functions (e.g. [Lee+ 09])



# Learning Neural Nets

# Learning: Don't Know Derivative for Hidden Units!

- For NNs, only know correct tag for last layer



# Answer: Back-Propagation

- Calculate derivative w/ chain rule

$$\frac{dP(y=1|x)}{dw_1} = \frac{dP(y=1|x)}{dw_4 h(x)} \frac{dw_4 h(x)}{dh_1(x)} \frac{dh_1(x)}{dw_1}$$

$$\frac{e^{w_4 \cdot h(x)}}{(1 + e^{w_4 \cdot h(x)})^2}$$

↓

Error of  
next unit ( $\delta_4$ )

$$w_{1,4}$$

↓

Weight

↓

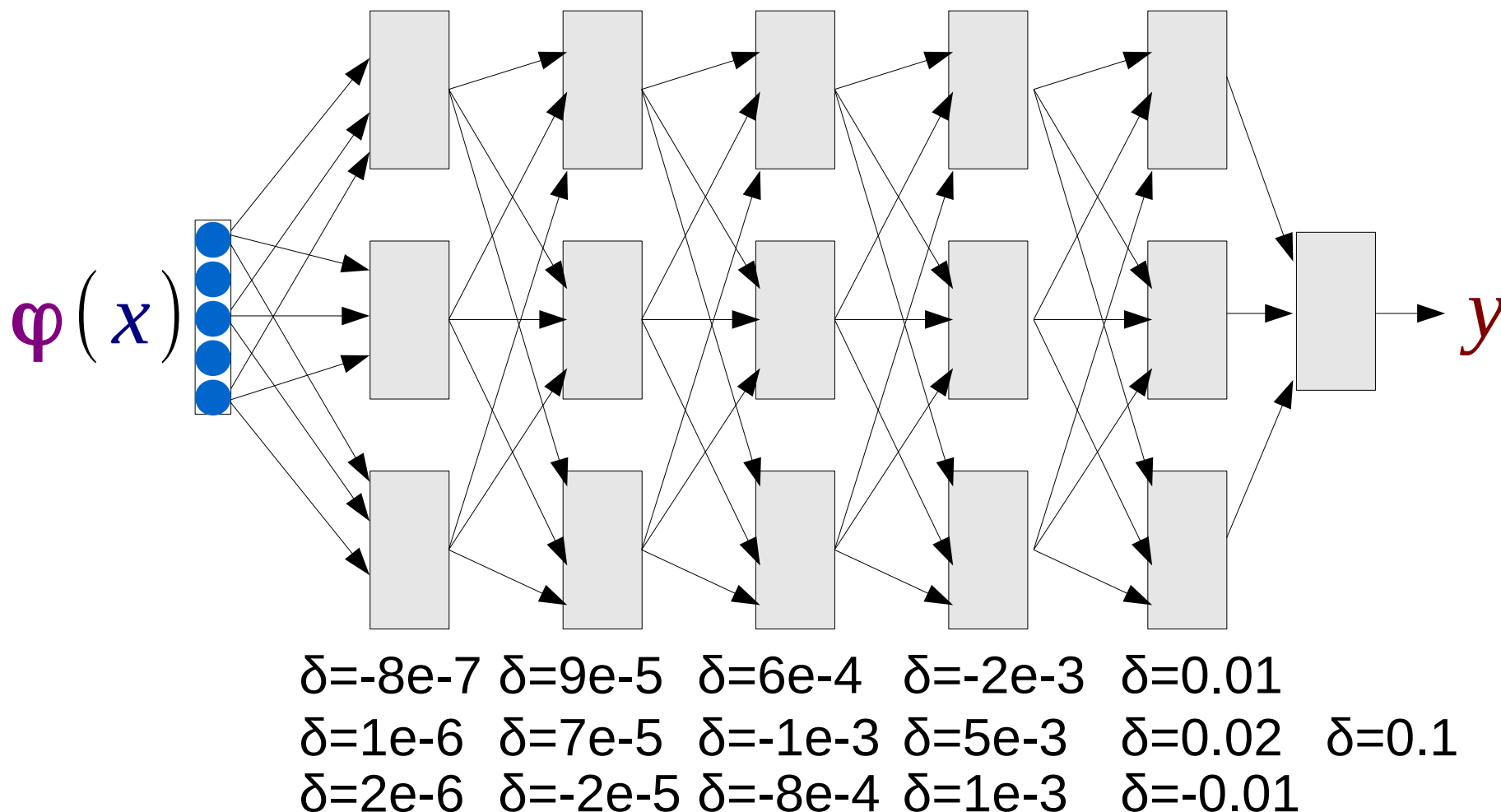
Gradient of  
this unit

## In General

Calculate  $i$  based  
on next units  $j$ :

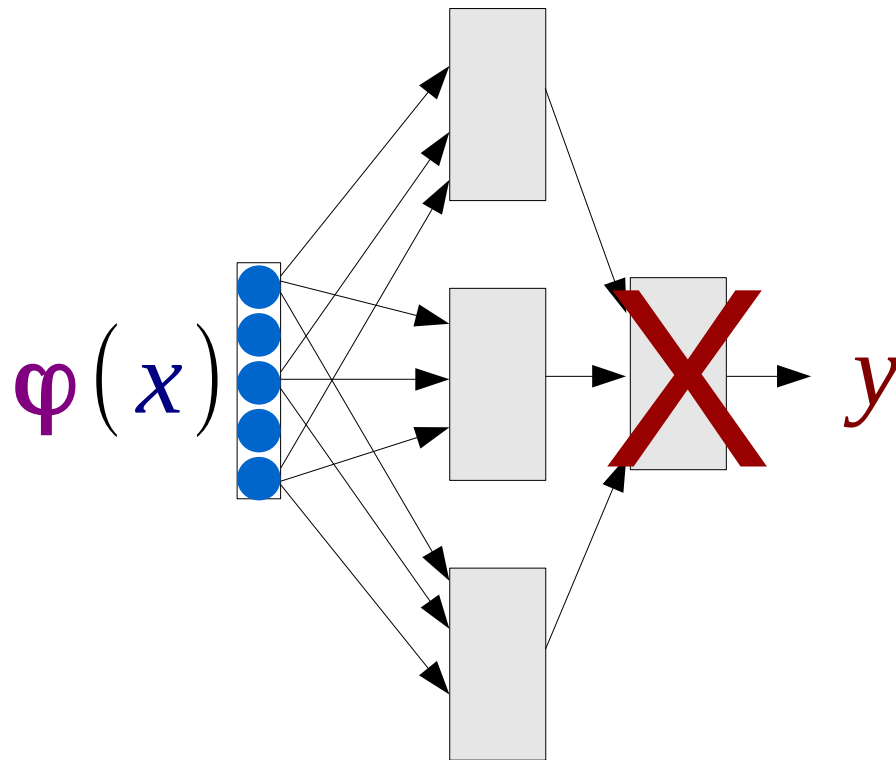
$$\frac{dP(y=1|x)}{dw_i} = \frac{dh_i(x)}{dw_i} \sum_j \delta_j w_{i,j}$$

# BP in Deep Networks: Vanishing Gradients



- Exploding gradient as well

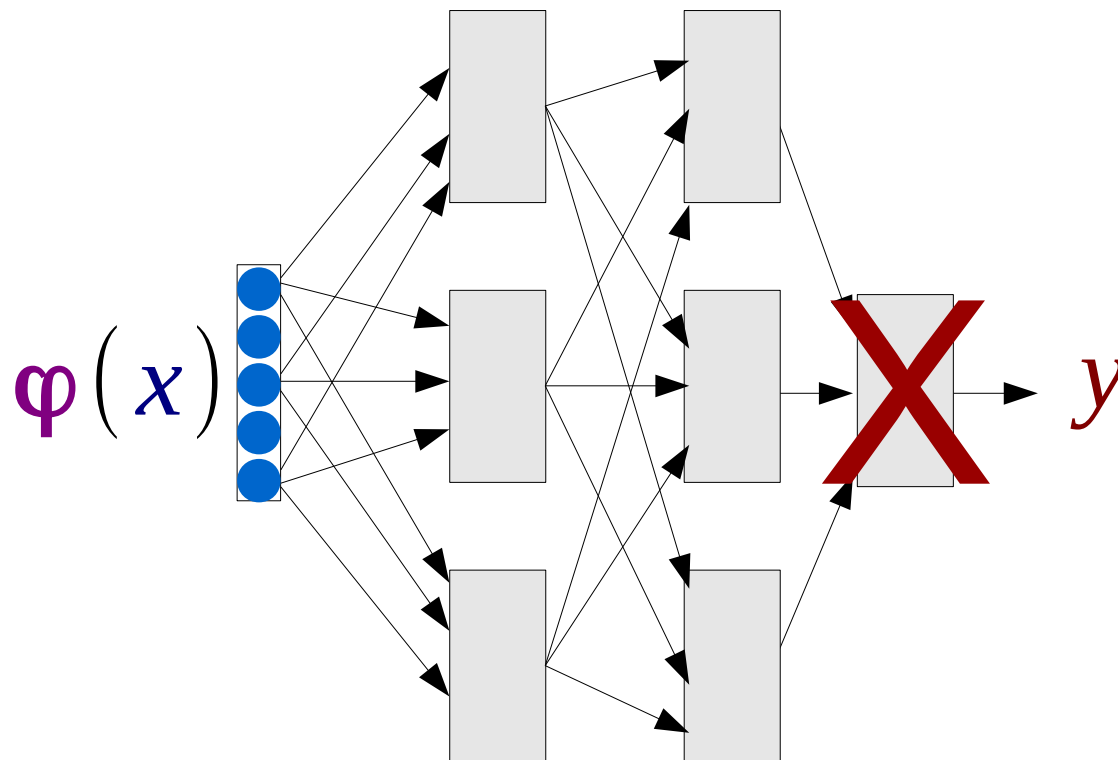
# Layerwise Training



- Train one layer at a time

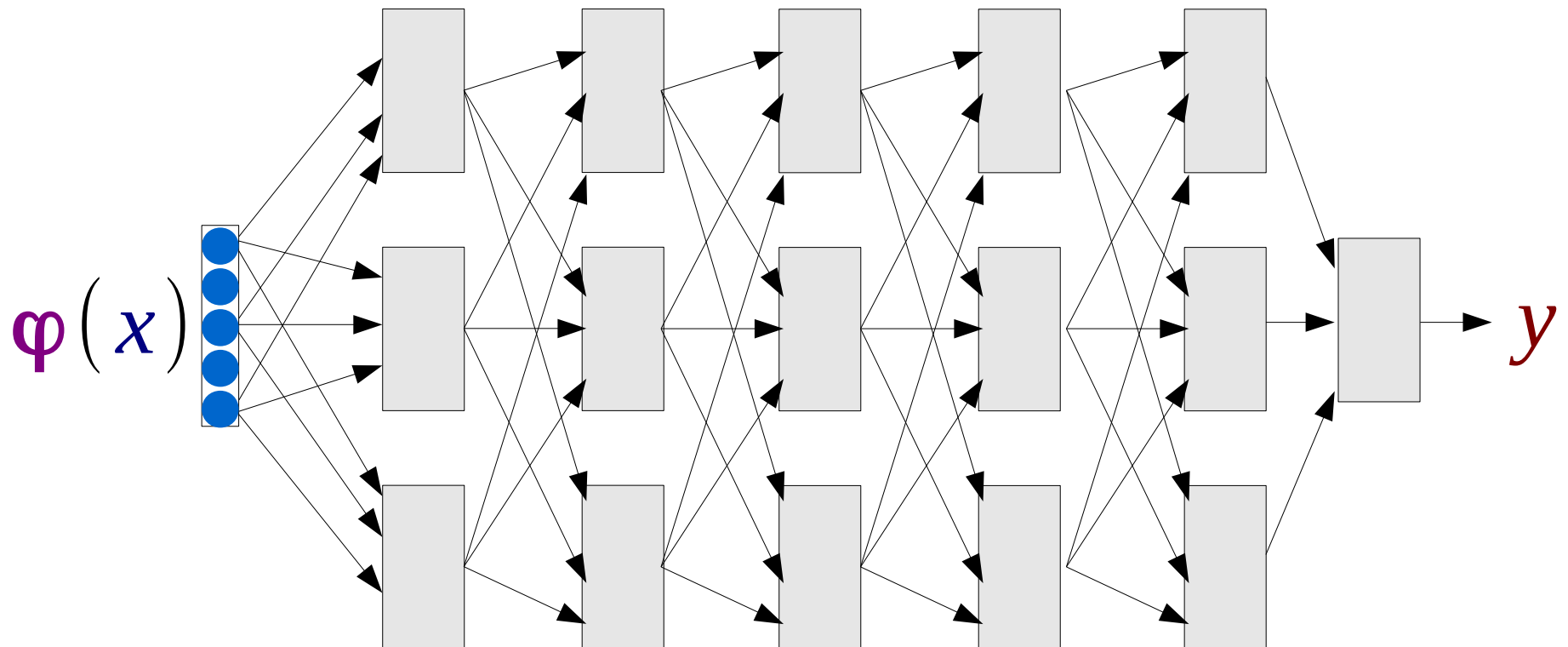


# Layerwise Training



- Train one layer at a time

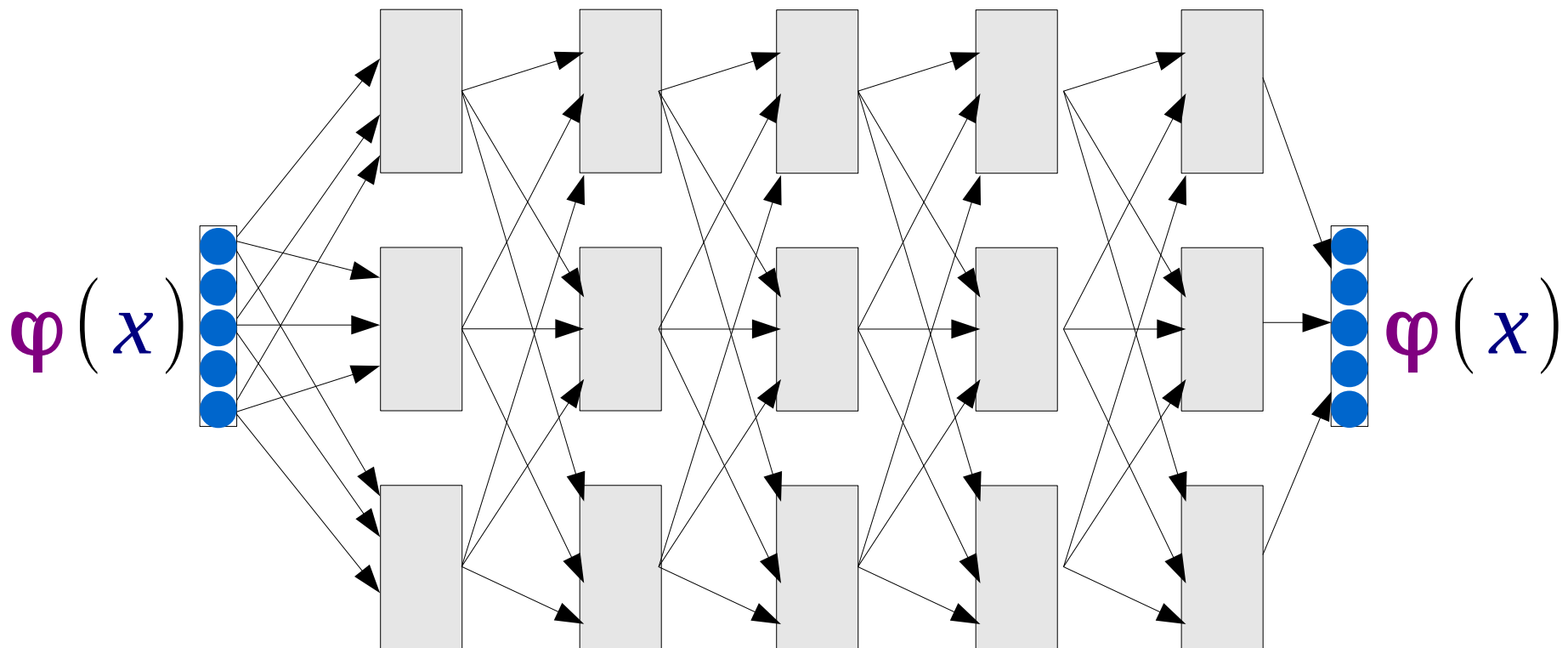
# Layerwise Training



- Train one layer at a time

# Autoencoders

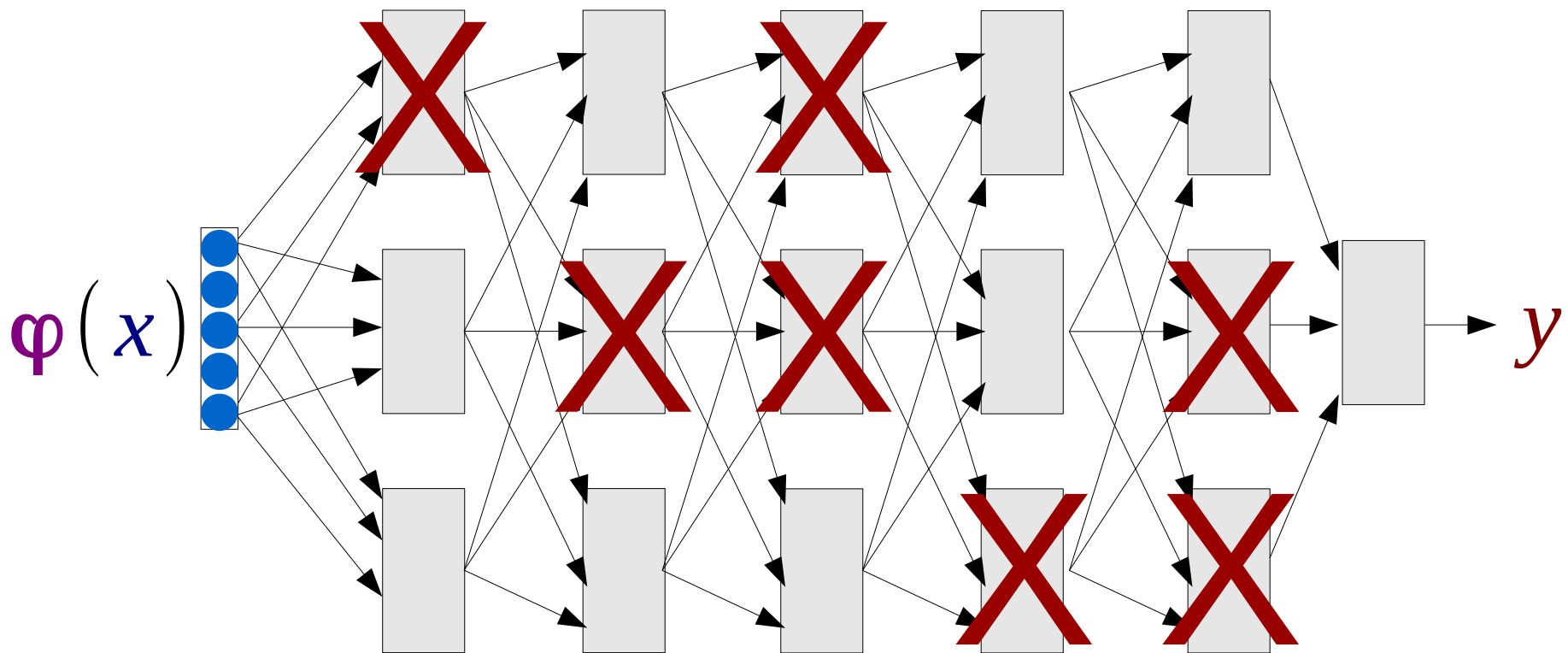
- Initialize the NN by training it to reproduce itself



- Advantage: No need for labels  $y$ !

# Dropout

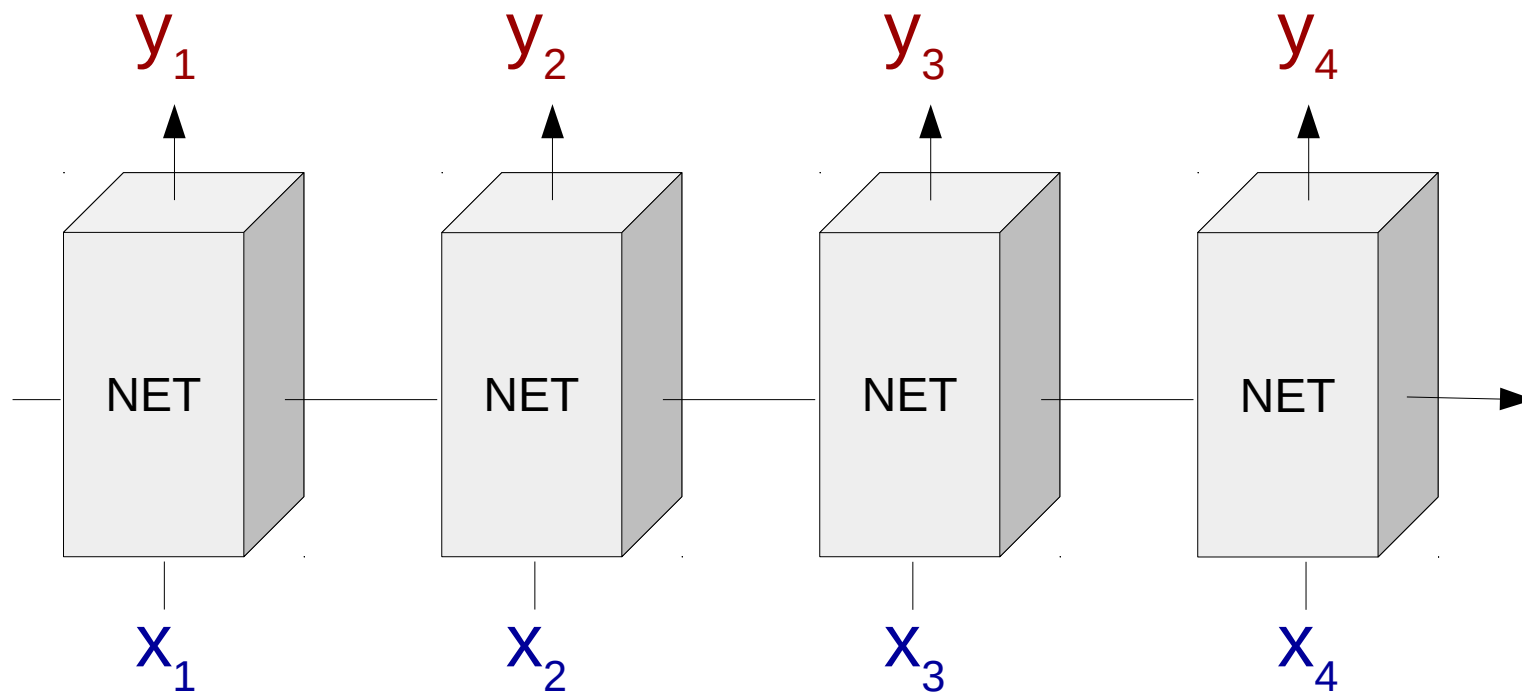
- Problem: Overfitting



- Deactivate part of the network on each update
- Can be seen as an ensemble method

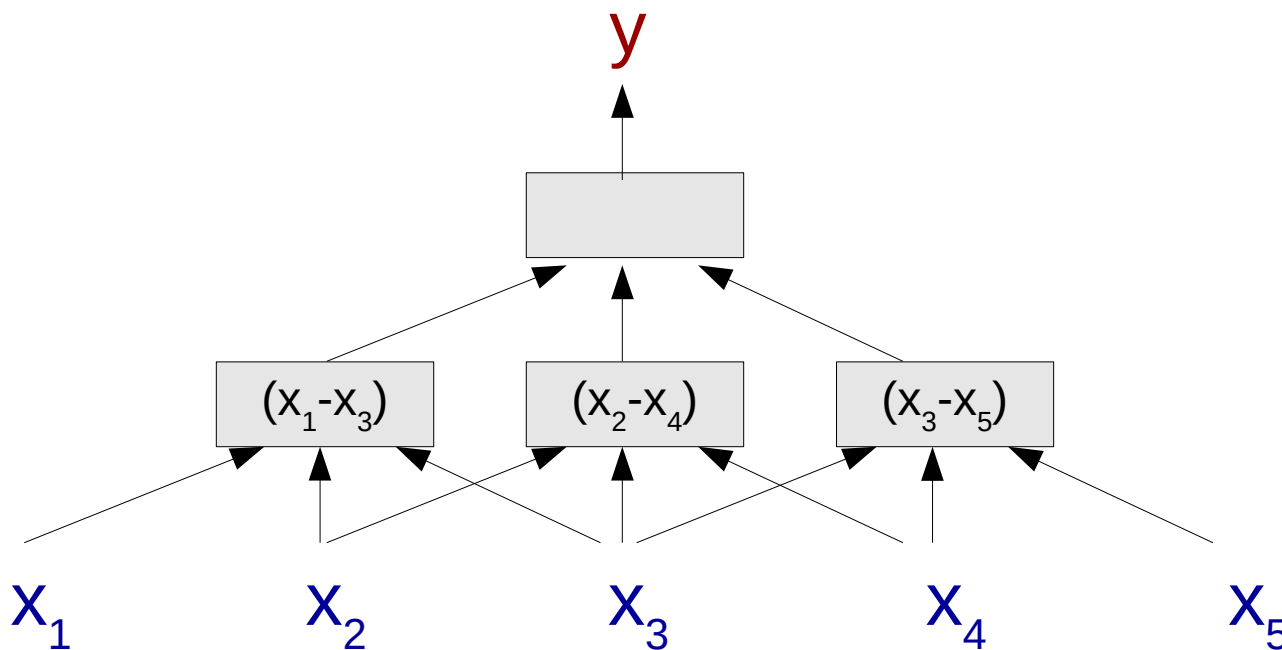
# Network Architectures

# Recurrent Neural Nets



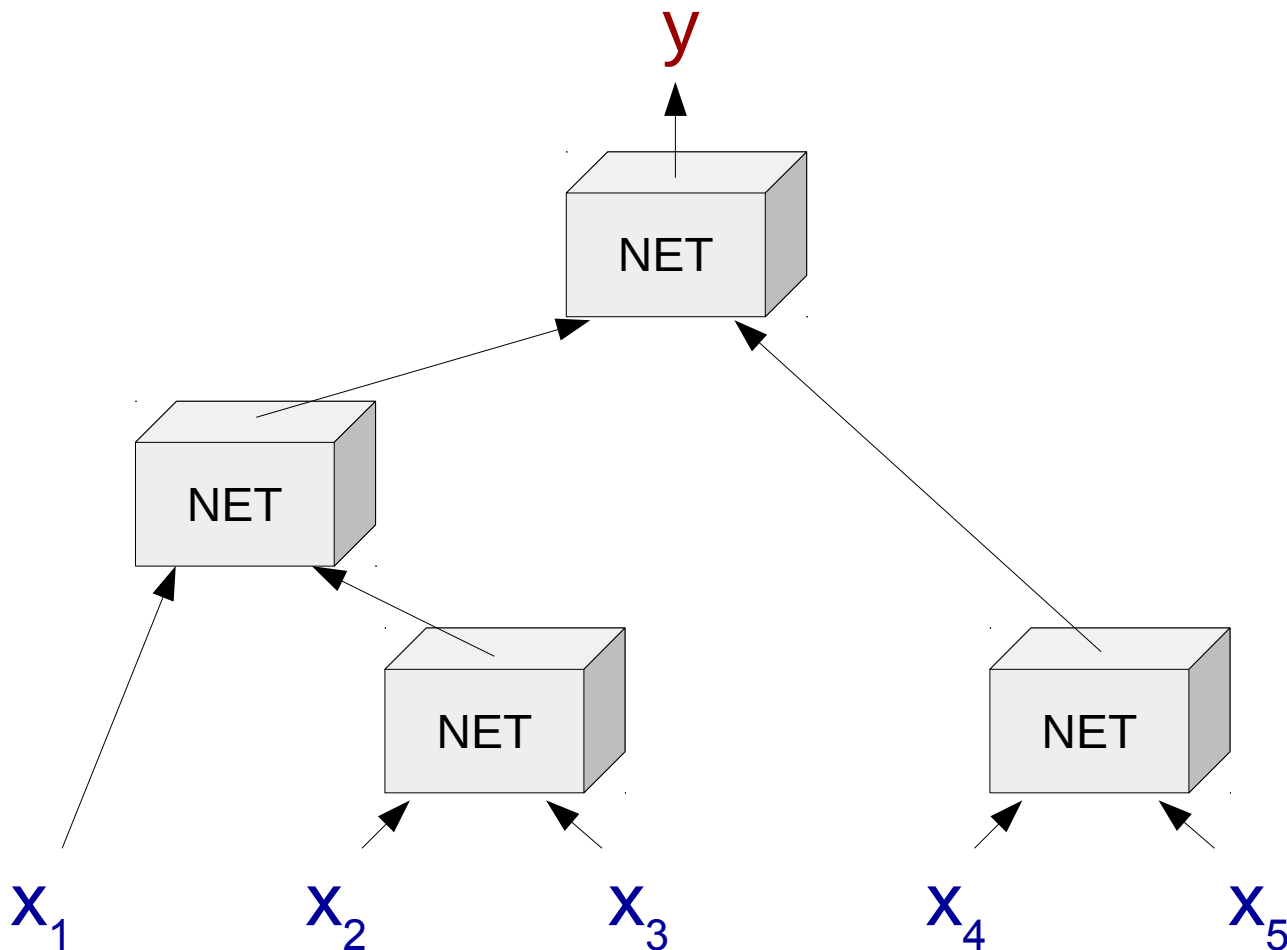
- Good for modeling sequence data
- e.g. Speech

# Convolutional Neural Nets



- Good for modeling data with spatial correlation
- e.g. Images

# Recursive Neural Nets



- Good for modeling data with tree structures
- e.g. Language



# Other Topics

## Other Topics

- Deep belief networks
  - Restricted Boltzmann machines
  - Contrastive estimation
- Generating with Neural Nets
- Visualizing internal states
- Batch/mini-batch update strategies
- Long short-term memory
- Learning on GPUs
- Tools for implementing deep learning