Import Libraries

```
In [607]:
          import os
          import csv
          import torch
          import torchvision.transforms as transforms
          from tqdm.notebook import tqdm
          import pandas as pd
          import numpy as np
          from torch.utils.data import Dataset, DataLoader
          from PIL import Image
          import matplotlib.pyplot as plt
          from tqdm.notebook import tqdm
          import torch.nn.functional as F
          import torch.nn as nn
          import seaborn as sns
          %matplotlib inline
```

Transforming Data to Tensors

```
In [562]: DATA DIR = '/content/drive/MyDrive/Colab Notebooks/Emotion Detect/new Fer2013.csv
In [563]: data df=pd.read csv(DATA DIR)
            data df.head()
Out[563]:
                emotion
                                                               pixels
                                                                       Usage
                                                                                label
             0
                          77 78 79 79 78 75 60 55 47 48 58 73 77 79 57 5... Training
                      0 85 84 90 121 101 102 133 153 153 169 177 189 1... Training Happy
             2
                          4 2 13 41 56 62 67 87 95 62 65 70 80 107 127 1... Training Happy
                           14 14 18 28 27 22 21 30 42 61 77 86 88 95 100 ... Training Happy
             3
                      0 252 250 246 229 182 140 98 72 53 44 67 95 95 8... Training Happy
In [564]: | classes = ['Happy', 'Sad', 'Neutral']
```

```
In [565]:

def __init__(self,transform=None, images=None, emotions=None):
    self.transform = transform
    self.images = images
    self.emotions = emotions

def __getitem__(self, index):
    image = self.images[index]
    emotion = self.emotions[index]
    if self.transform is not None:
        image = self.transform(image)
    return image, emotion

def __len__(self):
    return len(self.images)
```

```
In [566]: class DataSetFactory:
              def __init__(self):
                  images = list()
                  emotions = list()
                  val_images = list()
                  val emotions = list()
                  test images = list()
                  test_emotions = list()
                  with open(DATA_DIR, 'r') as file:
                       data = csv.reader(file)
                       next(data)
                       for row in data:
                           face = [int(pixel) for pixel in row[1].split()]
                           face = np.asarray(face).reshape(48, 48)
                           face = face.astype('uint8')
                           if row[-2] == 'Training':
                               emotions.append(int(row[0]))
                               images.append(Image.fromarray(face))
                           if row[-2] == "PrivateTest":
                               val emotions.append(int(row[0]))
                               val_images.append(Image.fromarray(face))
                           if row[-2]=="PublicTest":
                               test emotions.append(int(row[0]))
                               test images.append(Image.fromarray(face))
                  print('training size %d : val size %d : test size %d'%(len(images), len(\
                  train transform = transforms.Compose([
                       transforms.RandomHorizontalFlip(),
                       transforms.RandomRotation(10),
                       transforms.ToTensor(),
                  val transform = transforms.Compose([
                      transforms.ToTensor()
                   1)
                   self.training = DataSet(transform=train transform, images=images, emotion
                   self.validation = DataSet(transform=val_transform, images=val_images, emc
                   self.testing = DataSet(transform=val transform, images=test images, emoti
```

```
In [569]: batch size=128
          factory = DataSetFactory()
          training loader = DataLoader(factory.training, batch_size=batch_size, shuffle=Tru
          validation loader = DataLoader(factory.validation, batch size=batch size, shuffle
          testing_loader=DataLoader(factory.testing, batch_size=64, shuffle=True, num_worke
          training size 17010 : val size 2099 : test size 2155
In [570]: def decode_target(target, text_labels=False):
              result = list()
              if text_labels:
                   result.append(classes[target] + "(" + str(target) + ")")
                  return ' '.join(result)
              for i, x in enumerate(target):
                  if (x == torch.max(target)):
                    # result.append(classes[i] + "(" + str(i) + ")")
                    # return ' '.join(result)
                    return int(i)
In [571]: def show_sample(img, target, predict = False):
              img=img.squeeze(0)
              if predict:
                return decode_target(target)
              else:
                print('Labels:',decode target(target,text labels=True))
In [572]: if torch.cuda.is available():
            device = torch.device('cuda')
          device
Out[572]: device(type='cuda')
In [573]: def to_device(data, device):
              """Move tensor(s) to chosen device"""
              if isinstance(data, (list,tuple)):
                   return [to device(x, device) for x in data]
              return data.to(device, non blocking=True)
          class DeviceDataLoader():
              """Wrap a dataloader to move data to a device"""
              def init (self, dl, device):
                  self.dl = dl
                  self.device = device
              def __iter__(self):
                   """Yield a batch of data after moving it to device"""
                  for b in self.dl:
                      yield to device(b, self.device)
              def __len__(self):
                   """Number of batches"""
                  return len(self.dl)
```

```
In [574]: def accuracy(outputs, labels):
    _, preds = torch.max(outputs, dim=1)
    return torch.tensor(torch.sum(preds == labels).item() / len(preds))

In [575]: training_loader = DeviceDataLoader(training_loader, device)
    validation_loader = DeviceDataLoader(validation_loader, device)
    testing_loader = DeviceDataLoader(testing_loader, device)
```

Building Model CNN

```
In [576]: class Face(nn.Module):
              def training_step(self, batch):
                  images, labels = batch
                  out = self(images)
                                                     # Generate predictions
                  loss = F.cross_entropy(out, labels) # Calculate loss
                  return loss
              def validation_step(self, batch):
                  images, labels = batch
                  out = self(images)
                                                       # Generate predictions
                  loss = F.cross_entropy(out, labels) # Calculate loss
                  acc = accuracy(out, labels)
                                                      # Calculate accuracy
                  return {'val_loss': loss, 'val_acc': acc}
              def validation epoch end(self, outputs):
                  batch losses = [x['val loss'] for x in outputs]
                  epoch loss = torch.stack(batch losses).mean() # Combine Losses
                  batch_accs = [x['val_acc'] for x in outputs]
                  epoch acc = torch.stack(batch accs).mean() # Combine accuracies
                  return {'val_loss': epoch_loss.item(), 'val_acc': epoch_acc.item()}
              def epoch end(self, epoch, result):
                  print("Epoch [{}],last_lr: {:.4f}, val_loss: {:.4f}, val_acc: {:.4f}".for
```

```
In [577]: class SeparableConv2d(nn.Module):
              def __init__(self, in_channels, out_channels, kernel_size=1, stride=1, paddir
                  super(SeparableConv2d, self). init ()
                  self.depthwise = nn.Conv2d(in_channels, in_channels, kernel_size, stride
                                              bias=bias)
                  self.pointwise = nn.Conv2d(in_channels, out_channels, 1, 1, 0, 1, 1, bias
              def forward(self, x):
                  x = self.depthwise(x)
                  x = self.pointwise(x)
                  return x
          class ResidualBlock(nn.Module):
              def __init__(self, in_channeld, out_channels):
                  super(ResidualBlock, self).__init__()
                  self.residual conv = nn.Conv2d(in channels=in channeld, out channels=out
                                                  bias=False)
                  self.residual_bn = nn.BatchNorm2d(out_channels, momentum=0.99, eps=1e-3)
                  self.sepConv1 = SeparableConv2d(in_channels=in_channeld, out_channels=out
                                                   padding=1)
                  self.bn1 = nn.BatchNorm2d(out channels, momentum=0.99, eps=1e-3)
                  self.relu = nn.ReLU()
                  self.sepConv2 = SeparableConv2d(in_channels=out_channels, out_channels=out_channels)
                                                   padding=1)
                  self.bn2 = nn.BatchNorm2d(out_channels, momentum=0.99, eps=1e-3)
                  self.maxp = nn.MaxPool2d(kernel size=3, stride=2, padding=1)
              def forward(self, x):
                  res = self.residual_conv(x)
                  res = self.residual bn(res)
                  x = self.sepConv1(x)
                  x = self.bn1(x)
                  x = self.relu(x)
                  x = self.sepConv2(x)
                  x = self.bn2(x)
                  x = self.maxp(x)
                  return res + x
          class FaceCnnModel(Face):
              def init (self):
                  super(FaceCnnModel, self).__init__()
                  self.conv1 = nn.Conv2d(in channels=1, out channels=8, kernel size=3, stri
                  self.bn1 = nn.BatchNorm2d(8, affine=True, momentum=0.99, eps=1e-3)
                  self.relu1 = nn.ReLU()
                  self.conv2 = nn.Conv2d(in channels=8, out channels=8, kernel size=3, strj
                  self.bn2 = nn.BatchNorm2d(8, momentum=0.99, eps=1e-3)
                  self.relu2 = nn.ReLU()
```

```
self.module1 = ResidualBlock(in_channeld=8, out_channels=16)
    self.module2 = ResidualBlock(in_channeld=16, out_channels=32)
    self.module3 = ResidualBlock(in_channeld=32, out_channels=64)
    self.module4 = ResidualBlock(in_channeld=64, out_channels=128)
    self.last_conv = nn.Conv2d(in_channels=128, out_channels=7, kernel_size=3
    self.avgp = nn.AdaptiveAvgPool2d((1, 1))
def forward(self, input):
    x = input
    x = self.conv1(x)
    x = self.bn1(x)
    x = self.relu1(x)
   x = self.conv2(x)
   x = self.bn2(x)
    x = self.relu2(x)
    x = self.module1(x)
   x = self.module2(x)
   x = self.module3(x)
   x = self.module4(x)
    x = self.last_conv(x)
    x = self.avgp(x)
    x = x.view((x.shape[0], -1))
    return x
```

Training Model

```
In [578]: @torch.no grad()
          def evaluate(model, val loader):
              model.eval()
              outputs = [model.validation step(batch) for batch in val loader]
              return model.validation_epoch_end(outputs)
          def get lr(optimizer):
              for param_group in optimizer.param_groups:
                  return param group['lr']
          def fit_one_cycle(epochs, max_lr, model, train_loader, val_loader,
                            weight_decay=0, grad_clip=None, opt_func=torch.optim.SGD):
              torch.cuda.empty_cache()
              history = []
              # Set up cutom optimizer with weight decay
              optimizer = opt_func(model.parameters(), max_lr, weight_decay=weight_decay)
              # Set up one-cycle learning rate scheduler
              sched = torch.optim.lr scheduler.OneCycleLR(optimizer, max lr, epochs=epochs)
                                                           steps per epoch=len(train loader)
              for epoch in range(epochs):
                  # Training Phase
                  model.train()
                  train losses = []
                  lrs = []
                  for batch in tqdm(train loader):
                      loss = model.training step(batch)
                      train losses.append(loss)
                      loss.backward()
                      # Gradient clipping
                      if grad clip:
                          nn.utils.clip grad value (model.parameters(), grad clip)
                      optimizer.step()
                      optimizer.zero_grad()
                      # Record & update Learning rate
                      lrs.append(get_lr(optimizer))
                      sched.step()
                  # Validation phase
                  result = evaluate(model, val_loader)
                  result['train_loss'] = torch.stack(train_losses).mean().item()
                  result['lrs'] = lrs
                  model.epoch_end(epoch, result)
                  history.append(result)
              return history
```

```
In [579]: model = to_device(FaceCnnModel(), device)
```

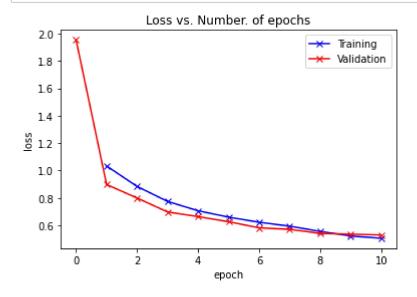
```
In [580]: max_lr=0.01
    grad_clip = 0.1
    weight_decay = 1e-4
    epochs=10
    opt_func = torch.optim.Adam
In [581]: history = [evaluate(model, validation_loader)]
```

```
In [582]: history += fit_one_cycle(epochs, max_lr, model, training_loader, validation_loade
                                   grad_clip=grad_clip,
                                   weight_decay=weight_decay,
                                   opt func=opt func)
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [0], last lr: 0.0028, val loss: 0.8980, val acc: 0.5700
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [1],last_lr: 0.0076, val_loss: 0.7991, val_acc: 0.6394
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [2], last lr: 0.0100, val loss: 0.6972, val acc: 0.6778
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [3],last_lr: 0.0095, val_loss: 0.6632, val_acc: 0.7049
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [4], last lr: 0.0081, val loss: 0.6258, val acc: 0.7281
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [5], last lr: 0.0061, val loss: 0.5811, val acc: 0.7371
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [6], last lr: 0.0039, val loss: 0.5704, val acc: 0.7527
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [7], last lr: 0.0019, val loss: 0.5406, val acc: 0.7663
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [8], last lr: 0.0005, val loss: 0.5353, val acc: 0.7695
          HBox(children=(FloatProgress(value=0.0, max=133.0), HTML(value='')))
          Epoch [9], last lr: 0.0000, val loss: 0.5291, val acc: 0.7780
```

Plotting and Comparisions

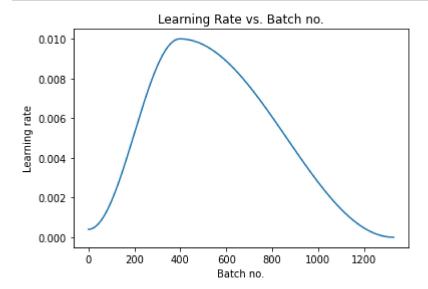
```
In [583]: def plot_losses(history):
    train_losses = [x.get('train_loss') for x in history]
    val_losses = [x['val_loss'] for x in history]
    plt.plot(train_losses, '-bx')
    plt.plot(val_losses, '-rx')
    plt.xlabel('epoch')
    plt.ylabel('loss')
    plt.legend(['Training', 'Validation'])
    plt.title('Loss vs. Number. of epochs');
```

In [584]: plot_losses(history)



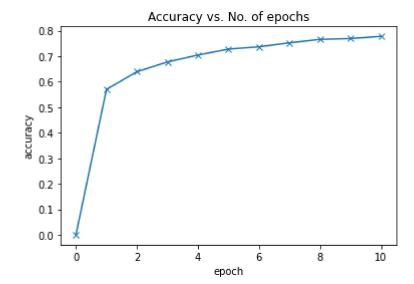
```
In [585]: def plot_lrs(history):
    lrs = np.concatenate([x.get('lrs', []) for x in history])
    plt.plot(lrs)
    plt.xlabel('Batch no.')
    plt.ylabel('Learning rate')
    plt.title('Learning Rate vs. Batch no.');
```

```
In [586]: plot_lrs(history)
```



```
In [587]: def plot_accuracies(history):
    accuracies = [x['val_acc'] for x in history]
    plt.plot(accuracies, '-x')
    plt.xlabel('epoch')
    plt.ylabel('accuracy')
    plt.title('Accuracy vs. No. of epochs');
```

In [588]: plot_accuracies(history)



```
In [589]: def predict_single(image):
    xb = image.unsqueeze(0)
    xb = to_device(xb, device)
    preds = model(xb)
    prediction = preds[0]
    # test=torch.max(prediction)
# # print(test)
# index = prediction.cpu().data.numpy().argmax()
# # print("Prediction: ", prediction)
    return show_sample(image, prediction, predict = True)
```

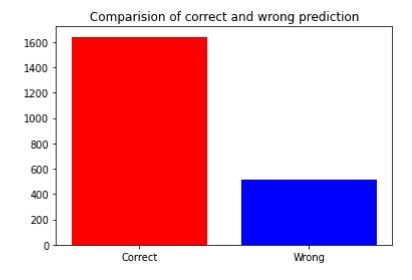
```
In [590]: prediction_list = []
    for i in range(len(factory.testing)):
        prediction_list.append(predict_single(factory.testing[i][0]) == int(factory.testing[i][0])
```

```
In [591]: correct = prediction_list.count(True)
wrong = prediction_list.count(False)
height = [correct, wrong]
bars = ("Correct", "Wrong")
x_pos = np.arange(len(bars))

# Create bars with different colors
plt.bar(x_pos, height, color=['red','blue'])

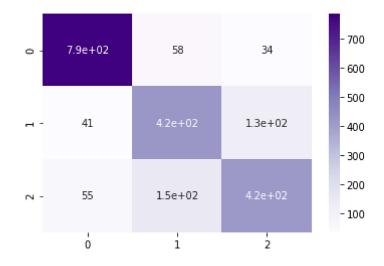
# Create names on the x-axis
plt.xticks(x_pos, bars)
plt.title("Comparision of correct and wrong prediction")
# Show graph
```

Out[591]: Text(0.5, 1.0, 'Comparision of correct and wrong prediction')



```
In [597]: sn.heatmap(confusion_matrix,annot=True,cmap='Purples')
```

Out[597]: <matplotlib.axes._subplots.AxesSubplot at 0x7f188ea25910>



```
In [593]: after = [evaluate(model, validation_loader)]
after

Out[593]: [{'val_acc': 0.7738339900970459, 'val_loss': 0.5342395901679993}]
```

```
In [601]: accuracy = (confusion_matrix.diag()/confusion_matrix.sum(1))
```

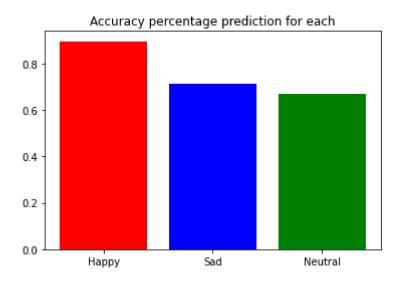
Out[601]: [0.8953356146812439, 0.7104377150535583, 0.669329047203064]

```
In [604]: height = accuracy.tolist()
  bars = ("Happy", "Sad", "Neutral")
  x_pos = np.arange(len(bars))

# Create bars with different colors
  plt.bar(x_pos, height, color=['red','blue', "green"])

# Create names on the x-axis
  plt.xticks(x_pos, bars)
  plt.title("Accuracy percentage prediction for each")
# Show graph
```

Out[604]: Text(0.5, 1.0, 'Accuracy percentage prediction for each')



Saving Model

```
In [605]: torch.save(model, 'Benten_CNN.pt')
```