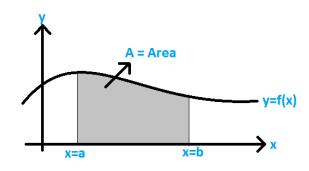
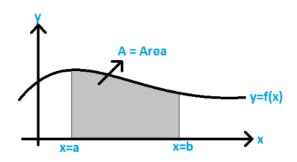
# **Applications of Integration**

# Area

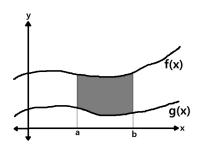
Integration is really useful when finding the area under graphs .i.e. The area between an axis and the curve. It can also be used to find the area bound due to multiple curves.

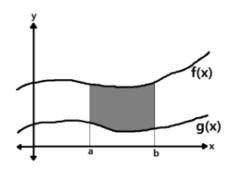


In the following graph, Area is:



$$A = \int_a^b f(x) \, dx$$

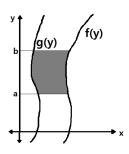


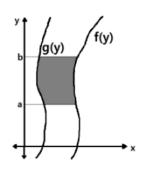


#### Area bound by two (or more) curves:

Consider the functions f(x) and g(x) in [a,b] where f(x)>g(x). Then the area bound by these curves from x=a to x=b is:

$$A = \int_a^b ig(f(x) - g(x)ig)\,dx$$





In this case, we have two functions f(y) and g(y) in [a,b]. If f(y)>g(y), then the area bound by the curves from y=a to y=b is:

$$A = \int_a^b ig(f(y) - g(y)ig)\,dy$$

Now, let's look at this table with row representing quadrant and columns representing variable of integration and fill in the sign:

|     | $\boldsymbol{x}$ as variable of integration | $\boldsymbol{y}$ as variable of integration |
|-----|---|---|
| Q 1 | +   | +   |
| Q 2 | +   | _   |
| Q 3 | _   | _   |
| Q 4 | _   | +   |

When finding the area of an enclosed region, it is advised to take the absolute value of the evaluated integral, so that the areas of the region in each quadrant gets added.

# **Volume**

## **Cross Section / Slicing Method**

Similar to finding area of 2D figures using integration, volumes of any 3D shape can also be found using the same method, using only two vairables such as x and y.

**Cross Section**: The region of intersection of a plane with a solid is called a cross section.

For any solid, the volume V is just the sum of areas of each cross section. If the area of cross section varies with A(x), and the height of the solid is h=b-a, where x=b is the right end of the solid and x=a is the left end of the solid, we may take individual cross sections of thickness dx and add them all.

Let the  $i^{
m th}$  cross section be written as  $x_i^*$  , then using Riemann sum,

$$V = \lim_{n o\infty} \sum_{i=1}^n A(x_i^*)\, dx = \int_a^b A(x)\, dx$$

We limit  $n \to \infty$  because the more cross sections we take with lesser thickness, the more accurate our volume becomes and that is what the integral exactly does.

### Solids of Revolution

Certain 2D shapes, when rotated along an axis form a 3D solid, with axis at the centre. All such 3D solids have a circular cross section perpendicular to the axis. Such 3D solids are called solids of revolution.

#### **Disk Method**

This method is a way to find the volume of such solids where the solid is filled inside.

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Consider a function f(x) to create a 2D shape under it with the axis (x-axis). When this shape is rotated about the axis, we obtain a solid, where the cross section is non-uniform and varies based on the area function A(x). Since the cross sections are circular, the area function definitely represents a circle. Here, the radius varies with x as f(x) due to the shape that forms the solid.

Hence, 
$$A(x) = \pi \cdot ig(f(x)ig)^2$$

Now, to find the volume V, just integrate the area function. Hence,

$$V = \int_a^b A(x) \, dx = \int_a^b \pi \cdot ig(f(x)ig)^2 \, dx$$

#### **Washer Method**

This method is a way to find the volume of such solids where the solid is hollow inside (or not filled completely).

Consider a function f(x) to create a 2D shape under it with the axis (x-axis). When this shape is rotated about the axis, we obtain a solid, where the cross section is non-uniform and varies based on the area function  $A_1(x)$ . Since the cross sections are circular, the area function definitely represents a circle. Here, the radius varies with x as f(x) due to the shape that forms the solid.

Hence, 
$$A_1(x) = \pi \cdot ig(f(x)ig)^2$$

Also, consider a function g(x) that represents the inner curve, and hence the inner portion of the solid. Now, let the area of the curve be  $A_2(x)$ . This cross section is also circular because the shape is being rotated.

Hence, 
$$A_2(x) = \pi \cdot ig(g(x)ig)^2$$

Now the final area of cross section becomes  $A(x)=A_1(x)-A_2(x)$  because the volume due to g(x) must be scooped out.

Now, to find the volume V, just integrate the area function. Hence,

$$V = \int_a^b A(x) \, dx = \int_a^b \pi \cdot \left( \left( f(x) 
ight)^2 - \left( g(x) 
ight)^2 
ight) dx$$

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