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Project Group Report

Command	Binary	Hex	Description
irmovl	0x1110 ———	Oxe-	This instruction takes a register in the next four bits, and prepares to insert that number into the given register. Example: e4 20 will put the digit number 32 into register %ecx
rmmovl	0x1101 ———	Oxd-	This will put the contents of a given register into a place in RAM. Example: d4 80 will place the contents of register %ecx into the memory slot 80 in the RAM memory. The first four bits are the command, the second four are the register being commanded. The program should know to grab the next byte inorder to place the value in that memory address.
mrmovl	N/A	N/A	N/A

Command	Binary	Hex	Description
addl	0x0010 ———	0x2-	Adds the contents of two registers. Example: register %ecx has the digit 32 (20 or 0010 0000) inside of it, and register %edx has the digit 3 inside of it (03 or 0000 0011). What it will do is add 32 and 3 to make 35 (23 or 0010 0011).
halt	0x0111 ———	0x7-	Basically skips the place in memory or doesnt do anything. It is looking for a starter 7
%eax	0x 0000	0x-0	The first register, represented by a 0 in RAM. All registers need one of the two implemented commands in order to use it, as the four bits will always follow the four bits of a command.
%ebx	0x 0100	0x-4	The second register, represented by a 4 in RAM.
%есх	0x 1000	0x-8	The third register, represented by an 8 in RAM.
%edx	0x 1100	0x-c	The fourth register, represented by a c in RAM.
0x0000: 0x0000: 30f00100 0x0006: 30f30000 0x000c: 40030000 0x0012: 30f00200	00000 irmovl \$0, 00000 rmmovl %ea	%ebx x, 0(%ebx)	30 f0 01 00 30 f3 00 00

```
0x0000: 30f001000000 | irmovl $1, %eax

0x0000: 30f300000000 | irmovl $0, %ebx

0x0000: 400300000000 | rmmovl %eax, 0(%ebx)

0x0012: 30f002000000 | irmovl $2, %eax

0x0018: 400304000000 | rmmovl %eax, 4(%ebx)

0x001e: 30f003000000 | irmovl $3, %eax

0x0024: 400308000000 | rmmovl %eax, 8(%ebx)

0x002a: 30f004000000 | irmovl $4, %eax

0x0030: 40030c0000000 | rmmovl %eax, 12(%ebx)
```

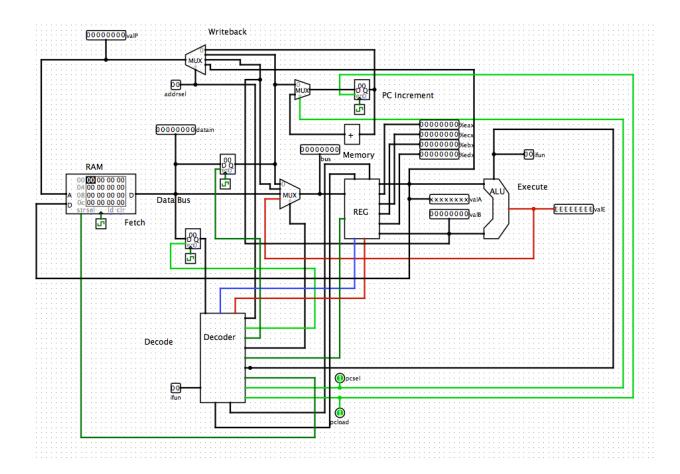
```
irmovl $5, %eax
0x0036: 30f005000000
0x003c: 30f300000000
                        irmovl $0, %ebx
0x0042: 400310000000
                        rmmovl %eax, 16(%ebx)
                        irmovl $6, %eax
0x0048: 30f006000000
0x004e: 400314000000
                        rmmovl %eax, 20(%ebx)
0x0054: 30f007000000
                        irmovl $7, %eax
0x005a: 400318000000
                        rmmovl %eax, 24(%ebx)
0x0060: 30f008000000
                        irmovl $8, %eax
0x0066: 40031c000000
                        rmmovl %eax, 28(%ebx)
0x006c: 500300000000
                        mrmovl 0(%ebx), %eax
0x0072: 501310000000
                        mrmovl 16(%ebx), %ecx
0x0078: 6001
                        addl %eax, %ecx
0x007a: 401320000000
                        rmmovl %ecx, 32(%ebx)
                        mrmovl 4(%ebx), %eax
0x0080: 500304000000
                        mrmovl 20(%ebx), %ecx
0x0086: 501314000000
0x008c: 6001
                        addl %eax, %ecx
0x008e: 401324000000
                        rmmovl %ecx, 36(%ebx)
0x0094: 500308000000
                        mrmovl 8(%ebx), %eax
0x009a: 501318000000
                        mrmovl 24(%ebx), %ecx
0x00a0: 6001
                        addl %eax, %ecx
0x00a2: 401328000000
                        rmmovl %ecx. 40(%ebx)
0x00a8: 50030c000000
                        mrmovl 12(%ebx), %eax
                                                   50 03 0c
0x00ae: 50131c000000
                                                   50 13 1c
0x00b4: 6001
                        addl %eax, %ecx
                                                  60 01
0x00b6: 40132c000000
                        rmmovl %ecx, 44(%ebx)
                                                  40 13 2c
0x00bc: 00
                       halt
```

```
● ● ↑ jaredwheeler — ssh -Y jaredwheeler94@compute.cse.tamu.edu — 80×24
[jaredwheeler94]@compute-linux1 ~/CSCE312/Project> (03:11:01 12/04/16)
:: ../sim/yis Project_Assembly.yo
Stopped in 35 steps at PC = 0xbc. Status 'HLT', CC Z=0 S=0 0=0
Changes to registers:
        0×00000000
                        0x00000004
%eax:
%ecx:
        0×00000000
                        0x0000000c
Changes to memory:
0x0000: 0x0001f030
                        0x00000001
0x0004: 0xf3300000
                        0x00000002
                        0x00000003
0×0008: 0×00000000
0x000c: 0x00000340
                        0x00000004
0x0010: 0xf0300000
                        0×00000005
0x0014: 0x00000002
                        0x00000006
0x0018: 0x00040340
                        0×00000007
0x001c: 0xf0300000
                        0x00000008
0x0020: 0x00000003
                        0x00000006
0x0024: 0x00080340
                        0×00000008
0x0028: 0xf0300000
                        0x0000000a
0x002c: 0x00000004
                        0x0000000c
[jaredwheeler94]@compute-linux1 ~/CSCE312/Project> (03:11:12 12/04/16)
```

Matrix A:
$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

Matrix B: $\begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix}$

Matrix C: $\begin{pmatrix} 6 & 8 \\ 1 & 3 \end{pmatrix}$



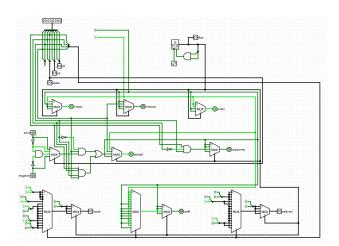
(No idea what is up with the red wire in this picture)

The Processor main: The design is based off of what was presented in the lecture powerpoint, featuring the clearly labeled Fetch, Decode, Execute, Memory, Writeback, and PC Increment sections.

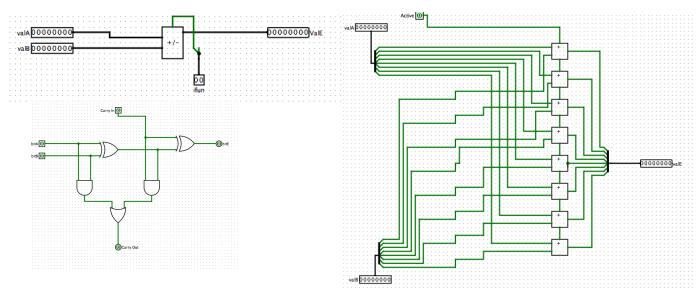
<u>Fetch</u>: Read the instruction memory from the assembly image that needs to be uploaded. It will send out the instructions that the image dictates.

<u>Decode</u>: Tells the program what to put into the registers, and what to do with it. In this program,

the only things it can do is write to memory, load a register, and add registers. This is the sections that this will be decided.



<u>Execute</u>: The ALU consists of three circuits: the bit adder from lab 4, the eight bit adder from Lab 4, and a condensed ALU that is easier to look at. All of this particular circuit is pulled directly from Lab 4.



Memory: Gives a value in memory to write to.
Write Back: Writes the address in memory back to the registers.
PC Update: Increments the program counter by one to get the next instruction.

