

# ECE 113 HW 2

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## Problem 1

(a)

$$x_{1_{even}}[n] = \frac{u(n-3) + u(-(n+3))}{2}$$
$$x_{1_{odd}}[n] = \frac{u(n-3) - u(-(n+3))}{2}$$

(b)

$$x_{2_{even}}[n] = \frac{\alpha^n u[n-1] + \alpha^{-n} u[-(n+1)]}{2}$$
$$x_{2_{odd}}[n] = \frac{\alpha^n u[n-1] - \alpha^{-n} u[-(n+1)]}{2}$$

(c)

$$x_{3_{even}}[n] = \frac{n\alpha^n u[n-1] - n\alpha^{-n} u[-(n+1)]}{2}$$

$$x_{2_{even}}[n] = \frac{\alpha^n u[n-1] + n\alpha^{-n} u[-(n+1)]}{2}$$

(d)

$$\begin{aligned} x_{4_{even}}[n] &= x_4[n] = \alpha^{|n|} \\ x_{4_{odd}}[n] &= 0 \end{aligned}$$

## Problem 2

(a)

False, for instance,  $x_n[n] = \cos(\pi n)$  is a power signal since it has a bounded power of  $p(x) = \frac{1}{2} \sum_{n=0}^1 |\cos(\pi n)|^2 = 1$ . while the energy is  $\sum_{n=-\infty}^{\infty} |\cos(\pi n)|^2 = \infty$ .

(b)

True, for an energy sequence we have that  $\sum_{n=-\infty}^{\infty} |x_n[n]|^2 = e_x < \infty$ , therefore for the power of the signal we have in general

$$P_x = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x_n[n]|^2$$

therefore

$$\begin{aligned} P_x &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} e_x \\ &= e_x \lim_{N \rightarrow \infty} \frac{1}{2N+1} \\ &= 0 \end{aligned}$$

(c)

True, first we start by proving that the energy of a signal  $x[n-1]$  is the same as the energy of  $x[n]$ ,  $e_x$ . We have that the energy of  $x[n-1]$ ,  $e_{x-1}$  is

$$e_{x-1} = \sum_{n=-\infty}^{\infty} |x[n-1]|^2$$

Letting  $k=n-1$  we have that

$$\begin{aligned} \sum_{n=-\infty}^{\infty} |x[n-1]|^2 &= \sum_{k=-\infty-1}^{\infty+1} |x[k]|^2 \\ &= \sum_{k=-\infty}^{\infty} |x[k]|^2 \\ &= e_x \end{aligned}$$

therefore we have that

$$\begin{aligned} e_x - e_{x-1} &= \sum_{n=-\infty}^{\infty} |x[n]|^2 - \sum_{k=-\infty-1}^{\infty+1} |x[k]|^2 \\ e_x - e_x &= |x[-\infty]|^2 + |x[\infty]|^2 \\ 0 &= |x[-\infty]|^2 + |x[\infty]|^2 \end{aligned}$$

Since  $|x[-\infty]|^2 \geq 0$  and  $|x[\infty]|^2 \geq 0$  we have that  $x[n] = 0$  as  $n \rightarrow \infty$

(d)

True, let  $x[n] = \sqrt{|n|}$ , then we have that the power of the signal  $P_x$  is

$$\begin{aligned} P_x &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x_n[n]|^2 \\ &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N \left( \sqrt{|n|} \right)^2 \\ &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |n| \\ &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \left( 1 + 2 \sum_{n=1}^N n \right) \\ &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \left( 1 + 2 \frac{N(N+1)}{2} \right) \\ &= \lim_{N \rightarrow \infty} \frac{N(N+1) + 1}{2N+1} \\ &= \infty \end{aligned}$$

### Problem 3

For System 1 let  $x[n] \leq B < \infty$  for all  $n$ , we have

$$y[n] = \log(|x[n-1]|)$$

since  $x[n-1] \leq B$  for all  $n$  and since  $\log(x)$  is an convex function

$$y[n] = \log(|x[n-1]|) \leq \log(B) < \infty$$

Therefore System I is BIBO stable. To test for time invariant, let the input  $x[n-k]$  corresponds to the output  $y_1$ , then we have that

$$y_1[n] = \log(|x[(n-1)-k]|) = y[n-k]$$

therefore System I is time invariant.

For System II let  $x[n] \leq B < \infty$  for all  $n$ , we have

$$y[n] = e^{x[2n]}$$

since  $x[n] \leq B$  for all  $n$  and since  $e^x$  is an convex function, we have

$$y[n] = e^{x[2n]} \leq e^B < \infty$$

Therefore System II is BIBO stable. To test for time invariant, let the input  $x[n - k]$  corresponds to the output  $y_2$ , then we have that

$$y_2[n] = e^{x[2n-k]}$$

this is not equal to

$$y[n - k] = e^{x[2(n-k)]}$$

therefore System II is time variant.

Thus we have that statement (a) is correct.