## ECE 141 Homework 4

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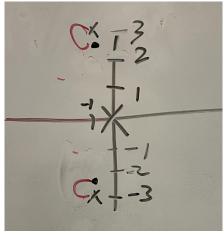
May 17, 2022

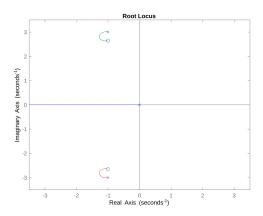
## Problem 5.5

(c)

L(s) has zeros at  $\frac{-2\pm j2\sqrt{7}}{2}$ , and poles at 0 and  $\frac{-2\pm j6}{2}$ , therefore we have  $\alpha=0$   $\phi_1=180^\circ$ , And the departure angle for poles  $-1\pm 3j$  is  $\pm 161.565^\circ$ , And the arival angle for the zeros  $-1\pm\sqrt{7}j$  is  $\pm 200^\circ$ 

Therefore the sketch fo the root locus looks like the following





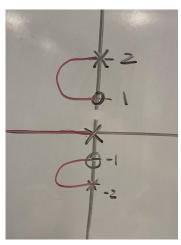
That was produced with this code

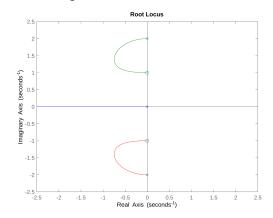
```
sys = tf([1 2 8],[1 2 10 0]);
rlocus(sys)
ylim([-3.5 3.5])
xlim([-3.5 3.5])
```

(e)

L(s) has zeros at  $\pm j$ , and poles at 0 and  $\pm 2j$ , therefore we have  $\alpha=0$   $\phi_1=180^\circ$ , And the departure angle for poles  $\pm 2j$  is  $180^\circ$ , And the arival angle for the zeros  $\pm 1j$  is  $180^\circ$ 

Therefore the sketch fo the root locus looks like the following





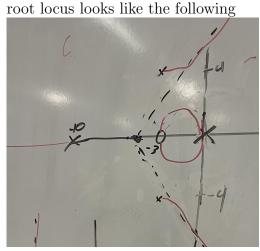
That was produced with this code

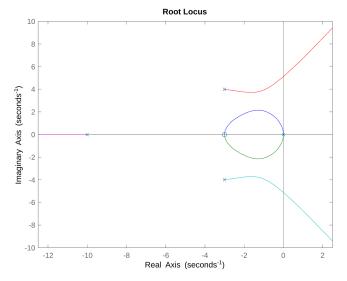
```
sys = tf([1 0 1],[1 0 4 0]);
rlocus(sys)
ylim([-2.5 2.5])
xlim([-2.5 2.5])
```

## Problem 5.7

(c)

This functions has 2 zeros at -3 and 5 poles: 2 at 0, 1 at -10, and 2 at  $-3 \pm 4j$  Therefore  $\alpha = -3.333$  and and that the three branches intersecting the real axis, intersect at degrees of  $60^{\circ}$ ,  $180^{\circ}$ , and  $300^{\circ}$ , therefore we have for pole -10 + 0j, departure angle 1:  $180^{\circ}$  for poles  $-3 \pm 4j$  the departure angles are  $\pm 13.484^{\circ}$  for the dual poles at the 0 the departure angles are  $\pm 90^{\circ}$  for the dual zeros at 0 the arrival angles ar  $\pm 90^{\circ}$  Therefore the sketch fo the





That was produced with this code

```
sys = tf([1 6 9],[1 16 85 250 0 0]);
rlocus(sys)
ylim([-10 10])
xlim([-12.5 2.5])
```

(e)

L(s) had zeros at  $-1 \pm 1j$  and 4 poles, 2 at 0, 1 at -2 and -3. Therefore we have

$$\alpha = -1.5$$

And there are two lines asymptomatic to this at angles of  $\pm 90^{\circ}$ 

We have

for pole -3, departure angle 1:  $0.0^{\circ}$ 

for pole -2, departure angle 1: 180°

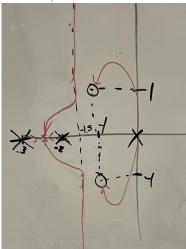
for pole 0, departure angle 1: 270°

for pole 0, departure angle 2: 90°

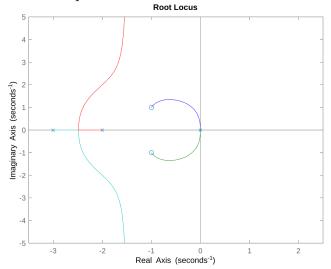
for zero  $-1 \pm 1j$ , arrival angle:  $\pm 71.565^{\circ}$ 

Furthermore from Rule 6 we have that there are multiple roots where s =

-2.485, therefore the sketch of the root locus looks like



This coresponds well with the matlab root locus plot:  ${}^{_{_{{\bf Root Locus}}}}$ 



That was produced with this code

```
sys = tf([1 2 2],[1 5 6 0 0]);
rlocus(sys)
ylim([-5 5])
xlim([-3.5 2.5])
```

## Problem 5.8

(e)

L(s) has a zero at -2 and 4 poles, 2 at -6, one at 0, and one at 1. Therefore,

$$\alpha = -3$$

and three lines are asymptomatic to it at angles of 180, 60, and 180. For the poles we have that:

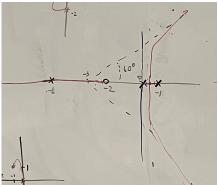
for pole -6, departure angle 1:  $180^{\circ}$ 

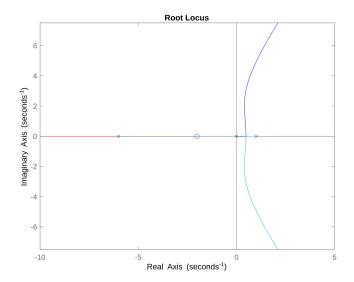
for pole -6, departure angle 2:  $0^{\circ}$ 

for pole 0, departure angle 1:  $0^{\circ}$ 

for pole 1, departure angle 1: 180°

and for the zero we have that the angle of arival is  $180^{\circ}$ , Furthermore from Rule 6 we have that there are multiple roots where s=-6,0.488, therefore the sketch of the root locus looks something like





That was produced with this code

```
sys = tf([1 2],[1 11 24 -36 0]);
rlocus(sys)
ylim([-7.5 7.5])
xlim([-10 5])
```