

# Exercise 1

Consider the state space graph shown above. A is the start state and G is the goal state. The costs for each edge are shown on the graph. Each edge can be traversed in both directions. Note that the heuristic  $h_1$  is consistent but the heuristic  $h_2$  is not consistent.

## (a) Possible paths returned

For each of the following graph search strategies (*do not answer for tree search*), mark which, if any, of the listed paths it could return. Note that for some search strategies the specific path returned might depend on tie-breaking behavior. In any such cases, make sure to mark *all* paths that could be returned under some tie-breaking scheme.

Search Algorithm	A-B-D-G	A-C-D-G	A-B-C-D-F-G
Depth first search			X
Breadth first search		X	
Uniform cost search			X
A* search with heuristic ( $h_1$ )			
A* search with heuristic ( $h_2$ )			

## Nós de árvore



