

# Exercise 1

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Consider the state space graph shown above. A is the start state and G is the goal state. The costs for each edge are shown on the graph. Each edge can be traversed in both directions. Note that the heuristic  $h_1$  is consistent but the heuristic  $h_2$  is not consistent.

## (a) Possible paths returned

For each of the following graph search strategies (*do not answer for tree search*), mark which, if any, of the listed paths it could return. Note that for some search strategies the specific path returned might depend on tie-breaking behavior. In any such cases, make sure to mark *all* paths that could be returned under some tie-breaking scheme.

| Search Algorithm                   | A-B-D-G | A-C-D-G | A-B-C-D-F-G |
|------------------------------------|---------|---------|-------------|
| Depth first search                 |         |         | X           |
| Breadth first search               |         | X       |             |
| Uniform cost search                |         |         | X           |
| A* search with heuristic ( $h_1$ ) |         | X       |             |
| A* search with heuristic ( $h_2$ ) |         | X       |             |

## Nós de árvore



