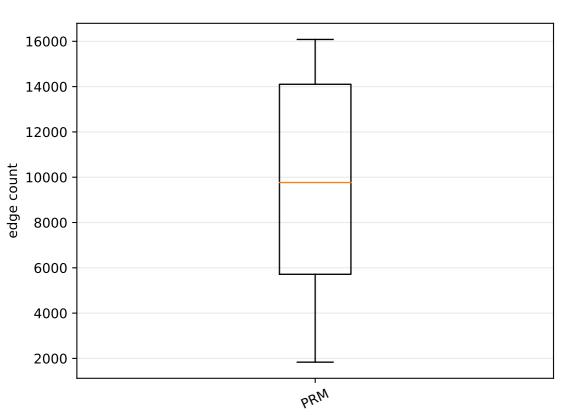
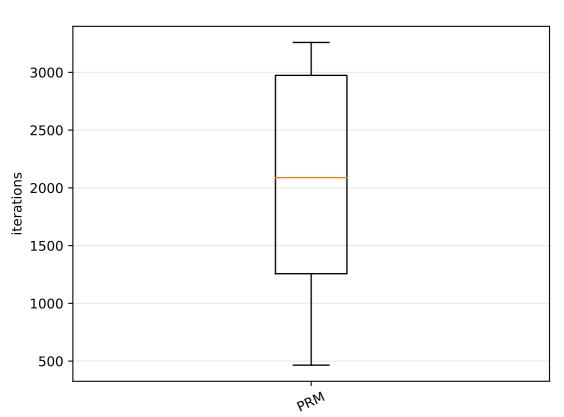


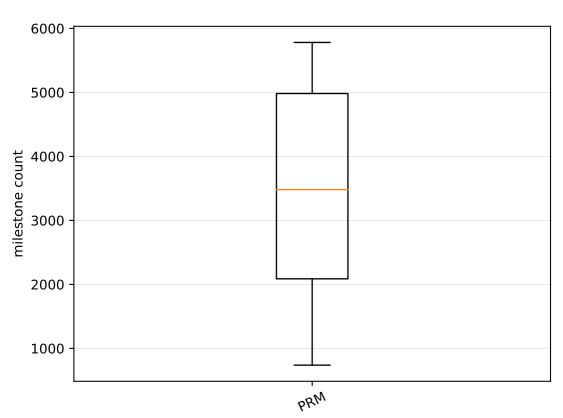
Motion planning algorithm



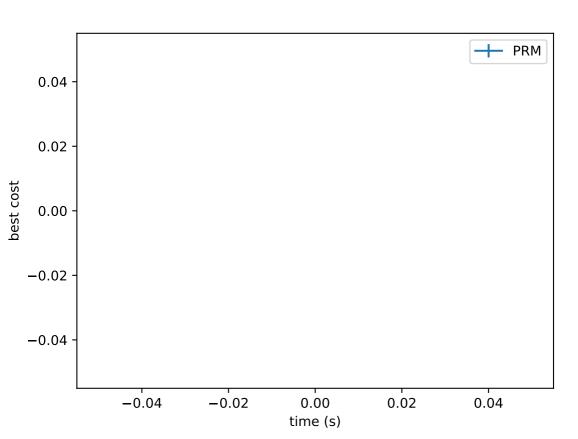
Motion planning algorithm

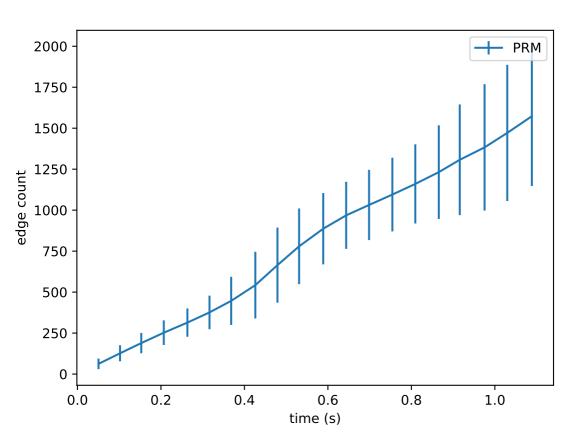


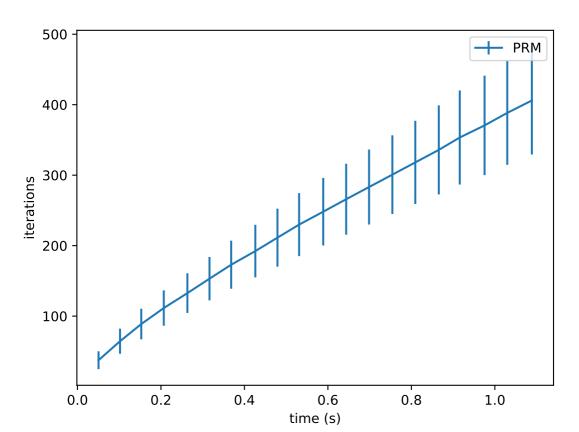
Motion planning algorithm

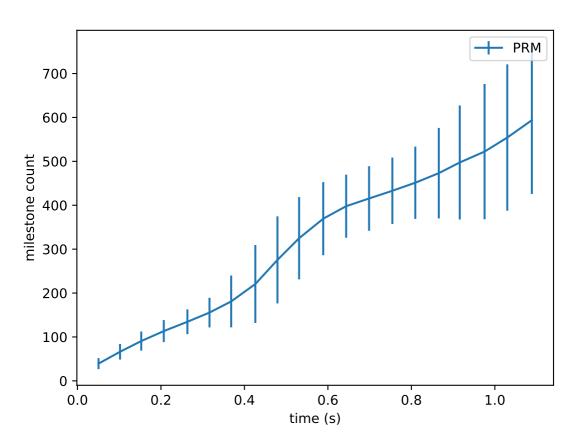


Motion planning algorithm









Experiment "cubicles\_obstaclebased\_sampler"

Number of averaged runs: 500

Time limit per run: 10 seconds

Memory limit per run: 10000 MB