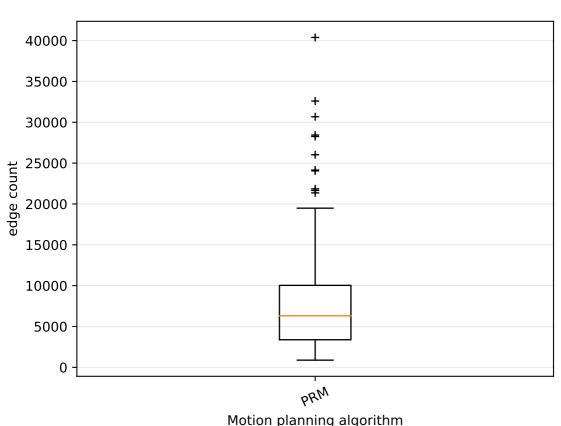
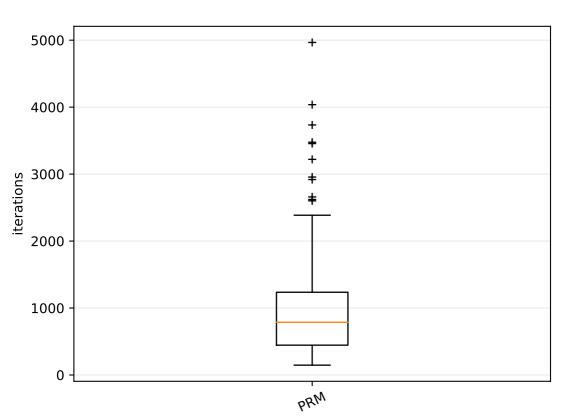
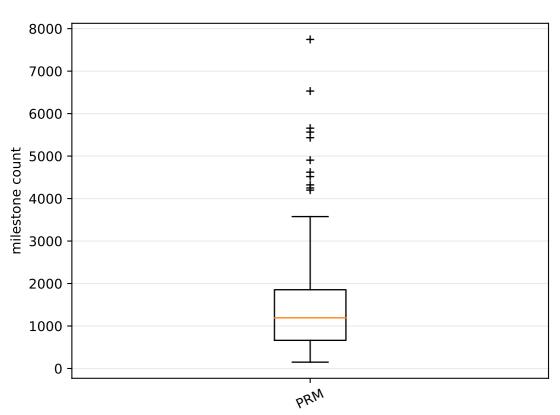


Motion planning algorithm

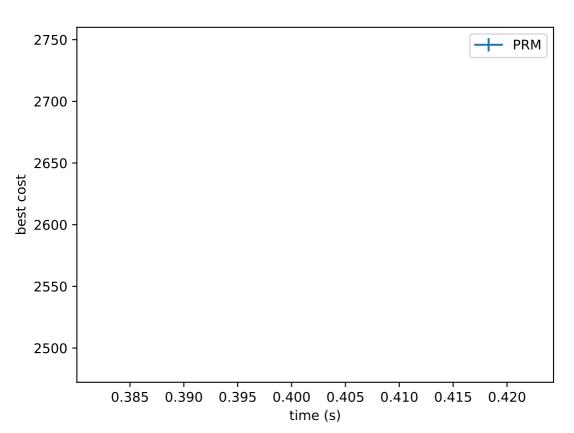


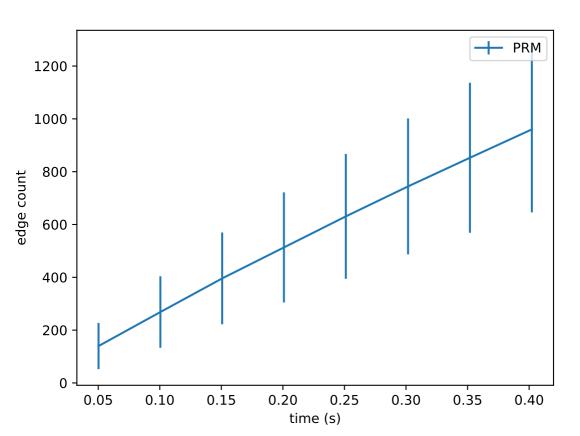


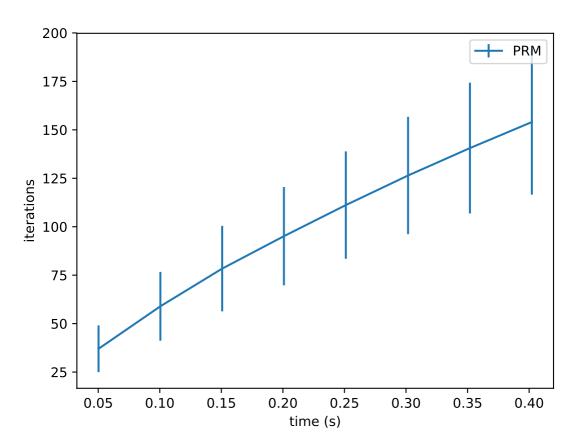
Motion planning algorithm

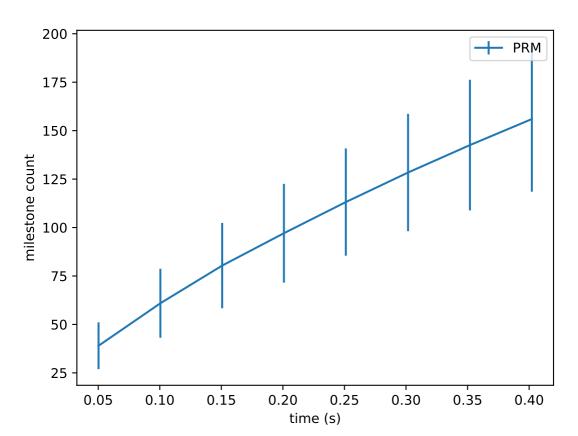


Motion planning algorithm









Experiment "cubicles_uniform_sampler"

Number of averaged runs: 100

Time limit per run: 50 seconds

Memory limit per run: 10000 MB