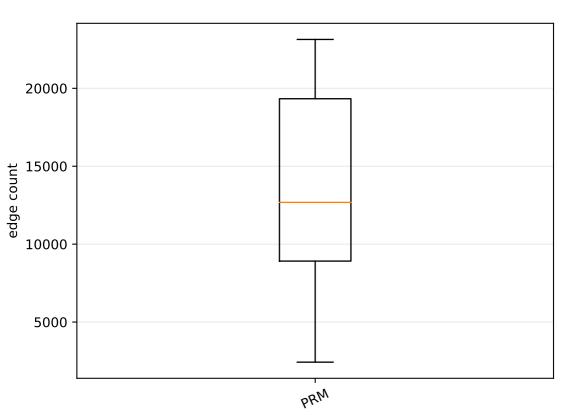
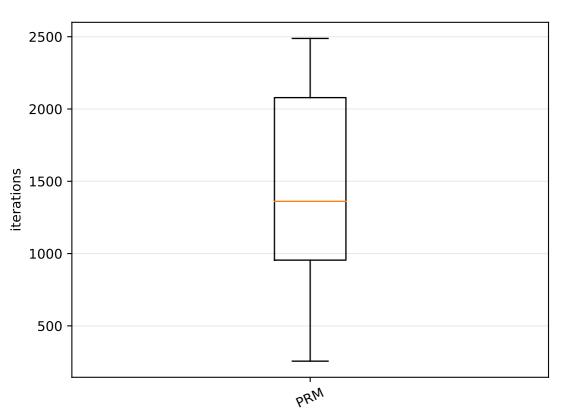


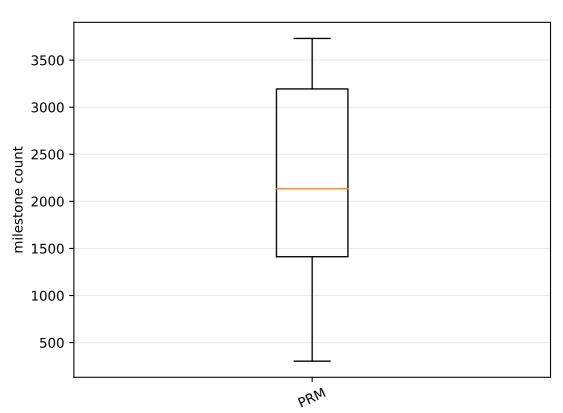
Motion planning algorithm



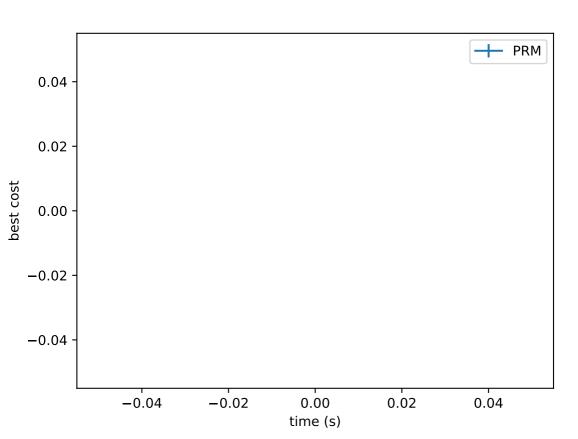
Motion planning algorithm

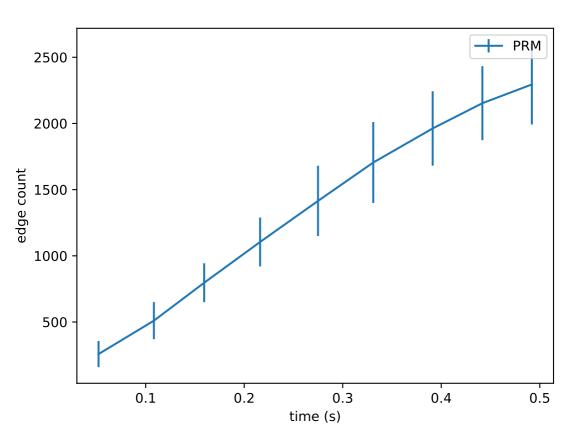


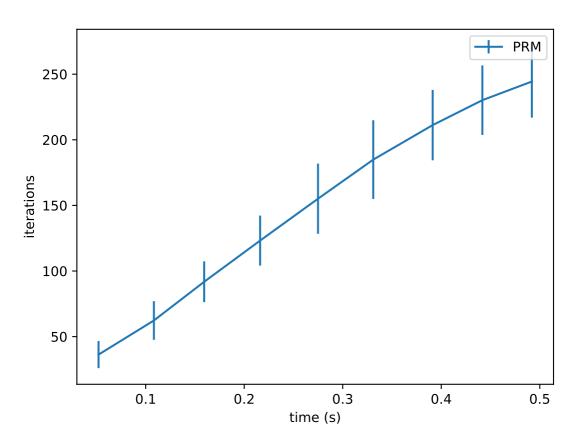
Motion planning algorithm

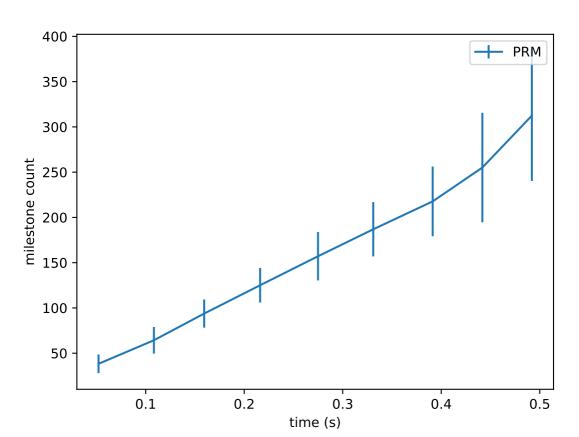


Motion planning algorithm









Experiment "Twistycool_uniform_sampler"

Number of averaged runs: 10

Time limit per run: 5 seconds

Memory limit per run: 1000 MB