COMP 540 HW 5

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Due: 3/5/2018

1: Deep neural networks

1. Why do deep neural networks typically outperform shallow networks?

Solution. By using deep neural network and adding more layers, we can approximate function using less parameters. The deep network encodes a set of prior beliefs about the structure of the function we want to learn. Thus, the deep nerual networks reduce the amount of data we should use to get a satisfying result.

2. What is leaky RELU activation and why is it used?

Solution. Leaky relu is basically based on relu activation function and tries to fix the 'dying' problem of relu. When x < 0, the leaky relu has a small slope instead of being zero.

The reason why we use leaky relu is that it can give a small constant gradient when the input falls in the region x < 0. So it can fix the problem of "dead relu".

3. In one or more sentences, and using sketches as appropriate, contrast: AlexNet, VGGNet, GoogleNet and ResNet. What is the one defining characteristic of each network?

Solution. AlexNet: AlexNet uses RELU activate function instead of sigmoid function for the first time. And it also introduce a new dropout layer in the network.

VGGNet: VGGNet consists of either 16 or 19 convolutional layers and has very uniform architecture.

GoogleNet: This module is based on several very small convolutions in order to drastically reduce the number of parameters.

ResNet: ResNet introduces a so called "shortcut connection" that skips one or more layers, which allow the gradients can be backprop to the first layers. This allows us to train a much deeper network up to 152 layers.

2: Decision trees, entropy and information gain

1. Show that H(S)1 and that H(S) = 1 when p = n.

Solution. Since

$$H(q) = -qlog(q) - (1-q)log(1-q)$$

the second derivative of the -H(q) is non-negative, so the negative entropy is convex. The H(q) is concave. The maximum can be obtained at $\frac{\partial H}{\partial q} = 0$

$$\frac{\partial H}{\partial q} = -log(q) + log(1 - q)$$

thus we got q = 0.5, which means that p = n and H(S) = 1.

Therefore, H(S)1 and that H(S) = 1 when p = n.

2. Calculate the reduction in cost using misclassification rate, entropy, and Gini index for models A and B. Which is the preferred split (model A or model B) according to these cost calculations?

Solution. Misclassification rate:

$$error_A = \frac{100 + 100}{400 + 400} = 0.25$$

$$error_B = \frac{200}{400 + 400} = 0.25$$

Entropy For both A and B:

$$H(D) = 1$$

For A:

$$H(D_1) = H(D_2) = -0.75log(0.75) - 0.25log(0.25) = 0.811$$

 $g(D, A) = H(D) - 0.5H(D_1) - 0.5H(D_2) = 0.189$

For B:

$$H(D_1) = -\frac{1}{3}log(\frac{1}{3}) - \frac{2}{3}log(\frac{2}{3}) = 0.913$$

 $H(D_2) = 0$

$$g(D,B) = H(D) - 0.75H(D_1) - 0.25H(D_2) = 0.312$$

Gini Index:

$$Gini(A) = 0.5(1 - 0.75^{2} - 0.25^{2}) + 0.25(1 - 0.25^{2} - 0.75^{2}) = 0.375$$
$$Gini(B) = 0.75(1 - \frac{2}{3}^{2} - \frac{1}{3}^{2}) + 0.25(1 - 1 - 0) = \frac{1}{3}$$

Among these three cost calculations, the entropy is the preferred split since the difference between A and B in this cost calculation is the biggest.

3. Can the misclassification rate ever increase when splitting on a feature? If so, give an example. If not, give a proof.

Solution. No, the misclassification rate will not increase when splitting on a feature.

3: Bagging

1. Assuming that the individual errors $\epsilon_l(\mathbf{x})$ have zero mean and are uncorrelated, that is $E_x[\epsilon_l(x)] = 0$ and $E_x[\epsilon_m(x)\epsilon_l(x)] = 0$ for $m \neq l$, show that

$$E_{bag} = \frac{1}{L} E_{av}$$

Solution. Since

$$\epsilon_{bag} = \frac{1}{L} \sum_{l=1}^{L} (f(x) + \epsilon_l(x)) - f(x)$$

where $\epsilon_l N(\mu, \sigma_l^2)$, and they are uncorrelated If we calculate the E_{bag} , then

$$E_{bag} = E[\epsilon_{bag}(x)^2] = var(\epsilon_{bag}(x))$$

the result is $\frac{1}{L^2} \sum_{l=1}^{L} \sigma_L^2$ And we have

$$E_{av} = \frac{1}{L} \sum_{l=1}^{L} E_x[\epsilon_l(x)^2]$$