USA Computing Olympiad

OVERVIEW

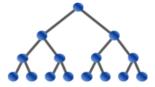
TRAINING

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USACO 2022 FEBRUARY CONTEST, SILVER PROBLEM 2. ROBOT INSTRUCTIONS

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Not submitted yet

English (en) 🗸

Bessie is learning how to control a robot she has recently received as a gift.

The robot begins at point (0,0) on the coordinate plane and Bessie wants the robot to end at point (x_g,y_g) . Bessie initially has a list of N $(1 \le N \le 40)$ instructions to give to the robot, the i-th of which will move the robot x_i units right and y_i units up (or left or down when x_i and y_i are negative, respectively).

For each K from 1 to N, help Bessie count the number of ways she can select K instructions from the original N such that after the K instructions are executed, the robot will end at point (x_a, y_a) .

Note: the time and memory limits for this problem are 4s and 512MB, twice the defaults.

INPUT FORMAT (input arrives from the terminal / stdin):

The first line contains N. The next line contains x_g and y_g , each in the range $-10^9 \dots 10^9$. The final N lines describe the instructions. Each line has two integers x_i and y_i , also in the range $-10^9 \dots 10^9$.

It is guaranteed that $(x_g, y_g) \neq (0, 0)$ and $(x_i, y_i) \neq (0, 0)$ for all i.

OUTPUT FORMAT (print output to the terminal / stdout):

Print N lines, the number of ways Bessie can select K instructions from the original N for each K from 1 to N.

SAMPLE INPUT:

SAMPLE OUTPUT:

In this example, there are six ways Bessie can select the instructions:

For the first way, the robot's path looks as follows:

$$(0,0) \rightarrow (-2,0) \rightarrow (1,0) \rightarrow (5,0) \rightarrow (5,10) \rightarrow (5,0) \rightarrow (5,10)$$

SCORING:

- Test cases 2-4 satisfy $N \leq 20$
- Test cases 5-16 satisfy no additional constraints.

Problem credits: Alex Liang

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Submit Solution