

No Universal Mechanism for Attention Sink in Transformers: Evidence from GPT-2

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Abstract

Transformers commonly exhibit an attention sink: disproportionately high attention to the first position. We study this behavior in GPT-2-style models with learned query biases and absolute positional embeddings. Combining analysis with targeted interventions, we find that the sink arises from the interaction among (i) a learned query bias, (ii) the first-layer transformation of the positional encoding and (iii) structure in the key projection. Together with observations of sinks in models without query biases or absolute positional embeddings (e.g., ALiBi), this indicates that attention sinks do not arise from a single universal mechanism but instead depend on architecture. These findings inform mitigation of attention sink, and motivate broader investigation of sink mechanisms across different architectures.

1 Introduction

Transformers (?) routinely display an *attention sink*: a persistent tendency to allocate disproportionate attention mass to early (often first) positions independent of semantic content (??). The effect is robust across many language and vision architectures. It has been observed across training stages and hyperparameters (??), across model families and datasets (?), and under diverse positional encodings—including absolute and learnable embeddings, ALiBi (?), RoPE (?), and even no explicit positional encodings (?). Similar sink-like patterns have also been reported in large multimodal systems and vision transformers (???). Together, these results indicate a robust, recurring phenomenon rather than a quirk of any single training recipe.¹

The practical stakes are significant. Attention sinks can reduce effective context use and lower accuracy(??), aggravate numerical error and hinder quantization (??), and obscure interpretability

by dominating attention maps (?). Understanding when sinks arise and how to control them is therefore directly relevant for model performance and interpretability.

We study the sink mechanistically in GPT-2-style Transformers with learned query biases and absolute positional embeddings (?). Combining descriptive measurements with targeted causal interventions, we tie the first-token sink to three interacting components: learned query bias, first-layer transformation of positional information (captured by effective positional encoding, EPE), and structure in the key projection. To establish causality, we pair each measurement with targeted interventions showing the sink weakens, disappears, or moves accordingly; additionally, when alternative explanations are plausible, we ablate them and find the sink persists, isolating the causal pathway.

Finally, we situate these findings within the broader ecosystem. Many popular architectures do not include the components our GPT-2 analysis identifies as central in this setting: they omit learned attention biases and use alternative positional schemes (for example ALiBi) instead of absolute embeddings, or even omit explicit positional encodings completely (NoPE) (????). Yet such models also robustly exhibit attention sinks (??). Thus, the GPT-2 mechanism we uncover cannot account for their sinks. The behavior is robust across families, but the implementation pathway depends on architecture. This has two implications: first, attention sinks may play a fundamental computational role that arises irrespective of particular architectural choices. Second, effective mitigation should be mechanism-aware rather than a one-size-fits-all approach.

¹Some non-transformer architectures have been reported to have little to no sink (?).

2 Preliminaries

2.1 Attention mechanism

Let $X^{(i)} = [x_1^{(i)}, \dots, x_n^{(i)}]$ denote the input to attention layer i , where $x_t^{(i)} \in \mathbb{R}^d$ is the representation for position t (after LayerNorm). We denote projection matrices and biases by $W_q^{(i)}, W_k^{(i)}, W_v^{(i)} \in \mathbb{R}^{d \times d}$ and $b_Q^{(i)}, b_K^{(i)}, b_V^{(i)} \in \mathbb{R}^d$. Queries, keys, and values are: $q_t^{(i)} = x_t^{(i)} W_q^{(i)} + b_Q^{(i)}$, $k_t^{(i)} = x_t^{(i)} W_k^{(i)} + b_K^{(i)}$, and $v_t^{(i)} = x_t^{(i)} W_v^{(i)} + b_V^{(i)}$. Some architectures include biases (??), others omit them (??).

For autoregressive generation, attention weights are $\alpha_{tj} = \text{softmax}_j(q_t^{(i)}(k_j^{(i)})^\top / \sqrt{d})$ where the softmax is over valid positions $j \leq t$. Multi-head attention divides the feature dimension across h heads, computing attention independently within each head’s subspace before concatenating outputs. For simplicity, our experiments treat W_k and b_Q in their original form prior to head-wise reshaping.

2.2 Positional encoding

Attention layers are invariant to input permutations, lacking inherent awareness of token order. To address this, Transformers incorporate positional information through various schemes (?, ?). We focus on learned absolute positional encodings: a set of trainable vectors $\{p_i\}_{i=1}^L \subset \mathbb{R}^d$, where i is the token position and L is the sequence length. These are added to token embeddings e_i : $x_i^{(0)} = e_i + p_i$.

2.2.1 Effective positional encoding (EPE)

We define the *effective positional encoding* (EPE) for position i as $\text{EPE}_i = \text{MLP}^{(1)}(p_i) + p_i$, where $\text{MLP}^{(1)}$ is the first layer’s feed-forward network applied to raw positional encoding p_i . We term this “effective” because it captures the net positional signal emerging after first-layer transformation. Experimentally, adding EPE_i to the first layer’s output (when no positional encoding was initially provided) has roughly the same effect as adding p_i before the first layer, demonstrating that EPE_i represents the effective positional contribution (see section A.1 for details).

3 Methodology and Results

We first describe the mechanism underlying attention sinks in models with learnable query biases and absolute positional encodings. Then, we provide evidence through experimental analyses and causal interventions.

Throughout, we use the sentence "My name is Ozymandias, king of kings: Look on my works, ye Mighty, and despair!" as input, though our analysis generalizes to almost any similar-length inputs (see more examples in section C)

3.1 The Mechanism behind Attention Sinks

Consider layer i . Before softmax (and scaling), the attention score from source position t to target position j is $s_{t \rightarrow j}^{(i)} = q_t^{(i)}(k_j^{(i)})^\top$, with $q_t^{(i)} = x_t^{(i)} W_q^{(i)} + b_Q^{(i)}$ and $k_j^{(i)} = x_j^{(i)} W_k^{(i)} + b_K^{(i)}$. Expanding gives

$$s_{t \rightarrow j}^{(i)} = (x_t^{(i)} W_q^{(i)})(x_j^{(i)} W_k^{(i)})^\top + (x_t^{(i)} W_q^{(i)}) b_K^{(i)\top} + (b_Q^{(i)})(x_j^{(i)} W_k^{(i)})^\top + (b_Q^{(i)}) b_K^{(i)\top}.$$

The third term, $\Delta_j^{(i)} \triangleq b_Q^{(i)} W_k^{(i)\top} x_j^{(i)\top}$, is a token-specific, source-agnostic shift: it raises or lowers the score for *all* sources t toward the same target j . This term represents the projection of token j ’s representation onto the direction $b_Q^{(i)} W_k^{(i)\top}$. We find that this bias term for the first token, $\Delta_1^{(i)}$, is conspicuously large in most deep layers, creating a strong prior to attend to position 1. The underlying reason for the large $\Delta_1^{(i)}$ is the effective positional encoding EPE_1 . EPE_1 has very large absolute values on a small set of coordinates (a phenomenon called *massive activations* (?)) which are exactly those coordinates where $b_Q^{(i)} W_k^{(i)\top}$ has the largest magnitude in almost all layers. This co-adaptation enables EPE_1 to dramatically amplify $\Delta_1^{(i)}$, yielding an attention sink at the first position.

3.2 Empirical Validation

We validate our proposed mechanism through three complementary analyses on GPT-2 (more detail in section B), followed by causal interventions that confirm the necessity of each component described in section 3.1. In section 3.2.1 we show that $\Delta_1^{(i)}$ is conspicuously large relative to other positions across multiple layers. We then investigate its underlying cause and show in section 3.2.2 that $\text{EPE}_1 W_k^{(i)}$ exhibits strong alignment with vector $b_Q^{(i)}$ in deep layers. In section 3.2.3 we establish that EPE_1 exhibits massive activations precisely at coordinates where the bias projection $b_Q^{(i)} W_k^{(i)\top}$ has high magnitude. Finally, in section 3.2.4 we use causal interventions to verify that disrupting any component abolishes the sink while transplanting components transfers it to new positions.

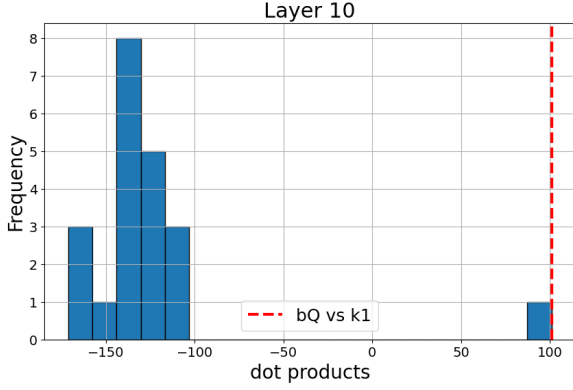


Figure 1: Distribution of bias terms $\Delta_j^{(10)}$ across positions. The first-position term $\Delta_1^{(10)}$ (red) centers at ≈ 100 , while all other positions (blue) center at ≈ -140 , demonstrating a learned preference for the first token.

3.2.1 Bias Term Magnitude Analysis

First, we verify that $\Delta_j^{(i)} \triangleq b_Q^{(i)} W_k^{(i)\top} x_j^{(i)\top}$ is anomalously large for position 1. Histograms of $\Delta_j^{(i)}$ across positions j show $\Delta_1^{(i)}$ as a consistent distinct outlier. fig. 1 shows this for layer 10, where $\Delta_1^{(i)}$ substantially exceeds other positions (results across all layers are in Appendix A.2).

3.2.2 EPE-Bias Projection Alignment

Having established the magnitude of $\Delta_1^{(i)}$, we investigate its underlying cause. Since $x_1^{(i)}$ contains both token and positional information, it remains to disentangle which of the two is responsible for the large $\Delta_1^{(i)}$. To that end, we examine alignment between $\text{EPE}_1 W_k^{(i)}$ and query bias $b_Q^{(i)}$. fig. 2 shows $\text{EPE}_1 W_k^{(10)}$ strongly aligns with $b_Q^{(10)}$, while other positions cluster near zero (full results for all layers are in Appendix A.3).

3.2.3 Coordinate-Level Structural Analysis

Massive coordinates of EPE_1 should coincide with coordinates favored by the bias projection. Let $\gamma^{(i)} = b_Q^{(i)} W_k^{(i)\top} \in \mathbb{R}^d$; its entry $\gamma^{(i)}[d]$ measures coordinate d 's contribution to source-agnostic shift $\Delta_j^{(i)}$. We identify coordinates with conspicuously large absolute values in EPE_1 (see Appendix A.4 for details). For each such coordinate d , we compare $|\gamma^{(i)}[d]|$ against other rows. table 1 shows massive coordinates ($d=138, 447$) substantially exceed baseline, confirming EPE_1 is large exactly where bias projection is large (full results for all layers are in Appendix A.5).

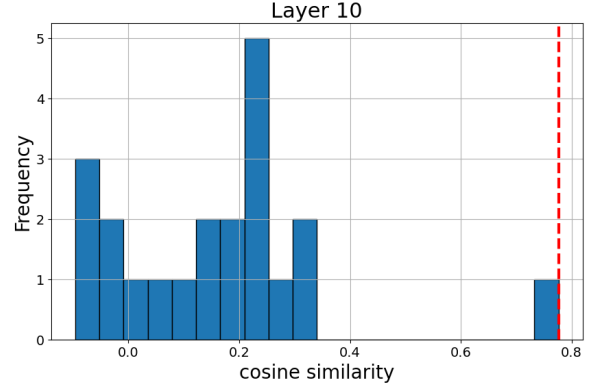


Figure 2: Cosine similarity between query bias $b_Q^{(10)}$ and $\text{EPE}_1 W_k^{(10)}$. $\text{EPE}_1 W_k^{(10)}$ (red) shows strong positive alignment (≈ 0.7), while other positions (blue) cluster near 0.2.

Layer	Baseline (rand)	$d=138$	$d=447$
layer 7	1.12 ± 2.701	12.453	18.17
layer 9	1.23 ± 3.225	17.846	26.014
layer 11	1.403 ± 4.002	27.547	27.691

Table 1: $\gamma^{(i)} = b_Q^{(i)} W_k^{(i)\top}$ at coordinates where EPE_1 has massive activations (dims 138, 447) versus the baseline mean \pm two standard deviations across all coordinates. The massive- EPE_1 coordinates consistently exceed the baseline by wide margins, demonstrating that EPE_1 is irregularly large precisely where the bias projection has strong influence.

3.2.4 Causal Interventions

To establish causality beyond correlation, we perform targeted interventions on each mechanism component during forward passes to test necessity (removing a component) and sufficiency (transplanting it) of each component. Full intervention results across all layers are provided in Appendix A.6.

- **Intervention 1 — Nullify b_Q (query bias is necessary).** Set b_Q to zero; the sink substantially diminishes (fig. 3b), showing that b_Q is necessary for the large first-token contribution.
- **Intervention 2 — Replace EPE_1 (specificity of the positional signal).** Swap EPE_1 with another position's EPE; the first-position sink disappears (fig. 3c), indicating that EPE_1 is critical to induce a sink.
- **Intervention 3 — Moving EPE_1 induces a sink at the new token (sufficiency).** We transplant EPE_1 from position 1 to position 2 (and give position 1 a different EPE). A strong sink forms

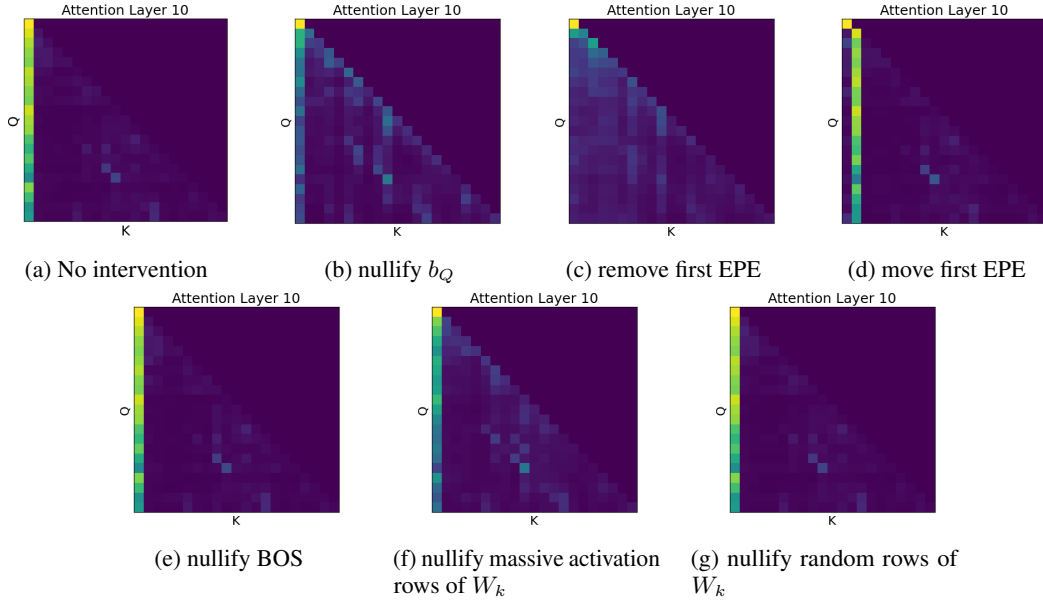


Figure 3: Comparison of attention maps under different interventions. (a) no intervention; (b) intervention 1: nullify b_Q ; (c) intervention 2: remove the learned EPE at position 1 and add a different EPE (the second); (d) intervention 3: transplant the learned EPE to another position (the second). (e) intervention 4: nullify BOS token embedding. (f) intervention 5: nullify massive activation rows of W_k . (g) nullify random rows of W_k .

at position 2 (fig. 3d), demonstrating that EPE_1 is sufficient to elicit a sink at the new location.

- **Intervention 4 — BOS token does not drive the sink.** We zero the BOS token embedding before adding positional signals. The sink persists (fig. 3e), ruling out the embedding of the BOS token as a main driver of the sink.
- **Intervention 5 — Zero W_k at bias-projection coordinates (structural pathway is necessary).** Zero W_k rows at massive- EPE_1 coordinates compared to zeroing W_k rows at random coordinates; only the prior case substantially reduces the sink (fig. 3f, fig. 3g), confirming that these specific coordinates are core drivers for translating EPE_1 into the attention bias.

4 Conclusions

Attention sinks are robust across Transformer architectures and modalities, but mechanisms differ by architecture. In GPT-2–style models, we identify a concrete implementation pathway: interaction between (i) a learned query bias, (ii) the first-layer transformation of positional information, and (iii) structure in the key projection. Crucially, this circuit cannot account for sinks in architectures lacking these components—models without learned query biases or that use alternative positional schemes (ALiBi, or no positional encod-

ings)—yet these also exhibit attention sinks. This implies that while attention sinks are robust as a phenomenon, they are not governed by a single universal mechanism.

Implications The lack of a single universal mechanism reveals attention sinks as an optimization-friendly attractor: when multiple pathways exist, training reliably discovers circuits that implement the sink behavior. This has important implications for both understanding and controlling these phenomena. First, it suggests that attention sinks may serve a fundamental computational role that emerges regardless of specific architectural choices. Second, it indicates that effective mitigation strategies must be mechanism-aware. Naive interventions targeting individual components will likely fail, as optimization can compensate through alternative pathways. Instead, successful approaches must either address the underlying computational pressures that drive sink formation, or develop architecture-specific interventions.

5 Limitations

5.1 Scope across architectures and scales

Our analyses focus on a GPT-2–style model with learned query biases and absolute positional encodings. The broader Transformer ecosystem includes architectures that omit such biases or use alterna-

tive positional schemes (e.g., RoPE, ALiBi). While we do show that the same circuit can not form in those settings, we leave the investigation of specific mechanisms that do form in these models to future work. In addition, GPT-2 is small by contemporary standards; with scale, the mechanism could strengthen, fragment into multiple pathways, or be replaced by different circuits.

5.2 Learning dynamics

We provide a post-hoc, static analysis of a trained checkpoint. We do not track when the circuit emerges during pre-training, which gradients give rise to it, or whether intermediate snapshots exhibit qualitatively different pathways. We believe our static analysis could inform future work researching the emergence of the attention sink mechanism.

5.3 Mechanism vs. function

Our contribution is mechanistic: we explain *how* an attention sink can be implemented in the studied architecture. We do not claim a definitive functional rationale for *why* such a sink is beneficial or harmful across tasks. Establishing the downstream utility or cost of the sink, and the conditions under which it is selected by optimization, is left for future work.

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A Further Experiments

A.1 Effective positional encoding demonstration

In this section, we illustrate that EPE_i roughly captures the net positional signal that is added to the input after the first layer’s transformation when adding the positional encoding p_i to the input $x_i^{(0)}$. To that end, we define an approximation of the result of processing the input by the first MLP: $R_i := x_i^{(0)} + MLP^{(1)}(x_i^{(0)})$. We then define the input without positional information $e_i := x_i^{(0)} - p_i$, and the result of processing the input without the positional information: $O_i = e_i + MLP^{(1)}(e_i)$. We then compare EPE_i to the difference $R_i - O_i$, computing the cosine similarity for each token i . This directly measures whether the incremental contribution caused by adding p_i aligns in direction with EPE_i . The results range between 0.776 at the lowest and 0.996 at the highest (fig. 4). These similarities are very high, indicating that EPE_i represents the effective contribution of positional information after being processed through the network’s initial transformations.

A.2 Bias Term Magnitude Across All Layers

This section reproduces the bias-term magnitude analysis from section 3.2.1 across all layers: we plot the distribution of $\Delta_j^{(i)} \triangleq b_Q^{(i)} W_k^{(i)\top} x_j^{(i)\top}$,

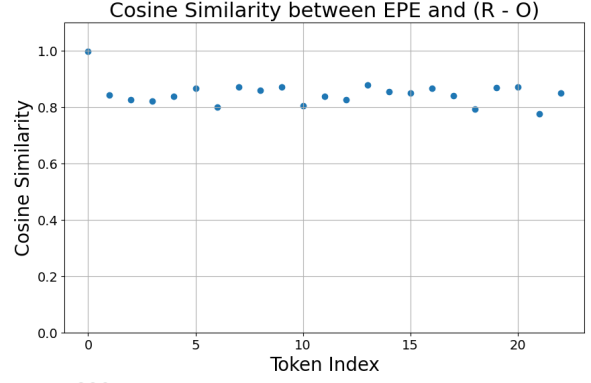


Figure 4: Coordinate values of EPE_i for the first token (replicating the distribution described in section 3.2.3). Most coordinates are near zero; a small set exhibits extremely large magnitudes (“massive activations”).

across positions for each layer (cf. fig. 1). In most layers, the first-position term $\Delta_1^{(i)}$ is a conspicuous outlier, indicating a strong prior to attend to position 1 (see fig. 5).

A.3 EPE-Bias Alignment Across All Layers

This section repeats the alignment analysis from section 3.2.2: for each layer i and position j we compute $\cos(b_Q^{(i)}, EPE_j W_k^{(i)})$, highlighting position 1. In most layers, position 1 shows strong positive alignment while other positions do not (see fig. 6).

A.4 Identifying Massive Activations in First-Position EPE

This section explains how we identify coordinates with unusually large absolute values in EPE_1 . We select coordinates whose absolute values exceed the mean absolute value by at least three standard deviations; in our model this criterion selects indices 105, 218, and 329. Elements at these indices are clear outliers, each more than 15 standard deviations away from the mean. Each such selected dimension exhibits the coordinate-level phenomenon described in section 3.2.3 (i.e., large $|\gamma^{(i)}[d]|$ and a strong contribution to the source-agnostic shift). See fig. 7 for a visualization of EPE_1 . It is clear visually that coordinates 105, 218, and 329 have conspicuously larger norms than other indices.

A.5 Coordinate-Level Alignment Across All Layers

This section tabulates $\gamma^{(i)} = b_Q^{(i)} W_k^{(i)\top}$ at coordinates where $|EPE_1|$ is conspicuously large, mirroring the coordinate-level analysis in section 3.2.3.

Layer	Baseline	$d=138$	$d=447$
layer 1	4.47 ± 22.226	12.116	11.064
layer 2	2.8 ± 6.62	8.065	24.468
layer 3	1.717 ± 5.826	10.178	23.047
layer 4	1.657 ± 5.02	18.199	17.149
layer 5	1.561 ± 4.618	3.072	23.854
layer 6	0.86 ± 1.59	5.644	6.142
layer 8	1.404 ± 3.546	19.806	28.01
layer 10	1.313 ± 3.618	23.131	28.42
layer 12	1.145 ± 2.65	4.5	13.59

Table 2: $\gamma^{(i)} = b_Q^{(i)} W_k^{(i)\top}$ at coordinates where EPE_1 has massive activations (dims 138, 447) versus the baseline mean \pm two standard deviations across all coordinates. Massive- EPE_1 coordinates consistently exceed the baseline, indicating that EPE_1 is irregularly large precisely where the bias projection is large.

Values are compared against the baseline mean \pm two standard deviations across all coordinates (see table 2).

A.6 Intervention Results Across All Layers

This section reproduces the intervention analyses from section 3.2.4 across all layers, including the baseline and five targeted interventions. Each subsection mirrors the corresponding main-text figure and shows the layer-wise attention maps.

A.6.1 Baseline: No Intervention

We show attention maps with no intervention (cf. fig. 3a), demonstrating the prevalence of the first-position sink across layers (see fig. 8).

A.6.2 Intervention 1: Nullifying Query Bias

We zero b_Q (cf. fig. 3b), which substantially diminishes the sink across layers.

A.6.3 Intervention 2: Replacing First Position EPE

We swap EPE_1 with another position’s EPE (cf. fig. 3c), which removes the first-position sink.

A.6.4 Intervention 3: Transplanting EPE to New Position

We transplant EPE_1 from position 1 to 2 (cf. fig. 3d), which induces a sink at position 2.

A.6.5 Intervention 4: Nullifying BOS Token

We zero the BOS token embedding prior to adding positional signals (cf. fig. 3e); the sink persists.

Layer	Baseline (rand)	$d=138$	$d=447$
layer 7	TBD	TBD	TBD
layer 9	TBD	TBD	TBD
layer 11	TBD	TBD	TBD

Table 3: $\gamma^{(i)} = b_Q^{(i)} W_k^{(i)\top}$ at coordinates where EPE_1 has massive activations for sentence [YRM: add sentence number 1 here]. This is analogous to table 1. See the main text for more details.

A.6.6 Intervention 5: Nullifying Massive Activation Coordinates

We zero W_k rows at massive- EPE_1 coordinates (cf. fig. 3f), which reduces the sink far more than zeroing random rows.

A.6.7 Intervention 5 Control: Nullifying Random Coordinates

As a control, we zero an equal number of random W_k rows (cf. fig. 3g); the sink largely remains.

B Model Details

All experiments used the pretrained GPT-2 checkpoint from the Hugging Face Hub (model id gpt2), which corresponds to the 124M-parameter GPT-2 released by OpenAI. The checkpoint comprises the model weights (e.g. pytorch_model.bin or pytorch_model.safetensors), the model configuration (config.json), and the tokenizer files (e.g. vocab.json, merges.txt, tokenizer_config.json).

C Figures for Additional Sentences

In this section we replicate the four main-text visualizations for 10 additional sentences. For each sentence, we include: (1) bias-term distribution (analog of fig. 1); (2) EPE-bias alignment (analog of fig. 2); (3) coordinate-level table (analog of table 1); and (4) interventions comparison (analog of fig. 3).

C.1 Sentence 1

We plot the figures in the main text for the sentence [YRM: add sentence number 1 here]. For an analogous figure to fig. 1 see fig. 15. For an analogous figure to fig. 2 see fig. 16. For an analogous table to table 1 see table 3. For an analogous interventions panel to fig. 3 see fig. 17.

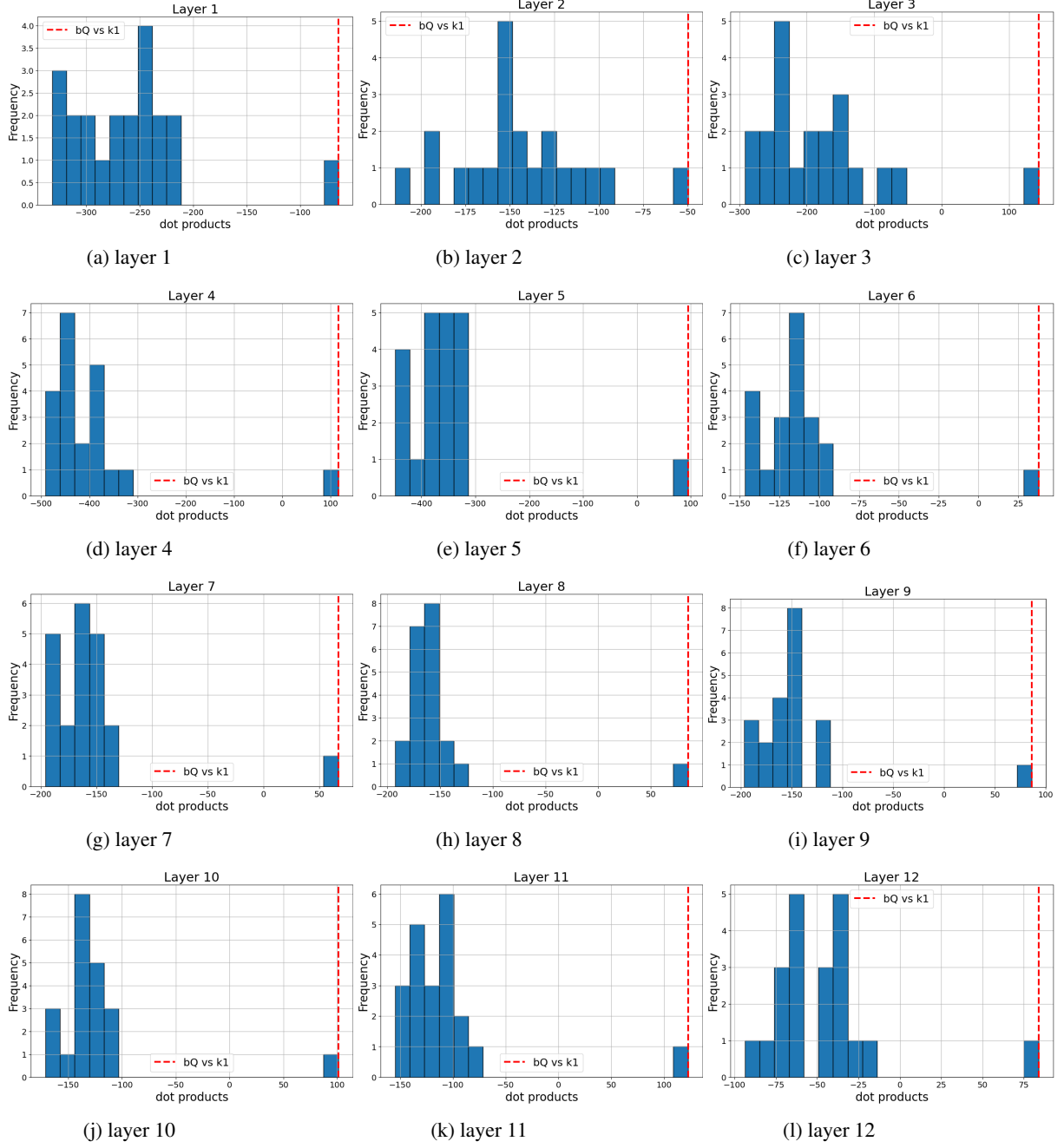


Figure 5: Bias-term distributions Δ_j across positions j for each layer i (replicating fig. 1). Red denotes the first-position term $\Delta_1^{(i)}$; blue denotes all other positions. In most layers, the red distribution is shifted far to the right, evidencing an anomalously large first-position bias.

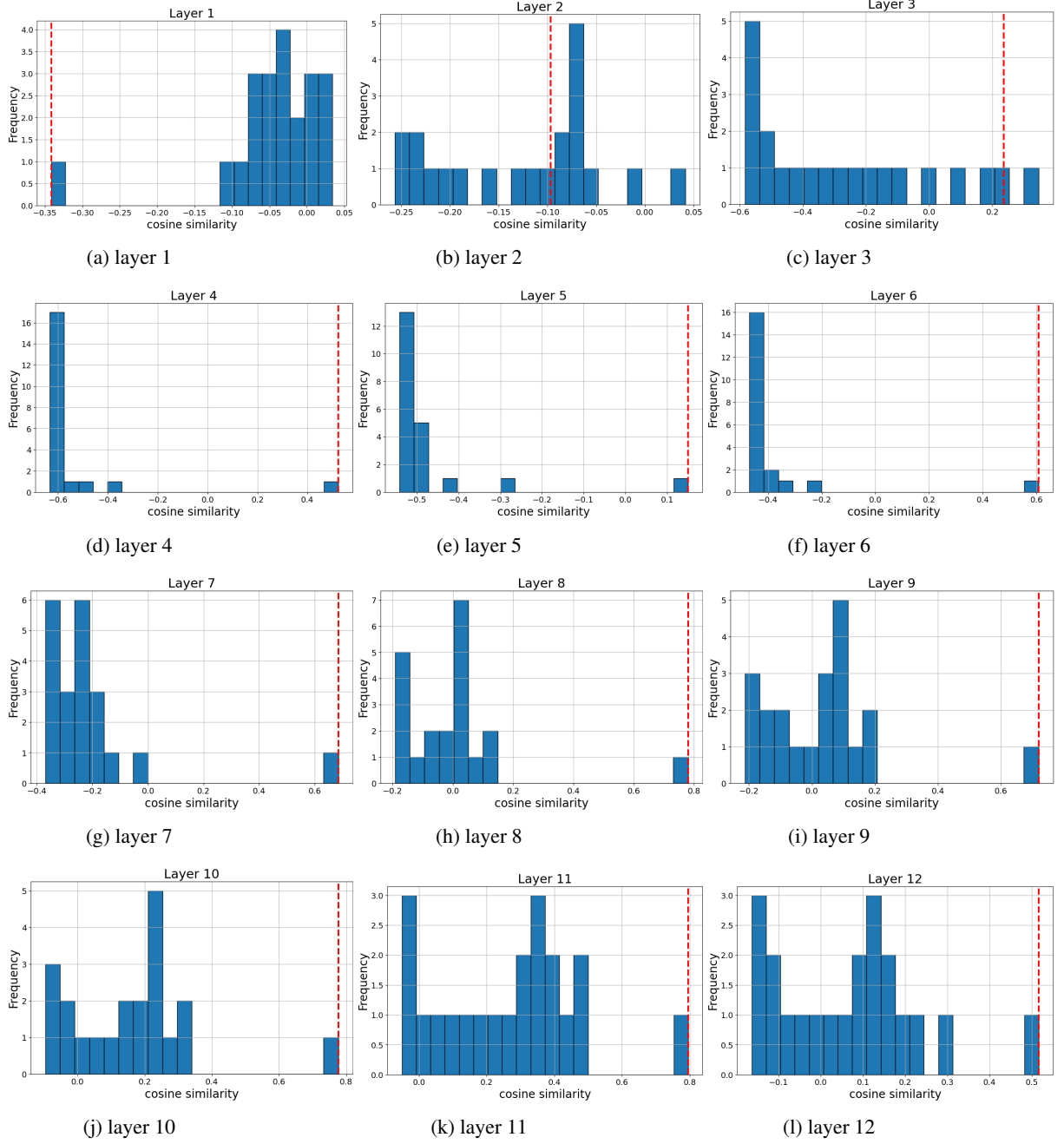


Figure 6: Cosine similarity between the query bias and EPE-projected keys across layers and positions (replicating fig. 2). For each layer i and position j , we plot $\cos(b_Q^{(i)}, \text{EPE}_j W_k^{(i)})$. Red marks position $j=1$; blue marks all other positions. Position 1 shows strong positive alignment while other positions do not, indicating that $\text{EPE}_1 W_k^{(i)}$ is specifically aligned with $b_Q^{(i)}$.

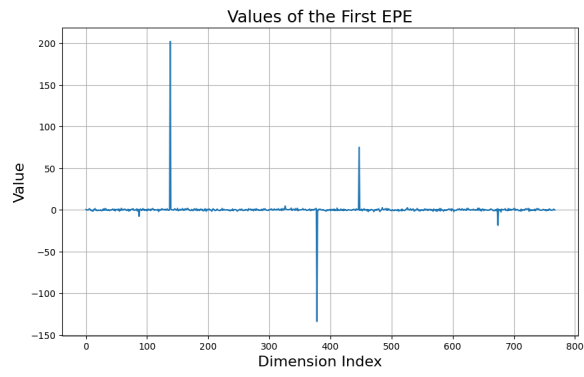


Figure 7: Coordinate values of EPE_1 for the first token (replicating the distribution described in section 3.2.3). Most coordinates are near zero; a small set exhibits extremely large magnitudes (“massive activations”).

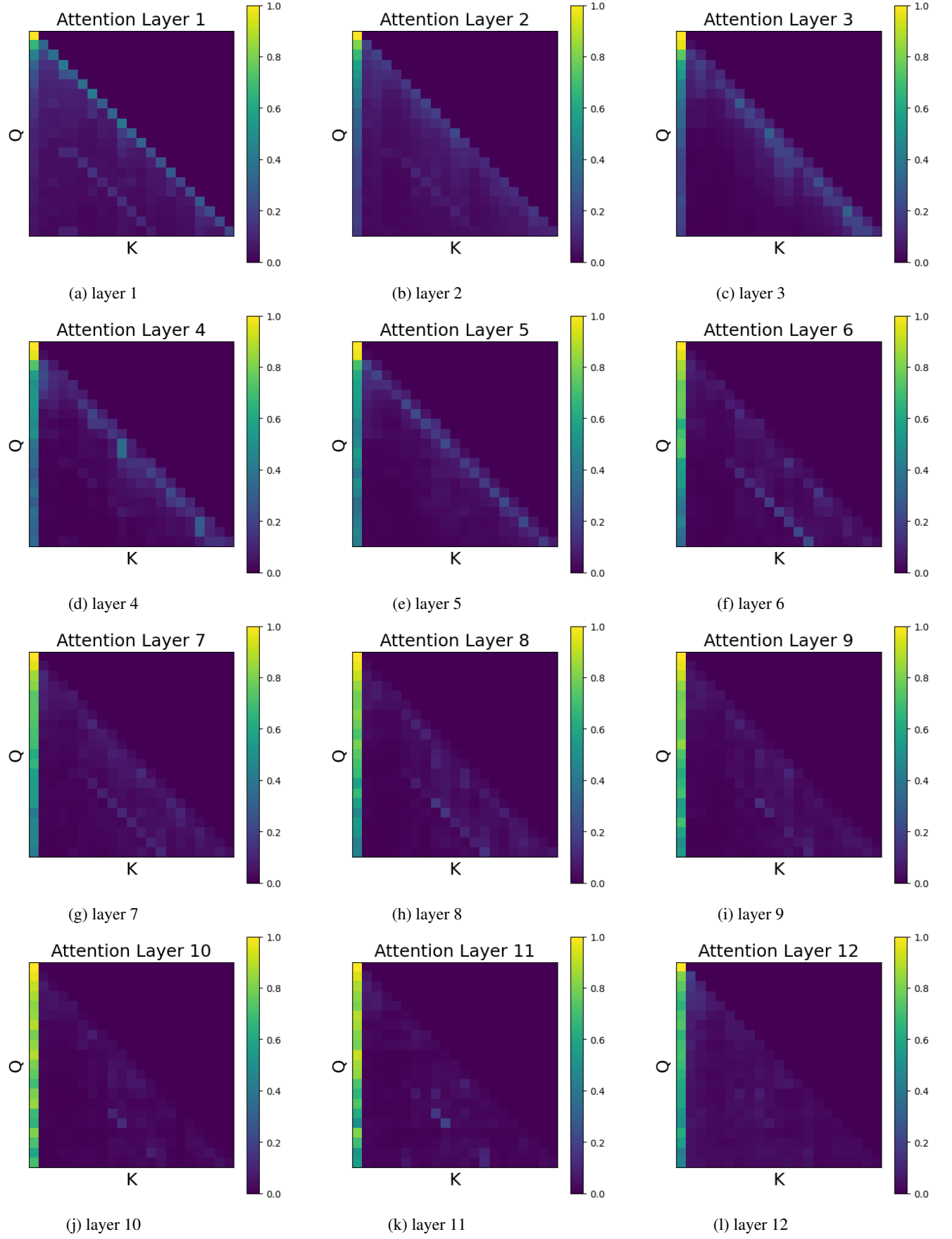


Figure 8: Attention maps for all layers with no intervention (replicating fig. 3a). A prominent first-position sink is visible in most layers.

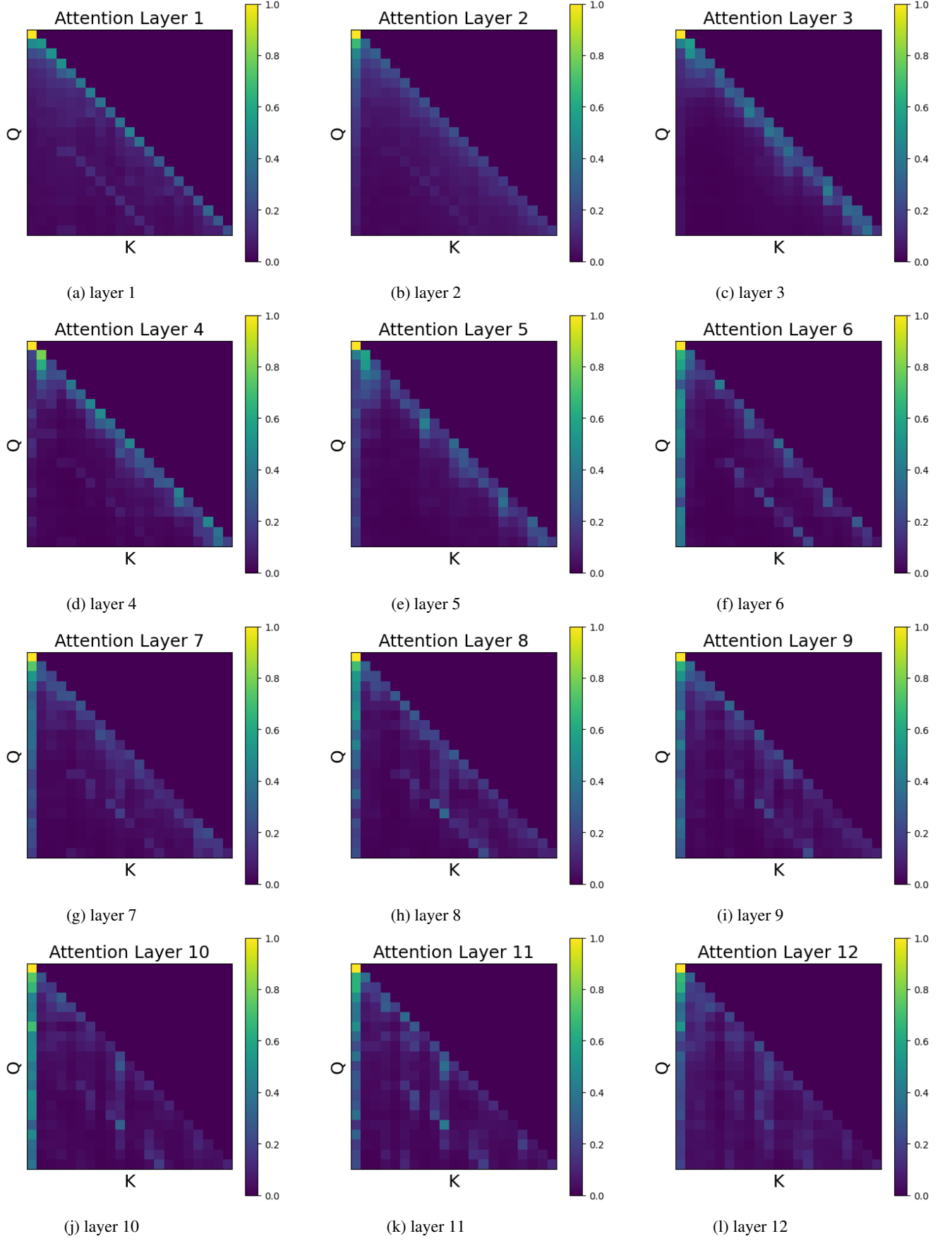


Figure 9: Attention maps for all layers with b_Q set to zero (replicating fig. 3b). The sink is substantially reduced across layers.

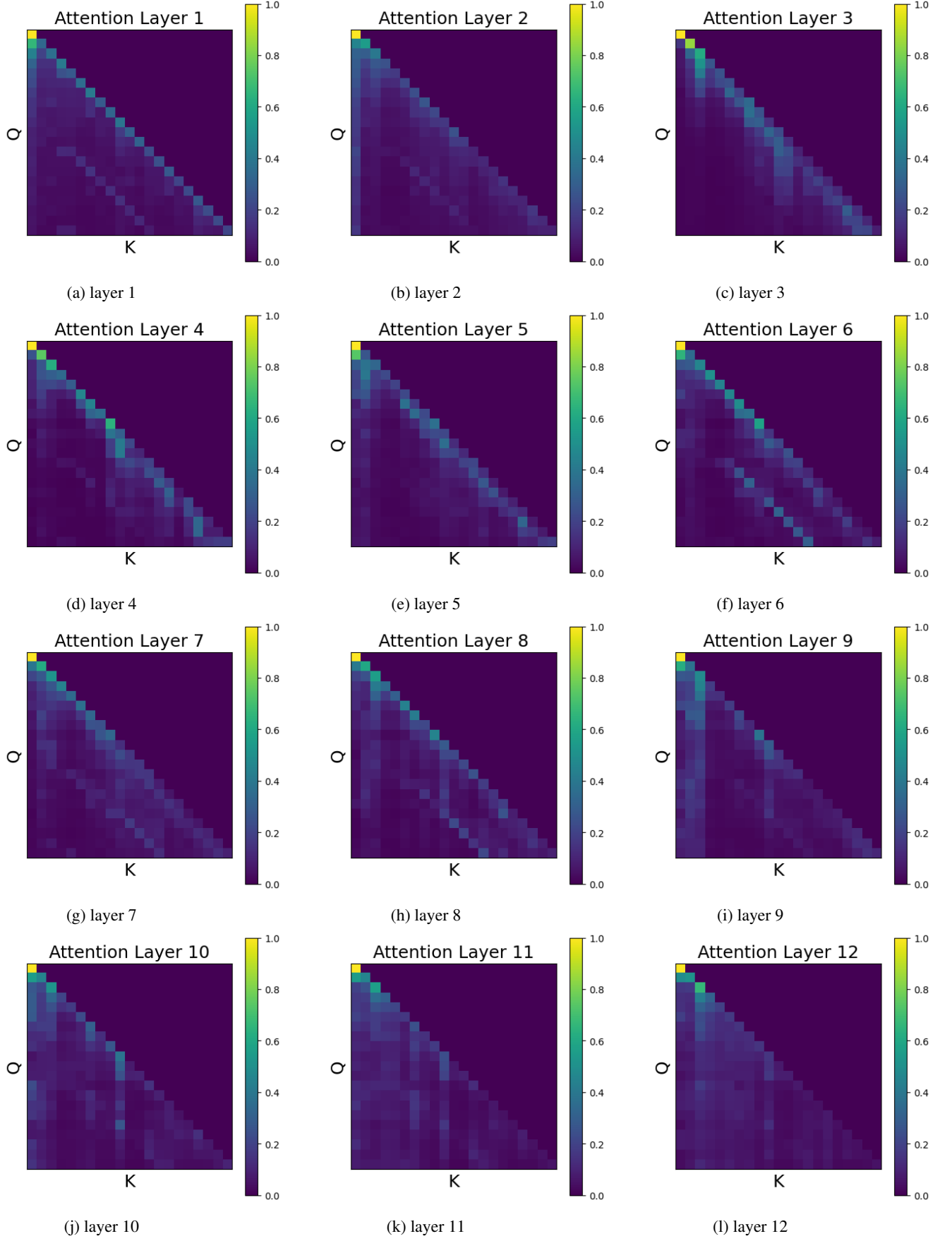


Figure 10: Attention maps for all layers after swapping EPE_1 with another position's EPE (replicating fig. 3c). The first-position sink disappears.

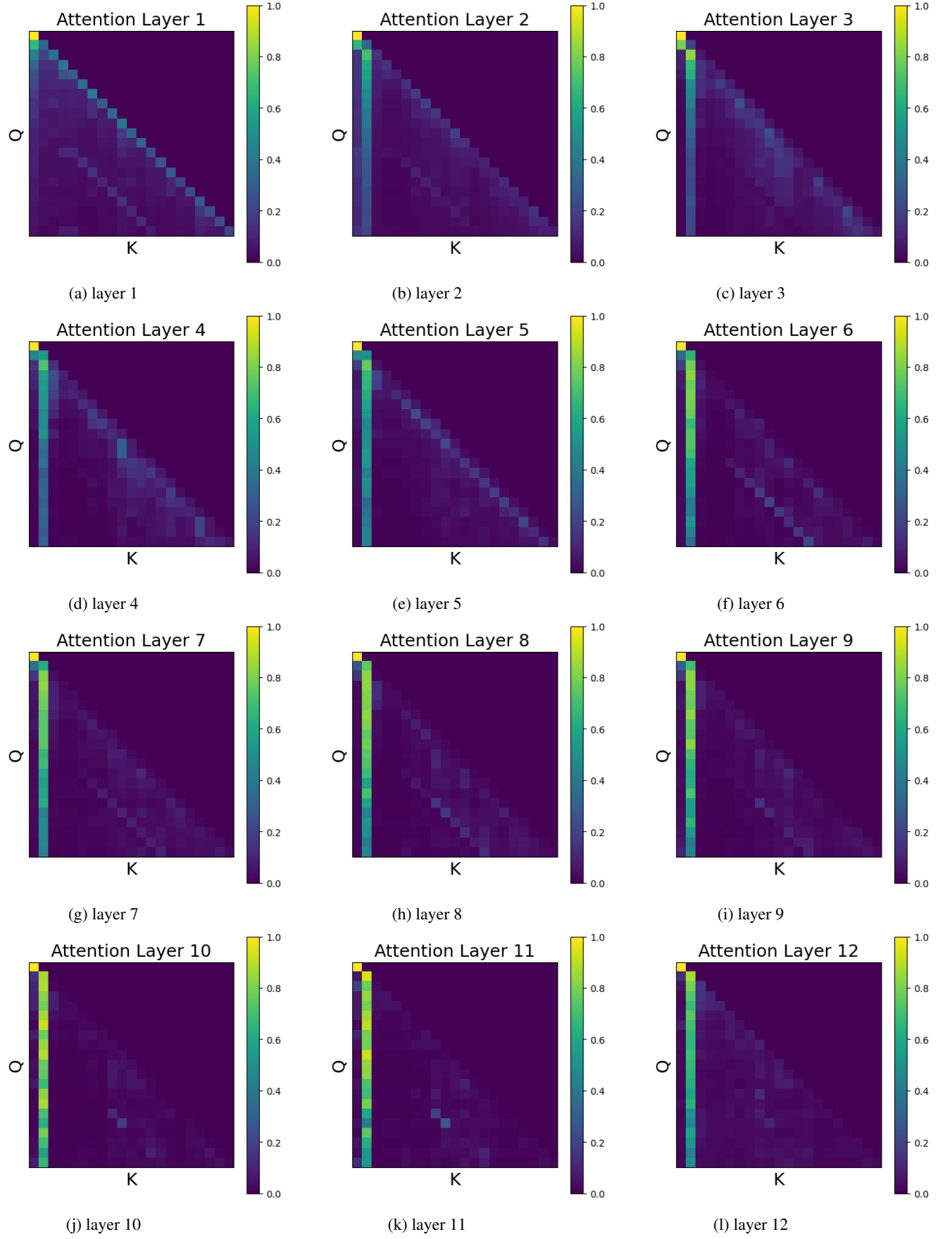


Figure 11: Attention maps for all layers after moving EPE_1 from position 1 to 2 (replicating fig. 3d). A strong sink forms at position 2.

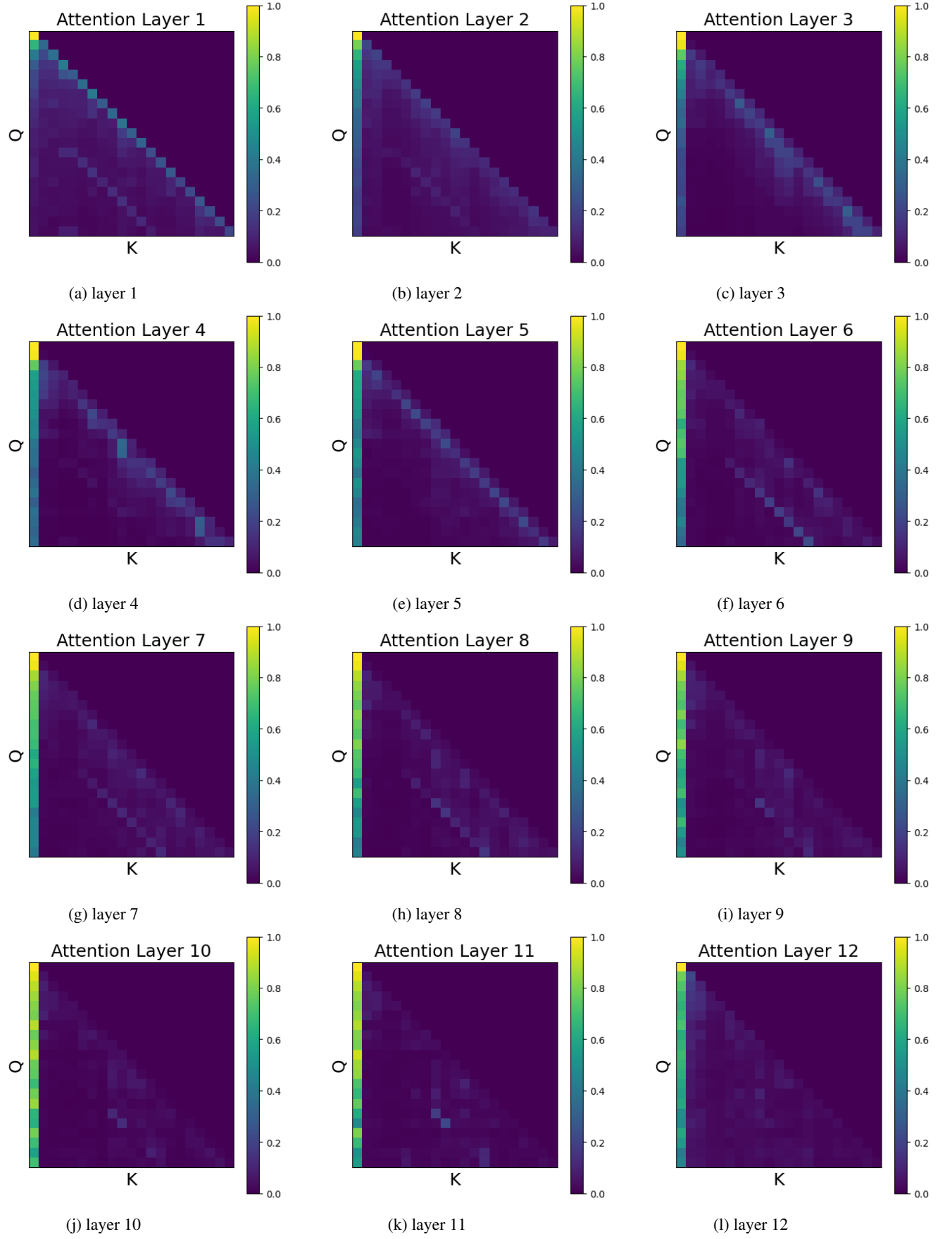


Figure 12: Attention maps for all layers after zeroing the BOS token embedding (replicating fig. 3e). The sink remains.

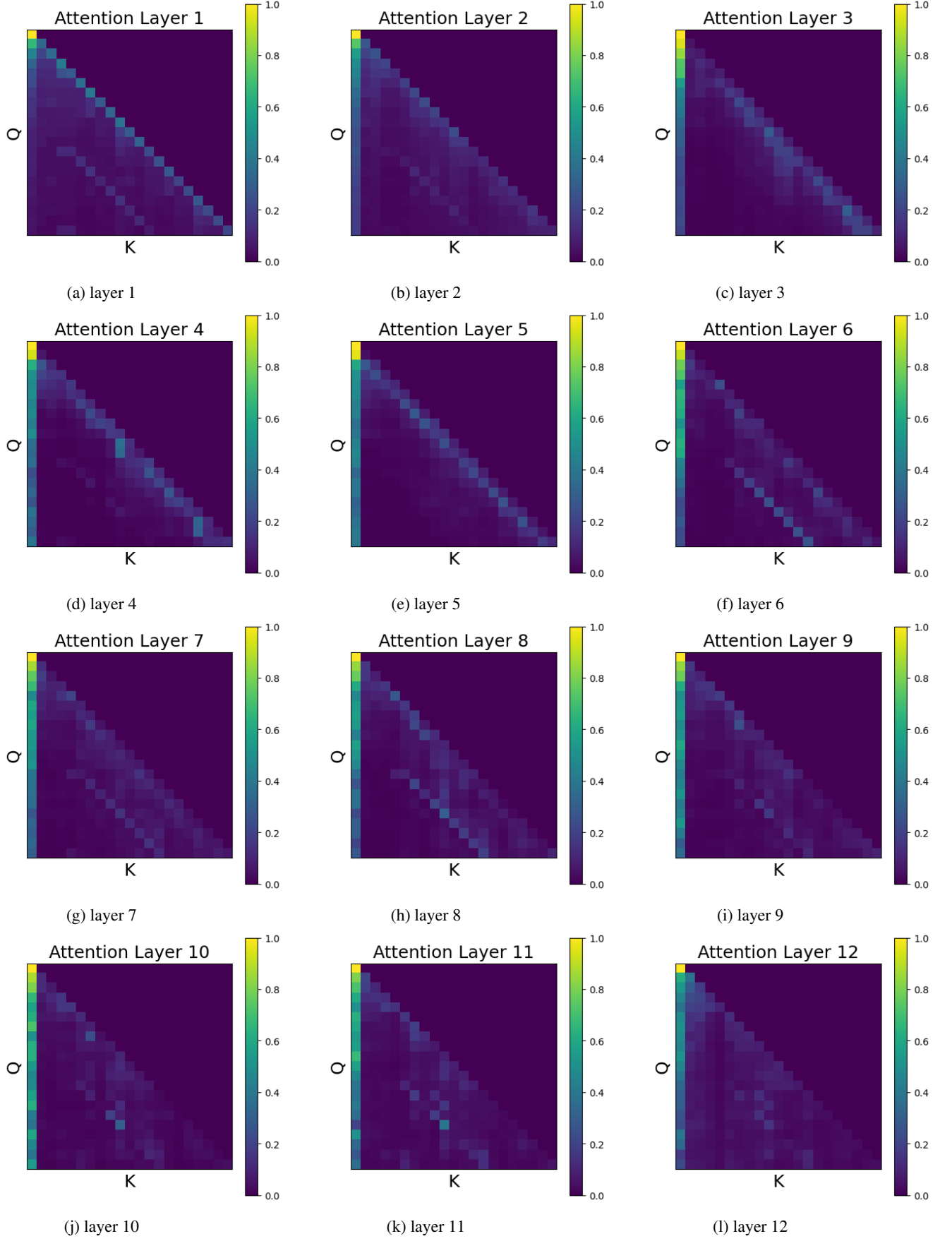


Figure 13: Attention maps for all layers after zeroing W_k at massive-EPE₁ coordinates (replicating fig. 3f). The sink is markedly reduced compared to random-coordinate zeroing.

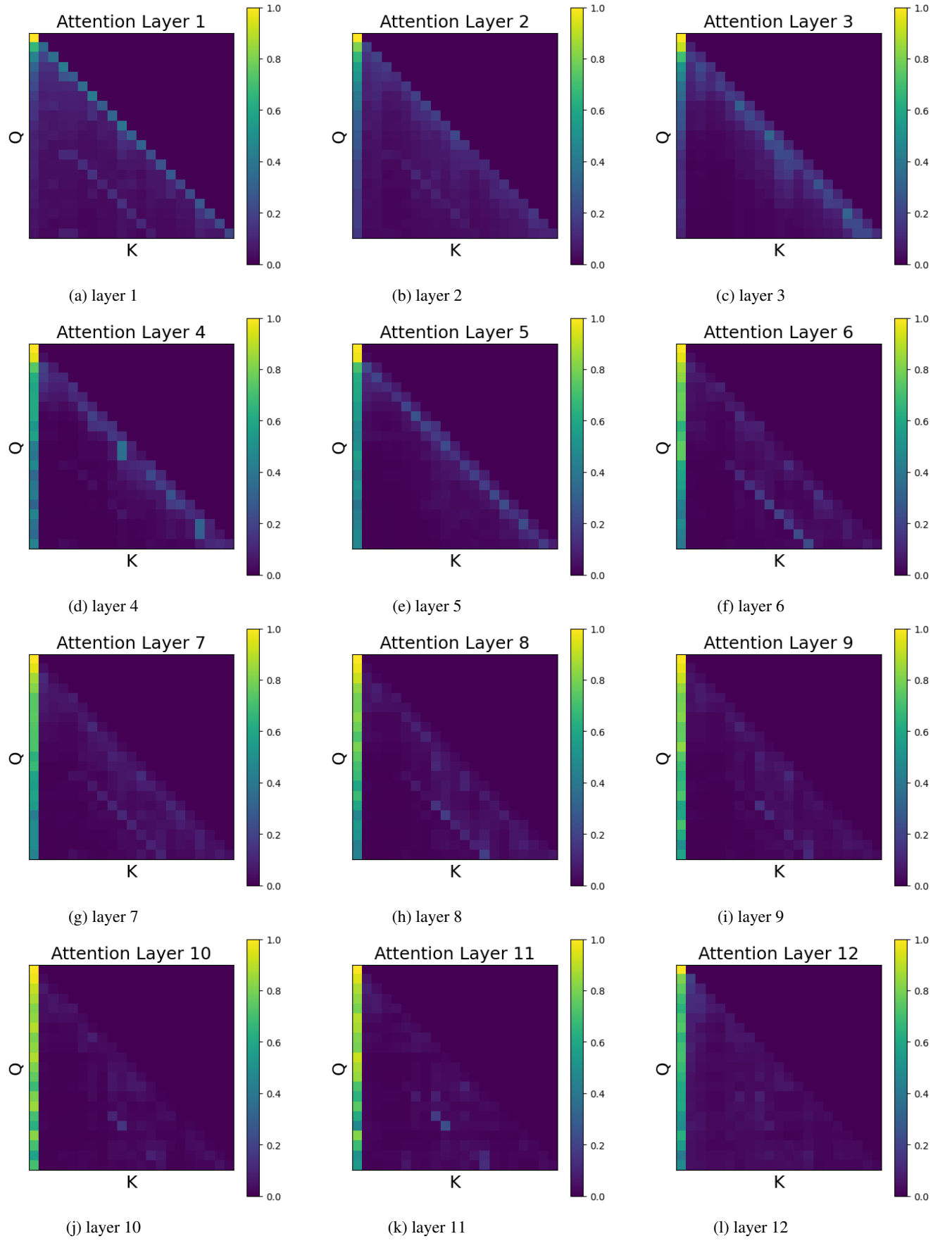


Figure 14: Attention maps for all layers after zeroing random W_k coordinates (replicating fig. 3g). The sink remains.

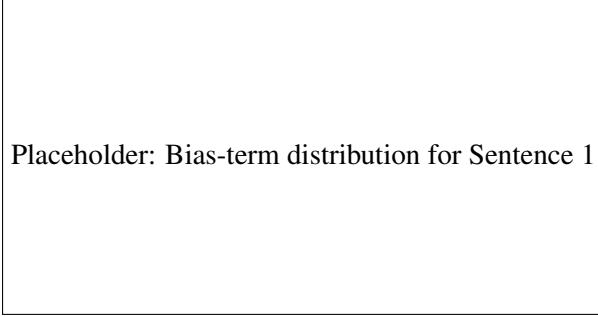


Figure 15: Distribution of bias terms $\Delta_j^{(i)}$ across positions for sentence [YRM: add sentence number 1 here]. This is analogous to fig. 1. See the main text for more details.

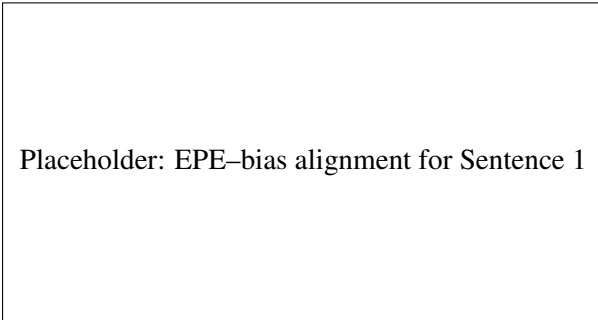


Figure 16: Cosine similarity between $b_Q^{(i)}$ and $\text{EPE}_j W_k^{(i)}$ for sentence [YRM: add sentence number 1 here]. This is analogous to fig. 2. See the main text for more details.

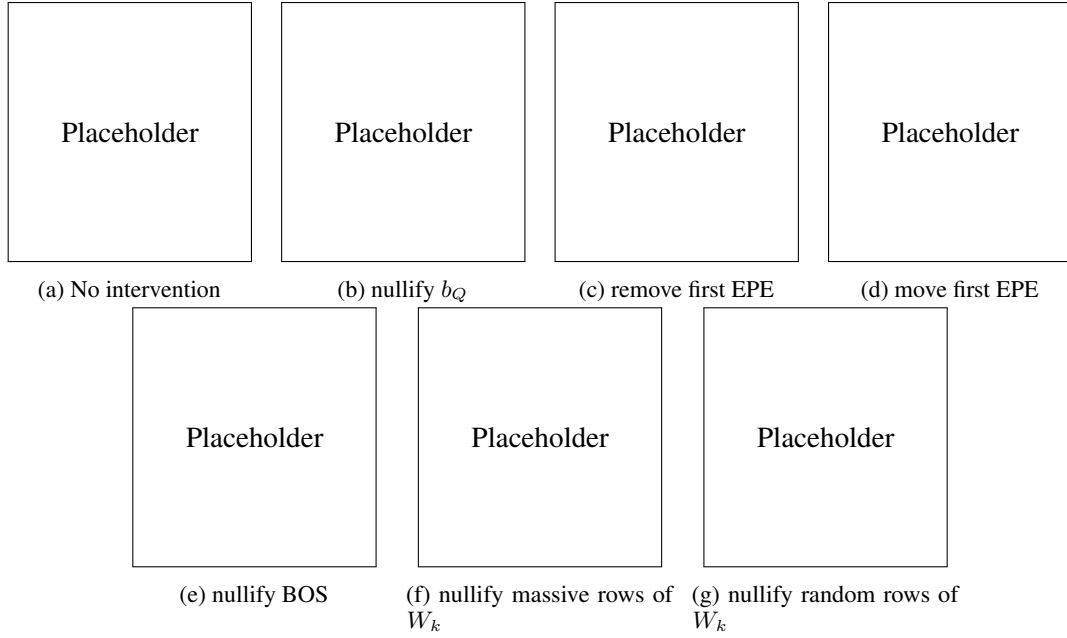


Figure 17: Comparison of attention maps under interventions for sentence [YRM: add sentence number 1 here]. This is analogous to fig. 3. See the main text for more details.