

DIPLOMA THESIS ASSIGNMENT

Student: **Bc. Tomáš Báča**

Study programme: Open Informatics
Specialisation: Artificial Intelligence

Title of Diploma Thesis: **Model predictive control of micro aerial vehicle using onboard microcontroller**

Guidelines:

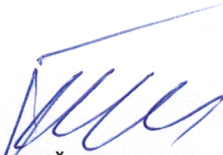
The main purpose of the thesis is to design, implement and experimentally verify a novel algorithm for stabilization and control of Micro Aerial Vehicle (MAV) along a predefined trajectory. The method will be based on prediction of MAV movement using precisely identified model (Model Predictive Control - MPC). From the beginning of the development, the algorithm will be suited for very limited computational resources onboard of MAV (microcontroller), and for control in real time using only onboard sensors. In addition, a quad-rotor helicopter will be prepared for this task, which includes development of control and communication boards and identification of MAV model. Designed and implemented system will be verified by experiments with real MAV and in numerical simulations. Results will be compared with performance of the current system being used by the Multi-robotic Systems group, which relies on PID controller.

Bibliography/Sources:

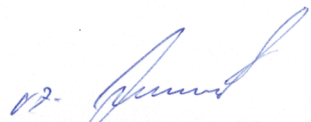
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Prague, March 25, 2015