# BRNO UNIVERSITY OF TECHNOLOGY FACULTY OF INFORMATION TECHNOLOGY

# RDS Encoder and Decoder Wireless and Mobile Networks – Assignment

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# 1 Introduction

Radio Data System (RDS) is a communications protocol standard for embedding small amounts of digital information in conventional FM radio broadcasts. It was developed by the European Broadcasting Union (EBU) Member countries with the goal to create an internationally agreed standard for such a system. The specification was initially published in 1984 and then revisited by the European Committee for Electrotechnical Standardization (CENELEC) in 1998. This project is based on the 1998 specification [1].

There are 15 message group types (resp. 30 – each type has two variants) used to transmit various information. For example Group 0 is used to transmit basic tuning and switching information, Group 2 encodes Radio Text. For illustration imagine you are driving your car with the radio turned on. The message that you see in the radio dashboard (eg. information about the song that is currently playing) was probably transmitted to your car using the RDS Group 2.

The basic structure for messages of all group types is pictured in figure 1. Each group is 104 bits long, divided into 4 blocks of 26 bits length each. The blocks then consist of a 16 bit information word containing the encoded data, and a 10 bit checkword, which is created by calculating a CRC of the information word in addition with a specified offset word (more on that later 3.3). The contents of the actual information parts differ for each group.

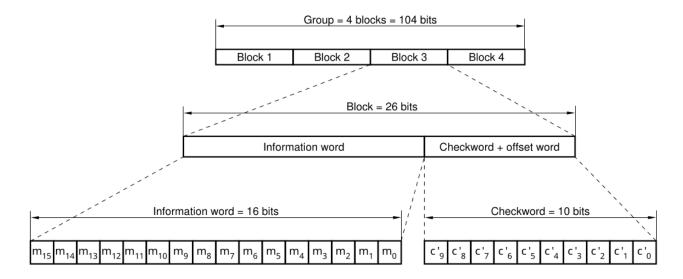


Figure 1: Basic group structure [1]

The aim of this assignment was to create an encoder and a decoder for the Group 0A and 2A message types. The encoder takes input data (such as Program identification, list of Alternative frequencies, etc.) and encodes them into a binary string conforming to the structure of the specified message group. The decoder is then able to take the recieved binary string and decode the original data from it.

# 1.1 Overview of Group 0A

Group 0A is used for encoding basic tuning and switching information. Specifically it contains the following information [2]:

- Programme identification (PI) Unique 16-bit code defining the station (every station in the country should have a unique code).
- Group type Unique 5-bit code defining each group type (00000 for group 0A).
- Programme type (PTY) 31 pre-defined programme types (genres). For example Rock music, News, etc.
- Traffic programme (TP) and Traffic announcement (TA) Flags used to signal that the incoming message is a traffic bulletin. So a reciever can, for example, pause a CD so a driver can listen to the news regarding traffic.
- Music/Speech (MS) Whether there is currently speech or music playing on the station.
- Decoder control bits Address of the group (0 to 3).
- Alternative Frequencies (AF) A list of frequencies providing the same station the reciever can re-tune to if the original signal becomes too weak.
- Programme service name (PS) 2 characters of an 8-character station identity name.

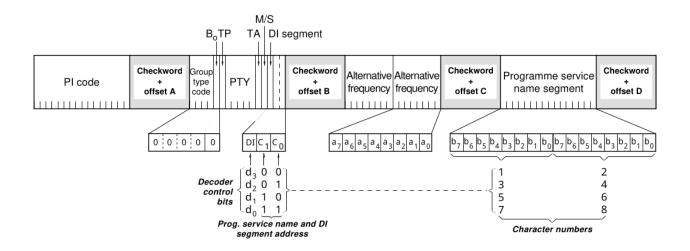


Figure 2: Structure of Group 0A [1]

# 1.2 Overview of Group 2A

Group 2A is used for encoding radio text, i.e. the message that is displayed on the reciever's display (eg. in someone's car). The group encodes the following information:

- Programme identification (PI) Unique 16-bit code defining the station (every station in the country should have a unique code).
- Group type Unique 5-bit code defining each group type (00100 for group 2A).
- Programme type (PTY) 31 pre-defined programme types (genres). For example Rock music, News, etc.

- Text Segment address code Address of the group (0 to 15).
- RadioText Segment 1-2 characters of a 64-character message.
- RadioText Segment 2 Another 2 characters of the 64-character message.

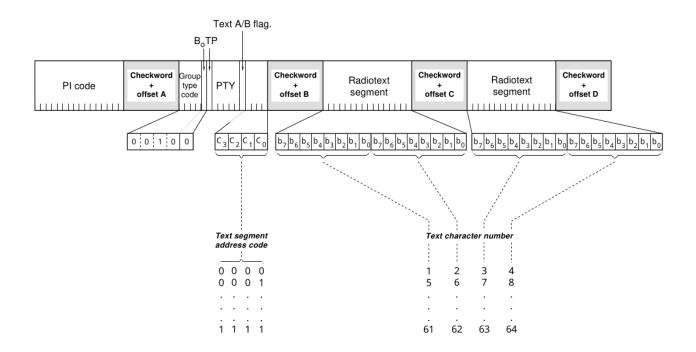


Figure 3: Structure of Group 2A [1]

# 2 Program usage

This section covers the usage of both the rds\_encoder and rds\_decoder programs.

# 2.1 Compilation

The project can be compiled using the command make. The source files are written in C++14, the compiler in use is GCC. The command make clean may be used to delete all object and executable files.

# 2.2 Encoder usage

Encoding of group 0A:

```
./rds_encoder [-g 0A] [-pi <pi>] [-pty <pty>] [-tp <tp>] [-ms <ms>] [-ta <ta>] [-af <af>] [-ps <ps>] [-help]
```

Encoding of group 2A:

```
./rds_encoder [-g 2A] [-pi <pi>] [-pty <pty>] [-rt <rt>] [-ab <ab>] [-help]
```

All arguments are mandatory (except for --help).

### Meaning and expected values for each argument:

- -g: Group type (either "0A" or "2A"),
- -pi: Programme id (16-bit unsigned int),
- -pty: Programme type (5-bit unsigned int),
- -tp: Traffic programme (boolean, 0 or 1),
- -ms: Music/Speech (boolean, 0 or 1),
- -ta: Traffic announcement (boolean, 0 or 1),
- -af: Alternative frequencies (float, float), values must be between 87.6 and 113.0,
- -ps: Programme service name (max. 8-char long string),
- -rt: Radio text (max. 64-char long string),
- -ab: Radio text A\B (boolean, 0 or 1).

# 2.3 Decoder usage

```
./rds_encoder [-b <b>] [--help]
```

The -b argument value should contain a binary string that is n\*104 bits long and it is also a **mandatory** argument.

# 3 Implementation

This chapter focuses on describing the implementation of both the encoder and the decoder as well as pointing out some challenging parts of the implementation.

# 3.1 Implementation of the encoder

First of all comes the parsing of command line arguments. All of the arguments in argv are being looped through, parsed, and stored in the Arguments object one by one. In the end there are some logical checks to ensure that the input combination of arguments is valid.

After that we may approach the actual encoding part. There are two main classes — Group 0A and Group 2A, of which the appropriate one is selected based on the supplied arguments. There is a for loop that loops 4 or 16 times (depending on the group type), in each iteration one group gets encoded (A group 0A message takes 4 groups, while a group 2A message takes 16 groups). The output of each individual group is concatenated to the output string and in the end printed on standard output.

Let's take a look at the encoding of one individual 0A group (the encoding of group 2A is analogical, just slightly different data):

The group object (instance of the aforementioned GroupOA class) has one main method that does all the necessary work -encode\_part (int addr) and also has the Arguments object as a variable. The method goes through the arguments one by one and encodes them into binary strings. For each block it also calculates and encodes the checkwords. The result is then stored in the variable encoded\_string, which is used in the end when concatenating the results from all the groups.

Overall there were not many challenging parts when implementing the encoder, only the creation of checkwords, which will be described later.

# 3.2 Implementation of the decoder

The decoding is trickier. Not the parsing of command line arguments tho, the decoder only takes one argument – the input binary string (so we only need to check whether all of its characters are 1's and 0's and that it has a valid length).

After parsing the arguments the next step is to identify which group we should be decoding. For that the first 104 bits (the first group) are used. Again the decoding process is very similar for both groups, so I will only explain the basic process on the example of group 0A:

The first challenging part is looking out for mixed up groups and properly reordering them. For that a couple of arrays are used — boolean <code>group\_recieved[4]</code> and string <code>message[4]</code>. While decoding each group, the address of the group is extracted and used as an index in these two arrays. The <code>group\_recieved</code> array is initialized to all false, and when a group with say address 1 is decoded, then the flag at index 1 in the array is set to true. That way we can check for duplicate groups as well as whether all groups have been recieved.

The message array is used simply to store parts of the message at their actual correct places and then in the end concatenating the parts into the final message.

Another challenging part is deciding whether there are parts of the message missing. That cannot be done by simply checking if the decoded string is 4\*104 chars long, because shorter messages are also valid. Instead a simple algorithm is used that once again utilizes the group\_recieved boolean

array. We can loop through the array and look for the first encountered false flag. Once encountered, there may be no true flags in the rest of the array, otherwise it will be clear that a part of the originally sent message has been lost (eg. [true, false, true, true] indicates that the second part was not received).

When decoding one specific group, another challenging part is to detect any mixed up blocks and correctly reorder them. For that we can use the checkwords of each block. The program splits the group into four blocks and iterates through them one by one. In each block it calculates the checkword for the information part of the block (the exact same process that happens during encoding – that way we can look for any differences) and compares it with the actual recieved checkword. If they don't match, it tries again with a different offset word and if none of the offset words create a proper checkword, it is clear that some part of the message has been corrupted.

Anyways, depending on which offset word works to create the actual checkword, we can determine which part of the message we are actually looking at (for example looking at the first 26 bits but the checkword corresponds to offset word 'C' - so we are actually looking at the third block and can reorder it in a similar way to the groups reordering).

After reordering all the groups and blocks the process remains relatively simple. The first group that we decoded way back at the start serves as a sort of a standard for the remaining groups. All the decoded data (apart from the group address and the text part of course) are compared to the data of the first group and if there are any differences, then there has clearly been some sort of an error during transmission of the message and we can print an error.

In the end all there's left to do is to concatenate all the decoded text parts and print the decoded info.

## 3.3 Checkword creation

Cyclic redundancy check (CRC) is used in RDS, much like in many other networking standards and protocols, to ensure data integrity. It works by creating a unique checksum for the information part of each block. Thanks to that we can then detect and even to some extent repair errors which occur during transmission. However in this project the CRC is only used to detect errors, repairing is not implemented.

As mentioned previously, every group in RDS is divided into 4 blocks, 26 bits long each. Each block then contains 16 bits of information and a 10-bit checkword. The checkword is created by calculating the CRC of the information part and adding the result to a predetermined offset word. Each block uses a different offset word. Thanks to that we can detect any block mix ups within groups.

The CRC algorithm operates using polynomial division in binary form. The process begins with appending a predetermined number of zero bits to the information part of the block. This number corresponds to the degree of the generator polynomial used for the CRC. The polynomial used in RDS is  $x^{10} + x^8 + x^7 + x^5 + x^4 + x^3 + 1$ . The binary data concatenated with zero bits is then divided by the generator polynomial using modulo-2 division, where no carries are involved. The division results in a remainder, which serves as the CRC value.

All the bitwise operations are implemented on strings of 1's and 0's rather than on bitsets or binary vectors, because it's not really any more difficult using just strings (XOR implementation is trivial). Parts of the implementation are presented in the screenshots below (fig. 4, 5, 6).

Figure 4: Modulo 2 division

```
string calculate_crc(string input) {
   //x^10 + x^8 + x^7 + x^5 + x^4 + x^3 + 1
   string generator = "00110111001";
   int gen_length = generator.length();

   //pad the input with zeros
   string padded_input = input + string(gen_length - 1, '0');

   //calculate the remainder
   string remainder = modulo2_division(padded_input, generator);
   return remainder;
}
```

Figure 5: CRC calculation

Figure 6: Final checkword creation

# 4 Testing

This section presents various test cases for both the encoder and the decoder. This is only a selection of the most important ones, the complete lists of all used test cases can be found in the \*\_test\_inputs.txt files in the root directory of the project.

For example the decoder tests presented here are only for Group 0A, but the same exact tests were performed for Group 2A and all passed.

# 4.1 Valid encoder inputs

## Correct Group 0A input:

#### Correct Group 0A input with shorter message (adds padding spaces):

#### Correct Group 2A input:

[michalb@fedora proj]\$ ./rds\_encoder -g 2A -pi 4660 -pty 5 -tp 1 -rt "Now Playing Song Title by Artist" -ab 0 000011011100

# 4.2 Invalid encoder inputs

#### Missing arguments:

```
[michalb@fedora proj]$ ./rds_encoder -g 0A -pty 5 -tp 1 -ms 0 -af 104.5,98.0 -ps "RadioXYZ" Error: Invalid arguments. Use --help for more information
```

#### Message too long:

```
[michalb@fedora proj]$ ./rds_encoder -g 0A -pi 4660 -pty 5 -tp 1 -ms 0 -ta 1 -af 104.5,98.0 -ps "RadioABCD" Error: Message too long
```

# PI value out of range:

```
[michalb@fedora proj]$ ./rds_encoder -g 0A -pi 65536 -pty 5 -tp 1 -ms 0 -ta 1 -af 104.5,98.0 -ps "RadioXYZ" Error: Argument value out of range
```

#### Invalid AF format:

[michalb@fedora proj]\$ ./rds\_encoder -g 0A -pi 4660 -pty 5 -tp 1 -ms 0 -ta 1 -af 98.5-104.5 -ps "RadioXYZ" Error: Invalid alternative frequencies format

## AF out of range:

```
[michalb@fedora proj]\$ ./rds_encoder -g 0A -pi 4660 -pty 5 -tp 1 -ms 0 -ta 1 -af 10.0,98.0 -ps "RadioXYZ" Error: The lowest allowed alternative frequency is 87.6 MHz
```

# Invalid group:

```
[michalb@fedora proj]$ ./rds_encoder -g 1A -pi 4660 -pty 5 -tp 1 -ms 0 -ta 1 -af 104.5,98.0 -ps "RadioXYZ" Error: Group (-g) must be 0A or 2A
```

# 4.3 Valid decoder inputs

# Groups and blocks in the right order:

## Mixed blocks within groups, group order correct:

## Mixed groups (0 2 1 3), block order correct:

## Mixed groups (0 2 1 3), mixed blocks within groups:

#### Recieved message shorter than max. length (rec. groups 0 1 2):

# 4.4 Invalid decoder inputs

#### Invalid input string length:

# Failed CRC calculation:

# Recieved groups 0 1 and 3 (2 missing):

#### Duplicate group address:

## 4.5 Combined tests

## Group 0A encoding, then decoding:

[michalb@fedora proj]\$ ./rds\_encoder -g 0A -pi 1234 -pty 10 -tp 1 -ms 1 -ta 0 -af 100.2,97.4 -ps "Test" PI: 1234 GT: 0A TP: 1 PTY: 10 TA: Inactive MS: Music DI: 0 AF: 100.2, 97.4 PS: "Test"

## Group 2A encoding, then decoding:

```
[michalb@fedora proj]$ ./rds_encoder -g 2A -pi 3333 -pty 3 -tp 1 -rt "Now playing The Emptiness Machine by Linkin Park
PI: 3333
GT: 2A
TP: 1
PTY: 3
RT: "Now playing The Emptiness Machine by Linkin Park"
```

# 5 References

- [1] CENELEC. EN50067 RDS Standard. 1998. URL: http://www.interactive-radio-system.com/docs/EN50067\_RDS\_Standard.pdf. visited on 10/12/2024.
- [2] Wikipedia: Radio Data System. URL: https://en.wikipedia.org/wiki/Radio\_Data\_System. visited on 10/12/2024.