

2. Una partícula se mueve en el potencial:

$$V(r) = \frac{a}{r} + \frac{b}{r^2}.$$

a) Determine la órbita de la partícula $r=r(\theta)$

La posición de la partícula está dada por:

$$\vec{r} = r \hat{r} \rightarrow \dot{\vec{r}} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

$$\rightarrow \text{Su lagrangiana es: } L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - \frac{a}{r} - \frac{b}{r^2}$$

Que, como el potencial no depende de las velocidades y el lagrangiano es independiente del tiempo, nos da:

$$\frac{dL}{dt} = \frac{\partial L}{\partial r} \dot{r} + \frac{\partial L}{\partial \dot{r}} \ddot{r} + \frac{\partial L}{\partial \theta} \dot{\theta} + \frac{\partial L}{\partial \dot{\theta}} \ddot{\theta}$$

$$= \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) \dot{r} + \frac{\partial L}{\partial \dot{r}} \ddot{r} = \frac{d}{dt} \left[\frac{\partial L}{\partial \dot{r}} \dot{r} \right]$$

$$\rightarrow \frac{d}{dt} \left[\frac{\partial L}{\partial \dot{r}} \dot{r} - L \right] = 0 \rightarrow \frac{\partial L}{\partial \dot{r}} \dot{r} - L = \text{cte}$$

$$\rightarrow 2T - T + V = T + V = E_m = \text{cte}$$

$$\text{ie, } E = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - \frac{a}{r} + \frac{b}{r^2}$$

$$\rightarrow \frac{1}{2} m \dot{r}^2 = E - \frac{a}{r} - \frac{b}{r^2} - \frac{m r^2 \dot{\theta}^2}{2} \geq 0$$

$$\rightarrow \dot{r} = \sqrt{\frac{2}{m} \left(E - \frac{a}{r} - \frac{b}{r^2} - \frac{m r^2 \dot{\theta}^2}{2} \right)} = \frac{dr}{dt}$$

$$\therefore \int_{t=0}^t dt = \int_{r_0}^r \frac{1}{\sqrt{\frac{m}{2} \left(E - \frac{a}{r} - \frac{b}{r^2} - \frac{m r^2 \dot{\theta}^2}{2} \right)}} dr \Rightarrow t(r)$$

$$\mu \ddot{r} = f(r) + \frac{l^2}{mr^3}$$

Ahora, debido a que el potencial es central, tenemos que:

$$\tau = \vec{r} \times \vec{F} = \vec{r} \times f(r) \hat{r} = 0 \Leftrightarrow \frac{d}{dt} \vec{L} = 0 \Leftrightarrow \vec{L} = \text{cte}$$

→ Tanto el ángulo como el módulo del momento angular se conservan. Por lo cual, podemos obtener de: lo siguiente que:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0 \Leftrightarrow \frac{\partial L}{\partial \dot{\theta}} = mr^2 \dot{\theta} = l$$

Por lo cual, podemos tener que:

$$\frac{d\theta}{dt} = \frac{d\theta}{dr} \frac{dr}{dt} = \frac{l}{mr^2}$$

$$\rightarrow \frac{d\theta}{dr} = \frac{l}{mr^2} \frac{1}{\frac{dr}{dt}} = \frac{l}{mr^2} \frac{1}{\sqrt{\frac{2}{m} \left(E - \frac{1}{2} mr^2 \dot{\theta}^2 - \frac{a}{r} - \frac{b}{r^2} \right)}}$$

$$- \text{Pero de } mr^2 \dot{\theta} = l \Rightarrow \frac{l^2}{2mr^2}$$

$$\rightarrow \int_{\theta_0}^{\theta} d\theta = \frac{l}{m} \int_{r_0}^r \frac{1}{r^2} \frac{dr}{\sqrt{\frac{2}{m} \left(E - \frac{l^2}{2mr^2} - \frac{a}{r} - \frac{b}{r^2} \right)}}$$

$$\therefore \theta(r) = \frac{l}{m} \int_{r_0}^r \frac{dr}{r^2 \sqrt{\frac{2}{m} \left(E - \frac{l^2}{2mr^2} - \frac{a}{r} - \frac{b}{r^2} \right)}} + \theta_0$$

! Pero nos queda una ecuación del movimiento para $r(\theta)$. Entonces, de la ecuación de Euler-Lagrange para r :

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) - \frac{\partial L}{\partial r} = 0 \rightarrow m \ddot{r} - (m \dot{\theta}^2) + \frac{a}{r^2} + \frac{2b}{r^3} = 0 \quad (1)$$

Pero, haciendo lo siguiente:

$$\frac{dg}{dt} = \frac{dg}{d\theta} \frac{d\theta}{dt} = \frac{1}{mr^2} \frac{dg}{d\theta} \rightarrow \frac{d}{dt} = \frac{1}{mr^2} \frac{d}{d\theta}$$

Para una función g arbitraria. Luego,

$$\ddot{r} = \frac{d}{dt} \left(\frac{dr}{dt} \right) = \frac{d}{dt} \left(\frac{1}{mr^2} \frac{dr}{d\theta} \right)$$

$$= \frac{1}{mr^2} \frac{d}{d\theta} \left(\frac{1}{mr^2} \frac{dr}{d\theta} \right) \quad (1)$$

Por lo cual, en la ecuación (1):

$$m \ddot{r} = \frac{l^2}{mr^3} + \frac{a}{r^2} + \frac{2b}{r^3} = 0$$

$$\rightarrow m \ddot{r} = \frac{l^2}{mr^3} + \frac{a}{r^2} + \frac{2b}{r^3} = f(r) = -\frac{\partial V}{\partial r} \quad (x)$$

Pero: $\frac{\partial V}{\partial r} = \frac{\partial V}{\partial u} \frac{\partial u}{\partial r}$

Qu, para $u = \frac{1}{r} \rightarrow \frac{\partial V}{\partial r} = \frac{\partial V}{\partial u} \left(-\frac{1}{r^2} \right) = \frac{\partial V}{\partial u} (-u^2)$

\rightarrow en (x), con (1):

$$\frac{\partial u}{\partial \theta} = \left(-\frac{1}{r^2} \right) \frac{\partial r}{\partial \theta} = -u^2 \frac{\partial r}{\partial \theta}$$

$$\rightarrow \frac{l^2}{m} \frac{d}{d\theta} \left(-\frac{\partial u}{\partial \theta} \right) - \frac{l^2 u^3}{m} = -u^2 \frac{\partial V}{\partial u} u^3$$

$$\rightarrow \frac{l^2}{m} \left(\frac{d^2 u}{d\theta^2} + u \right) = -\frac{\partial V}{\partial u}$$

La anterior ecuación constituye la ecuación diferencial de la órbita para $r(\theta) = 1/u(\theta)$ en términos del potencial $V(r) = V(1/u)$

$$\rightarrow \frac{\partial V}{\partial u} = \frac{\partial V}{\partial r} \frac{\partial r}{\partial u} = \left(-\frac{a}{r^2} - \frac{2b}{r^3} \right) \left(-\frac{1}{u^2} \right)$$

$$= (au^2 + 2bu^3) \left(\frac{1}{u^2} \right) = a + 2bu$$

$$\rightarrow -\frac{\partial V}{\partial u} = a + 2bu = \frac{l^2}{m} \left(\frac{\partial^2 u}{\partial \theta^2} + u \right)$$

$$\rightarrow a + 2bu - \frac{l^2}{m} u = \frac{l^2}{m} \frac{\partial^2 u}{\partial \theta^2}$$

$$\rightarrow a + u \left(2b - \frac{l^2}{m} \right) = \frac{l^2}{m} \frac{\partial^2 u}{\partial \theta^2}$$

$$a + u \left(2b - \frac{l^2}{m} \right) = \frac{l^2}{m} \frac{\partial}{\partial \theta} \left(\frac{\partial u}{\partial \theta} \right)$$

$$-\frac{l^2}{m} \frac{\partial^2 u}{\partial \theta^2} + \left(\frac{l^2}{m} - 2b \right) u = a$$

$$\rightarrow \frac{\partial^2 u}{\partial \theta^2} + \left(1 - \frac{2bm}{l^2} \right) u = \frac{ma}{l^2}$$

$$\text{So } m^2 + \left(1 - \frac{2bm}{l^2} \right) = 0$$

$$\rightarrow m^2 = \frac{2bm}{l^2} - 1$$

$$\rightarrow m_{1,2} = \pm \sqrt{\frac{2bm}{l^2} - 1} = \pm i \omega_0$$

$$\therefore u_c(\theta) = A e^{\omega_0 \theta} + B e^{-\omega_0 \theta}$$

$$\text{Also, So } \frac{\partial^2 u}{\partial \theta^2} + \left(1 - \frac{2bm}{l^2} \right) u = \frac{ma}{l^2}$$

$$\rightarrow \text{Sea } y_p(\theta) = C$$

$$\rightarrow \left(1 - \frac{2mb}{l^2}\right)C = \frac{ma}{l^2}$$

$$\rightarrow C = \frac{ma}{l^2 - 2mb}$$

$$\begin{aligned} \therefore u(\theta) &= u_c + u_p \\ &= A e^{w_0 \theta} + B e^{-w_0 \theta} + \frac{ma}{l^2 - 2mb} \end{aligned}$$

pero, como $r = 1/u$,

$$\rightarrow r(\theta) = \frac{1}{u(\theta)} = \frac{1}{A e^{w_0 \theta} + B e^{-w_0 \theta} + \frac{ma}{l^2 - 2mb}}$$

El denominador de cada término es $M_T/8$ en colisión. 1 m.

(b) Dibuja esquemáticamente el potencial efectivo para este sistema.

$$E = \frac{1}{2}m(\dot{r}^2 + r^2\dot{\theta}^2) + \frac{a}{r} + \frac{b}{r^2}$$
$$\rightarrow V_{\text{ef}}(r) = r^2\dot{\theta}^2 + \frac{a}{r} + \frac{b}{r^2}$$

