```
import shutil
from pathlib import Path
import cv2
import matplotlib.pyplot as plt
import numpy as np
import torch
from pytube import YouTube
from facenet pytorch import MTCNN, InceptionResnetV1
from IPython.display import Video
from PIL import Image
from torch.utils.data import DataLoader
from torchvision import datasets, transforms
Start coding or generate with AI.
import torch
import torchvision
print(f"PyTorch version: {torch.__version__}")
print(f"Torchvision version: {torchvision.__version__}")
→ PyTorch version: 2.8.0+cu128
     Torchvision version: 0.23.0+cu128
if torch.cuda.is_available():
    device = torch.device("cuda")
else:
    device = torch.device("cpu")
print(f"Using {device} device")
→ Using cuda device
data_dir = Path("data")
print(data dir)
→ data
video_name = "/Rohit Sharma Interviews Virat Kohli _ Kohli on His 71st Century _.mp4"
```

```
Start coding or <u>generate</u> with AI.

Start coding or <u>generate</u> with AI.

Video(video_name, width=400, embed=True)

The start coding or generate with AI.
```

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```
frames_dir = data_dir / "frames"
frames_dir.mkdir(parents=True, exist_ok=True)
print(frames_dir)
→ data/frames
video_capture = cv2.VideoCapture(video_name)
frame_rate = round(video_capture.get(cv2.CAP_PROP_FPS))
print(f"Frame rate: {frame_rate}")
→ Frame rate: 24
interval = 6
frame cnt = 0
print("Start Extracting individual frames...")
while True:
  ret, frame = video_capture.read()
 if not ret:
   print("Finished!")
    break
 if frame_cnt % interval == 0:
   frame_path = frames_dir / f"frame_{frame_cnt}.jpg"
   cv2.imwrite(frame_path, frame)
```

```
frame cnt += 1
video capture.release()
→ Start Extracting individual frames...
     Finished!
images_dir = data_dir / "images"
images_dir.mkdir(exist_ok = True)
print(images_dir)
    data/images
virat_dir = images_dir / "virat"
virat_dir.mkdir(exist_ok = True)
print(virat dir)
→ data/images/virat
rohit_dir= images_dir / "rohit"
rohit_dir.mkdir(exist_ok = True)
print(rohit_dir)
→ data/images/rohit
virat_imgs = [
 "frame_1002.jpg",
 "frame_1812.jpg",
 "frame_3468.jpg",
 "frame_4248.jpg",
  "frame19.jpg",
 "frame21.jpg",
  "frame22.jpg",
  "frame20.jpg"
rohit_imgs = [
    "frame_0.jpg",
    "frame_12.jpg",
    "frame1.jpg",
    "frame7.jpg",
    "frame5.jpg",
    "frame3.jpg"
```

```
virat img path = [frames dir / i for i in virat imgs]
rohit img path = [frames dir / i for i in rohit imgs]
fig, axs = plt.subplots(1, 6, figsize=(10, 8))
for i, ax in enumerate(axs):
    ax.imshow(Image.open(virat_img_path[i]))
    ax.axis("off")
fig, axs = plt.subplots(1, 6, figsize=(10, 8))
for i, ax in enumerate(axs):
    ax.imshow(Image.open(rohit img path[i]))
    ax.axis("off")
→*
for image_path in virat_img_path:
    shutil.copy(image_path, virat_dir)
for image_path in rohit_img_path:
  shutil.copy(image_path, rohit_dir)
print("Number of files in lupita directory:", len(list(virat dir.iterdir())))
print("Number of files in christoph directory:", len(list(rohit_dir.iterdir())))
    Number of files in lupita directory: 8
     Number of files in christoph directory: 6
mtcnn = MTCNN(keep_all = True, min_face_size=40)
print(f"MTCNN min face size: {mtcnn.min_face_size}")
print(f"MTCNN keeping all faces: {mtcnn.keep_all}")
```

```
MTCNN min face size: 40
MTCNN keeping all faces: True
```

```
sample_img_file = "frame13.jpg"
sample_img_path = frames_dir / sample_img_file
sample_img = Image.open(sample_img_path)
sample_img
```





boxes, probs, landmarks = mtcnn.detect(sample_img, landmarks=True)

```
[[234.7548370361328 86.96129608154297]
       [258.8223571777344 85.01781463623047]
       [248.49777221679688 98.38945007324219]
       [238.57534790039062 112.03851318359375]
       [258.57928466796875 110.50773620605469]]
      [[238.4308624267578 147.1172637939453]
       [250.38262939453125 145.60923767089844]
       [245.43763732910156 154.9967041015625]
       [241.02821350097656 160.63148498535156]
       [250.9916229248047 159.37039184570312]]]
fig, ax = plt.subplots()
ax.imshow(sample_img)
for box, landmark in zip(boxes, landmarks):
    rect = plt.Rectangle(
        (box[0], box[1]), box[2] - box[0], box[3] - box[1], fill=False, color="blue"
    ax.add patch(rect)
    for point in landmark:
        ax.plot(point[0], point[1], marker="o", color="red")
plt.axis("off");
₹
```





```
resnet = InceptionResnetV1(pretrained="vggface2").eval()
print(f"InceptionResnet weight set: {resnet.pretrained}")
```

```
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     InceptionResnet weight set: vggface2
dataset = datasets.ImageFolder(images dir)
print(dataset)
→ Dataset ImageFolder
        Number of datapoints: 14
         Root location: data/images
idx_to_class = {i:c for c, i in dataset.class_to_idx.items()}
print(idx_to_class)
→ {0: 'rohit', 1: 'virat'}
def collate_fn(x):
  return x[0]
loader = DataLoader(dataset, collate_fn=collate_fn)
print(loader.dataset)
→ Dataset ImageFolder
         Number of datapoints: 14
         Root location: data/images
name to embeddings = {name: [] for name in idx to class.values()}
for img, idx in loader:
   faces, probs = mtcnn(img, return prob=True)
   if faces is not None:
        for face, prob in zip(faces, probs):
           if prob >= 0.80:
                emb = resnet(face.unsqueeze(0))
                name to embeddings[idx to class[idx]].append(emb)
print(name to embeddings.keys())
print(type(name to embeddings["virat"]))
print(type(name_to_embeddings["rohit"]))
→ dict_keys(['rohit', 'virat'])
     <class 'list'>
     <class 'list'>
embeddings_virat = torch.stack(name_to_embeddings["virat"])
embeddings_rohit = torch.stack(name_to_embeddings["rohit"])
```

```
print(f"Shape of stack of embeddings for virat: {embeddings virat.shape}")
print(f"Shape of stack of embeddings for rohit: {embeddings rohit.shape}")
→ Shape of stack of embeddings for virat: torch.Size([9, 1, 512])
    Shape of stack of embeddings for rohit: torch.Size([6, 1, 512])
avg embedding virat = torch.mean(embeddings virat, dim=0)
avg_embedding_rohit = torch.mean(embeddings_rohit, dim=0)
print(f"Shape of avg embedding virat: {avg embedding virat.shape}")
print(f"Shape of avg_embedding_rohit: {avg_embedding_rohit.shape}")
Shape of avg_embedding_virat: torch.Size([1, 512])
     Shape of avg embedding rohit: torch.Size([1, 512])
test_images = [
    'frame22.jpg',
    "frame_0.jpg",
    "frame 1008.jpg",
    "frame_1026.jpg",
test_paths = [frames_dir / frame for frame in test_images]
fig, axs = plt.subplots(1, len(test_paths), figsize=(10, 8))
for i, ax in enumerate(axs):
   ax.imshow(Image.open(test_paths[i]))
    ax.axis("off")
→
def recognize_faces(img_path, embedding_data, mtcnn, resnet, threshold=0.7):
   image = Image.open(img path)
   boxes, probs = mtcnn.detect(image)
   cropped_images = mtcnn(image)
   if boxes is None:
        return
```

```
# This sets the image size and draws the original image
   width, height = image.size
   dpi = 96
   fig = plt.figure(figsize=(width / dpi, height / dpi), dpi=dpi)
   axis = fig.subplots()
   axis.imshow(image)
   plt.axis("off")
   # Iterating over each face and comparing it against the pre-calculated embeddings
   # from our "database"
   for box, prob, face in zip(boxes, probs, cropped_images):
        if prob < 0.90:
           continue
        # Draw bounding boxes for all detected faces
        rect = plt.Rectangle(
           (box[0], box[1]),
           box[2] - box[0],
           box[3] - box[1],
           fill=False,
           color="blue",
        axis.add patch(rect)
        # Find the closest face from our database of faces
        emb = resnet(face.unsqueeze(0))
       distances = {}
       for known_emb, name in embedding_data:
           dist = torch.dist(emb, known emb).item()
           distances[name] = dist
        closest, min dist = min(distances.items(), key=lambda x: x[1])
        # Drawing the box with recognition results
        name = closest if min_dist < threshold else "Unrecognized"</pre>
        color = "red" if name == "Unrecognized" else "blue"
        label = f"{name} {min_dist:.2f}"
        axis.text(box[0], box[1], label, fontsize=8, color=color)
   plt.axis("off")
   plt.show()
embedding list = [avg_embedding_virat, avg_embedding_rohit]
name_list = ["virat", "rohit"]
embedding_data = list(zip(embedding_list, name_list))
print(embedding_data[0][0].shape, embedding_data[0][1])
print(embedding_data[1][0].shape, embedding_data[1][1])
```

```
torch.Size([1, 512]) virat
torch.Size([1, 512]) rohit

recognized_faces = []
for test_img_path in test_paths:
    recognized_faces.append(
        recognize_faces(test_img_path, embedding_data, mtcnn, resnet))
```









recognize_faces(frames_dir / "frame_1062.jpg", embedding_data, mtcnn, resnet)





recognize_faces(frames_dir / "frame13.jpg", embedding_data, mtcnn, resnet)



