

ESC201: INTRODUCTION TO ELECTRONICS

MODULE 5: AMPLIFIERS

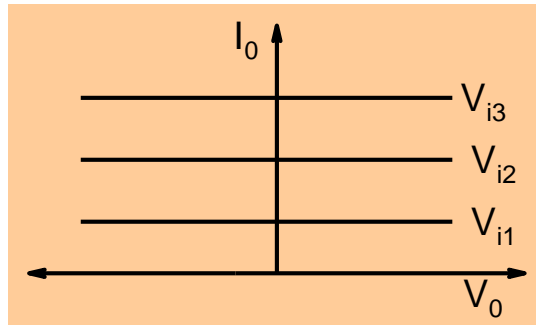
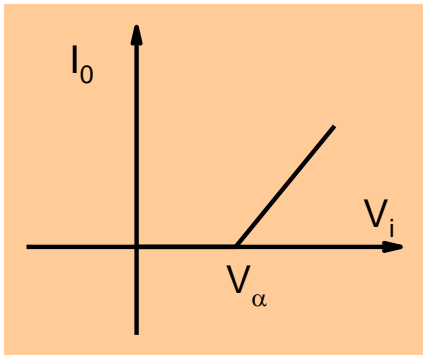
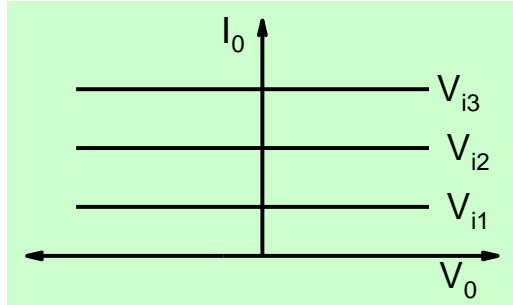
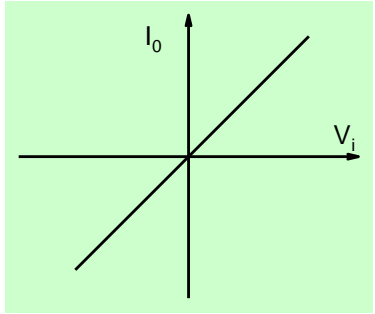


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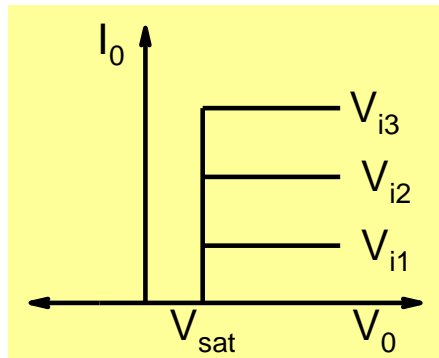
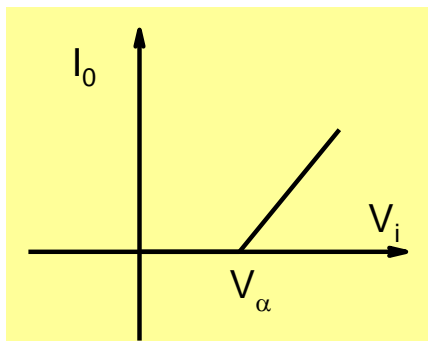


Why do Transistors Amplify Signals if Biased Properly

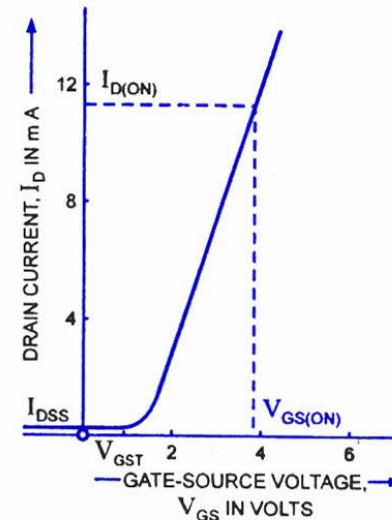
Ideal transistor



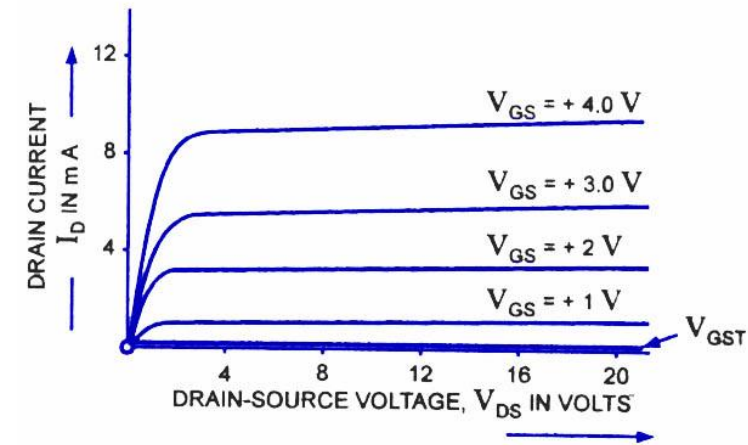
Device X



Device Y

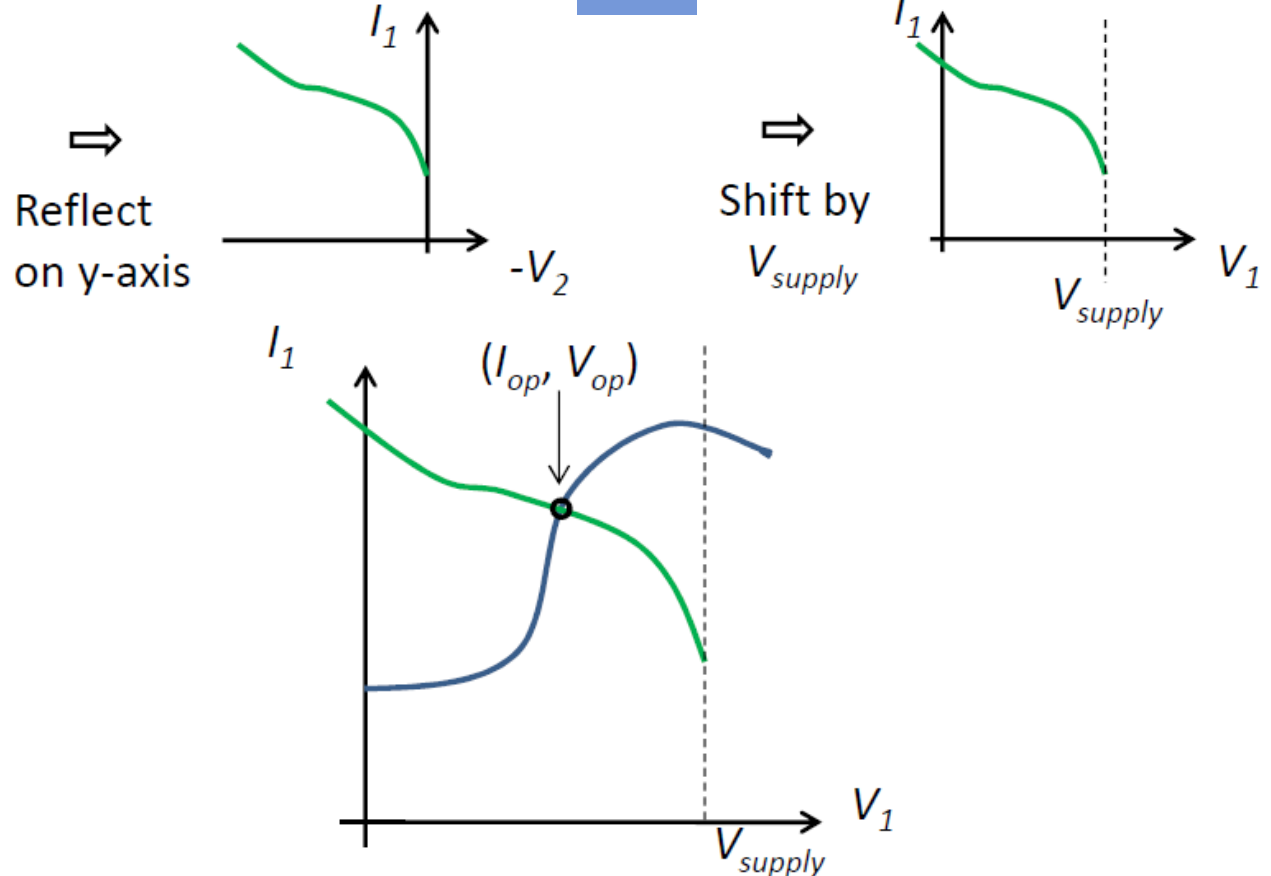
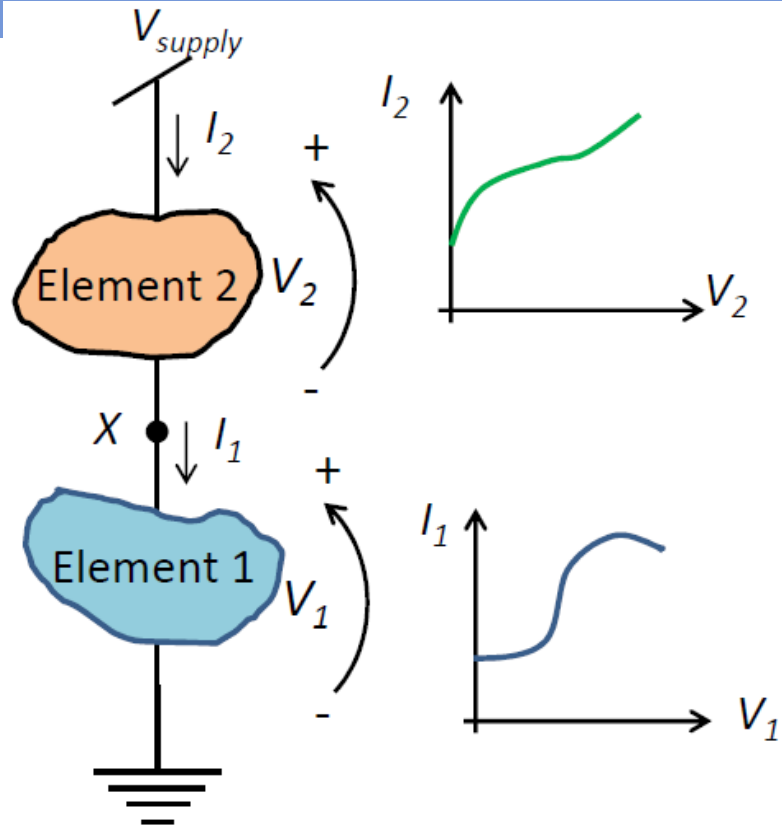


Transfer Characteristic



Drain Characteristics

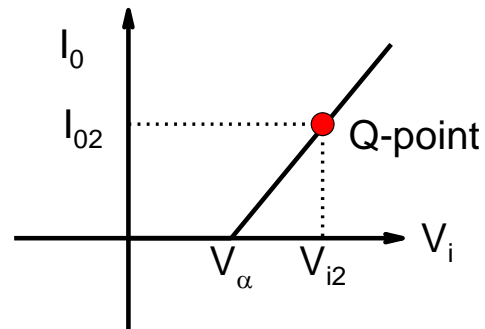
REVISITING LOAD LINE ANALYSIS



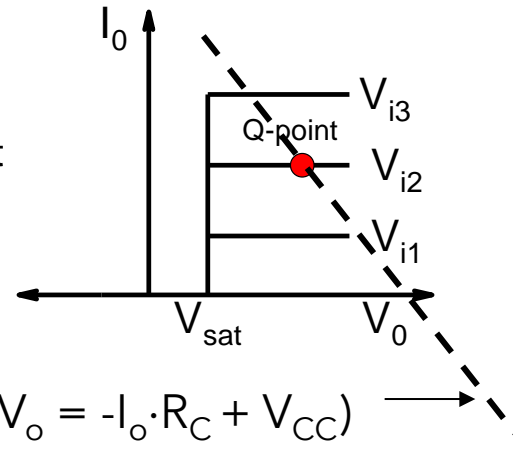
- $I_2 = I_1$ (no change in the direction); $V_2 = V_{supply} - V_1$ i.e. $V_1 = V_{supply} - V_2$
- Current in both Elements 1 & 2 is I_{op} .
- Voltage in node X is V_{op} .
- Voltage drop is V_{op} and $(V_{supply} - V_{op})$ in Elements 1 & 2, respectively.

Revised Amplifier Schematic for Device Y

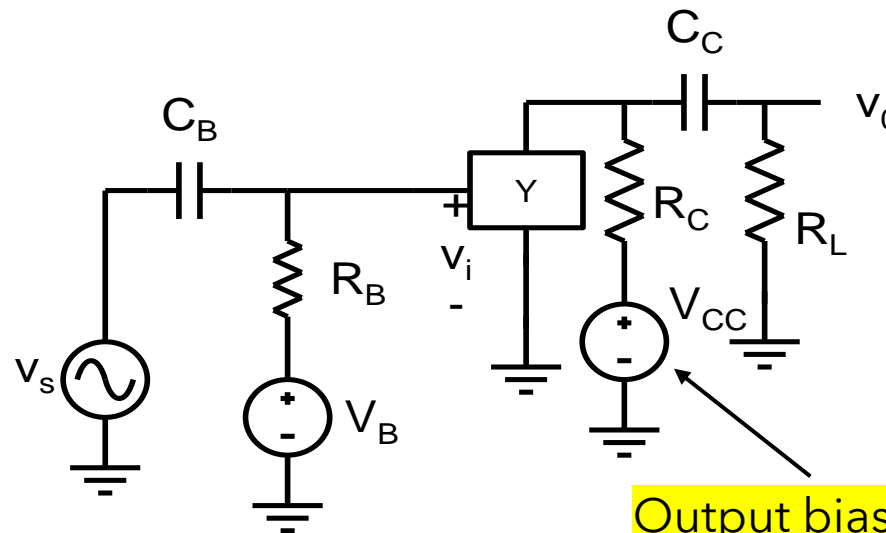
Transfer Characteristics



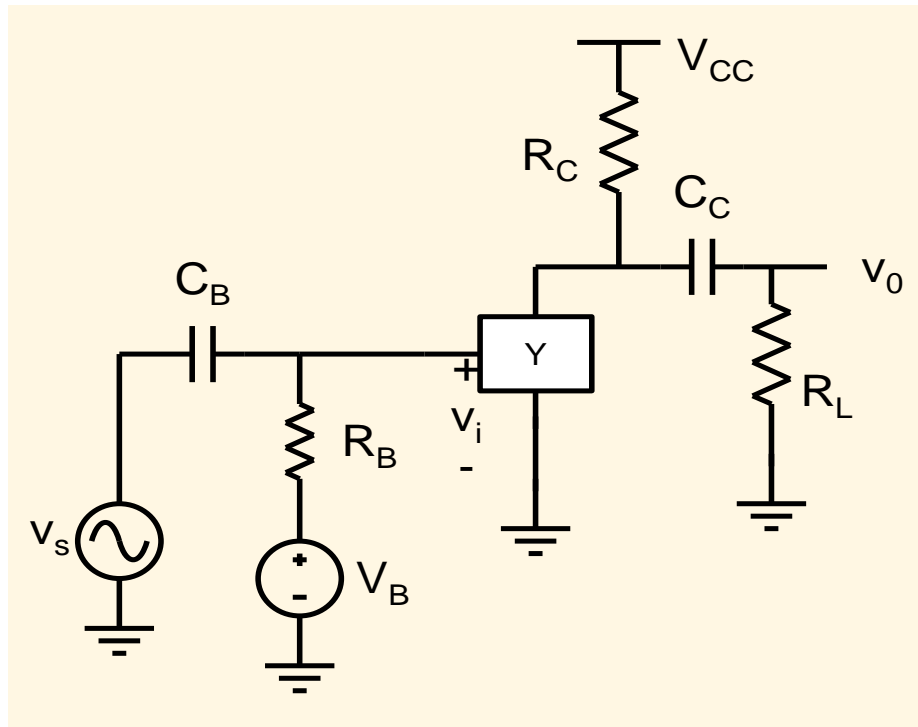
Output Characteristics



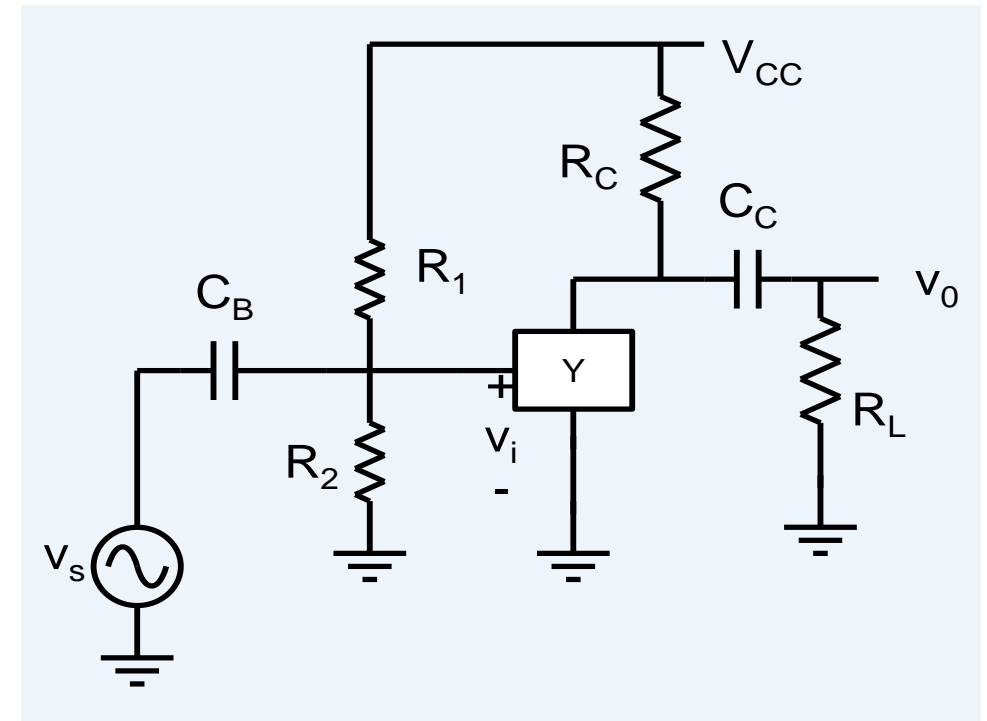
Usually V_{CC} is fixed
 I_o and R_C are varied



Do we really need two DC power supplies?



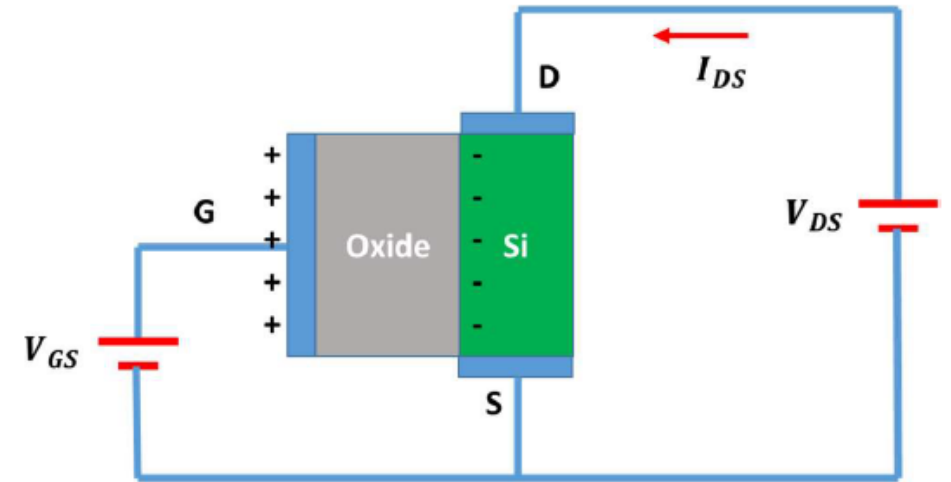
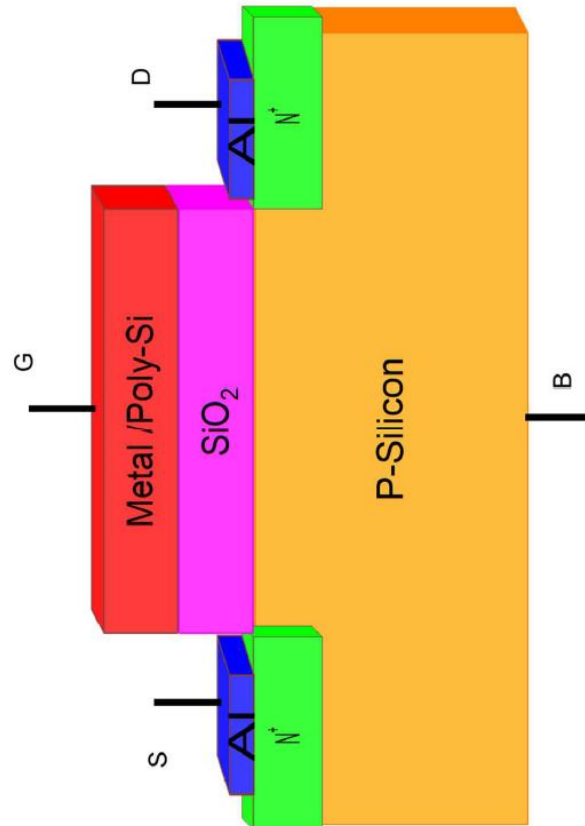
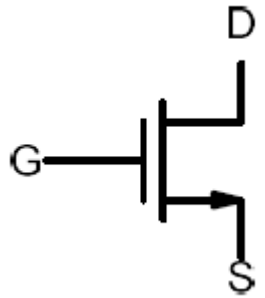
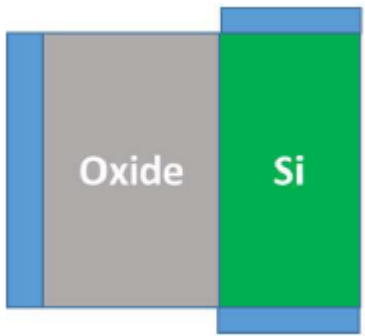
$$V_B = V_{CC} \times \frac{R_2}{R_1 + R_2}$$



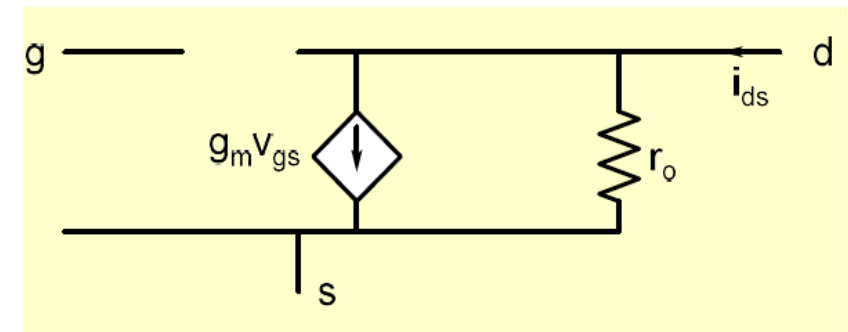
Remember: input of Y is open circuit

MOSFETs: Workhorse of Semiconductor Industry

MOSFET : Metal Oxide Semiconductor Field effect Transistor

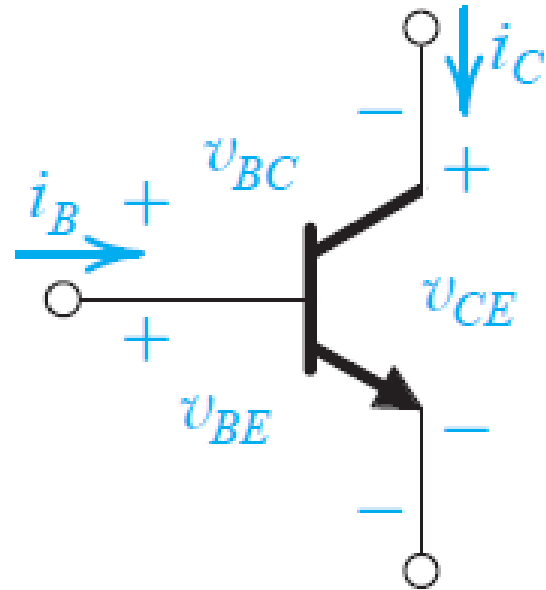


Drain current is controlled by gate voltage



Voltage controlled current source

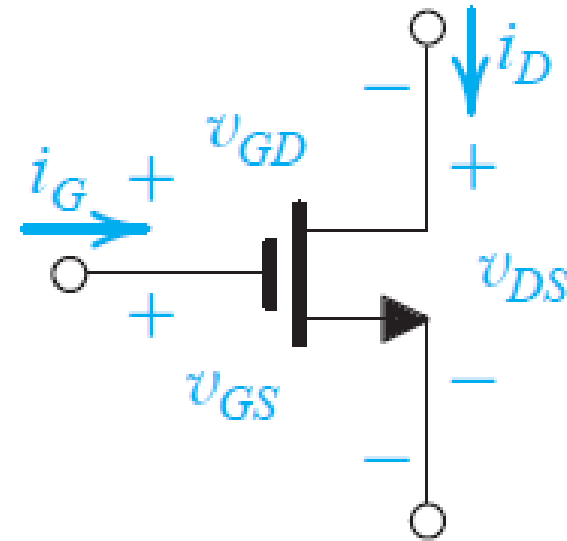
BJT vs. MOSFET



High gain

Small caps

Static power

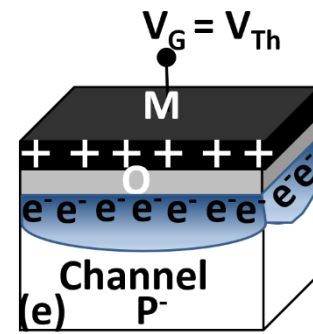
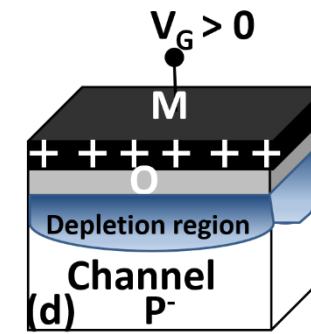
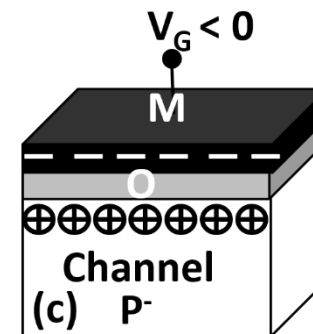
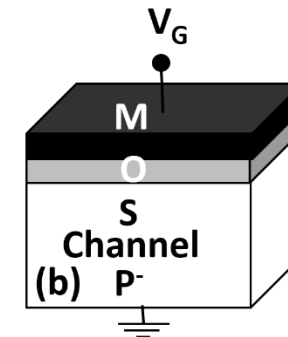
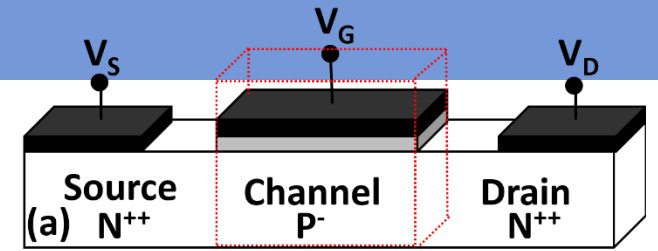
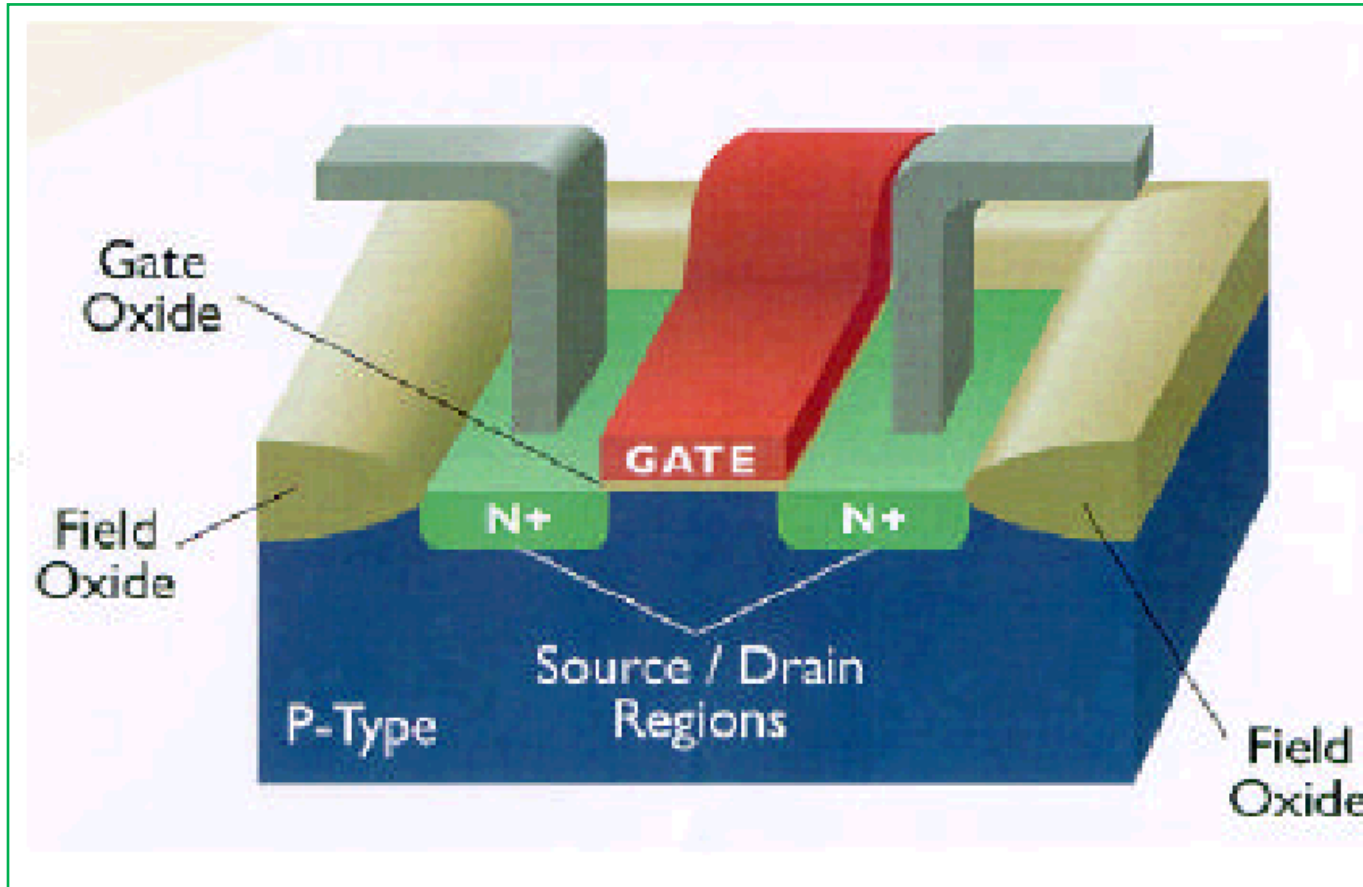


Low gain

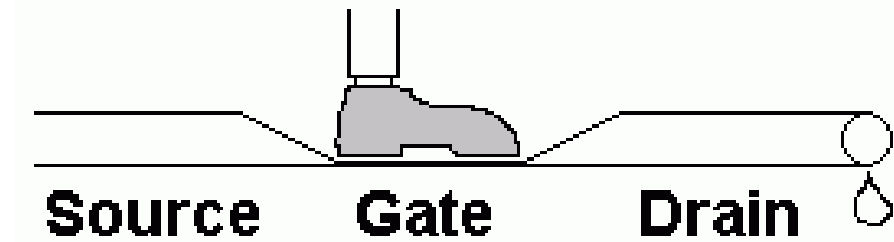
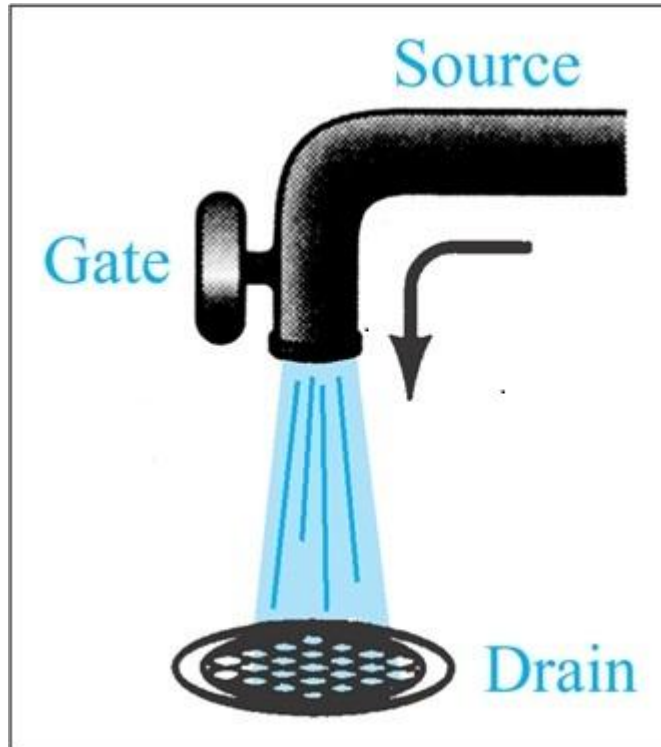
Large caps

Dynamic power

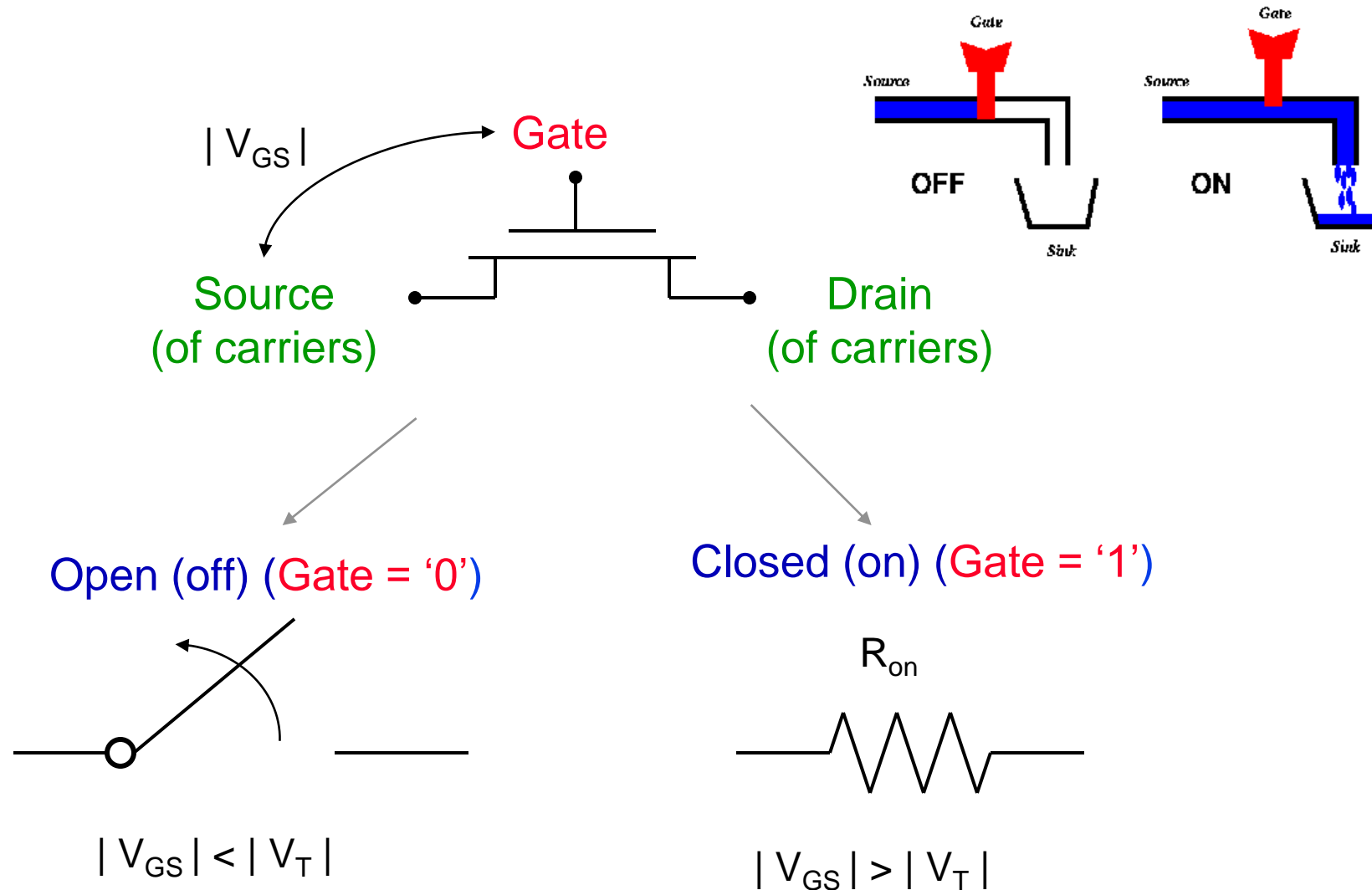
The MOSFET



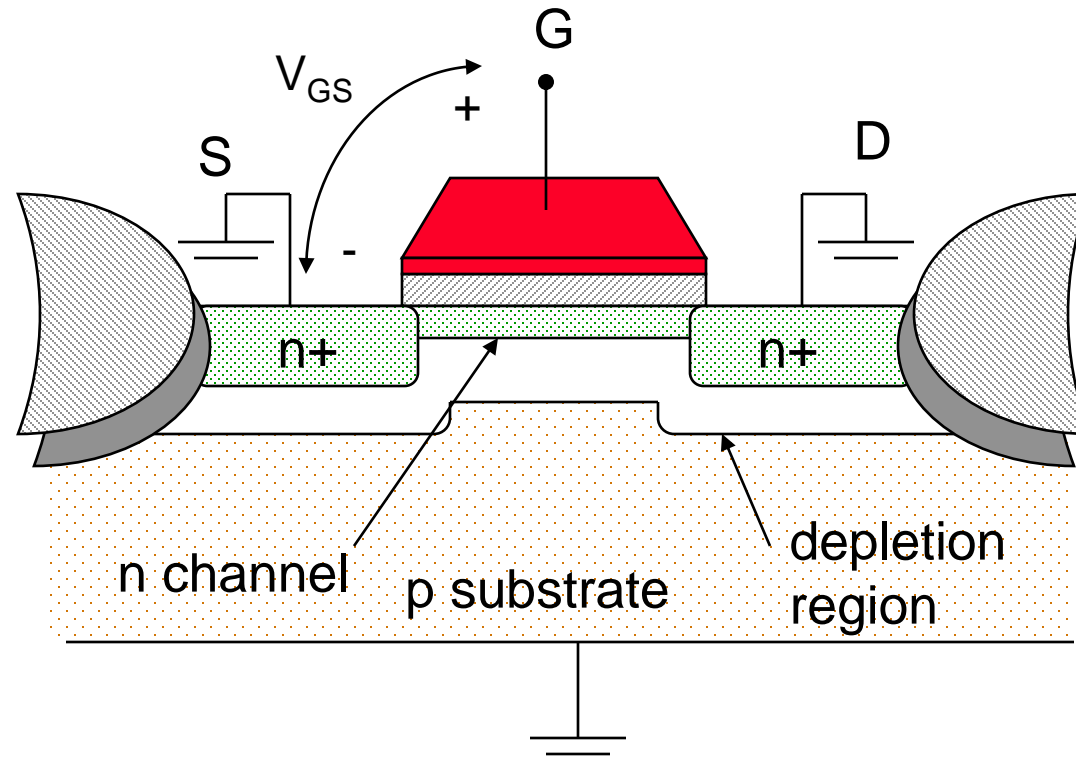
Water Analogy - V_G control



Switch Model of NMOS Transistor



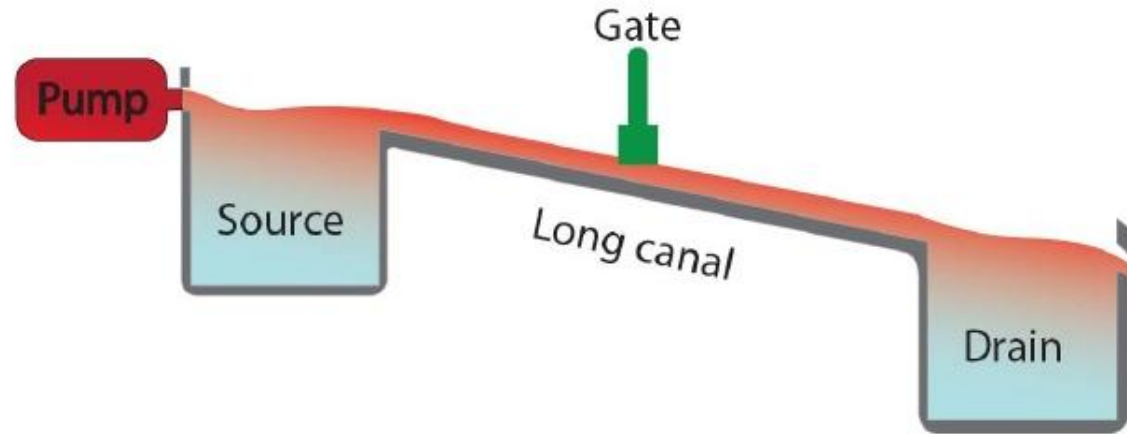
Threshold Voltage Concept



- Conductivity of the channel is modulated by the gate voltage
 - Larger the voltage difference between gate and source, the smaller the resistance of the conducting channel and the larger the current
- The value of V_{GS} where strong inversion occurs is called the threshold voltage, V_T

Water Analogy – Effect of V_G and V_{DS}

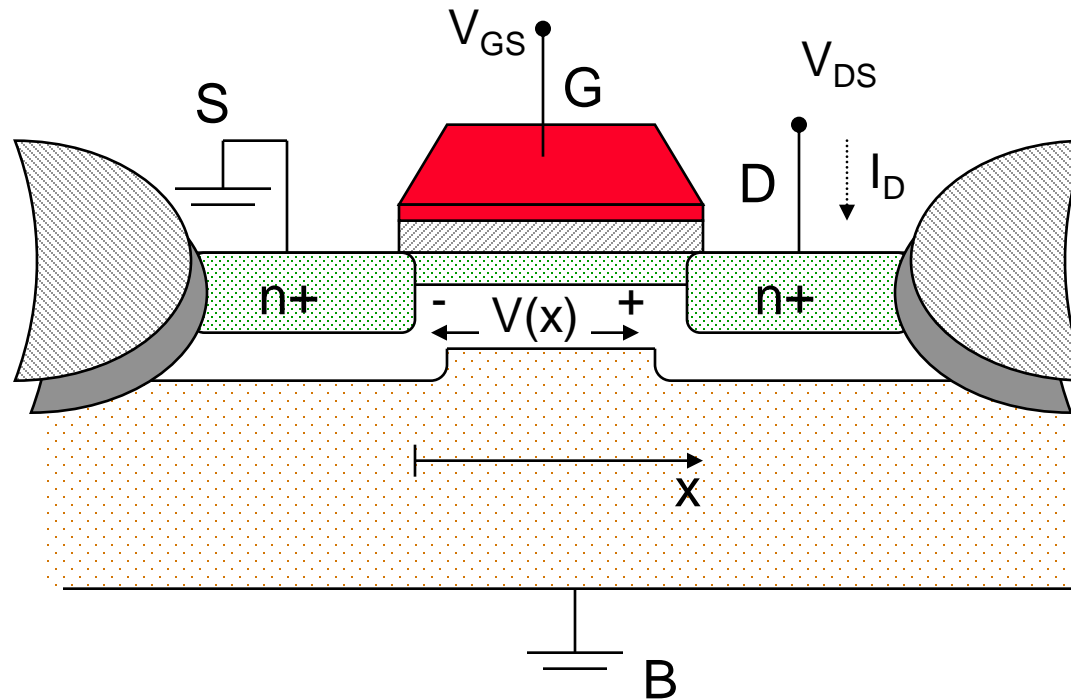
Water \leftrightarrow Current



- When a wall present between source/drain reservoirs is pulled up: water flows (ON)
- Good control over leakage through or over the wall and well set open/closed state.

Transistor in Linear Mode

Assuming $V_{GS} > V_T$



The current is a linear function of both V_{GS} and V_{DS}

Voltage-Current Relation: Linear Mode

For long channel devices

□ When $V_{DS} \leq V_{GS} - V_T$

$$I_D = k'_n \frac{W}{L} \left[(V_{GS} - V_T)V_{DS} - \frac{V_{DS}^2}{2} \right]$$

where

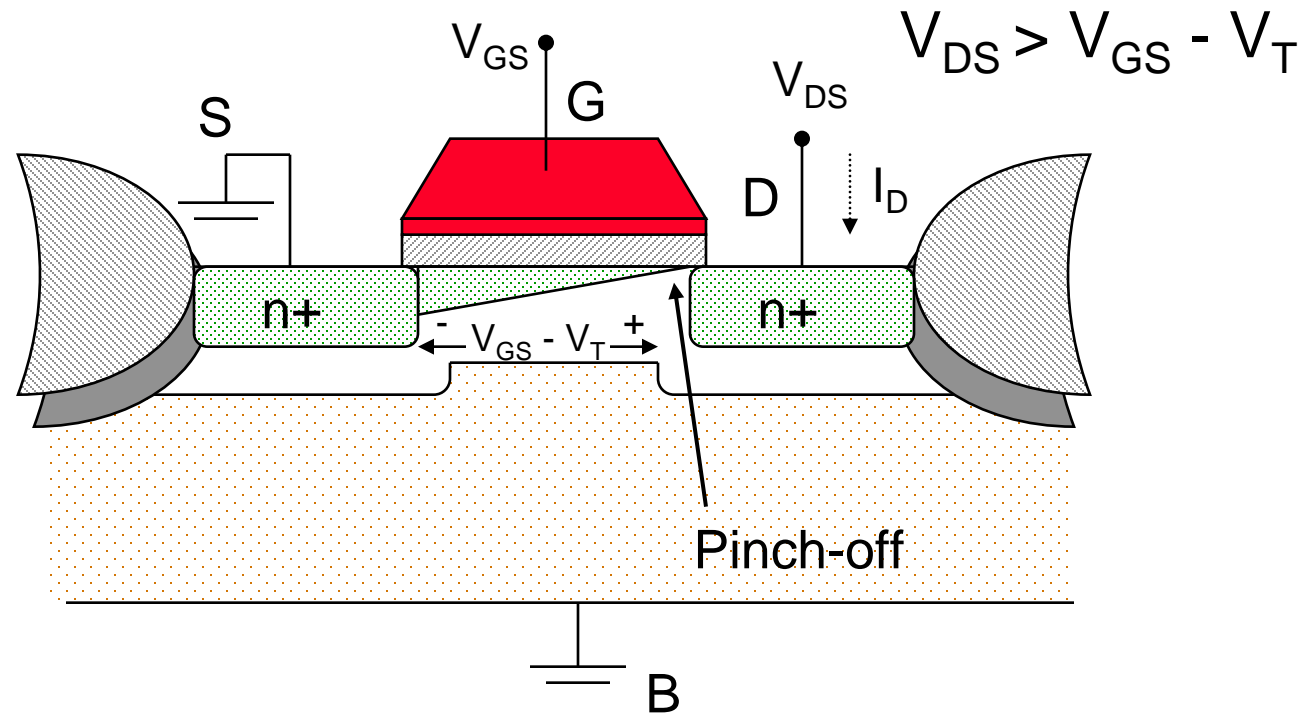
$k'_n = \mu_n C_{ox} = \mu_n \epsilon_{ox} / t_{ox}$ = is the **process transconductance parameter** (μ_n is the carrier mobility ($m^2/Vsec$))

$k_n = k'_n W/L$ is the **gain factor** of the device

For small V_{DS} , there is a linear dependence between V_{DS} and I_D , hence the name **resistive** or **linear** region

Transistor in Saturation Mode

Assuming $V_{GS} > V_T$



The current remains constant (saturates).

Voltage-Current Relation: Saturation Mode

For long channel devices

□ When $V_{DS} \geq V_{GS} - V_T$

$$I_D = k_n \frac{W}{L} \left[\frac{(V_{GS} - V_T)^2}{2} \right]$$

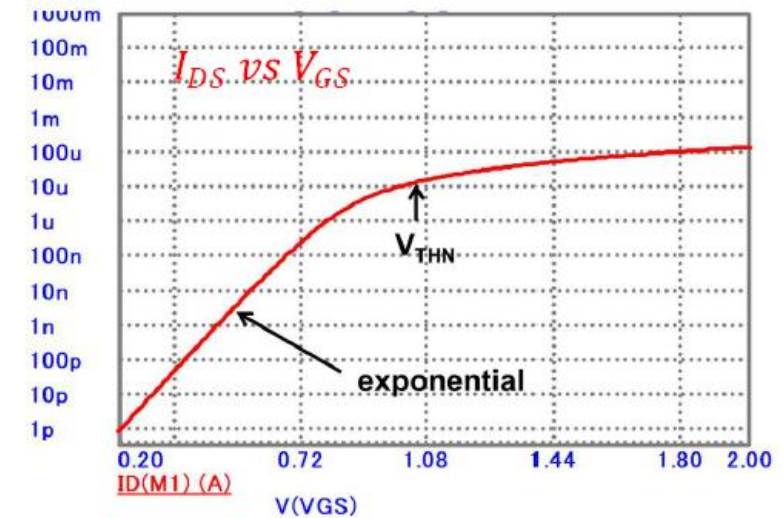
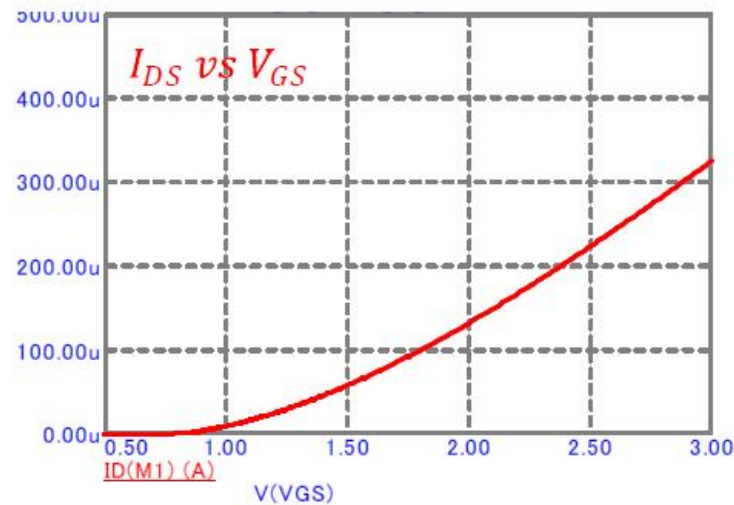
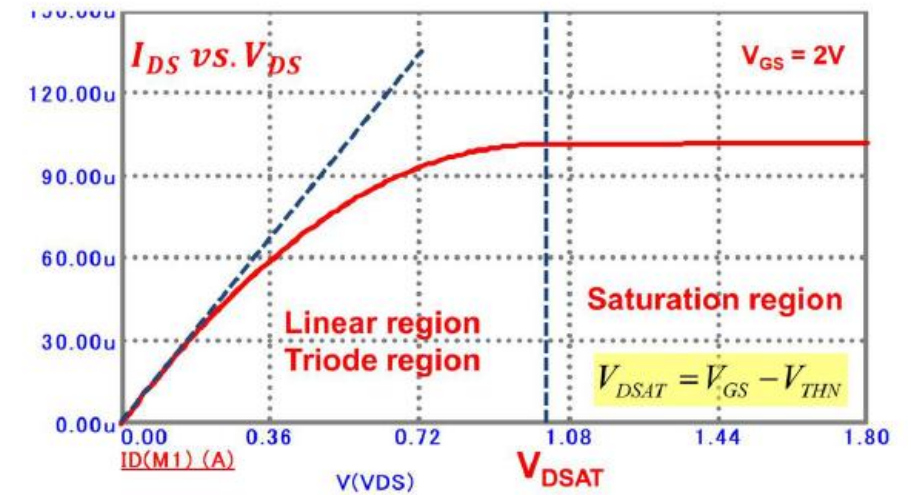
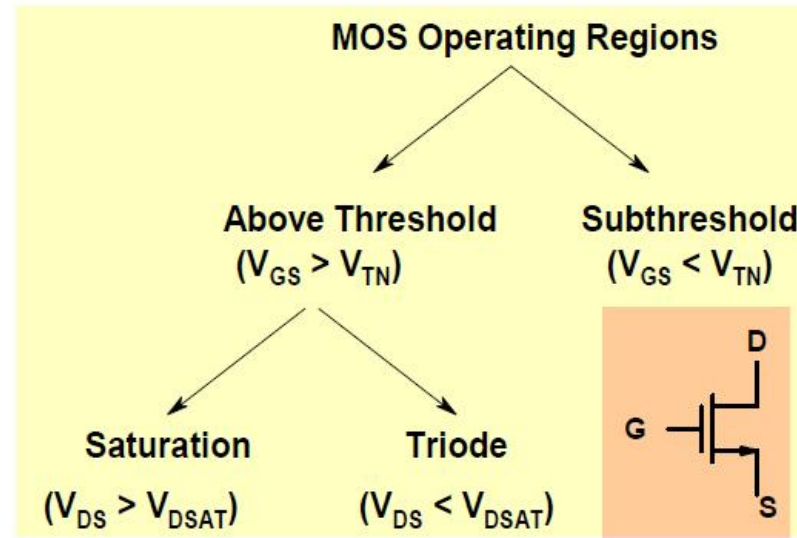
Voltage difference over the induced channel (from the **pinch-off** point to the source) remains fixed at $V_{GS} - V_T$

□ However, the effective length of the conductive channel is modulated by the applied V_{DS} , so

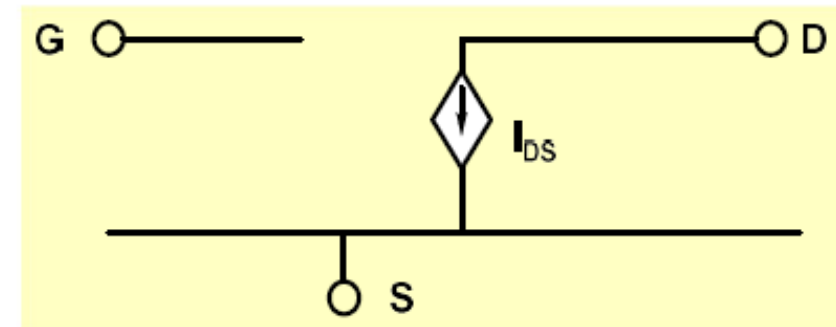
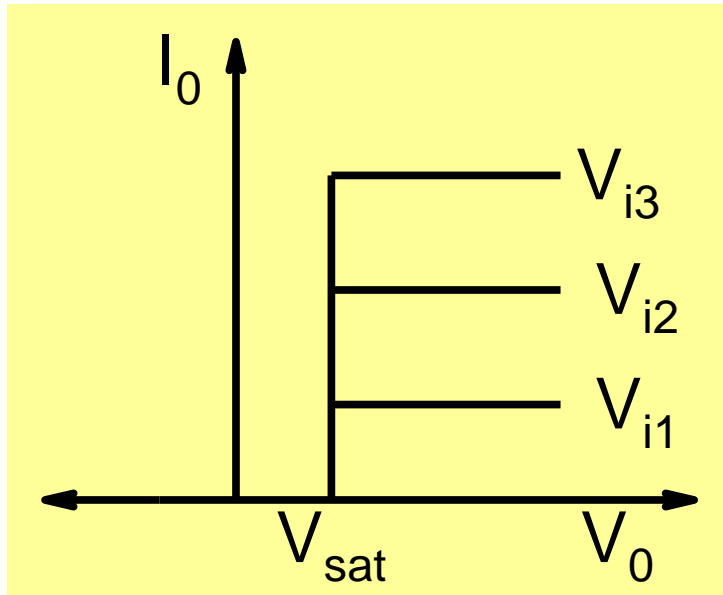
$$I_D = I_D' (1 + \lambda V_{DS})$$

where λ is the **channel-length modulation** (varies with the inverse of the channel length)

Factors Determining Current

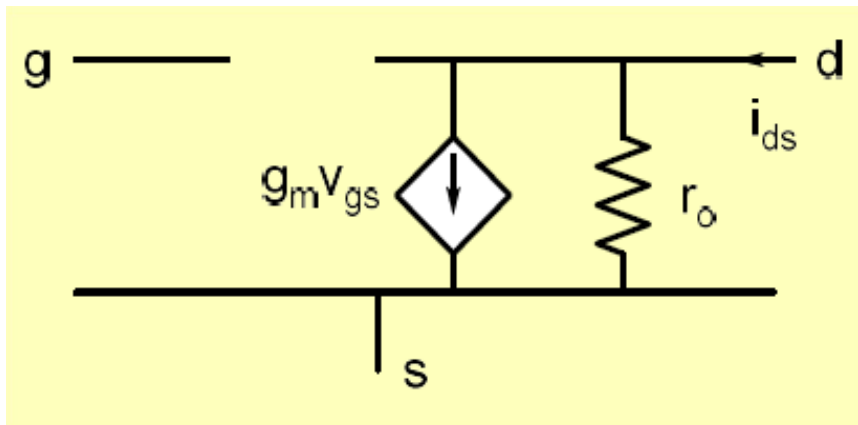


DC and AC model of a MOSFET



$$I_{DS} = \frac{\beta_N}{2} (V_{GS} - V_{THN})^2 ; \beta_N = KP_N \times \frac{W}{L}$$

KP_N : Transconductance parameter $\frac{\mu A}{V^2}$



$$g_m = \frac{2I_{DSQ}}{V_{GSQ} - V_{THN}} = \sqrt{2I_{DSQ}\beta}$$

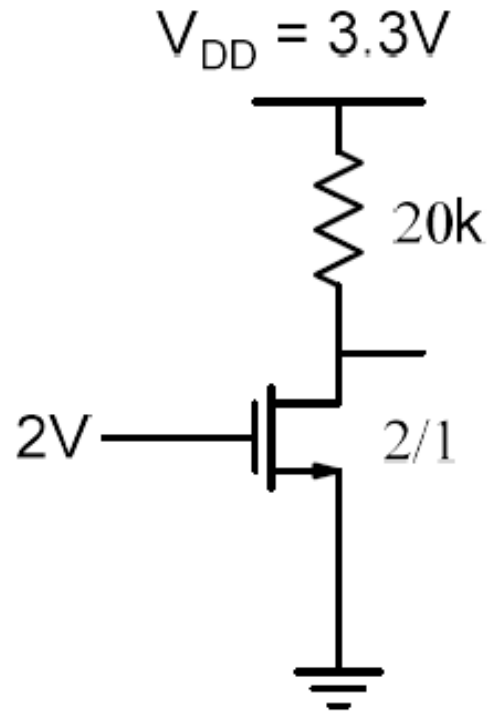
$$r_o = \frac{1}{\lambda_n I_{DSQ}}$$

λ_N is the channel length modulation parameter

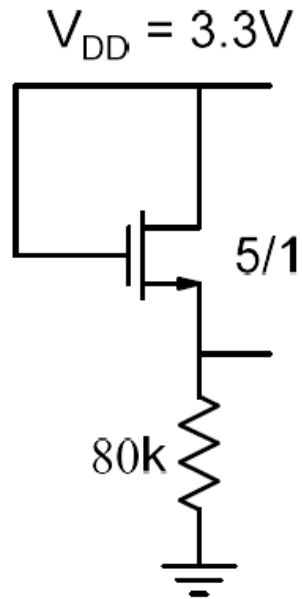
Example 1

$$KP_N = 100\mu A/V^2; V_{THN} = 1V; \lambda_n = 0.01V^{-1}$$

Determine I_{DS} and V_{DS}



Example 2



$$KP_N = 100 \mu A/V^2; V_{THN} = 1V; \lambda_n = 0.01 V^{-1}$$

Determine I_{DS} and V_{DS}

$$V_{DS} = V_{GS} \\ \Rightarrow V_{DS} > V_{GS} - V_{THN} = V_{DSAT} \Rightarrow \text{Saturation}$$

$$I_{DS} = KP_N \times \frac{W}{L} \times \frac{(V_{GS} - V_{THN})^2}{2}; V_{GS} = 3.3 - I_{DS} \times 80 \times 10^3 \\ \Rightarrow I_{DS} = 2.48 \times 10^{-5} A; V_{GS} = 1.315V$$

For the other solution $V_{GS} = 0.653V$ which is not possible since it is less than V_{THN}