

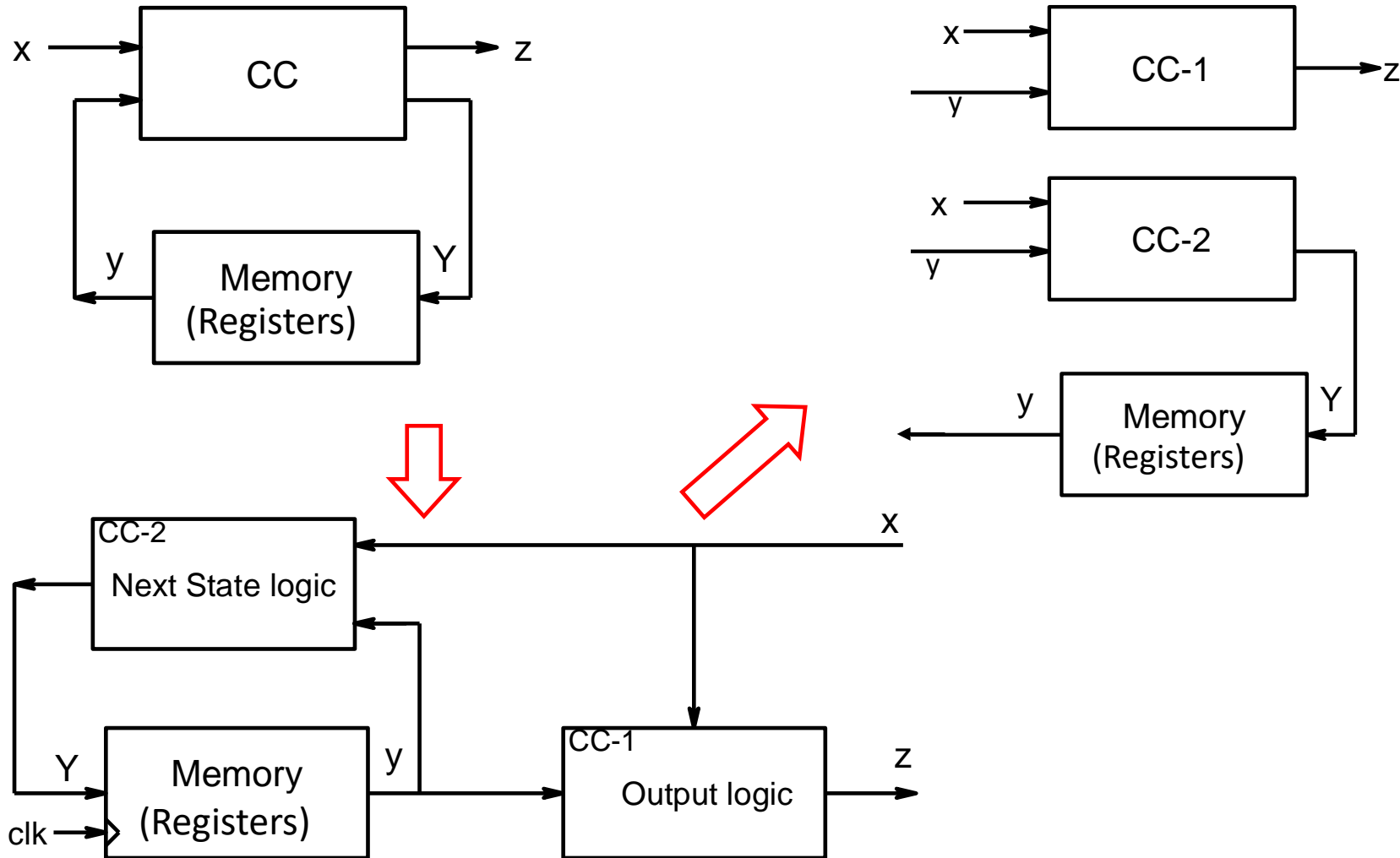
# ESC201: INTRODUCTION TO ELECTRONICS

## MODULE 6: DIGITAL CIRCUITS



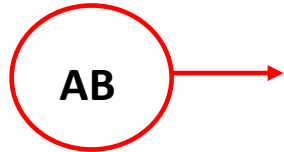
**Dr. Shubham Sahay,**  
**Associate Professor,**  
**Department of Electrical Engineering,**  
**IIT Kanpur**

# Visualising the Sequential Circuit

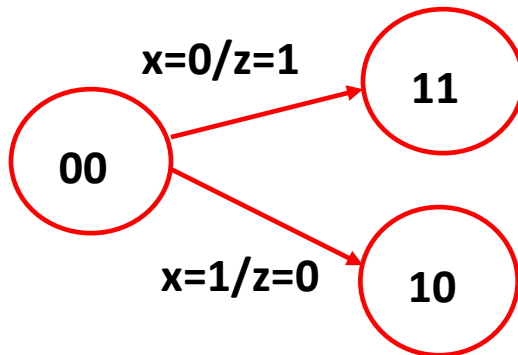


# State Transition Diagrams

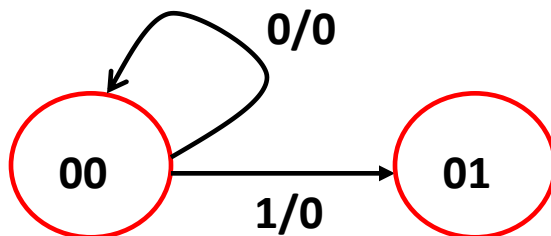
For Analysis, we want to visualise the sequential circuit as “State Transition Diagrams”.



**Memory state** decided by contents of registers A& B



**Initial state** is 00. **Next state** can be 11 or 10 depending x.  
Value of z is defined by current state and input x.



If  $x = 0$  then  $z = 0$

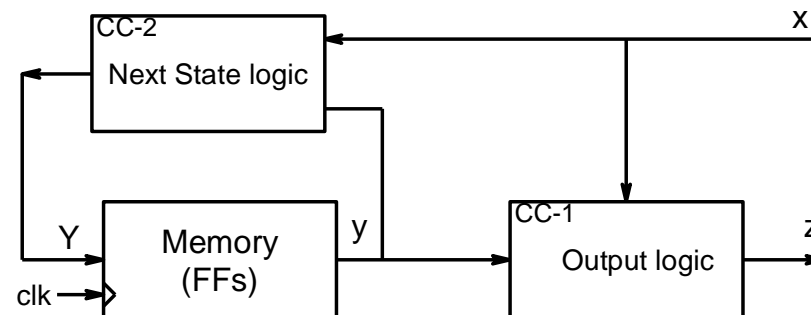
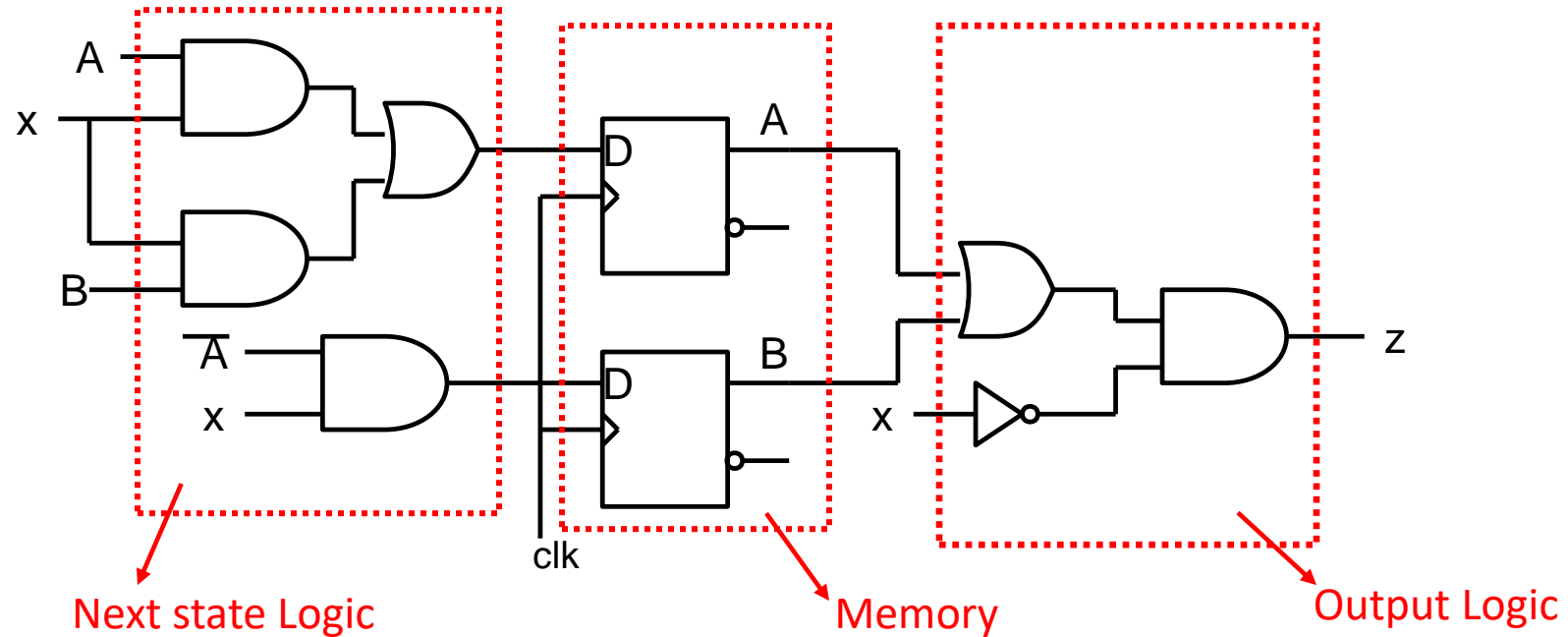
the system would stay in 00 state at clock edge.

If  $x = 1$  then  $z = 0$ .

the system would go to 01 state at clock edge.

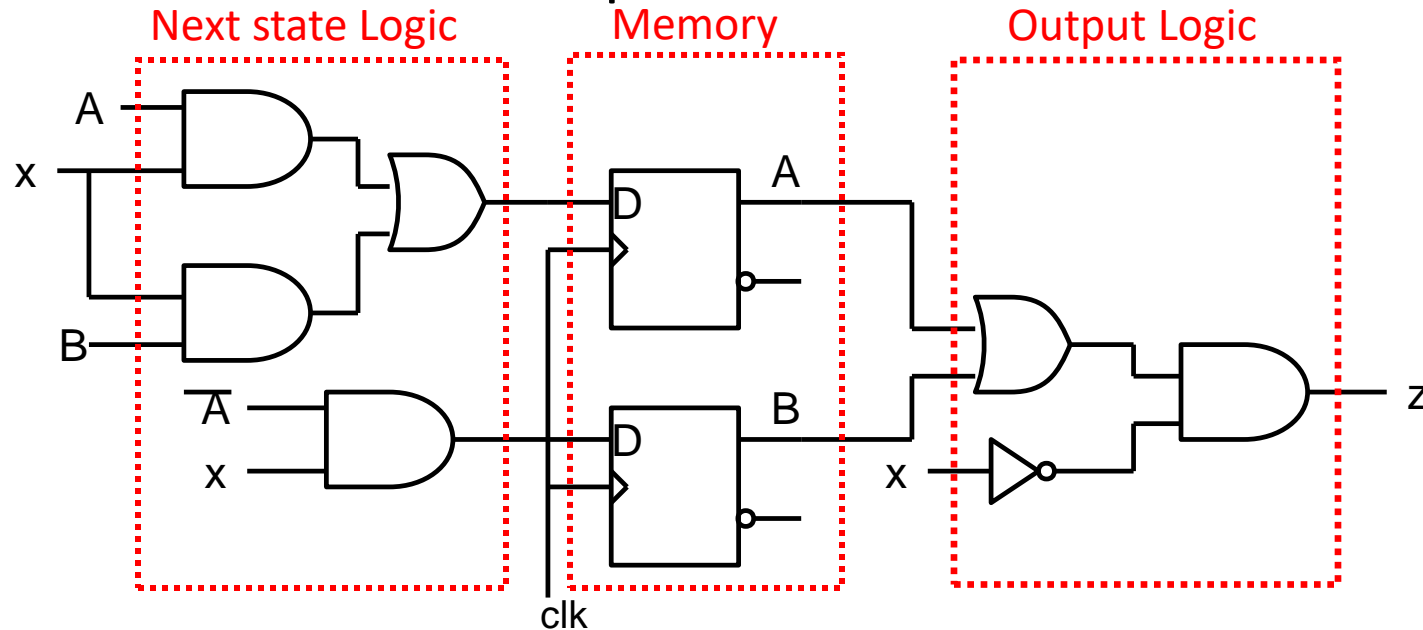
## Example

# Sequential Circuit “Canonical Form”



## Example - continued

# What To Look for In Sequential Circuits



The dependence of output z on input x depends on the state of the memory (A,B)

The memory has 2 registers and each register can be in state 0 or 1.

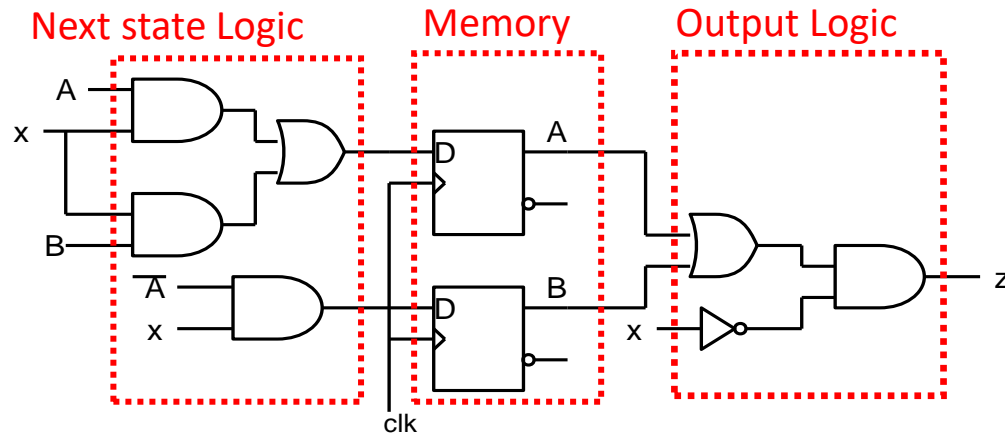
- Thus there are four possible states: AB: 00,01,10,11.

To describe the behavior of a sequential circuit, we need to show

1. how the system goes from one memory state to the next as the input changes
2. how the output responds to input in each state

## Example - continued

# Obtaining State Transition Table



$$D_A = A.x + B.x \quad ; \quad D_B = \overline{A}.x; z = (A + B).\overline{x}$$

$$A(t+1) = A(t).x + B(t).x$$

$$B(t+1) = \overline{A(t)}.x$$

$$z = (A + B).\overline{x}$$

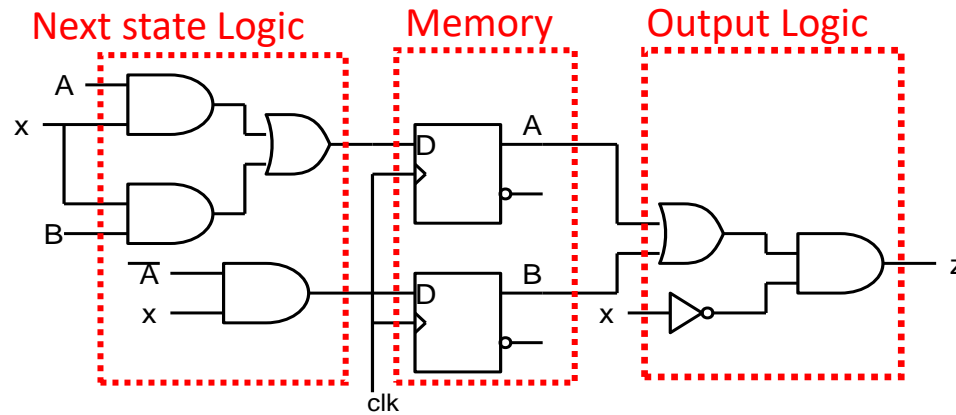


State Transition Table

Present State		Input x	Next State		Output z
A	B		A	B	
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	0	0	1
0	1	1	1	1	0
1	0	0	0	0	1
1	0	1	1	0	0
1	1	0	0	0	1
1	1	1	1	0	0

## Example - continued

# Obtaining State Transition Diagram



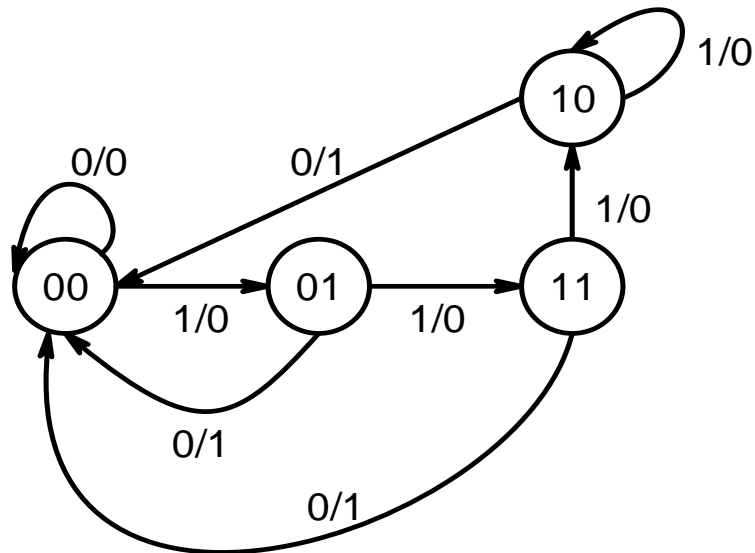
$$A(t+1) = A(t).x + B(t).x$$

$$B(t+1) = \overline{A(t)}.x$$

$$z = (A + B). \overline{x}$$

State Transition Table

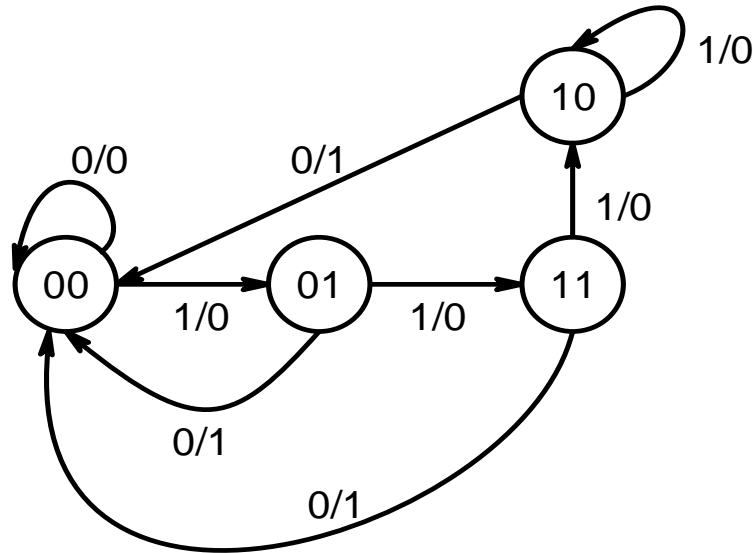
Present State		Input	Next State		Output
$A(t)$	$B(t)$	$x$	$A(t+1)$	$B(t+1)$	$z$
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	0	0	1
0	1	1	1	1	0
1	0	0	0	0	1
1	0	1	1	0	0
1	1	0	0	0	1
1	1	1	1	0	0



State Transition Diagram

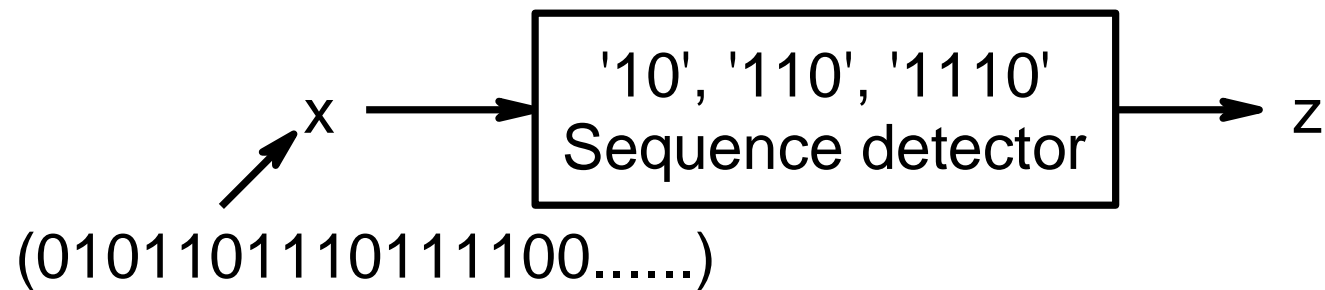
## Example - continued

# Understanding the Given Sequential Circuit



**State Transition Diagram**

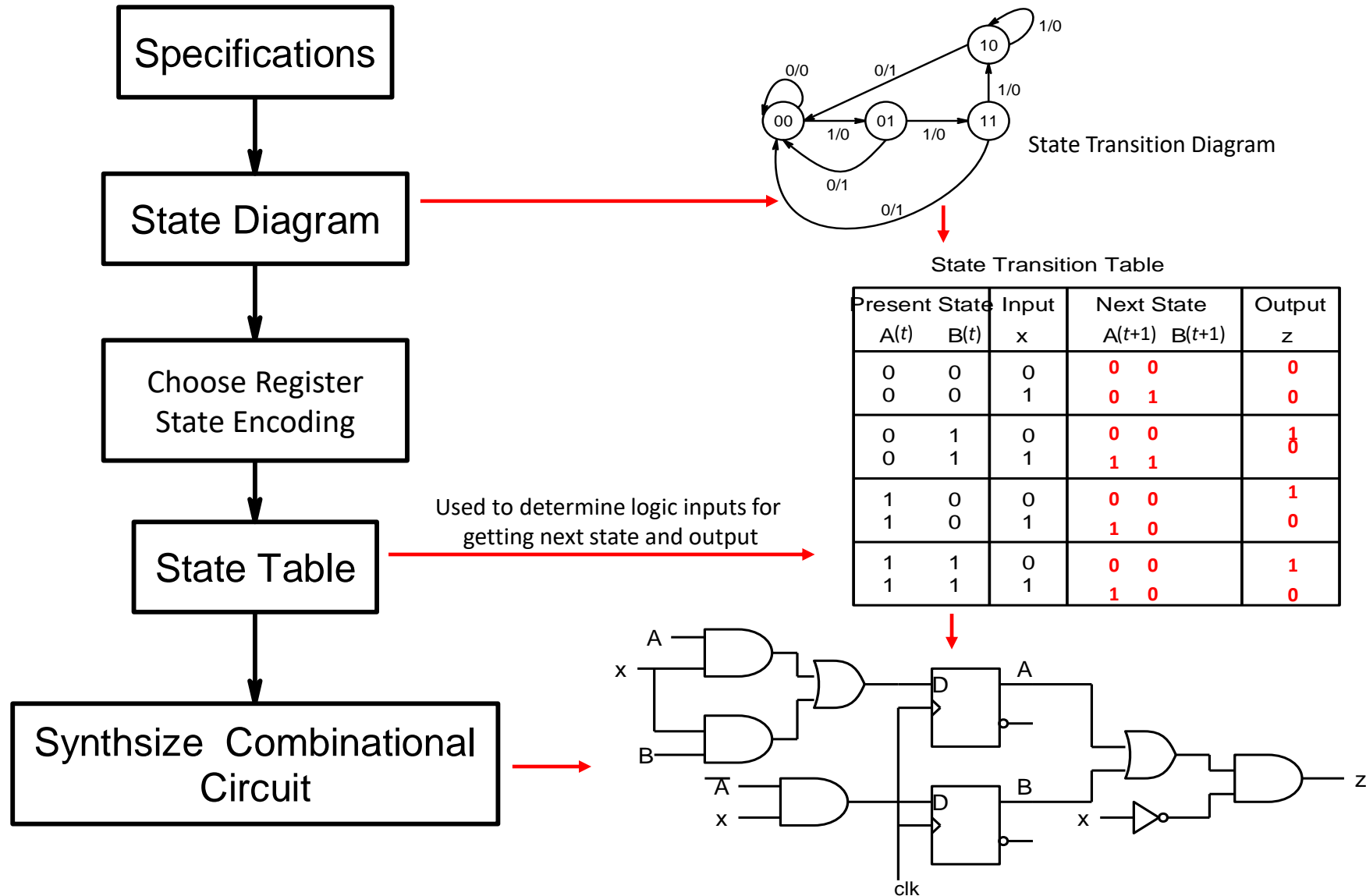
From state transition diagram, one figures out the purpose of the sequential circuit





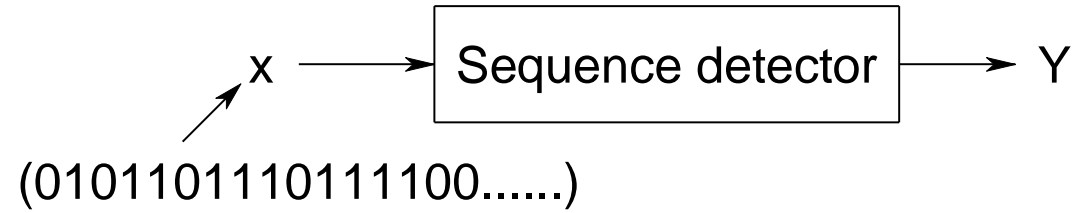
- Redraw circuit in “canonical form”
- Identify the blocks
- Determine logic for next state inputs and output
- Write out state transition table
- Draw state transition diagram

# Designing of Sequential Circuits

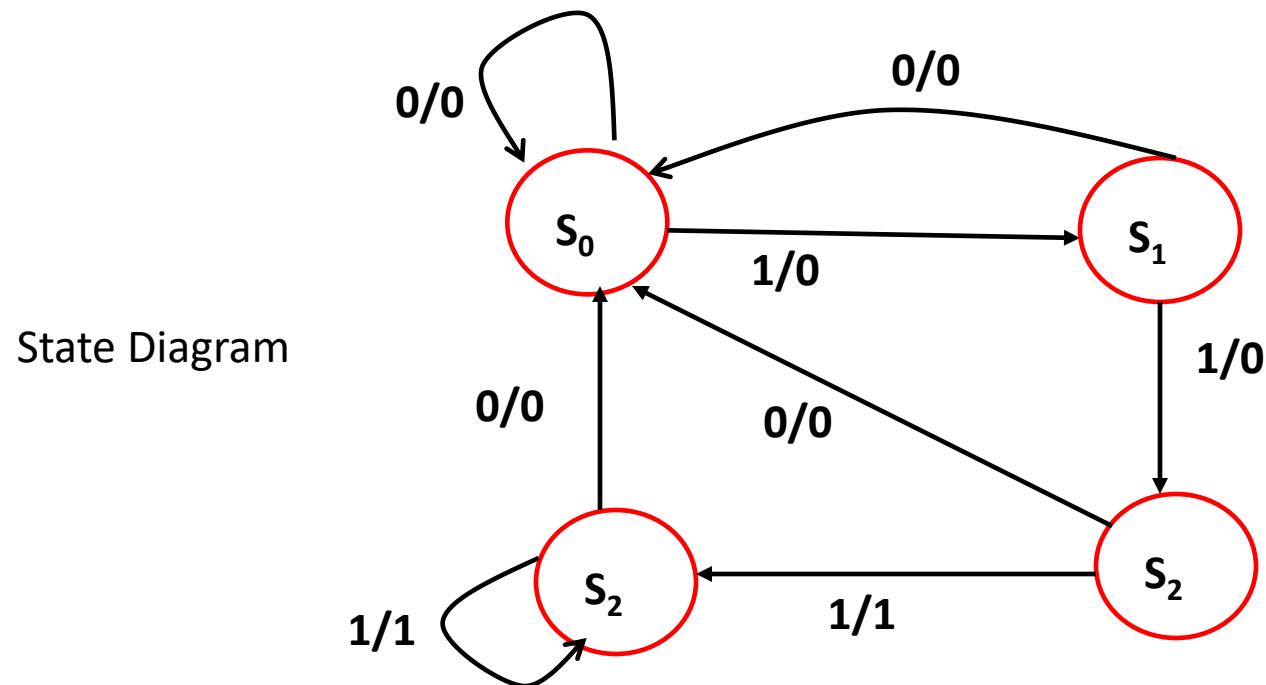


# System specification to State diagram

## Example-0

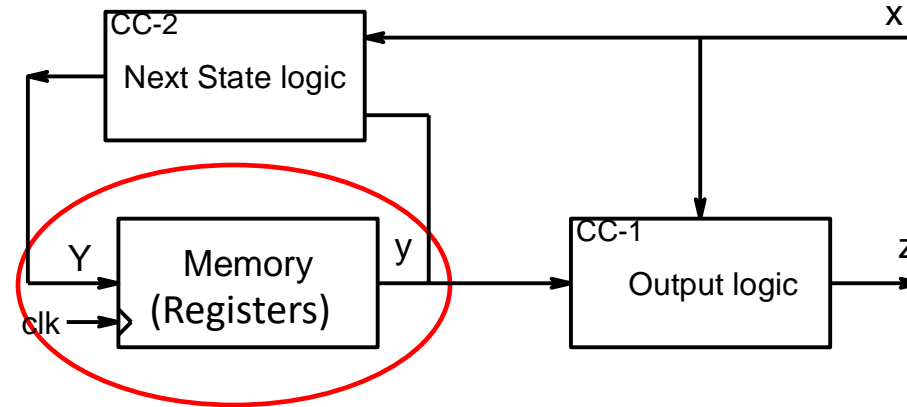
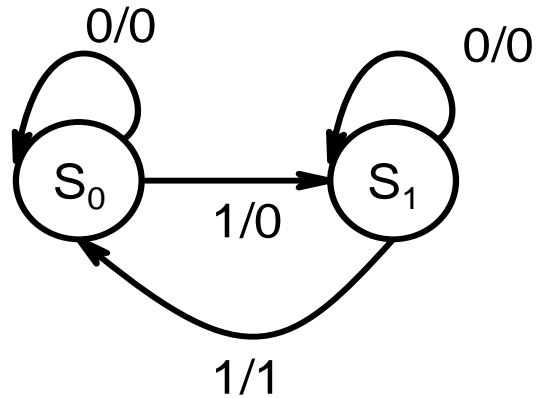


Detect 3 or more consecutive 1's in the input stream



## Example-1

### Conversion of State transition graph to a circuit



3 blocks need to be designed

1. How many registers do we need?

**N registers can represent  $2^N$  states  
→ so minimum is 1**

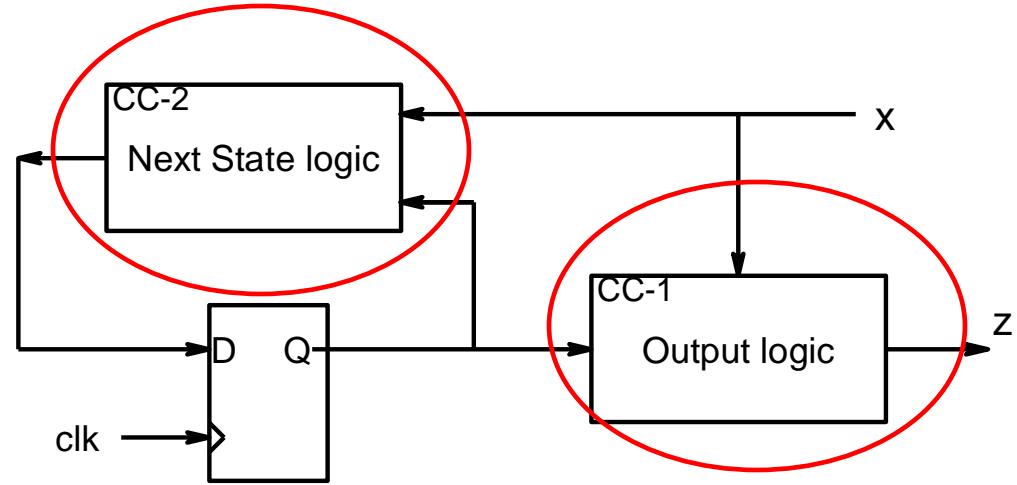
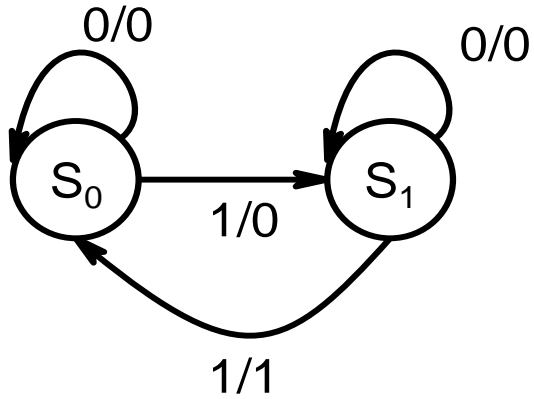
2. Which register do we choose?

**Say D register**

3. How are the states encoded?

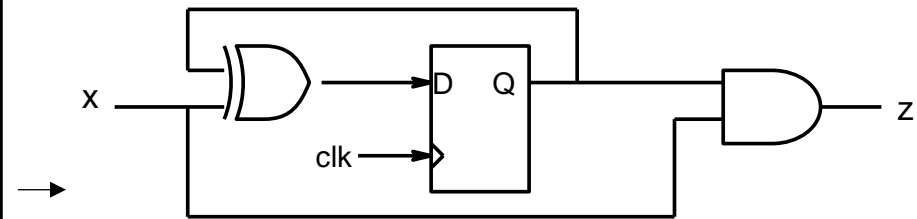
**Say register output  $Q=0$  represents  $S_0$  and  $Q=1$  represents  $S_1$  state**

### Example-1 continued



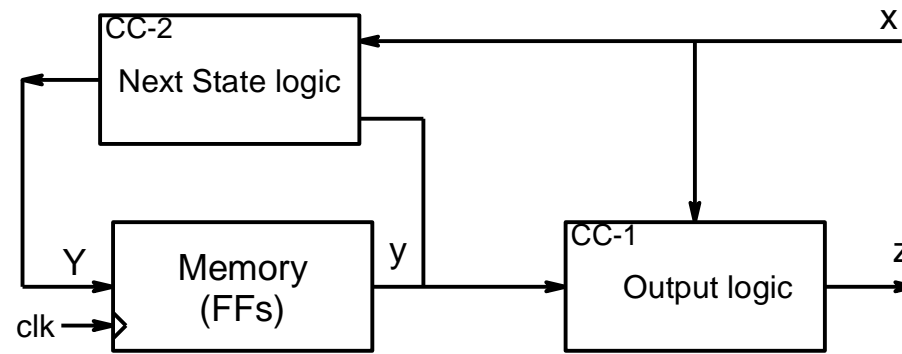
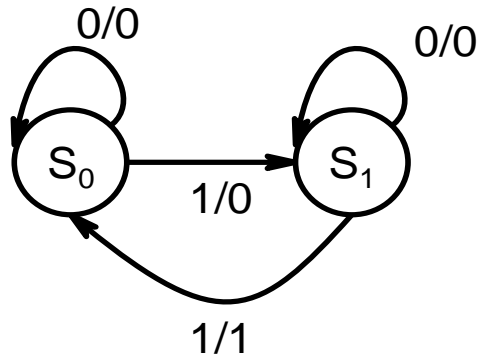
State Transition Table

Present State Q(t)	Input x	Next State Q(t+1)	D	Output z
0	0	0	0	0
0	1	1	1	0
1	0	1	1	0
1	1	0	0	1



$$D = \bar{Q}.x + Q.\bar{x} \quad ; \quad z = Q.x$$

## Example-2



1. How many registers do we need?

**1**

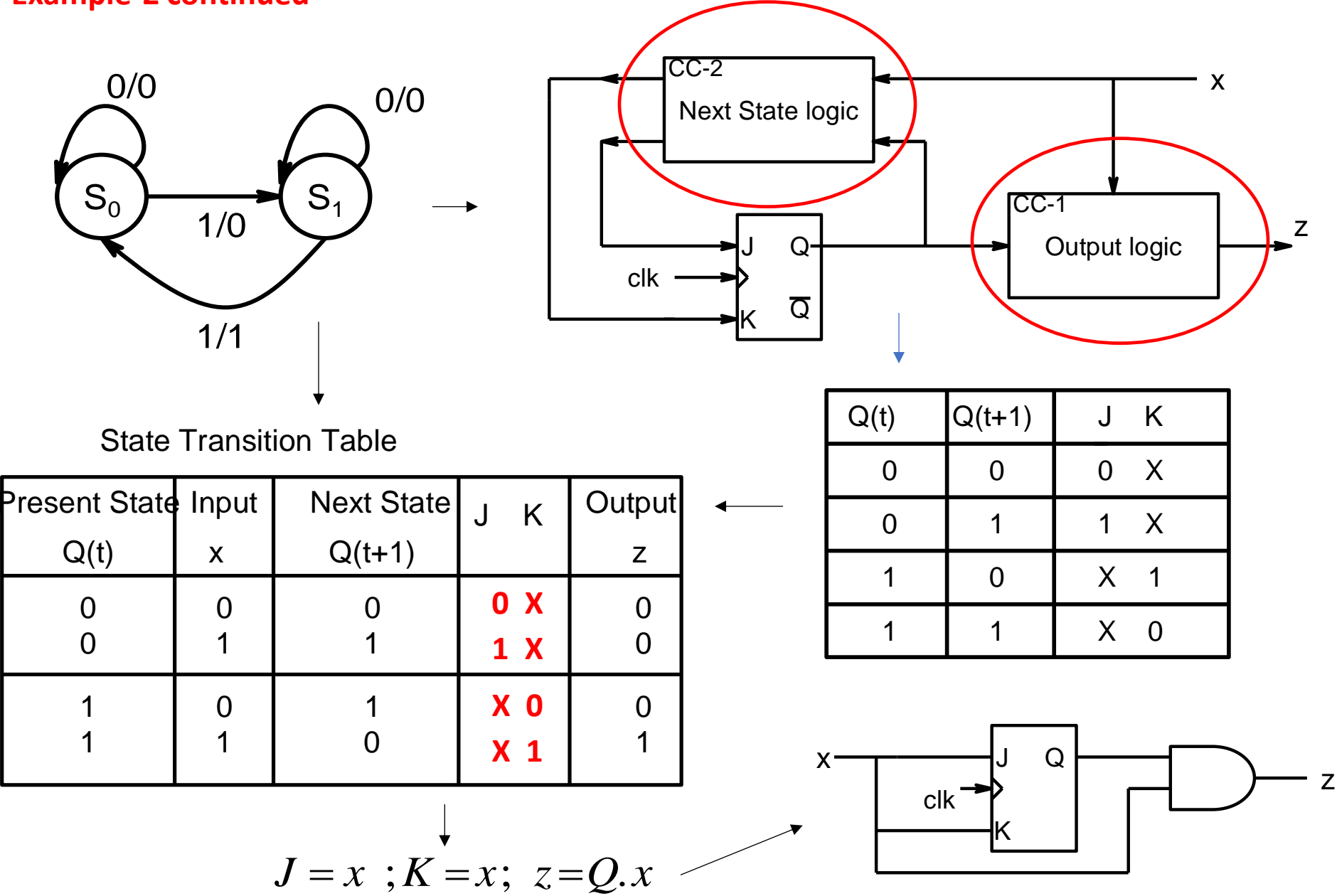
2. Which register do we choose?

**Say JK register**

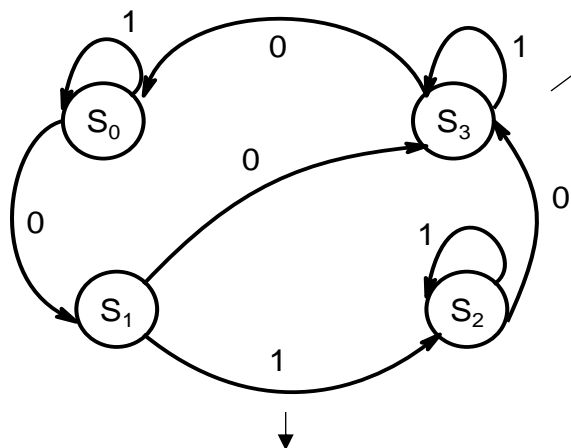
3. How are the states encoded?

**Say register output  $Q=0$  represents  $S_0$  and  $Q=1$  represents  $S_1$  state**

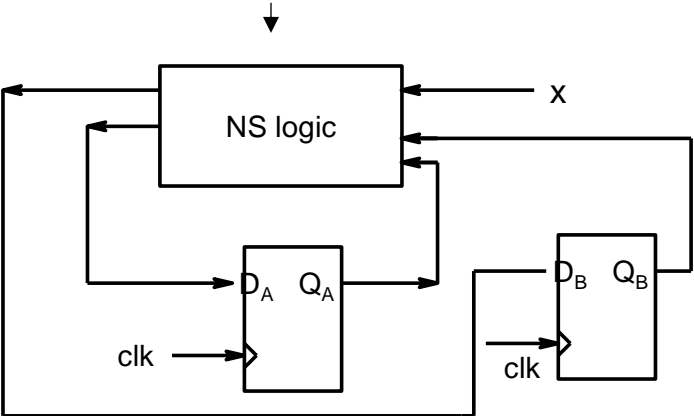
Example-2 continued



# Example-3



For 4 states a minimum of two registers will be required. Let us choose 2 D FFs A & B



Present State		Input	Next State			
$A(t)$	$B(t)$	$x$	$A(t+1)$	$B(t+1)$	$D_A$	$D_B$
0	0	0	0	1	0	1
0	0	1	0	0	0	0
0	1	0	1	1	1	1
0	1	1	1	0	1	0
1	0	0	1	1	1	1
1	0	1	1	0	1	0
1	1	0	0	0	0	0
1	1	1	1	1	1	1

State	FF O/P	
	A	B
$S_0$	0	0
$S_1$	0	1
$S_2$	1	0
$S_3$	1	1



### Example-3 continued

Present State		Input	Next State			
A(t)	B(t)	x	A(t+1)	B(t+1)	D <sub>A</sub>	D <sub>B</sub>
0	0	0	0	1	0	1
0	0	1	0	0	0	0
0	1	0	1	1	1	1
0	1	1	1	0	1	0
1	0	0	1	1	1	1
1	0	1	1	0	1	0
1	1	0	0	0	0	0
1	1	1	1	1	1	1

D<sub>A</sub>

x \ AB				
	00	01	11	10
0	0	1	0	1
1	0	1	1	1

$$D_A = \bar{A}B + xB + A\bar{B}$$

$$= A \oplus B + x.B$$

D<sub>B</sub>

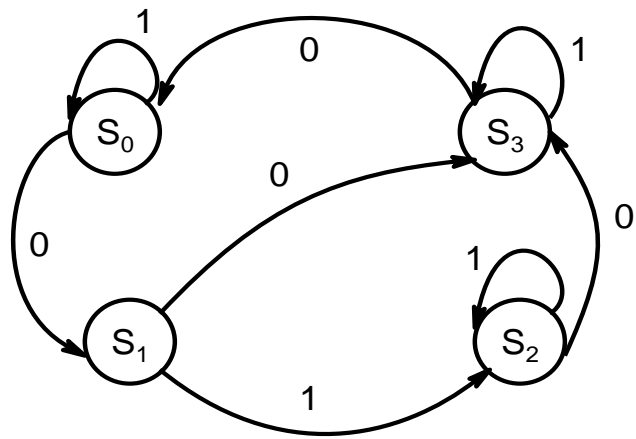
x \ AB				
	00	01	11	10
0	1	1	0	1
1	0	0	1	0

$$D_B = \bar{x}.\bar{A} + \bar{x}.\bar{B} + x.A.B$$

$$= \bar{x}.(\bar{A} + \bar{B}) + x.A.B$$

$$= \bar{x}.\overline{AB} + x.AB = \overline{x \oplus AB}$$

### Example-3 continued



With help of next  
state tables & K-map

$$D_A = A \oplus B + x.B$$

$$D_B = \overline{x \oplus AB}$$

