

Assignment 2

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$$(a) |n_1\rangle = (1 \ 1 \ 1)^T \quad |n_2\rangle = (1 \ 1 \ 0)^T \quad |n_3\rangle = (1 \ 0 \ 1)^T$$

$$\text{Let } \sum_{i=1}^3 a_i |n_i\rangle = 0$$

$$\Rightarrow a_1 + a_2 + a_3 = 0 \quad \text{--- (1)}$$

$$a_1 + a_2 = 0 \quad \text{--- (2)}$$

$$a_1 + a_3 = 0 \quad \text{--- (3)}$$

$$\text{From (1) and (2) : } a_3 = 0$$

$$\text{From (1) and (3) : } a_2 = 0$$

$$\Rightarrow a_1 = 0$$

Since $(a_1, a_2, a_3) = (0, 0, 0)$ is the only solution,
the set of vectors is linearly independent

$$(b) |v_1\rangle = \frac{1}{\sqrt{3}} (1 \ 1 \ 1)^T$$

$$|v_2\rangle = (1 \ 1 \ 0)^T - \left[(1 \ 1 \ 1) \cdot (1 \ 1 \ 0)^T \right] \left(\frac{1}{\sqrt{3}} \right) (1 \ 1 \ 1)^T$$

$$= (1 \ 1 \ 0)^T - \frac{2}{\sqrt{3}} (1 \ 1 \ 1)^T$$

$$= \left(\left(1 - \frac{2}{\sqrt{3}} \right) \quad \left(1 - \frac{2}{\sqrt{3}} \right) \quad -\frac{2}{\sqrt{3}} \right)^T$$

$$= \frac{1}{\sqrt{6}} (1 \ 1 \ -2)^T$$

$$|v_3\rangle = \frac{1}{\sqrt{6}} (1 \ 1 \ -2)^T$$

$$|v_3\rangle = |n_3\rangle - \langle v_1 | n_3 \rangle |v_1\rangle - \langle v_2 | n_3 \rangle |v_2\rangle$$

$$= (1 \ 0 \ 1)^T - \frac{2}{\sqrt{3}} (1 \ 1 \ 1)^T + \frac{1}{\sqrt{6}} (1 \ 1 \ -2)^T$$

$$\Rightarrow |w_3\rangle = \frac{1}{\sqrt{6}} (3 - 3 - 0)^T$$

$$\Rightarrow |w_3\rangle = \frac{1}{\sqrt{2}} (1 - 1 - 0)^T$$

$$|w_3\rangle = \frac{1}{\sqrt{2}} (1 - 1 - 0)^T$$

$$(c) P_1 = |w_1\rangle \langle w_1| = \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

$$P_2 = |w_2\rangle \langle w_2| = \frac{1}{6} \begin{pmatrix} 1 & 1 & -2 \\ 1 & 1 & -2 \\ -2 & -2 & 4 \end{pmatrix}$$

$$P_3 = |w_3\rangle \langle w_3| = \frac{1}{2} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$4) \bar{\sigma}_n = (\sigma_x, \sigma_y, \sigma_z)$$

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$(a) \bar{\sigma} \times \bar{\sigma} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \sigma_x & \sigma_y & \sigma_z \\ \sigma_x & \sigma_y & \sigma_z \end{vmatrix}$$

$$= \left(\sigma_y \sigma_z - \sigma_z \sigma_y, [\sigma_z, \sigma_x], [\sigma_x, \sigma_y] \right)$$

$$= 2(i\sigma_x, i\sigma_y, i\sigma_z)$$

$$= 2i\bar{\sigma}$$

$$\text{as } [\sigma_i, \sigma_j] = i \epsilon_{ijk} \sigma_k$$

$$4(b) (\bar{\sigma} \cdot \bar{A})(\bar{\sigma} \cdot \bar{B}) = A \cdot B + i \bar{\sigma} \cdot (\bar{A} \times \bar{B})$$

$$\text{Let } \bar{A} = (A_x, A_y, A_z) \quad \bar{B} = (B_x, B_y, B_z)$$

$$\text{LHS} = (A_x \sigma_x + A_y \sigma_y + A_z \sigma_z)(B_x \sigma_x + B_y \sigma_y + B_z \sigma_z)$$

$$\neq / A_x B_x \text{ now } \sigma_i \sigma_j = i \sigma_k \epsilon_{ijk} + I \delta_{ij}$$

$$\Rightarrow \text{LHS} = A_x B_x I + A_x B_y i \sigma_z - A_x B_z i \sigma_y \\ + - B_x A_y i \sigma_z + A_y B_y I + A_y B_z i \sigma_z \\ + A_z B_x i \sigma_y - A_z B_y i \sigma_x + A_z B_z I$$

$$= I (A_x B_x + A_y B_y + A_z B_z) + \\ i \sigma_x (A_y B_z - A_z B_y) + i \sigma_y (A_z B_x - A_x B_z) + \\ i \sigma_z (A_x B_y - A_y B_x)$$

$$= \bar{A} \cdot \bar{B} I + i \bar{\sigma} \cdot (\bar{A} \times \bar{B}) \quad \text{RHS} \quad \therefore \text{QED}$$

$$5(c) \text{ To prove: } e^{\pm i \bar{\sigma} \cdot \bar{v}} = \cos v \pm i (\bar{\sigma} \cdot \hat{v}) \sin v$$

$$\hat{v} = \bar{v} / |v|, \quad v = |v|$$

$$\exp(\pm i \bar{\sigma} \cdot \bar{v}) = 1 \pm \frac{i \bar{\sigma} \cdot \bar{v}}{1!} + \frac{(i \bar{\sigma} \cdot \bar{v})^2}{2!} \pm \frac{(i \bar{\sigma} \cdot \bar{v})^3}{3!} + \dots$$

$$\bar{\sigma} \cdot \bar{v} = \sigma_x v_x + \sigma_y v_y + \sigma_z v_z$$

$$(\bar{\sigma} \cdot \bar{v})^2 = (v_x^2 + v_y^2 + v_z^2) I$$

$$(\bar{\sigma} \cdot \bar{v})^3 = (v_x^2 + v_y^2 + v_z^2)^{1/2} (\sigma_x v_x + \sigma_y v_y + \sigma_z v_z)$$

$$(\bar{\sigma} \cdot \bar{v})^4 = (v_x^2 + v_y^2 + v_z^2)^2 \quad \text{and so on}$$

$$\textcircled{1} - \cos v = 1 + \frac{(i v)^2}{2!} + \frac{(i v)^4}{4!} + \dots = 1 + \frac{(i \bar{\sigma} \cdot \bar{v})^2}{2!} + \frac{(i \bar{\sigma} \cdot \bar{v})^4}{4!} + \dots$$

$$\begin{aligned} \sin v &= \frac{v^1}{1!} + \frac{v^3}{3!} + \frac{v^5}{5!} + \dots \\ &+ \left(\frac{(i\bar{\sigma}_0 v)}{1!} + \frac{(i\bar{\sigma}_0 v)^3}{3!} + \frac{(i\bar{\sigma}_0 v)^5}{5!} + \dots \right) \\ &= \pm(i\bar{\sigma}_0 v) \left(\frac{v}{1!} + \frac{v^2 v}{3!} + \frac{v^4 v}{5!} + \dots \right) \\ &\sim \pm(i\bar{\sigma}_0 v) \sin v \quad - \textcircled{2} \end{aligned}$$

combining \textcircled{1} and \textcircled{2}:

$$\exp(\pm i\bar{\sigma}_0 v) = \cos v \pm i(\bar{\sigma}_0 v) \sin v \quad \text{- QED}$$

$$(8) \quad \ln \sigma_j = \frac{i\pi}{2} [\mathbb{I} - \sigma_j]$$

exponentiating both sides

$$\sigma_j = \exp\left(\frac{i\pi}{2} [\mathbb{I} - \sigma_j]\right)$$

solving the RHS

$$\exp(i\theta M) = \mathbb{I}(\cos \theta) + (i \sin \theta) M$$

for any matrix that satisfies $M^2 = \mathbb{I}$

$$\text{Work: } \mathbb{I}, (i\mathbb{I} + \sigma_j)^2 / \mathbb{I}^2 - 2\sigma_j + \sigma_j^2$$

$$\text{RHS} = \exp\left(\frac{i\pi}{2} \mathbb{I}\right) \exp\left(\frac{-i\pi}{2} \sigma_j\right)$$

$$= \left(\mathbb{I} \cos \frac{\pi}{2} + i \mathbb{I} \sin \frac{\pi}{2} \right) \left(\mathbb{I} \cos \frac{\pi}{2} + i \sigma_j \sin \frac{\pi}{2} \right)$$

$$= (i^2 \mathbb{I})(-1) \sigma_j = \boxed{\sigma_j} = \text{LHS}$$

QED

$$(a) H = \frac{-\hbar^2}{2m} \frac{d^2}{dy^2} + \frac{1}{2} m \omega^2 y^2$$

$$x = y/a \quad a = \sqrt{\hbar/(m\omega)}$$

$$H = \frac{\hbar\omega}{2} \left[-\frac{d^2}{dx^2} + x^2 \right]$$

$$a = \frac{1}{\sqrt{2}} \left[x + \frac{d}{dx} \right], \quad a^\dagger = \frac{1}{\sqrt{2}} \left[x \frac{d}{dx} \right]$$

where $\left(\frac{d}{dx} \right)^+ = -\frac{d}{dx}$, $H = \hbar\omega(a^\dagger a + 1/2)$

$$\begin{aligned} (a) [a, a^\dagger] \psi &= \frac{1}{2} \left[x^2 \psi - x \frac{d\psi}{dx}, \frac{d}{dx} (x\psi) - \frac{d^2}{dx^2} (\psi) \right] - \\ &\quad \frac{1}{2} \left[x^2 \psi + x \frac{d\psi}{dx} - \frac{d}{dx} (x\psi) - \frac{d^2}{dx^2} \psi \right] \\ &= \frac{1}{2} \left[-x \frac{d\psi}{dx} + \cancel{x\psi} + x \frac{d\psi}{dx} - x \frac{d\psi}{dx} + \cancel{\psi} + x \frac{d\psi}{dx} \right] \\ &= \psi \quad \Rightarrow \quad \boxed{[a, a^\dagger] = 1} \end{aligned}$$

$$(b) e^a a^\dagger e^{-a} = a^\dagger + 1, \quad e^{a^\dagger} a e^{-a^\dagger} = a - 1$$

By Hadamard lemma:

$$e^A B e^{-A} = B + [A, B] + \frac{1}{2!} [A, [A, B]] + \frac{1}{3!} [A, [A, [A, B]]] + \dots$$

$$\Rightarrow e^a a^\dagger e^{-a} = a^\dagger + [a, a^\dagger] + \frac{1}{2!} [a, [a, a^\dagger]] + \dots$$

$$\Rightarrow a^\dagger + 1 + 0 + 0 \dots = \boxed{a^\dagger + 1}$$

now !
 $e^{a^+} a e^{-a^+} = \underline{\underline{a}} = 1$

$$= a + [a^+, a^+] + \frac{1}{2!} [a^+, [a^+, a]] \dots$$

$$= a - 1 + 0 + 0 \quad \text{QED}$$

(c) $U \equiv U(\lambda, \lambda^*) = e^{\lambda a^+ - \lambda^* a}$

To prove: $U^+ U = U U^+ = 1$

$$U = e^{\lambda a^+} e^{-\lambda^* a} \quad \text{let } X = \lambda a^+ - \lambda^* a$$

$$\text{now } X^+ = \lambda^* a - \lambda a^+ = -X$$

$$U^+ U = e^{X^+} e^X = e^{-X} e^X = 1 -$$

$$U U^+ = e^X e^{X^+} = e^X e^{-X} = 1$$

$$\Rightarrow U^+ U = U U^+ = 1$$

(d) To show: $e^{\lambda^* a - \lambda a^+} a e^{\lambda a^+ - \lambda^* a} = a + \lambda$

again, we use the Hadamard lemma:

$$e^A B e^{-A} = B + [A, B] + \frac{1}{2!} [A, [A, B]] + \dots$$

$$\text{set } X = \lambda^* a - \lambda a^+ \quad \text{now } \lambda a^+ - \lambda^* a = -X = X^+$$

$$\text{LHS} = a + [\lambda^* a - \lambda a^+, a] + \frac{1}{2!} [X, [X, a]] + \dots$$

$$= a + \lambda^* [a, a] - \lambda [a^+, a] + \dots$$

$$= a - \lambda (-1) + \dots$$

$$= a + \lambda + \frac{1}{2!} [X, \lambda] + \dots$$

$\rightarrow 0$

$$\Rightarrow e^{\lambda^* a - \lambda a^*} a e^{\lambda a^* - \lambda^* a} = a + \lambda$$

(1) > (1) (d-1) + 10 > (1) (d-1)

similarly :

$$e^{\lambda^* a - \lambda a^*} a^* e^{\lambda a^* - \lambda^* a} = a^* + (\lambda^* [a, a^*] - \lambda [a^*, a]) - 0 + 0 -$$

$$= \boxed{a^* + \lambda^*}$$

(1) > (1) (d-1) + 10 > (1) (d-1)

Obtaining second exp from first, take a conj. on both sides:

$$(e^{\lambda^* a - \lambda a^*} a e^{\lambda a^* - \lambda^* a})^+ = (a + \lambda)^+$$

$$\Rightarrow e^{\lambda^* a - \lambda a^*} a^* e^{\lambda a^* - \lambda^* a} = a^* + \lambda^*$$

$$(ii) M = \begin{pmatrix} a & b \\ 1-a & 1-b \end{pmatrix}, \quad \begin{array}{l} a \in [0, 1] \\ b \in [0, 1] \end{array}$$

$$(a) M = n_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + n_2 \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} + n_3 \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix} + n_0 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{array}{l} a = n_3 + n_0 \\ b = n_1 - i n_2 \\ 1-a = n_1 + i n_2 \\ 1-b = n_1 + i n_2 \end{array} \quad \begin{array}{l} a = 1 - n_1 - i n_2 \\ b = n_0 - n_3 \end{array}$$

$$\Rightarrow \boxed{\frac{1+b-a}{2} = n_1}, \quad \boxed{\frac{1-a-b}{2i} = n_2}$$

$$\boxed{\frac{1+a-b}{2} = n_0}, \quad \boxed{\frac{a-1+b}{2} = n_3}$$

$$(b) M = a|0\rangle\langle 0| + b|0\rangle\langle 1| + (1-a)|1\rangle\langle 0| + (1-b)|1\rangle\langle 1|$$

$$(c) \det M|v\rangle = \lambda|v\rangle \quad \text{where } |v\rangle = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

now, from (b):

~~$$M|v\rangle = a|0\rangle\langle 0|v\rangle + b|0\rangle\langle 1|Bv\rangle + (1-a)|1\rangle\langle 0|v\rangle + (1-b)|1\rangle\langle 1|v\rangle$$~~

~~$$\Rightarrow \begin{pmatrix} av_1 + bv_2 \\ (1-a)v_1 + (1-b)v_2 \end{pmatrix} = \lambda \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$~~

eigenvalue eq: $|M - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} a-\lambda & b \\ 1-a & 1-b-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (a-\lambda)(1-b-\lambda) - (b)(1-a) = 0$$

$$\Rightarrow a - ab - \lambda a - \lambda + b\lambda + \lambda^2 - b + ab = 0$$

$$\Rightarrow (a-b) + \lambda^2(1) + \lambda(b-a-1) = 0$$

$$\Rightarrow \lambda = \frac{(a+1-b) \pm \sqrt{a^2+b^2+1+2a-2b-2ab-4a+4b}}{2}$$

$$\Rightarrow \lambda = \frac{(a+1-b) \pm \sqrt{(b-a+1)^2}}{2}$$

$$\Rightarrow \lambda_{\pm} = 1, (a-b)$$

$$\begin{pmatrix} a & b \\ 1-a & 1-b \end{pmatrix} \begin{pmatrix} v_+^{(1)} \\ v_+^{(2)} \end{pmatrix} = \begin{pmatrix} (a-b) v_+^{(1)} \\ (a-b) v_+^{(2)} \end{pmatrix}$$

$$\Rightarrow av_+^{(1)} + bv_+^{(2)} = av_+^{(1)} - bv_+^{(2)}$$

$$\Rightarrow v_+^{(1)} = -v_+^{(2)}$$

$$\nexists / \lambda \in \mathbb{R} / \exists \text{ also, } (1-a)v_+^{(1)} + (1-b)v_+^{(2)} = \\ av_+^{(2)} - bv_+^{(2)}$$

$$\Rightarrow (v_+^{(1)} + v_+^{(2)}) - av_+^{(1)} - bv_+^{(2)} = av_+^{(2)} - bv_+^{(2)}$$

$$\Rightarrow av_+^{(2)} + bv_+^{(2)} - bv_+^{(2)} - av_+^{(2)} = 0$$

which is true

$$\Rightarrow |v_+\rangle = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

now for $\lambda = 1$

$$\begin{pmatrix} a & b \\ 1-a & 1-b \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\Rightarrow ax + by = x \quad \Rightarrow y = \frac{1-a}{b}x$$

$$\Rightarrow |v_-\rangle = \begin{pmatrix} b/(1-a) \\ 1 \end{pmatrix}$$

$$(d) \text{ let } x \begin{pmatrix} -1 \\ 1 \end{pmatrix} + y \begin{pmatrix} b/(1-a) \\ 1 \end{pmatrix} = 0 = M \quad (1)$$

$$\Rightarrow \frac{by}{1-a} - x = 0, \quad y + x = 0$$

$$\Rightarrow \frac{by}{1-a} + y = 0 \quad \Rightarrow y = -x$$

$$\Rightarrow \frac{(1-a+b)y}{1-a} = 0$$

$$\Rightarrow y = 0 \quad \Rightarrow x = 0 \quad \forall a, b$$

Since $(x, y) = (0, 0)$ is the only solution,
 $|v_+\rangle$ are linearly independent

$\langle v_+ | v_- \rangle = \frac{b}{a-1} + 1 \neq 0$, hence they are not orthogonal

$$|v'_+\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$|v''_-\rangle = \begin{pmatrix} b/(1-a) \\ 1 \end{pmatrix} - \left(\frac{b+a-1}{a-1} \right) \cdot \frac{1}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{2b}{2(1-a)} + \frac{b+a-1}{2(a-1)} \\ 1 + \frac{b+a-1}{2(1-a)} \end{pmatrix} = \frac{b-a+1}{2(1-a)} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow |v'_-\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

the orthogonal vectors are $\frac{1}{\sqrt{2}}(-1), \frac{1}{\sqrt{2}}(1)$

$$(f) M = U^* D U^+$$

$$\lambda_+ = (-1) \quad \lambda_- = (a-b)$$

$$D = \begin{pmatrix} \lambda_+ & 0 \\ 0 & \lambda_- \end{pmatrix}$$

$$U = (|v'_+\rangle \cdot |v'_-\rangle) = \boxed{\frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}}$$

For M to be normalizable, $M^* M = M M^*$

$$\Rightarrow \begin{pmatrix} a^2+b^2 & a-a^2+b-b^2 \\ a-a^2+b-b^2 & 2-a^2+b^2-2a-2b \end{pmatrix} = \begin{pmatrix} 2a^2+1-2a & 2ab+1-2a-2b \\ 2ab+1-2a-2b & 2b^2+1-2b \end{pmatrix}$$

$$\Rightarrow \boxed{a+b=1}$$

$$15) R_x(\phi) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\phi & \sin\phi \\ 0 & -\sin\phi & \cos\phi \end{pmatrix}$$

$$R_y(\phi) = \begin{pmatrix} \cos\phi & 0 & -\sin\phi \\ 0 & 1 & 0 \\ \sin\phi & 0 & \cos\phi \end{pmatrix}$$

$$R_z(\phi) = \begin{pmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(a) Rotation about x axis:

$$\begin{aligned} x' &= x \\ y' &= y \cos\phi + z \sin\phi \Rightarrow \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\phi & \sin\phi \\ 0 & -\sin\phi & \cos\phi \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \\ z' &= -y \sin\phi + z \cos\phi \end{aligned}$$

Rotation about y axis:

$$\begin{aligned} x' &= x \cos\phi - z \sin\phi \\ y' &= y \\ z' &= x \sin\phi + z \cos\phi \Rightarrow \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos\phi & 0 & -\sin\phi \\ 0 & 1 & 0 \\ \sin\phi & 0 & \cos\phi \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \end{aligned}$$

Rotation about z axis:

$$\begin{aligned} x' &= x \cos\phi + y \sin\phi \Rightarrow \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \\ y' &= -x \sin\phi + y \cos\phi \\ z' &= z \end{aligned}$$

(b) we use $\cos S\phi \rightarrow 1$, $\sin S\phi \rightarrow S\phi$

$$\begin{aligned} \text{now } R_x(S\phi) &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & S\phi \\ 0 & -S\phi & 1 \end{pmatrix} = I + iS\phi \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \\ &= I + iS\phi J_2 \end{aligned}$$

we get similar results for $R_y(S\phi)$ and $R_z(S\phi)$ as $\cos S\phi$ terms lie on the diagonal. Simplifying, we get:

$$J_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad J_y = \begin{pmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix} \quad J_z = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

(c) Let $S\phi = \phi/n$ as $n \rightarrow \infty$

now $R_k(\phi)$ is a result of application of 'n' $S\phi$

$$\Rightarrow R_k(\phi) = (R_k(S\phi))^n \text{ as } n \rightarrow \infty$$

$$\Rightarrow R_k(\phi) = \lim_{n \rightarrow \infty} [R_k(S\phi)]^n = \lim_{n \rightarrow \infty} \left[I + \frac{i\phi J_k}{n} \right]^n$$

This is the identity for the exponential

$$\Rightarrow R_k(\phi) = \exp(i\phi J_k)$$

$$(d) [J_x, J_y] = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = i J_z$$

similarly $[J_y, J_z] = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} = i J_x$

$$[J_z, J_x] = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix} = i J_y$$

now since $[A, B] = -[B, A]$ $\Rightarrow [J_k, J_l] = i \epsilon_{klm} J_m$

Homework 3

$$10. H = \frac{p^2(t)}{2m} + \frac{1}{2} m \omega^2 z^2(t)$$

$$z(t) = \sqrt{\frac{m\omega}{2\hbar}} z(t) + i \frac{p(t)}{\sqrt{2m\hbar\omega}}$$

$$\dot{z} = \frac{\partial H}{\partial p} = p/m$$

$$\dot{p} = -\frac{\partial H}{\partial z} = -m\omega^2 z$$

$$\text{now, } \ddot{z} = \frac{\partial z}{\partial t} = \sqrt{\frac{m\omega}{2\hbar}} \dot{z} + i \frac{\dot{p}}{\sqrt{2m\hbar\omega}}$$

$$\begin{aligned} \Rightarrow \ddot{z} &= \sqrt{\frac{\omega}{2\hbar m}} p + i \frac{m\omega^2 z}{\sqrt{2m\hbar\omega}} \\ &= \frac{\omega}{i\hbar} \frac{p(t)}{\sqrt{2m\hbar\omega}} + \frac{\omega(i)}{i^2} \frac{z(t)}{\sqrt{2\hbar}} \end{aligned}$$

$$\Rightarrow \ddot{z} = -i\omega z \quad \text{equation of motion}$$

solⁿ of form $z(t) = C \exp(-i\omega t)$

$$z(t) \Rightarrow z(t) = \left(\sqrt{\frac{m\omega}{2\hbar}} z(0) + i \frac{p(0)}{\sqrt{2m\hbar\omega}} \right) e^{-i\omega t}$$

solution to the equation

$$x(t) = \frac{1}{\sqrt{2m\hbar\omega}} (z(t) + z^*(t))$$

$$p(t) = \frac{1}{i\sqrt{2}} (z(t) - z^*(t))$$

$$\text{let } \sqrt{\frac{m\omega}{2\hbar}} z(0) + i \frac{p(0)}{\sqrt{2m\hbar\omega}} = C \Rightarrow z^* = C^* e^{i\omega t}$$

$$\Rightarrow x(t) = \frac{\hbar}{\sqrt{2m\omega}} (C e^{-i\omega t} + C^* e^{i\omega t})$$

$$p(t) = -i \sqrt{\frac{m\hbar\omega}{2}} (C e^{-i\omega t} - C^* e^{i\omega t})$$

we can write $C = A e^{i\phi} \Rightarrow C^* = A e^{-i\phi}$

substituting and solving, we obtain:

$$x(t) = \frac{\sqrt{\hbar}}{\sqrt{2m\omega}} (2A \cos(\omega t - \phi))$$

$$\boxed{\frac{2\hbar}{\sqrt{m\omega}} A \cos(\omega t - \phi)}$$

$$p(t) = -\sqrt{2m\hbar\omega} A \sin(\omega t - \phi)$$

Ans 2- $S_p = \sum_{n=0}^{\infty} p^n e^{in\theta}$ $\frac{1-p e^{-i\theta}}{1-2p \cos\theta + p^2}$, $|p| < 1$

plot $|S_p|^2$ vs θ for $p = 0.01, 0.5, 0.99$

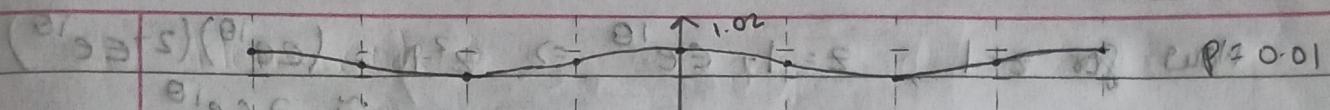
$$\text{let } N = 1 - p e^{i\theta} \Rightarrow |N|^2 = (1 - p e^{-i\theta})(1 - p e^{i\theta})$$

$$\Rightarrow |N|^2 = 1 + p^2 - p(e^{i\theta} + e^{-i\theta}) = 1 + p^2 - 2p \cos\theta$$

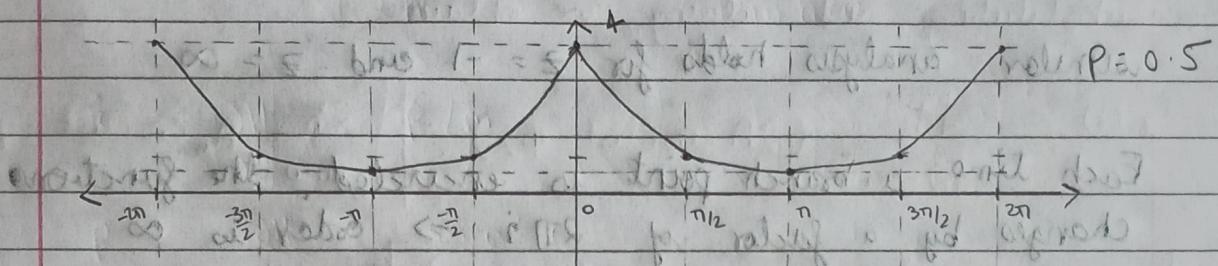
Tans. $\Rightarrow (a) |S_p|^2 = \frac{1}{1 + p^2 - 2p \cos\theta}$

$(S_p)^2$	$\frac{1}{(1-p)^2}$	$\frac{1}{1+p^2}$	$\frac{1}{(1+p^2)^2}$	$\frac{1}{1+p^2}$	$\frac{1}{(1-p)^2}$
θ	0	$\pi/12$	π	$3\pi/2$	2π

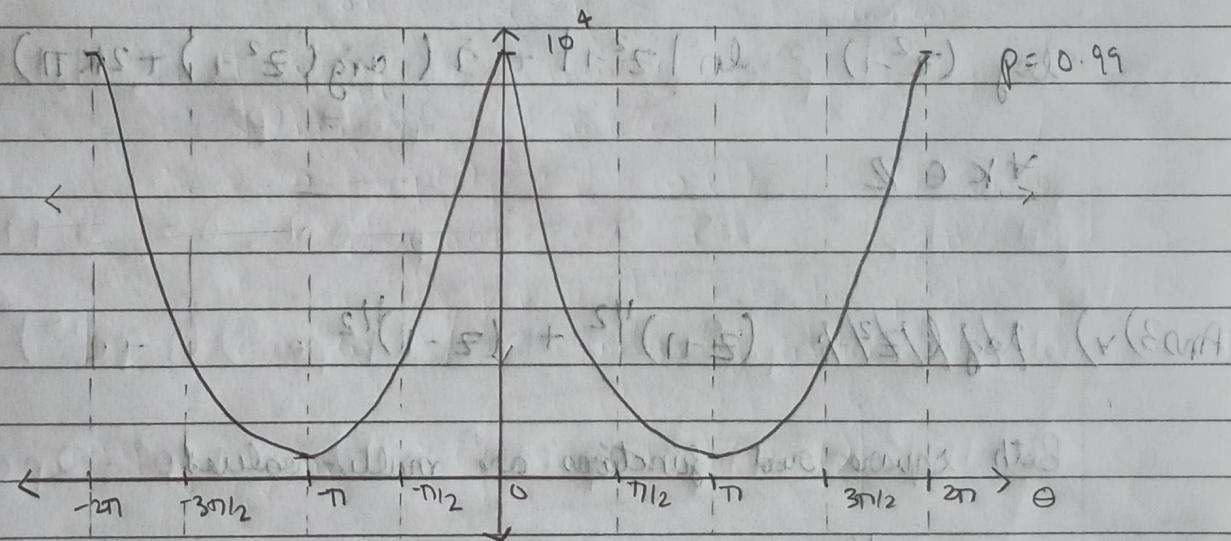
now plotting for various values of p :



above path for transition is not analytic at $\theta = \pi$
 i.e. function is not differentiable at $\theta = \pi$ since it has two different values
 which indicates the value of $s(\theta)$ is not unique
 along the path at $\theta = \pi$



do consider for minimum, singular points etc.



Ans 3) iv) $\log(z^2 - 1)$ this is a multi-valued function

Branch points exist where $(z^2 - 1) = 0$ or ∞

$\Rightarrow z = 1, -1, \infty$ all are branch points

To verify, Trace a small circle around each point.

Now for $z=1$, $z = 1 + ee^{i\theta} \Rightarrow z^2 - 1 = (ee^{i\theta})(2+ee^{i\theta}) \approx 2ee^{i\theta}$

\Rightarrow As θ goes from 0 to 2π , argument of log circles to origin and value of $\log(z^2 - 1)$ changes by $2\pi i$. Since $f(z)$ does not return to its starting point, $z=1$ is a branch point.

similar analysis holds for $z = -1$ and $z = \infty$

Each time a branch point is encircled, the function changes by a factor of $2\pi i \Rightarrow$ order is ∞

There exist infinite number of branches as:

$$\log(z^2 - 1) = \ln|z^2 - 1| + i(\arg(z^2 - 1) + 2k\pi)$$

$$k \in \mathbb{Z}$$

Ans 3) v) ~~\log~~ $\sqrt{z^2 - 1} (z+1)^{1/2} + (z-1)^{1/2}$

Both square root functions are multi-valued.

$\rightarrow (z+1)^{1/2}$ has branch points at $z = -1, \infty$

$\rightarrow (z-1)^{1/2}$ has branch points at $z = 1, \infty$

now trace a small closed loop around each point.

(a) For $z = 1$:

As we circle $z=1$, the value of $(z-1)^{1/2}$ changes sign. The function $(z+1)^{1/2}$ is analytic within this loop, so its value does not change. Hence the

value of the function changes from $(z+1)^{1/2} + (z-1)^{1/2}$
to $(z+1)^{1/2} - (z-1)^{1/2}$.

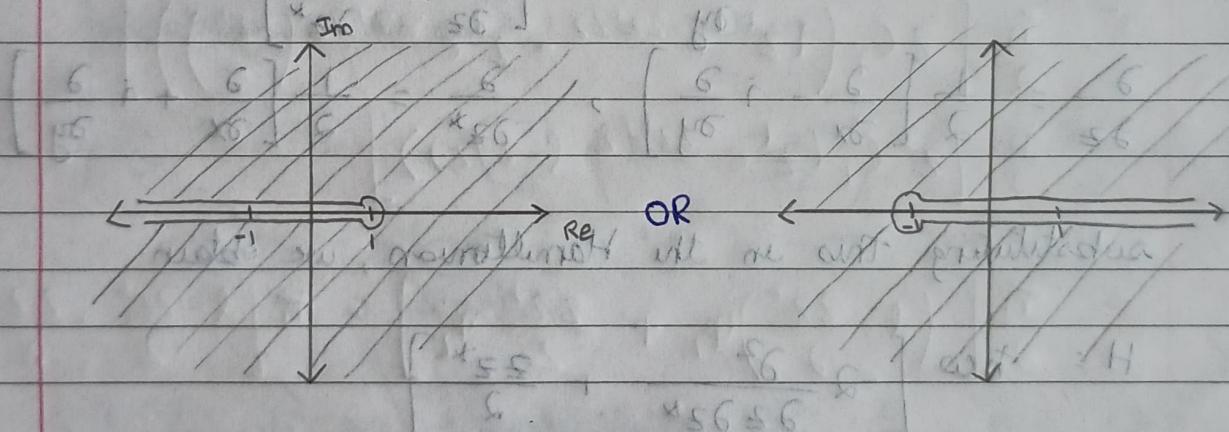
Hence $z=1$ is a branch point

By symmetric analysis, $z=-1$ is also a branch point

At $z=\infty$, both functions change signs hence the complete function changes sign-making $z=\infty$ one of the branch points.

$z = 1, -1, \infty$ are branch points, all of order 1.

For each square root function there are two possible distinct values, hence $2 \times 2 = 4$ branches are present in the function.



Branch cuts and single-valued domains for 3(iv) & 3(v)

$$\text{Ans 9- } H = -\frac{\hbar^2}{2M} \left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right] + \frac{1}{2} M \omega^2 (x^2 + y^2)$$

$$E_{n_r, m} = \hbar \omega (2n_r + |m| + 1) = \hbar \omega (n + 1)$$

$$\text{where } n = 2n_r + |m|, \quad n_r = 0, 1, 2, \dots$$

$$m = 0, \pm 1, \pm 2, \dots$$

(a) $a_0 = \sqrt{\frac{\hbar(\omega)}{M\omega}}$, $z = x + iy$ w.r.t. all the above
 oscillator length

we map this problem to z, z^* coordinates

~~tricky~~

let $\hat{x} = x/a_0$ $\hat{y} = y/a_0$

~~and want angle coords~~
 $\Rightarrow H = \hbar\omega \left[\frac{1}{2} \left(\frac{\partial^2}{\partial \hat{x}^2} + \frac{\partial^2}{\partial \hat{y}^2} \right) + \frac{1}{2} (\hat{x}^2 + \hat{y}^2) \right]$

now $\hat{x} \rightarrow x$, $\hat{y} \rightarrow y$

also $z = \hat{x} + i\hat{y} \rightarrow x + iy$

we know that: $\frac{\partial}{\partial x} = \frac{\partial}{\partial z} + \frac{\partial}{\partial z^*}$

~~also~~
 $\frac{\partial}{\partial y} = i \left[\frac{\partial}{\partial z} - \frac{\partial}{\partial z^*} \right]$

$$\frac{\partial}{\partial z} = \frac{1}{2} \left[\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right], \quad \frac{\partial}{\partial z^*} = \frac{1}{2} \left[\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right]$$

substituting this in the Hamiltonian, we obtain:

$$H = \hbar\omega \left[-2 \frac{\partial^2}{\partial z \partial z^*} + \frac{zz^*}{2} \right]$$

(b) For $n=0$, $|m|=1$, consider:

~~H $\psi(z, z^*) = E \psi(z, z^*)$~~

~~The solⁿ is: $\psi = z^2 \exp(-|z|^2/2)$~~

(b) To show: $H\Psi_l = E_l \Psi_l$ for $\Psi_l(z, z^*) = C_l z^l e^{-|z|^2/2}$

where $C_l = \frac{(-1)^l}{\sqrt{\pi a_0^2 l!}} \left(\frac{l+1}{2}\right)$

$$H\Psi_l = \hbar\omega \left[-2 \frac{\partial^2}{\partial z \partial z^*} + \frac{zz^*}{2} \right] (C_l z^l e^{-|z|^2/2})$$

$$\frac{\partial \Psi_l}{\partial z^*} = -\frac{C_l}{2} z^{l+1} e^{-|z|^2/2}$$

$$\frac{\partial}{\partial z} \left(\frac{\partial \Psi_l}{\partial z^*} \right) = -\frac{C_l}{2} \left[(l+1) - \frac{zz^*}{2} \right] z^l e^{-|z|^2/2}$$

$$= -\frac{1}{2} \left(l+1 - \frac{zz^*}{2} \right) \Psi_l$$

substituting this back, we obtain:

$$H\Psi_l = \hbar\omega \left[-2 \left(\frac{-1}{2} \left(l+1 - \frac{zz^*}{2} \right) \Psi_l \right) + \frac{zz^*}{2} \Psi_l \right]$$

$$= \hbar\omega \left[(l+1 - zz^*/2) + zz^*/2 \right] \Psi_l$$

$$= \hbar\omega (l+1) \Psi_l$$

$\Rightarrow \Psi_l$ is an eigenfunction with $E_l = \hbar\omega (l+1)$

Now we know that $H = H^*$ since the system is invariant under time-reversal operation

we have $H\Psi_l = E_l \Psi_l$

$$\Rightarrow H^* \Psi_l^* = E_l^* \Psi_l^*, \quad E_l = \hbar\omega(l+1) \in \mathbb{R}$$

$$\Rightarrow H \Psi_l^* = E_l \Psi_l^*$$

hence Ψ_l^* is also an eigenf" with same eigenvalue E_l

$$\begin{aligned}
 (c) L_z &= -i\hbar \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right) \\
 &= -i\hbar \left[\left(\frac{z+z^*}{2} \right) \left[i \left(\frac{\partial}{\partial z} - \frac{\partial}{\partial z^*} \right) \right] - \left(\frac{z-z^*}{2i} \right) \left(\frac{\partial}{\partial z} + \frac{\partial}{\partial z^*} \right) \right] \\
 &= \frac{-i\hbar}{2} \left[z i \frac{\partial}{\partial z} - z i \frac{\partial}{\partial z^*} + i z^* \frac{\partial}{\partial z} - i z^* \frac{\partial}{\partial z^*} \right. \\
 &\quad \left. - \frac{z}{i} \frac{\partial}{\partial z} - \frac{z}{i} \frac{\partial}{\partial z^*} + \frac{z}{i} \frac{\partial}{\partial z} + \frac{z}{i} \frac{\partial}{\partial z^*} \right] \\
 &= \boxed{\frac{\hbar^2}{2} \left[z \frac{\partial}{\partial z} - z^* \frac{\partial}{\partial z^*} \right]} \quad \text{QED}
 \end{aligned}$$

$$(d)(i) L_z \Psi_1(z, z^*)$$

$$\begin{aligned}
 &= \frac{\hbar}{2} \left[z \frac{\partial \Psi_1}{\partial z} - z^* \frac{\partial \Psi_1}{\partial z^*} \right] \\
 &= \frac{\hbar}{2} \left[z \zeta_1 \left(2z^{1/2} e^{-zz^*/2} + z^{1/2} e^{-zz^*/2} \left(\frac{-z^*}{z} \right) \right) \right] \\
 &\quad - \frac{\hbar}{2} \left[z^* \zeta_1 \left(z^{1/2} e^{-zz^*/2} \left(\frac{-z}{z} \right) \right) \right] \\
 &= \frac{\hbar}{2} \left[\left(1 - \frac{zz^*}{2} \right) \Psi_1 + \frac{z^* z}{2} \Psi_1 \right] = \frac{\hbar}{2} \left[1 - \frac{zz^*}{2} + \frac{z^* z}{2} \right] \Psi_1
 \end{aligned}$$

$$\Rightarrow \boxed{L_z \Psi_1 = \gamma \hbar \Psi_1}$$

$$(ii) \text{ we know } L_z \Psi_1(z, z^*) = \gamma \hbar \Psi_1(z, z^*)$$

$$L_z^* = \frac{\hbar}{2} \left[z^* \frac{\partial}{\partial z^*} - z \frac{\partial}{\partial z} \right] = -L_z$$

$$\text{now } L_z^* \Psi_1^* = \gamma \hbar \Psi_1^*$$

$$\Rightarrow \boxed{L_z \Psi_1^* = -\gamma \hbar \Psi_1^*} \quad \text{QED}$$

$$(e) \Psi_l(z, z^*) = \frac{1}{(\pi a_0^2 l!)^{1/2}} z^l e^{-|z|^2/2}$$

$$\Psi_l(z) = \frac{1}{\sqrt{\pi a_0^2}} \frac{1}{(l!)^{1/2}} z^l e^{-|z|^2/2}$$

$$|\Psi_l(z)|^2 = \frac{1}{\pi a_0^2 l!} (|z|^2)^l e^{-|z|^2}$$

$$\Rightarrow S = \frac{e^{-|z|^2}}{\pi a_0^2} \sum_{l=0}^{\infty} \frac{(|z|^2)^l}{l!} = \frac{e^{-|z|^2}}{\pi a_0^2} e^{|z|^2}$$

$$\Rightarrow S = 1 / \pi a_0^2 \quad \text{QED}$$

$$\text{Ans 11)} \quad \phi_m(z) = \frac{1}{\sqrt{2\pi 2^m m!}} z^m \quad m = 0, 1, 2, \dots$$

$$\mu[z, z^*] = \exp(-|z|^2/2)$$

$$\langle \phi_n | \phi_m \rangle = \int_{-\infty}^{\infty} \phi_n^*(z) \phi_m(z) \mu[z, z^*] dx dy$$

$$(a) \langle \phi_n | \phi_m \rangle = \int_{-\infty}^{\infty} \frac{(z^*)^n z^m}{2\pi \sqrt{2^{n+m} n! m!}} \exp(-|z|^2/2) dx dy$$

now convert this problem to polar coordinates
 $dx dy \rightarrow r dr d\theta \quad |z|^2 = r^2 \quad (d)$

$$z = r e^{i\theta} \Rightarrow \langle \phi_n | \phi_m \rangle = C_{m,n} \int r^{n+m} e^{i(n+m)\theta} e^{-r^2/2} r dr d\theta$$

$$\Rightarrow \langle \phi_n | \phi_m \rangle = C_{m,n} \int e^{i(n+m)\theta} d\theta \int r^{n+m+1} e^{-r^2/2} dr$$



Now if $n \neq m$:

$$\int_0^{2\pi} \exp[i(m-n)\theta] d\theta = \left[\frac{e^{i(m-n)\theta}}{i(m-n)} \right]_0^{2\pi} = \frac{1-1}{i(m-n)} = 0$$

In $m = n$:

$$\int_0^{2\pi} e^0 d\theta = 2\pi$$

$$\Rightarrow \langle \phi_n | \phi_m \rangle = 0 \text{ if } n \neq m$$

now $\int_0^\infty r^{n+m+1} \exp(-r^2/2) dr$

let $r^2/2 = u$
 $\Rightarrow r dr = du$
 $\Rightarrow (2u)^{1/2} = r$

$$= \int_0^\infty r^{m+n} (\exp(-u)) du$$

$$= \int_0^\infty 2^{\frac{m+n}{2}} u^{\frac{m+n}{2}} \exp(-u) du$$

$$= \sqrt{2^{m+n}} \underbrace{\int_0^\infty u^m \exp(-u) du}_{(S151) \text{ qna}} = \sqrt{2^m m!}$$

gamma function

substituting: $\langle \phi_m | \phi_m \rangle = \frac{1}{2\pi m! 2^m} (2\pi) (m! 2^m) = 1$

$$\Rightarrow \boxed{\langle \phi_m | \phi_n \rangle = \delta_{mn}} \text{ QED}$$

(b) $b^T = z/\sqrt{2}$ $b = \sqrt{2} \frac{d}{dz}$

To show $b^T \phi_m \propto \phi_{m+1}$

$$b \phi_m \propto \phi_{m+1}$$

$$b^T \phi_m = \frac{1}{\sqrt{2\pi 2^{m+1} m!}} z^{m+1} = \phi_{m+1} \sqrt{(m+1)}$$

Hence b^+ raises the state from ϕ_m to ϕ_{m+1}

$$b\phi_m = \sqrt{2} \frac{d}{dz} \phi_m = \frac{m z^{m-1}}{\sqrt{2\pi 2^{m-1} (m-1)! m}} = \sqrt{m} \phi_{m-1}$$

Hence b lowers the state from ϕ_m to ϕ_{m-1}

$$(c) [b, b^+] = \left[\sqrt{2} \frac{d}{dz}, \frac{z}{\sqrt{2}} \right]$$

$$\begin{aligned} [b, b^+] \psi &= \frac{\sqrt{2}}{\sqrt{2}} \frac{d}{dz} (z\psi) - \frac{\sqrt{2}}{\sqrt{2}} z \frac{d\psi}{dz} \\ &= z \frac{d\psi}{dz} + \psi - z \frac{d\psi}{dz} = \psi \end{aligned}$$

$$\Rightarrow \boxed{[b, b^+] \psi = 1} \quad \text{QED}$$