

CL249: ASSIGNMENT 8

PROBLEM

We have to solve a set of differential equations using RK4 and RK5 technique, which represent one of the simple models to describe spreading of COVID 19.

$$\frac{dy_1}{dx} = -cy_1y_2 \quad \frac{dy_2}{dx} = cy_1y_2 - dy_2 \quad \frac{dy_3}{dx} = dy_2$$

y_1 = Healthy people

y_2 = Infected people

y_3 = People under quarantine

$$y_1(x=0) = 95 \quad y_2(x=0) = 5 \quad y_3(x=0) = 0$$

And plot the graphs

Description of Method

RK4 Method

we have $\frac{dy}{dx} = f(x, y)$

and we define h represents stepsize

$$K_1 = f(x_i, y_i)$$

$$K_2 = f\left(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_1h\right)$$

$$K_3 = f\left(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_2h\right)$$

$$K_4 = f(x_i + h, y_i + K_3h)$$

and

$$y_{i+1} = y_i + \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)h$$

where y is the required function

RK5 Method

we have $\frac{dy}{dx} = f(x, y)$

define

$h = \text{stepsize}$

$$K_1 = f(x_i, y_i)$$

$$K_2 = f\left(x_i + \frac{1}{4}h, y_i + \frac{1}{4}K_1h\right)$$

$$K_3 = f\left(x_i + \frac{1}{4}h, y_i + \frac{K_1h}{8} + \frac{K_2h}{8}\right)$$

$$K_4 = f\left(x_i + \frac{1}{2}h, y_i - \frac{K_2h}{2} + K_3h\right)$$

$$K_5 = f\left(x_i + \frac{3}{4}h, y_i + \frac{3K_1h}{16} + \frac{9K_2h}{16} + \frac{9K_3h}{16} - \frac{3K_4h}{16}\right)$$

$$K_6 = f\left(x_i + h, y_i - \frac{3K_1h}{7} + \frac{2K_2h}{7} + \frac{13K_3h}{7} - \frac{K_4h}{7} + \frac{8K_5h}{7}\right)$$

and

$$y_{i+1} = y_i + \frac{1}{90}(7K_1 + 32K_2 + 12K_3 + 32K_4 + 7K_5 + K_6)h$$

where y is the required f^h

PSEUDO CODE

RK4.m to calculate using RK4 method.

let x, y_1, y_2, y_3 be empty array
and $c_1 = 1$ $d = 5$ be given const.

Initial values

$$y_1(1) = 9.5; y_2(1) = 5;$$

Iterate through 1 to $N-1$

$$x_{i+1} = x_i + h$$

$$(k_1 y_1, k_2 y_1, k_3 y_1) = \text{derivative}(y_1(i), y_2(i))$$

$$(k_2 y_1, k_2 y_2, k_2 y_3) = \text{der}(y_1 + \frac{k_1 y_1 h}{2})$$

$$(k_3 y_1, k_3 y_2, k_3 y_3) = \text{der}(y_1 + \frac{k_2 y_1 h}{2})$$

$$(k_4 y_1, k_4 y_2, k_4 y_3) = \text{der}(y_1 + \frac{k_3 y_1 h}{2})$$

update values y_1, y_2, y_3 as

$$y_{i+1} = y_i + \frac{h}{4} (k_1 + 2k_2 + 2k_3 + k_4)$$

return y_1, y_2, y_3 ;

derivative.m

get y_1 and y_2 and c, d

$$y_1' = -c y_1 y_2$$

$$y_2' = c y_1 y_2 - d y_2$$

$$y_3' = d y_2$$

return all values.

RK5-m

get all the arrays and constants.

assign initial values to y_1, y_2, y_3

Iterate from 1 to N-1

Increase x_{i+1} as $x_i + h$

or

Calculate for y_1, y_2, y_3

$$(K_1, K_2, K_3) = \text{derivativ} (x_i, y_i)$$

~~K_2, K_3~~

$$K_2 = \text{derivativ} (y_i + K_1 h)$$

$$K_3 = \text{derivativ} (y_i + \frac{K_1 h}{8} + \frac{K_2 h}{8})$$

$$K_4 = \text{derivativ} (y_i - \frac{K_2 h}{2} + \frac{K_3 h}{2})$$

$$K_5 = \text{derivativ} (y_i + \frac{K_1 h}{10} + \frac{9 K_4 h}{10})$$

$$K_6 = \text{derivativ} (y_i - \frac{3 K_1 h}{7} + \frac{2 K_2 h}{7} + \frac{12 K_3 h}{7} - \frac{12 K_4 h}{7} + \frac{8 K_5 h}{7})$$

update each y as ~~$y_{i+1} = y_i + h$~~

$$y_{i+1} = y_i + \frac{h}{90} (7 K_1 + 32 K_3 + 12 K_4 + 32 K_5 + 7 K_6)$$

Main.m

get all y_1, y_2, y_3 from RK4 and RK5

plot ~~y_1, y_2, y_3~~ Vs x

end

```
% Interval of X
a = 0;
b = 4;
% Number of steps
N = 500;
% Step size
h = (b-a)/N;

% Calculating Y1, Y2, Y3, by RK4 Method
[X1, Y1_RK4, Y2_RK4, Y3_RK4] = rk4(a, b, h, N);
% Calculating Y1, Y2, Y3 by RK5 Method
[X2, Y1_RK5, Y2_RK5, Y3_RK5] = rk5(a, b, h, N);

% Plotting the RK4 Method Solution
figure(1)
plot(X1, Y1_RK4, 'DisplayName', 'Y1 (Healthy People)', 'LineWidth', 1.25);
hold on
plot(X1, Y2_RK4, 'DisplayName', 'Y2 (Infected Prople)', 'LineWidth', 1.25);
hold on
plot(X1, Y3_RK4, 'DisplayName', 'Y3 (People Under Quarantine)', 'LineWidth', 1.25);
title('Solution by RK1 Method')
xlabel('X')
ylabel('Y')
legend

% Plotting the RK5 Method Solution
figure(2)
plot(X2, Y1_RK5, 'DisplayName', 'Y1 (Healthy People)', 'LineWidth', 1.25);
hold on
plot(X2, Y2_RK5, 'DisplayName', 'Y2 (Infected Prople)', 'LineWidth', 1.25);
hold on
plot(X2, Y3_RK5, 'DisplayName', 'Y3 (People Under Quarantine)', 'LineWidth', 1.25);
title('Solution by RK2 Method')
xlabel('X')
ylabel('Y')
legend
```

```
% Function to calculate solution by RK4 Method
```

```
function [X, Y1, Y2, Y3] = rk4(a, b, h, N)
```

```
    % Given Constants
```

```
    c = 1;
```

```
    d = 5;
```

```
    % Declaring arrays
```

```
    X = zeros(1, N);
```

```
    Y1 = zeros(1, N);
```

```
    Y2 = zeros(1, N);
```

```
    Y3 = zeros(1, N);
```

```
    % Initial Values
```

```
    Y1(1) = 95;
```

```
    Y2(1) = 5;
```

```
    Y3(1) = 0;
```

```
    % Iteration Loop
```

```
    for i = 1:N-1
```

```
        % Increment in X
```

```
        X(i+1) = X(i) + h;
```

```
        % Calculating k1, k2, k3, k4 for y1 and y2 by using the derivative
```

```
        [k1y1, k1y2, k1y3] = derivative(Y1(i), Y2(i), c, d);
```

```
        [k2y1, k2y2, k2y3] = derivative(Y1(i) + (k1y1*h/2), Y2(i) + ✓
```

```
(k1y2*h/2), c, d);
```

```
        [k3y1, k3y2, k3y3] = derivative(Y1(i) + (k2y1*h/2), Y2(i) + ✓
```

```
(k2y2*h/2), c, d);
```

```
        [k4y1, k4y2, k4y3] = derivative(Y1(i) + (k3y1*h), Y2(i) + (k3y2*h), ✓
```

```
c, d);
```

```
        % Updating the next y values
```

```
        Y1(i+1) = Y1(i) + (k1y1 + (2*k2y1) + (2*k3y1) + k4y1)*h/6;
```

```
        Y2(i+1) = Y2(i) + (k1y2 + (2*k2y2) + (2*k3y2) + k4y2)*h/6;
```

```
        Y3(i+1) = Y3(i) + (k1y3 + (2*k2y3) + (2*k3y3) + k4y3)*h/6;
```

```
    end
```

```
    return
```

```
end
```

```

function [X, Y1, Y2, Y3] = rk5(a, b, h, N)
    % Given Constants
    c = 1;
    d = 5;
    % Declaring arrays
    X = zeros(1, N);
    Y1 = zeros(1, N);
    Y2 = zeros(1, N);
    Y3 = zeros(1, N);

    % Initial Values
    Y1(1) = 95;
    Y2(1) = 5;
    Y3(1) = 0;

    % Iteration Loop
    for i = 1:N-1
        % Increment in X
        X(i+1) = X(i) + h;

        % Calculating K's for y1, y2 using derivative function
        [k1y1, k1y2, k1y3] = derivative(Y1(i), Y2(i), c, d);
        [k2y1, k2y2, k2y3] = derivative(Y1(i) + (k1y1*h/4), Y2(i) + ✓
(k1y2*h/4), c, d);
        [k3y1, k3y2, k3y3] = derivative(Y1(i) + (k1y1*h/8) + (k2y1*h/8), Y2 ✓
(i) + (k1y2*h/8) + (k2y2*h/8), c, d);
        [k4y1, k4y2, k4y3] = derivative(Y1(i) - (k2y1*h/2) + (k3y1*h), Y2(i) ✓
- (k2y2*h/2) + (k3y2*h), c, d);
        [k5y1, k5y2, k5y3] = derivative(Y1(i) + (k1y1*h*3/16) + ✓
(k4y1*h*9/16), Y2(i) + (k1y2*h*3/16) + (k4y2*h*9/16), c, d);
        [k6y1, k6y2, k6y3] = derivative(Y1(i) - (k1y1*h*3/7) + (k2y1*h*2/7) ✓
+ (k3y1*h*12/7) - (k4y1*h*12/7) + (k5y1*h*8/7), Y2(i) - (k1y2*h*3/7) + ✓
(k2y2*h*2/7) + (k3y2*h*12/7) - (k4y2*h*12/7) + (k5y2*h*8/7) , c, d);

        % Updating the Y values
        Y1(i+1) = Y1(i) + ((7*k1y1) + (32*k3y1) + (12*k4y1) + (32*k5y1) + ✓
(7*k6y1))*h/90;
        Y2(i+1) = Y2(i) + ((7*k1y2) + (32*k3y2) + (12*k4y2) + (32*k5y2) + ✓
(7*k6y2))*h/90;
        Y3(i+1) = Y3(i) + ((7*k1y3) + (32*k3y3) + (12*k4y3) + (32*k5y3) + ✓
(7*k6y3))*h/90;
    end
    return
end

```

% Function to calculate derivative values

function [Y1_dash, Y2_dash, Y3_dash] = derivative(y1, y2, c, d)

Y1_dash = -c*y1*y2;

Y2_dash = (c*y1*y2) - (d*y2);

Y3_dash = d*y2;

return

end

The image shows the MATLAB R2021a interface with two code editors side-by-side. The left editor, named 'rk5.m', contains a function 'rk5' that uses a 'derivative' function. The right editor, named 'rk4.m', contains a function 'rk4' that implements the Runge-Kutta 4th order algorithm directly. A red rectangle highlights the code in both editors. The text 'Algorithm Execution' is written in red at the bottom right.

```
rk5.m
1  function [Y1, Y2, Y3] = rk5(X, N)
2
3  Y1 = zeros(1, N);
4  Y2 = zeros(1, N);
5  Y3 = zeros(1, N);
6
7  % Initial Values
8  Y1(1) = 95;
9  Y2(1) = 5;
10 Y3(1) = 0;
11
12 % Iteration Loop
13 for i = 1:N-1
14     % Increment in X
15     X(i+1) = X(i) + h;
16
17     % Calculating K's for y1, y2 using derivative function
18     [k1y1, k1y2, k1y3] = derivative(Y1(i), Y2(i), c, d);
19     [k2y1, k2y2, k2y3] = derivative(Y1(i) + (k1y1*h/4), Y2(i)
20     [k3y1, k3y2, k3y3] = derivative(Y1(i) + (k1y1*h/8) + (k2y
21     [k4y1, k4y2, k4y3] = derivative(Y1(i) - (k2y1*h/2) + (k3y
22     [k5y1, k5y2, k5y3] = derivative(Y1(i) + (k1y1*h*3/16) + (
23     [k6y1, k6y2, k6y3] = derivative(Y1(i) - (k1y1*h*3/7) + (k
24
25     % Updating the Y values
26     Y1(i+1) = Y1(i) + ((7*k1y1) + (32*k3y1) + (12*k4y1) + (32
27     Y2(i+1) = Y2(i) + ((7*k1y2) + (32*k3y2) + (12*k4y2) + (32
28     Y3(i+1) = Y3(i) + ((7*k1y3) + (32*k3y3) + (12*k4y3) + (32
29
30 end
31 return
```

```
rk4.m
1  % Declaring arrays
2  X = zeros(1, N);
3  Y1 = zeros(1, N);
4  Y2 = zeros(1, N);
5  Y3 = zeros(1, N);
6
7  % Initial Values
8  Y1(1) = 95;
9  Y2(1) = 5;
10 Y3(1) = 0;
11
12 % Iteration Loop
13 for i = 1:N-1
14     % Increment in X
15     X(i+1) = X(i) + h;
16
17     % Calculating k1, k2, k3, k4 for y1 and y2 by using t
18     [k1y1, k1y2, k1y3] = derivative(Y1(i), Y2(i), c, d);
19     [k2y1, k2y2, k2y3] = derivative(Y1(i) + (k1y1*h/2), Y
20     [k3y1, k3y2, k3y3] = derivative(Y1(i) + (k2y1*h/2), Y
21     [k4y1, k4y2, k4y3] = derivative(Y1(i) + (k3y1*h), Y2(
22
23     % Updating the next y values
24     Y1(i+1) = Y1(i) + (k1y1 + (2*k2y1) + (2*k3y1) + k4y1)
25     Y2(i+1) = Y2(i) + (k1y2 + (2*k2y2) + (2*k3y2) + k4y2)
26     Y3(i+1) = Y3(i) + (k1y3 + (2*k2y3) + (2*k3y3) + k4y3)
27
28 end
29 return
30 end
```

Algorithm Execution

Figure 1

File Edit View Insert Tools Desktop Window Help

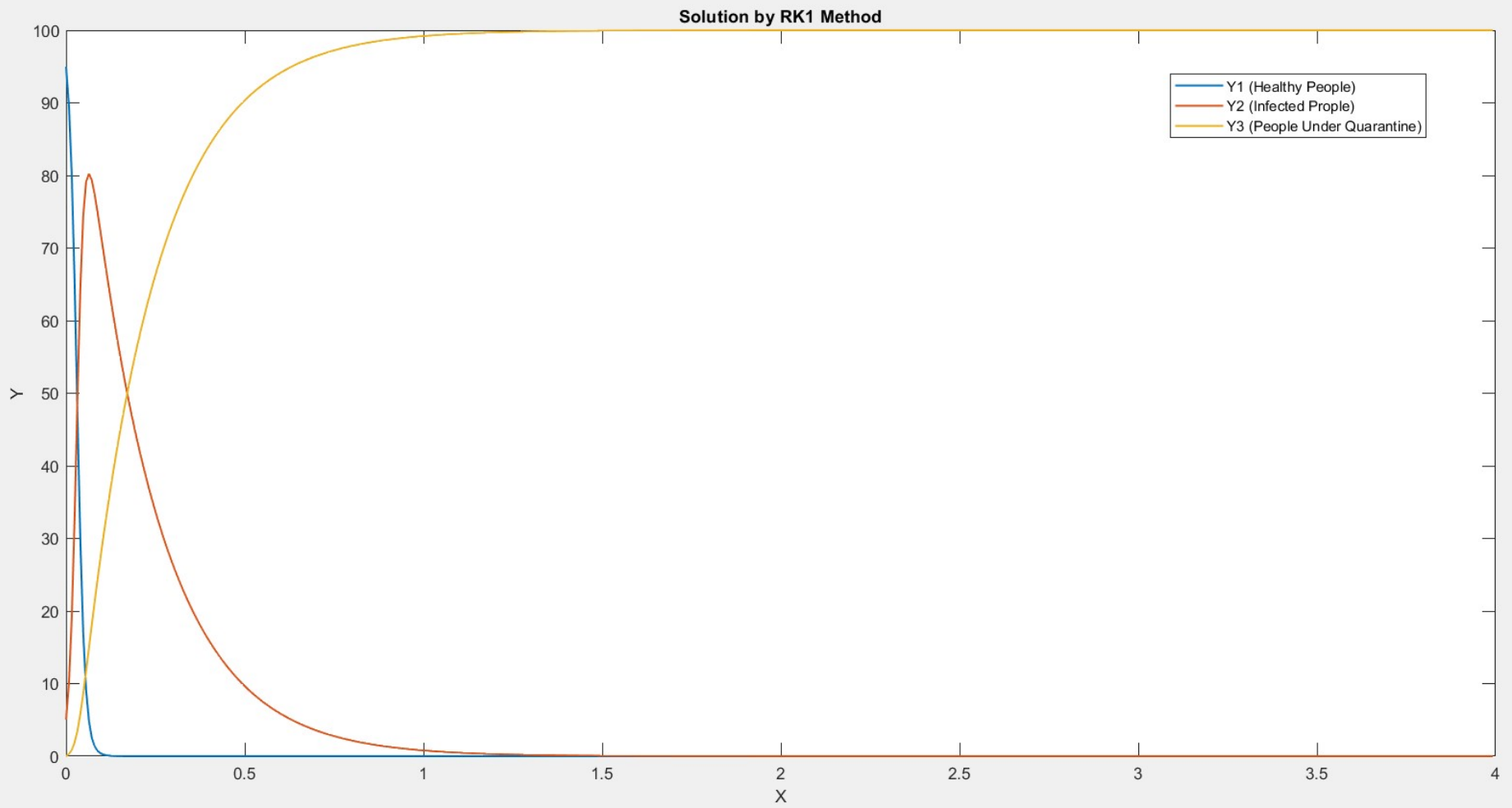
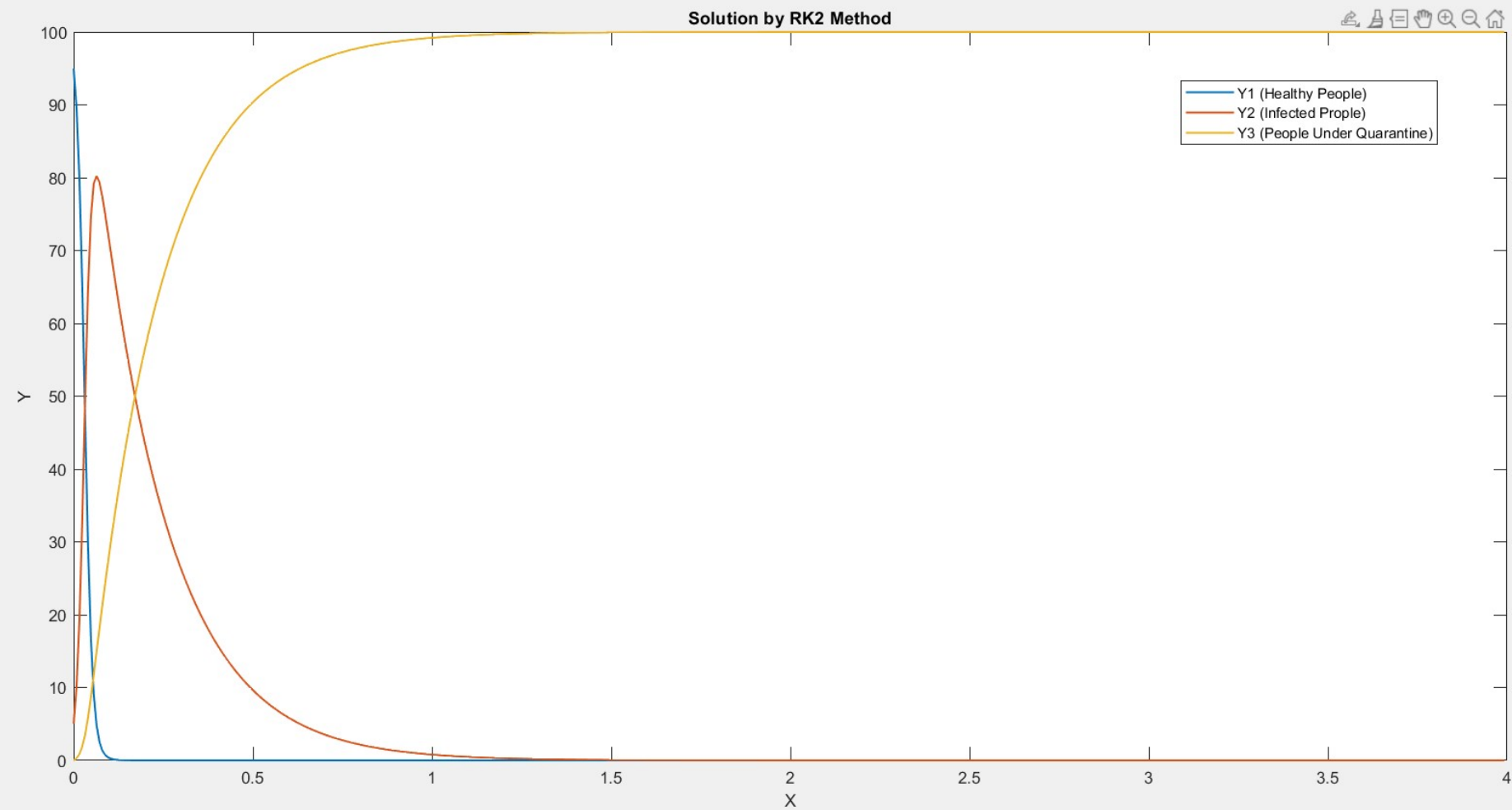


Figure 2

File Edit View Insert Tools Desktop Window Help



Conclusions

- RK4 ~~method~~ method is accurate enough and takes less time (less calculations), so it is more reliable.
- RK5 method is accurate but takes more calculations and hence computational time.