

# White Box Testing

# White box testing

- ▶ Black box testing focuses only on functionality
  - ▶ What the program does; not how it is implemented
- ▶ White box testing focuses on implementation
  - ▶ Aim is to exercise different program structures with the intent of uncovering errors
- ▶ Is also called *structural testing*
- ▶ Various criteria exist for test case design
- ▶ Test cases have to be selected to satisfy coverage criteria

# Types of structural testing

- ▶ Control flow based criteria
  - ▶ looks at the coverage of the control flow graph
- ▶ Data flow based testing
  - ▶ looks at the coverage in the definition-use graph
- ▶ Mutation testing
  - ▶ looks at various mutants of the program

# Control flow based criteria

- ▶ Considers the program as control flow graph
  - ▶ Nodes represent code blocks - i.e. set of statements always executed together
  - ▶ An edge  $(i,j)$  represents a possible transfer of control from  $i$  to  $j$
- ▶ Assume a start node and an end node
- ▶ A path is a sequence of nodes from start to end

# Statement Coverage Criterion

- ▶ Criterion: Each statement is executed at least once during testing
- ▶ I.e. set of paths executed during testing should include all nodes
- ▶ Limitation: does not require a decision to evaluate to false if no else clause
- ▶ E.g.: `abs (x) : if ( x >= 0) x = -x; return(x)`
  - ▶ The set of test cases  $\{x = 0\}$  achieves 100% statement coverage, but error not detected
- ▶ Guaranteeing 100% coverage not always possible due to possibility of unreachable nodes

# Statement Coverage

- ▶ Statement coverage methodology:
  - ▶ Design test cases so that every statement in the program is executed at least once.

# Statement Coverage

- ▶ The principal idea:
  - ▶ Unless a statement is executed,
  - ▶ We have no way of knowing if an error exists in that statement.

# Statement Coverage Criterion

- ▶ Observing that a statement behaves properly for one input value:
  - ▶ No guarantee that it will behave correctly for all input values.



# Example

```
▶ int f1(int x, int y){  
▶ 1 while (x != y){  
▶ 2   if (x>y) then  
▶ 3     x=x-y;  
▶ 4   else y=y-x;  
▶ 5 }  
▶ 6 return x;    }
```

Euclid's GCD Algorithm

# Euclid's GCD Computation Algorithm

- ▶ By choosing the test set  $\{(x=3, y=3), (x=4, y=3), (x=3, y=4)\}$ 
  - ▶ All statements are executed at least once.

# Branch coverage

- ▶ Criterion: Each edge should be traversed at least once during testing
- ▶ i.e. each decision must evaluate to both true and false during testing
- ▶ Branch coverage implies stmt coverage
- ▶ If multiple conditions in a decision, then all conditions need not be evaluated to T and F

# Branch Coverage

- ▶ Branch testing guarantees statement coverage:
  - ▶ A stronger testing compared to the statement coverage-based testing.

# Stronger Testing

- ▶ Test cases are a superset of a weaker testing:
  - ▶ A stronger testing covers at least all the elements of the elements covered by a weaker testing.

# Example

```
▶ int f1(int x,int y){  
▶ 1 while (x != y){  
▶ 2   if (x>y) then  
▶ 3     x=x-y;  
▶ 4   else y=y-x;  
▶ 5 }  
▶ 6 return x;    }
```

# Example

- ▶ Test cases for branch coverage can be:
- ▶  $\{(x=3, y=3), (x=3, y=2), (x=4, y=3), (x=3, y=4)\}$

# Condition Coverage

- ▶ Test cases are designed such that:
  - ▶ Each component of a composite conditional expression
    - ▶ Given both true and false values.



# Example

- ▶ Consider the conditional expression
  - ▶  $((c1.and.c2).or.c3)$ :
- ▶ Each of  $c1$ ,  $c2$ , and  $c3$  are exercised at least once,
  - ▶ i.e. given true and false values.

# Branch Testing

- ▶ Branch testing is the simplest condition testing strategy:
  - ▶ Compound conditions appearing in different branch statements
    - ▶ Are given true and false values.

# Branch testing

- ▶ Condition testing
  - ▶ Stronger testing than branch testing.
- ▶ Branch testing
  - ▶ Stronger than statement coverage testing.



# Condition coverage

- ▶ Consider a boolean expression having  $n$  components:
  - ▶ For condition coverage we require  $2^n$  test cases.
- ▶ Condition coverage-based testing technique:
  - ▶ Practical only if  $n$  (the number of component conditions) is small.

# Path Coverage

- ▶ Design test cases such that:
  - ▶ All linearly independent paths in the program are executed at least once.
- ▶ Defined in terms of
  - ▶ Control flow graph (CFG) of a program.

# Path Coverage-Based Testing

- ▶ To understand the path coverage-based testing:
  - ▶ we need to learn how to draw control flow graph of a program.
- ▶ A control flow graph (CFG) describes:
  - ▶ the sequence in which different instructions of a program get executed.
  - ▶ the way control flows through the program.

# How to Draw Control Flow Graph?

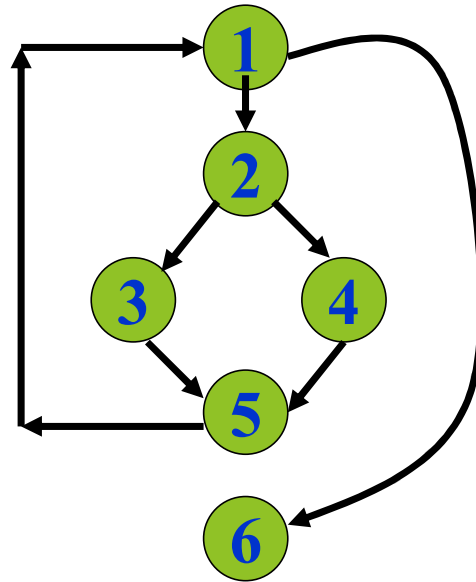
- ▶ Number all the statements of a program.
- ▶ Numbered statements:
  - ▶ Represent nodes of the control flow graph.
- ▶ An edge from one node to another node exists:
  - ▶ If execution of the statement representing the first node can result in transfer of control to the other node.

# Example

```
▶ int f1(int x,int y){  
▶ 1 while (x != y){  
▶ 2   if (x>y) then  
▶ 3     x=x-y;  
▶ 4   else y=y-x;  
▶ 5 }  
▶ 6 return x;    }
```



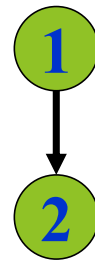
# Example Control Flow Graph



# How to draw Control flow graph?

## ► Sequence:

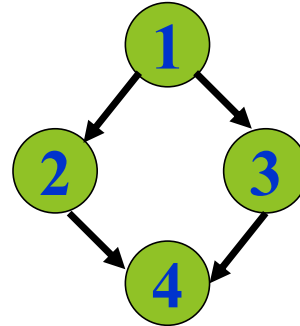
- 1  $a=5;$
- 2  $b=a*b-1;$



# How to draw Control flow graph?

## ► Selection:

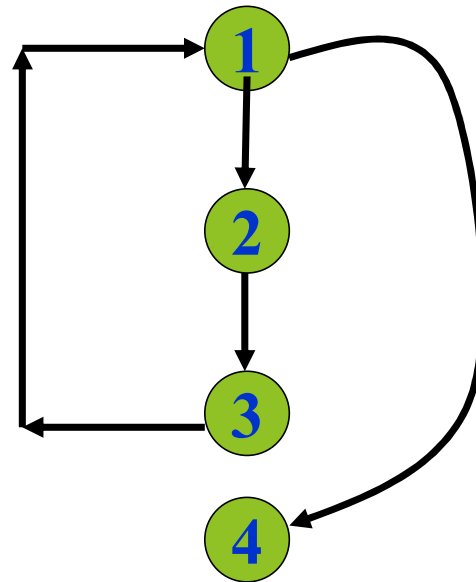
- 1 if(a>b) then
- 2        c=3;
- 3 else    c=5;
- 4 c=c\*c;



# How to draw Control flow graph?

## ► Iteration:

- 1 while(a>b){
- 2     b=b\*a;
- 3     b=b-1;}
- 4 c=b+d;



# Path

- ▶ A path through a program:
  - ▶ A node and edge sequence from the starting node to a terminal node of the control flow graph.
  - ▶ There may be several terminal nodes for program.

# Linearly Independent Path

- ▶ Any path through the program:
  - ▶ Introducing at least one new edge:
    - ▶ That is not included in any other independent paths.



# Independent path

- ▶ It is straight forward:
  - ▶ To identify linearly independent paths of simple programs.
- ▶ For complicated programs:
  - ▶ It is not so easy to determine the number of independent paths.



# McCabe's Cyclomatic Metric

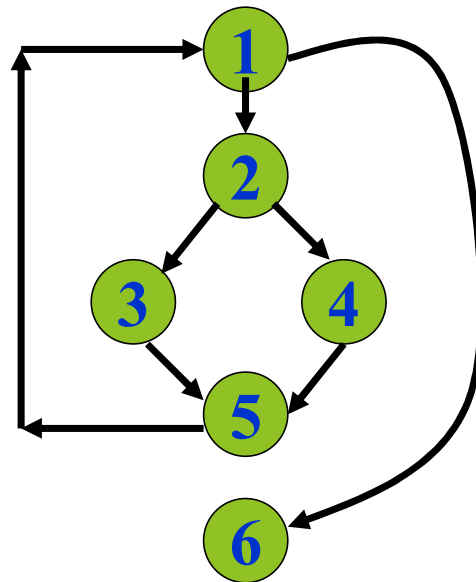
- ▶ An upper bound:
  - ▶ For the number of linearly independent paths of a program
- ▶ Provides a practical way of determining:
  - ▶ The maximum number of linearly independent paths in a program.



# McCabe's Cyclomatic Metric

- ▶ Given a control flow graph  $G$ , cyclomatic complexity  $V(G)$ :
  - ▶  $V(G) = E - N + 2$ 
    - ▶  $N$  is the number of nodes in  $G$
    - ▶  $E$  is the number of edges in  $G$

## Example Control Flow Graph

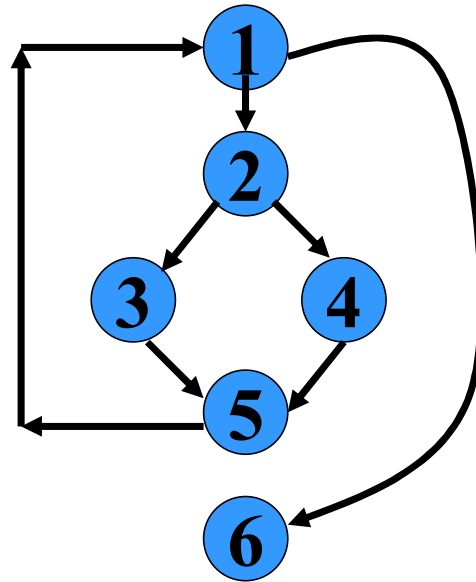


**Cyclomatic complexity =  
 $7 - 6 + 2 = 3$ .**

# Cyclomatic Complexity

- ▶ Another way of computing cyclomatic complexity:
  - ▶ inspect control flow graph
  - ▶ determine number of bounded areas in the graph
- ▶  $V(G) = \text{Total number of bounded areas} + 1$ 
  - ▶ Any region enclosed by a nodes and edge sequence.

# Example Control Flow Graph



# Example

- ▶ From a visual examination of the CFG:
  - ▶ the number of bounded areas is 2.
  - ▶ cyclomatic complexity =  $2+1=3$ .



# Cyclomatic complexity

- ▶ McCabe's metric provides:
  - ▶ A quantitative measure of testing difficulty and the ultimate reliability
- ▶ Intuitively,
  - ▶ Number of bounded areas increases with the number of decision nodes and loops.

# Cyclomatic Complexity

- ▶ The first method of computing  $V(G)$  is amenable to automation:
  - ▶ You can write a program which determines the number of nodes and edges of a graph
  - ▶ Applies the formula to find  $V(G)$ .

# Cyclomatic complexity

- ▶ The cyclomatic complexity of a program provides:
  - ▶ A lower bound on the number of test cases to be designed
  - ▶ To guarantee coverage of all linearly independent paths.



# Cyclomatic Complexity

- ▶ Knowing the number of test cases required:
  - ▶ Does not make it any easier to derive the test cases,
  - ▶ Only gives an indication of the minimum number of test cases required.

# Path Testing

- ▶ The tester proposes:
  - ▶ An initial set of test data using his experience and judgement.
- ▶ A dynamic program analyzer is used:
  - ▶ To indicate which parts of the program have been tested
  - ▶ The output of the dynamic analysis
    - ▶ used to guide the tester in selecting additional test cases.

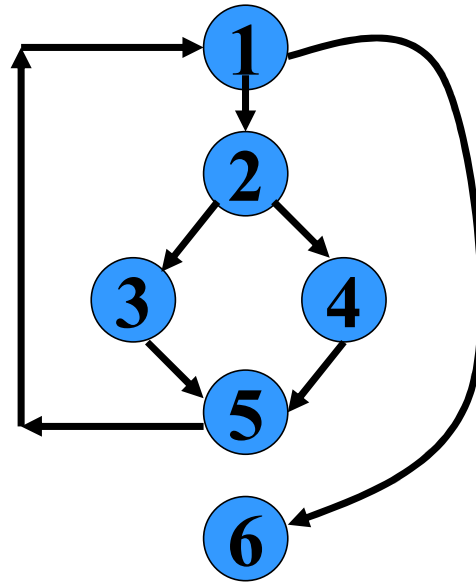
# Derivation of Test Cases

- ▶ Let us discuss the steps:
  - ▶ to derive path coverage-based test cases of a program.
- ▶ Draw control flow graph.
- ▶ Determine  $V(G)$ .
- ▶ Determine the set of linearly independent paths.
- ▶ Prepare test cases:
  - ▶ to force execution along each path.

# Example

```
▶ int f1(int x,int y){  
▶ 1 while (x != y){  
▶ 2   if (x>y) then  
▶ 3     x=x-y;  
▶ 4   else y=y-x;  
▶ 5 }  
▶ 6 return x;    }
```

# Example Control Flow Diagram



# Derivation of Test Cases

- ▶ Number of independent paths: 3
  - ▶ 1,6 test case (x=1, y=1)
  - ▶ 1,2,3,5,1,6 test case(x=1, y=2)
  - ▶ 1,2,4,5,1,6 test case(x=2, y=1)

## An interesting application of cyclomatic complexity

- ▶ Relationship exists between:
  - ▶ McCabe's metric
  - ▶ The number of errors existing in the code,
  - ▶ The time required to find and correct the errors.

# Cyclomatic Complexity

- ▶ Cyclomatic complexity of a program:
  - ▶ Also indicates the psychological complexity of a program.
  - ▶ Difficulty level of understanding the program.





# Cyclomatic Complexity

- ▶ From maintenance perspective,
  - ▶ limit cyclomatic complexity
    - ▶ of modules to some reasonable value.
  - ▶ Good software development organizations:
    - ▶ restrict cyclomatic complexity of functions to a maximum of 10 or so.



## Control flow based...

- ▶ There are other criteria too - path coverage, predicate coverage, cyclomatic complexity based, ...
- ▶ None is sufficient to detect all types of defects (e.g. a program missing some paths cannot be detected)
- ▶ They provide some quantitative handle on the breadth of testing
- ▶ More used to evaluate the level of testing rather than selecting test cases

# Tool support and test case selection

- ▶ Two major issues for using these criteria
  - ▶ How to determine the coverage
  - ▶ How to select test cases to ensure coverage
- ▶ For determining coverage - tools are essential
- ▶ Tools also tell which branches and statements are not executed
- ▶ Test case selection is mostly manual - test plan is to be augmented based on coverage data

# In a Project

- ▶ Both functional and structural should be used
- ▶ Test plans are usually determined using functional methods; during testing, for further rounds, based on the coverage, more test cases can be added
- ▶ Structural testing is useful at lower levels only; at higher levels ensuring coverage is difficult
- ▶ Hence, a combination of functional and structural at unit testing
- ▶ Functional testing (but monitoring of coverage) at higher levels

# Comparison

	Code Review	Structural Testing	Functional Testing
Computational	M	H	M
Logic	M	H	M
I/O	H	M	H
Data handling	H	L	H
Interface	H	H	M
Data defn.	M	L	M
Database	H	M	M

# System Testing

- ▶ There are three main kinds of system testing:
  - ▶ Alpha Testing
  - ▶ Beta Testing
  - ▶ Acceptance Testing

# Alpha Testing

- ▶ **System testing is carried out by the test team within the developing organization.**
- ▶ **Its main purpose is to discover software bugs that were not found before.**
- ▶ **At the stage of alpha testing, software behavior is verified under real-life conditions by imitating the end-users' actions.**
- ▶ **The alpha phase includes the following testing types: smoke, sanity, integration, systems, usability, UI (user interface), acceptance, regression, and functional testing.**
- ▶ **If an error is detected, then it is immediately addressed to the development team.**
- ▶ **Alpha testing helps to discover issues missed at the stage of requirement gathering.**
- ▶ **The alpha release is the software version that has passed alpha testing.**
- ▶ **The next stage is beta testing.**

# Beta Testing

- ▶ System testing performed by a select group of friendly customers.
- ▶ All the testing activities are performed outside the organization that has developed the product.
- ▶ Beta checking helps to identify the gaps between the stage of requirements gathering and their implementation.
- ▶ Beta testing can be called pre-release testing.
- ▶ It can be conducted by a limited number of end-users called beta testers before the official product delivery.
- ▶ The main purpose of beta testing is
  - ▶ to verify software compatibility with different software and hardware configurations, types of network connection, and to get the users' feedback on software usability and functionality.



# Beta Testing

- ▶ There are two types of beta testing:
  - **open beta** is available for a large group of end-users or to everyone interested
  - **closed beta** is available only to a limited number of users that are selected especially for beta testing.
- ▶ During beta testing, end users detect and report bugs they have found.
- ▶ The product version that has passed beta testing is called beta release.
- ▶ After the beta phase comes gamma testing.

# Gamma Testing

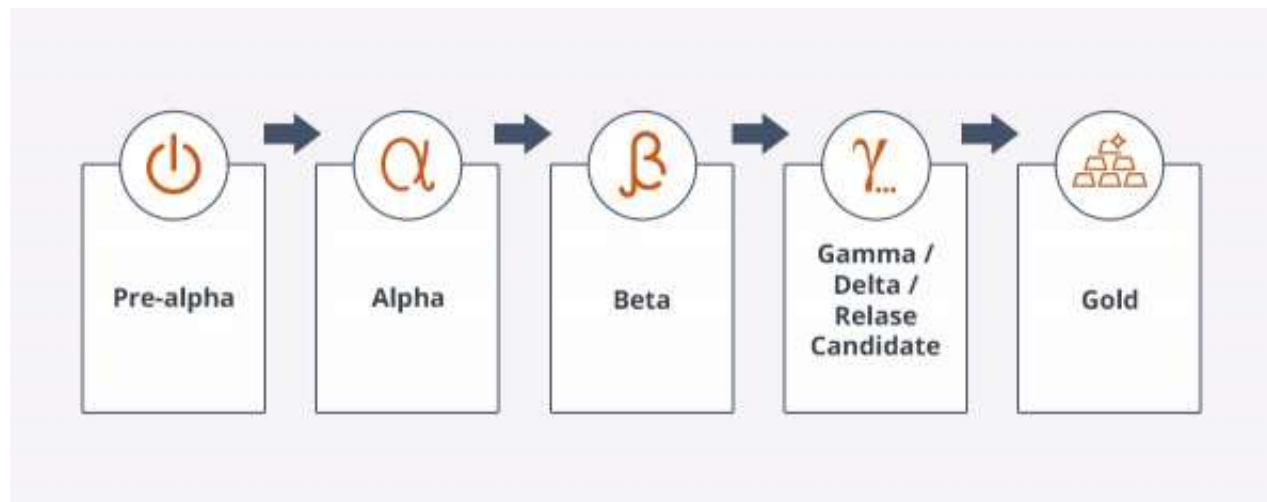
- ▶ **Gamma testing is the final stage of the testing process conducted before software release.**
- ▶ **It makes sure that the product is ready for market release according to all the specified requirements.**
- ▶ **Gamma testing focuses on software security and functionality.**
- ▶ **But it does not include any in-house Quality Assurance (QA) activities.**
- ▶ **During gamma testing, the software does not undergo any modifications unless the detected bug is of a high priority and severity.**
- ▶ **Only a limited number of users perform gamma testing, and testers do not participate.**
- ▶ **The checking includes the verification of certain specifications, not the whole product.**
- ▶ **Feedback received after gamma testing is considered as updates for upcoming software versions.**
- ▶ **But, because of a limited development cycle, gamma testing is usually skipped.**

# Acceptance Testing

- ▶ System testing performed by the customer himself:
  - ▶ to determine whether the system should be accepted or rejected.

# software release life cycle

- **pre-alpha stage** that consists of activities done before the QA and testing phase.



# Metrics

Testing

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# Data

- ▶ Defects found are generally logged
- ▶ The log forms the basic data source for metrics and analysis during testing
- ▶ Main questions of interest for which metrics can be used
  - ▶ How good is the testing that has been done so far?
  - ▶ What is the quality or reliability of software after testing is completed?

# Coverage Analysis

- ▶ Coverage is very commonly used to evaluate the thoroughness of testing
- ▶ This is not white box testing, but evaluating the overall testing through coverage
- ▶ Organization sometimes have guidelines for coverage, particularly at unit level (say 90% before checking code in)
- ▶ Coverage of requirements also checked - often by evaluating the test suites against requirements

# Reliability Estimation

- ▶ High reliability is an important goal to be achieved by testing
- ▶ Reliability is usually quantified as a probability or a failure rate or mean time to failure
  - ▶  $R(t) = P(X > t)$
  - ▶ MTTF = mean time to failure
  - ▶ Failure rate- failures per unit time
- ▶ For a system reliability can be measured by counting failures over a period of time
- ▶ Measurement often not possible for software as due to fixes reliability changes, and with one-off, not possible to measure



# Reliability Metrics

- ▶ Reliability metrics are used to quantitatively express the reliability of the software product.
- ▶ **Mean Time to Failure (MTTF)**
  - ▶ **MTTF** is described as the time interval between the two successive failures.
  - ▶ The time units are entirely dependent on the system & it can even be stated in the number of transactions.
  - ▶ To measure **MTTF**, we can evidence the failure data for n failures. Let the failures appear at the time instants  $t_1, t_2, \dots, t_n$ .
  - ▶ **MTTF can be calculated as**

$$\sum_{i=1}^n \frac{t_{i+1} - t_i}{(n-1)}$$

# Reliability Metrics

## ► Mean Time to Repair (MTTR)

- Once failure occurs, some-time is required to fix the error.
- **MTTR** measures the average time it takes to track the errors causing the failure and to fix them.

## ► Mean Time Between Failure (MTBF)

- We can merge **MTTF** & **MTTR** metrics to get the MTBF metric.

$$\mathbf{MTBF = MTTF + MTTR}$$

- Thus, an **MTBF** of 300 denoted that once the failure appears, the next failure is expected to appear only after 300 hours.
- In this method, the time measurements are real-time & not the execution time as in **MTTF**.

# Reliability Estimation

- ▶ Simple method of measuring reliability achieved during testing
  - ▶ Failure rate, measured by no of failures in some duration
- ▶ for using this for prediction, assumed that during this testing software is used as it will be by users
- ▶ Execution time is often used for failure rate, it can be converted to calendar time

# Reliability Estimation...

- ▶ Sw reliability estimation models are used to model the failure followed by fix model of software
- ▶ Data about failures and their times during the last stages of testing is used by these model
- ▶ These models then use this data and some statistical techniques to predict the reliability of the software
- ▶ Software reliability growth models are quite complex and sophisticated

# Defect removal efficiency

- ▶ Basic objective of testing is to identify defects present in the programs
- ▶ Testing is good only if it succeeds in this goal
- ▶ Defect removal efficiency of a QC activity = % of present defects detected by that QC activity
- ▶ High DRE of a quality control activity means most defects present at the time will be removed

## Defect removal efficiency ...

- ▶ DRE for a project can be evaluated only when all defects are known, including delivered defects
- ▶ Delivered defects are approximated as the number of defects found in some duration after delivery
- ▶ The *injection stage* of a defect is the stage in which it was introduced in the software, and *detection stage* is when it was detected
  - ▶ These stages are typically logged for defects
- ▶ With injection and detection stages of all defects, DRE for a QC activity can be computed

# Defect Removal Efficiency ...

- ▶ DREs of different QC activities are a process property - determined from past data
- ▶ Past DRE can be used as expected value for this project
- ▶ Process followed by the project must be improved for better DRE

# Verification versus Validation

- ▶ Verification is the process of determining
  - ▶ Whether output of one phase of development conforms to its previous phase.
- ▶ Validation is the process of determining
  - ▶ Whether a fully developed system conforms to its SRS document.
- ▶ Verification is concerned with phase containment of errors,
  - ▶ Whereas the aim of validation is that the final product be error free.