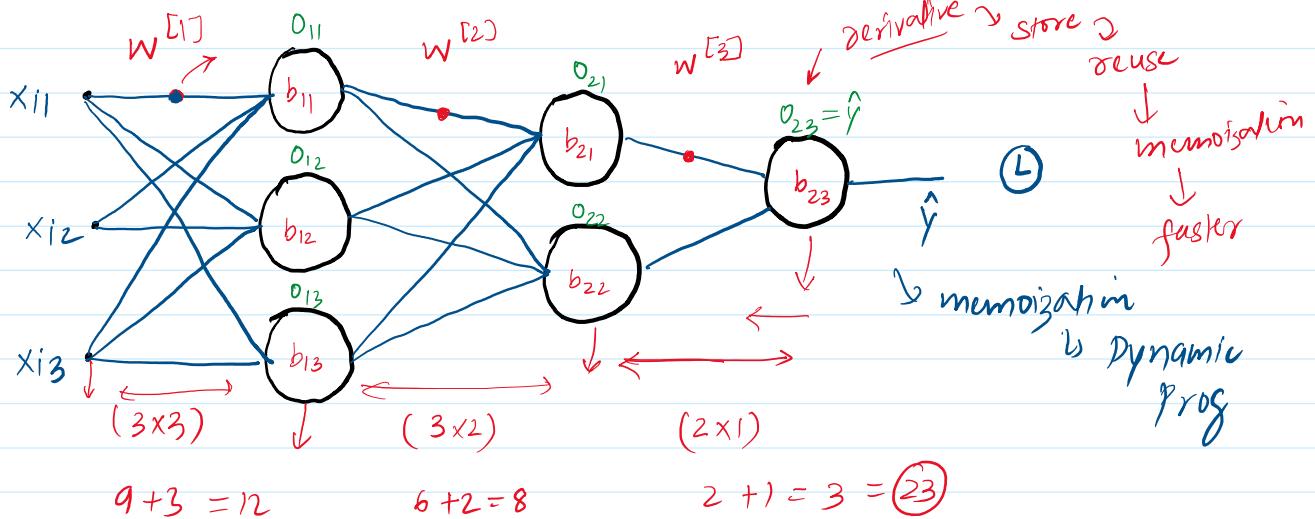


MLP Memoization

Thursday, April 7, 2022 7:45 AM

backprop update \rightarrow w/b deriv



Chain rule

$$L \rightarrow \hat{y} \rightarrow o_{21} \rightarrow o_{11} \rightarrow w_{11}^1$$

$$\frac{\partial L}{\partial w_{11}^3} = \boxed{\frac{\partial L}{\partial \hat{y}}} \times \boxed{\frac{\partial \hat{y}}{\partial w_{11}^3}}$$

$$\boxed{\frac{\partial L}{\partial \hat{y}}} = \boxed{\frac{\partial L}{\partial \hat{y}}} \times \boxed{\frac{\partial \hat{y}}{\partial o_{21}}} \times \boxed{\frac{\partial o_{21}}{\partial w_{11}^1}}$$

$$x \rightarrow f(x), g(x) \rightarrow h(f(x), g(x)) = \frac{\partial h}{\partial x} = \left[\frac{\partial h}{\partial f(x)} \times \frac{\partial f(x)}{\partial x} \right] + \left[\frac{\partial h}{\partial g(x)} \times \frac{\partial g(x)}{\partial x} \right]$$

$$\frac{\partial \hat{y}}{\partial w_{11}^1} \rightarrow w_{11}^1 \rightarrow o_{11} \rightarrow o_{21} \rightarrow \hat{y} \rightarrow L$$

$$\frac{\partial L}{\partial w_{11}^1}$$

$$\frac{\partial L}{\partial w_{11}^1} = \boxed{\frac{\partial L}{\partial \hat{y}}} \left[\boxed{\frac{\partial \hat{y}}{\partial o_{21}}} \times \boxed{\frac{\partial o_{21}}{\partial o_{11}}} \times \boxed{\frac{\partial o_{11}}{\partial w_{11}^1}} + \boxed{\frac{\partial \hat{y}}{\partial o_{22}}} \times \boxed{\frac{\partial o_{22}}{\partial o_{11}}} \times \boxed{\frac{\partial o_{11}}{\partial w_{11}^1}} \right]$$

Backprop \rightarrow Chain diff (rule) + Memoization
maths

Keras
TF