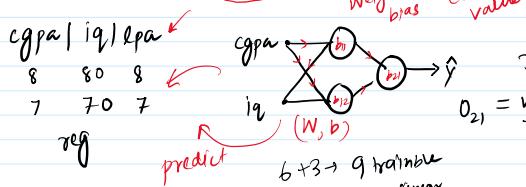


Pre requisite

- Gradient Descent (✓) →
- Forward Propagation (✓) →

Backprop
↓
Algo → train nn

(How)

trainingWeights
bias → correct
value $\sigma(z)$

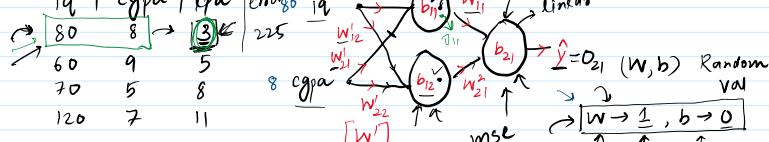
$$O_{21} = w_{11}^2 O_{11} + w_{12}^2 O_{12} + b_{21}$$

6 → 3 → 9 trainable

activation = linear

 $L \min \rightarrow \hat{y} \rightarrow O_{21}$ Backprop

1 students

Steps → 0) Init w, b ✓

1) You select a point (row) ✓

↳ student

Hierarchical
Backprop

2) Predict (lpa) → forward prop [dot product]

3) Choose a loss function (mse)

 $L = (y - \hat{y})^2$ $(3 - 18)^2 = 225$
error

4) Weights and bias update ✓

↳ Gradient descent

$W_{11, new} = W_{11, old} - \eta \frac{\partial L}{\partial W_{11}}$

$b_{11, new} = b_{11, old} - \eta \frac{\partial L}{\partial b_{11}}$

$W_{21, new} = W_{21, old} - \eta \frac{\partial L}{\partial W_{21}}$

$b_{21, new} = b_{21, old} - \eta \frac{\partial L}{\partial b_{21}}$

derivative of loss wrt weight

$$\frac{\partial L}{\partial W_{11}}$$

↳ partial derivative

derivative

$$\frac{\partial L}{\partial W_{11}}$$

↳ (min)

 $\frac{dy}{dx}$

$\frac{\partial L}{\partial W_{11}}, \frac{\partial L}{\partial W_{21}}, \frac{\partial L}{\partial b_{11}}, \frac{\partial L}{\partial b_{21}}$

$\frac{\partial L}{\partial W_{11}} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial W_{11}}$ ↳ chain rule of diff.

$\frac{\partial L}{\partial \hat{y}} = \frac{\partial L}{\partial y} \times \frac{\partial y}{\partial \hat{y}}$

$\frac{\partial L}{\partial y} = -2(y - \hat{y})$

$\frac{\partial L}{\partial W_{11}} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial W_{11}}$

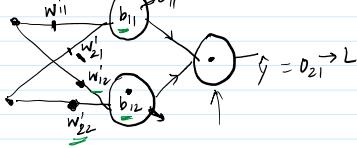
$\frac{\partial L}{\partial W_{11}} = -2(y - \hat{y}) O_{11}$

$\frac{\partial L}{\partial W_{21}} = -2(y - \hat{y}) O_{12}$

$\frac{\partial L}{\partial b_{11}} = -2(y - \hat{y})$

$$\frac{\partial L}{\partial w_{21}^2} = -2(y - \hat{y}) \delta_{12} \quad | \quad 2 \quad \begin{array}{c} \hat{y} \rightarrow b \\ \uparrow \\ L \end{array} \quad \frac{\partial \hat{y}}{\partial b_{21}} = 1$$

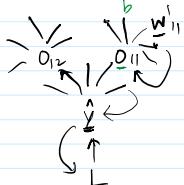
$$\frac{\partial L}{\partial b_{21}} = -2(y - \hat{y}) \quad | \quad 3 \quad \frac{\partial L}{\partial b_{21}} = \left[\frac{\partial L}{\partial \hat{y}} \right] \times \frac{\partial \hat{y}}{\partial b_{21}}$$



$$\frac{\partial L}{\partial w_{11}^2} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \delta_{11}} \frac{\partial \delta_{11}}{\partial w_{11}^2} \rightarrow [-2(y - \hat{y}) w_{11}^2 x_{11}] \quad 4$$

$$\frac{\partial L}{\partial w_{21}} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \delta_{12}} \frac{\partial \delta_{12}}{\partial w_{21}} \rightarrow [-2(y - \hat{y}) w_{21}^2 x_{12}] \quad 5$$

$$\frac{\partial L}{\partial b_{11}} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \delta_{11}} \frac{\partial \delta_{11}}{\partial b_{11}} \rightarrow [-2(y - \hat{y}) w_{11}^2] \quad 6$$



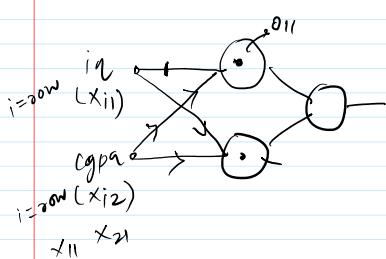
$$\frac{\partial L}{\partial w_{12}^2} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \delta_{12}} \frac{\partial \delta_{12}}{\partial w_{12}^2} \rightarrow [-2(y - \hat{y}) w_{12}^2 x_{12}] \quad 7$$

$$\frac{\partial L}{\partial w_{22}^2} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \delta_{12}} \frac{\partial \delta_{12}}{\partial w_{22}^2} \rightarrow [-2(y - \hat{y}) w_{22}^2 x_{12}] \quad 8$$

$$w_{11}^2$$

$$\frac{\partial \hat{y}}{\partial \delta_{12}} = w_{21}^2$$

$$\frac{\partial L}{\partial b_{12}} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \delta_{12}} \frac{\partial \delta_{12}}{\partial b_{12}} \rightarrow [-2(y - \hat{y}) w_{21}^2] \quad 9$$



$$\frac{\partial \delta_{11}}{\partial w_{11}^1} = \underbrace{\partial q_w w_{11}^1}_{\text{forward}} + \underbrace{\partial q_{pa} w_{21}^1 + b_{11}}_{\text{backward}} = (iq)$$

$$\frac{\partial \delta_{11}}{\partial w_{11}^1} = x_{11}$$

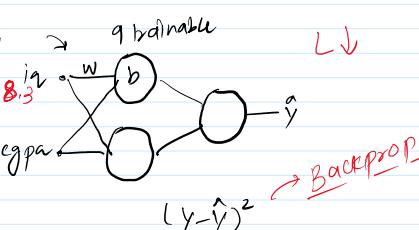
$$\frac{\partial \delta_{11}}{\partial b_{11}} = 1$$

$$\frac{\partial \delta_{12}}{\partial w_{12}^1} = \frac{\partial}{\partial w_{12}^1} [\underbrace{iq w_{12}^1}_{\text{forward}} + \underbrace{cgpa w_{22}^1 + b_{12}}_{\text{backward}}] = iq(x_{12})$$

$$\frac{\partial \delta_{12}}{\partial w_{22}^1} = x_{12}$$

$$\frac{\partial \delta_{12}}{\partial b_{12}} = 1$$

| | | multiple choice | |
|----------------|--------------------------------|-----------------|----|
| | | cgpa | iq |
| 1 | steps (once again) | random | 80 |
| 0 | weights/bias → init | w=1 | 80 |
| loop - 100/100 | b=0 | 6 | 60 |
| convex | i) for i in range(10): | 7 | 70 |
| | 1a) 1 student → forward prop → | 9 | 90 |



$$(y - \hat{y})^2$$

1a) 1 student → forward prop →

$$lpa \rightarrow 12 \text{ min}$$

1b) Loss calculate (mse) → .

1c) Adjust all weights and bias → .

The How

$$W_{new} = W_{old} - \eta \frac{\partial L}{\partial W_{old}}$$

Backpropagation Algorithm

epochs = 5

for i in range(epochs):

for j in range(x.shape[0]):

$$\frac{\partial L}{\partial w_{11}^2} = \underbrace{-2(y - \hat{y}) \delta_{11}}_{\text{Ready}}$$

$$\frac{\partial L}{\partial w_{21}^2} = \underbrace{-2(y - \hat{y}) \delta_{12}}_{\text{Ready}}$$

for i in range(epochs):

 for j in range(x.shape[0]):

 → Select 1 row (random)

 → Predict (using Forward prop)

 → Calculate loss (using Loss function → mse)

 → Update weights and bias using GD

$$w_n = w_0 - \eta \frac{\partial L}{\partial w}$$

 → Calculate avg loss for the epoch

L_{avg}

$$\frac{\partial L}{\partial w_{21}} = -2(y - \hat{y}) o_{21} \quad \checkmark$$

$$\frac{\partial L}{\partial b_{21}} = -2(\hat{y} - y) \quad \checkmark$$

$$\frac{\partial L}{\partial w_{11}} = -2(y - \hat{y}) w_{11}^2 x_{11} \quad \checkmark$$

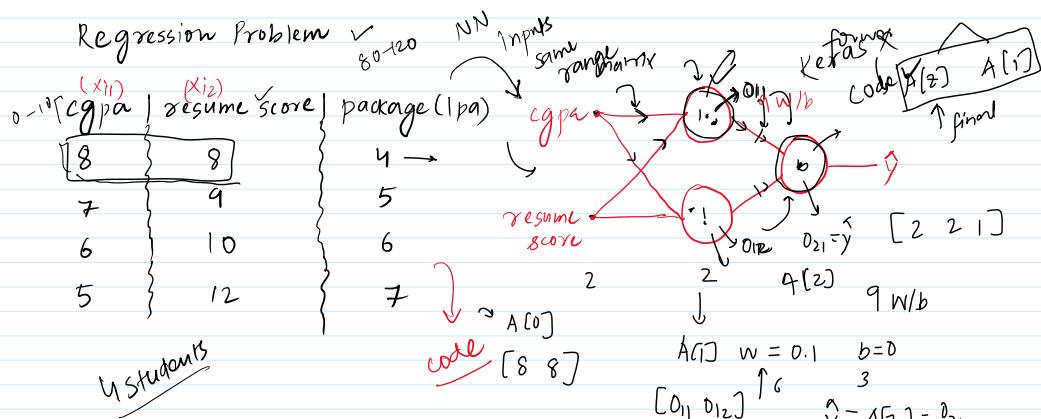
$$\frac{\partial L}{\partial w_{12}} = -2(y - \hat{y}) w_{12}^2 x_{12} \quad \checkmark$$

$$\frac{\partial L}{\partial b_{11}} = -2(y - \hat{y}) w_{11}^2 \quad \checkmark$$

$$\frac{\partial L}{\partial w_{12}} = -2(y - \hat{y}) w_{12}^2 x_{12} \quad \checkmark$$

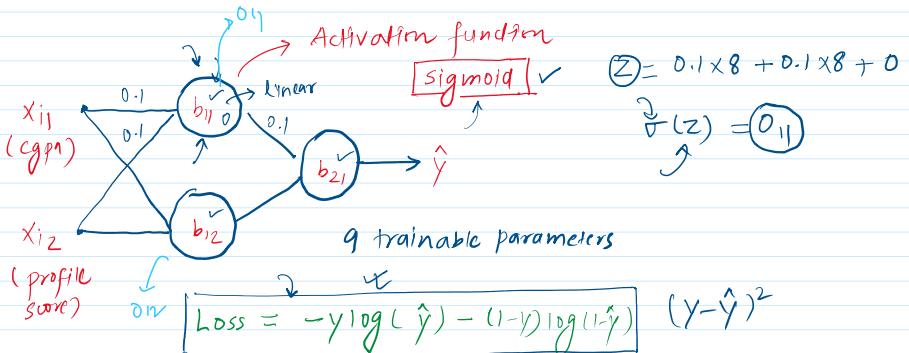
$$\frac{\partial L}{\partial w_{22}} = -2(y - \hat{y}) w_{22}^2 \quad \checkmark$$

$$\frac{\partial L}{\partial b_{12}} = -2(y - \hat{y}) w_{22}^2 \quad \checkmark$$



Classification Example

| cgpa | profile score | placement |
|------|---------------|-----------|
| 8 | 8 | 1 |
| 7 | 9 | 1 |
| 6 | 10 | 0 |
| 5 | 5 | 0 |



Backpropagation Algorithm

epochs = 5 ✓

for i in range(epochs): (rows)

 for j in range(x.shape[0]):

 → Select 1 row (random) → 1by1

 → Predict (using Forward prop) → predict

 → Calculate loss (using Loss function → bce) → code convert y

 → Update weights and bias using GD

Backpropagation Algorithm

epochs = 5 ✓

for i in range(epochs): (rows)

for j in range(x.shape[0]):

→ Select 1 row (random) → by

→ Predict (using Forward prop) → predict

→ Calculate loss (using Loss function → bce) → code convert

→ Update weights and bias using GD

$$w_n = w_0 - \eta \frac{\partial L}{\partial w}$$

q w, b update

→ Calculate avg loss for the epoch

Lavg

$$L = -y \log(\hat{y}) - (1-y) \log(1-\hat{y})$$

$$z = w_{11}^2 o_{11} + w_{21}^2 o_{12} + b_2$$

$$\hat{y} = \sigma(z)$$

der wrt z

$$\frac{\partial L}{\partial w_{11}} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z} \times \frac{\partial z}{\partial w_{11}} = -(y-\hat{y}) o_{11} \quad (1)$$

$$\frac{\partial L}{\partial w_{21}} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z} \times \frac{\partial z}{\partial w_{21}} = -(y-\hat{y}) o_{12} \quad (2)$$

$$\frac{\partial L}{\partial b_2} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z} \times \frac{\partial z}{\partial b_2} = -(y-\hat{y})$$

$$\boxed{\frac{\partial L}{\partial \hat{y}}} = \frac{\partial}{\partial \hat{y}} [-y \log(\hat{y}) - (1-y) \log(1-\hat{y})]$$

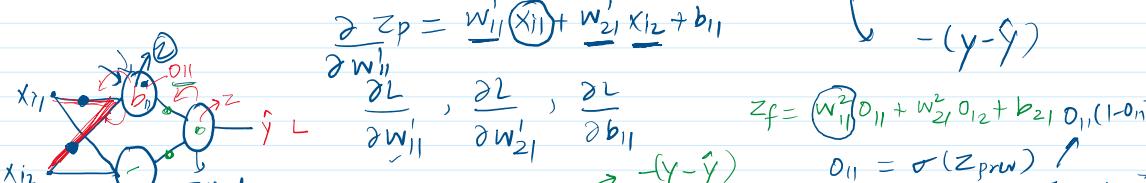
$$= -\frac{y}{\hat{y}} + \frac{(1-y)}{(1-\hat{y})} = \frac{-y(1-\hat{y}) + \hat{y}(1-y)}{\hat{y}(1-\hat{y})} = \frac{-y + y\hat{y} + \hat{y} - y\hat{y}}{\hat{y}(1-\hat{y})}$$

$$\hat{y} = \sigma(z) \quad \frac{\partial \sigma(z)}{\partial z} = \sigma(z)[1 - \sigma(z)] \quad \sigma(z) = \hat{y}$$

$$\boxed{\frac{\partial \hat{y}}{\partial z}} = \frac{\partial}{\partial z} (\sigma(z)) = \sigma(z)[1 - \sigma(z)] = \hat{y}(1-\hat{y})$$

$$\frac{\partial L}{\partial \hat{y}} = -\frac{(y-\hat{y})}{\hat{y}(1-\hat{y})} \quad \frac{\partial \hat{y}}{\partial z} = \hat{y}(1-\hat{y}) \Rightarrow \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z} = \frac{-(y-\hat{y}) \times \hat{y}(1-\hat{y})}{\hat{y}(1-\hat{y})} = -(y-\hat{y})$$

$$\frac{\partial z_p}{\partial w_{11}} = w_{11}' x_{11} + w_{21}' x_{12} + b_{11}$$



$$z_f = (w_{11}^2 o_{11} + w_{21}^2 o_{12} + b_2) o_{11} (1-o_{11})$$

$$o_{11} = \sigma(z_{pred})$$

cross entropy

$$z_f = w_{11}^2 o_{11} + w_{21}^2 o_{12} + b_{21} o_{11}(1-o_{11})$$

$$o_{11} = \sigma(z_{\text{prev}}) = \sigma(z_{\text{prev}})[1-\sigma(z_{\text{prev}})]$$

$$\frac{\partial L}{\partial w_{11}} = \left[\frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z_f} \right] \times \frac{\partial z_f}{\partial o_{11}} \times \frac{\partial o_{11}}{\partial z_{\text{prev}}} \times \frac{\partial z_{\text{prev}}}{\partial w_{11}} \rightarrow x_{i1}$$

\downarrow
 w_{11}^2
 \downarrow
 $o_{11}(1-o_{11})$

$$\boxed{\frac{\partial L}{\partial w_{11}} = -(y - \hat{y}) w_{11}^2 o_{11}(1-o_{11}) x_{i1}} \quad (3)$$

$$\boxed{\frac{\partial L}{\partial w_{21}} = -(y - \hat{y}) w_{21}^2 o_{12}(1-o_{12}) x_{i2}}$$

$$\boxed{\frac{\partial L}{\partial b_{11}} = -(y - \hat{y}) w_{11}^2 o_{11}(1-o_{11})}$$

$$\frac{\partial z_f}{\partial o_{12}} = w_{11}^2 o_{11} + w_{21}^2 o_{12} + b_{21} o_{12}(1-o_{12})$$

$$\frac{\partial L}{\partial w_{12}} = \left[\frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z_f} \right] \times \frac{\partial z_f}{\partial o_{12}} \times \frac{\partial o_{12}}{\partial z_p} \times \frac{\partial z_p}{\partial w_{12}} \rightarrow x_{i1}$$

\downarrow
 w_{21}^2
 \downarrow
 $o_{12}(1-o_{12})$

$$\boxed{\frac{\partial L}{\partial w_{12}} = -(y - \hat{y}) w_{21}^2 o_{12}(1-o_{12}) x_{i1}} \quad (3)$$

$$\boxed{\frac{\partial L}{\partial w_{22}} = -(y - \hat{y}) w_{21}^2 o_{12}(1-o_{12}) x_{i2}}$$

$$\boxed{\frac{\partial L}{\partial b_{12}} = -(y - \hat{y}) w_{21}^2 o_{12}(1-o_{12})}$$

Backpropagation → The Why?

The intuition behind the algorithm ✓

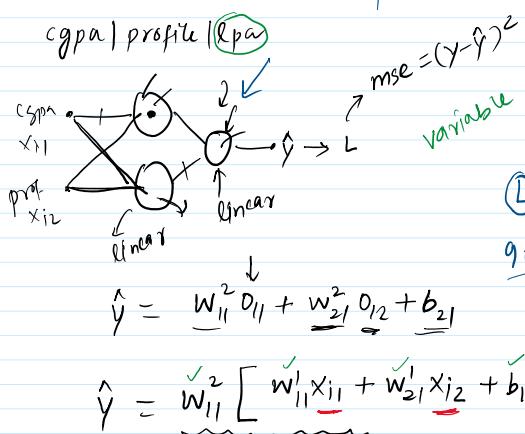
Backpropagation Algorithm

```

epochs = 5
for i in range(epochs):
    for j in range(x.shape[0]):
        → Select 1 row (random)
        → Predict (using Forward prop) →  $\hat{y}$ 
        → Calculate loss (using loss function → mse)
        → Update weights and bias using GD
             $W_n = W_0 - \eta \frac{\partial L}{\partial W}$  rule
            magic
        → Calculate avg loss for the epoch
             $L_{avg}$ 
    → bce

```

→ Loss function is a function of all trainable parameters



data → target

$$L = (y - \hat{y})^2$$

$$L = \frac{(y - \hat{y})^2}{\text{constant}}$$

mathematical function

$$L(\theta) = \frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$$

$$\frac{\partial L}{\partial \theta} = \frac{1}{n} \sum_{i=1}^n \frac{\partial}{\partial \theta} (y_i - f(x_i))^2$$

$$\frac{\partial L}{\partial \theta} = \frac{1}{n} \sum_{i=1}^n 2(y_i - f(x_i)) \cdot (-f'(x_i))$$

→ Concept of Gradient

Gradient descent

fancy word for derivative

$$y = f(x) = x^2 + x$$

$$\frac{dy}{dx} = \frac{d}{dx}(fx) = \frac{d}{dx}(x^2 + x) = 2x + 1$$

derivative

$y \rightarrow x \rightarrow$ derivative

$$\frac{d}{dx}$$

$$z = f(x, y) = x^2 + y^2$$

$$\frac{\partial z}{\partial x} = 2x \quad \frac{\partial z}{\partial y} = 2y$$

gradient

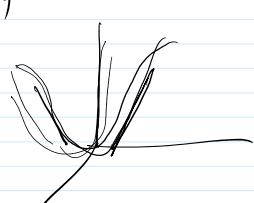
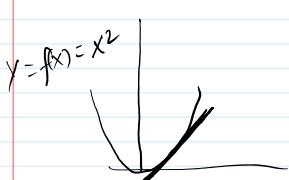
$$\left[\begin{array}{c} \frac{\partial z}{\partial x} \\ \frac{\partial z}{\partial y} \end{array} \right]$$

gradient complex

$$\frac{\partial L}{\partial w}, \frac{\partial L}{\partial b} \quad L(w_{11}', w_{12}', \dots, w_{21}', b_{11}, b_{12})$$

9D function → 9 diff slopes wrt each dim

$$3D \rightarrow z = x^2 + y^2 \quad z = f(x, y)$$



→ Concept of Derivative → Derivative
at or
point
intuition

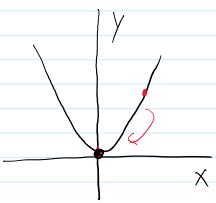
$$\frac{\partial L}{\partial w_i}$$

w_{11} — 1 unit
 $L \rightarrow ?$ (mag)
— (sign)

$$\begin{aligned} & \text{derivative} \\ & y = x^2 + 2x \quad \boxed{x=5} \rightarrow \text{deriv} \\ & \frac{dy}{dx} = (2x+1)_{x=5} \\ & \left(\frac{dy}{dx} \right)_{x=5} = \text{slope} \end{aligned}$$

$$W_{\text{act}} = W_{\text{old}} - \eta \frac{\partial L}{\partial w}$$

→ the concept of minima



$$Y = X^2$$

$$\frac{dy}{dx} = 2x = 0$$

\downarrow

$x=0$

L (9 param)
 w, b \min

L ↴ J

$$\frac{\partial L}{\partial w_{11}} \dots \frac{\partial L}{\partial b_{12}} = 0$$

9dim) minima

→ Backprop Intuition ↗ $\eta = 1$

$$W_{\text{new}} = W_{\text{old}} - \eta \frac{\partial L}{\partial W} \quad \xleftarrow{\text{q step}}$$

$$W_{new} = W_{old} - \frac{\partial L}{\partial W}$$

← each parameters

L =

constants

9
8
complain

$$\underline{L} \left(\frac{b_{21}}{\pi} \right)$$

$$b_{21} = \boxed{b_2} \quad \boxed{\frac{\partial L}{\partial b_{21}}} \quad b_{21} = 5 \text{ v/e}$$

$$\frac{\partial L}{\partial b_{21}} \xrightarrow{\text{Smart}} \begin{matrix} \text{L derivative w.r.t } b_{21} \\ \uparrow \\ ? \end{matrix}$$

LJ

$$\frac{\partial L}{\partial b_{21}} = -ve$$

game ... in line

-ve of the gradient

$$b_{21} + \frac{\partial L}{\partial b_{21}}$$

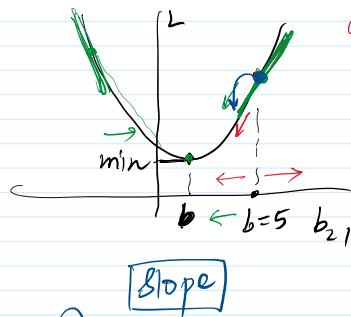
game derivative
(b_2)

-ve of the gradient

$$b_2 = b_2 - \frac{\partial L}{\partial b_2}$$

$$\frac{\partial L}{\partial b} = \text{slope}$$

+ve



$$\frac{\partial L}{\partial b} = -\text{ve}$$

slope (gradient)
↓ -ve

Slope

$$w_n = w_0 - \eta \frac{\partial L}{\partial w}$$

$$\eta$$

$$w_n = w_0 - \eta \frac{\partial L}{\partial w}$$

→ Effect of Learning Rate (η)

$$w_n = w_0 - \eta \frac{\partial L}{\partial w}$$

$$\frac{\partial L}{\partial b} = -50$$

$$b = -5 - (-50) = 45$$

$$b = 45$$

train

$$\eta = \text{parameter}$$

$$0.01$$

$$\eta = 0.00001$$

$$\frac{\partial L}{\partial b} = 50$$

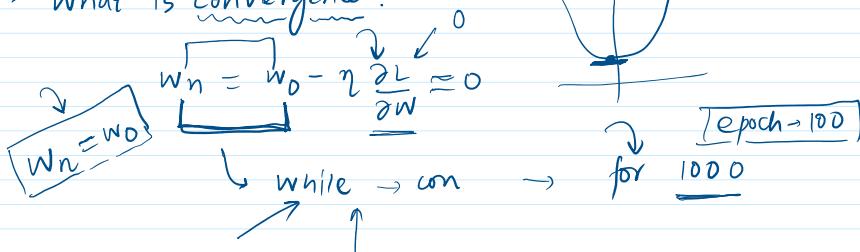
$$b = 45 - 50$$

$$b = -5 - 50 \eta = 0.01$$

$$b = -5 + (0.01 \times 50) = 0.5$$

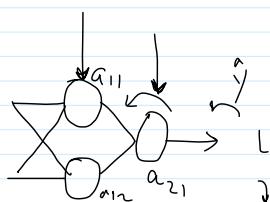
$$= -4.5$$

→ What is convergence?



$$i = 1, 0$$

activation = ②



$$-(y - \hat{y})$$

$$\hat{y}(1 - \hat{y}) O_{11}$$

$$-y \log(a_{21}) - (1-y) \log(1-a_{21})$$

$$-\frac{y}{\hat{y}} + \frac{(1-y)}{(1-\hat{y})}$$

$$\frac{\partial L}{\partial w_{11}} = \left[\frac{\partial L}{\partial a_{21}} \right] \times \frac{\partial a_{21}}{\partial w_{11}}$$

$$\frac{\partial L}{\partial w} =$$

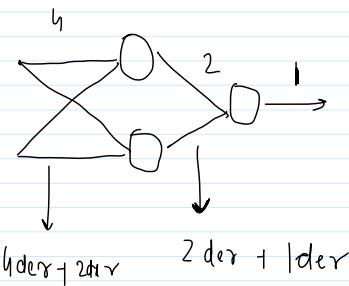
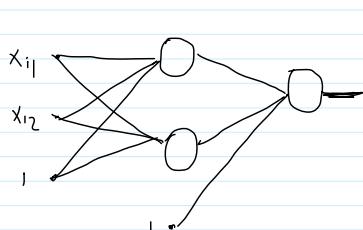
$$\frac{\partial L}{\partial w_{21}^2} = \text{curr_activa} = a[1]$$

$$\frac{\partial L}{\partial b_{21}} =$$

$$\delta_{1+a} = (y - \hat{y}) a^{(1)} (1 - a^{(1)})$$

$$W[1] \quad [1 \times 2]$$

$$\begin{aligned} & -\frac{y}{\hat{y}} + \frac{(1-y)}{(1-\hat{y})} \\ & \left. \begin{array}{l} -(\hat{y} - y) a_{21} (1 - a_{21}) a_{11} \\ -(\hat{y} - y) a_{21} (1 - a_{21}) a_{12} \\ -(\hat{y} - y) a_{21} (1 - a_{21}) \end{array} \right\} \\ & \boxed{-(\hat{y} - y) a_{21} (1 - a_{21})} * \begin{bmatrix} a[1] \\ a_{11} \\ a_{12} \end{bmatrix} \end{aligned}$$



$1 \times 1 \quad 1 \times 2$

$1 \times 2 \quad x \quad 2 \times 2$

$$\begin{bmatrix} a_{01} \\ a_{02} \end{bmatrix} \quad \begin{bmatrix} a_{11} \\ a_{12} \end{bmatrix} \quad \begin{bmatrix} a_{21} \end{bmatrix}$$

$\hookrightarrow Q_2 \rightarrow a_1 \rightarrow$

$$\frac{\partial L}{\partial a_2} \times \frac{\partial a_2}{\partial a_1} \frac{\partial a_1}{\partial w}$$

$$\frac{\partial L}{\partial w} = \boxed{\frac{\partial L}{\partial a_2}} \times \boxed{\frac{\partial a_2}{\partial w}}$$

$$\begin{bmatrix} \frac{\partial L}{\partial w_{11}^1} & \frac{\partial L}{\partial w_{12}^1} \\ \frac{\partial L}{\partial w_{21}^1} & \frac{\partial L}{\partial w_{22}^1} \end{bmatrix} \quad \begin{bmatrix} \frac{\partial L}{\partial w_{11}^2} \\ \frac{\partial L}{\partial w_{12}^2} \end{bmatrix}$$