Some Examples

1. Hello World!

3. Peterson Algorithm

It is a concurrent programming algorithm for mutual exclusion that allows two or more processes to share a single-use resource without conflict, using only shared memory for communication. It was formulated by Gary L. Peterson in 1981. While Peterson's original formulation worked with only two processes, the algorithm can be generalized for more than two.

The algorithm uses two variables, flag and turn. A flag[n] value of true indicates that the process n wants to enter the critical section. Entrance to the critical section is granted for process P0 if P1 does not want to enter its critical section or vice versa.

```
bool flag[2] = {false, false};
int turn;
                                         P1: flag[1] = true;
      flag[0] = true;
P0 gate: turn = 1;
                                         Pl gate: turn = 0;
        while (flag[1] == true δδ
                                                  while (flag[0] == true &&
turn == 1)
                                          turn == 0)
            // busy wait
                                                       // busy wait
         // critical section
                                                  // critical section
         // end of critical section
                                                   // end of critical section
         flag[\theta] = false;
                                                   flag[1] = false;
```

The algorithm

satisfies the three essential criteria: mutual exclusion, progress, and bounded waiting. In spin:

```
bool turn, flag[2];
byte ncrit;
active [2] proctype user()
       assert(_pid == 0 || _pid == 1);
again:
       flag[pid] = 1;
      turn = 1 - _pid;
       (flag[1 - _pid] == 0 || turn == _pid);
       ncrit++;
       assert(ncrit == 1); /* critical section */
       ncrit--;
       flag[_pid] = 0;
       goto again
}
4. Producer-Consumer Problem
mtype = { P,C }; /* symbols used */
mtype turn = P; /* shared variable */
active proctype producer(){
do
:: (turn == P) ->
/* Guard */
printf("Produce\n");
turn = C
od
}
active proctype consumer(){
again:
if
:: (turn == C) ->
/* Guard */
printf("Consume\n");
turn = P;
goto again
fi
5. Sender and Receiver Process
5.1: Message with one data item
chan x = [3] of \{ int \};
```

int turn = 0;

```
active proctype sender()
{
      x!3; x!2; x!1;
turn = 1;
       printf("sender process\n");
}
active proctype receiver()
       if
       :: (turn == 1) -> int var1, var2, var3;
                     x?var1; x?var2; x?var3;
printf("Receiver Process: %d %d %d\n",var1,var2,var3); fi
5.2: Message with multiple data items
chan x = [1] of \{ int , int \};
int turn = 0;
active proctype sender()
      x!3,2,1;
turn = 1;
       printf("sender process\n");
}
active proctype receiver()
{
       :: (turn == 1) -> int var1, var2, var3;
                     x?var1,var2,var3;
printf("receiver process: %d %d %d\n",var1,var2,var3); fi
5.2: Other channel operations
chan glob = [1] of { chan };
active proctype A(){
chan loc = [1] of { int }
int var;
glob!loc;
loc?var;
printf("Loc = %d\n",var);
active proctype B(){
chan who;
```

```
glob?who;
who!1000;
}
6. Alternating Bit Protocol
mtype = { msg, ack };
chan to_sndr = [2] of { mtype, bit };
chan to_rcvr = [2] of { mtype, bit };
active proctype Sender ()
{ bit seq_out=1, seq_in;
       do
       :: to_rcvr!msg (seq_out) ->
             to_sndr?ack (seq_in);
              :: seq_in == seq_out ->
                    printf("ack received\n"); seq_out = !seq_out
              :: else ->
                    printf("ack not received\n"); skip
             fi
       od
}
active proctype Receiver ()
{ bit seq_in;
       do
       :: to_rcvr?msg (seq_in) ->
             printf("msg received\n"); to_sndr!ack (seq_in)
       :: timeout ->
             printf("time out\n"); to_sndr!ack (seq_in)
```

od

}