

Gopal Sharma

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Education

University of Massachusetts, Amherst

PHD IN COMPUTER SCIENCE (GPA: 3.96 / 4.0)

Amherst, MA, USA

2017 - PRESENT

Indian Institute of Technology (IIT), Roorkee

B.TECH. IN ELECTRICAL ENGINEERING

Roorkee, India

2012 - 2016

Skills

- **Programming Languages:** Python, C++, Matlab/Octave, C
- **Scientific Computing:** Pytorch, TensorFlow, Keras, CuPy, Scipy, Scikit-Learn, OpenCV, Eigen, OpenMP
- **Tools:** Git, Emacs, \LaTeX , Visual Studio
- **Courses:** Machine Learning, Intelligent Visual Computing, Probabilistic Graphical Models, Deep Learning, Reinforcement Learning, Mathematical Statistics

Publications

CONFERENCE PAPERS

- *CSGNet: Neural Shape Parser for Constructive Solid Geometry* Sharma, Gopal, Goyal, Rishabh, Liu, Difan, Kalogerakis, Evangelos, and Maji, Subhansu ArXiv 2017
- *Persistent Aerial Tracking system for UAVs* Mueller, Matthias, Sharma, Gopal, Smith, Neil, and Ghanem, Bernard In 2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2016

Research Experience

Program Induction for Visual Domain

UMass

RESEARCH ASSISTANTSHIP

On going

- The aim of the project is to induce program for various visual domains like 2D image or 3D shapes using Reinforcement Learning. A version of the paper is available on Arxiv.

Exploring LSTMs for shape recognition

UMass

RESEARCH ASSISTANTSHIP

Sep 2016 Feb 2017

- The aim of the project is to exploit the sequential information present in uniformly rendered images from 3D shapes. We used LSTMs for processing sequentially rendered images for 3D shape recognition and retrieval tasks.

Activity recognition and Object tracking

KAUST

SUMMER INTERNSHIP

May July 2015

- **Activity recognition:** Developed code (C++, PYTHON and MATLAB) for activity recognition and scene understanding on the Activity-Net data-set, which aimed to find semantics between activity, object, and background scenes. Got experience of working with the following state-of-the-art algorithms on object detection like Fast RCNN and object proposals like Edge boxes and Bing.
- **Persistent Object tracking:** Experimentally demonstrated persistent object tracking methodology for swarm of UAVs. Developed a novel algorithm (C++ and PYTHON) to use object proposals (BING) for object tracking, based on the existing object trackers.

Word recognition in natural scene images

IIIT

SUMMER INTERNSHIP

May July 2016

- Developed algorithms based on CNNs and bidirectional LSTMs to detect and recognize words in unconstrained natural scenes.