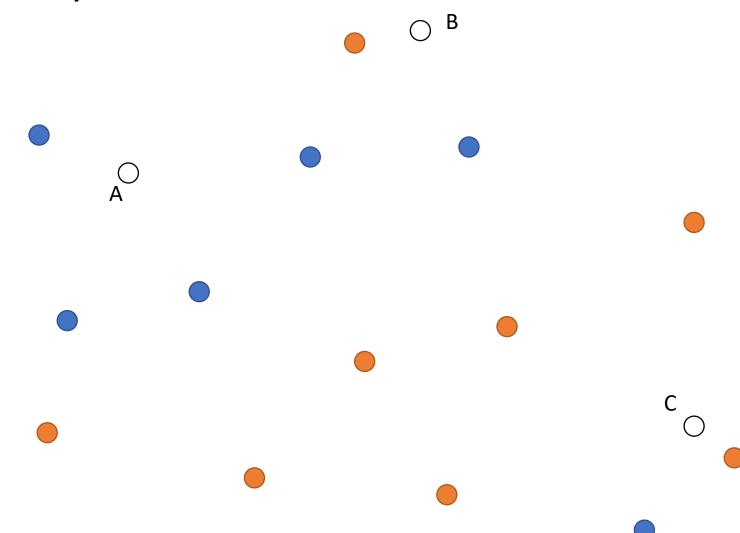
# Nearest Neighbor XX Classification

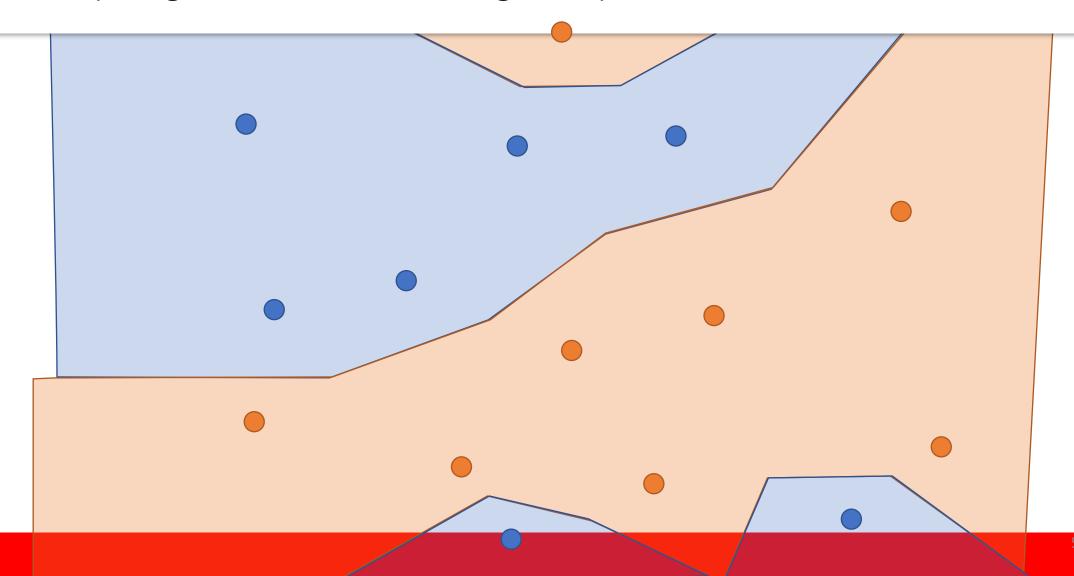
## How would you color the blank circles?



#### How would you color the blank circles?

If we based it on the color of their nearest  $\bigcirc$  B neighbors, we would get A: Blue B: Orange C: Orange

Training data partitions the entire instance space (using labels of nearest neighbors)



#### Nearest Neighbors: The basic version

- Training examples are vectors  $\mathbf{x}_i$  associated with a label  $y_i$
- Learning: Just store all the training examples
- Prediction for a new example x
  - Find the training example  $x_i$  that is *closest* to x
  - Predict the label of  $\mathbf{x}$  to the label  $y_i$  associated with  $\mathbf{x}_i$

#### K-Nearest Neighbors

- Training examples are vectors  $\mathbf{x}_i$  associated with a label  $y_i$
- Learning: Just store all the training examples
- Prediction for a new example x
  - Find the k closest training examples to x
  - Construct the label of x using these k points. How?
  - For classification: ?

#### K-Nearest Neighbors

- Training examples are vectors  $\mathbf{x}_i$  associated with a label  $y_i$
- Learning: Just store all the training examples
- Prediction for a new example x
  - Find the k closest training examples to x
  - Construct the label of x using these k points. How?
  - For classification: Every neighbor votes on the label. Predict the most frequent label among the neighbors.
  - For regression: ?

#### K-Nearest Neighbors

- Training examples are vectors  $\mathbf{x}_i$  associated with a label  $y_i$
- Learning: Just store all the training examples
- Prediction for a new example x
  - Find the k closest training examples to x
  - Construct the label of x using these k points. How?
  - For classification: Every neighbor votes on the label. Predict the most frequent label among the neighbors.
  - For regression: Predict the mean value

#### Distance between instances

• In general, a good place to inject knowledge about the domain

Behavior of this approach can depend on this

How do we measure distances between instances?

#### Distance between instances

#### Numeric features, represented as n dimensional vectors

Euclidean distance

$$||\mathbf{x}_1 - \mathbf{x}_2||_2 = \sqrt{\sum_{i=1}^n (\mathbf{x}_{1,i} - \mathbf{x}_{2,i})^2}$$

Manhattan distance

$$||\mathbf{x}_1 - \mathbf{x}_2||_1 = \sum_{i=1}^n |\mathbf{x}_{1,i} - \mathbf{x}_{2,i}|$$

- $L_p$ -norm
  - Euclidean =  $L_2$
  - Manhattan =  $L_1$
  - Exercise: What is  $L_{\infty}$ ?

$$||\mathbf{x}_1 - \mathbf{x}_2||_p = \left(\sum_{i=1}^n |\mathbf{x}_{1,i} - \mathbf{x}_{2,i}|^p\right)^{rac{1}{p}}$$

#### Advantages

- Training is *very fast* 
  - Just adding labeled instances to a list
  - More complex indexing methods can be used, which slow down learning slightly to make prediction faster
- Can learn very complex functions
- We always have the training data
  - For other learning algorithms, after training, we don't store the data anymore. What if we want to do something with it later...

#### Disadvantages

- Needs a lot of storage
  - Is this really a problem now?
- Prediction can be slow!
  - Naïvely: O(dN) for N training examples in d dimensions
  - More data will make it slower
  - Compare to other classifiers, where prediction is very fast

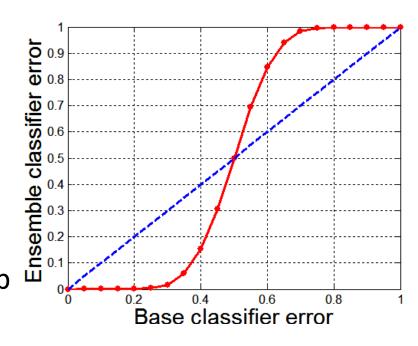
## Ensemble Classifiers \*\*

#### Ensemble Classifiers

- Given a training set  $D = \{ (x_i, y_i) \} (i=1,2,...,N)$ 
  - For binary classification, assume  $y_i \in \{-1, +1\}$
- Construct an ensemble of classification models  $f_1(x)$ ,  $f_2(x)$ , ...,  $f_k(x)$  from the training set
- Predict the class of an example x by combining the predictions made by the classifier ensemble, i.e.,  $f(x) = g[\Sigma_j \alpha_j f_j(x)]$ 
  - where g is a function to combine the individual predictions (e.g., sign function)

#### Why Ensemble Methods work?

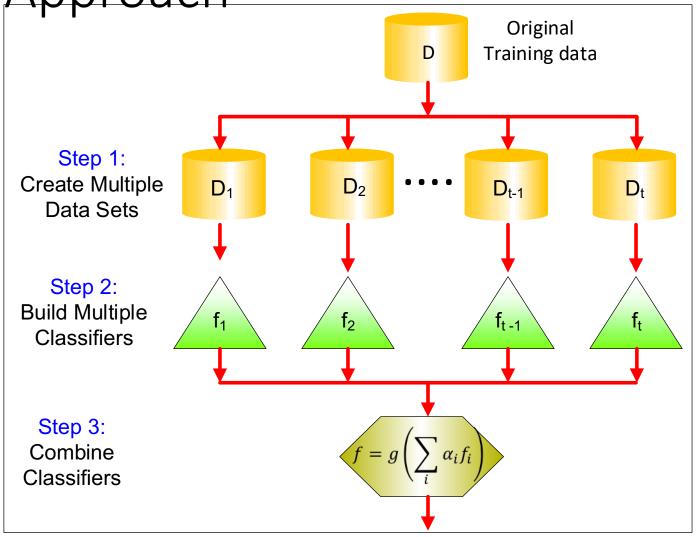
- Suppose there are 25 base classifiers
  - Each classifier has error rate,  $\varepsilon = 0.35$
  - Assume the errors made by the classifiers are <u>independent</u>
  - Probability that the ensemb classifier makes a wrong prediction:



X: number of classifiers that made a wrong prediction

$$P(X \ge 13) = \sum_{i=13}^{25} {25 \choose i} \varepsilon^{i} (1-\varepsilon)^{25-i} = 0.06 < 0.35$$

General Approach



## Bagging



#### Bagging

- Use bootstrap sampling (i.e., sampling with replacement) to create the multiple training sets
- Train a classifier on each bootstrap sample
  - Each sample has a probability  $1 (1 1/n)^n$  of being selected

Original Data	1	2	3	4	5	6	7	8	9	10	
Bagging (Round 1)	7	8	10	8	2	5	10	10	5	9	$f_1(x)$
Bagging (Round 2)	1	4	9	1	2	3	2	7	3	2	$\rightarrow f_2(x)$
Bagging (Round 3)	1	8	5	10	5	5	9	6	3	7	$\rightarrow f_3(x)$

• Prediction step (for Binary Classification): 
$$f(x) = \text{sign}[\ \Sigma_j f_j(x)\ ] = \int 1 \text{ if } \Sigma_j f_j(x) \ge 0$$
$$-1 \text{ otherwise}$$

#### Bagging Algorithm

#### Algorithm 5.6 Bagging Algorithm

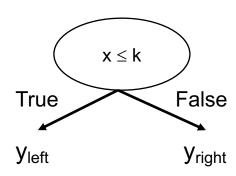
- Let k be the number of bootstrap samples.
- 2: for i = 1 to k do
- 3: Create a bootstrap sample of size n,  $D_i$ .
- Train a base classifier C<sub>i</sub> on the bootstrap sample D<sub>i</sub>.
- 5: end for
- 6:  $C^*(x) = \arg \max_y \sum_i \delta(C_i(x) = y)$ ,  $\{\delta(\cdot) = 1 \text{ if its argument is true, and } 0 \text{ otherwise.}\}$

Consider 1-dimensional data set:

#### **Original Data:**

X	0.1	0.2	0.3	0.4	0.5	0.6	0.7	8.0	0.9	1
У	1	1	1	-1	-1	-1	7	1	1	1

- Base classifier is a decision stump (a decision tree with a single node)
  - Decision rule:  $x \le k$  versus x > k
  - Split point k is chosen based on entropy



Baggir	ng Rour	nd 1:									
X	0.1	0.2	0.2	0.3	0.4	0.4	0.5	0.6	0.9	0.9	$x \le 0.35 \Rightarrow y = 1$
У	1	1	1	1	-1	-1	-1	-1	1	1	$x > 0.35 \rightarrow y = -1$
Baggir	ng Rour	nd 2:									
X	0.1	0.2	0.3	0.4	0.5	0.5	0.9	1	1	1	$x \le 0.7 \Rightarrow y = 1$
У	1	1	1	-1	-1	-1	1	1	1	1	$x > 0.7 \implies y = 1$
Baggir	ng Rour	nd 3:									
X	0.1	0.2	0.3	0.4	0.4	0.5	0.7	0.7	8.0	0.9	$x \le 0.35 \Rightarrow y = 1$
У	1	1	1	-1	-1	-1	-1	-1	1	1	$x > 0.35 \implies y = -1$
Baggir	ng Rour	nd 4:									
X	0.1	0.1	0.2	0.4	0.4	0.5	0.5	0.7	8.0	0.9	$x <= 0.3 \implies y = 1$
У	1	1	1	-1	-1	-1	-1	-1	1	1	$x > 0.3 \implies y = -1$
Baggir	ng Rour	nd 5:									
X	0.1	0.1	0.2	0.5	0.6	0.6	0.6	1	1	1	$x \le 0.35 \Rightarrow y = 1$
У	1	1	1	-1	-1	-1	-1	1	1	1	$x > 0.35 \rightarrow y = -1$
										-	

Baggiı	ng Rour	ıd 6:									
X	0.2	0.4	0.5	0.6	0.7	0.7	0.7	0.8	0.9	1	$x <= 0.75 \rightarrow y = -1$
у	1	-1	-1	-1	-1	-1	-1	1	1	1	$x > 0.75 \implies y = 1$
Baggiı	ng Rour	nd 7:									
X	0.1	0.4	0.4	0.6	0.7	0.8	0.9	0.9	0.9	1	$x \le 0.75 \Rightarrow y = -1$
У	1	-1	-1	-1	-1	1	1	1	1	1	$x > 0.75 \implies y = 1$
Baggiı	ng Rour	ıd 8:									_
X	0.1	0.2	0.5	0.5	0.5	0.7	0.7	0.8	0.9	1	$x <= 0.75 \rightarrow y = -1$
У	1	1	-1	-1	-1	-1	-1	1	1	1	$x > 0.75 \implies y = 1$
Baggiı	ng Rour	nd 9:									
X	0.1	0.3	0.4	0.4	0.6	0.7	0.7	0.8	1	1	$x <= 0.75 \rightarrow y = -1$
У	1	1	-1	-1	-1	-1	-1	1	1	1	$x > 0.75 \implies y = 1$
Baggiı	ng Rour	nd 10:									
X	0.1	0.1	0.1	0.1	0.3	0.3	8.0	8.0	0.9	0.9	$x \le 0.05 \Rightarrow y = 1$ $x > 0.05 \Rightarrow y = 1$
У	1	1	1	1	1	1	1	1	1	1	x > 0.03 <del>-y</del> y - 1

• Summary of training sets:

Round	Split Point	Left Class	Right Class
1	0.35	1	-1
2	0.7	1	1
3	0.35	1	-1
4	0.3	1	-1
5	0.35	1	-1
6	0.75	-1	1
7	0.75	-1	1
8	0.75	-1	1
9	0.75	-1	1
10	0.05	1	1

- Suppose the test set is the same as training set
- Use majority vote to determine class of ensemble classifier:  $y_i$  = sign[  $f(x_i)$  ] = sign[  $\Sigma_i f_i(x_i)$  ]

Round	x=0.1	x=0.2	x=0.3	x=0.4	x=0.5	x=0.6	x=0.7	x=0.8	x=0.9	x=1.0
1	1	1	1	-1	-1	-1	-1	-1	-1	-1
2	1	1	1	1	1	1	1	1	1	1
3	1	1	1	-1	-1	-1	-1	-1	-1	-1
4	1	1	1	-1	-1	-1	-1	-1	-1	-1
5	1	1	1	-1	-1	-1	-1	-1	-1	-1
6	-1	-1	-1	-1	-1	-1	-1	1	1	1
7	-1	-1	-1	-1	-1	-1	-1	1	1	1
8	-1	-1	-1	-1	-1	-1	-1	1	1	1
9	-1	-1	-1	-1	-1	-1	-1	1	1	1
10	1	1	1	1	1	1	1	1	1	1
Sum	2	2	2	-6	-6	-6	-6	2	2	2
Sign	1	1	1	-1	-1	-1	-1	1	1	1

Predicted Class

## Boosting $\prec$

#### Boosting

- Similar to bagging:
  - Ensemble is created by resampling the training data
- Resampling procedure is different from bagging
  - In bagging, each example has equal probability of being selected to form the training set (at every bagging round)
    - In boosting, each training example is assigned a weight  $w_i$  (initially, all examples have equal weights; but the weights are changed after each boosting round)
    - Boosting adaptively changes the distribution of training data by focusing more on examples that are hard to classify
  - Final classifier:  $f^*(x) = \sum_j \alpha_j f_j(x)$ 
    - In boosting,  $\alpha_i$  measures the "importance" of model  $f_i(x)$
    - In bagging,  $\alpha_i = 1$  for all j's

#### Boosting

- After each boosting round
  - Examples that are wrongly classified will have their weights increased
  - Examples that are classified correctly will have their weights decreased

Original Data	1	2	3	4	5	6	7	8	9	10
<b>Boosting (Round 1)</b>	7	3	2	8	7	9	4	10	6	3
<b>Boosting (Round 2)</b>	5	4	9	4	2	5	1	7	4	2
<b>Boosting (Round 3)</b>	(4)	(4)	8	10	(4)	5	(4)	6	3	(4)

- Example 4 is hard to classify
- Its weight is increased so that it is more likely to be chosen again in subsequent rounds

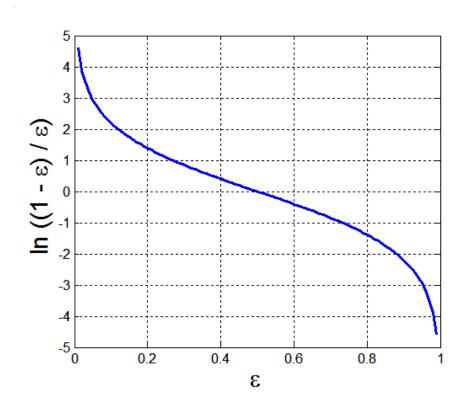
#### AdaBoost

- Let f<sub>1</sub>, f<sub>2</sub>, ..., f<sub>T</sub> be the base models
- Each training example has a weight  $w_i$
- Error rate for model f<sub>t</sub>:

$$\varepsilon_t = \sum_{j=1}^N w_j \delta(f_t(x_j) \neq y_j)$$

• Importance of model f<sub>t</sub>

$$\alpha_t = \frac{1}{2} \ln \left( \frac{1 - \varepsilon_t}{\varepsilon_t} \right)$$



#### AdaBoost Algorithm

- 1. Assign uniform weights to all the data points
- 2. Repeat until maximum iteration is reached
  - Create a training set D<sub>t</sub> by sampling the data points according to their weights
  - Train a new model f<sub>t</sub> based on D<sub>t</sub>
  - Apply  $f_t$  to the training set and calculate its error rate  $e_t$  and importance factor  $\alpha_t$
  - Update the weights for all data points
    - Increase the weight of misclassified data points
    - Decrease the weight of correctly classified data points

#### Weight Update in AdaBoost

• Weight update:

$$w_i^{(j+1)} = \frac{w_i^{(j)}}{Z_j} \begin{cases} \exp^{-\alpha_j} & \text{if } f_j(x_i) = y_i \\ \exp^{\alpha_j} & \text{if } f_j(x_i) \neq y_i \end{cases}$$
$$= \frac{w_i^{(j)}}{Z_j} \exp^{-\alpha_j y_i f_j(x_i)}$$

where  $Z_i$  is the normalization factor

 If any intermediate rounds produce an error rate higher than 50%, the weights are reverted back to 1/N and the resampling procedure is repeated

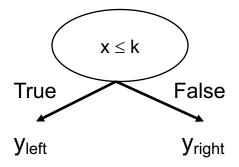
#### AdaBoost Example

• Consider 1-dimensional data set:

#### **Original Data:**

X	0.1	0.2	0.3	0.4	0.5	0.6	0.7	8.0	0.9	1
У	1	1	1	-1	-1	-1	1	1	1	1

- Classifier is a decision stump
  - Decision rule:  $x \le k$  versus x > k
  - Split point k is chosen based on entropy



#### AdaBoost Example

• Training sets for the first 3 boosting rounds:

Boostii	Boosting Round 1:											
X	0.1	0.4	0.5	0.6	0.6	0.7	0.7	0.7	8.0	1		
У	1	-1	-1	-1	-1	-1	-1	-1	1	1		
Boostii	ng Roui	nd 2:										
X	0.1	0.1	0.2	0.2	0.2	0.2	0.3	0.3	0.3	0.3		
У	1	1	1	1	1	1	1	1	1	1		
Boostii	ng Roui	nd 3:										
X	0.2	0.2	0.4	0.4	0.4	0.4	0.5	0.6	0.6	0.7		
У	1	1	-1	-1	-1	-1	-1	-1	-1	-1		
							•	•		•		

• Summary:

Round	Split Point	Left Class	Right Class	alpha
1	0.75	-1	1	1.738
2	0.05	1	1	2.7784
3	0.3	1	-1	4.1195

#### AdaBoost Example

Weights

Round	x=0.1	x=0.2	x = 0.3	x=0.4	x=0.5	x = 0.6	x=0.7	x=0.8	x = 0.9	x = 1.0
1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1
2	0.311	0.311	0.311	0.01	0.01	0.01	0.01	0.01	0.01	0.01
3	0.029	0.029	0.029	0.228	0.228	0.228	0.228	0.009	0.009	0.009

Classification

Round	x=0.1	x=0.2	x = 0.3	x=0.4	x=0.5	x=0.6	x=0.7	x=0.8	x=0.9	x=1.0
1	-1	-1	-1	-1	-1	-1	-1	1	1	1
2	1	1	1	1	1	1	1	1	1	1
3	1	1	1	-1	-1	-1	-1	-1	-1	-1
Sum	5.16	5.16	5.16	-3.08	-3.08	-3.08	-3.08	0.397	0.397	0.397
Sign	1	1	1	-1	-1	-1	-1	1	1	1

Predicted Class

#### Summary of Ensemble Methods

- Very powerful
  - Generally outperforms most of the single classifier methods
- More expensive to train
  - Bagging is easier to parallelize
  - Boosting is harder due to serial dependencies between models ( $f_t$  depends on  $f_{t-1}$ )
- Reduce bias and variance of classifiers

#### Bias and Variance of a Classifier

- Bias is high if classifier is too simple or makes a strong assumption
  - Example: linear classifiers
- Variance is high if model is sensitive to the choice of the training set
  - Example: nearest-neighbor classifiers

#### Practical Guide for Users

- What to do if your classification results are poor?
  - 1. Check for model overfitting/underfitting
    - If overfit:
      - Do more careful model selection to reduce model complexity
      - Eliminate noisy/ correlated features
      - Increase training set size by collecting more labeled examples
    - If underfit:
      - Add more discriminative features
      - Use more flexible models (e.g., nonlinear instead of linear models)

#### Practical Guide for Users

- What to do if your classification results are poor?
  - 2. Check data quality and algorithm execution
    - Are there a lot of mislabeled examples?
    - Are there lots of missing values?
    - Are the features correlated/irrelevant/noisy?
    - Has the learning algorithm converged?
    - Is the optimization procedure used suitable for the data? Is the error function appropriate?
    - Don't just rely on the default parameters of algorithm

#### Practical Guide for Users

- What to do if your classification results are poor?
  - 3. Check for model bias and variance
    - High bias: train error is high; test error ≈ train error
    - High variance: train error varies significantly when you apply cross-validation or repeated holdout
    - In both cases, ensemble methods generally help