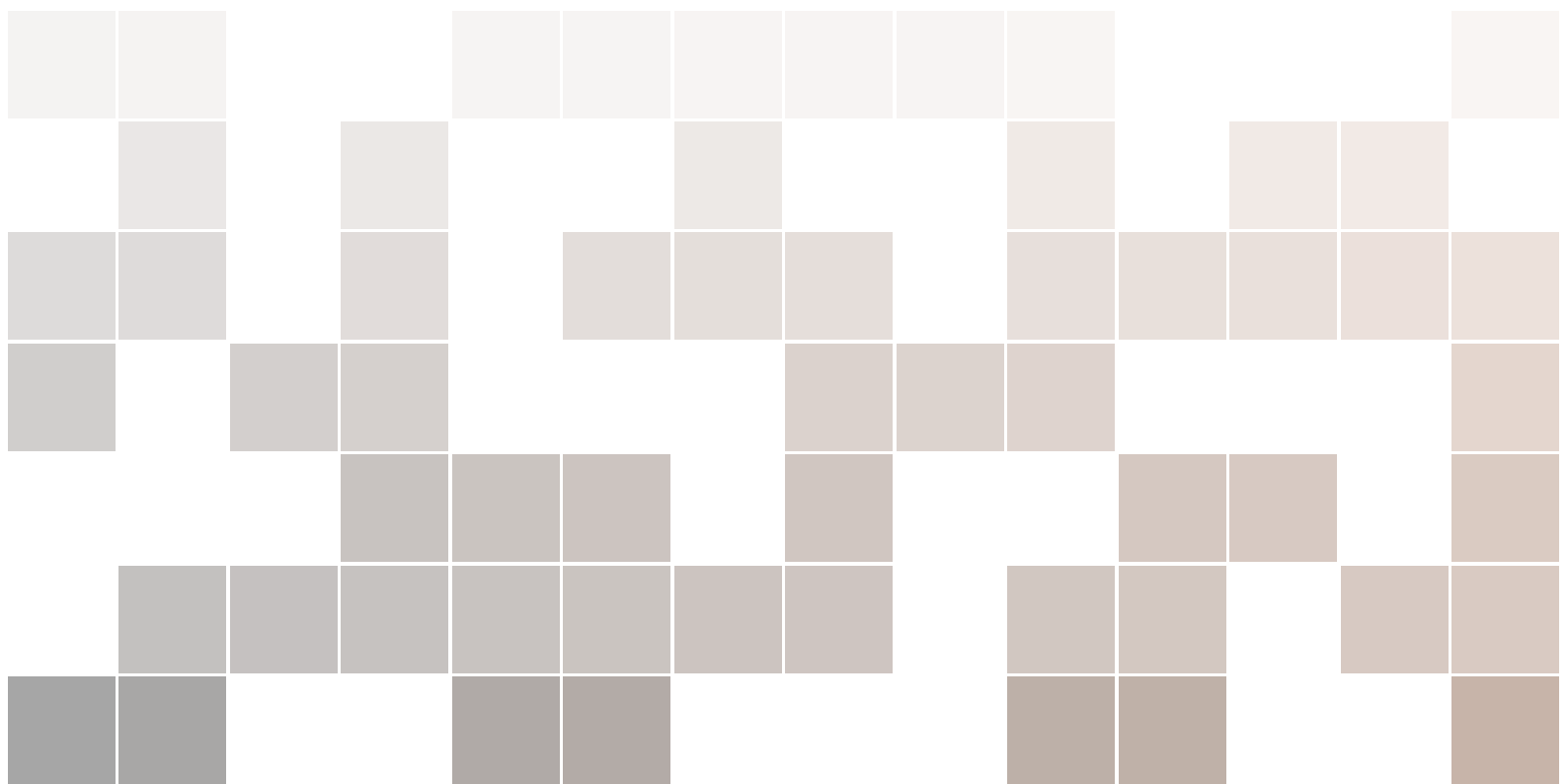


Particle Physics

Review for Particle Physics

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CONTENTS

Chapter 1	Analytical Mechanics	Page 2
1.1	Functional Derivative	2
	Definition — 2 • Two function case — 3 • Euler-Lagrange Equation — 4 • Important Property — 5	
1.2	Lagrange Formalism	5
	Quick Recap: Newtonian Mechanics — 5 • Lagrangian and Euler-Lagrange Equation — 6	
1.3	Hamiltonian Formalism	6

Chapter 2	Quantum Mechanics	Page 7
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Analytical Mechanics

1.1 Functional Derivative

1.1.1 Definition

Consider a quantity I defined as follows:

$$I := \int_A^B dx F(x) \quad (1.1)$$

Notice that I is not really a function of x , but if you had to say, it is more a "function" of F - may be $F(x) = e^x$, or $F(x) = ax^2 + bx + c$, or, etc. So, to denote the dependence of I on the function F , we write

$$I[f] := \int_A^B dx F(x) \quad (1.2)$$

This is called a functional. Now, imagine that F is a function of f , for example, $F[f] = f(x)^2$. By chain rule, a small change in F , denoted as δF , can be expressed as:

$$\delta F[f] = F[f + \delta f] - F[f] \quad (1.3)$$

$$= \frac{\partial F}{\partial f} \delta f \quad (1.4)$$

so, similarly,

$$\delta I[F] = I[F + \delta F] - I[F] \quad (1.5)$$

$$= \int_A^B dx \delta F[f] \quad (1.6)$$

$$= \int_A^B dx \frac{\partial F}{\partial f} \delta f \quad (1.7)$$

Then, the functional derivative of I with respect to f , $\frac{\delta I}{\delta f}$, is defined as follows:

Definition 1.1.1: Functional Derivative

If a function $X(x)$ exists, such that

$$\delta I = \int_A^B dx X(x) \delta f(x), \quad (1.8)$$

we say that $X(x)$ is the functional derivative of I with respect to f , and denote it as

$$\frac{\delta I}{\delta f} := X(x) \iff \delta I := \int_B^A dx \frac{\delta I}{\delta f} \delta f. \quad (1.9)$$

1.1.2 Two function case

Consider a case where I is the functional of F , which is also a functional of f and g :

$$I[F[f, g]] = \int_B^A dx F[f(x), g(x)] \quad (1.10)$$

Or more generally, if a function $D(x)$ satisfies the following Now, let us add some small change of f , δf :

$$I[F[f + \delta f, g]] = \int_B^A dx F[f(x) + \delta f(x), g(x)] \quad (1.11)$$

$$= \int_B^A dx F[f, g] + \frac{\partial F}{\partial f} \delta f \quad (1.12)$$

and similarly, by adding δg ,

$$I[F[f, g + \delta g]] = \int_B^A dx F[f(x), g(x) + \delta g(x)] \quad (1.13)$$

$$= \int_B^A dx F[f, g] + \frac{\partial F}{\partial g} \delta g \quad (1.14)$$

Combining these two, we have

$$I[F[f + \delta f, g + \delta g]] = \int_B^A dx F[f(x) + \delta f(x), g(x) + \delta g(x)] \quad (1.15)$$

$$= \int_B^A dx F[f, g] + \frac{\partial F}{\partial f} \delta f + \frac{\partial F}{\partial g} \delta g \quad (1.16)$$

$$\implies I[F[f + \delta f, g + \delta g]] - I[F[f, g]] = \int_B^A dx \frac{\partial F}{\partial f} \delta f + \frac{\partial F}{\partial g} \delta g \quad (1.17)$$

In this case, we just like our normal derivative, we should denote the LHS as:

$$\delta I := \int_B^A dx \frac{\partial F}{\partial f} \delta f + \frac{\partial F}{\partial g} \delta g \quad (1.18)$$

or alternatively,

$$\delta I := \int_B^A dx \frac{\delta I}{\delta f} \delta f + \frac{\delta I}{\delta g} \delta g \quad (1.19)$$

1.1.3 Euler-Lagrange Equation

For the two function case, especially consider that $g = \frac{df}{dx}$, and let us see what happens. Specifically, let us set that $\delta f(A) = \delta f(B) = 0$. Then, we have:

$$\frac{\delta I}{\delta g} \delta g = \frac{\delta I}{\delta \frac{df}{dx}} \delta \frac{df}{dx} \quad (1.20)$$

we can change the order of the derivative:

$$= \frac{\delta I}{\delta \frac{df}{dx}} \frac{d \delta f}{dx} \quad (1.21)$$

from the differentiation of a product, we have

$$= \frac{d}{dx} \left(\frac{\delta I}{\delta \frac{df}{dx}} \delta f \right) - \frac{d}{dx} \frac{\delta I}{\delta \frac{df}{dx}} \delta f \quad (1.22)$$

Now, substituting this to the two function case, we get:

$$\delta I = \int_B^A dx \left[\left(\frac{\delta I}{\delta f} - \frac{d}{dx} \frac{\delta I}{\delta \frac{df}{dx}} \right) \delta f + \frac{d}{dx} \left(\frac{\delta I}{\delta \frac{df}{dx}} \delta f \right) \right] \quad (1.23)$$

the total derivative term is zero, since $\delta f(A) = \delta f(B) = 0$. Thus, we have

$$\delta I = \int_B^A dx \left(\frac{\delta I}{\delta f} - \frac{d}{dx} \frac{\delta I}{\delta \frac{df}{dx}} \right) \delta f \quad (1.24)$$

and since $I = \int_B^A dx F[f(x), g(x)]$, we can say that

$$\frac{\partial F}{\partial f} = \frac{\delta I}{\delta f}, \quad \frac{\partial F}{\partial g} = \frac{\delta I}{\delta g} \quad (1.25)$$

Then

$$\delta I = \int_B^A dx \left(\frac{\partial F}{\partial f} - \frac{d}{dx} \frac{\partial F}{\partial \frac{df}{dx}} \right) \delta f \quad (1.26)$$

And if we somehow want to find a minimum of I , we can set $\delta I = 0$:

$$\implies \frac{\partial F}{\partial f} - \frac{d}{dx} \frac{\partial F}{\partial \frac{df}{dx}} = 0 \quad (1.27)$$

This is called the Euler-Lagrange equation.

1.1.4 Important Property

In general, consider that the functional F is a function of f_1, f_2, \dots, f_n :

$$F[f_1, f_2, \dots, f_n] \implies \delta F = \sum_{j=1}^n \frac{\partial F}{\partial f_j} \delta f_j \quad (1.28)$$

$$(1.29)$$

1.2 Lagrange Formalism

1.2.1 Quick Recap: Newtonian Mechanics

In Newtonian mechanics, the motion of a particle is described through a few important quantities: for a particle of (inertial) mass m , position \vec{r} , we have

$$\text{velocity : } \vec{v} = \frac{d\vec{r}}{dt} \quad (1.30)$$

$$\text{acceleration : } \vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2} \quad (1.31)$$

$$\text{momentum : } \vec{p} = m\vec{v} = m \frac{d\vec{r}}{dt} \quad (1.32)$$

and the relations between these quantities, in the presence of external forces $\vec{F}_{\text{ext}}^{(i)}$ acting on the particle, are given by Newton's second law:

$$\frac{d\vec{p}}{dt} = m \frac{d^2\vec{r}}{dt^2} = \sum_i \vec{F}_{\text{ext}}^{(i)} \quad (1.33)$$

The work done by such forces is given by

$$W_{\text{total}} = \sum_i \int_l d\vec{x} \cdot \vec{F}_{\text{ext}}^{(i)}, \quad \text{where } l \text{ is the path of the particle.} \quad (1.34)$$

This is the energy change of the particle through the motion:

$$W_{\text{total}} = \sum_i \int_l d\vec{x} \cdot \vec{F}_{\text{ext}}^{(i)} \quad (1.35)$$

$$= \int_{t_i}^{t_f} dt \vec{v} \cdot m \frac{d\vec{v}}{dt} \quad (1.36)$$

$$= \int_{t_i}^{t_f} dt \frac{m}{2} \frac{d}{dt} \vec{v}^2 \quad (1.37)$$

$$= \frac{m}{2} \vec{v}_f^2 - \frac{m}{2} \vec{v}_i^2 \quad (1.38)$$

1 Analytical Mechanics

meaning that $m\vec{v}^2/2$ is the energy due to the motion of the particle: the kinetic energy T :

$$T = \frac{m}{2} \vec{v}^2 \quad (1.39)$$

Now, often, the external force acting on the particle is due to a potential V :

$$\vec{F}_{\text{ext}} = -\nabla V \quad (1.40)$$

For example, for a 1D spring, the potential is given by

Example 1.2.1 (1D spring/ Harmonic potential)

$$V = \frac{1}{2} kx^2 \implies F_{\text{ext}} = -kx \quad (1.41)$$

or the electrostatic potential:

Example 1.2.2 (Electrostatic potential)

$$V = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r} \implies F_{\text{ext}} = -\nabla V = -\frac{q_1 q_2}{4\pi\epsilon_0 r^2} \hat{r} \quad (1.42)$$

1.2.2 Lagrangian and Euler-Lagrange Equation

Let us define quantities called the Lagrangian L and action S :

$$L := T - V, \quad S := \int_{t_i}^{t_f} dt L \quad (1.43)$$

For one particle, the Lagrangian in general contains the position $q_i(t)$ and velocity $\dot{q}_i(t)$ and time t :

$$L = L(q_i, \dot{q}_i, t) \quad (1.44)$$

The action is then given by

$$S = \int_{t_i}^{t_f} dt L(q_i(t), \dot{q}_i(t), t) \quad (1.45)$$

1.3 Hamiltonian Formalism

Chapter

2

Quantum Mechanics