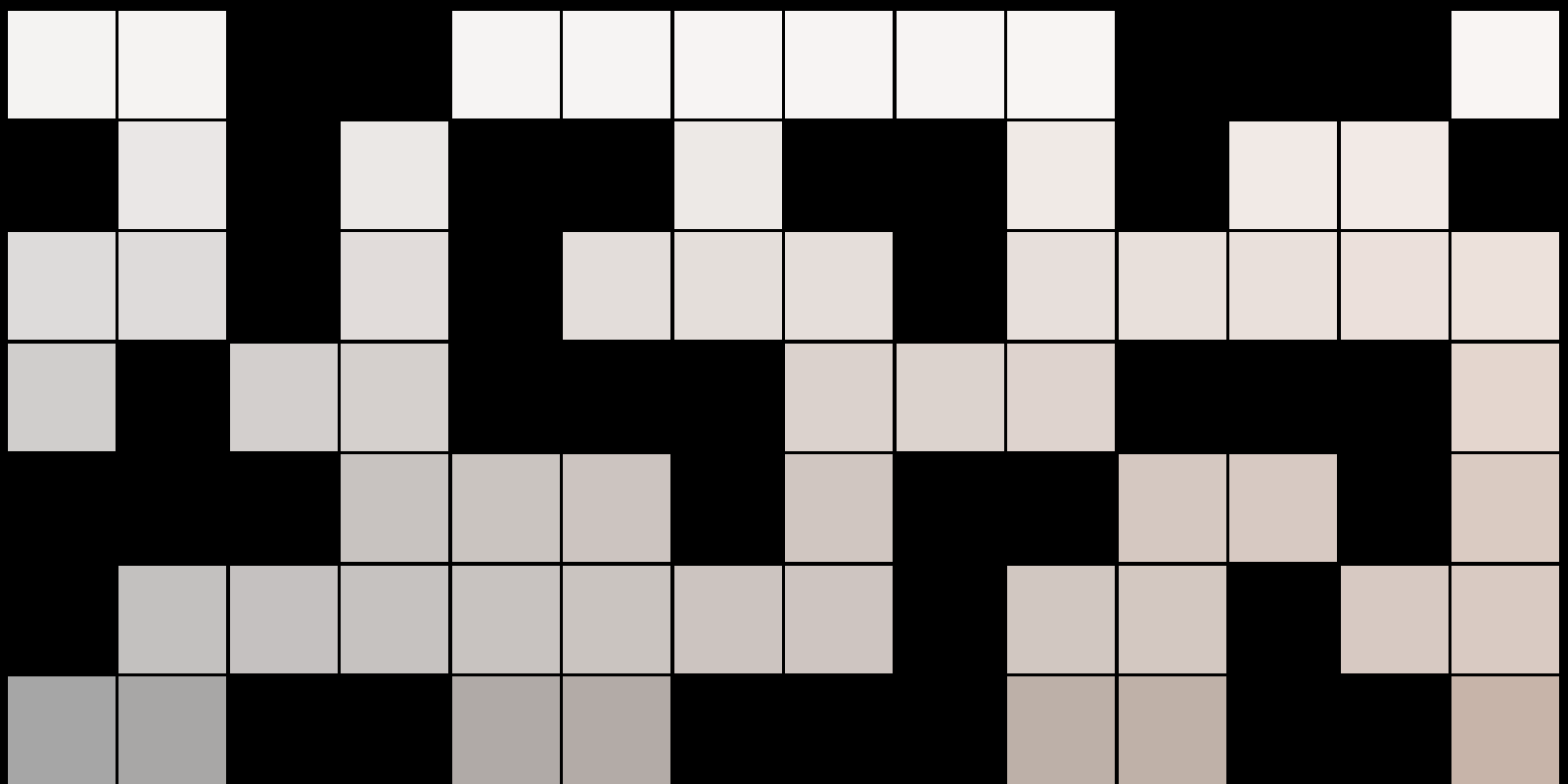


Particle Physics

Review for Particle Physics

Name:

ID:



CONTENTS

CHAPTER 1 Mathematical Remarks Page 2

- 1.1 Functional Derivative 2
Definition — 2 • Two function case — 3 • Euler-Lagrange Equation — 4 • Important
Property — 5 • In a n -dimensional space — 6

CHAPTER 2 Physics of Fields Page 8

- 2.1 Hamilton Formalism 8
Legendre Transformation — 8 • Canonical Equations of Fields — 9 • Poisson Bracket —
10

Mathematical Remarks

1.1 Functional Derivative

1.1.1 Definition

Consider a quantity I defined as follows:

$$I := \int_A^B dx F(x) \quad (1.1)$$

Notice that I is not really a function of x , but if you had to say, it is more a "function" of F - may be $F(x) = e^x$, or $F(x) = ax^2 + bx + c$, or, etc. So, to denote the dependence of I on the function F , we write

$$I[f] := \int_A^B dx F(x) \quad (1.2)$$

This is called a **(linear) functional**. Now, imagine that F is a function of f , for example, $F[f] = f(x)^2$. By chain rule, a small change in F , denoted as δF , can be expressed as:

$$\delta F[f] = F[f + \delta f] - F[f] \quad (1.3)$$

$$= \frac{\partial F}{\partial f} \delta f \quad (1.4)$$

so, similarly,

$$\delta I[F] = I[F + \delta F] - I[F] \quad (1.5)$$

$$= \int_A^B dx \delta F[f] \quad (1.6)$$

$$= \int_A^B dx \frac{\partial F}{\partial f} \delta f \quad (1.7)$$

Then, the **functional derivative** of I with respect to f , $\frac{\delta I}{\delta f}$, is defined as follows:

Definition 1.1: Functional Derivative

If a function $\phi(x)$ exists, such that

$$\delta I = \int_A^B dx \phi(x) \delta f(x), \quad (1.8)$$

we say that $\phi(x)$ is the **functional derivative** of I with respect to f , and denote it as

$$\frac{\delta I}{\delta f(x)} := \phi(x) \iff \delta I := \int_B^A dx \frac{\delta I}{\delta f(x)} \delta f(x). \quad (1.9)$$

Immediatly, by comparing Eq.(1.9) and Eq.(1.7), we see the following relation:

Theorem 1.1.1 Functional-density relation

For a quantity $I[F]$ and its density $F[f(x)]$, the functional derivative satisfies the following relation:

$$I = \int_A^B dx F[f(x)] \implies \frac{\delta I}{\delta f(x)} = \frac{\partial F[f(x)]}{\partial f(x)} \quad (1.10)$$

1.1.2 Two function case

Consider a case where I is the functional of F , which is also a functional of f and g :

$$I[F[f, g]] = \int_B^A dx F[f(x), g(x)] \quad (1.11)$$

Or more generally, if a function $D(x)$ satisfies the following Now, let us add some small change of f , δf :

$$I[F[f + \delta f, g]] = \int_B^A dx F[f(x) + \delta f(x), g(x)] \quad (1.12)$$

$$= \int_B^A dx F[f, g] + \frac{\partial F}{\partial f} \delta f \quad (1.13)$$

and similarly, by adding δg ,

$$I[F[f, g + \delta g]] = \int_B^A dx F[f(x), g(x) + \delta g(x)] \quad (1.14)$$

$$= \int_B^A dx F[f, g] + \frac{\partial F}{\partial g} \delta g \quad (1.15)$$

Combining these two, we have

$$I[F[f + \delta f, g + \delta g]] = \int_B^A dx F[f(x) + \delta f(x), g(x) + \delta g(x)] \quad (1.16)$$

$$= \int_B^A dx F[f, g] + \frac{\partial F}{\partial f} \delta f + \frac{\partial F}{\partial g} \delta g \quad (1.17)$$

$$\implies I[F[f + \delta f, g + \delta g]] - I[F[f, g]] = \int_B^A dx \frac{\partial F}{\partial f} \delta f + \frac{\partial F}{\partial g} \delta g \quad (1.18)$$

In this case, we just like our normal derivative, we should denote the LHS as:

$$\delta I := \int_B^A dx \frac{\partial F}{\partial f} \delta f + \frac{\partial F}{\partial g} \delta g \quad (1.19)$$

or alternatively,

$$\delta I := \int_B^A dx \frac{\delta I}{\delta f} \delta f + \frac{\delta I}{\delta g} \delta g \quad (1.20)$$

1.1.3 Euler-Lagrange Equation

For the two function case, especially consider that $g = \frac{df}{dx}$, and let us see what happens. Specifically, let us set that $\delta f(A) = \delta f(B) = 0$. Then, we have:

$$\frac{\delta I}{\delta g} \delta g = \frac{\delta I}{\delta \frac{df}{dx}} \delta \frac{df}{dx} \quad (1.21)$$

we can change the order of the derivative:

$$= \frac{\delta I}{\delta \frac{df}{dx}} \frac{d \delta f}{dx} \quad (1.22)$$

from the differentiation of a product, we have

$$= \frac{d}{dx} \left(\frac{\delta I}{\delta \left(\frac{df}{dx} \right)} \delta f \right) - \frac{d}{dx} \frac{\delta I}{\delta \left(\frac{df}{dx} \right)} \delta f \quad (1.23)$$

Now, substituting this to the two function case, we get:

$$\delta I = \int_B^A dx \left[\left(\frac{\delta I}{\delta f} - \frac{d}{dx} \frac{\delta I}{\delta \left(\frac{df}{dx} \right)} \right) \delta f + \frac{d}{dx} \left(\frac{\delta I}{\delta \left(\frac{df}{dx} \right)} \delta f \right) \right] \quad (1.24)$$

the total derivative term is zero, since $\delta f(A) = \delta f(B) = 0$. Thus, we have

$$\delta I = \int_B^A dx \left(\frac{\delta I}{\delta f} - \frac{d}{dx} \frac{\delta I}{\delta \left(\frac{df}{dx} \right)} \right) \delta f \quad (1.25)$$

and since $I = \int_B^A dx F[f(x), g(x)]$, we can say that

$$\frac{\partial F}{\partial f} = \frac{\delta I}{\delta f}, \quad \frac{\partial F}{\partial g} = \frac{\delta I}{\delta g} \quad (1.26)$$

Then

$$\delta I = \int_B^A dx \left(\frac{\partial F}{\partial f} - \frac{d}{dx} \frac{\partial F}{\partial \left(\frac{df}{dx}\right)} \right) \delta f \quad (1.27)$$

And if we somehow want to find a minimum of I , we can set $\delta I = 0$:

$$\implies \frac{\partial F}{\partial f} - \frac{d}{dx} \frac{\partial F}{\partial \left(\frac{df}{dx}\right)} = 0 \quad (1.28)$$

This is called the **Euler-Lagrange equation**.

Theorem 1.1.2 Euler-Lagrange Equation

For a functional $I\left[F\left(f, \frac{df}{dx}\right)\right]$ to be stationary, ($\delta I = 0$), the **Euler-Lagrange equation** must be satisfied:

$$\delta I\left[F\left(f, \frac{df}{dx}\right)\right] \iff \frac{\partial F}{\partial f} - \frac{d}{dx} \left(\frac{\partial F}{\partial \left(\frac{df}{dx}\right)} \right) = 0 \quad (1.29)$$

1.1.4 Important Property

In general, consider that the functional F is a function of $f_1(t), f_2(t), \dots, f_n(t)$:

$$F[f_1, f_2, \dots, f_n] \implies \delta F = \sum_{j=1}^n \frac{\delta F}{\delta f_j(t)} \delta f_j(t) \quad (1.30)$$

If $F = f_i$, we expect that

$$\frac{\delta f_i}{\delta f_i} = 1 \implies \delta f_i = \sum_{j=1}^n \frac{\delta f_i}{\delta f_j} \delta f_j \implies \frac{\delta f_i}{\delta f_j} = \delta_{ij} \quad (1.31)$$

Similarly, consider a continous case where F is a function of $f(x)$;

$$F[f(x, t)] \implies \delta F = \int_A^B dx' \frac{\delta F}{\delta f(x', t)} \delta f(x', t) \quad (1.32)$$

Note the distinction between the variable x and the integration variable x' . This is because x is an "index" of $f(t)$: $f_i \rightarrow f(x)$. Then, if we set $F = f(x)$, we expect that

$$\frac{\delta f(x, t)}{\delta f(x, t)} = 1 \implies \delta f(x, t) = \int_A^B dx' \frac{\delta f(x, t)}{\delta f(x', t)} \delta f(x', t) \quad (1.33)$$

Comparing with this with the definition of **Dirac delta function**:

Definition 1.2: Dirac Delta Function

The **Dirac delta function** $\delta(x)$ is defined as a function that satisfies the following property:

$$\int dx' \delta(x' - x) \varphi(x') = \varphi(x), \quad \forall \varphi(x') \in C^\infty \quad (1.34)$$

we have

Theorem 1.1.3 Property of Functional Derivative

For a functional $f_i(t)$ or $f(x, t)$, the functional derivative satisfies the following property:

$$\frac{\delta f_i(t)}{\delta f_j(t)} = \delta_{ij}, \quad \text{or} \quad \frac{\delta f(x, t)}{\delta f(x', t)} = \delta(x - x') \quad (1.35)$$

1.1.5 In a n-dimensional space

In the previous discussions, we have considered the functional I as an integral on 1D space represented by x . Here, we aim to generalize the discussion to n -dimensional space, e.g. \mathbb{R}^n . For \mathbb{R}^n , let us define a functional I and functional derivative as follows:

Definition 1.3: Functional on \mathbb{R}^n

A quantity $I \in \mathbb{R}$ defined on $V \subset \mathbb{R}^n$ is called a **(linear) functional** if it can be expressed as follows:

$$I[f_i] := \int_{x \in V} d^n x F(f_i(x)) = \int_V d^n x F(f_i(x)), \quad i \in \mathbb{N} \quad (1.36)$$

Definition 1.4: Functional Derivative on \mathbb{R}^n

Then, the variation of the functional δI can be expressed as:

$$\delta I = \delta \int_V d^n x' F(f_j(x')) = \int_V d^n x' \delta F(f_j(x')) = \int_V d^n x' \sum_j \frac{\partial F}{\partial f_j(x')} \delta f_j(x') \quad (1.37)$$

Now,

$$\delta f_j(x') = \int_V d^n x \delta^n(x - x') \delta f_j(x) \quad (1.38)$$

$$= \int_V d^n x \sum_i \delta_{ij} \delta^n(x - x') \delta f_i(x) \quad (1.39)$$

$$\frac{\delta f_j(x')}{\delta f_i(x)} = \delta_{ij} \delta^n(x - x') \quad (1.40)$$

so,

$$\frac{\delta I}{\delta f_i(x)} = \int_V d^n x' \frac{\partial F}{\partial f_i(x')} \delta(x - x') = \frac{\partial F}{\partial f_i(x)} \quad (1.41)$$

thus we see that the functional-density relation still holds:

Theorem 1.1.4 Functional-density relation

For a quantity $I[F]$ and its density $F[f_i(x)]$, the functional derivative satisfies the following relation:

$$I = \int_V d^n x F[f_j(x)] \quad \Longrightarrow \quad \frac{\delta I[f_j]}{\delta f_i(x)} = \frac{\partial F[f_j]}{\partial f_i(x)} \quad (1.42)$$

or equivalently,

$$\frac{\delta f_j(x')}{\delta f_i(x)} = \delta_{ij} \delta^n(x - x') \quad (1.43)$$

Physics of Fields

2.1 Hamilton Formalism

2.1.1 Legendre Transformation

Now, remember that we obtained the **Hamiltonian** H of the system through the **Legendre transformation** of the Lagrangian L :

$$H(q_i, p_i) = \sum_i p_i \dot{q}_i - L(q_i, \dot{q}_i) \quad (2.1)$$

where i represents each degree of freedom of the system.

In the field, the degree of freedom is infinite - each indexed by the spatial position \vec{x} , then,

Definition 2.1: Hamiltonian of a Field

The **Hamiltonian** of a field $\psi(\vec{x}, t)$ (whose canonical conjugate field is $\pi(\vec{x}, t)$) is defined as

$$H[\psi, \partial_i \psi, \pi] = \int d^3 \vec{x} \left[\pi \cdot \partial_t \psi \right] - L = \int d^3 \vec{x} \left[\pi \cdot \partial_t \psi - \mathcal{L} \right] \quad (2.2)$$

thus, we should define the **Hamiltonian density** \mathcal{H} as:

Definition 2.2: Hamiltonian Density

Hamiltonian density \mathcal{H} is defined as the Hamiltonian per unit volume of the field:

$$\mathcal{H}(\psi, \partial_i \psi, \pi, t) = \pi \cdot \partial_t \psi - \mathcal{L}(\psi, \partial_i \psi, \partial_t \psi, t) \quad (2.3)$$

which satisfies:

$$\int d^3 \vec{x} \mathcal{H}(\psi, \partial_i \psi, \pi, t) = H[\psi, \partial_i \psi, \pi, t] \quad (2.4)$$

which makes the Hamiltonian H a functional of the field ψ , its spatial derivatives $\partial_i \psi$, and the conjugate field π .

Note:

Similarly to the discrete case, we can write the Lagrangian density \mathcal{L} in terms of the Hamiltonian density \mathcal{H} :

$$\mathcal{L}[\psi(\vec{x}, t), \pi(\vec{x}, t)] = \pi \cdot \partial_t \psi - \mathcal{H}[\psi(\vec{x}, t), \pi(\vec{x}, t)] \quad (2.5)$$

where

$$\partial_t \psi = \frac{\partial \mathcal{H}[\psi, \pi]}{\partial \pi} \quad (2.6)$$

2.1.2 Canonical Equations of Fields

We are also interested in the **canonical equations** of fields, which are derived from the variational principle:

$$\delta S = 0 \iff \delta \int dt \int d^3 \vec{x} \mathcal{L} = \delta \int dt \int d^3 \vec{x} \pi \cdot \partial_t \psi - \mathcal{H} \quad (2.7)$$

The variation on this integral can be expanded as follows:

$$\delta S = \int dt \int d^3 \vec{x} \delta \pi \partial_t \psi + \pi \delta(\partial_t \psi) - \delta \mathcal{H} \quad (2.8)$$

$$= \int dt \int d^3 \vec{x} \delta \pi \partial_t \psi + \pi \partial_t(\delta \psi) - \frac{\partial \mathcal{H}}{\partial \psi} \delta \psi - \frac{\partial \mathcal{H}}{\partial \pi} \delta \pi - \frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \delta(\partial_i \psi) \quad (2.9)$$

$$= \int dt \int d^3 \vec{x} \left(\partial_t \psi - \frac{\partial \mathcal{H}}{\partial \pi} \right) \delta \pi + \left(\pi \partial_t(\delta \psi) - \frac{\partial \mathcal{H}}{\partial \psi} \delta \psi - \frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \partial_i(\delta \psi) \right) \quad (2.10)$$

the $\delta \psi$ term can be integrated by parts:

$$\int dt \int d^3 \vec{x} \pi \partial_t(\delta \psi) - \frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \partial_i(\delta \psi) \quad (2.11)$$

$$= \int dt \int d^3 \vec{x} \partial_t(\pi \delta \psi) - \int dt \int d^3 \vec{x} \partial_t \pi \cdot \delta \psi \quad (2.12)$$

$$\begin{aligned} & - \int dt \int d^3 \vec{x} \partial_i \left(\frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \delta \psi \right) + \int dt \int d^3 \vec{x} \partial_i \left(\frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \right) \delta \psi \\ & = \int d^3 \vec{x} [\pi \delta \psi]_{\text{boundary}} - \int dt \int d^3 \vec{x} \partial_t \pi \delta \psi \\ & \quad - \int dt \int_{\text{boundary}} dS \frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \delta \psi + \int dt \int d^3 \vec{x} \partial_i \left(\frac{\partial \mathcal{H}}{\partial(\partial_i \psi)} \right) \delta \psi \end{aligned} \quad (2.13)$$

the boundary terms vanish, so we end up with:

$$\int dt \int d^3\vec{x} \pi \partial_t(\delta\psi) - \frac{\partial\mathcal{H}}{\partial(\partial_i\psi)} \partial_i(\delta\psi) = - \int dt \int d^3\vec{x} \partial_t\pi \delta\psi + \int dt \int d^3\vec{x} \partial_i \left(\frac{\partial\mathcal{H}}{\partial(\partial_i\psi)} \right) \delta\psi \quad (2.14)$$

$$= - \int dt \int d^3\vec{x} \left[\partial_t\pi - \nabla \cdot \left(\frac{\partial\mathcal{H}}{\partial(\nabla\psi)} \right) \right] \delta\psi \quad (2.15)$$

and thus the variation of the action becomes:

$$\delta S = \int dt \int d^3\vec{x} \left(\partial_t\psi - \frac{\partial\mathcal{H}}{\partial\pi} \right) \delta\pi - \left(\partial_t\pi - \nabla \cdot \left(\frac{\partial\mathcal{H}}{\partial(\nabla\psi)} \right) \right) \delta\psi \quad (2.16)$$

for the action to be stationary, the integrand must vanish:

$$\begin{cases} \partial_t\psi - \frac{\partial\mathcal{H}}{\partial\pi} \\ \partial_t\pi + \frac{\partial\mathcal{H}}{\partial\psi} - \partial_i \left(\frac{\partial\mathcal{H}}{\partial(\partial_i\psi)} \right) \end{cases} = 0 \iff \begin{cases} \frac{\partial\psi(\vec{x},t)}{\partial t} = \frac{\partial\mathcal{H}[\psi,\pi]}{\partial\pi} \\ \frac{\partial\pi(\vec{x},t)}{\partial t} = -\frac{\partial\mathcal{H}[\psi,\pi]}{\partial\psi} + \partial_i \left(\frac{\partial\mathcal{H}}{\partial(\partial_i\psi)} \right) \end{cases} \quad (2.17)$$

Thus we have the **canonical equations of fields**:

Theorem 2.1.1 Canonical Equations of Fields

The variational principle in Hamilton formalism leads to the **canonical equations of fields**:

$$\frac{\partial\psi(\vec{x},t)}{\partial t} = \frac{\partial\mathcal{H}(\psi, \partial_i\psi, \pi)}{\partial\pi}, \quad \frac{\partial\pi(\vec{x},t)}{\partial t} = -\frac{\partial\mathcal{H}(\psi, \partial_i\psi, \pi)}{\partial\psi} + \partial_i \left(\frac{\partial\mathcal{H}(\psi, \partial_i\psi, \pi)}{\partial(\partial_i\psi)} \right) \quad (2.18)$$

Corollary 2.1.1 Canonical Equations of Fields using H

Using Theorem 1.1.1, the **canonical equations of fields** can be re-written using the Hamiltonian H instead of the Hamiltonian density \mathcal{H} :

$$\frac{\partial\psi(\vec{x},t)}{\partial t} = \frac{\delta H[\psi,\pi]}{\delta\pi}, \quad \frac{\partial\pi(\vec{x},t)}{\partial t} = -\frac{\delta H[\psi,\pi]}{\delta\psi} \quad (2.19)$$

2.1.3 Poisson Bracket

In the discrete case, the time evolution of a physical quantity $X(q_i, p_i, t)$, \dot{X} can be written as:

$$\dot{X} = \frac{dX}{dt} = \frac{\partial X}{\partial t} + \sum_i \left(\frac{\partial X}{\partial q_i} \dot{q}_i + \frac{\partial X}{\partial p_i} \dot{p}_i \right) = \frac{\partial X}{\partial t} + \{X, H\} \quad (2.20)$$

In the continuous case, a physical quantity X should be an integral of "density" \tilde{X} over

some volume:

$$X = \int_V d^3 \vec{x}' \tilde{X}(\vec{x}', t) \quad (2.21)$$

and assume that \tilde{X} is a function of the field $\psi(\vec{x}, t)$ and its conjugate field $\pi(\vec{x}, t)$ (which makes X a functional of the fields):

$$\implies X[\psi, \pi, t] = \int_V d^3 \vec{x}' \tilde{X}(\psi(\vec{x}', t), \pi(\vec{x}', t), t) \quad (2.22)$$

Then the time evolution of X can be written as:

$$\frac{dX[\psi, \pi, t]}{dt} = \frac{d}{dt} \int_V d^3 \vec{x}' \tilde{X}(\psi(\vec{x}', t), \pi(\vec{x}', t), t) = \int_V d^3 \vec{x}' \frac{d\tilde{X}(\psi(\vec{x}', t), \pi(\vec{x}', t), t)}{dt} \quad (2.23)$$

$$= \int_V d^3 \vec{x}' \frac{\partial \tilde{X}(\psi, \pi, t)}{\partial t} + \frac{\partial \tilde{X}(\psi, \pi, t)}{\partial \psi} \partial_t \psi + \frac{\partial \tilde{X}(\psi, \pi, t)}{\partial \pi} \partial_t \pi \quad (2.24)$$

$$= \int_V d^3 \vec{x}' \frac{\partial \tilde{X}}{\partial t} + \int_V d^3 \vec{x}' \left(\frac{\partial \tilde{X}}{\partial \psi} \frac{\partial \mathcal{H}}{\partial \pi} - \frac{\partial \tilde{X}}{\partial \pi} \frac{\partial \mathcal{H}}{\partial \psi} \right) \quad (2.25)$$

Using Theorem 1.1.1, the partial derivatives can be replaced with functional derivatives:

$$\frac{\partial \tilde{X}}{\partial t} = \frac{\delta X}{\delta t}, \quad \frac{\partial \tilde{X}}{\partial \psi} = \frac{\delta \mathcal{H}}{\delta \psi}, \quad \frac{\partial \tilde{X}}{\partial \pi} = \frac{\delta \mathcal{H}}{\delta \pi} \quad (2.26)$$

Thus, we can write the time evolution of X as:

$$\frac{dX[\psi, \pi, t]}{dt} = \frac{\partial X[\psi, \pi, t]}{\partial t} + \int d^3 \vec{x}' \left(\frac{\delta X}{\delta \psi} \frac{\delta \mathcal{H}}{\delta \pi} - \frac{\delta X}{\delta \pi} \frac{\delta \mathcal{H}}{\delta \psi} \right) \quad (2.27)$$

If we were to write the coordinates explicitly,

$$\frac{dX[\psi, \pi, t]}{dt} = \frac{\partial X}{\partial t} + \int d^3 \vec{x}' \left(\frac{\delta X[\psi, \pi, t]}{\delta \psi(\vec{x}', t)} \frac{\delta \mathcal{H}[\psi, \pi, t]}{\delta \pi(\vec{x}', t)} - \frac{X[\psi, \pi, t]}{\delta \pi(\vec{x}', t)} \frac{\delta \mathcal{H}[\psi, \pi, t]}{\delta \psi(\vec{x}', t)} \right) \quad (2.28)$$

Comparing with the discrete case, we can define the **Poisson bracket** of two physical quantities X and Y as:

Definition 2.3: Poisson Bracket of a Field

The **Poisson bracket** of two physical quantities $X[\psi, \pi, t]$ and $Y[\psi, \pi, t]$ is defined as:

$$\{X, Y\} = \int d^3 \vec{x}' \left(\frac{\delta X}{\delta \psi(\vec{x}', t)} \frac{\delta Y}{\delta \pi(\vec{x}', t)} - \frac{\delta X}{\delta \pi(\vec{x}', t)} \frac{\delta Y}{\delta \psi(\vec{x}', t)} \right) \quad (2.29)$$

Theorem 2.1.2 Time Evolution of a Physical Quantity

The time evolution of a physical quantity $X[\psi, \pi, t]$ can be written as:

$$\frac{dX}{dt} = \frac{\partial X}{\partial t} + \{X, H\} \quad (2.30)$$

Theorem 2.1.3 Poisson Brackets of Fields

For ψ and its conjugate field π , the Poisson bracket satisfies the following properties:

$$\left\{ \psi(\vec{x}, t), \pi(\vec{x}', t) \right\} = \delta^3(\vec{x} - \vec{x}') \quad (2.31)$$

$$\left\{ \psi(\vec{x}, t), \psi(\vec{x}', t) \right\} = 0 \quad (2.32)$$

$$\left\{ \pi(\vec{x}, t), \pi(\vec{x}', t) \right\} = 0 \quad (2.33)$$

Bibliography

- [1] 広江克彦. “汎関数微分.”[Online]. Available: <https://eman-physics.net/analytic/functional.html>.
- [2] 前野昌弘. “最小作用の原理はどこからくるか?.”[Online]. Available: <http://irobutsu.a.la9.jp/fromRyukyu/wiki/index.php?%BA%C7%BE%AE%BA%EE%CD%D1%A4%CE%B8%B6%CD%FD%A4%CF%A4%C9%A4%B3%A4%AB%A4%E9%A4%AF%A4%EB%A4%AB%A1%A9>.
- [3] 広江克彦. “ルジャンドル変換.”[Online]. Available: <https://eman-physics.net/analytic/legendre.html>.
- [4] A. Einstein, “The collected papers of albert einstein,” in J. Stachel, Ed. Princeton University Press, 1990, vol. 2, ch. On a Heuristic Point of View Concerning the Production and Transformation of Light.
- [5] A. H. Compton, “Physical review letters,” *A Quantum Theory of the Scattering of X-rays by Light Elements*, vol. 21, no. 483, 1923.
- [6] L. de Broglie, “Recherches sur la théorie des quanta,” Ph.D. dissertation, Paris, 1925.
- [7] N. Bohr, “On the constitution of atoms and molecules,” *The London, Edinburgh, and Dublin Philosophical Magazine and Journal of Science*, vol. 26, no. 151, 1913.
- [8] 広江克彦. “流体の運動方程式.”[Online]. Available: https://eman-physics.net/fluid/eq_of_motion.html.
- [9] 鈴木康夫. “流体力学における最小作用の原理（提案）.”[Online]. Available: <https://hooktail.sub.jp/fluid/PrincipleofLeastActionforFluidMechanics/>.