



Introduction to Data Mining

Lecture10 Adaboost

Jun Huang

Anhui University of Technology

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huangjun_cs@163.com



How to improve the generalization ability of machine learning learners?

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Ensemble
Methods

Bagging

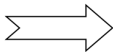
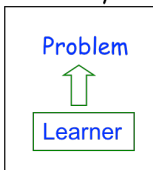
Boosting

Random Forest

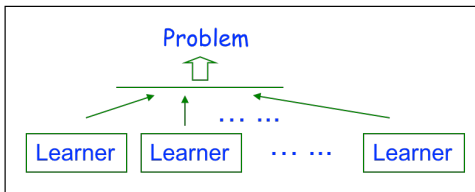
Adaboost

- **Ensemble learning**
- A machine learning paradigm where multiple learners are used to solve the problem
- The generalization ability of the ensemble is usually significantly better than that of an individual learner
- Boosting is one of the most important families of ensemble methods

Previously:



Ensemble:





Ensemble Methods: Increasing the Accuracy

Bagging and Boosting

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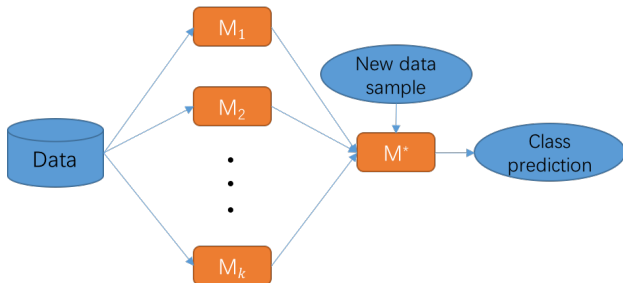
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- Ensemble methods
 - Use a combination of models to increase accuracy
 - Combine a series of k learned models, M_1, M_2, \dots, M_k , with the aim of creating an improved model M^*
- Popular ensemble methods
 - Bagging
 - Boosting





Bagging: Bootstrap Aggregation

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Adaboost

- Analogy: Diagnosis based on multiple doctors' majority vote
- Training
 - Give a data set \mathcal{D} of N samples, at each iteration i , a training set \mathcal{D}_i is sampled with replacement from \mathcal{D}
 - A classifier model M_i is learned for each training set \mathcal{D}_i
- Classification: classify an unknown data sample X
 - Each classifier M_i returns its class prediction
 - The bagged classifier M^* counts the votes and assigns the class with the **most votes** to X



Bagging: Bootstrap Aggregation

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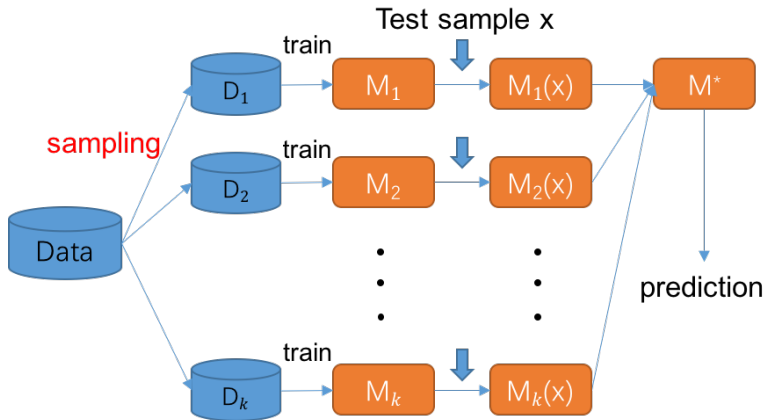
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- $M^*(x) = \text{maxcount}_t M_t(x)$



Bagging: Bootstrap Aggregation

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Adaboost

- Prediction: can be applied to the prediction of **continuous values** by taking the **average value** of each prediction for a given test tuple
- Accuracy
 - Often significant better than a single classifier derived from \mathcal{D}
 - For noise data: not considerably worse, more robust
 - Proved improved accuracy in prediction



Exercise

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Following is a data set to construct a bagging classifier

x	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
y	1	1	1	-1	-1	-1	-1	1	1	1

Examples chosen for training in each round are shown below:

x	0.1	0.2	0.2	0.3	0.4	0.4	0.5	0.6	0.9	0.9
y	1	1	1	1	-1	-1	-1	-1	-1	-1
Classifier: ① $x \leq 0.35 \rightarrow y=1$, ② $x > 0.35 \rightarrow y=-1$										
x	0.1	0.2	0.3	0.5	0.5	0.8	0.9	1	1	1
y	1	1	1	-1	-1	1	1	1	1	1
Classifier: ① $0.4 \leq x \leq 0.55 \rightarrow y=-1$, ② $x > 0.55 \rightarrow y=1$, ③ $x < 0.4 \rightarrow y=1$										
x	0.1	0.2	0.3	0.4	0.4	0.5	0.7	0.7	0.8	0.9
y	1	1	1	-1	-1	-1	-1	-1	1	1
Classifier: ① $x \leq 0.35 \rightarrow y=1$, ② $0.35 \leq x \leq 0.75 \rightarrow y=-1$, ③ $x > 0.75 \rightarrow y=1$										

Please predict the class label for $x = 0.38$?



Boosting

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Adaboost

- Analogy: Consult several doctors, based on a combination of weighted diagnoses - weight assigned based on the previous diagnosis accuracy
- How boosting works?
 - After a classifier M_i is learned, the weights are updated to allow the subsequent classifier M_{i+1} pay more attention to the training tuples that were misclassified by M_i
 - A series of k classifiers are iteratively learned
 - The final M^* combines the votes of each individual classifier, where the weight of each classifier's vote is a function of its accuracy



Boosting

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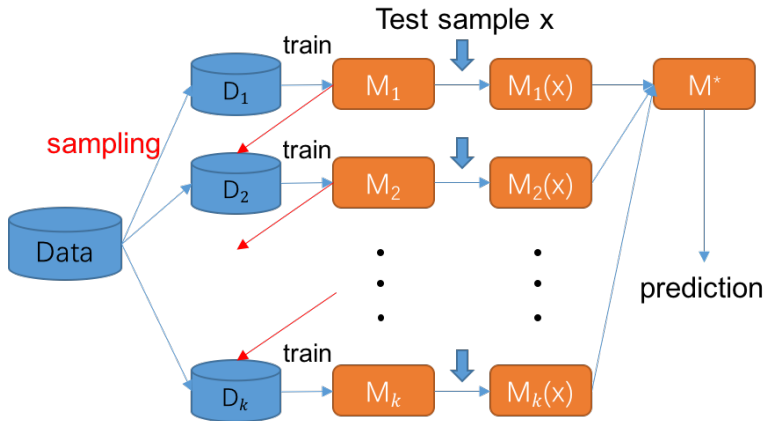
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- $$M^*(x) = \operatorname{argmax}_{M_c} \sum_t^k w_t M_t(x)$$



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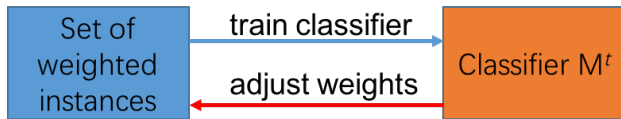
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- The boosting algorithm can be extended for the prediction of continuous values
- Comparing with bagging: boosting tends to achieve greater accuracy, but it also risks overfitting the model to the misclassified data





Bagging vs. Boosting

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- Model training:
 - Bagging: random sampling, independent classifiers
 - Boosting: subsequent classifier M_{i+1} pay more attention to the training tuples that were misclassified by M_i
- Model usage:
 - Bagging: equal weight
 - Boosting: different weights assigned



Boosting

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Adaboost

- **Significant advantageous:**
 - Solid theoretical foundation
 - Very accurate prediction
 - Very simple (“just 10 lines of code” [R. Schapire])
 - Wide and successful applications
 -
- R. Schapire and Y. Freund won **the 2003 Godel Prize** (one of the most prestigious awards in theoretical computer science)
 - Prize winning paper (which introduced AdaBoost): “A decision theoretic generalization of on-line learning and an application to Boosting, “Journal of Computer and System Sciences, 1997, 55: 119-139.



Random Forest

Tree bagging

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- Given a training set $\mathcal{D} = \{x_i, y_i\}_{i=1}^n$, $x_i \in \mathbb{R}^d$, and y_i is the corresponding class label.
- The procedures of Tree bagging is summarized as following:
 - For $b = 1$ to B
 - Sample, with replacement, n training examples from \mathcal{D} , call $\mathcal{D}_b = \{x_i, y_i\}_{i=1}^n$;
 - Train a classification or regression tree f_b on \mathcal{D}_b ;
 - End
- Predictions for unseen samples x' can be made by taking the majority vote in the case of classification trees.
- or by averaging the predictions from all the individual regression trees on x'

$$\hat{f} = \frac{1}{B} f_b(x')$$



Random Forest

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- Random forests differ in only one way from Tree Bagging
 - They use a modified tree learning algorithm that selects, at each candidate split in the learning process, a random subset of the features.
 - 1 For $b = 1$ to B
 - 2 Sample, with replacement, n training examples **with p features** from \mathcal{D} , call $\mathcal{D}_b = \{x_i, y_i\}_{i=1}^n, x_i \in \mathbb{R}^p$;
 - 3 Train a classification or regression tree f_b on \mathcal{D}_b ;
 - 4 End
- Typically, for a classification problem with d features, \sqrt{d} (**rounded down**) **features** are used in each split.
- For regression problems the inventors recommend $d/3$ (**rounded down**) **with a minimum node size of 5** as the default. (**The Elements of Statistical Learning, 2nd ed.**)



Random Forest

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- Decision trees are a popular method for various machine learning tasks. Tree learning comes closest to meeting the requirements for serving as an off-the-shelf procedure for data mining
- It is invariant under scaling and various other transformations of feature values, is robust to inclusion of irrelevant features
- Random forests or random decision forests are an ensemble learning method for classification, regression and other tasks
- Random decision forests correct for decision trees' habit of overfitting to their training set



A formal description of Boosting

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- given training set $\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)\}$
- $y_i \in \{0, 1\}$ correct label of instance $\mathbf{x}_i \in \mathcal{X}$
- for $t = 1, \dots, T$
 - construct distribution \mathcal{D}_t on $\{1, \dots, m\}$
 - find weak classifier

$$h_t: \mathcal{X} \rightarrow \{-1, +1\}$$

- with small error ϵ_t on \mathcal{D}_t

$$\epsilon_t = \Pr_{i \sim \mathcal{D}_t}[h_t(\mathbf{x}_i) \neq y_i]$$

- output final classifier H_{final}



AdaBoost

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- constructing \mathcal{D}_t :
 - $\mathcal{D}_1(i) = \frac{1}{m}$
 - given \mathcal{D}_t and h_t :

$$\begin{aligned}\mathcal{D}_{t+1}(i) &= \frac{\mathcal{D}_t(i)}{Z_t} \times \begin{cases} e^{-\alpha_t}, & \text{if } y_i = h_t(\mathbf{x}_i) \\ e^{-\alpha_t}, & \text{if } y_i \neq h_t(\mathbf{x}_i) \end{cases} \\ &= \frac{\mathcal{D}_t(i)}{Z_t} e^{-\alpha_t y_i h_t(\mathbf{x}_i)}\end{aligned}$$

where

Z_t = normalization constant

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right) > 0$$

- final classifier

$$H_{\text{final}}(\mathbf{x}) = \text{sign} \left(\sum_t \alpha_t h_t(\mathbf{x}) \right)$$



Adaboost (Adaptive Boost) Algorithm

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① **Input:** Training set $\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)\}$, , T rounds, base learner \mathcal{L}

② **Output:** $H_{\text{final}}(\mathbf{x}) = \text{sign} \left(\sum_{t=1}^T \alpha_t h_t(\mathbf{x}) \right)$

③ $\mathcal{D}_1(i) = \frac{1}{m}, 1 \leq i \leq m$

④ **for** $t = 1, \dots, T$

⑤ $h_t = \mathcal{L}(\mathcal{D}, \mathcal{D}_t)$

⑥ $\epsilon_t = \Pr_{i \sim \mathcal{D}_t}[h_t(\mathbf{x}_i) \neq y_i]$

⑦ **if** $\epsilon_t > 0.5$, **then** break

⑧ $\alpha_t = \frac{1}{2} \ln \left(\frac{1-\epsilon_t}{\epsilon_t} \right)$

⑨

$$\mathcal{D}_{t+1}(i) = \frac{\mathcal{D}_t(i)}{Z_t} \times \begin{cases} e^{-\alpha_t}, & \text{if } y_i = h_t(\mathbf{x}_i) \\ e^{-\alpha_t}, & \text{if } y_i \neq h_t(\mathbf{x}_i) \end{cases} = \frac{\mathcal{D}_t(i)}{Z_t} e^{-\alpha_t y_i h_t(\mathbf{x}_i)}$$

⑩ **end**



Toy Example

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Toy Example

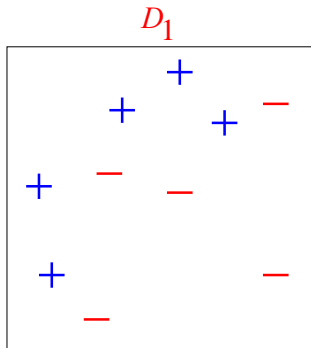
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- weak classifiers = vertical or horizontal half-planes





Round1

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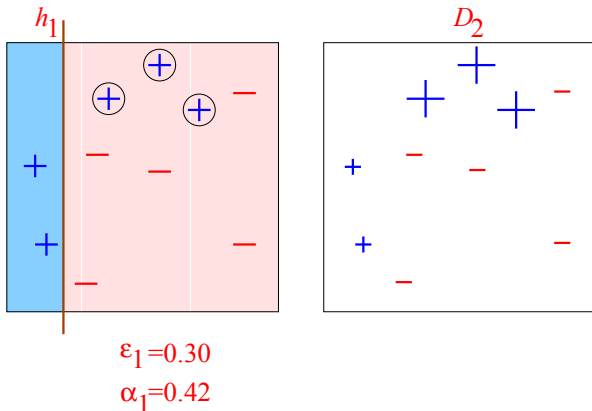
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Round2

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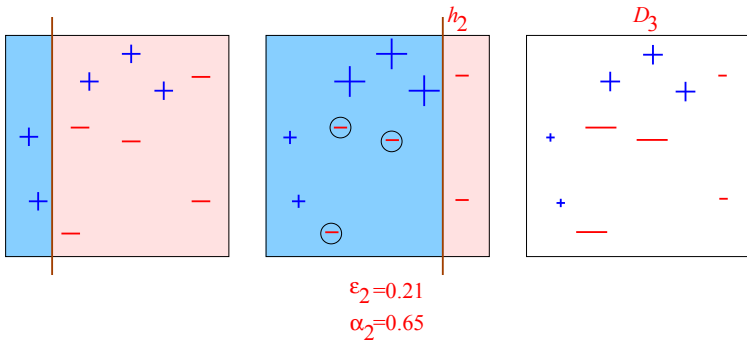
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Round3

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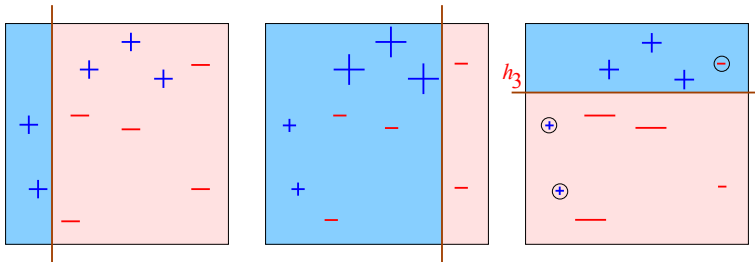
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$$\epsilon_3=0.14$$

$$\alpha_3=0.92$$



Final Classifier

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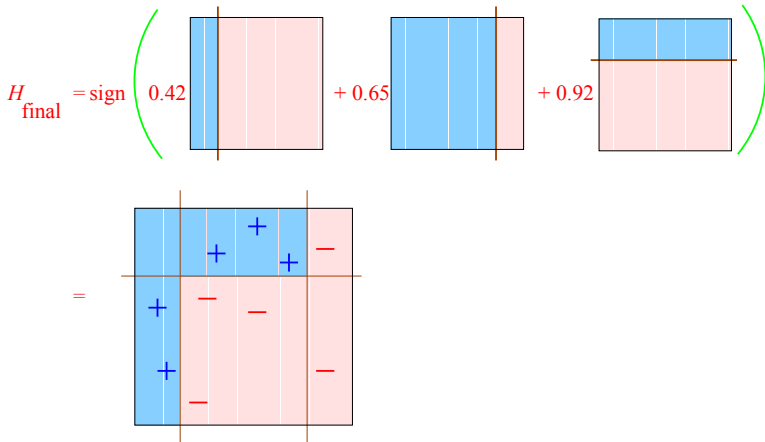
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Analyzing the training error

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- Theorem:

- write ϵ_t as $\frac{1}{2} - \gamma_t$
- then

$$\begin{aligned}\text{training error}(H_{\text{final}}) &\leq \prod_t \left[2\sqrt{\epsilon_t(1-\epsilon_t)} \right] \\ &= \prod_t \sqrt{1-4\gamma_t^2} \\ &\leq \exp \left(-2 \sum_t \gamma_t^2 \right)\end{aligned}$$

- so, if $\forall t: \gamma_t \geq \gamma > 0$, then $\text{training error}(H_{\text{final}}) \leq e^{-2\gamma^2 T}$
- AdaBoost is adaptive:
 - does not need to know γ or T apriori
 - can exploit $\gamma_t \gg \gamma$



Proof

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- Let $f(\mathbf{x}) = \sum_t \alpha_t h_t(\mathbf{x}) \Rightarrow H_{\text{final}}(\mathbf{x}) = \text{sign}(f(\mathbf{x}))$
- Step 1: unwrapping recurrence:

$$\begin{aligned} \mathcal{D}_{\text{final}}(i) &= \frac{1}{m} \frac{\exp(-y_i \sum_t \alpha_t h_t(\mathbf{x}_i))}{\prod_t Z_t} \\ &= \frac{1}{m} \frac{\exp(-y_i f(\mathbf{x}_i))}{\prod_t Z_t} \end{aligned}$$



Proof (cont.)

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- Step 2: training error(H_{final}) $\leq \prod_t Z_t$
- proof:

$$\begin{aligned}\text{training error}(H_{\text{final}}) &= \frac{1}{m} \sum_i \begin{cases} 1, & \text{if } y_i \neq H_{\text{final}}(\mathbf{x}_i) \\ 0, & \text{else} \end{cases} \\ &= \frac{1}{m} \sum_i \begin{cases} 1, & \text{if } y_i f(\mathbf{x}_i) \leq 0 \\ 0, & \text{else} \end{cases} \\ &\leq \frac{1}{m} \sum_i \exp(-y_i f(\mathbf{x}_i)) \\ &= \sum_i \mathcal{D}_{\text{final}}(i) \prod_t Z_t \\ &= \prod_t Z_t\end{aligned}$$



Proof (cont.)

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- Step 3: $Z_t = 2\sqrt{\epsilon_t(1 - \epsilon_t)}$
- Proof:

$$\begin{aligned} Z_t &= \sum_i \mathcal{D}_t(i) \exp(-\alpha_t y_i h_t(\mathbf{x}_t)) \\ &= \sum_{i: y_i \neq h_t(\mathbf{x}_t)} \mathcal{D}_t(i) e^{\alpha_t} + \sum_{i: y_i = h_t(\mathbf{x}_t)} \mathcal{D}_t(i) e^{-\alpha_t} \\ &= \epsilon_t e^{\alpha_t} + (1 - \epsilon_t) e^{-\alpha_t} \\ &= 2\sqrt{\epsilon_t(1 - \epsilon_t)} \end{aligned}$$



How Will Test Error Behave? (A first Guess)

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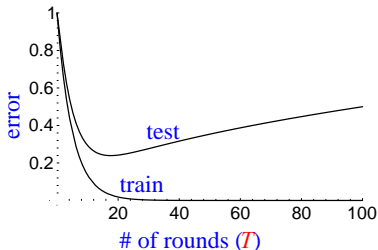
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- Expect:
 - training error to continue to drop (or reach zero)
 - test error to increase when H_{final} becomes “too complex”
 - “Occam’s razor”
 - overfitting
 - hard to know when to stop training



Actual Typical Run

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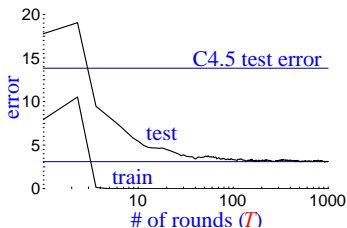
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(boosting C4.5 on
"letter" dataset)

- test error does not increase, even after 1000 rounds
 - (total size > 2,000,000 nodes)
- test error continues to drop even after training error is zero!

	# rounds		
	5	100	1000
train error	0.0	0.0	0.0
test error	8.4	3.3	3.1

- Occam' s razor wrongly predicts "simpler" rule is better



Overfitting

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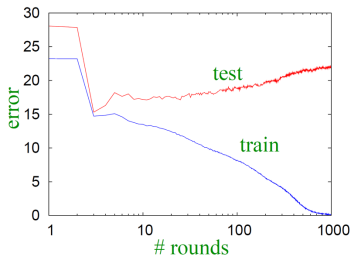
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- Overfitting:

- the data size is too small
- the base learner is too weak



(boosting “stumps” on
heart-disease dataset)



Conclusions

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- **Boosting is a practical tool for classification and other learning problems**
 - grounded in rich theory
 - performs well experimentally
 - often (but not always!) resistant to overfitting
 - many applications and extensions
- **Many ways to think about boosting**
 - none is entirely satisfactory by itself, but each useful in its own way
 - considerable room for further theoretical and experimental work



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