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190713X - L.H.N.WIJEWARDENA

Exercise 08

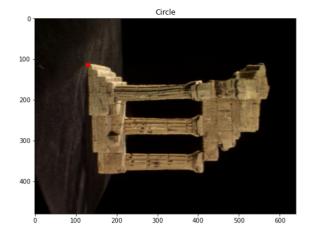
Question 1,2

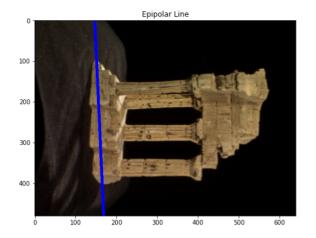
```
In [ ]:
         import cv2 as cv
         import numpy as np
         import matplotlib.pyplot as plt
         f=open(r'templeSparseRing\templeSR par.txt','r')
         assert f is not None
         n= int(f.readline())
         #reading the information of the 2nd image
         l=f.readline().split()
         im1 fn=1[0]
         k1=np.array([float(i) for i in 1[1:10]]).reshape((3,3))
         R1=np.array([float(i) for i in 1[10:19]]).reshape((3,3))
         t1=np.array([float(i) for i in 1[19:22]]).reshape((3,1))
         #reading the information of the 2nd image
         l=f.readline().split()
         im2 fn=1[0]
         k2=np.array([float(i) for i in 1[1:10]]).reshape((3,3))
         R2=np.array([float(i) for i in 1[10:19]]).reshape((3,3))
         t2=np.array([float(i) for i in 1[19:22]]).reshape((3,1))
         #read the two images and show
         im1= cv.imread(r'templeSparseRing/' + im1_fn,cv.IMREAD_COLOR)
         im2= cv.imread(r'templeSparseRing/' + im2_fn,cv.IMREAD_COLOR)
         assert im1 is not None
         assert im2 is not None
         #compute p1 and p2
         \#P=k*\lceil R \mid t \rceil
         P1=k1@np.hstack((R1,t1))
         P2=k2@np.hstack((R2,t2))
         print(P1)
         print(P2)
```

[1.53577034e+03 -6.41434324e+01 -1.63127843e+02 1.85810055e+02] [4.88387837e-02 -1.81568392e-01 -9.82164799e-01 6.14604846e-01]] [[-1.55882371e+02 1.44377186e+03 -5.42436214e+02 6.81806220e+01]

```
[ 1.34928131e+03 -8.41979541e+01 -7.49443961e+02 1.99929996e+02]
         [-3.40999743e-01 -1.74474039e-01 -9.23730472e-01 6.00850565e-01]]
In [ ]:
         from scipy.linalg import null space
         def skew(x):
             x=x.ravel()
             return np.array([[0, -x[2], x[1]], [x[2], 0, -x[0]], [-x[1], x[0], 0]])
         C=null space(P1)
         C=C*np.sign(C[0,0])
         e2=P2@C
         e2x=skew(e2)
         F=e2x@P2@np.linalg.pinv(P1)
         print(F)
        [[-2.87071497e-04 -3.96261289e-02 2.94221686e+02]
         [-3.55039713e-02 1.65329260e-04 1.78860854e+01]
         [-2.76702814e+02 2.12942175e+01 -9.06669374e+03]]
        Question 3
In [ ]:
         x=np.array([130,115,1])
         cv.circle(im1,(x[0],x[1]),5,(0,0,255),-1)
         12=F @ x.T
         p1=np.array([0,(12[0]*0+12[2])/12[1]]).astype(int)
         p2=np.array([500,(12[0]*500+12[2])/12[1]]).astype(int)
         cv.line(im2,(p1[0],p1[1]),(p2[0],p2[1]),(255,0,0),5)
         cv.namedWindow('im')
         cv.imshow('im',im1)
         cv.waitKey(0)
         cv.imshow('im',im2)
         cv.waitKey(0)
         cv.destroyAllWindows()
         fig,ax=plt.subplots(1,2,figsize=(18,6))
         ax[0].imshow(cv.cvtColor(im1,cv.COLOR BGR2RGB))
         ax[0].set title("Circle")
         ax[1].imshow(cv.cvtColor(im2,cv.COLOR_BGR2RGB))
         ax[1].set title("Epipolar Line")
        Text(0.5, 1.0, 'Epipolar Line')
Out[ ]:
```

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Ouestion 4

```
In [ ]:
         img1 = cv.imread(r'./templeSparseRing/'+im1 fn,0)
         img2 = cv.imread(r'./templeSparseRing/'+im2 fn,0)
         sift = cv.SIFT create()
         keypoint 1, descriptor 1 = sift.detectAndCompute(img1,None)
         keypoint_2, descriptor_2 = sift.detectAndCompute(img2,None)
         FLANN INDEX KDTREE = 1
         index params = dict(algorithm = FLANN INDEX KDTREE, trees = 5)
         search params = dict(checks=50)
         flann = cv.FlannBasedMatcher(index params, search params)
         matches = flann.knnMatch(descriptor 1, descriptor 2, k=2)
         points 1 = []
         points 2 = []
         for i,(m,n) in enumerate(matches):
             if m.distance < 0.8*n.distance:</pre>
                 points 1.append(keypoint 1[m.queryIdx].pt)
                 points 2.append(keypoint 2[m.trainIdx].pt)
         points 1 = np.int32(points 1)
         points 2 = np.int32(points 2)
         F, mask = cv.findFundamentalMat(points 1, points 2, cv.FM LMEDS)
         points 1 = points 1[mask.ravel()==1]
         points 2 = points 2[mask.ravel()==1]
         def drawlines(img1,img2,lines,points 1,points 2):
             rows, columns = img1.shape
             img1 = cv.cvtColor(img1,cv.COLOR GRAY2BGR)
             img2 = cv.cvtColor(img2,cv.COLOR GRAY2BGR)
             for rows,pt1,pt2 in zip(lines,points 1,points 2):
```

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```
color = tuple(np.random.randint(0,255,3).tolist())
        x0,y0 = map(int, [0, -rows[2]/rows[1]])
        x1,y1 = map(int, [columns, -(rows[2]+rows[0]*columns)/rows[1]
        img1 = cv.line(img1, (x0,y0), (x1,y1), color,1)
        img1 = cv.circle(img1,tuple(pt1),5,color,-1)
        img2 = cv.circle(img2,tuple(pt2),5,color,-1)
    return img1,img2
lines 1 = cv.computeCorrespondEpilines(points 2.reshape(-1,1,2), 2,F)
lines 1 = lines 1.reshape(-1,3)
img3,img4 = drawlines(img1,img2,lines_1,points_1,points_2)
lines 2 = cv.computeCorrespondEpilines(points 1.reshape(-1,1,2), 1,F)
lines 2 = lines 2.reshape(-1,3)
img5,img6 = drawlines(img2,img1,lines 2,points 2,points 1)
fig,ax=plt.subplots(1,2,figsize=(20,20))
ax[0].imshow(img5)
ax[1].imshow(img3)
plt.show()
```

