



# Testing in minimum time with ivy "seen enough & stop"

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#### What does it mean - a "valid" measurement



- Valid results are repeatable
  - If you run the test again, within specified +/- experimental error, you will get the same result again.
  - Valid, repeatable, results are for steady-state, sustainable conditions
- If the workload / subsystem are not steady-state, you can't make a valid measurement.
  - After imposing a workload on the subsystem, we need to wait for the behaviour to settle down into a steady state before we start measuring

#### [Go] statement measure=on is "seen enough & stop"



- measure = on
- accuracy\_plus\_minus = "5%"
  - Default is "5%".
- confidence = "95%"
  - How confident you need to be that your measurement falls within the specified plus or minus range around the long term average that you would get measuring forever.
  - Default is "95%"
  - Ivy has a menu of 11 specific pre-loaded confidence values that you pick from.
    - 50%, 60%, 70%, 80%, 90%, 95%, 98%, 99%, 99.5%, 99.8%, and 99.9%
    - http://en.wikipedia.org/wiki/Student%27s\_t-distribution

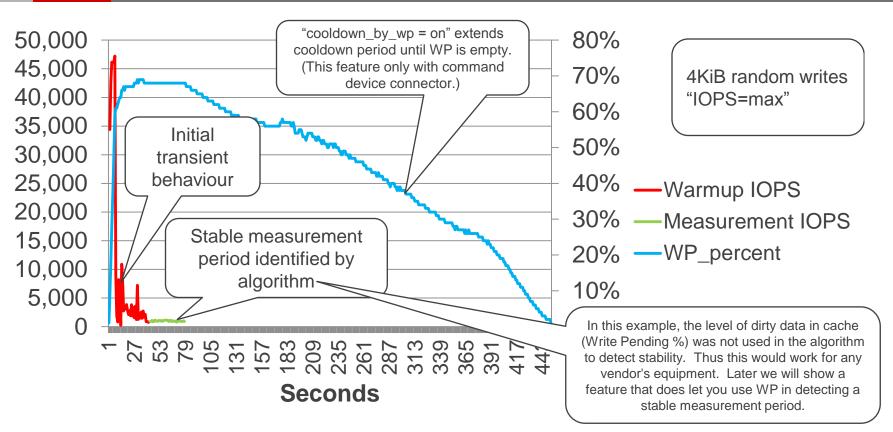
#### Standard statistical formulas need a tweak



- The standard formulas are for when you want to estimate what the mean (average)
  measurement would be if you sampled across the entire population, a huge number of
  samples.
- With the standard formulas, a set of samples is taken, each sample a random sample, meaning the selection of each sample is at random, unrelated to how any other sample was collected.
- In ivy, we are sampling consecutive subintervals, and there is a correlation from subinterval to subinterval.
- So my rough observation from running ivy a few times is to specify accuracy\_plus\_minus twice as tightely, e.g. say +/- 1 % to get +/- 2% accuracy

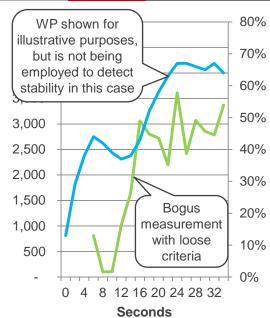
#### Detecting stability – by observing only IOPS/service time



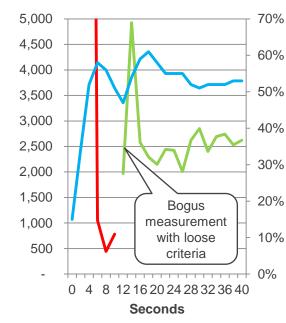


#### Even without command device, algorithm is effective

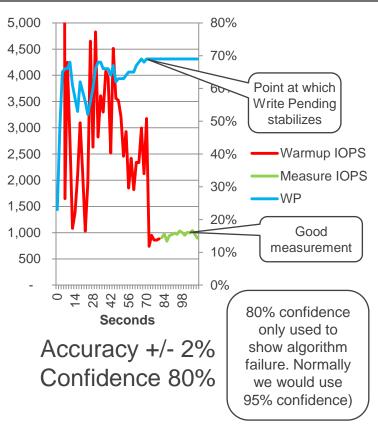




Accuracy +/- 20% Confidence 80%

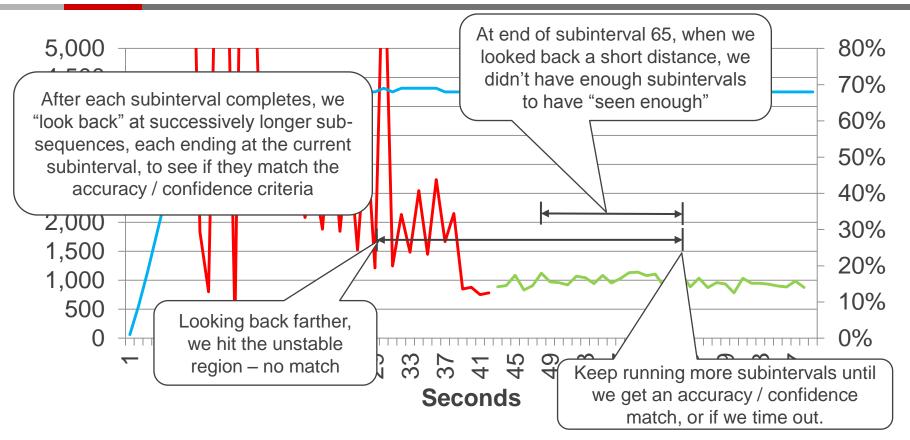


Accuracy +/- 10% Confidence 80%



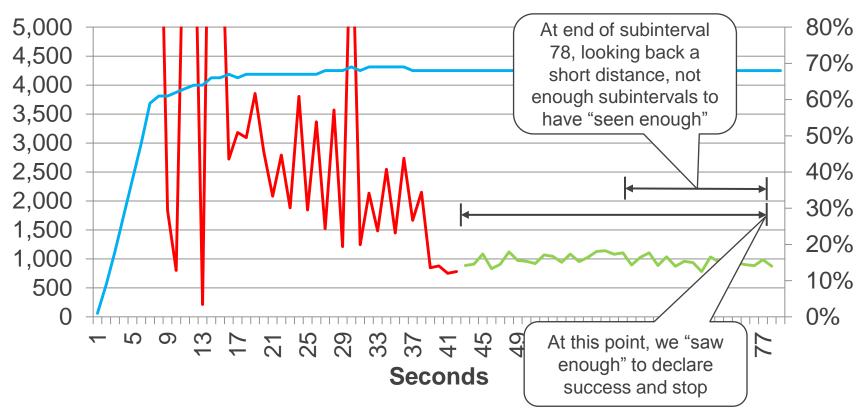
#### Have not "seen enough"





#### "saw enough & stopped"





#### We can get good results from just IOPS, service time



- With measure=on, if we set the accuracy\_plus\_minus and confidence parameters reasonably tight, we can detect when the subsystem has "settled down" and the workload has stabilized.
- When we say the subsystem has "settled down", what we generally mean is that Write Pending has settled down.
  - Detecting stability just looking at IOPS / service time means we need to be sufficiently careful (precise) so that the instability where WP hasn't yet stabilized is enough to prevent "matching" on the accuracy\_plus\_minus and confidence parameters.
- Thus measure=on should work just fine for any vendor's equipment, even without a proprietary "connector" to fetch internal performance data from the storage product.

#### Faster / more robust stability detection with command device



- Ivy automatically discovers and uses a command device to the target subsystems(s), if one is found on a test host and the command device connector is available.
- "measure=on" has Write Pending-based stability criteria you can use with a cmd dev.
  - max\_wp = "2%" default "100%"
    - A subinterval sequence will be rejected if WP is above the limit at any point in the sequence.
    - Use this for read tests to ensure WP is empty during the test.
  - min\_wp = "68%" default "0%"
    - A subinterval sequence will be rejected if WP is below the limit at any point in the sequence.
    - Use this for write tests to ensure WP is full during the test.
  - max\_wp\_range = "3%" default "3%"
    - A subinterval sequence will be rejected if WP varies up and down by more than the specified (absolute) amount at any point in the sequence. max wp range="3%" matches from 0% to 3%, as well as from 67% to 70%.
    - Use this in general all the time so you reject periods with major movement in Write Pending.

#### The cooldown by wp setting - optimize elapsed time



- Whether or not you use measure=on, cooldown\_by\_wp is enabled if a command device is discovered and the command device connector is available.
- The default is cooldown by wp=on
- Set cooldown\_by\_wp=off when it is valid to carry forward WP from one test step to the next.
  - This can speed up the next test step tremendously if the next step doesn't stabilize until WP is full, AND if both steps place the SAME things into WP. (An example follows in a later slide.)
  - If you are switching, say, from testing 4 KiB blocks to testing 8 KiB blocks, then after you make two trials, one with cooldown\_by\_wp set to on and one set to off, you can see if carrying WP over from the previous step with the different blocksize makes a difference. After seeing and thinking about it, will know if cooldown\_by\_wp=off is OK.

#### Designing your test to run in mimimal time



- Use min\_wp / max\_wp / max\_wp\_range with measure=on to measure only when wp has stabilized.
  - Lets you use looser accuracy / confidence parameters for a faster test if you don't need a meticulously accurate result, without losing detection of WP stabilization.
- With or without measure=on, use cooldown\_by\_wp where appropriate to carry WP contents forward from one test step to another, to minimize warmup time.
- cooldown\_by\_wp=off uses a single cooldown subinterval

### warmup\_seconds, measure\_seconds, subinterval seconds



- warmup seconds default = 5
- measure seconds default = 60
- With measure=off, the warmup and measurement periods are fixed.
- With measure=on, these values represent minimum periods during automatic detection of a valid measurement.
- subinterval\_seconds default is 5
  - Don't make this shorter, but if you are running really long test steps, you could use longer subintervals to reduce the volume of csv output.

#### Specifying measure=on - source=workload



- source=workload is always available the test host view of I/O timing.
  - Fully explained in "programming ivy" material.
  - (There is also source=RAID subsystem, not shown here.)
- I/O events are accumulated over a subinterval, and rolled up according to category
  - category = overall, read, write, random, sequential, random\_read, random\_write, sequential\_read, sequential\_write
  - Within these categories, there are also service time / response time histograms that are kept and shown in ivy output csv files.

#### accumulator\_type, accessor



- For each I/O, the service time is posted into one "accumulator", the bytes transferred into another, and if IOPS=max is not set, we post "response time" into another.
  - accumulator\_type = bytes\_transferred, service\_time, response\_time
  - Service time is from I/O launch to I/O completion. Response time is from scheduled I/O start to I/O completion.
    - I/Os will not launch at the scheduled time if there is no "tag" available, so response time can be longer than service time.
    - IOPS=max sets every I/O's scheduled time to zero, in which case "response time" is not posted.
- Retrieve data from a (rolled up) accumulator using an accessor
  - accessor = avg, count, min, max, sum, variance, standardDeviation
  - Use avg for service time, response time which are in seconds.
  - Use sum for bytes\_transferred. Divide by subinterval\_seconds to get bytes per second.
  - Divide service\_time's count by subinterval\_seconds to get IOPS.

#### focus rollup



- The detection of a valid measurement is performed at the granularity of the focus\_rollup.
  - A measurement subinterval sequence constitutes a valid measurement if for all instances of the focus rollup the validity criteria were met.
- The default is focus\_rollup="all", which looks for an overall valid measurement across all workload threads across all test hosts.
- If you have created a rollup by port, by saying
  - [CreateRollup] "port";
  - then you can specify focus\_rollup="port", and then for measure=on, ivy will look for a simultaneous valid measurement period on each instance of the port rollup.

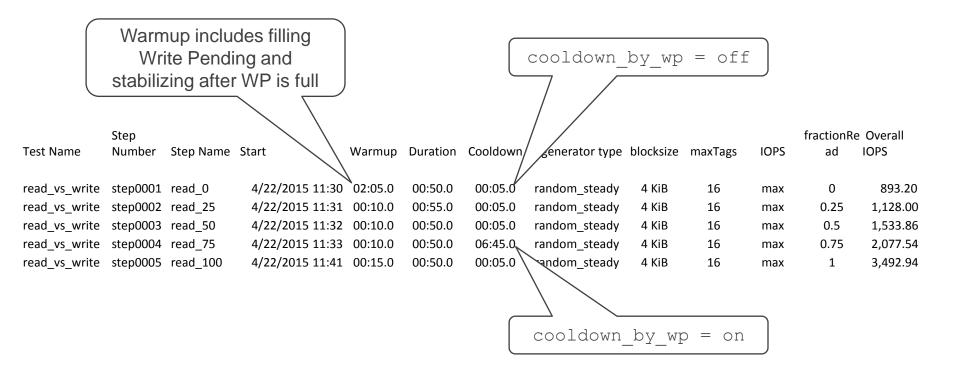
#### An example of running a test in minimum time



- Here we are doing a 4K random I/O run with IOPS=max, and we are showing the IOPS we get for 0%, 25%, 50%, 75%, and 100% writes.
- We start out by doing the 0% read step, with min\_wp="68%" and cooldown\_by\_wp=off
  - It takes some time to warm up because WP needs to fill up and stabilize.
  - The measurement itself takes a little extra time as the IOPS is not quite as stable when the subsystem is in emergency destage, and the subsystem takes some time to "switch gears" and for the IOPS to become stable once WP is full.
- The 25% reads, 50% reads cooldown\_by\_wp=off
  - The previous step leaves WP full, and we stabilize very quickly. It's OK as what we are putting into WP (4K random writes) is the same thing that is draining out (4K random writes to the same LDEVs)
- The 75% reads step cooldown\_by\_wp= on
- The 100% read step could use max\_wp="2%", but not necessary (previously cooldown\_by\_wp=on)

#### Example – minimum time % read test - output





#### Conclusion



- "Seen enough and stop" is effective to perform tests in minimum time.
  - Without a command device, we need tighter accuracy/confidence settings and thus a bit longer test time.
  - With a command device, we directly observe when WP stabilizes.
- Standard small sample set math is effective with a 2x fudge factor.
  - Distribution may not be a "normal distribution", but using the +/- accuracy and confidence % specifications for a normal distribution ("student's t-distribution) is effective to detect stability / establish needed length of measurement to adapt to the degree of instability in the measured results from subinterval to subinterval.
  - Because there is some correlation from subinterval to subinterval, achieved plus/minus accuracy is somewhat looser than specified. Specify 2x tighter accuracy to be sure.





## **Questions**and Discussion

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## **Thank You**

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