## CSC528 Assignment 3 Hithesh Shanmugam

#### Problem 1:

#### Code:

```
import numpy as np
 import cv2
 import matplotlib.pyplot as plt
 def read_img(filename):
    img = cv2.imread(filename, cv2.IMREAD GRAYSCALE)
      return img
 def initialize_parameters(img, k):
    img_flat = img.flatten()
      # Use k-means clustering to initialize the means
      criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 100, 1.0)
      _, labels, centers = cv2.kmeans(np.float32(img_flat), k, None, criteria, 10, cv2.KMEANS_RANDOM_CENTERS) means = centers.squeeze()
      # Initialize covariances and mixing coefficients
     covariances = [np.var(img_flat)] * k
mixing_coeffs = np.ones(k) / k
      return means, covariances, mixing_coeffs
 def expectation_step(img_flat, means, covariances, mixing_coeffs, k):
      responsibilities = np.zeros((img_flat.shape[0], k))
      for i in range(k):
           responsibilities[:, i] = mixing_coeffs[i] * gaussian_prob(img_flat, means[i], covariances[i])
      responsibilities /= np.sum(responsibilities, axis=1, keepdims=True) return responsibilities
 def maximization_step(img_flat, responsibilities, k):
      N = img_flat.shape[0]
      means = np.zeros(k)
covariances = np.zeros(k)
mixing_coeffs = np.zeros(k)
      for i in range(k):
           resp = responsibilities[:, i]
          means[i] = np.sum(resp * img_flat) / np.sum(resp)
covariances[i] = np.sum(resp * (img_flat - means[i]) ** 2) / np.sum(resp)
mixing_coeffs[i] = np.mean(resp)
      return means, covariances, mixing_coeffs
 def gaussian_prob(x, mean, cov):
    return np.exp(-(x - mean) ** 2 / (2 * cov)) / np.sqrt(2 * np.pi * cov)
 def compute_log_likelihood(img_flat, means, covariances, mixing_coeffs, k):
    log_likelihood = 0.0
      for i in range(k):
          log_likelihood += np.log(mixing_coeffs[i] * gaussian_prob(img_flat, means[i], covariances[i]))
      return np.sum(log_likelihood)
 def segment_image(img, k, n_iterations=100, epsilon=1e-7):
    img_flat = img.flatten()
      means, covariances, mixing_coeffs = initialize_parameters(img, k)
      log_likelihoods = []
      for iteration in range(n_iterations):
           # Expectation step
           responsibilities = expectation_step(img_flat, means, covariances, mixing_coeffs, k)
           # Maximization step
          means, covariances, mixing coeffs = maximization_step(img flat, responsibilities, k)
           # Compute log-likelihood
          log_likelihood = compute_log_likelihood(img_flat, means, covariances, mixing_coeffs, k)
log_likelihoods.append(log_likelihood)
           # Check for convergence
           if iteration > 0 and np.abs(log_likelihood - log_likelihoods[iteration-1]) < epsilon:
               break
      # Compute segmented image
      segmented_img = np.argmax(responsibilities, axis=1).reshape(img.shape)
      return segmented_img, log_likelihoods, means
```

```
img = read_img('C:/Users/sures/OneDrive - DePaul University/Desktop/ball.jpg')
# Segment the image
k = 2 # Number of Gaussian components
n iterations = 100
segmented_img, log_likelihoods, means = segment_image(img, k, n_iterations)
# Label pixels based on Gaussian models
labeled_img = np.zeros_like(segmented_img, dtype=np.uint8)
for i, mean in enumerate(means):
    labeled_img[segmented_img == i] = int(mean)
# Display the labeled image
plt.figure(figsize=(10, 5))
plt.subplot(121)
plt.imshow(img, cmap='gray')
plt.title('Original Image')
plt.axis('off')
plt.subplot(122)
plt.imshow(labeled_img, cmap='gray')
plt.title('Labeled Image')
plt.axis('off')
plt.tight_layout()
plt.show()
# Plot the convergence curve
plt.figure()
plt.plot(log_likelihoods)
plt.xlabel('Iteration')
plt.ylabel('Log-Likelihood')
plt.title('Convergence Curve')
plt.show()
```

### **Explanation:**

The code implements a Gaussian mixture model (GMM) using the Expectation-Maximization (EM) algorithm to segment an image.

- 1. The image is read using the *read\_img* function, which converts the image to grayscale.
- 2. The *initialize\_parameters* function initializes the means, covariances, and mixing coefficients for the GMM. It uses k-means clustering to estimate the initial means.
- 3. The *expectation\_step* function computes the responsibilities of each Gaussian component for each pixel in the image based on the current parameter estimates.
- 4. The *maximization\_step* function updates the means, covariances, and mixing coefficients based on the current responsibilities.
- 5. The *gaussian\_prob* function computes the probability of a given value belonging to a Gaussian distribution.
- The compute\_log\_likelihood function calculates the log-likelihood of the data given the current parameter estimates.
- 7. The *segment\_image* function performs the EM algorithm iteratively. It iteratively performs the expectation step and maximization step, updates the parameter estimates, and checks for convergence based on the change in log-likelihood.
- 8. The segmented image is obtained by finding the Gaussian component with the highest responsibility for each pixel.
- 9. The labeled image is created by assigning grayscale values to each pixel based on the mean of the corresponding Gaussian component.
- 10. The original image, labeled image, and convergence curve are displayed using Matplotlib.

Overall, the code segments the image into different regions based on intensity probabilities using a Gaussian mixture model and assigns grayscale values to pixels based on the Gaussian model they belong to. The convergence of the algorithm is checked based on the change in log-likelihood.

# **Output:**



