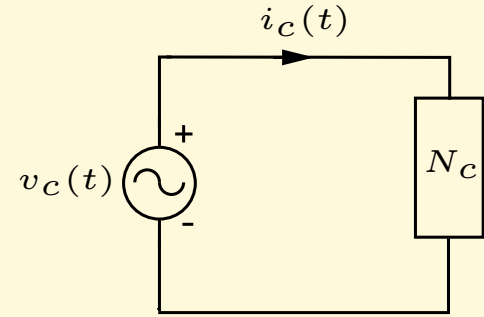
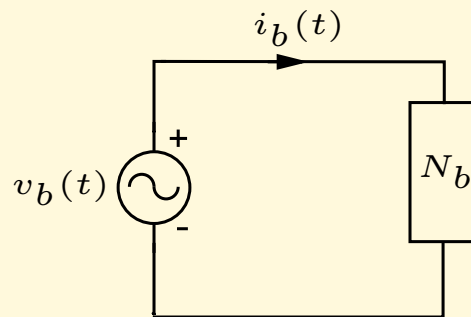
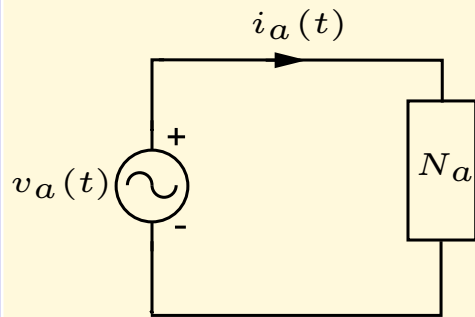
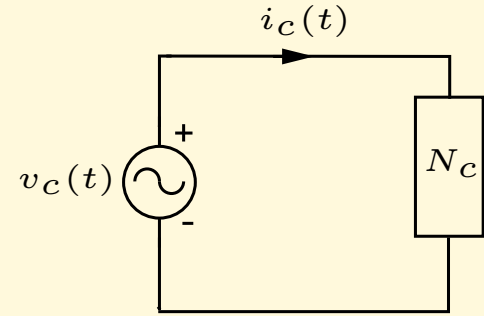
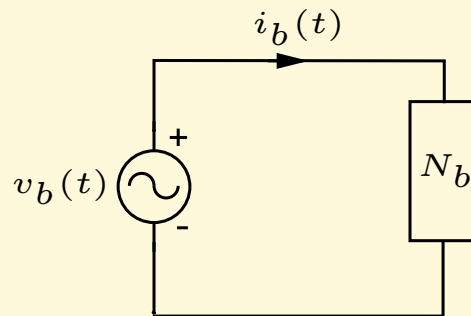
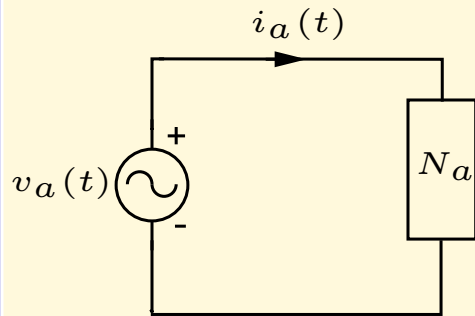


# Three Phase Systems

## System in time-domain

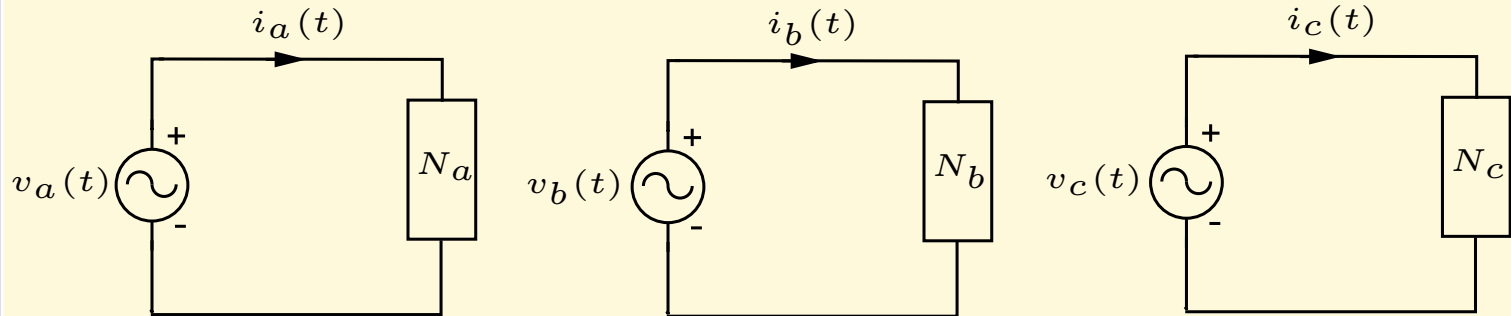


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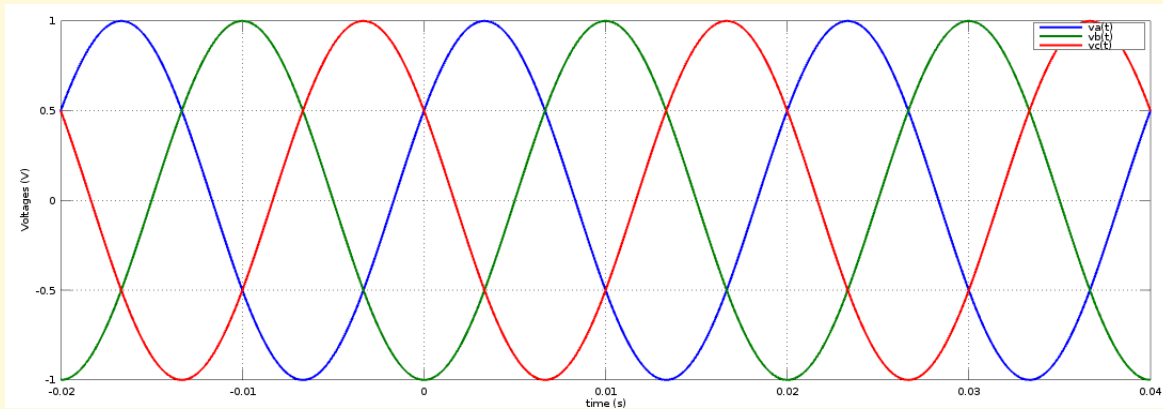


$$v_a(t) = V_m \sin(\omega t + \alpha) \quad v_b(t) = V_m \sin(\omega t + \alpha - 120^\circ) \quad v_c(t) = V_m \sin(\omega t + \alpha - 240^\circ) \text{ V}$$

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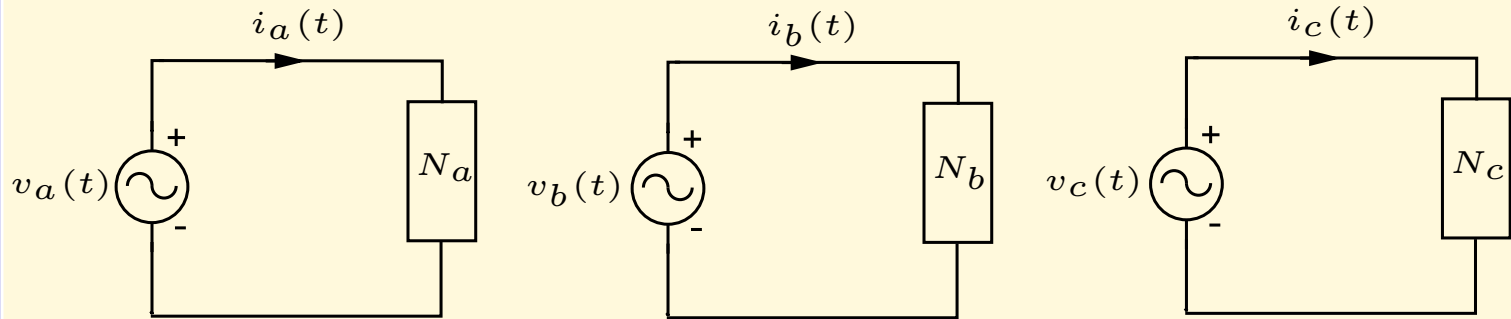


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**Balanced** sets of three phase voltages.

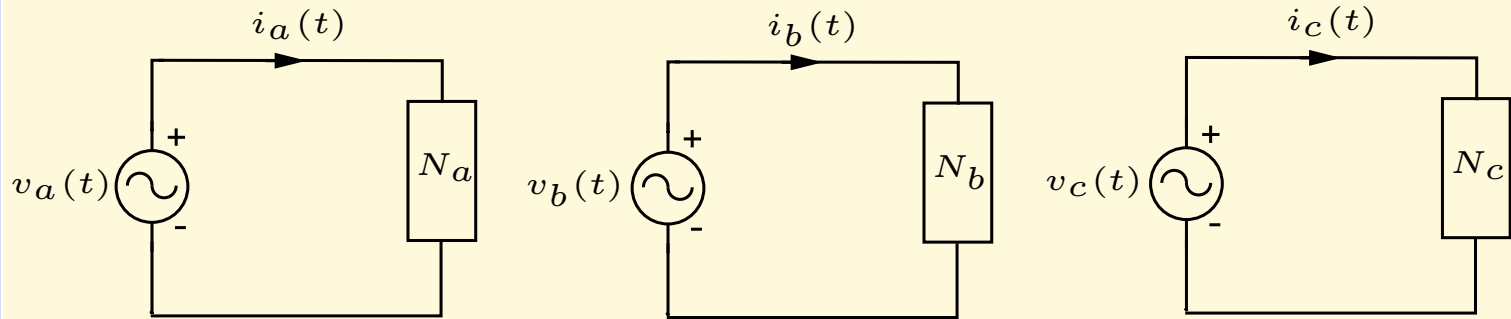
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$N_a$ ,  $N_b$  and  $N_c$  are three linear element network.

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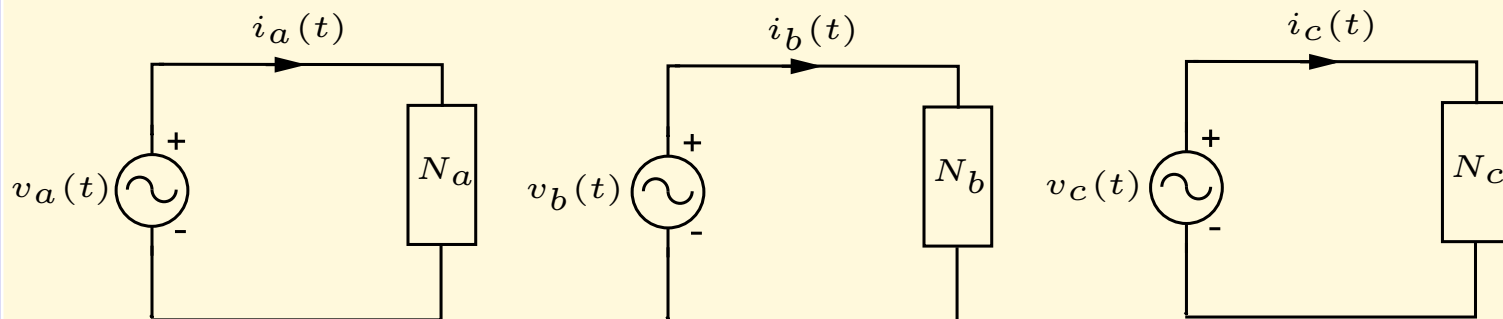


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If they are identical, then load is **balanced** and currents are given as:

## System in time-domain



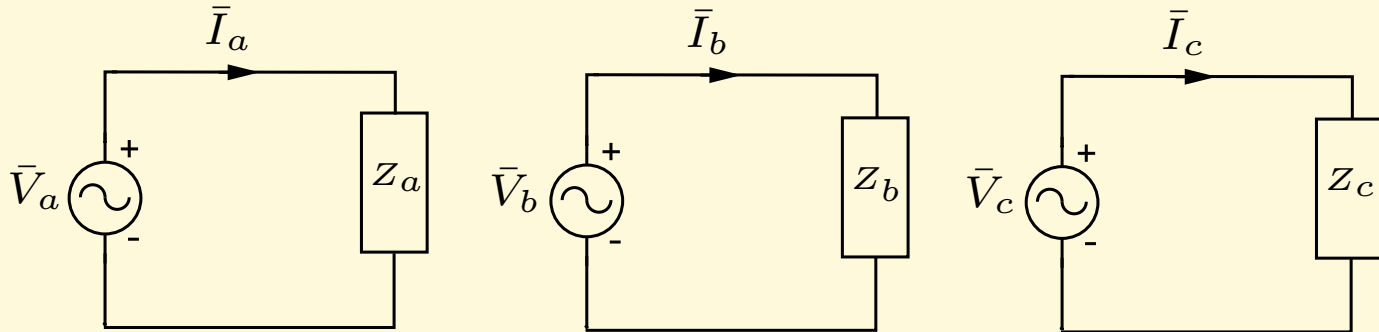
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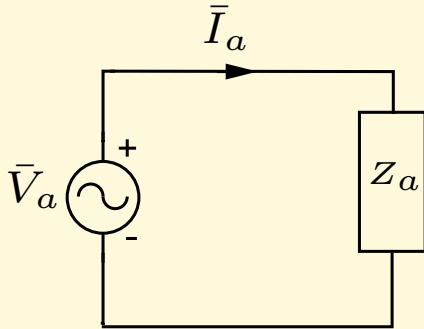
$$i_a(t) = I_m \sin(\omega t + \alpha - \phi) \quad i_b(t) = I_m \sin(\omega t + \alpha - \phi - 120^\circ) \quad i_c(t) = I_m \sin(\omega t + \alpha - \phi - 240^\circ) \text{ A}$$

## Balanced system in phasor domain

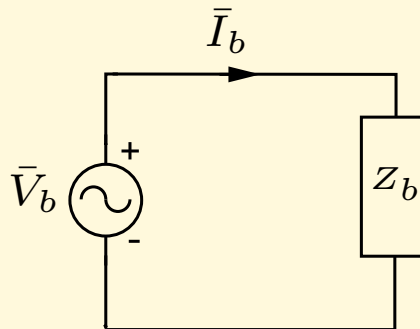




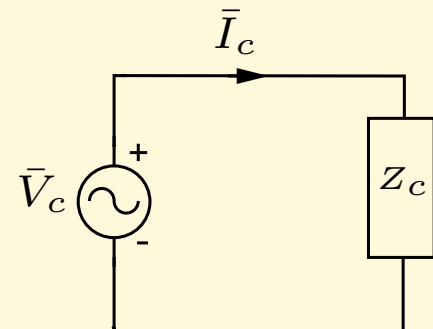
## Balanced system in phasor domain



$$\bar{V}_a = \frac{V_m}{\sqrt{2}} \angle \alpha^\circ$$

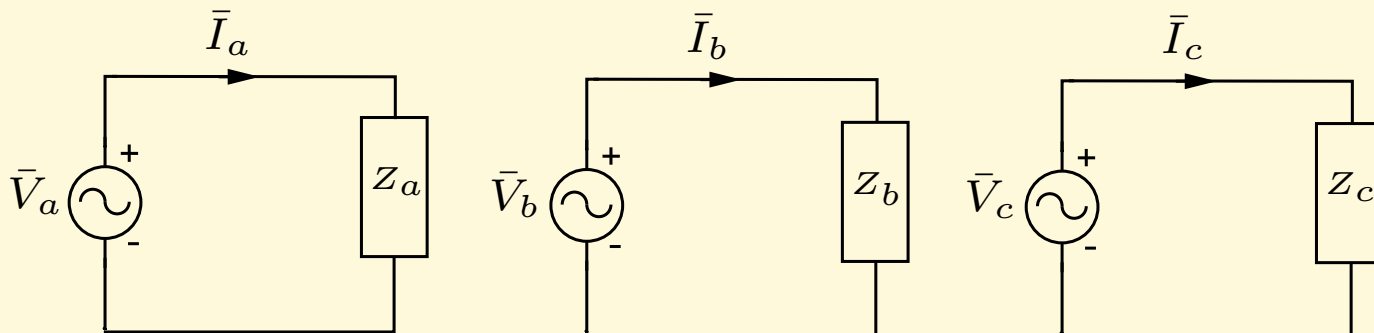


$$\bar{V}_b = \frac{V_m}{\sqrt{2}} \angle (\alpha - 120)^\circ$$



$$\bar{V}_c = \frac{V_m}{\sqrt{2}} \angle (\alpha - 240)^\circ \text{ V}$$

## Balanced system in phasor domain



$$\bar{V}_a = \frac{V_m}{\sqrt{2}} \angle \alpha^\circ \quad \bar{V}_b = \frac{V_m}{\sqrt{2}} \angle (\alpha - 120)^\circ \quad \bar{V}_c = \frac{V_m}{\sqrt{2}} \angle (\alpha - 240)^\circ \text{ V}$$

If  $Z_a = Z_b = Z_c$  and  $\phi = \angle Z_a = \angle Z_b = \angle Z_c$ , the currents are given as.

$$\bar{I}_a = \frac{\bar{V}_a}{Z_a} = \frac{I_m}{\sqrt{2}} \angle (\alpha - \phi)^\circ \quad \bar{I}_b = \frac{\bar{V}_b}{Z_b} = \frac{I_m}{\sqrt{2}} \angle (\alpha - 120 - \phi)^\circ \quad \bar{I}_c = \frac{\bar{V}_c}{Z_c} = \frac{I_m}{\sqrt{2}} \angle (\alpha - 240 - \phi)^\circ$$

A

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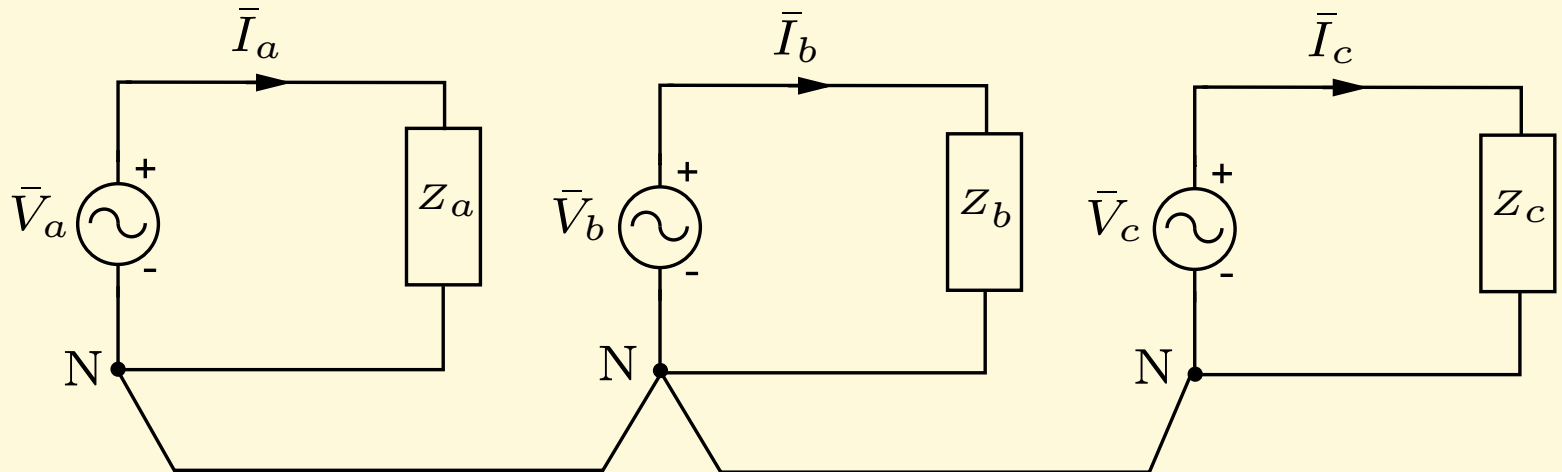
i.e. ( $Z_a = Z_b = Z_c$ ).

Note:

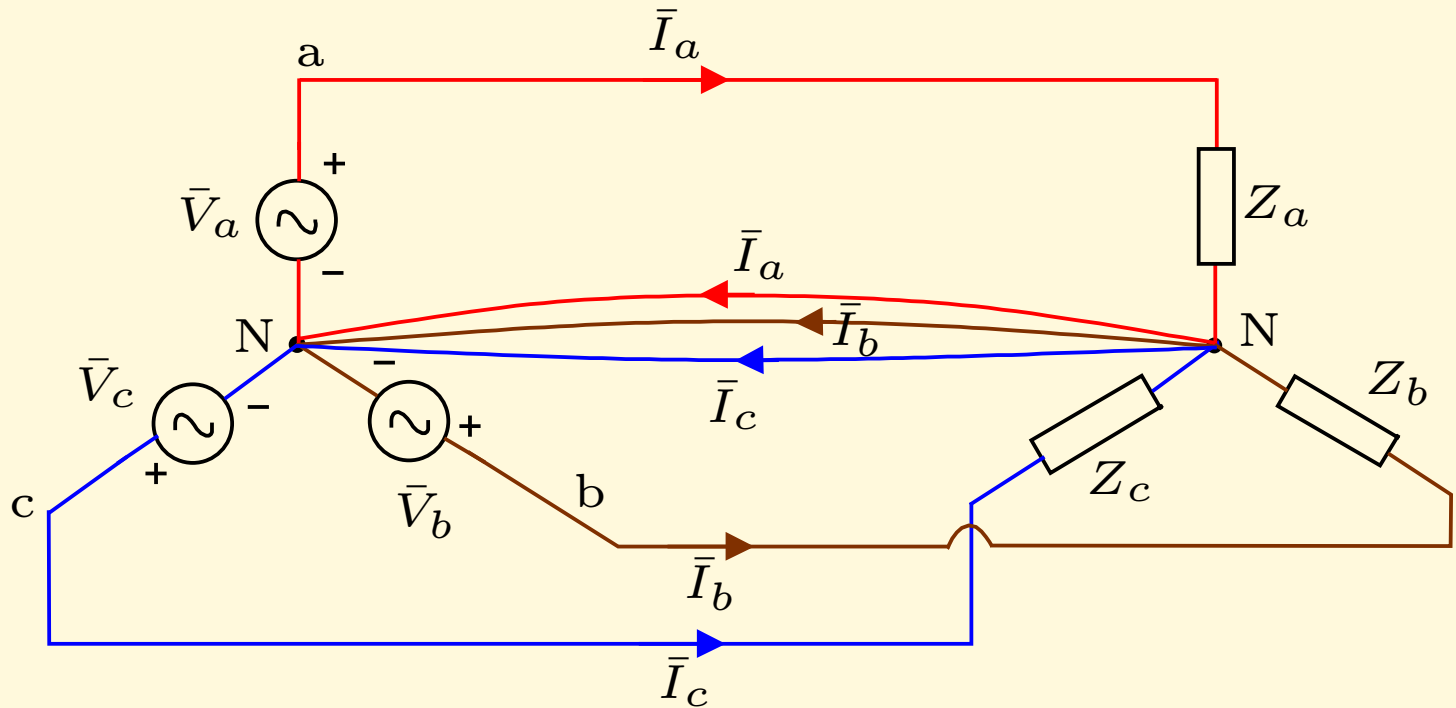
The convention used for voltage phasor:  $\bar{V}_b$  lags  $\bar{V}_a$  and  $\bar{V}_c$  lags  $\bar{V}_b$ .

## System in phasor domain

Consider a **three single-phase** balanced system with a common neutral (N).

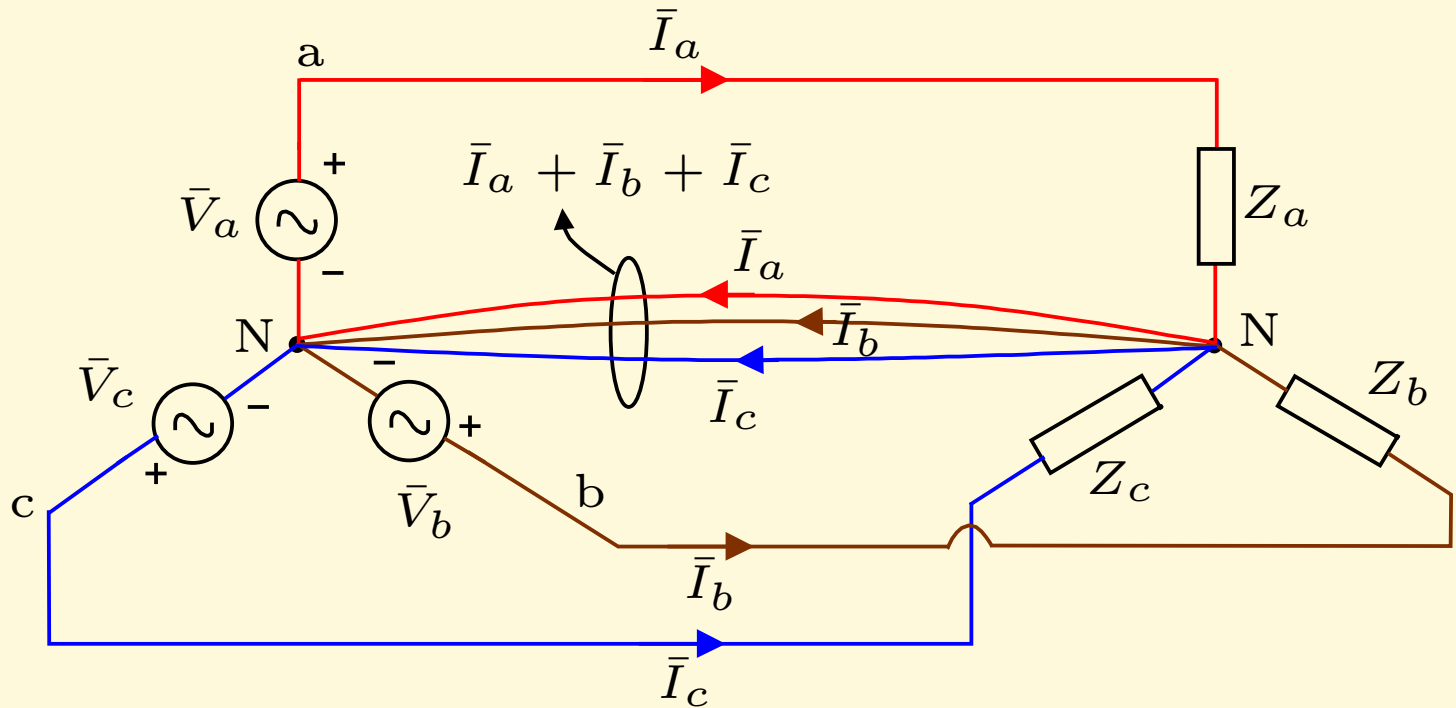


## System in phasor domain

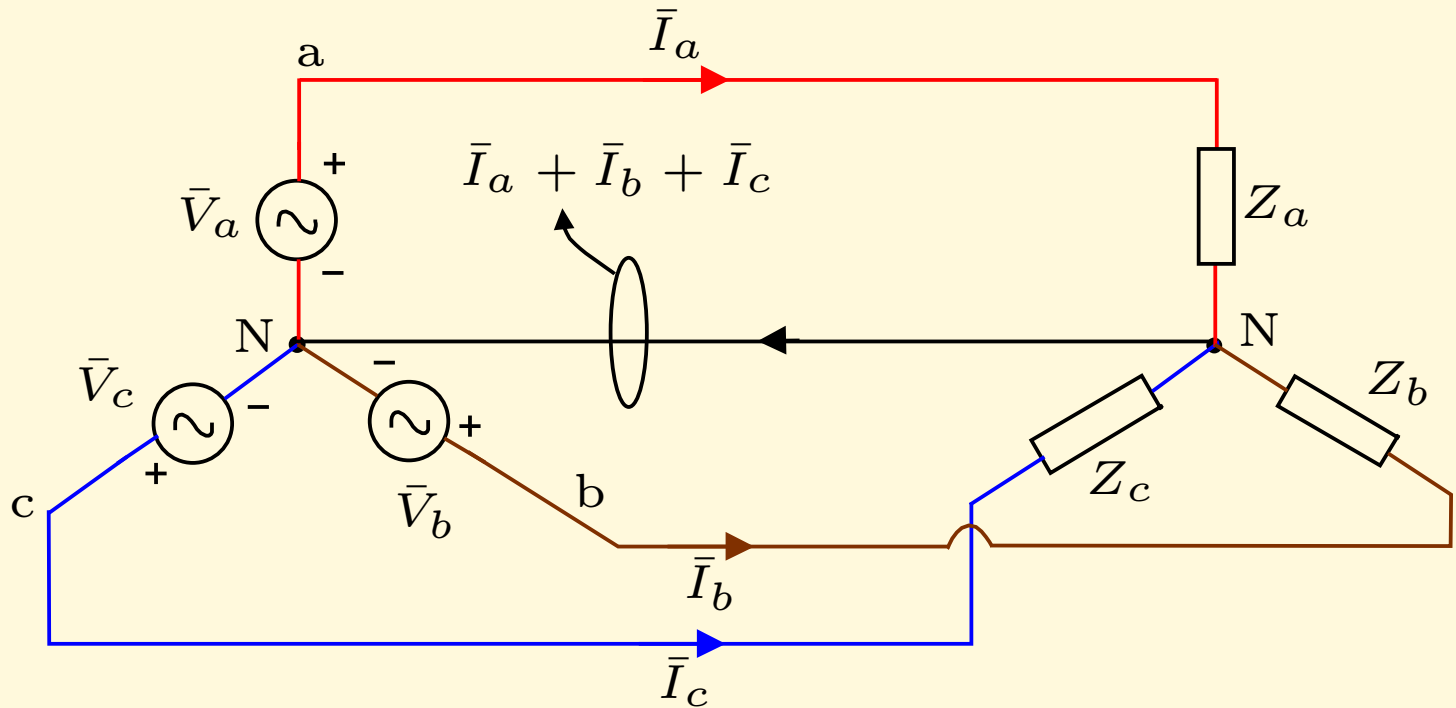




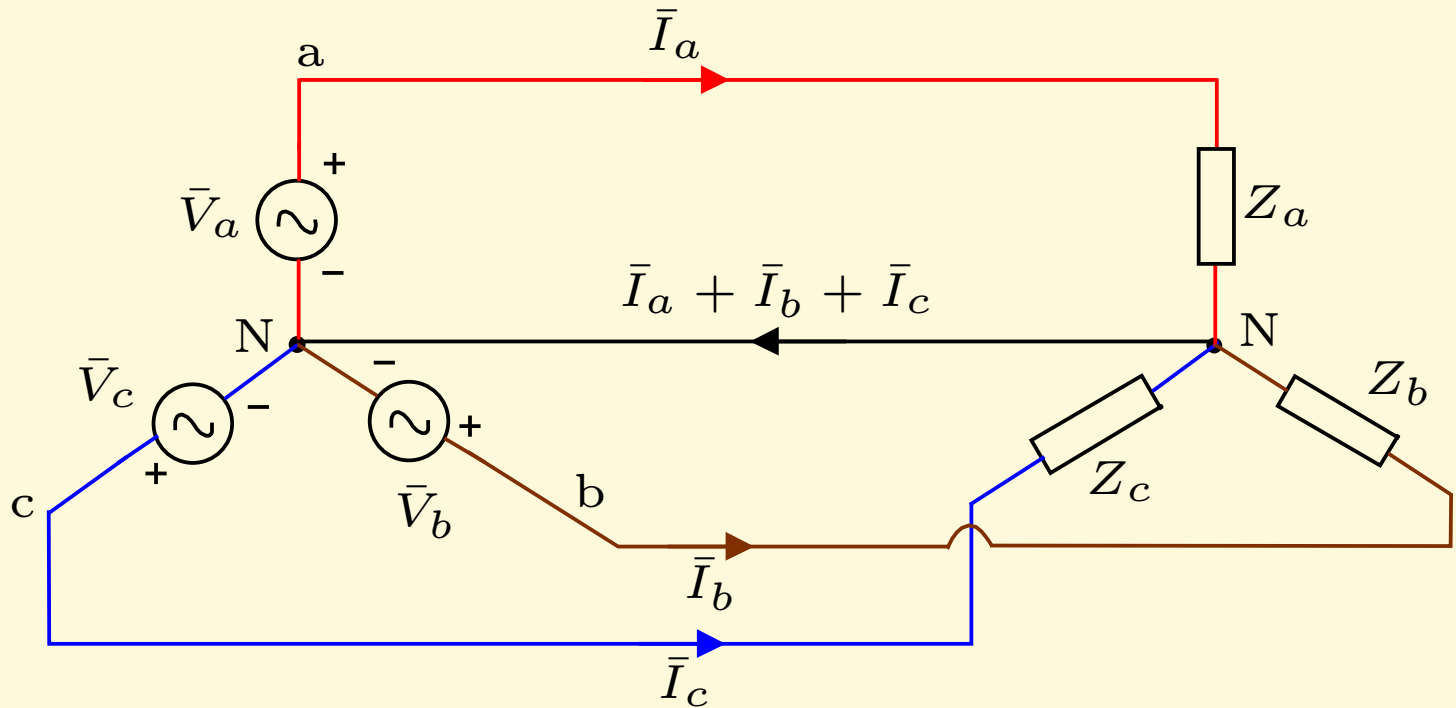
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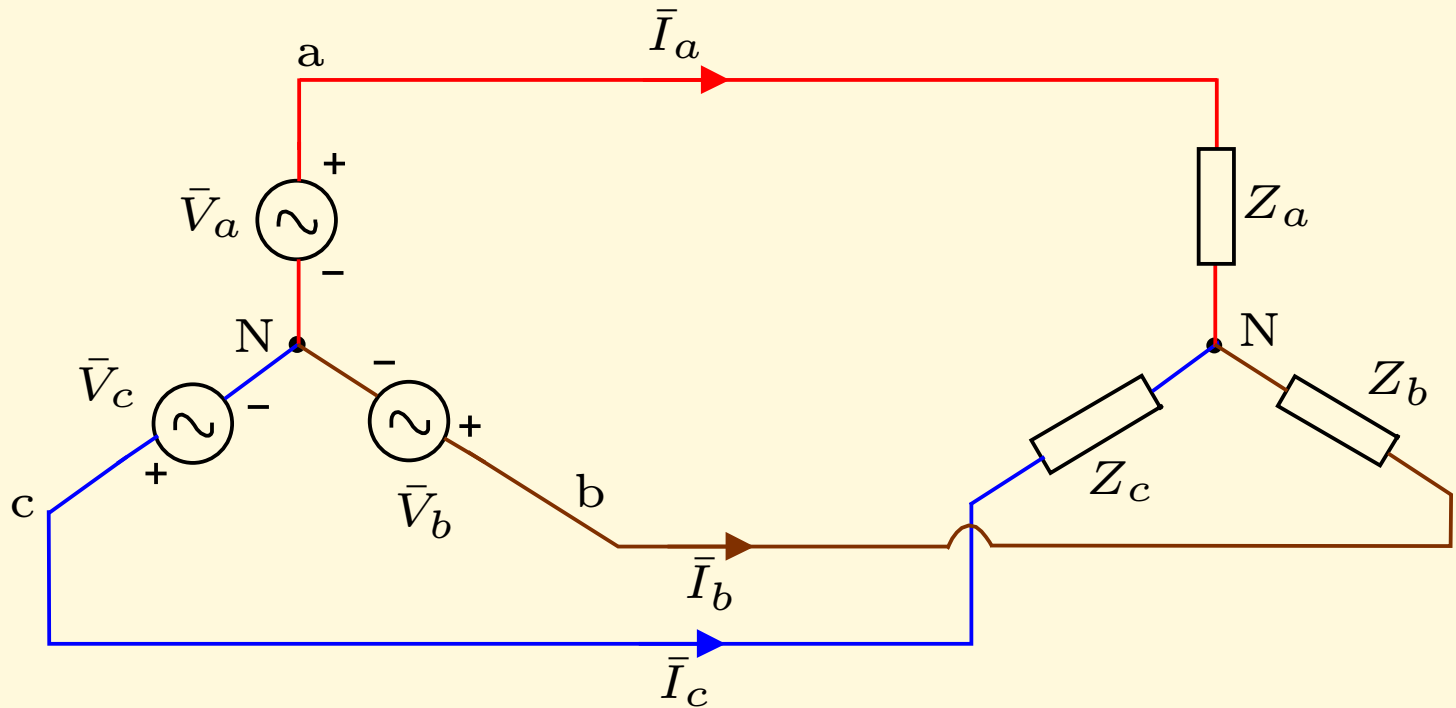
## System in phasor domain



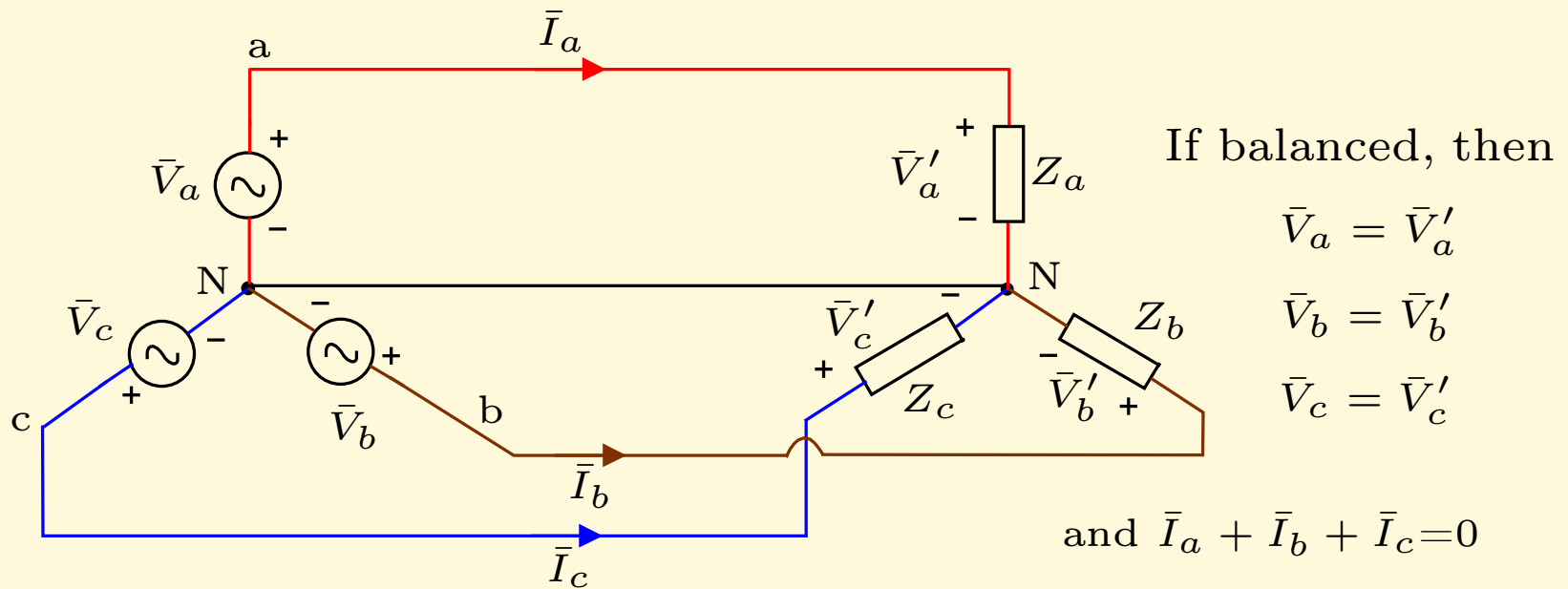
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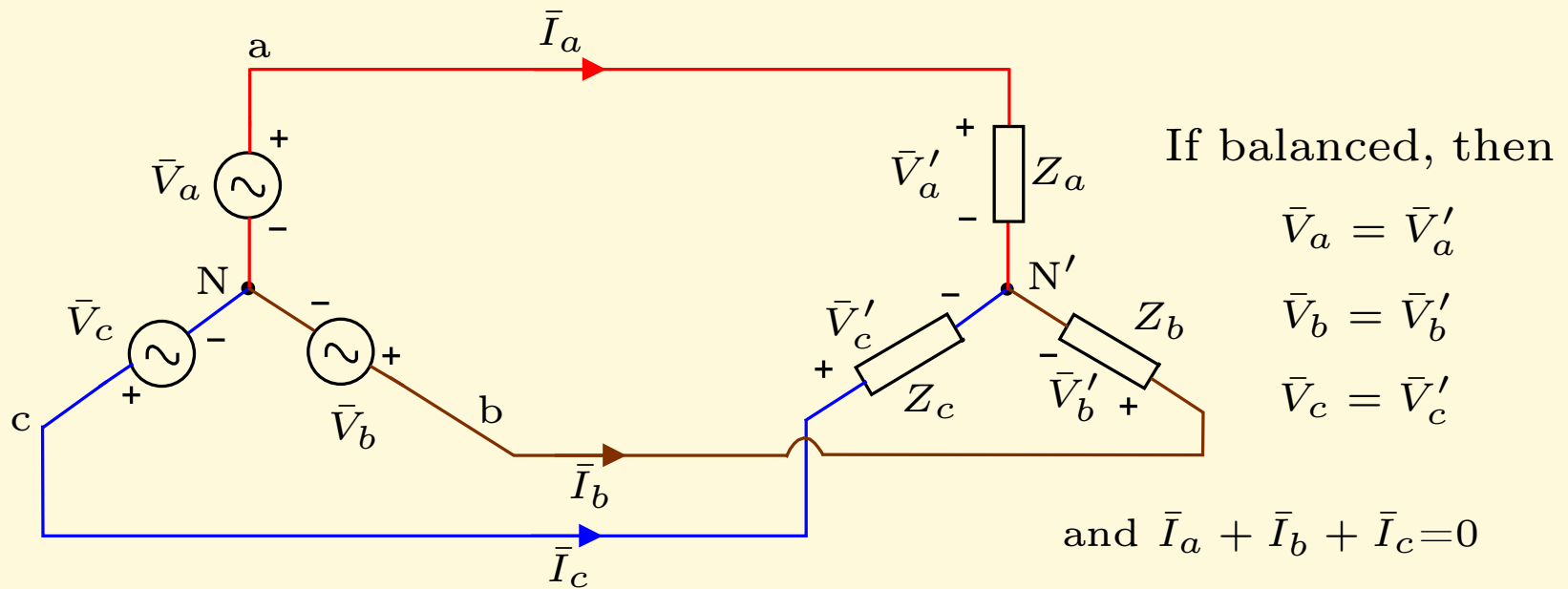
## System in phasor domain (balanced) case:



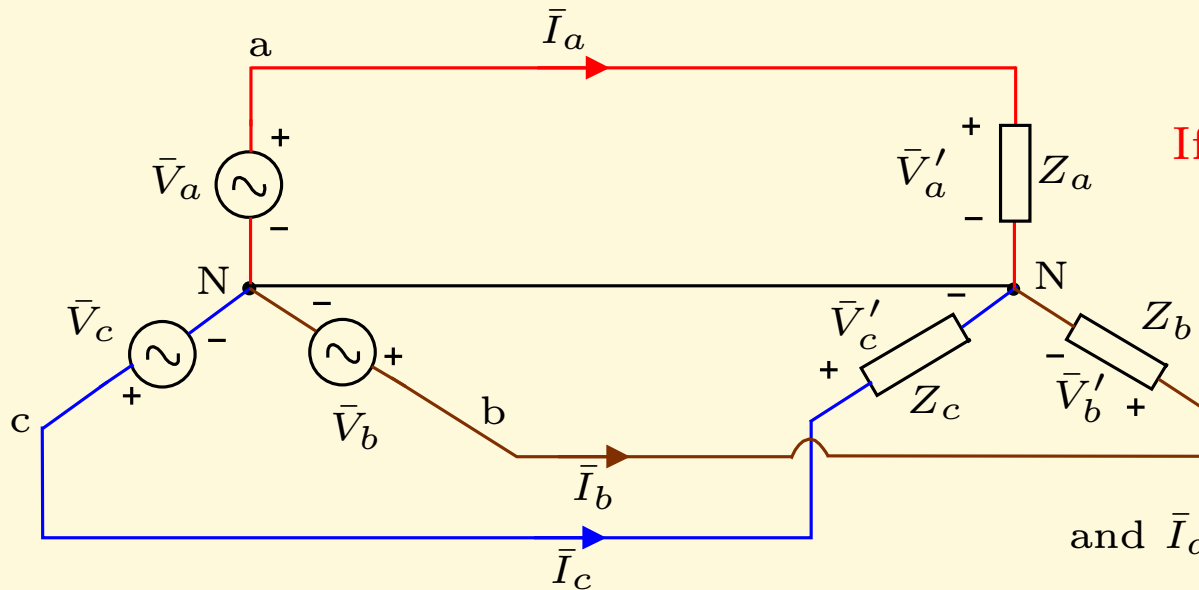
## System in phasor domain (balanced) case:



## System in phasor domain (balanced) case:



## System in phasor domain (**unbalanced**) case:



If unbalanced, then

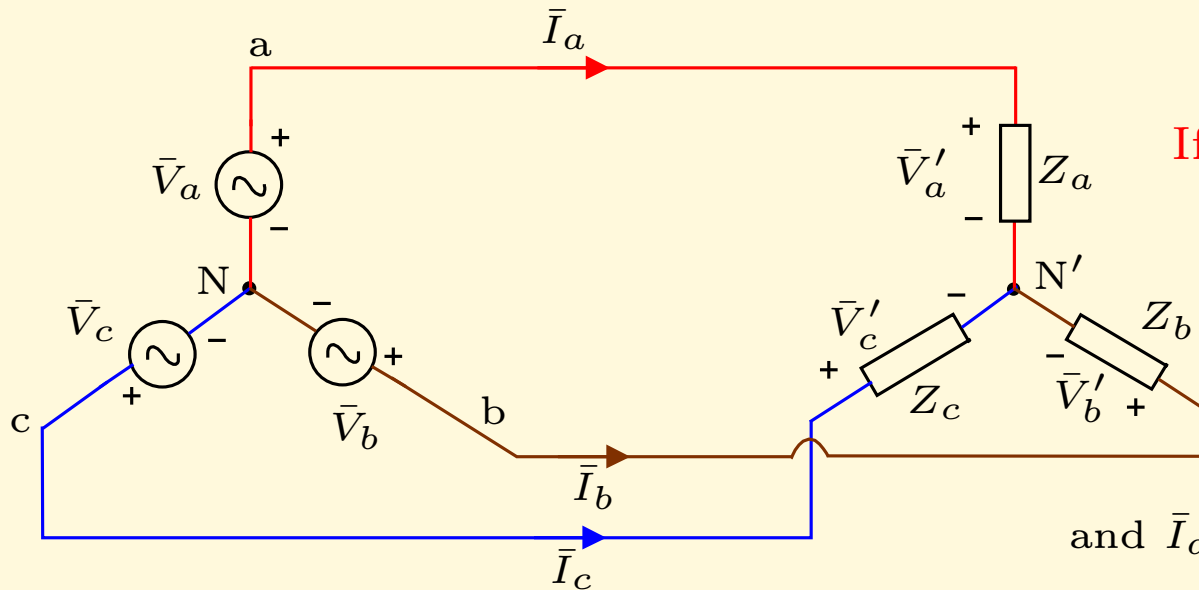
$$\bar{V}_a = \bar{V}'_a$$

$$\bar{V}_b = \bar{V}'_b$$

$$\bar{V}_c = \bar{V}'_c$$

$$\text{and } \bar{I}_a + \bar{I}_b + \bar{I}_c \neq 0$$

## System in phasor domain (**unbalanced**) case:



If unbalanced, then

$$\bar{V}_a \neq \bar{V}'_a$$

$$\bar{V}_b \neq \bar{V}'_b$$

$$\bar{V}_c \neq \bar{V}'_c$$

$$\text{and } \bar{I}_a + \bar{I}_b + \bar{I}_c = 0$$



# Power calculations:

**In time-domain:**

$$p(t) = v_a(t) \times i_a(t) + v_b(t) \times i_b(t) + v_c(t) \times i_c(t)$$

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$$\begin{aligned} p(t) &= v_a(t) \times i_a(t) + v_b(t) \times i_b(t) + v_c(t) \times i_c(t) \\ &= V_m \sin(\omega t + \alpha) \times I_m \sin(\omega t + \alpha - \phi) + \\ &\quad V_m \sin(\omega t + \alpha - 120^\circ) \times I_m \sin(\omega t + \alpha - 120^\circ - \phi) + \\ &\quad V_m \sin(\omega t + \alpha - 240^\circ) \times I_m \sin(\omega t + \alpha - 240^\circ - \phi) \end{aligned}$$

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Note:  $V_{rms}$ : “phase-to neutral rms voltage”.

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Note:  $V_{rms}$ : “phase-to neutral rms voltage”.

**In phasor domain:**  $P = 3 * \text{Real}\{\bar{V}_a \times \bar{I}_a^*\}$  (in W)

## Balanced $n$ -phase systems

Phase voltages:

$$v_k(t) = V_m \sin \left( \omega t + \alpha - \frac{2\pi}{n}(k-1) \right)$$

Phase currents:

$$i_k(t) = I_m \sin \left( \omega t + \alpha - \phi - \frac{2\pi}{n}(k-1) \right) \text{ where, } k = 1 \cdots n$$

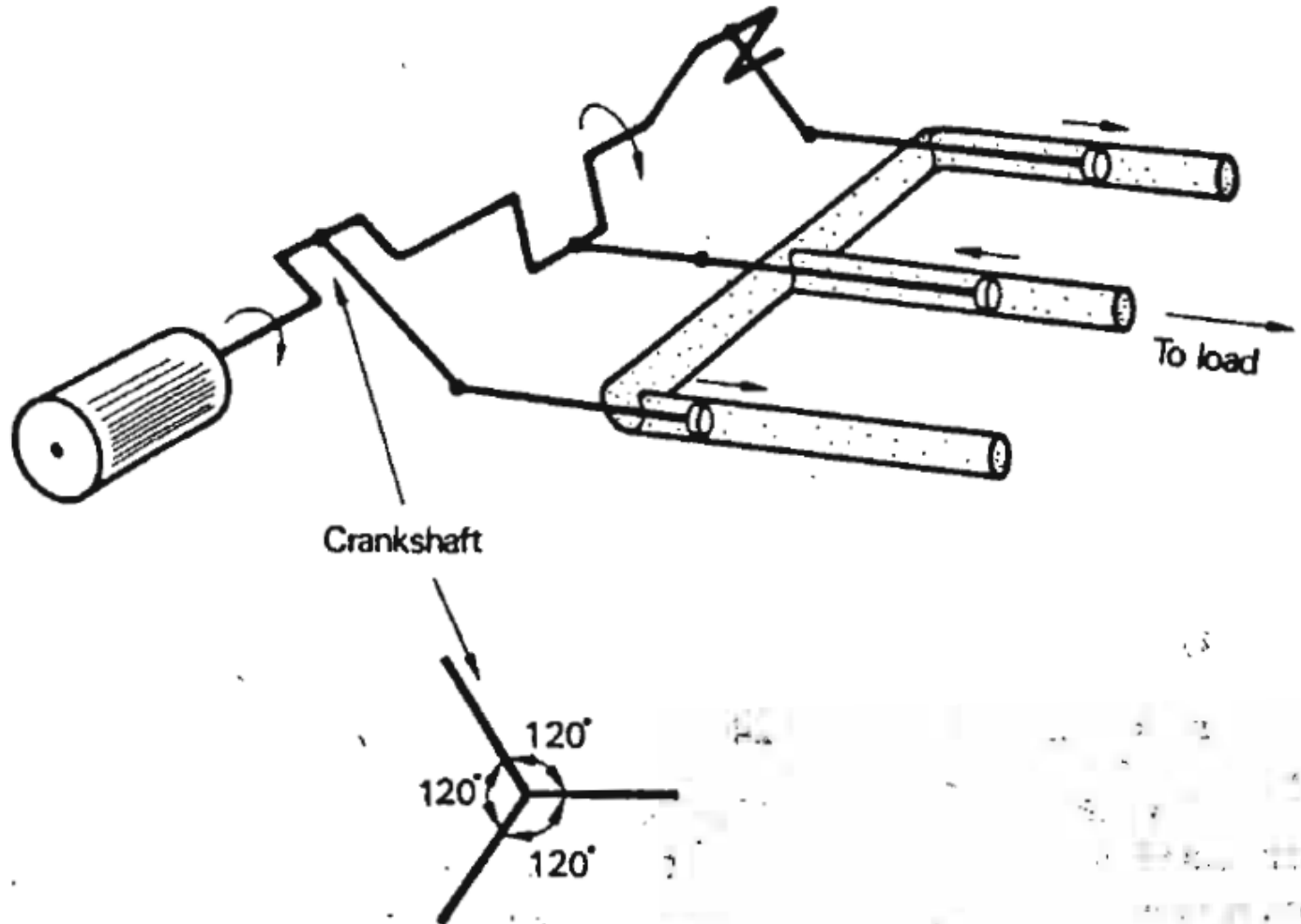
Sum of phase voltages:  $\sum_{k=1}^n v_k(t) = 0$  for  $k \geq 2$ .

Sum of phase currents:  $\sum_{k=1}^n i_k(t) = 0$  for  $k \geq 2$ .

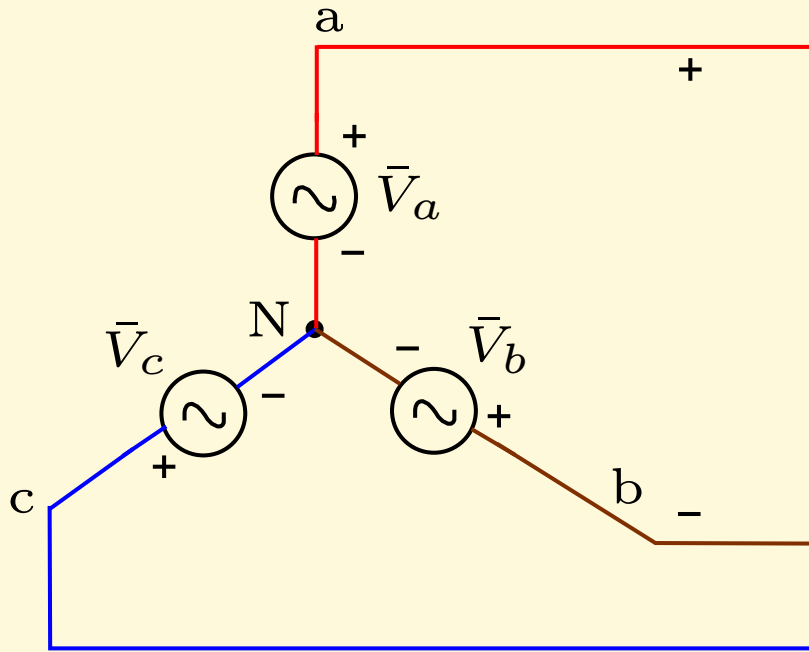
$p(t) = \sum_{k=1}^n v_k(t)i_k(t) = \text{constant}$  for  $k \geq 3$ .

Thus,  $p(t)$  is **time-independent** *except* for a two-phase ( $180^\circ$  phase shift) system.

# Mechanical equivalent for three phase system



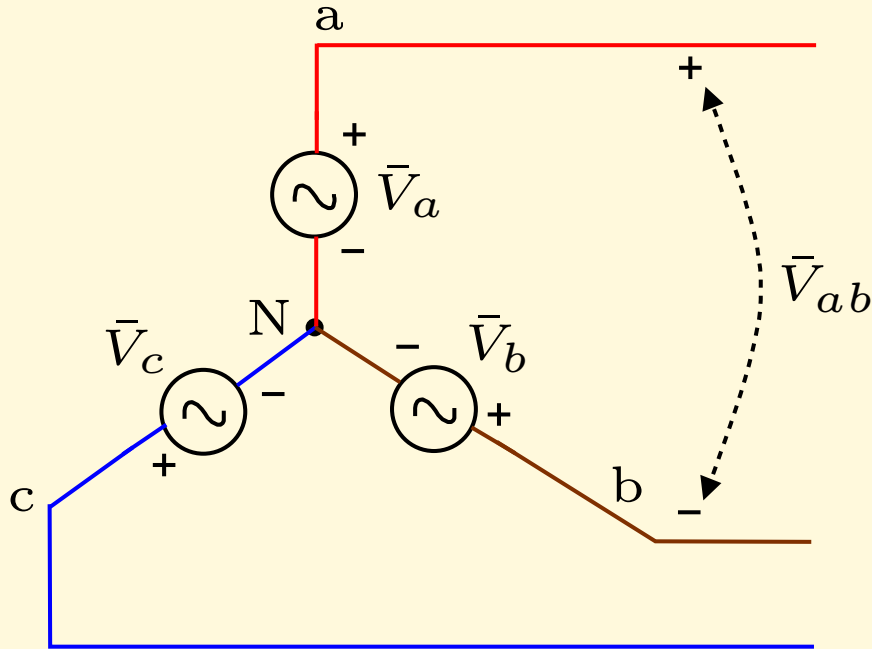
# Terminologies in three phase AC systems:



$\bar{V}_a, \bar{V}_b, \bar{V}_c$ : phase voltages.



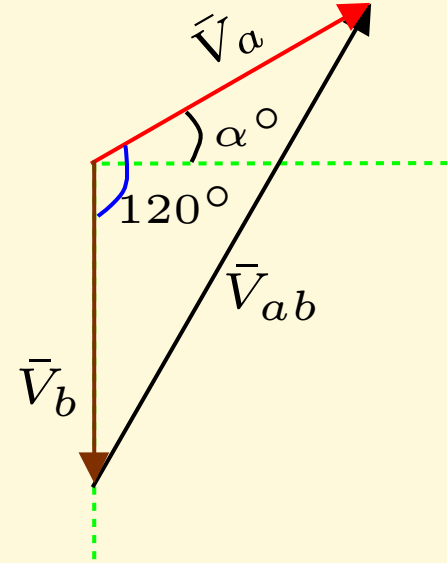
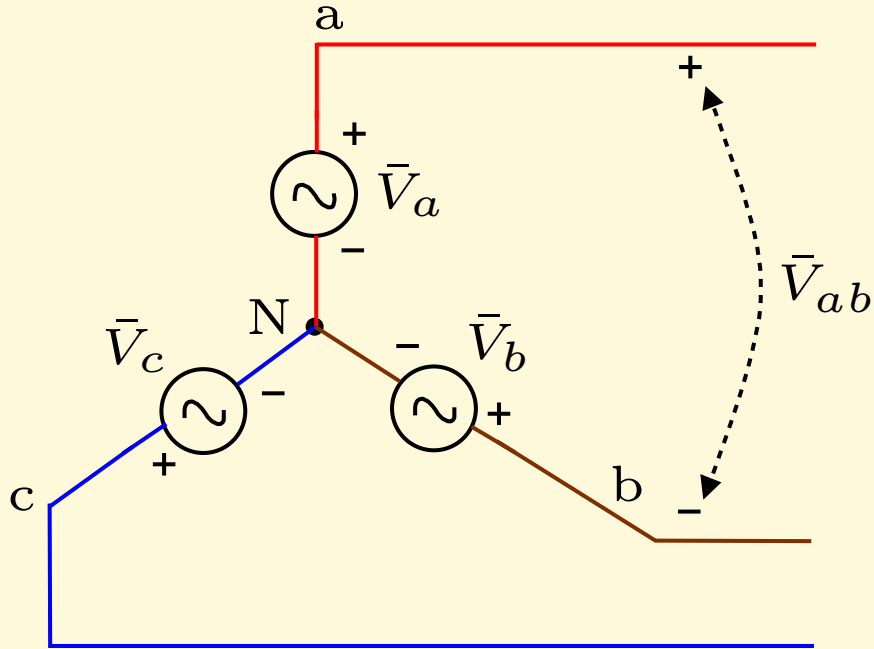
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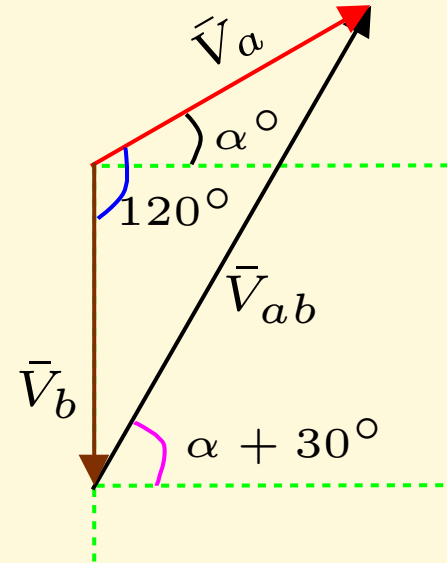
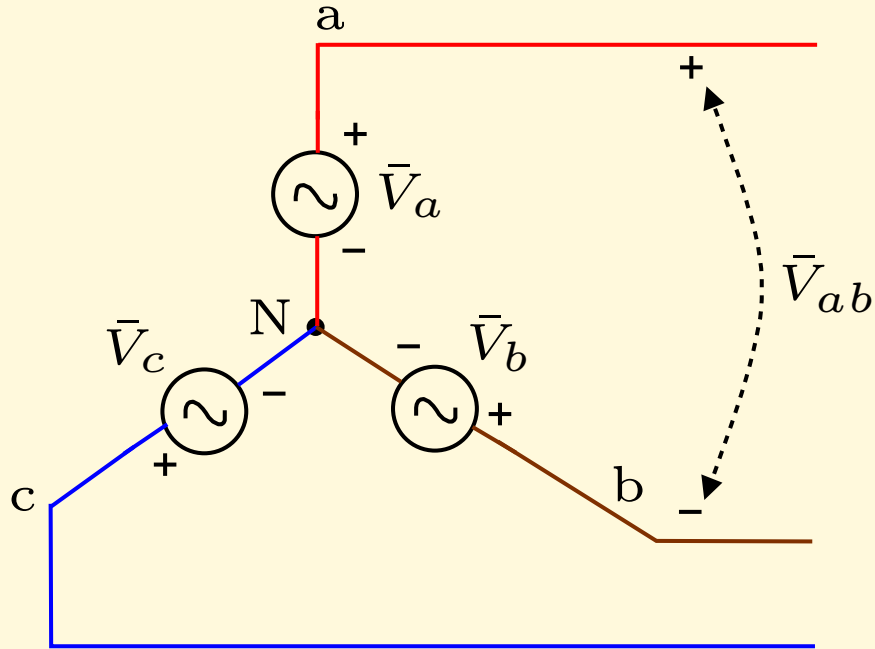


$\bar{V}_a, \bar{V}_b, \bar{V}_c$ : phase voltages.

$|\bar{V}_{ab}|$ : **line to line voltage.**

$$\bar{V}_{ab} = \bar{V}_a - \bar{V}_b = V_{rms} \angle \alpha - V_{rms} \angle (\alpha - 120^\circ)$$

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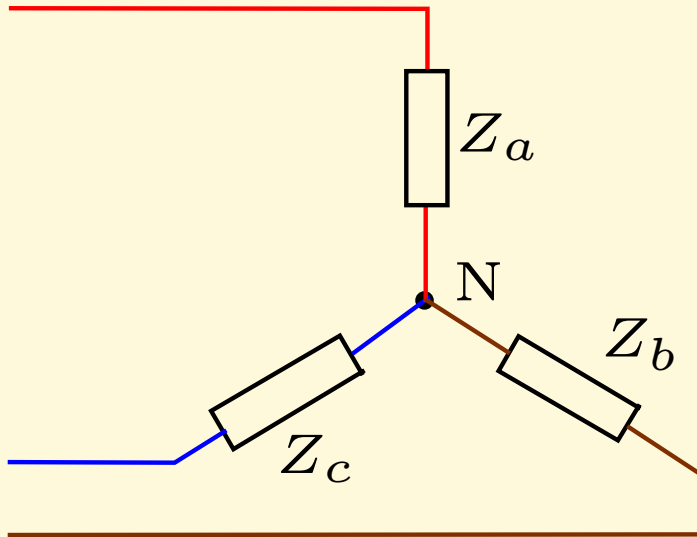
$|\bar{V}_{ab}|$ : **line to line voltage.**

$$\bar{V}_{ab} = \bar{V}_a - \bar{V}_b = V_{rms} \angle \alpha - V_{rms} \angle (\alpha - 120^\circ)$$

$$\bar{V}_{ab} = \sqrt{3} \times V_{rms} \angle (\alpha + 30^\circ) \text{ V.}$$

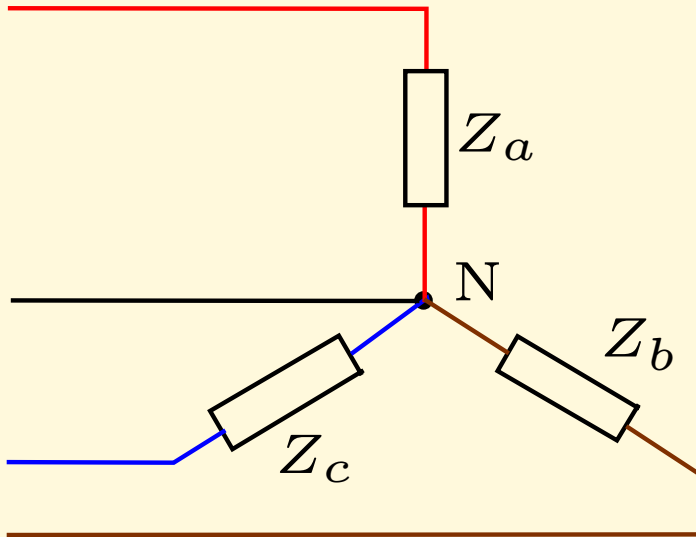
## Load configurations ...

Star connected three wire system



## Load configurations ...

Star connected four wire system



## Load configurations ...

Delta connected three wire system

