

Exciter and Governors

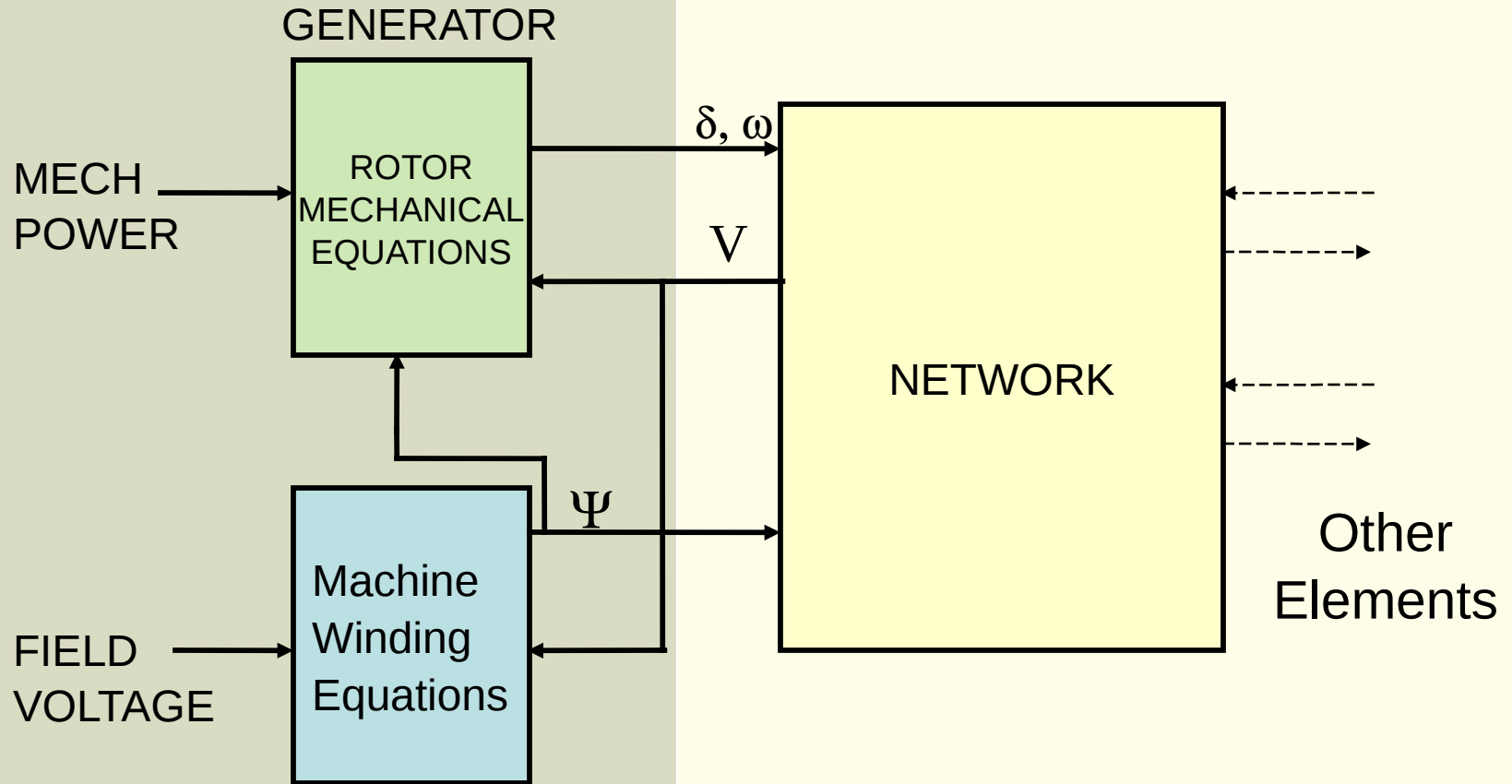


A.M.Kulkarni

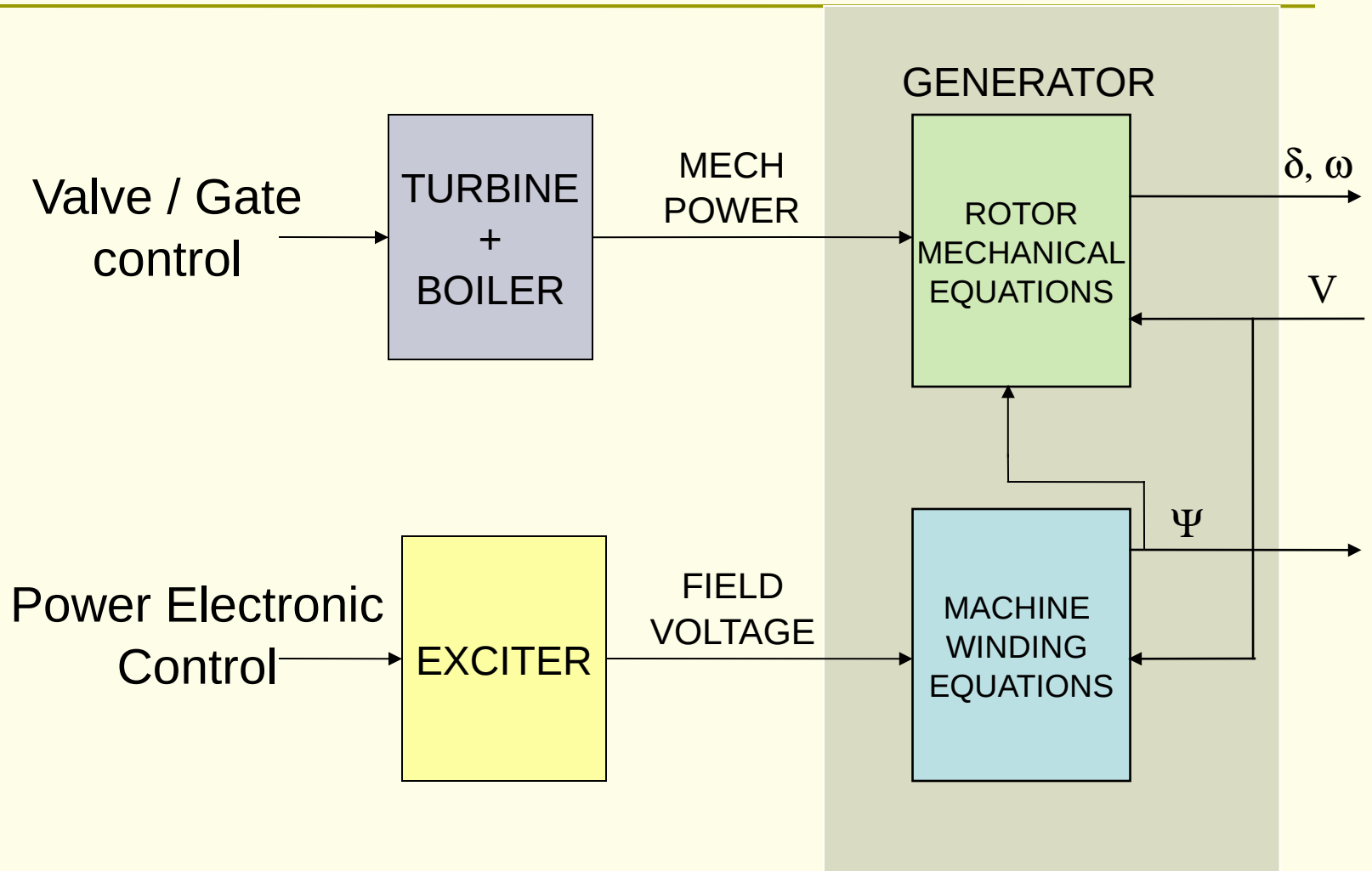
Department of Electrical
Engineering, IIT Bombay
Mumbai

Excitation Systems

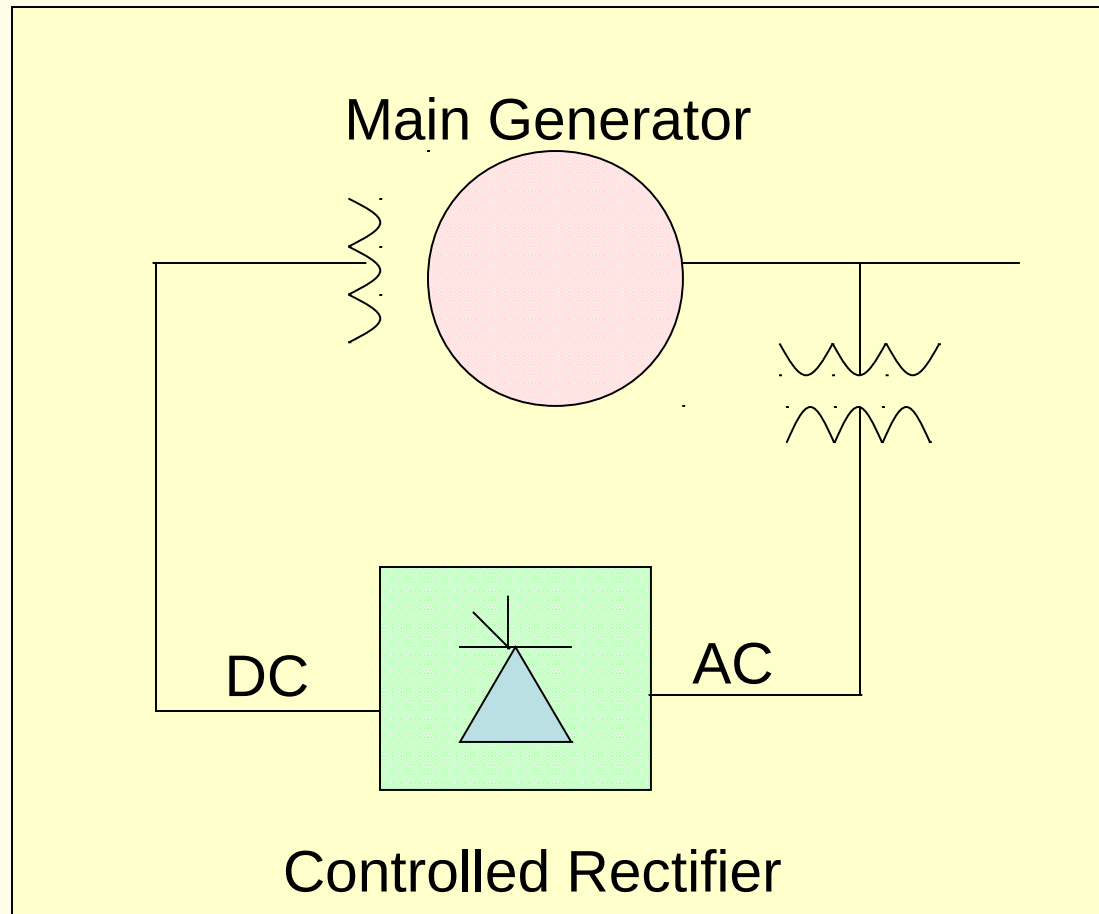
System Block Diagram



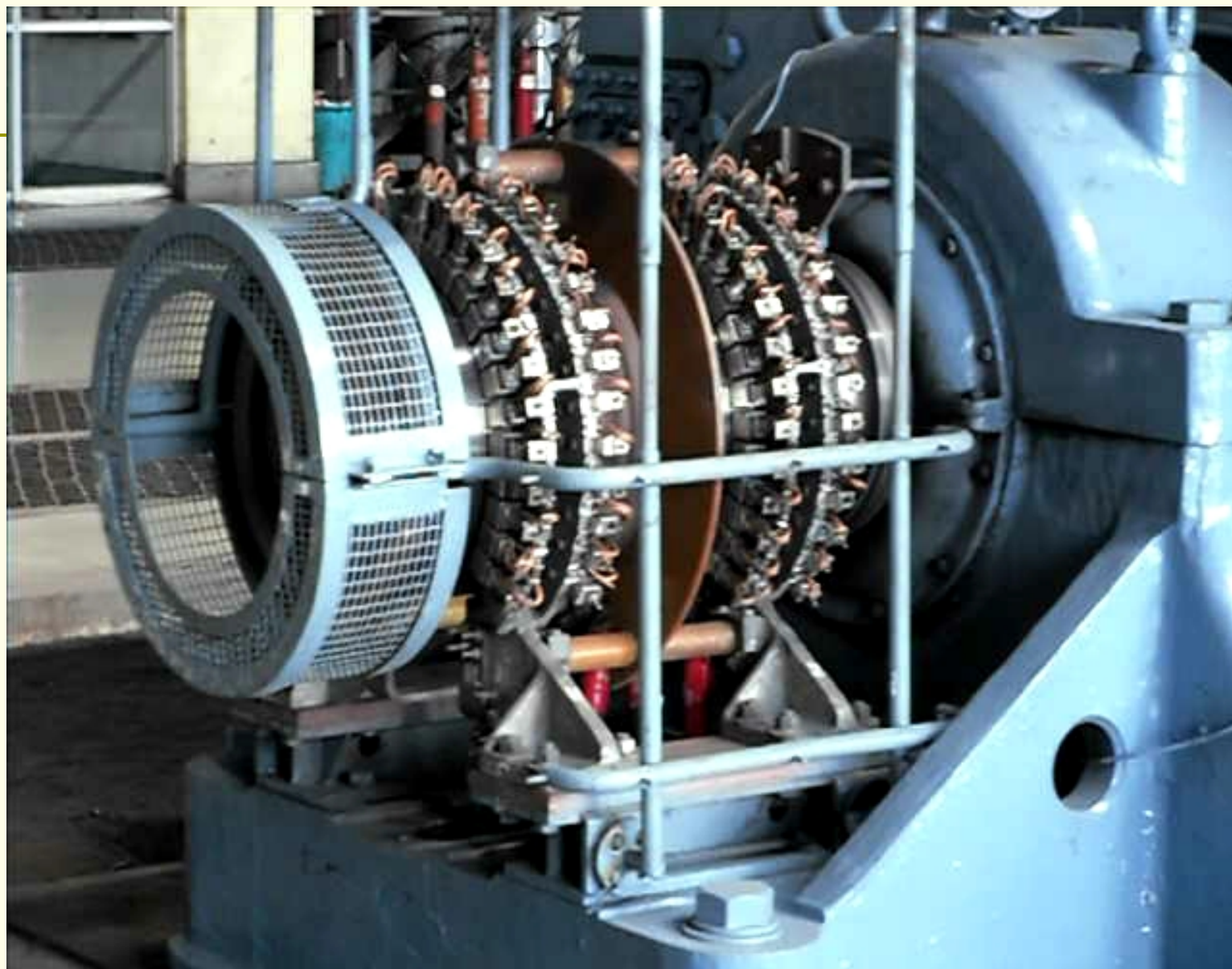
Additional Subsystems



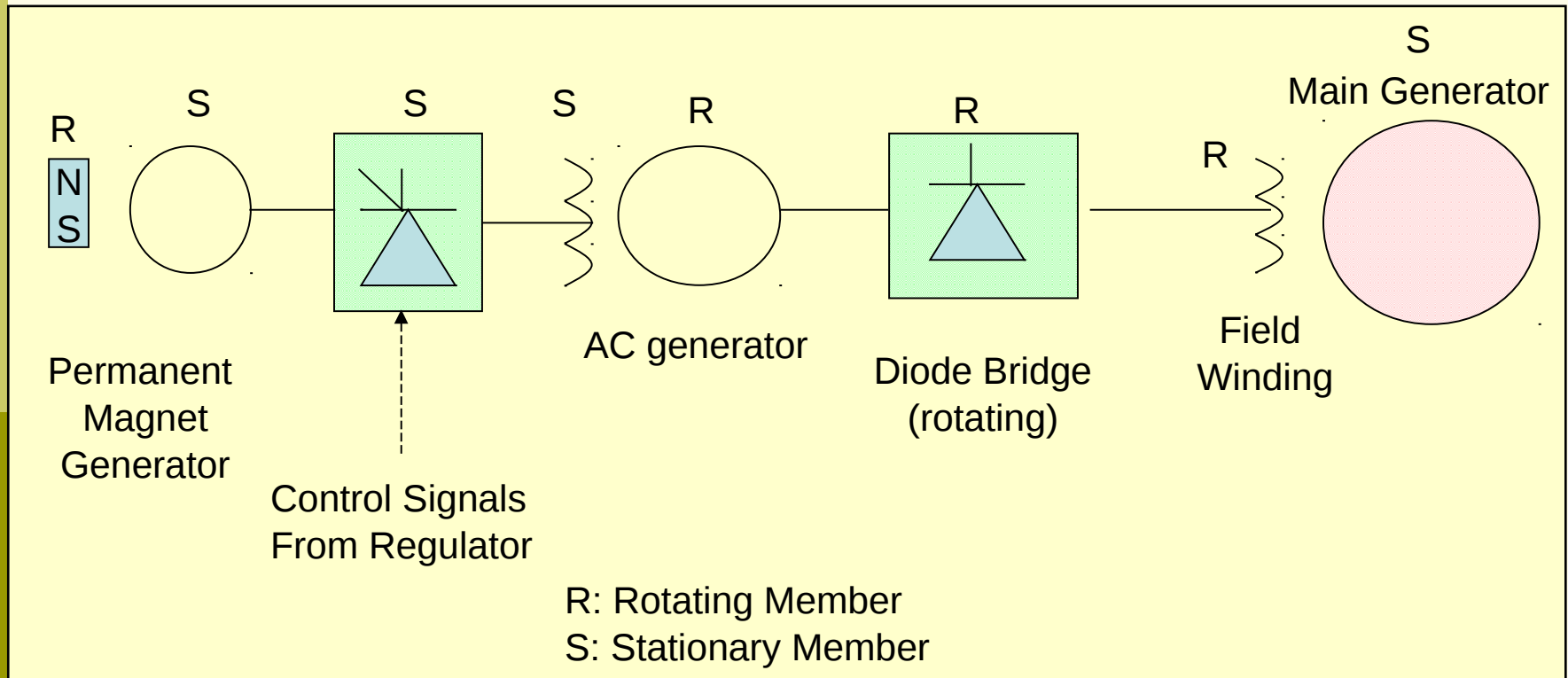
Static Excitation

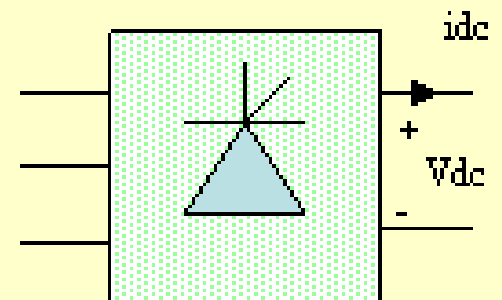
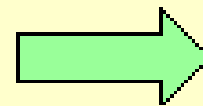
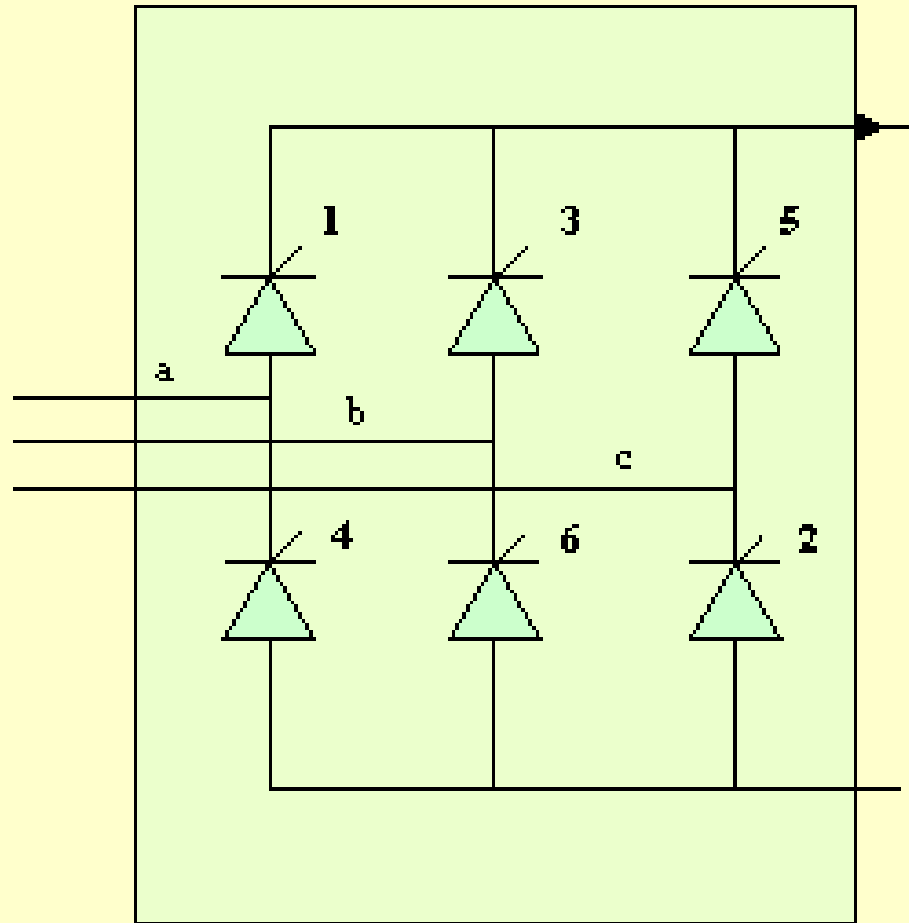






Brushless Excitation

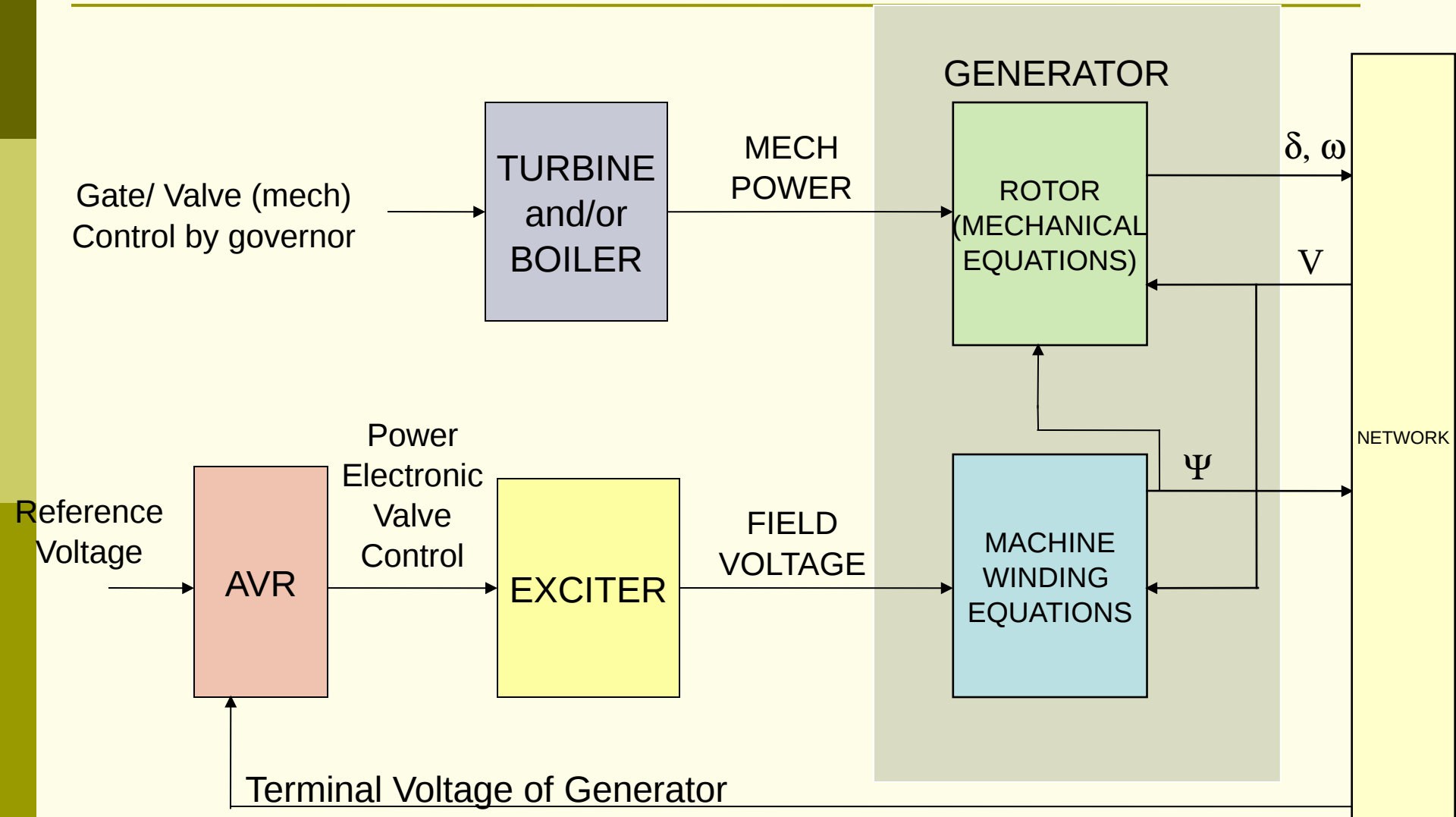




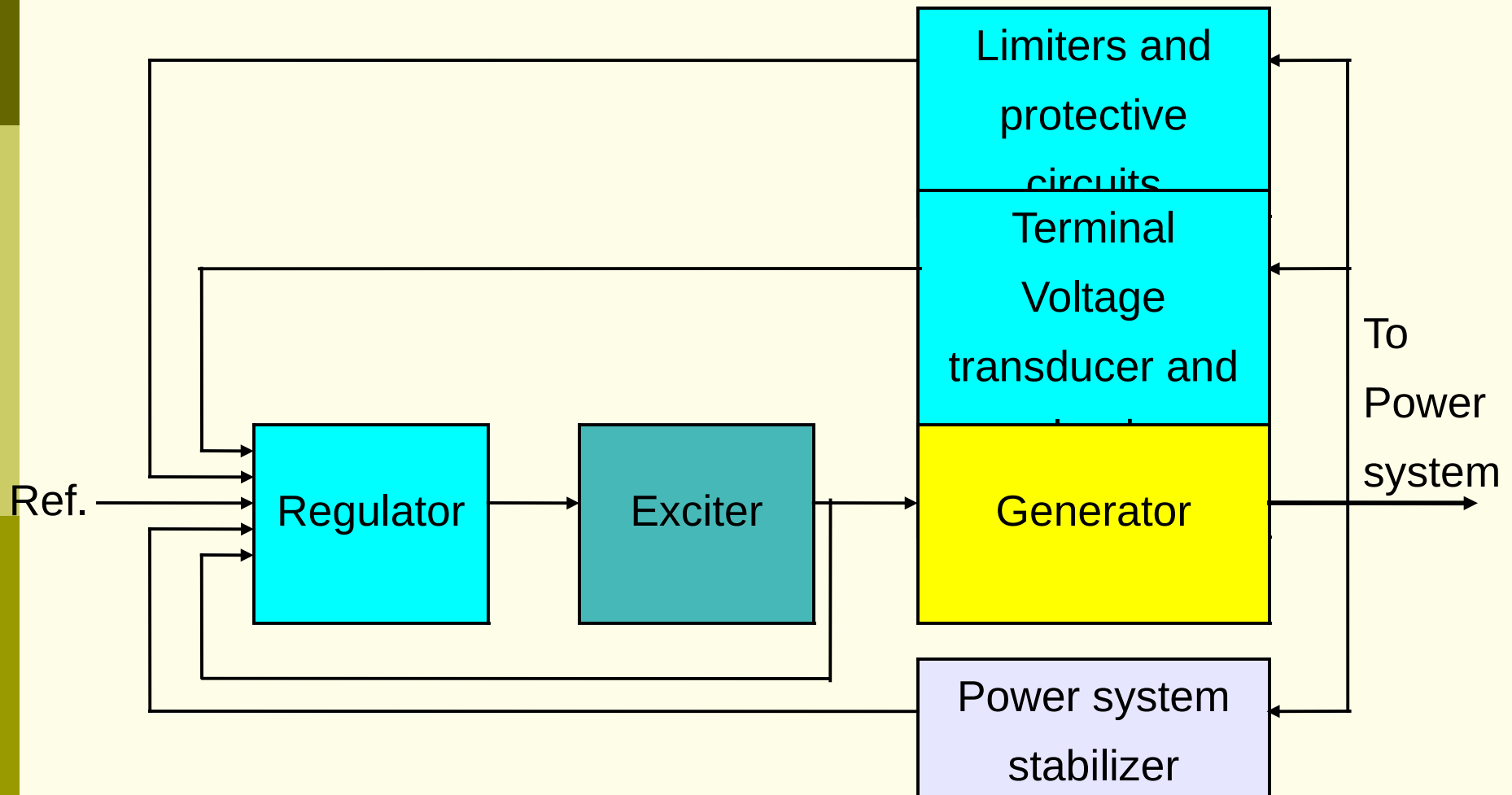
i_{dc} CANNOT be negative

V_{dc} can be positive or negative

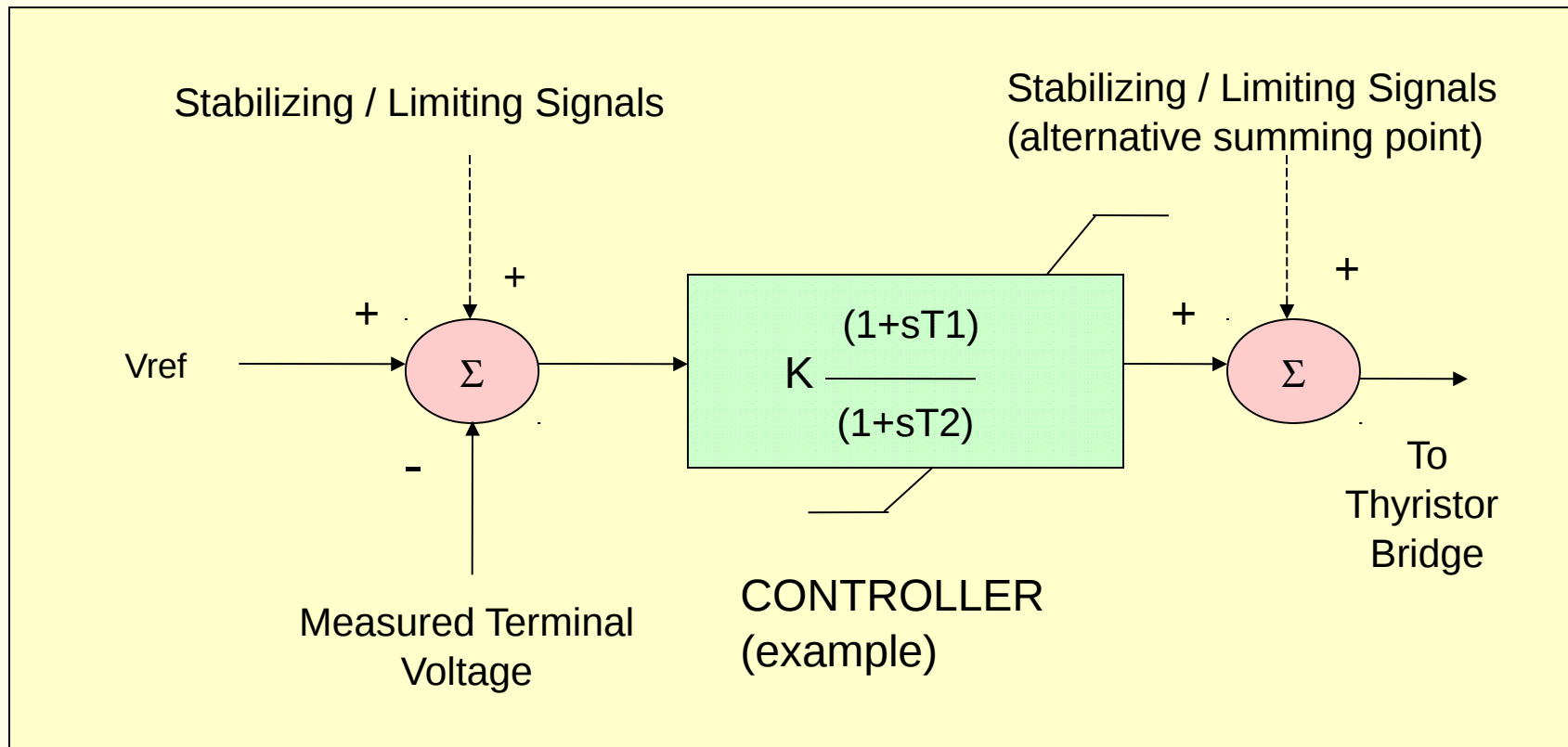
AVR



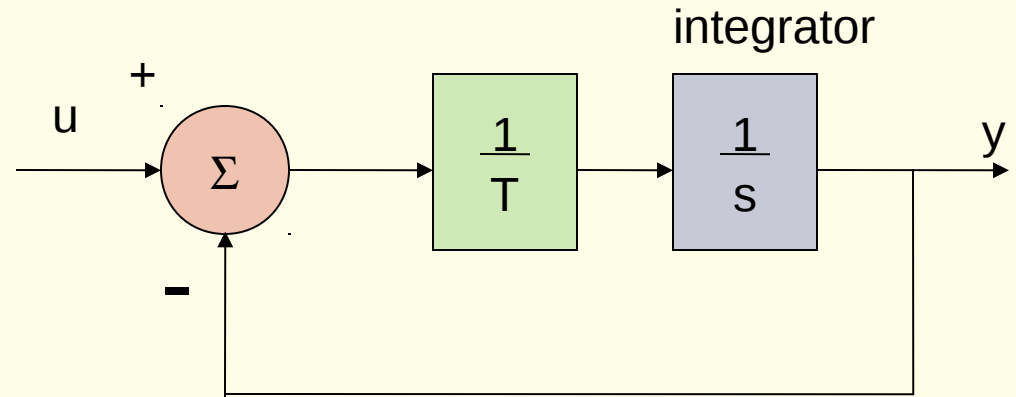
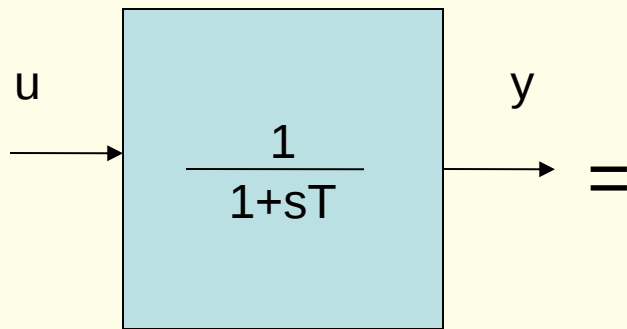
Functional block diagram (Kundur)



AVR Block Diagram - Example

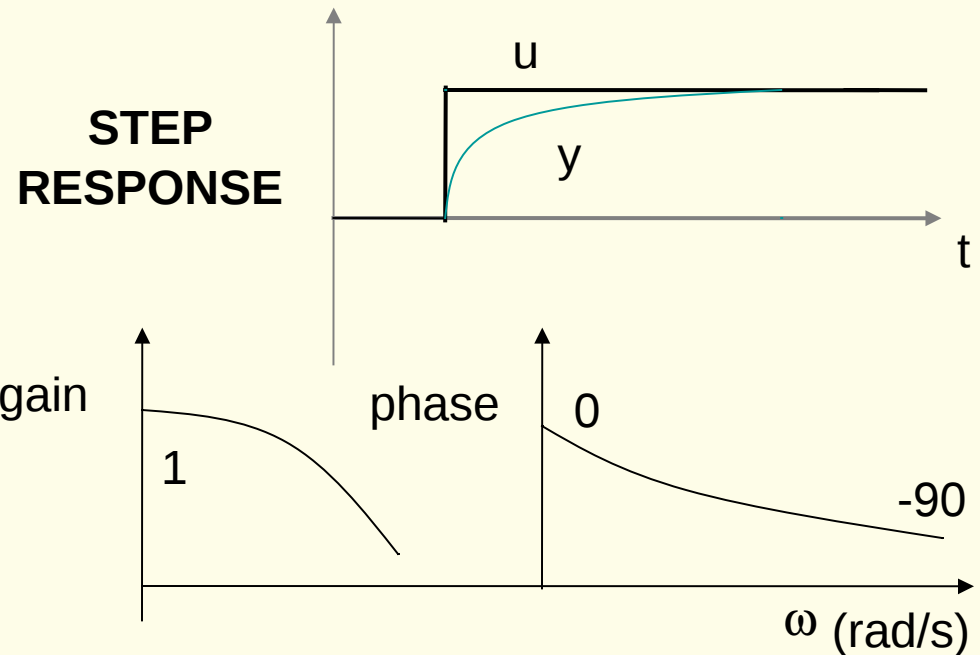


Understanding Transfer Functions

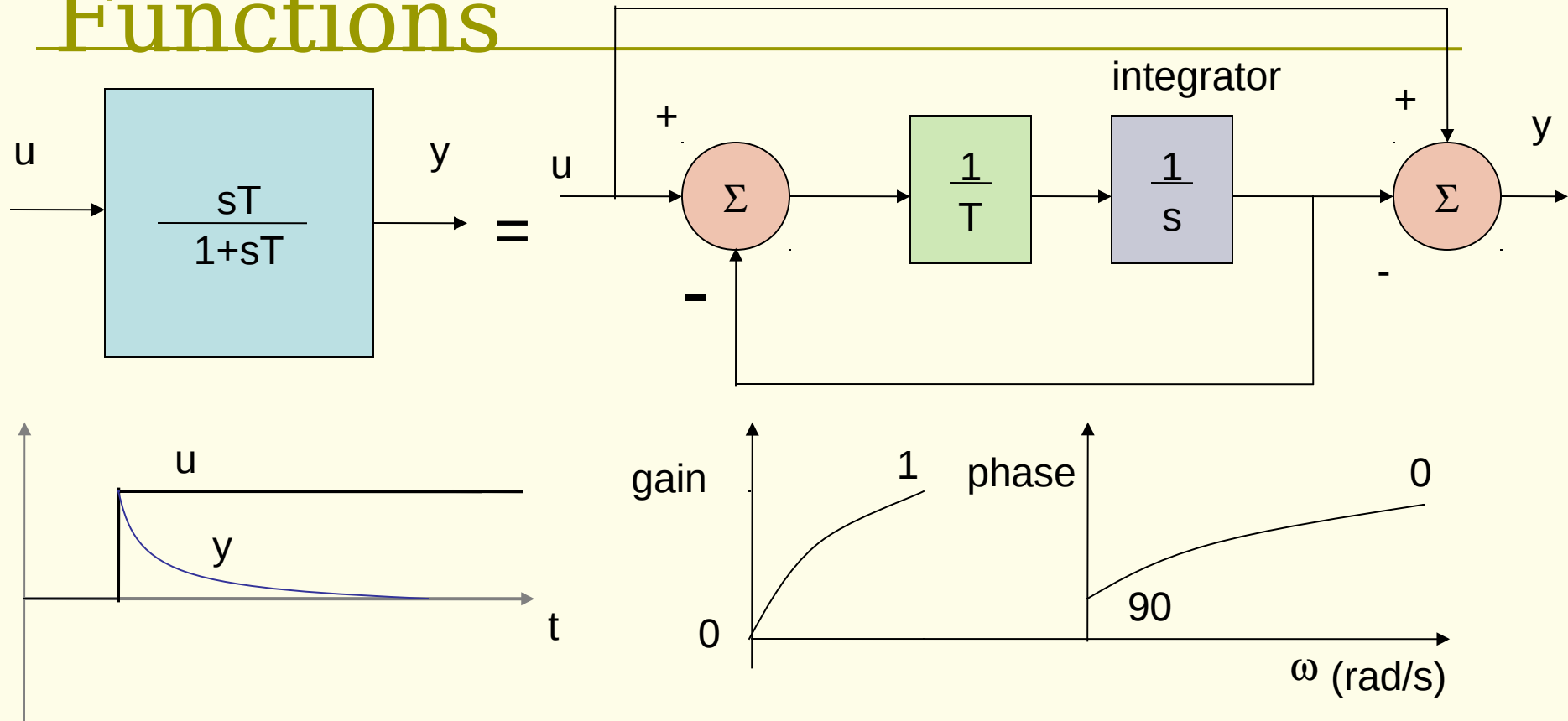


$$\frac{1}{s} \frac{u - y}{T} = y$$

**SINUSOIDAL STEADY
STATE RESPONSE
FOR VARIOUS FREQUENCIES**



Understanding Transfer Functions

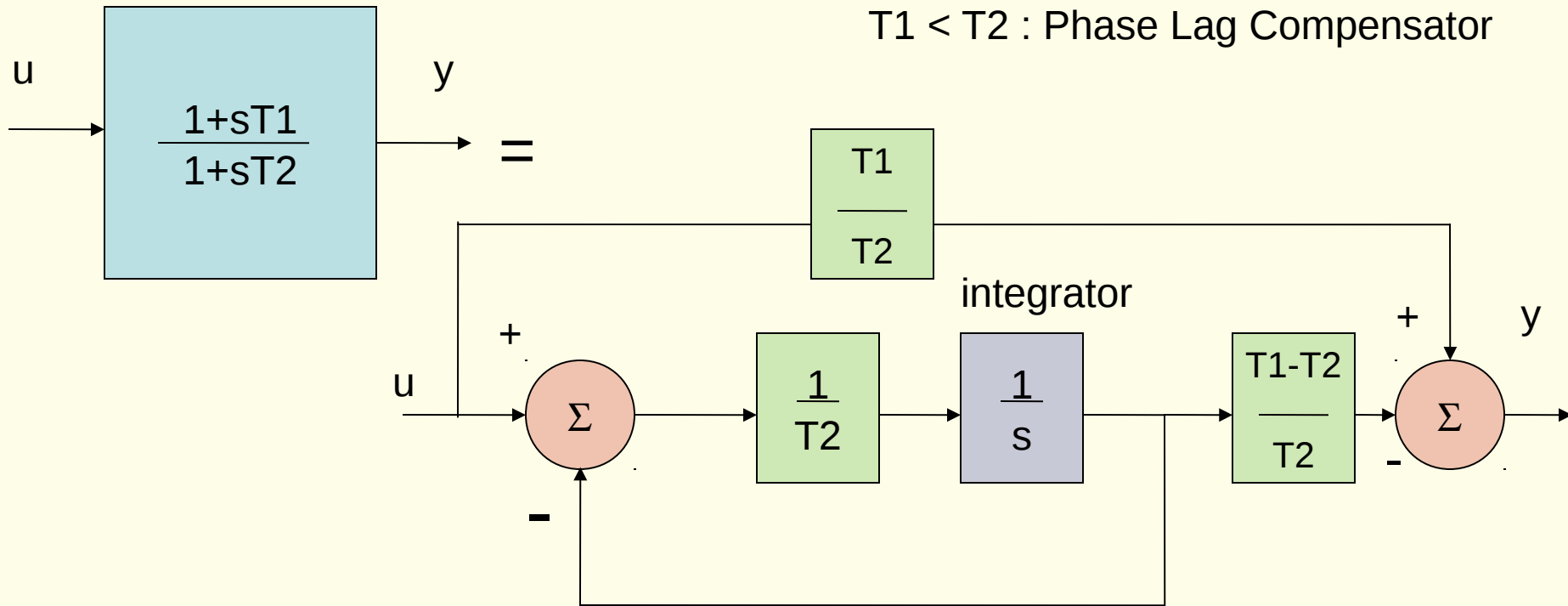


- Integration/Summing/Gains done by **OP-AMPS** in **Analog AVR**
- Integration/Summing/Gains done by **numerical algorithms** in **Digital AVR (DVR)**

Understanding Transfer Functions

$T1 > T2$: Phase Lead Compensator

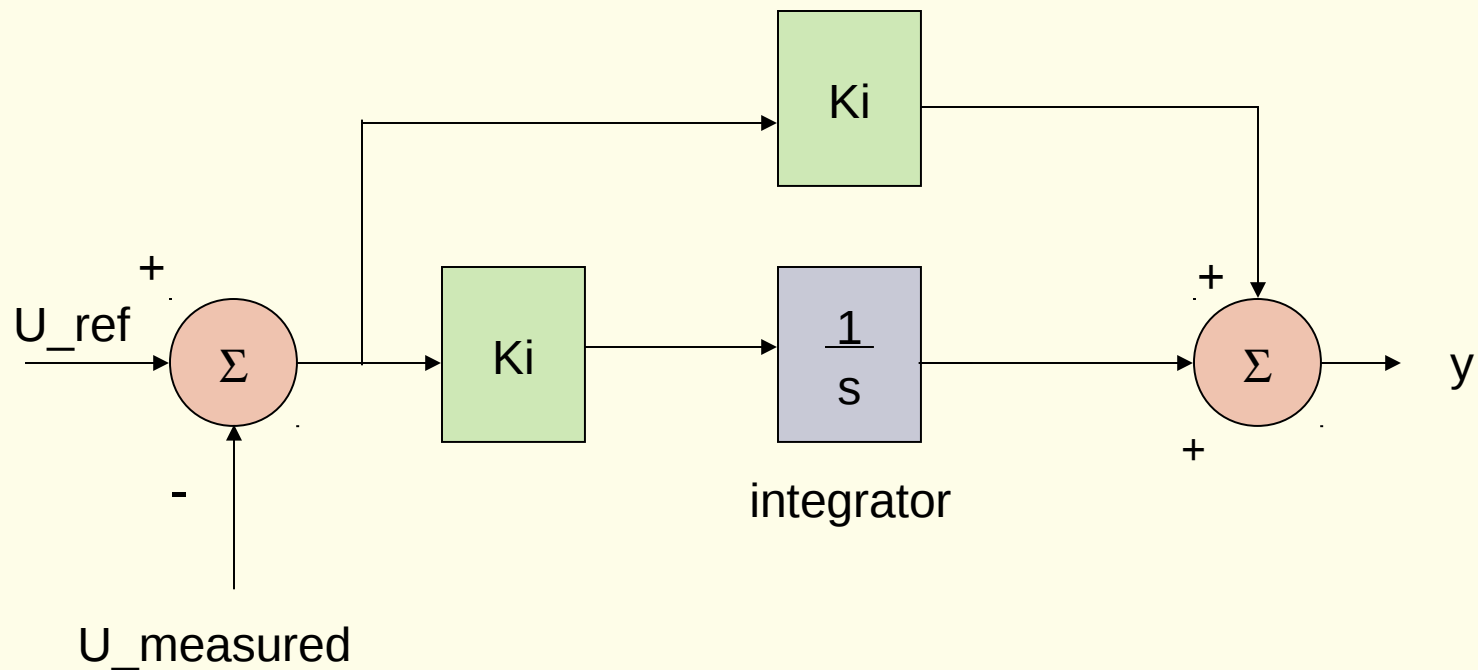
$T1 < T2$: Phase Lag Compensator



- Integration/Summing/Gains done by **OP-AMPS** in **Analog AVR**
- Integration/Summing/Gains done by **numerical algorithms** in **Digital AVR (DVR)**

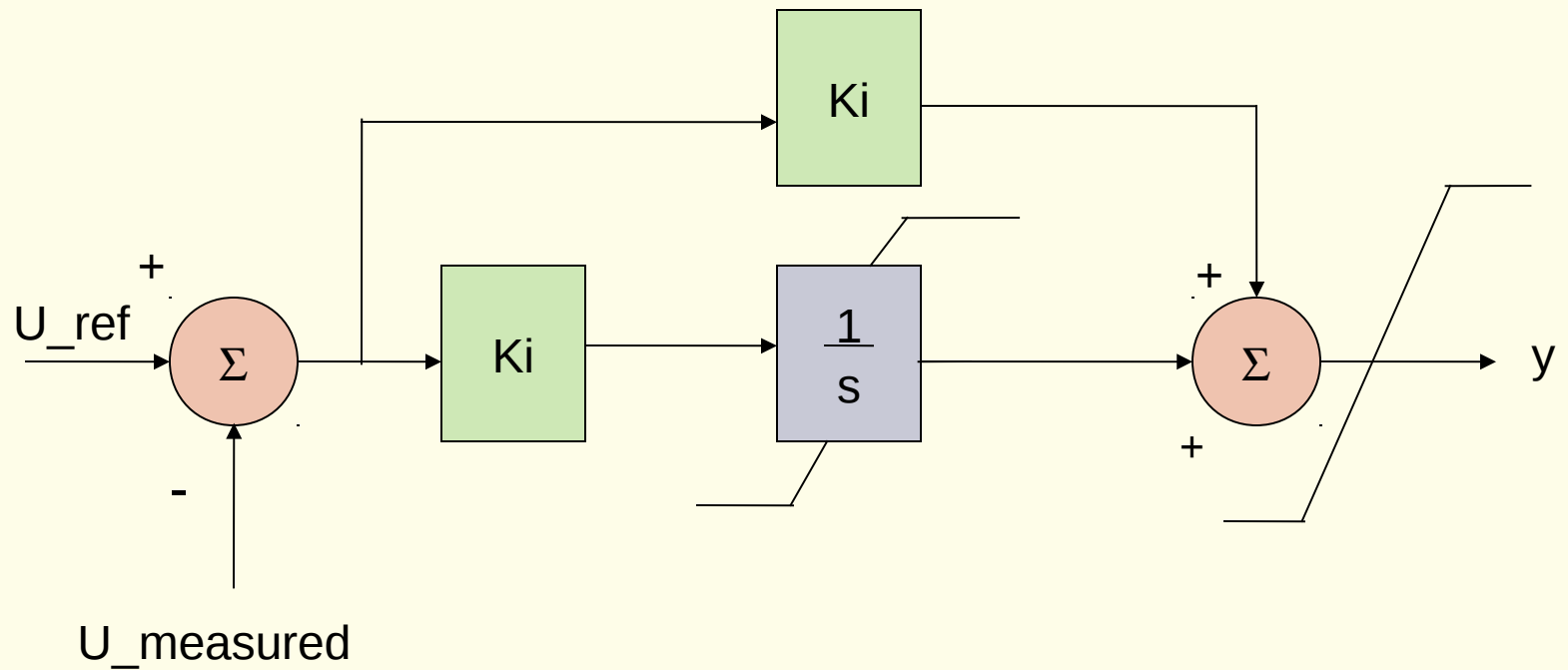
Understanding Transfer Functions

P-I Regulator



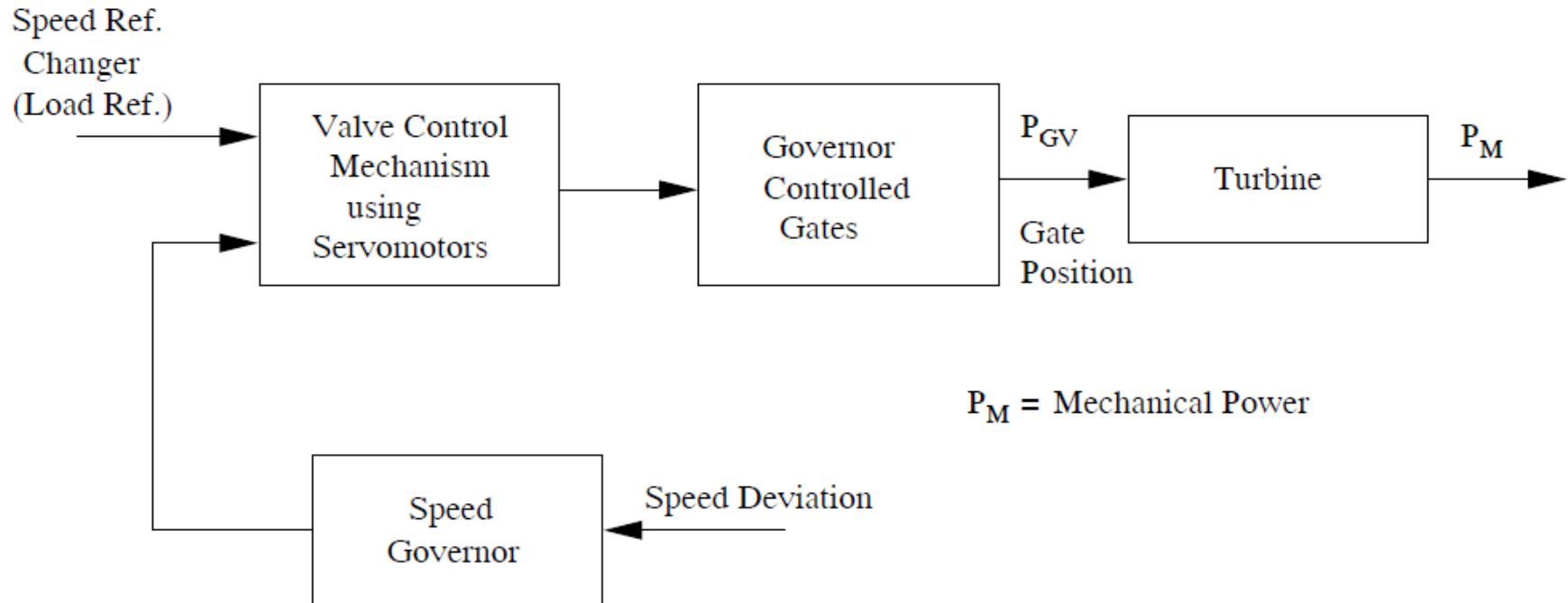
Steady State Error ?

Limiters

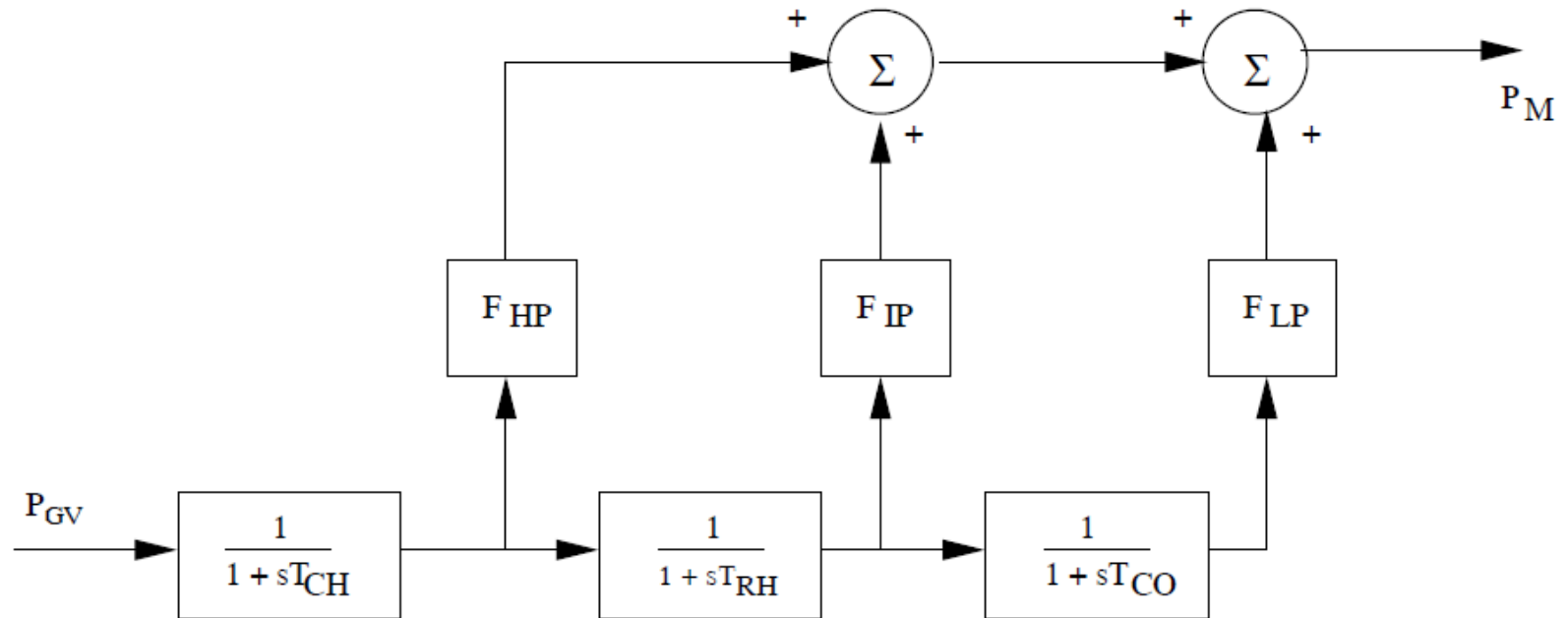


Hard and Soft limiters

Mechanical System

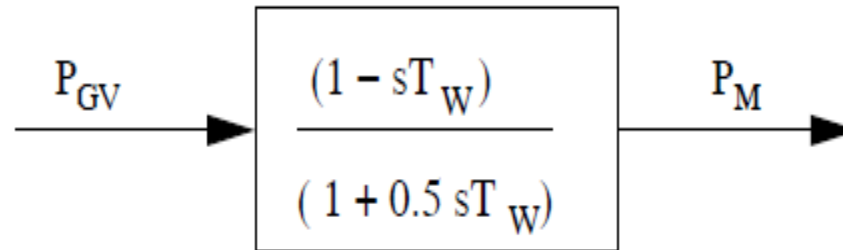


Tandem Compound Single Reheat (Steam Turbine)



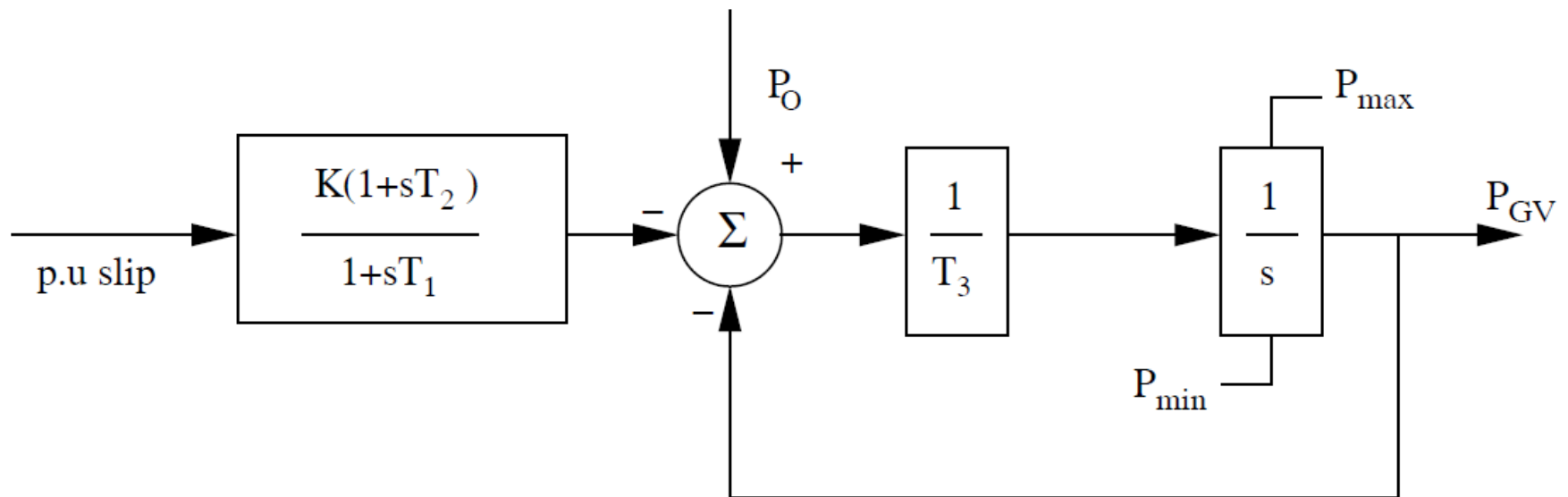
$T_{CH} = 0.1-0.4 \text{ s}$	$T_{RH} = 4-11 \text{ s}$	$T_{CO} = 0.3-0.5 \text{ s}$
$F_{HP} = 0.3$	$F_{IP} = 0.3$	$F_{LP} = 0.4$

Hydraulic Turbine Model



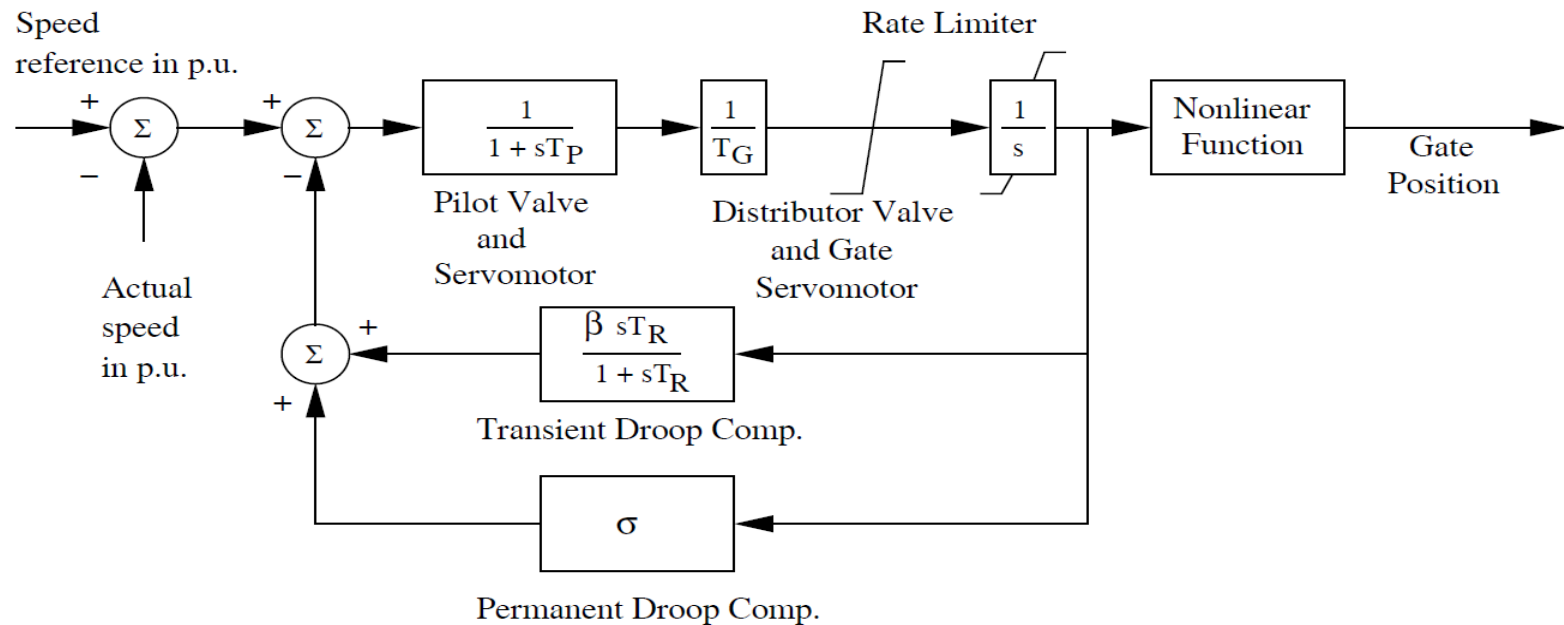
0.5 to 5 s

Governor Model (General Purpose) for Steam Turbines



$T_1 = 0.2 \text{ s}$	$T_2 = 0$	$T_3 = 0.1 \text{ s}$
$P_{\max} = 1.1 P_o$	$P_{\min} = 0.1 P_o$	

Governor (Hydraulic Turbine)



In the above figure, T_R and β are calculated as

$$T_R = 5T_W, \quad \beta = \frac{1.25T_W}{H}$$

where

T_W = water time constant.

H = inertia constant of a machine.

$T_W = 1.0 \text{ s}$	$T_G = 0.2 \text{ s}$	$T_2 = 0$
$\sigma = 0.05$		

Typical values of parameters for speed-governor of hydro turbines.