



**DEPARTMENT OF COMPUTER & SOFTWARE
ENGINEERING
COLLEGE OF E&ME, NUST, RAWALPINDI**



Digital Image Processing

Assignment #02

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Degree/ Syndicate: **43 CE B**

Retinal Image Segmentation and Objects Analysis

Introduction

The aim of this assignment is to use knowledge about spatial enhancement and segmentation to extract optic disc from given images.

Understanding the Assignment

Assignment Overview

The assignment at hand pertains to **Digital Image Processing** focusing on retinal image analysis, specifically targeting the segmentation and analysis of objects within fundus images.

Key Objectives

- **Spatial Enhancement and Filtering:** Employing transformation and filtering techniques for spatial enhancement.
- **Segmentation:** Extracting specific objects, particularly the optic disc, from fundus images.
- **Error Analysis:** Evaluating the accuracy of segmentation through error calculation.

Spatial Enhancement and Filtering

Spatial enhancement techniques involving transformation and image filtering play a vital role in preprocessing fundus images. These techniques aim to enhance specific features and improve the overall quality of the images, thereby facilitating subsequent analysis tasks.

Segmentation of Optic Disc

Understanding Fundus Images

Fundus images, capturing the retina's inner surface, serve as crucial diagnostic tools for various retinal diseases. Key landmarks within these images include the optic disc, blood vessels, and fovea.

Optic Disc Extraction

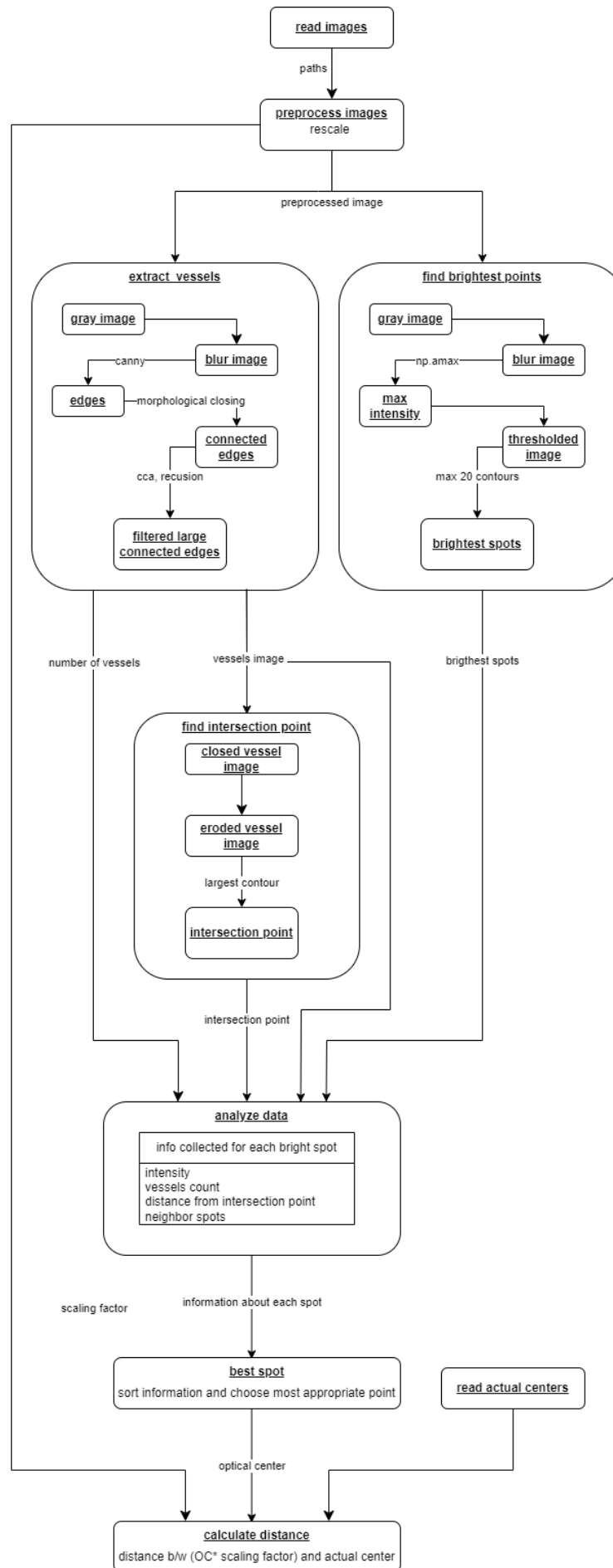
The primary objective of the assignment is to extract the optic disc from fundus images using spatial enhancement and segmentation techniques. This process involves identifying and isolating the bright region corresponding to the optic disc while mitigating potential false positives from other bright lesions.

Algorithmic Approach

1. **pre_process_image:**
 - Explanation: This function resizes an image to a specified size and returns the resized image along with the scaling factor used for resizing.

- Working: It calculates the scaling factor required to resize the image to the desired size. Then, it resizes the image using OpenCV's **cv2.resize** function and returns the resized image along with the scaling factor.
2. **extract_vessels:**
 - Explanation: This function extracts blood vessels from a retinal image using image processing techniques.
 - Working: It converts the input image to grayscale, applies Gaussian blur and Canny edge detection to detect edges of blood vessels. Then, it uses connected component analysis to identify connected regions (vessels) and filters out small components based on the minimum component area.
 3. **find_brightest_spots:**
 - Explanation: This function finds the brightest spots in an image, typically representing potential locations of the optic disc.
 - Working: It converts the input image to grayscale, applies Gaussian blur, and performs thresholding to identify bright regions. Then, it finds contours of these regions and selects the largest ones as the brightest spots.
 4. **find_intersection_point:**
 - Explanation: This function detects the intersection point of blood vessels in an image, which often corresponds to the location of the optic disc.
 - Working: It applies morphological operations to the input image to close gaps between vessel segments. Then, it finds contours and calculates the centroid of the largest contour as the intersection point.
 5. **analyze_data:**
 - Explanation: This function analyzes the characteristics of bright spots in an image, including intensity, vessel count, and distance from the intersection point.
 - Working: It iterates over each bright spot, masks the image around the spot, and calculates intensity and vessel count. It also calculates the distance from the intersection point and counts neighboring spots within a certain radius.
 6. **find_best_spot:**
 - Explanation: This function identifies the best candidate spot for the optic disc based on vessel count, intensity, distance from the intersection point, and the number of neighboring spots.
 - Working: It sorts the information of each spot based on specified criteria and returns the center of the spot with the highest score, which is considered the best candidate for the optic disc.

Detailed Flow Diagram



Example information about spot table:

Optic Disk Information:				
Center	Intensity	Vessel Count	Dst from IP	Nbr Spots
(423, 265)	1.49	1535	23	8
(423, 265)	1.47	1514	28	8
(423, 265)	1.45	1494	33	8
(423, 265)	1.43	1473	26	8
(423, 265)	1.42	1461	40	8
(423, 265)	1.41	1452	14	8
(423, 265)	1.34	1377	17	8
(399, 311)	1.3	1333	52	0
(394, 316)	1.26	1298	59	0
(423, 265)	1.19	1224	32	8
(380, 310)	1.13	1158	62	0
(423, 265)	1.09	1125	39	8
(370, 325)	1.03	1059	80	0
(356, 334)	0.95	976	96	0
(418, 205)	0.83	854	60	0
(330, 360)	0.81	830	133	0
(383, 204)	0.6	612	73	0

Optic Disk Information:				
Center	Intensity	Vessel Count	Dst from IP	Nbr Spots
(320, 229)	1.04	1070	33	9
(320, 229)	1.04	1069	35	9
(320, 229)	1.0	1024	48	9
(320, 229)	0.99	1013	14	9
(320, 229)	0.98	1003	38	9
(320, 229)	0.94	963	22	9
(320, 229)	0.92	947	36	9
(320, 229)	0.92	944	22	9
(320, 229)	0.89	912	28	9
(320, 229)	0.8	819	46	9
(108, 76)	0.42	429	261	0
(57, 189)	0.23	238	266	0

Optic Disk Information:				
Center	Intensity	Vessel Count	Dst from IP	Nbr Spots
(419, 234)	0.63	652	29	5
(419, 234)	0.52	538	26	5
(419, 234)	0.49	505	13	5
(419, 234)	0.49	499	17	5
(419, 234)	0.48	489	9	5
(419, 234)	0.46	476	20	5
(126, 334)	0.15	156	310	0
(248, 493)	0.03	33	310	0
(39, 157)	0.02	22	388	0
(35, 164)	0.01	13	390	0
(33, 169)	0.01	8	391	0

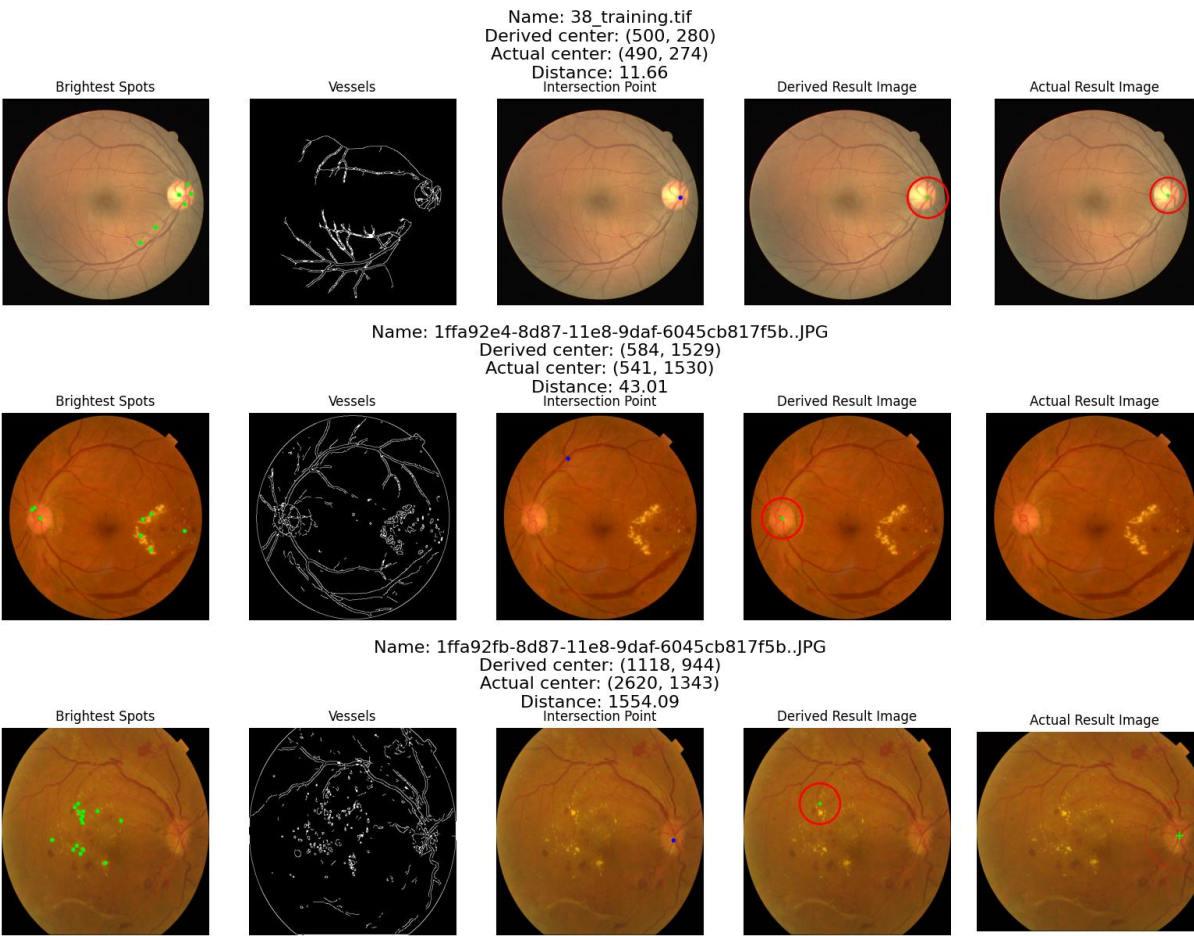
Results:

Sr no.	Image	Derived OC	Actual OC	Distance
1	02_test.tif	(466, 302)	(458, 275)	28.16
2	04_test.tif	(353, 261)	(361, 275)	16.12
3	06_test.tif	(462, 266)	(461, 268)	2.24
4	08_test.tif	(455, 278)	(485, 277)	30.02
5	10_left.jpeg	(2208, 2023)	(2439, 1697)	399.55

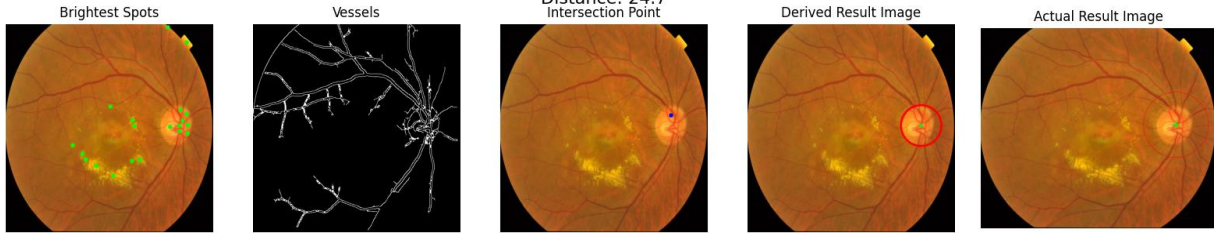
6	10_right.jpeg	(3331, 2320)	(2985, 1562)	833.23
7	10_test.tif	(472, 277)	(468, 278)	4.12
8	12_test.tif	(94, 233)	(82, 257)	26.83
9	13_left.jpeg	(486, 960)	(504, 832)	129.26
10	13_right.jpeg	(2080, 842)	(2119, 852)	40.26
11	13_test.tif	(472, 273)	(486, 268)	14.87
12	14_test.tif	(423, 449)	(479, 275)	182.79
13	15_test.tif	(201, 318)	(193, 282)	36.88
14	16_test.tif	(477, 295)	(479, 258)	37.05
15	17_left.jpeg	(1450, 1042)	(1396, 1322)	285.16
16	17_test.tif	(476, 279)	(467, 267)	15
17	18_test.tif	(451, 277)	(471, 262)	25
18	19_left.jpeg	(1427, 1306)	(1445, 1176)	131.24
19	19_right.jpeg	(2376, 1280)	(2456, 1269)	80.75
20	19_test.tif	(483, 281)	(486, 275)	6.71
21	1ffa92e4-8d87-11e8-9daf-6045cb817f5b..JPG	(584, 1529)	(541, 1530)	43.01
22	1ffa92fb-8d87-11e8-9daf-6045cb817f5b..JPG	(1118, 944)	(2620, 1343)	1554.09
23	1ffa9309-8d87-11e8-9daf-6045cb817f5b..JPG	(1219, 1039)	(609, 1167)	623.28
24	1ffa9523-8d87-11e8-9daf-6045cb817f5b..JPG	(684, 1085)	(652, 1070)	35.34
25	1ffa952f-8d87-11e8-9daf-6045cb817f5b..JPG	(2546, 1255)	(2523, 1246)	24.7
26	1ffa9555-8d87-11e8-9daf-6045cb817f5b..JPG	(452, 1436)	(512, 1501)	88.46
27	20_left.jpeg	(2513, 1508)	(2539, 1513)	26.48
28	20_right.jpeg	(1306, 1285)	(1293, 1296)	17.03
29	20_test.tif	(482, 280)	(482, 284)	4
30	21_left.jpeg	(1327, 2493)	(1724, 1589)	987.33
31	21_right.jpeg	(3146, 1404)	(3036, 1556)	187.63
32	21_training.tif	(173, 163)	(77, 257)	134.36
33	22_left.jpeg	(810, 821)	(747, 848)	68.54
34	22_right.jpeg	(1855, 873)	(1821, 910)	50.25
35	22_training.tif	(494, 282)	(471, 272)	25.08
36	23_left.jpeg	(1306, 1078)	(1417, 1127)	121.33
37	23_right.jpeg	(2073, 597)	(2676, 1242)	882.97
38	23_training.tif	(343, 344)	(428, 227)	144.62
39	24_training.tif	(484, 257)	(472, 289)	34.18
40	25_left.jpeg	(2543, 1442)	(2635, 1455)	92.91
41	25_right.jpeg	(896, 1817)	(791, 1846)	108.93
42	25_training.tif	(466, 278)	(464, 270)	8.25
43	26_training.tif	(101, 236)	(80, 245)	22.85
44	27_training.tif	(483, 287)	(492, 283)	9.85

45	29_training.tif	(496, 293)	(497, 271)	22.02
46	30_training.tif	(470, 292)	(492, 291)	22.02
47	31_left.jpeg	(3214, 2932)	(1665, 1542)	2081.23
48	31_right.jpeg	(3715, 1402)	(3366, 1536)	373.84
49	31_training.tif	(399, 268)	(393, 250)	18.97
50	32_training.tif	(472, 288)	(491, 285)	19.24
51	33_left.jpeg	(2512, 2639)	(1657, 1592)	1351.75
52	33_training.tif	(460, 292)	(470, 305)	16.4
53	34_training.tif	(273, 281)	(388, 223)	128.8
54	35_training.tif	(101, 272)	(81, 276)	20.4
55	37_training.tif	(499, 288)	(496, 292)	5
56	38_training.tif	(500, 280)	(490, 274)	11.66

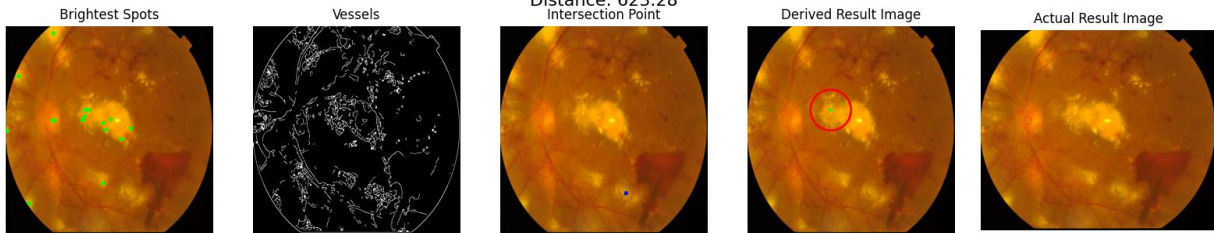
Outputs:



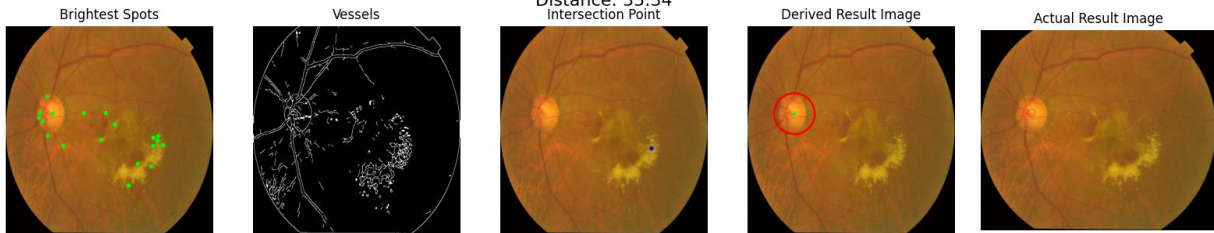
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Actual center: (2523, 1246)
Distance: 24.7
Intersection Point



Name: 1ffa9309-8d87-11e8-9daf-6045cb817f5b..JPG
Derived center: (1219, 1039)
Actual center: (609, 1167)
Distance: 623.28
Intersection Point



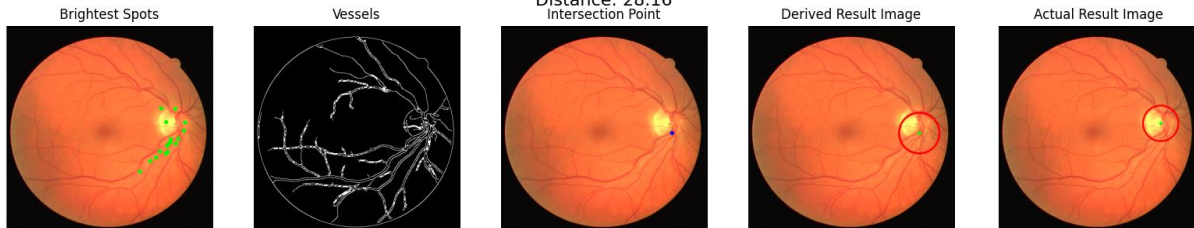
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Actual center: (652, 1070)
Distance: 35.34
Intersection Point

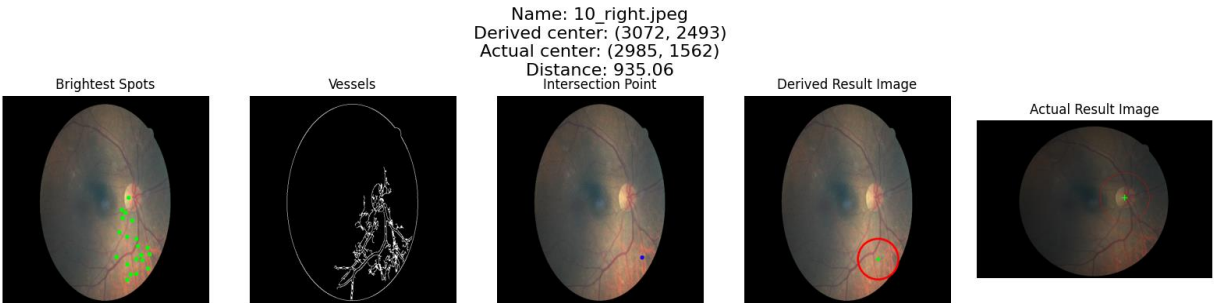
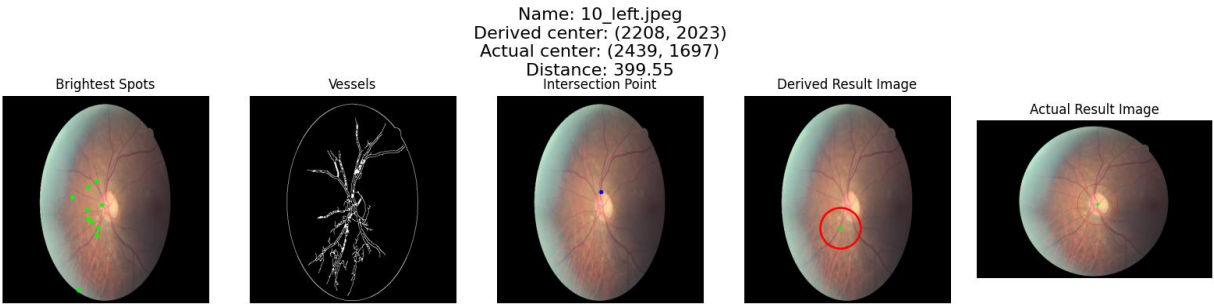
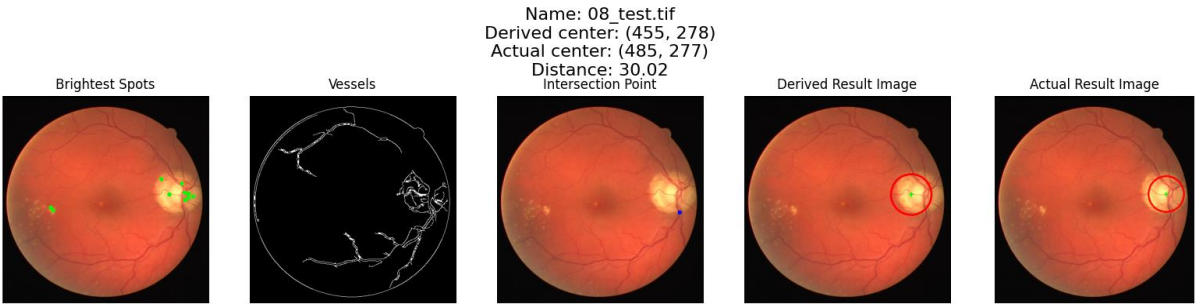
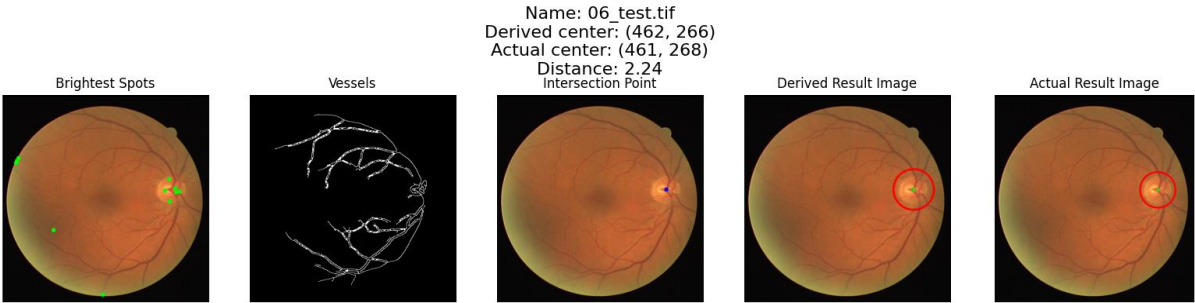
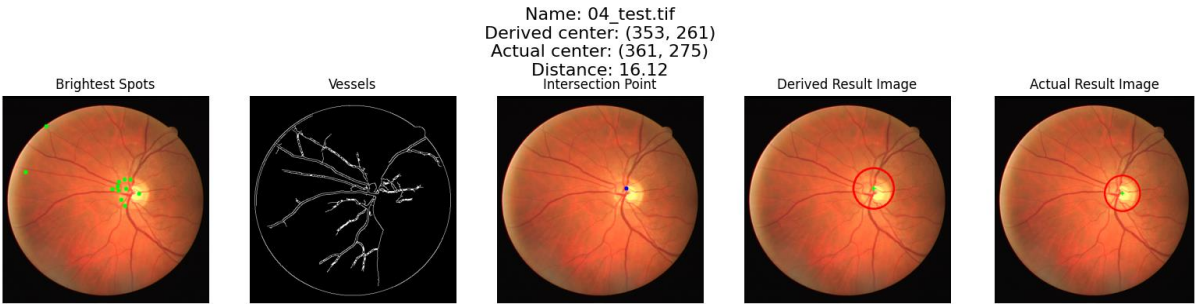


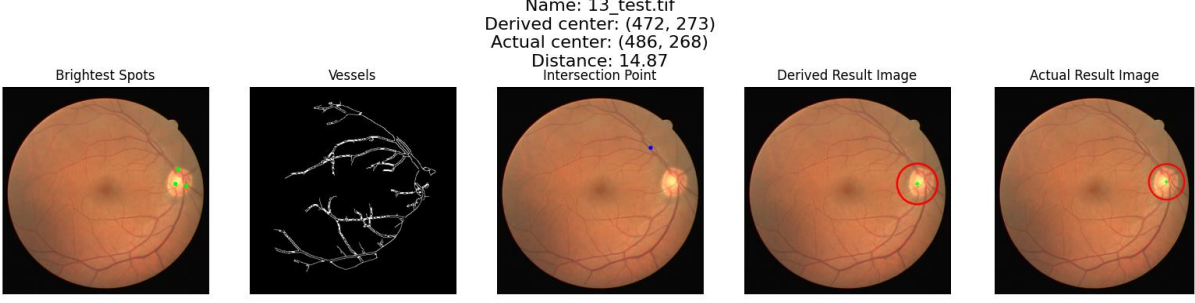
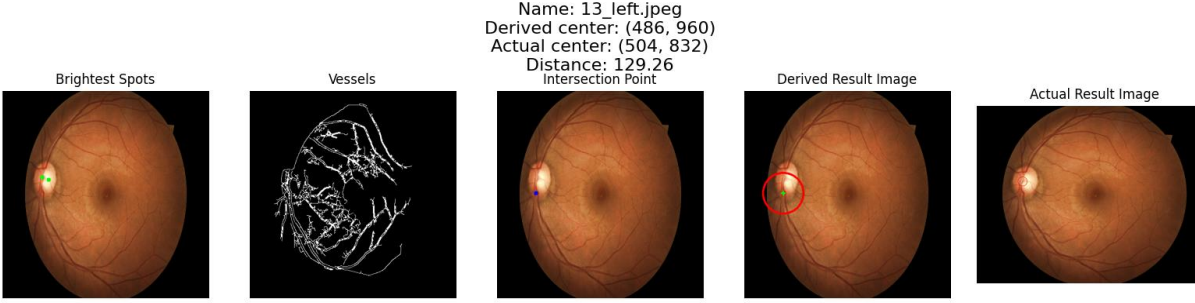
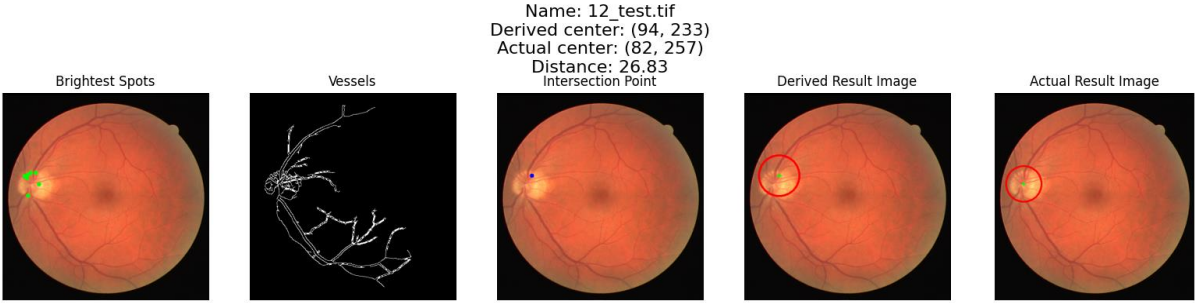
Name: 1ffa9555-8d87-11e8-9daf-6045cb817f5b..JPG
Derived center: (452, 1436)
Actual center: (512, 1501)
Distance: 88.46
Intersection Point

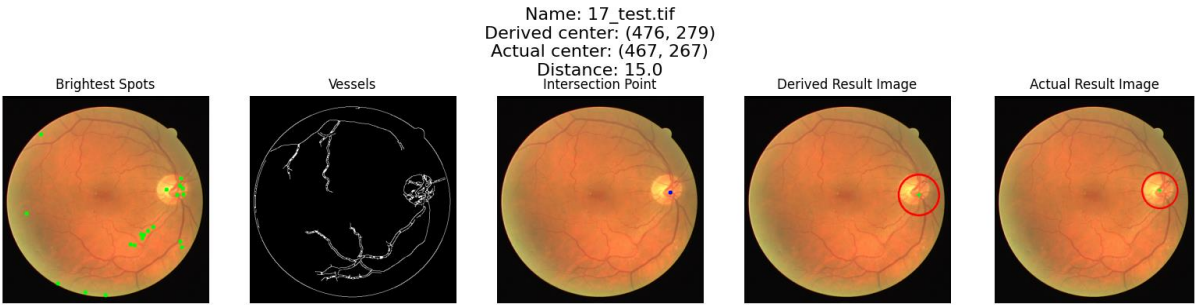
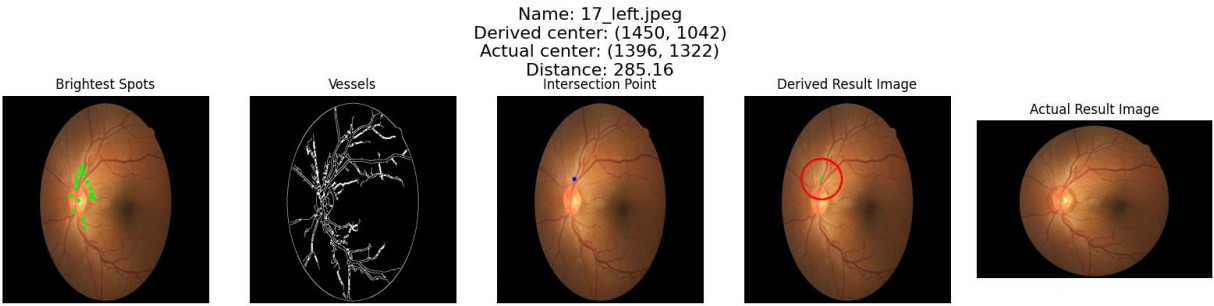
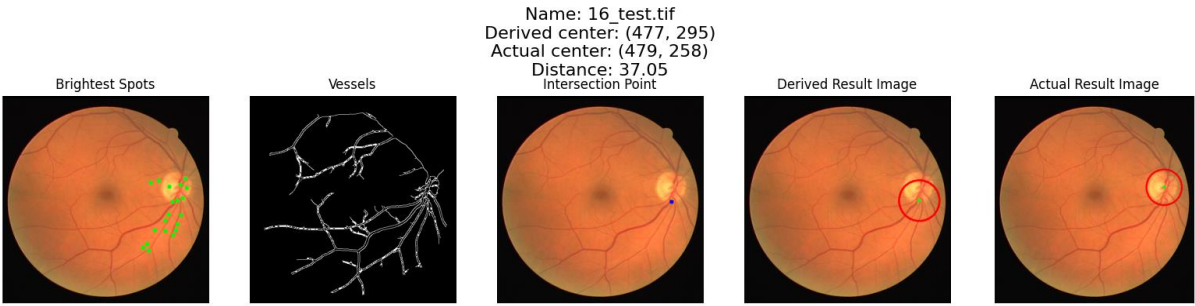
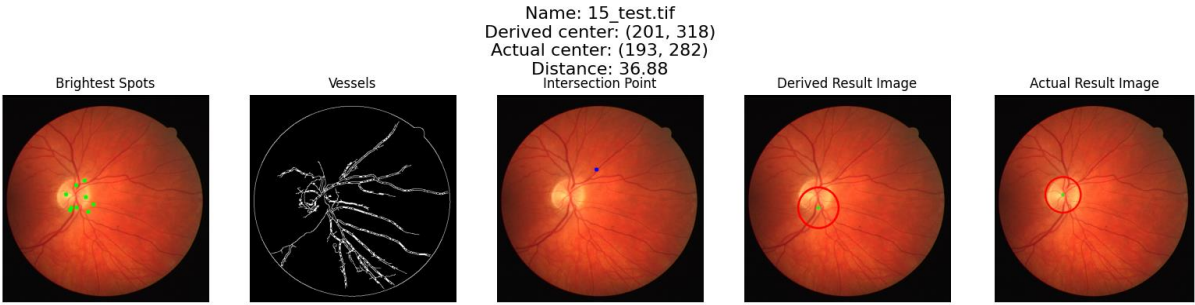
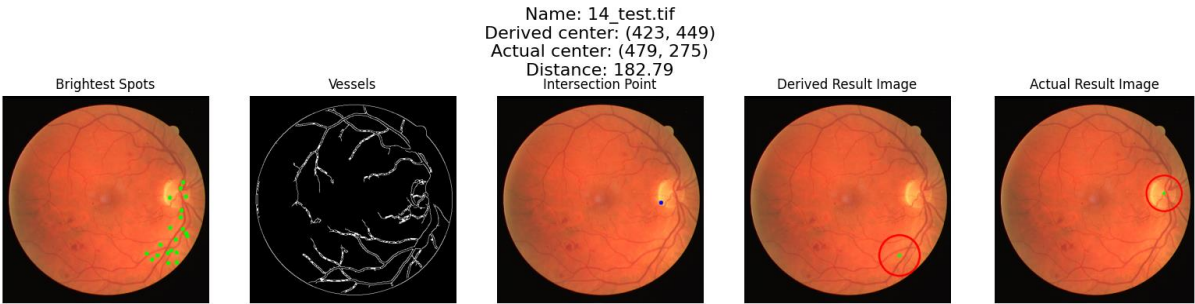


Name: 02_test.tif
Derived center: (466, 302)
Actual center: (458, 275)
Distance: 28.16
Intersection Point

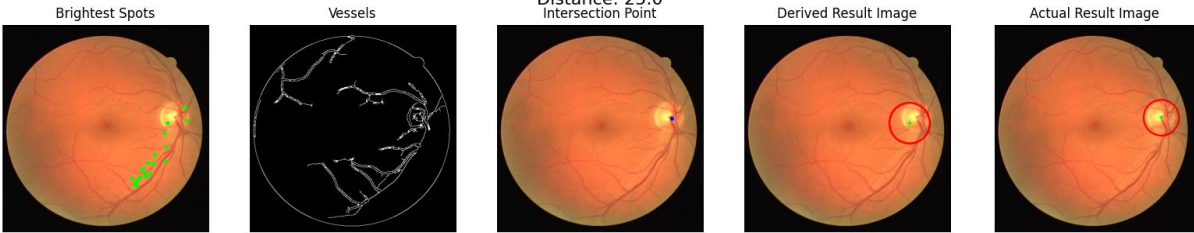




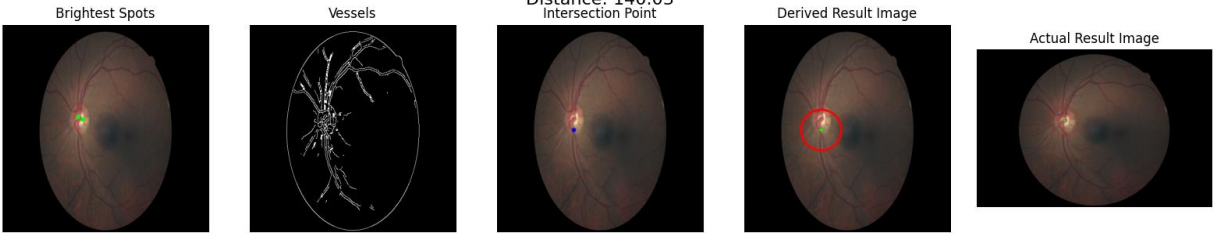




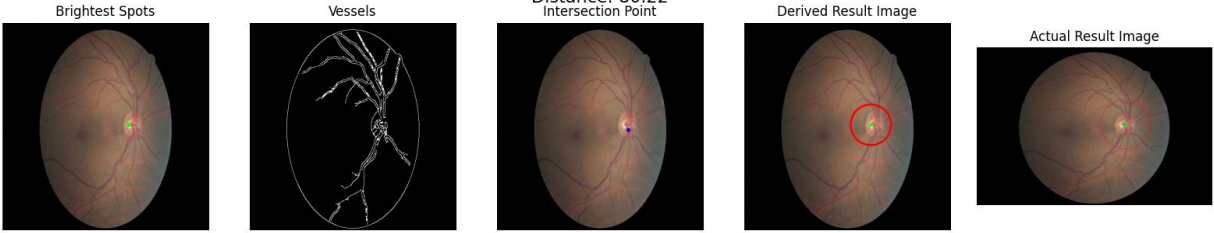
Name: 18_test.tif
Derived center: (451, 277)
Actual center: (471, 262)
Distance: 25.0
Intersection Point



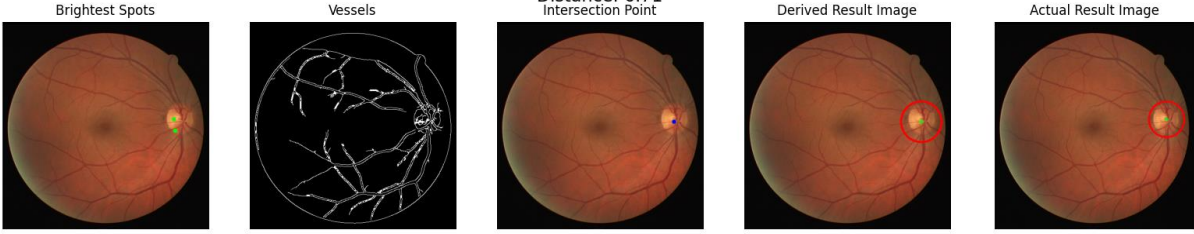
Name: 19_left.jpeg
Derived center: (1442, 1316)
Actual center: (1445, 1176)
Distance: 140.03
Intersection Point



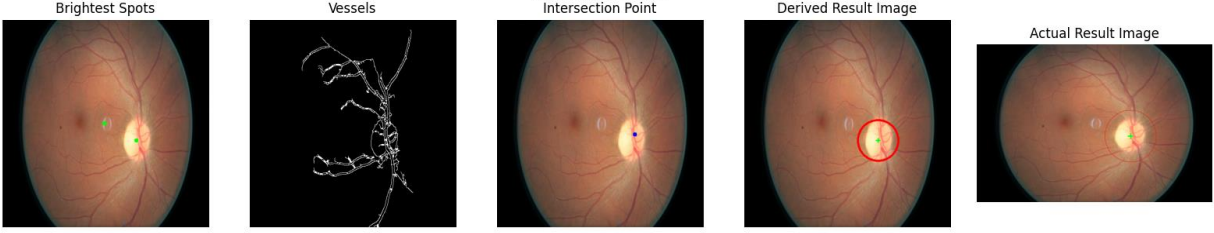
Name: 19_right.jpeg
Derived center: (2376, 1275)
Actual center: (2456, 1269)
Distance: 80.22
Intersection Point



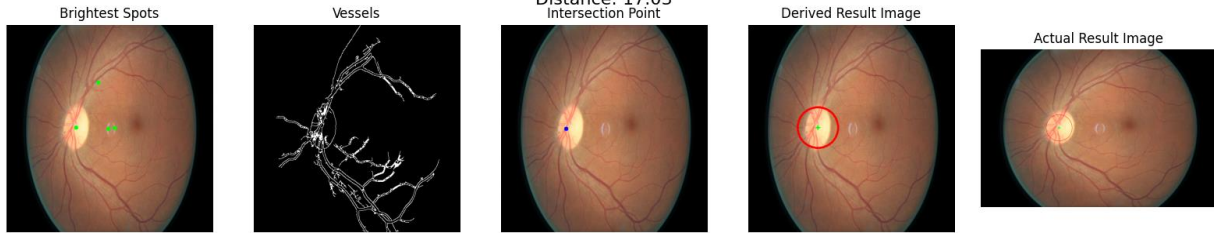
Name: 19_test.tif
Derived center: (483, 281)
Actual center: (486, 275)
Distance: 6.71
Intersection Point



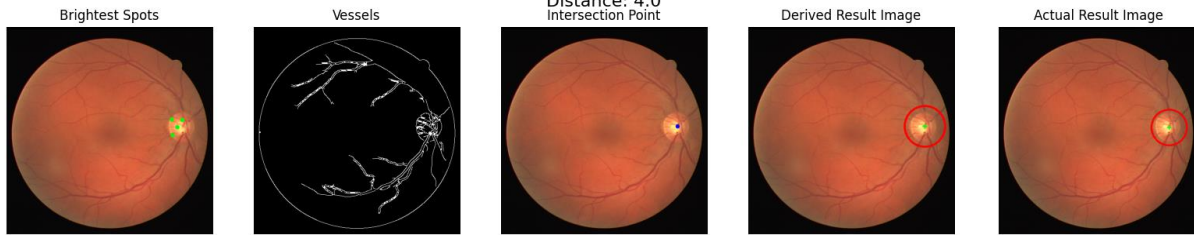
Name: 20_left.jpeg
Derived center: (2513, 1508)
Actual center: (2539, 1513)
Distance: 26.48
Intersection Point



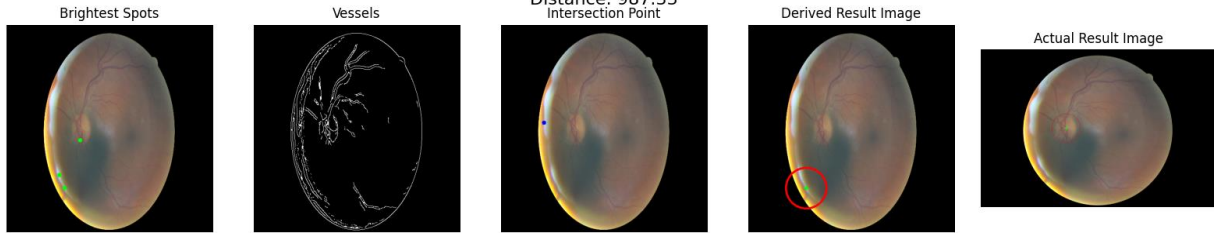
Name: 20_right.jpeg
 Derived center: (1306, 1285)
 Actual center: (1293, 1296)
 Distance: 17.03
 Intersection Point



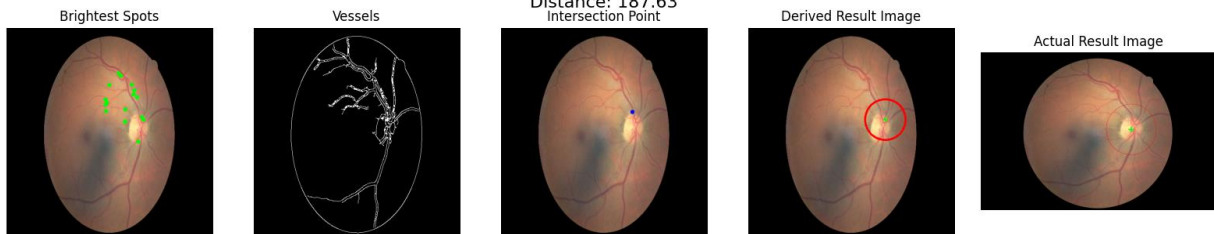
Name: 20_test.tif
 Derived center: (482, 280)
 Actual center: (482, 284)
 Distance: 4.0
 Intersection Point



Name: 21_left.jpeg
 Derived center: (1327, 2493)
 Actual center: (1724, 1589)
 Distance: 987.33
 Intersection Point



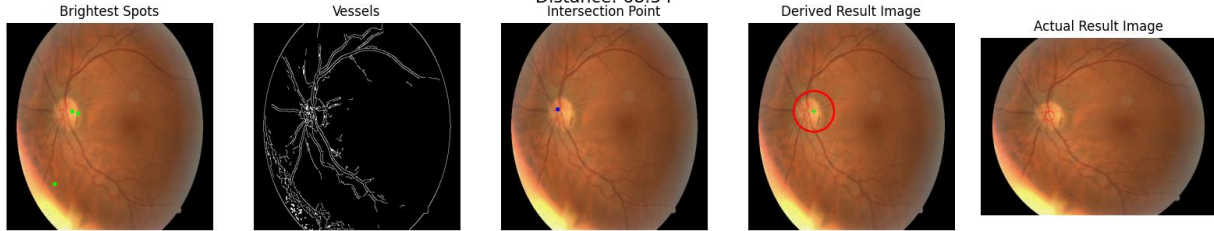
Name: 21_right.jpeg
 Derived center: (3146, 1404)
 Actual center: (3036, 1556)
 Distance: 187.63
 Intersection Point



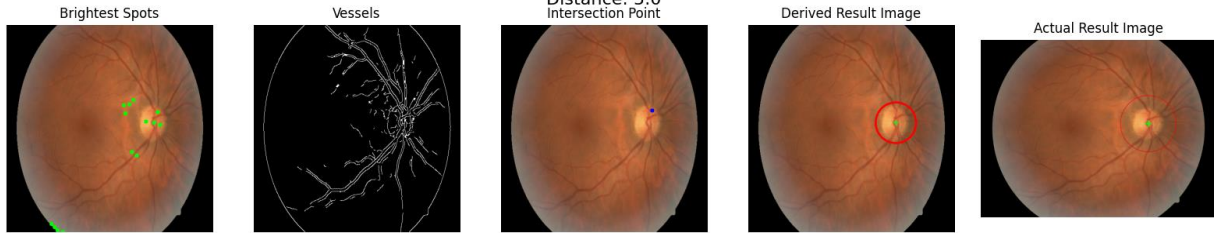
Name: 21_training.tif
 Derived center: (173, 163)
 Actual center: (77, 257)
 Distance: 134.36
 Intersection Point



Name: 22_left.jpeg
 Derived center: (810, 821)
 Actual center: (747, 848)
 Distance: 68.54
 Intersection Point



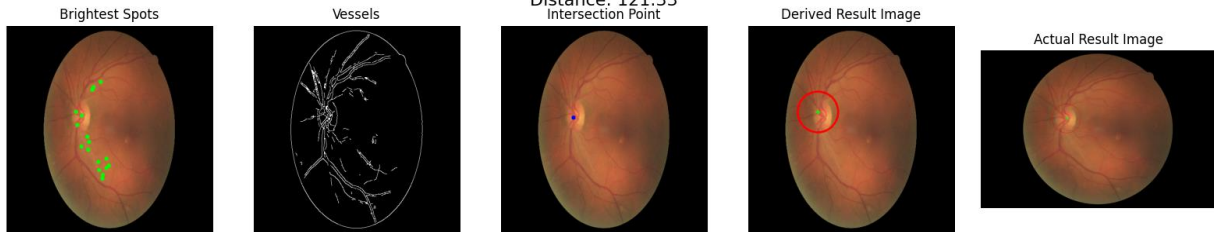
Name: 22_right.jpeg
 Derived center: (1825, 907)
 Actual center: (1821, 910)
 Distance: 5.0
 Intersection Point



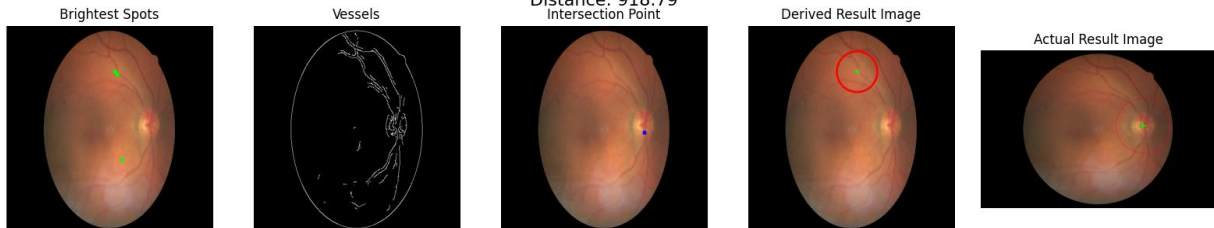
Name: 22_training.tif
 Derived center: (494, 282)
 Actual center: (471, 272)
 Distance: 25.08
 Intersection Point



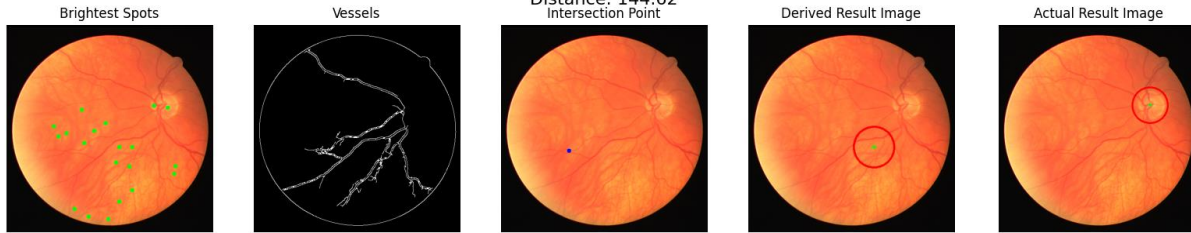
Name: 23_left.jpeg
 Derived center: (1306, 1078)
 Actual center: (1417, 1127)
 Distance: 121.33
 Intersection Point



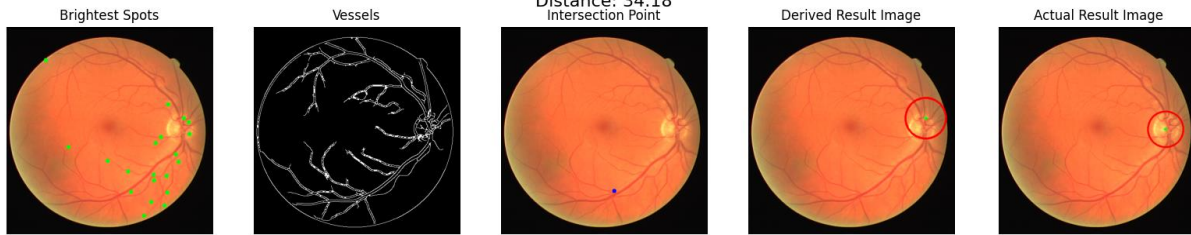
Name: 23_right.jpeg
 Derived center: (2042, 577)
 Actual center: (2676, 1242)
 Distance: 918.79
 Intersection Point



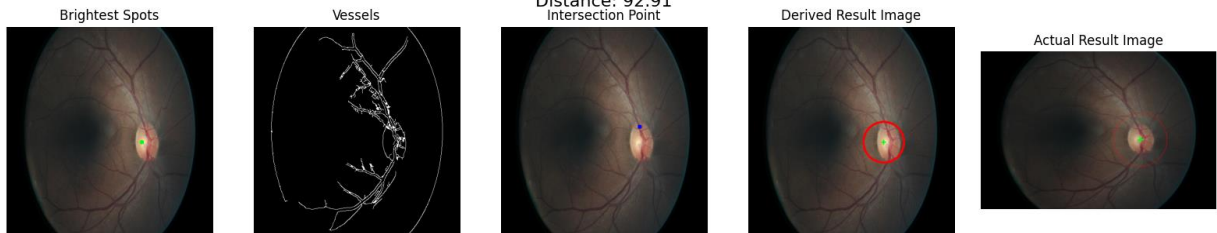
Name: 23_training.tif
 Derived center: (343, 344)
 Actual center: (428, 227)
 Distance: 144.62
 Intersection Point



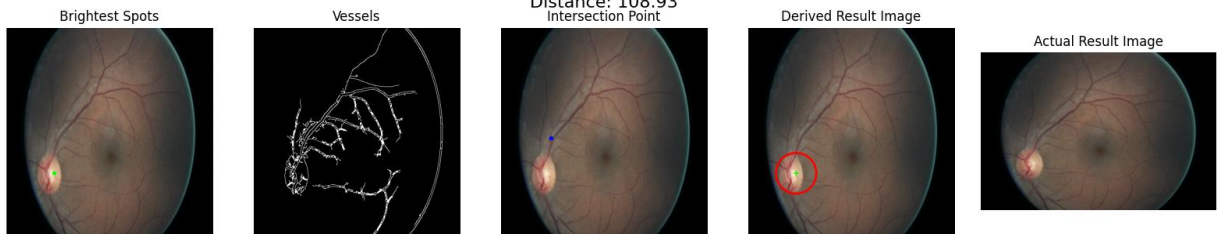
Name: 24_training.tif
 Derived center: (484, 257)
 Actual center: (472, 289)
 Distance: 34.18
 Intersection Point



Name: 25_left.jpeg
 Derived center: (2543, 1442)
 Actual center: (2635, 1455)
 Distance: 92.91
 Intersection Point

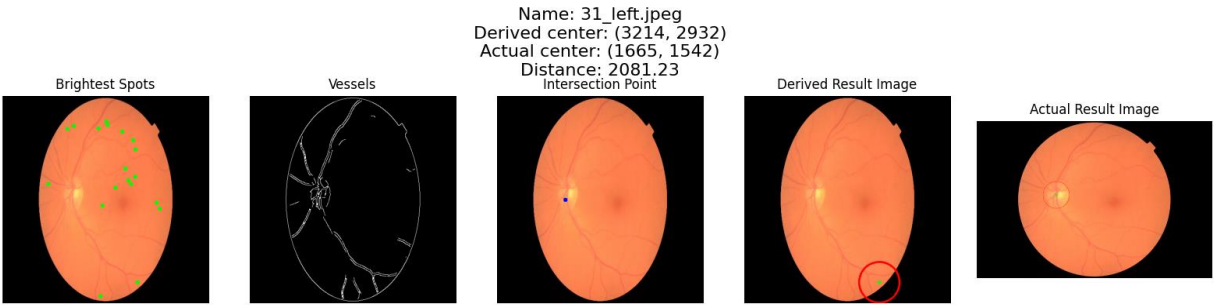
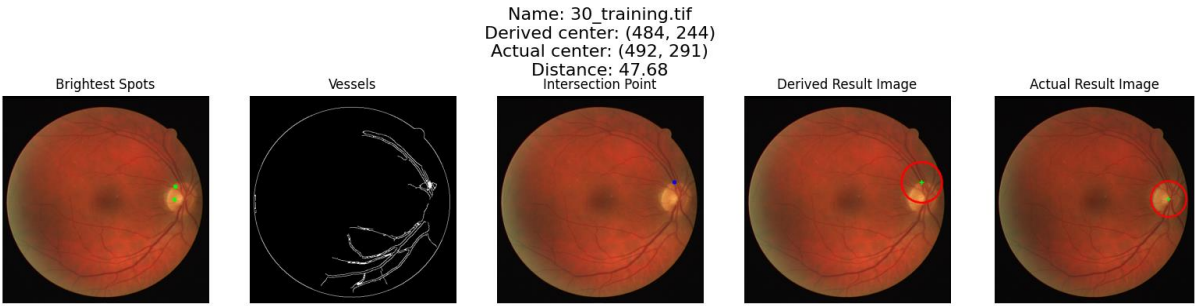
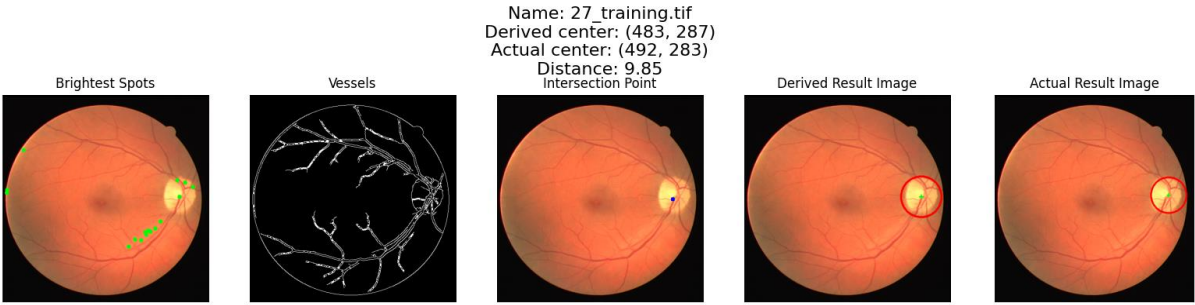
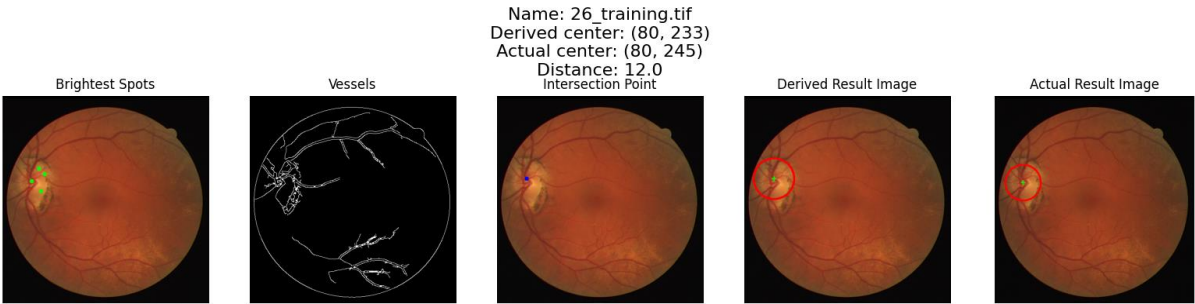


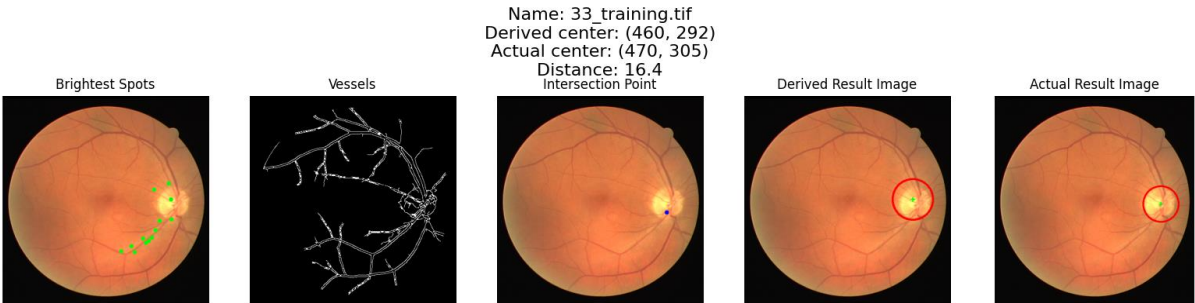
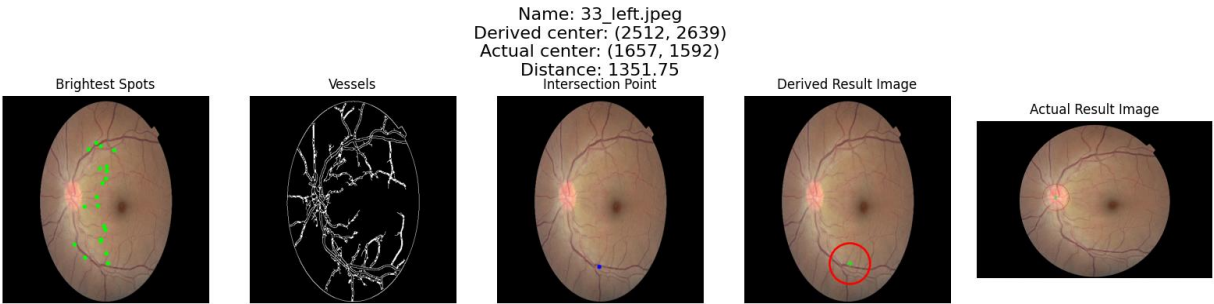
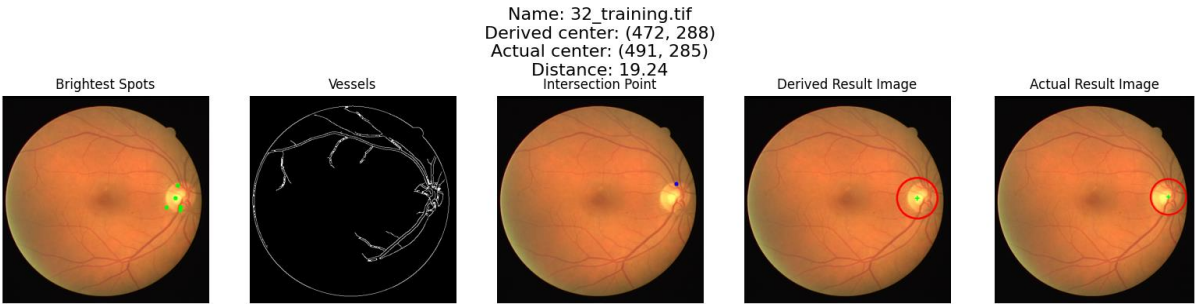
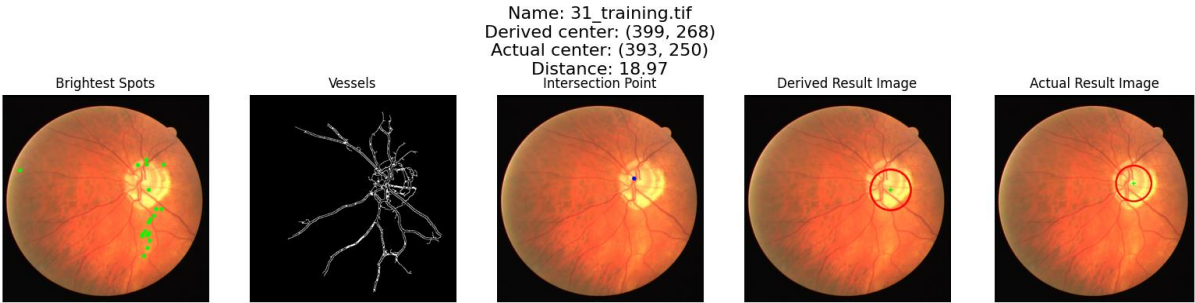
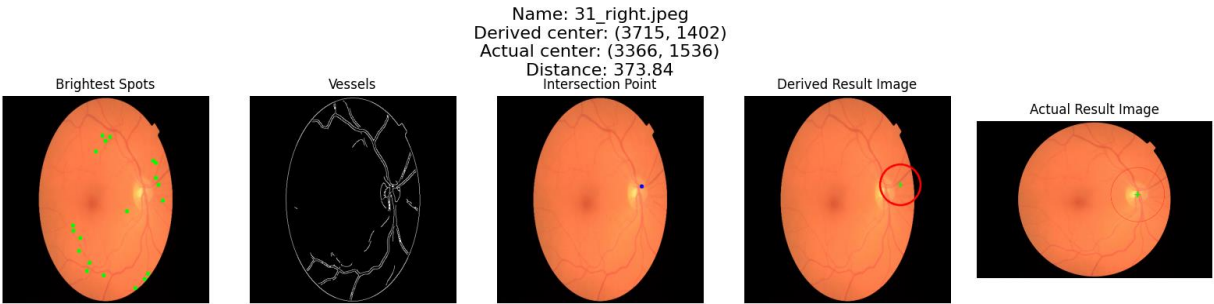
Name: 25_right.jpeg
 Derived center: (896, 1817)
 Actual center: (791, 1846)
 Distance: 108.93
 Intersection Point

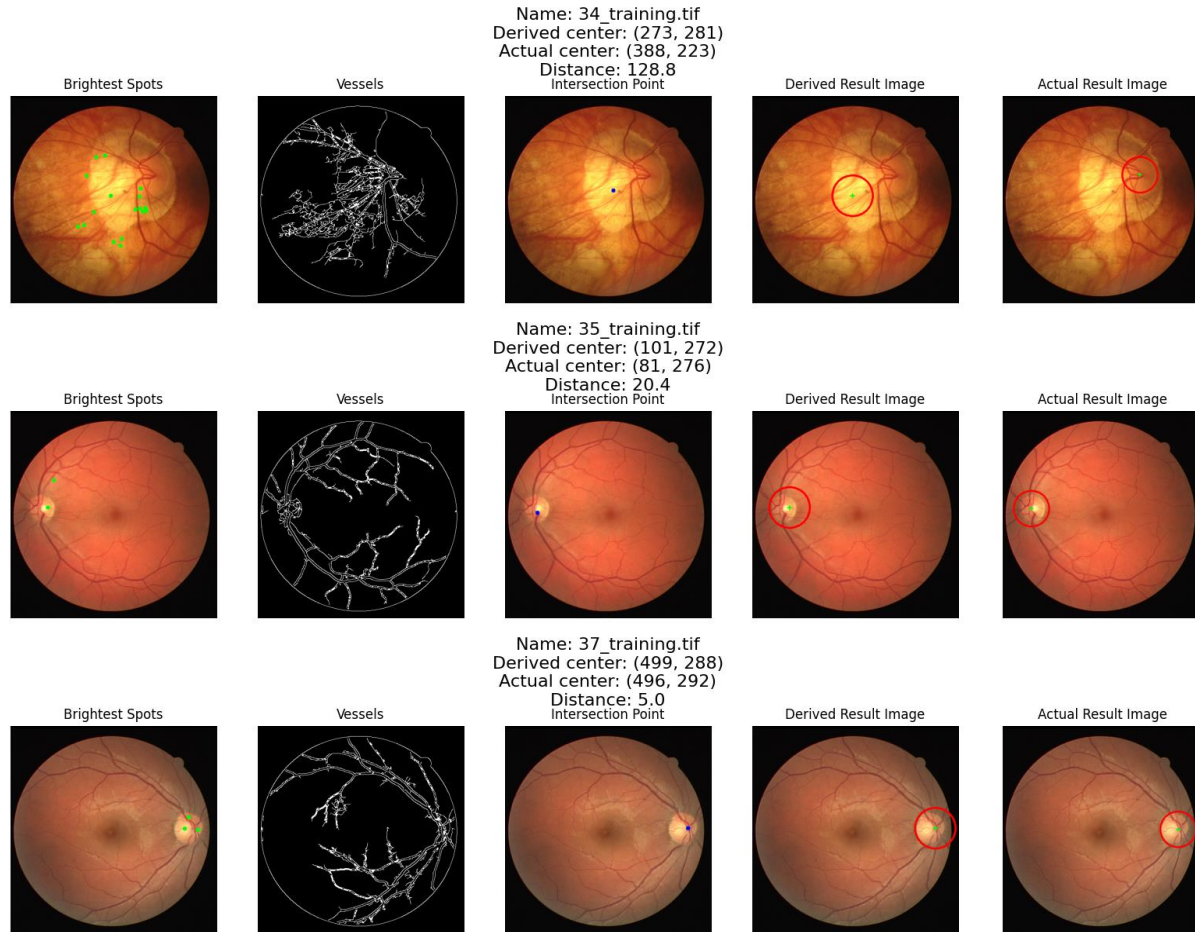


Name: 25_training.tif
 Derived center: (466, 278)
 Actual center: (464, 270)
 Distance: 8.25
 Intersection Point







**Code:**

```
import os
import cv2
import csv
import numpy as np
from matplotlib.image import imread
import matplotlib.pyplot as plt

def read_images_from_folders(folder_path):
    images = []
    names = []
    files = os.listdir(folder_path)
    files.sort()
    for file in files:
        path = os.path.join(folder_path, file)
        names.append(file)
        path = path.replace("\\", "/")
        images.append(path)
```

```
    return images,names

def read_image_centers(file_path):
    centers = []
    with open(file_path, 'r') as file:
        for line in file:
            line = line.strip()
            if line:
                parts = line.split(',')
                if len(parts) == 3:
                    x = int(parts[1].strip())
                    y = int(parts[2].strip())
                    centers.append((x, y))
    return centers

def pre_process_image(image, new_size=(512, 512)):
    original_size = image.shape[:2]
    target_size = new_size
    scaling_factor = (target_size[1] / original_size[1], target_size[0] / original_size[0])
    resized_image = cv2.resize(image, new_size)
    return resized_image, scaling_factor

def extract_vessels(image, min_component_area=2500):
    structure_element = cv2.getStructuringElement(cv2.MORPH_ELLIPSE, (3, 3))
    grayscale_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
    blur_image = cv2.GaussianBlur(grayscale_image, (5, 5), 0)
    edges = cv2.Canny(blur_image, 30, 20)
    connected_edges = cv2.morphologyEx(edges, cv2.MORPH_CLOSE, structure_element)
    num_labels, labels, stats, centroids = cv2.connectedComponentsWithStats(connected_edges, connectivity=8,
ltype=cv2.CV_32S)
    for label in range(1, num_labels):
        if stats[label, cv2.CC_STAT_AREA] < min_component_area:
            connected_edges[labels == label] = 0
    output = connected_edges
    num_vessels = cv2.countNonZero(connected_edges)
    # print('number of vessels found: ', num_vessels)
    if num_vessels < 6000:
        if min_component_area < 500:
            # print('less vessels found, s < 500 ')
            return output,num_vessels
        elif min_component_area < 1100:
            # print('less vessels found, s < 1100')
            output,num_vessels = extract_vessels(image, min_component_area-500)
    else:
        # print('less vessels found, s = 2500')
```

```
    output,num_vessels = extract_vessels(image,min_component_area-1500)

    return output, num_vessels

def find_brightest_spots(image):
    gray_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
    blurred_image = cv2.GaussianBlur(gray_image, (5, 5), 0)
    max_intensity = np.amax(blurred_image)
    _, thresholded_image = cv2.threshold(blurred_image, max_intensity * 0.7, 255, cv2.THRESH_BINARY)
    contours, _ = cv2.findContours(thresholded_image, cv2.RETR_EXTERNAL,
cv2.CHAIN_APPROX_SIMPLE)
    contours = sorted(contours, key=cv2.contourArea, reverse=True)[:20]

    bright_spots = []
    for contour in contours:
        x, y, w, h = cv2.boundingRect(contour)
        center_x = x + w // 2
        center_y = y + h // 2
        bright_spots.append((center_x, center_y))

    return bright_spots

def find_intersection_point(image):
    structure_element = cv2.getStructuringElement(cv2.MORPH_ELLIPSE, (7, 7))
    closed_image = cv2.morphologyEx(image, cv2.MORPH_CLOSE, structure_element)
    eroded_image = cv2.erode(closed_image, structure_element)
    contours, _ = cv2.findContours(eroded_image, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)
    if contours:
        largest_contour = max(contours, key=cv2.contourArea)
        M = cv2.moments(largest_contour)
        if M["m00"] != 0:
            center_x = int(M["m10"] / M["m00"])
            center_y = int(M["m01"] / M["m00"])
            intersection_point = (center_x, center_y)
            return intersection_point
    return None

def analyze_data(image, brightest_spots, intersection_point, count, radius):
    max_vessel_count = -1
    list_of_info = []
    skip = False
    for spot in brightest_spots:
        info = {
            "center": (0, 0),
            "intensity": 0,
```

```

        "vessel_count": 0,
        "distance_from_intersection": 0,
        "neighbor_spots": 0,
    }

    masked_image = mask_circle(image, spot, radius)
    center = spot
    intensity = np.mean(masked_image)
    vessel_count = cv2.countNonZero(masked_image)
    # print("Vessel Count: ",vessel_count, "Count: ", count)
    distance_from_intersection = float('inf')
    neighbor_spots = 0;

    if intersection_point is not None:
        distance_from_intersection = np.sqrt((spot[0] - intersection_point[0])**2 + (spot[1] -
intersection_point[1])**2)
        if distance_from_intersection < radius:

            for bright_spot in brightest_spots:
                if bright_spot != spot:
                    distance = float('inf')
                    if intersection_point is not None:
                        distance = np.sqrt((bright_spot[0] - intersection_point[0])**2 + (bright_spot[1] -
intersection_point[1])**2)
                    if distance < radius:
                        neighbor_spots += 1

            if neighbor_spots > len(brightest_spots)/2.5:
                center = intersection_point
                skip = True

    if skip is not True:
        if vessel_count > max_vessel_count:
            max_vessel_count = vessel_count

    info["center"] = center
    info["intensity"] = intensity
    info["vessel_count"] = vessel_count
    info["distance_from_intersection"] = distance_from_intersection
    info["neighbor_spots"] = neighbor_spots
    list_of_info.append(info)
    return list_of_info

def find_best_spot(info):

```

```
info = sorted(info, key=lambda x: (x["vessel_count"], x["intensity"], x["distance_from_intersection"],
x["neighbor_spots"]), reverse=True)
return info[0]["center"], info

def circle_brightest_spot(image, brightest_spot, radius):
    image = image.copy()
    cv2.circle(image, brightest_spot, radius, (0, 0, 255), 4)
    cross_size = int(radius/10)
    cross_thickness = int(radius/25)
    cross_color = (0, 255, 0)
    center_x, center_y = brightest_spot
    cv2.line(image, (center_x - cross_size, center_y), (center_x + cross_size, center_y), cross_color,
cross_thickness)
    cv2.line(image, (center_x, center_y - cross_size), (center_x, center_y + cross_size), cross_color,
cross_thickness)

    return image

def mask_circle(image, brightest_spot, radius):
    mask = np.zeros_like(image)
    cv2.circle(mask, brightest_spot, radius, (255, 255, 255), -1)
    masked_image = cv2.bitwise_and(image, mask)
    return masked_image

def draw_brightest_spots(image, brightest_spots):
    for spot in brightest_spots:
        cv2.circle(image, spot, 5, (0, 255, 0), -1)

def display(images, title, name, save_path):
    plt.figure(figsize=(16, 4))
    for i in range(len(images)):
        plt.subplot(1, len(images), i+1)
        plt.imshow(cv2.cvtColor(images[i], cv2.COLOR_BGR2RGB), aspect='equal')
        if i == 0:
            plt.title('Brightest Spots')
        elif i == 1:
            plt.title('Vessels')
        elif i == 2:
            plt.title('Intersection Point')
        elif i == 3:
            plt.title('Derived Result Image')
        else:
            plt.title('Actual Result Image')
    plt.suptitle(title, fontsize=16)
```



```

    plt.axis('off')
plt.tight_layout()
plt.savefig(save_path + "/" + name + ".png" )
plt.show()

def print_info_table(list_of_info):
    print("Optic Disk Information:")
    print("{:<15} {:<15} {:<15} {:<15} {:<15} ".format("Center", "Intensity", "Vessel Count", "Dst from IP",
"Nbr Spots"))
    for info in list_of_info:
        center = info["center"]
        intensity = round(info["intensity"], 2)
        vessel_count = info["vessel_count"]
        distance_from_intersection = round(info["distance_from_intersection"])
        neighbor_spots = info["neighbor_spots"]

        center_str = f"({center[0]}, {center[1]})"
        print("{:<15} {:<15} {:<15} {:<15} {:<15} ".format(center_str,intensity, vessel_count,
distance_from_intersection, neighbor_spots,))
        print('-----')

images,names = read_images_from_folders("Assignment-2/Fundus-image")
actual_centers = read_image_centers("Assignment-2/optic_disc_centres.csv")
derived_centers = []
distances = []
radius = 50
# images = [image for image,name in zip(images,names) if "test" in name]
# names = [name for name in names if "test" in name]

# images = [image for image,name in zip(images,names) if "1ffa" in name]
# names = [name for name in names if "1ffa" in name]

# images = images[:1]
# names = names[:1]

for path,name,center in zip(images,names,actual_centers):
    image = cv2.imread(path)
    preprocessed_image,scaling_factor = pre_process_image(image)
    intersection_point_image = preprocessed_image.copy()
    image_with_spots = preprocessed_image.copy()
    vessels,num_vessels = extract_vessels(preprocessed_image)
    brightest_spots = find_brightest_spots(preprocessed_image)
    intersection_point = find_intersection_point(vessels)
    if intersection_point:

```

```

    cv2.circle(intersection_point_image, intersection_point, 5, (255, 0, 0), -1)
info = analyze_data(vessels, brightest_spots, intersection_point, num_vessels, radius)
best_spot, info = find_best_spot(info)
derived_result_image = circle_brightest_spot(preprocessed_image, best_spot, radius)
draw_brightest_spots(image_with_spots, brightest_spots)
best_spot_scaled = (int( best_spot[0]/scaling_factor[0] ), int( best_spot[1]/scaling_factor[1] ))
actual_radius = radius
if center[0] > 1000:
    actual_radius = int(radius * (center[0]/300))
actual_result_image = circle_brightest_spot(image, center, actual_radius)
distance = round(np.sqrt((best_spot_scaled[0] - center[0])**2 + (best_spot_scaled[1] - center[1])**2), 2)
distances.append(distance)
derived_centers.append(best_spot_scaled)
display([image_with_spots, vessels, intersection_point_image,
derived_result_image, actual_result_image], 'Name: ' + name + '\nDerived center: ' + str(best_spot_scaled) +
'\nActual center: ' + str(center) + '\nDistance: ' + str(distance), name, "Assignment-2/Result" )
    print_info_table(info)

print("Distances:")
print("{:<20} {:<20} {:<20} {:<20}".format("Image", "Derived OC", "Actual OC", "Distance"))
for (name, derived_center, actual_center, distance) in zip(names, derived_centers, actual_centers, distances):
    print("{:<20} {:<20} {:<20} {:<20}".format(name, str(derived_center), str(actual_center), str(distance)))
with open("Assignment-2/resultant_optic_disc_centres.csv", mode='w', newline='') as file:
    writer = csv.writer(file)
    writer.writerow(["Image", "Derived OC", "Actual OC", "Distance"])
    for name, derived_center, actual_center, distance in zip(names, derived_centers, actual_centers, distances):
        writer.writerow([name, str(derived_center), str(actual_center), str(distance)])
print("Results have been written to", "Assignment-2/resultant_optic_disc_centres.csv")

```