



湖南大學  
HUNAN UNIVERSITY

# 研究生期末大作业

课程名称： 有限元方法及应用

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# 悬臂梁 abaqus 有限元建模方法分析

陈桓隆

## 一. 问题重述

### 1.1 问题描述

如图 1 所示的悬臂梁尺寸为 $10 \times 10 \times 100$ ，单位为 mm。杨氏模量  $E=2.1 \times 10^5 \text{Mpa}$ ，泊松比  $\sigma=0.3$ 。左端完全固定，右端施加于 y 方向大小为 $-100\text{N}$ 的集中荷载，分析悬臂梁自由端的变形。

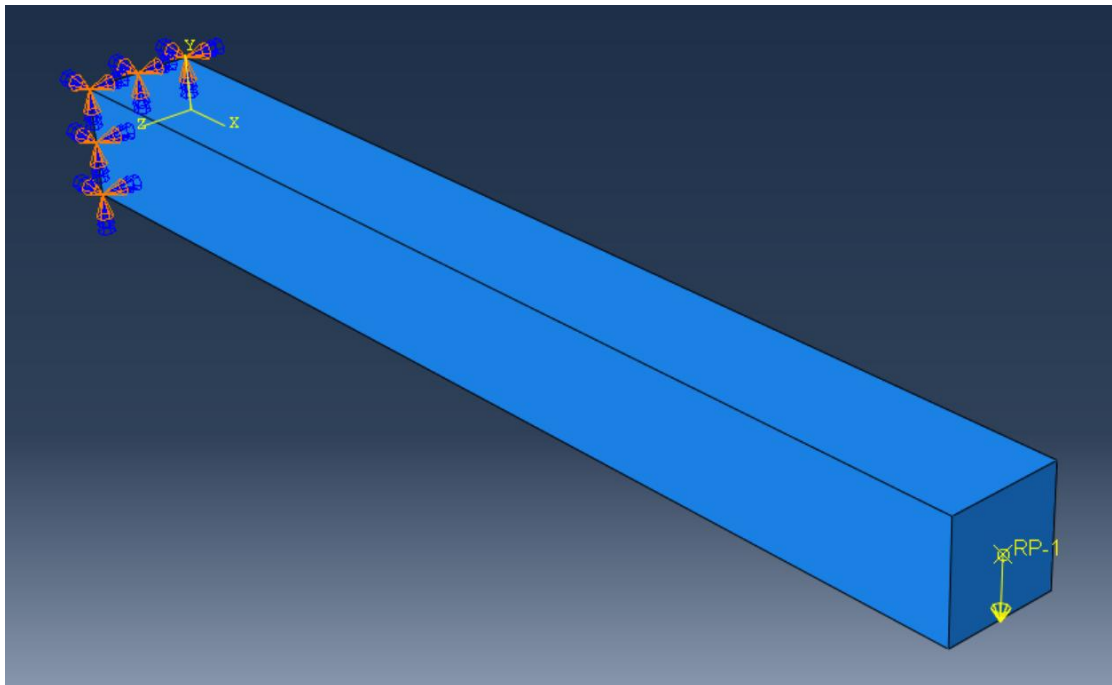


图 1. 悬臂梁的结构模型

### 1.2 理论分析

于 abaqus 中建立悬臂梁模型，建立采取模型空间为三维，类型为可变形但形状分别采用实体以及线两种不同类型的模型，计算各自最终结果与手算结果进行误差分析，确定两种不同建模方式的可行性。

## 二. 悬臂梁有限元分析的过程

### 2.1 线类型模型分析

#### 2.1.1 前处理

几何模型的构建：采用模型空间为三维，类型为可变性，形状为线的部件类型，得到一根长度为100mm的线。然后创建一个边长为10mm×10mm的矩形剖面，以该剖面为截面类型，指派该截面为线的截面。

材料参数的定义：杨氏模量为 2.1e5Mpa，泊松比为 0.3。

网络系统的构建：采用 B31 梁单元类型。

#### 2.1.2 求解

求解器的设定：设置一个静力学通用的分析步，设置保持默认。

边界条件的设定：模型左端点设置为完全固定，右端点施加一个延 y 方向负方向大小为 100N 的集中荷载，如图 2 所示。

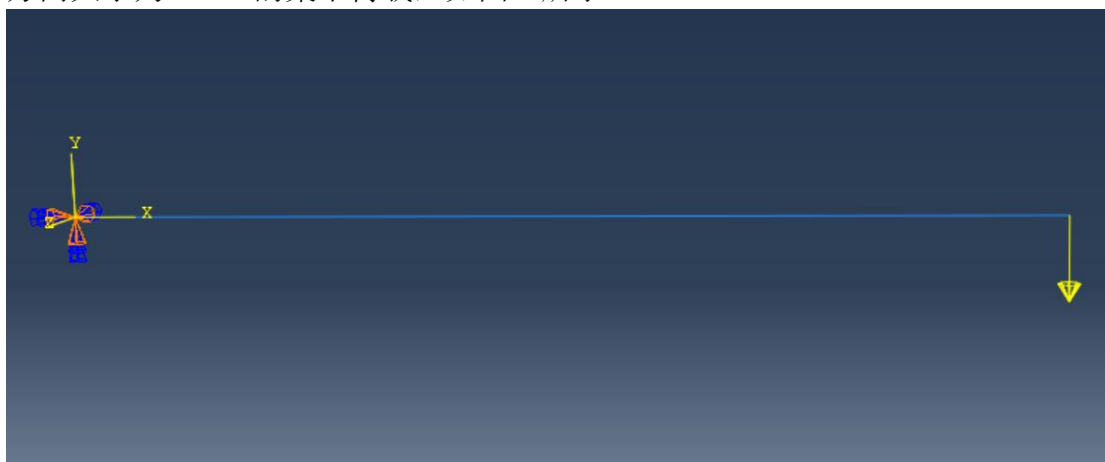


图 2.线模型构建

#### 2.1.3 后处理

创建作业文件 xian，提交计算。

打开视图 ODB 渲染选项，得到图 3。

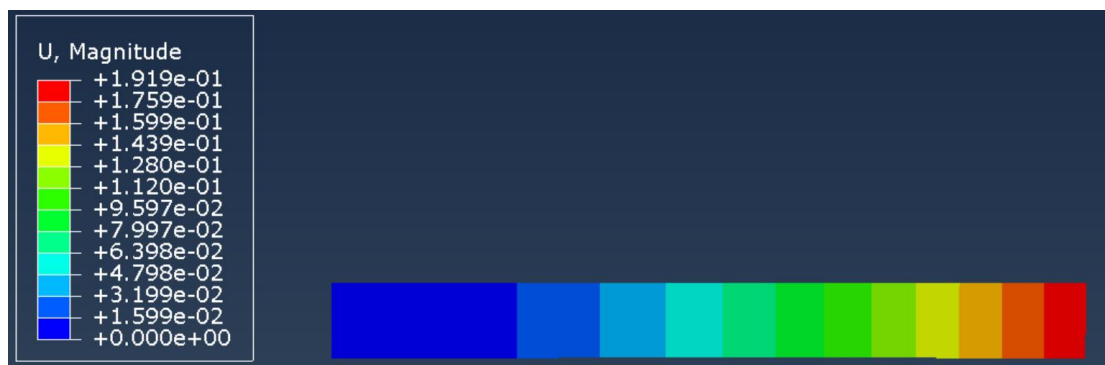


图 3.线模型后处理图像

## 2.2 实体类型模型分析

### 2.2.1 前处理

几何模型的构建：采用模型空间为三维，类型为可变性，形状为实体的部件类型，得到一根长度为100mm，边长为10mm×10mm的梁。

材料参数的定义：杨氏模量为 2.1e5Mpa，泊松比为 0.3。

网络系统的构建：采用 C3D8R 八结点线性六面体单元，10000 个单元节点。

### 2.2.2 求解

求解器的设定：设置一个静力学通用的分析步，设置保持默认。

边界条件的设定：模型左端设置为完全固定，右端首先在面中心设置一个参考点，然后将整个面耦合到参考点，最后再参考点施加一个延 y 方向负方向大小为 100N 的集中荷载，如图 4 所示。

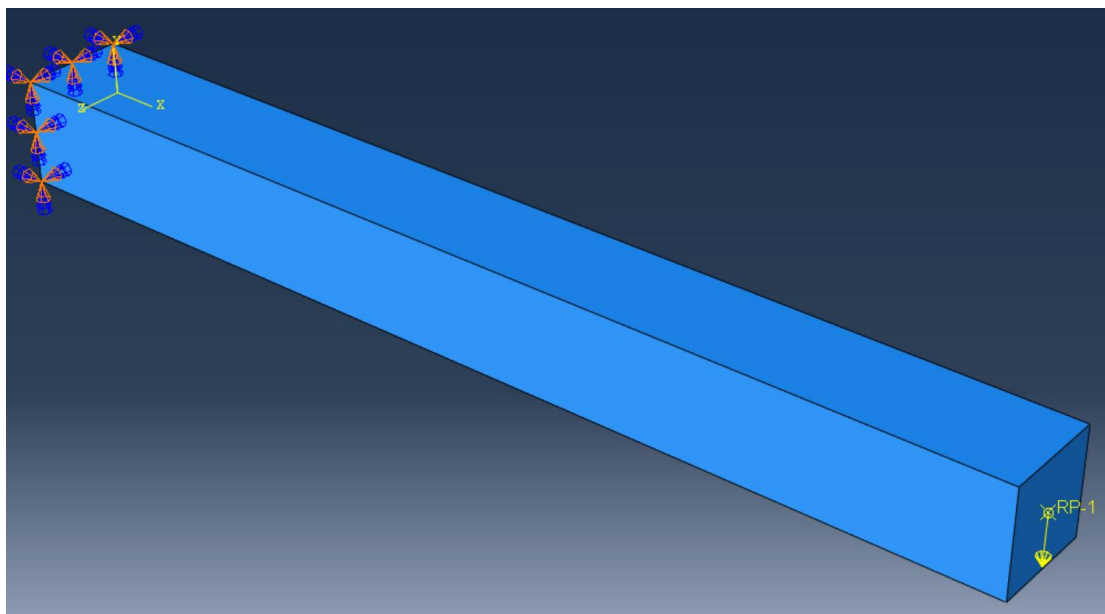


图 4.实体模型构建

### 2.2.3 后处理

创建作业文件 shiti, 提交计算, 得到图 5。

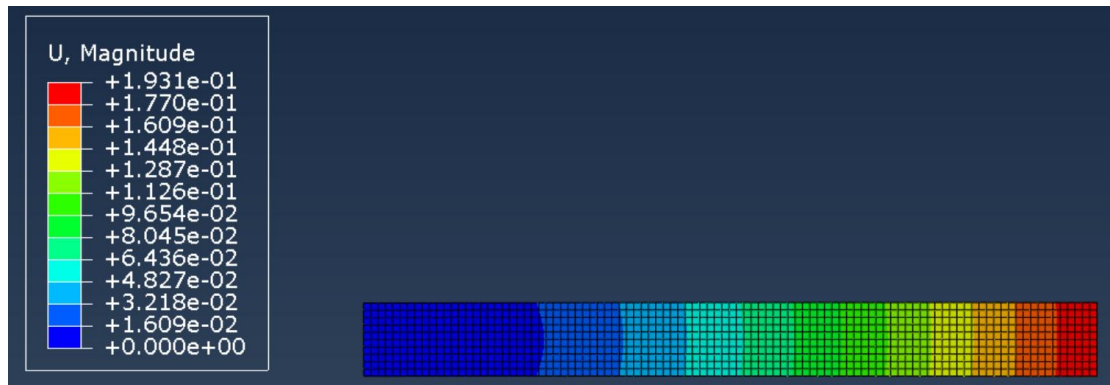


图 5.实体模型后处理图像

### 三. 误差分析

#### 3.1 材料力学手算

将问题简化为如图 6 所示的悬臂梁问题。



图 6.模型简化

由题可知弹性模量  $E = 2.1 \times 10^5 \text{ Mpa}$ ，泊松比  $\sigma = 0.3$ ，根据材料力学计算悬臂梁由集中力计算位移公式：

$$y = \frac{FL^3}{3EI}$$

可得位移  $y = 0.190476\text{mm}$

#### 3.2 误差分析

根据前面几种不同的方式得到的有关最大位移的数据，汇总可得表 1。

表 1：各种方式误差表（与手算相比）

计算方式	材料力学手算	Abaqus 线模型	Abaqus 实体模型
最大位移（mm）	0.1905	0.1919	0.1931
误差	0	0.735%	1.365%

据表 1 可知，两种不同的 Abaqus 建模方式与手算所得结果误差均很小，故两种建模方式均合理。

## 四. 附录代码

### 4.1 代码解释

代码是由 abaqus 软件附带的宏录制功能自动生成的 abaqusMacros.py 文件稍加更改后所得，将代码写入 py 文件后于 abaqus 中运行即可。

### 4.2 代码

#### 4.2.1 线模型代码

```
# -*- coding: mbcs -*-
# Do not delete the following import lines
from abaqus import *
from abaqusConstants import *
import __main__

import section
import regionToolset
import displayGroupMdbToolset as dgm
import part
import material
import assembly
import step
import interaction
import load
import mesh
import optimization
import job
import sketch
import visualization
import xyPlot
import displayGroupOdbToolset as dgo
import connectorBehavior
s = mdb.models['Model-1'].ConstrainedSketch(name='__profile__',
      sheetSize=200.0)
g, v, d, c = s.geometry, s.vertices, s.dimensions, s.constraints
s.setPrimaryObject(option=STANDALONE)
s.Line(point1=(0.0, 0.0), point2=(100.0, 0.0))
s.HorizontalConstraint(entity=g[2], addUndoState=False)
```



```

p = mdb.models['Model-1'].Part(name='Part-1', dimensionality=THREE_D,
    type=DEFORMABLE_BODY)
p = mdb.models['Model-1'].parts['Part-1']
p.BaseWire(sketch=s)
s.unsetPrimaryObject()
p = mdb.models['Model-1'].parts['Part-1']
session.viewports['Viewport: 1'].setValues(displayedObject=p)
del mdb.models['Model-1'].sketches['__profile__']
session.viewports['Viewport: 1'].partDisplay.setValues(sectionAssignments=ON,
    engineeringFeatures=ON)
session.viewports['Viewport: 1'].partDisplay.geometryOptions.setValues(
    referenceRepresentation=OFF)
mdb.models['Model-1'].Material(name='Material-1')
mdb.models['Model-1'].materials['Material-1'].Elastic(table=((210000.0, 0.3),
    ))
mdb.models['Model-1'].RectangularProfile(name='Profile-1', a=10.0, b=10.0)
mdb.models['Model-1'].BeamSection(name='Section-1',
    integration=DURING_ANALYSIS, poissonRatio=0.0, profile='Profile-1',
    material='Material-1', temperatureVar=LINEAR,
    consistentMassMatrix=False)
p = mdb.models['Model-1'].parts['Part-1']
e = p.edges
edges = e.getSequenceFromMask(mask=('#1 ', ), )
region = regionToolset.Region(edges=edges)
p = mdb.models['Model-1'].parts['Part-1']
p.SectionAssignment(region=region, sectionName='Section-1', offset=0.0,
    offsetType=MIDDLE_SURFACE, offsetField="",
    thicknessAssignment=FROM_SECTION)
p = mdb.models['Model-1'].parts['Part-1']
e = p.edges
edges = e.getSequenceFromMask(mask=('#1 ', ), )
region=regionToolset.Region(edges=edges)
p = mdb.models['Model-1'].parts['Part-1']
p.assignBeamSectionOrientation(region=region, method=N1_COSINES, n1=(0.0, 0.0,
    -1.0))
session.viewports['Viewport: 1'].partDisplay.setValues(sectionAssignments=OFF,
    engineeringFeatures=OFF, mesh=ON)
session.viewports['Viewport: 1'].partDisplay.meshOptions.setValues(
    meshTechnique=ON)
p = mdb.models['Model-1'].parts['Part-1']
p.seedPart(size=1.0, deviationFactor=0.1, minSizeFactor=0.1)
p = mdb.models['Model-1'].parts['Part-1']
p.generateMesh()
a = mdb.models['Model-1'].rootAssembly

```

```

session.viewports['Viewport: 1'].setValues(displayedObject=a)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(
    optimizationTasks=OFF, geometricRestrictions=OFF, stopConditions=OFF)
a = mdb.models['Model-1'].rootAssembly
a.DatumCsysByDefault(CARTESIAN)
p = mdb.models['Model-1'].parts['Part-1']
a.Instance(name='Part-1-1', part=p, dependent=ON)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(
    adaptiveMeshConstraints=ON)
mdb.models['Model-1'].StaticStep(name='Step-1', previous='Initial')
session.viewports['Viewport: 1'].assemblyDisplay.setValues(step='Step-1')
session.viewports['Viewport: 1'].assemblyDisplay.setValues(interactions=ON,
    constraints=ON, connectors=ON, engineeringFeatures=ON,
    adaptiveMeshConstraints=OFF)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(loads=ON, bcs=ON,
    predefinedFields=ON, interactions=OFF, constraints=OFF,
    engineeringFeatures=OFF)
a = mdb.models['Model-1'].rootAssembly
v1 = a.instances['Part-1-1'].vertices
verts1 = v1.getSequenceFromMask(mask=('#1 '], ), )
region = regionToolset.Region(vertices=verts1)
mdb.models['Model-1'].EncastreBC(name='BC-1', createStepName='Step-1',
    region=region, localCsys=None)
a = mdb.models['Model-1'].rootAssembly
v1 = a.instances['Part-1-1'].vertices
verts1 = v1.getSequenceFromMask(mask=('#2 '], ), )
region = regionToolset.Region(vertices=verts1)
mdb.models['Model-1'].ConcentratedForce(name='Load-1', createStepName='Step-1',
    region=region, cf2=-100.0, distributionType=UNIFORM, field="",
    localCsys=None)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(loads=OFF, bcs=OFF,
    predefinedFields=OFF, connectors=OFF)
mdb.Job(name='xian', model='Model-1', description="", type=ANALYSIS,
    atTime=None, waitMinutes=0, waitHours=0, queue=None, memory=90,
    memoryUnits=PERCENTAGE, getMemoryFromAnalysis=True,
    explicitPrecision=SINGLE, nodalOutputPrecision=SINGLE, echoPrint=OFF,
    modelPrint=OFF, contactPrint=OFF, historyPrint=OFF, userSubroutine="",
    scratch="", resultsFormat=ODB, multiprocessingMode=DEFAULT, numCpus=1,
    numGPUs=0)
mdb.jobs['xian'].submit(consistencyChecking=OFF)
session.mdbData.summary()
o3 = session.openOdb(name='D:/abaqus/exerciese/fem_final_work/chen/xian.odb')
session.viewports['Viewport: 1'].setValues(displayedObject=o3)
session.viewports['Viewport: 1'].makeCurrent()

```

```

session.viewports['Viewport: 1'].odbDisplay.display.setValues(plotState=(
    CONTOURS_ON_DEF, ))
session.viewports['Viewport: 1'].odbDisplay.basicOptions.setValues(
    renderBeamProfiles=ON)
session.viewports['Viewport: 1'].view.setValues(nearPlane=313.937,
    farPlane=423.522, width=329.056, height=147.319, cameraPosition=(
65.8325, 143.155, 337.314), cameraUpVector=(-0.0254501, 0.727746,
-0.685374), cameraTarget=(50.6721, -4.65693, 2.99307))
session.viewports['Viewport: 1'].odbDisplay.setPrimaryVariable(
    variableLabel='U', outputPosition=NODAL, refinement=(INVARIANT,
    'Magnitude'), )

```

#### 4.2.2 实体模型代码

```

# -*- coding: mbcs -*-
# Do not delete the following import lines
from abaqus import *
from abaqusConstants import *
import __main__

import section
import regionToolset
import displayGroupMdbToolset as dgm
import part
import material
import assembly
import step
import interaction
import load
import mesh
import optimization
import job
import sketch
import visualization
import xyPlot
import displayGroupOdbToolset as dgo
import connectorBehavior
s = mdb.models['Model-1'].ConstrainedSketch(name='__profile__',
    sheetSize=200.0)
g, v, d, c = s.geometry, s.vertices, s.dimensions, s.constraints
s.setPrimaryObject(option=STANDALONE)
s.Line(point1=(0.0, 5.0), point2=(0.0, -5.0))
s.VerticalConstraint(entity=g[2], addUndoState=False)

```

```

session.viewports['Viewport: 1'].view.setValues(nearPlane=156.875,
    farPlane=220.249, width=256.499, height=114.835, cameraPosition=(
    24.2102, 5.36152, 188.562), cameraTarget=(24.2102, 5.36152, 0))
s.Line(point1=(0.0, -5.0), point2=(100.0, -5.0))
s.HorizontalConstraint(entity=g[3], addUndoState=False)
s.PerpendicularConstraint(entity1=g[2], entity2=g[3], addUndoState=False)
s.Line(point1=(100.0, -5.0), point2=(100.0, 5.0))
s.VerticalConstraint(entity=g[4], addUndoState=False)
s.PerpendicularConstraint(entity1=g[3], entity2=g[4], addUndoState=False)
s.Line(point1=(100.0, 5.0), point2=(0.0, 5.0))
s.HorizontalConstraint(entity=g[5], addUndoState=False)
s.PerpendicularConstraint(entity1=g[4], entity2=g[5], addUndoState=False)
p = mdb.models['Model-1'].Part(name='Part-1', dimensionality=THREE_D,
    type=DEFORMABLE_BODY)
p = mdb.models['Model-1'].parts['Part-1']
p.BaseSolidExtrude(sketch=s, depth=10.0)
s.unsetPrimaryObject()
p = mdb.models['Model-1'].parts['Part-1']
session.viewports['Viewport: 1'].setValues(displayedObject=p)
del mdb.models['Model-1'].sketches['__profile__']
session.viewports['Viewport: 1'].partDisplay.setValues(sectionAssignments=ON,
    engineeringFeatures=ON)
session.viewports['Viewport: 1'].partDisplay.geometryOptions.setValues(
    referenceRepresentation=OFF)
mdb.models['Model-1'].Material(name='Material-1')
mdb.models['Model-1'].materials['Material-1'].Elastic(table=((210000.0, 0.3),
    ))
mdb.models['Model-1'].HomogeneousSolidSection(name='Section-1',
    material='Material-1', thickness=None)
p = mdb.models['Model-1'].parts['Part-1']
c = p.cells
cells = c.getSequenceFromMask(mask=('#1 ], ), )
region = regionToolset.Region(cells=cells)
p = mdb.models['Model-1'].parts['Part-1']
p.SectionAssignment(region=region, sectionName='Section-1', offset=0.0,
    offsetType=MIDDLE_SURFACE, offsetField="",
    thicknessAssignment=FROM_SECTION)
session.viewports['Viewport: 1'].partDisplay.setValues(sectionAssignments=OFF,
    engineeringFeatures=OFF, mesh=ON)
session.viewports['Viewport: 1'].partDisplay.meshOptions.setValues(
    meshTechnique=ON)
p = mdb.models['Model-1'].parts['Part-1']
p.seedPart(size=1.0, deviationFactor=0.1, minSizeFactor=0.1)
p = mdb.models['Model-1'].parts['Part-1']

```

```

p.generateMesh()
a = mdb.models['Model-1'].rootAssembly
session.viewports['Viewport: 1'].setValues(displayedObject=a)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(
    optimizationTasks=OFF, geometricRestrictions=OFF, stopConditions=OFF)
a = mdb.models['Model-1'].rootAssembly
a.DatumCsysByDefault(CARTESIAN)
p = mdb.models['Model-1'].parts['Part-1']
a.Instance(name='Part-1-1', part=p, dependent=ON)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(
    adaptiveMeshConstraints=ON)
mdb.models['Model-1'].StaticStep(name='Step-1', previous='Initial')
session.viewports['Viewport: 1'].assemblyDisplay.setValues(step='Step-1')
session.viewports['Viewport: 1'].assemblyDisplay.setValues(interactions=ON,
    constraints=ON, connectors=ON, engineeringFeatures=ON,
    adaptiveMeshConstraints=OFF)
a = mdb.models['Model-1'].rootAssembly
v11 = a.instances['Part-1-1'].vertices
a.DatumPointByMidPoint(point1=v11[1], point2=v11[3])
a = mdb.models['Model-1'].rootAssembly
d11 = a.datums
a.ReferencePoint(point=d11[4])
a = mdb.models['Model-1'].rootAssembly
r1 = a.referencePoints
refPoints1=(r1[5], )
region1=regionToolset.Region(referencePoints=refPoints1)
a = mdb.models['Model-1'].rootAssembly
s1 = a.instances['Part-1-1'].faces
side1Faces1 = s1.getSequenceFromMask(mask=('[#1 ]', ), )
region2=regionToolset.Region(side1Faces=side1Faces1)
mdb.models['Model-1'].Coupling(name='Constraint-1', controlPoint=region1,
    surface=region2, influenceRadius=WHOLE_SURFACE,
    couplingType=KINEMATIC,
    localCsys=None, u1=ON, u2=ON, u3=ON, ur1=ON, ur2=ON, ur3=ON)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(loads=ON, bcs=ON,
    predefinedFields=ON, interactions=OFF, constraints=OFF,
    engineeringFeatures=OFF)
session.viewports['Viewport: 1'].view.setValues(nearPlane=175.393,
    farPlane=257.853, width=98.7787, height=44.2234, cameraPosition=(
    -40.4632, 138.113, 145.264), cameraUpVector=(0.196319, 0.474249,
    -0.858223), cameraTarget=(54.3779, -2.61895, 3.24109))
a = mdb.models['Model-1'].rootAssembly
f1 = a.instances['Part-1-1'].faces
faces1 = f1.getSequenceFromMask(mask=('[#4 ]', ), )

```

```

region = regionToolset.Region(faces=faces1)
mdb.models['Model-1'].EncastreBC(name='BC-1', createStepName='Step-1',
    region=region, localCsys=None)
session.viewports['Viewport: 1'].view.setValues(nearPlane=164.657,
    farPlane=273.649, width=92.7323, height=41.5164, cameraPosition=(
211.314, 98.4504, 115.969), cameraUpVector=(-0.539243, 0.685225,
-0.489575), cameraTarget=(48.9493, -1.76378, 3.8727))
a = mdb.models['Model-1'].rootAssembly
r1 = a.referencePoints
refPoints1=(r1[5],)
region = regionToolset.Region(referencePoints=refPoints1)
mdb.models['Model-1'].ConcentratedForce(name='Load-1', createStepName='Step-1',
    region=region, cf2=-100.0, distributionType=UNIFORM, field="",
    localCsys=None)
session.viewports['Viewport: 1'].assemblyDisplay.setValues(loads=OFF, bcs=OFF,
    predefinedFields=OFF, connectors=OFF)
mdb.Job(name='shiti1', model='Model-1', description="", type=ANALYSIS,
    atTime=None, waitMinutes=0, waitHours=0, queue=None, memory=90,
    memoryUnits=PERCENTAGE, getMemoryFromAnalysis=True,
    explicitPrecision=SINGLE, nodalOutputPrecision=SINGLE, echoPrint=OFF,
    modelPrint=OFF, contactPrint=OFF, historyPrint=OFF, userSubroutine="",
    scratch="", resultsFormat=ODB, multiprocessingMode=DEFAULT, numCpus=1,
    numGPUs=0)
mdb.jobs['shiti1'].submit(consistencyChecking=OFF)
session.mdbData.summary()
o3 = session.openOdb(name='D:/abaqus/exerciese/fem_final_work/chen/shiti1.odb')
session.viewports['Viewport: 1'].setValues(displayedObject=o3)
session.viewports['Viewport: 1'].makeCurrent()
session.viewports['Viewport: 1'].odbDisplay.display.setValues(plotState=(
    CONTOURS_ON_DEF,))
session.viewports['Viewport: 1'].odbDisplay.setPrimaryVariable(
    variableLabel='U', outputPosition=NODAL, refinement=(INVARIANT,
    'Magnitude'),)

```

## 五.致谢

研一的第一个学期已然结束，感谢王琥老师在有限元方法课程中对我的悉心教导，让我不仅对 `abaqus` 等软件的使用更加熟悉，也加深了我对有限元方法的了解。万分感谢！