

■ Tensor algebra.

- Kronecker delta.

$$\delta_{ij} = \begin{cases} = 1, & i = j \\ = 0, & i \neq j \end{cases} = \delta_{ji}$$

- The Levi-Civita “e” tensor (permutation tensor).

$$e_{ijk} = \begin{cases} 1 & ijk = 123, 231, 312 \\ -1 & ijk = 321, 213, 132 \\ 0 & \text{otherwise} \end{cases}$$

- e-delta identity.

$$e_{ijk}e_{lmk} = \delta_{il}\delta_{jm} - \delta_{im}\delta_{jl}$$

- Operations of three-dimensional vector algebra.

Decomposition:  $\mathbf{u} = u_i \mathbf{e}_i$  (vector in  $x_1 x_2 x_3$  space  $\mathbf{x} = x_i \mathbf{e}_i$ )

Scalar (dot) product between unit vectors:  $\mathbf{e}_i \cdot \mathbf{e}_j = \delta_{ij}$  (orthonormality)

Projection:  $\mathbf{e}_i \cdot \mathbf{u} = \mathbf{e}_i \cdot \mathbf{e}_j u_j = \delta_{ij} u_j = u_i$

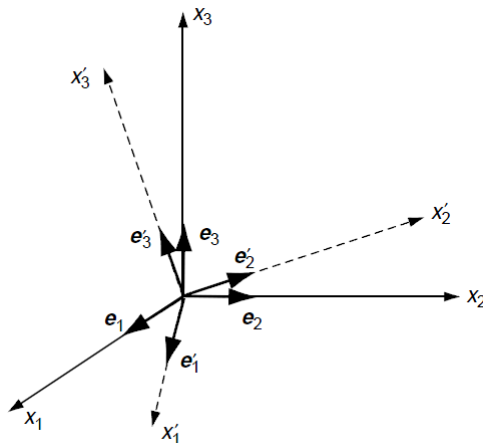
Scalar (dot) product between any two vectors:  $\mathbf{u} \cdot \mathbf{v} = u_i \mathbf{e}_i \cdot \mathbf{e}_j v_j = u_i v_i$

Vector (cross) product between unit vectors:  $\mathbf{e}_i \times \mathbf{e}_j = e_{ijk} \mathbf{e}_k$

Vector (cross) product between any two vectors:  $\mathbf{u} \times \mathbf{v} = \mathbf{e}_i e_{ijk} u_j v_k$

Scalar triple product:  $\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = (\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w} = e_{ijk} u_i v_j w_k$

- Tensor.



$$\mathbf{e}_i \cdot \mathbf{e}'_j = \beta_{ij} \quad (\beta_{ij} = \cos \theta, \quad \theta: \text{angle between } \mathbf{e}_i \text{ and } \mathbf{e}'_j)$$

$$\mathbf{e}_i = \sum_j \beta_{ij} \mathbf{e}'_j, \quad \mathbf{e}'_j = \sum_i \beta_{ji} \mathbf{e}_i.$$

$$\mathbf{u} = \sum_i u_i \mathbf{e}_i = \sum_i u'_i \mathbf{e}'_i$$

$$u'_i = \sum_{j=1}^3 \beta_{ij} u_j, \quad u_i = \sum_{j=1}^3 \beta_{ij} u'_j$$

$$u'_i = \sum_{j=1}^3 \beta_{ij} u_j = \sum_{j=1}^3 \beta_{ij} \sum_{k=1}^3 \beta_{jk} u'_k$$

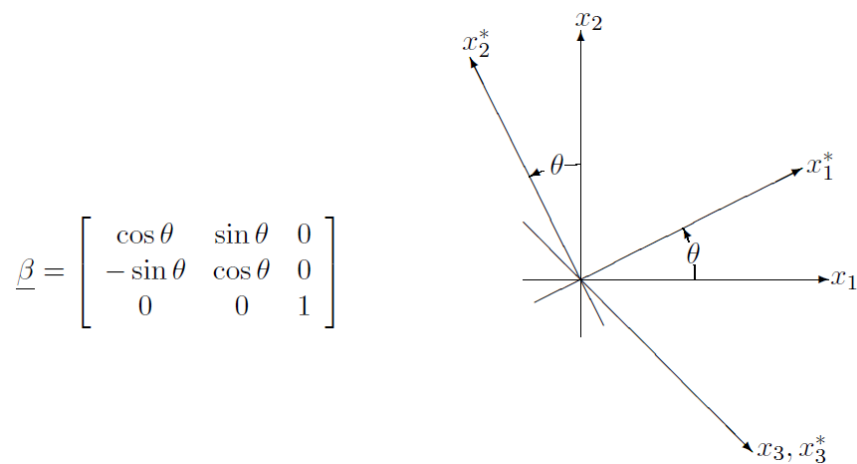
$$u_i = \sum_{j=1}^3 \beta_{ij} u'_j = \sum_{j=1}^3 \beta_{ij} \sum_{k=1}^3 \beta_{jk} u_k$$

$$u'_i = \delta_{ij} u'_j, \quad u_i = \delta_{ij} u_j$$

$$\sum_{j=1}^3 \beta_{ij} \sum_{k=1}^3 \beta_{jk} = \delta_{ik} \quad \therefore \text{matrix } \boldsymbol{\beta} = [\beta_{ij}] \Rightarrow \boldsymbol{\beta} \cdot \boldsymbol{\beta}^T = \boldsymbol{\beta}^T \cdot \boldsymbol{\beta} = \mathbf{I}(\text{orthogonal})$$

$$|\boldsymbol{\alpha}| = |\boldsymbol{\alpha}^T|, \quad |\boldsymbol{\alpha}\boldsymbol{\beta}| = |\boldsymbol{\alpha}| \cdot |\boldsymbol{\beta}| \quad \therefore \text{orthogonal: } (|\boldsymbol{\beta}|)^2 = |\mathbf{I}| = 1, \quad |\boldsymbol{\beta}| = \pm 1$$

예제)



$$\underline{\beta} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{e}'_j = \sum_i \beta_{ji} \mathbf{e}_i \Rightarrow \begin{bmatrix} \mathbf{e}'_1 \\ \mathbf{e}'_2 \\ \mathbf{e}'_3 \end{bmatrix} = \begin{bmatrix} \cos \theta & \cos(90 - \theta) & 0 \\ \cos(90 + \theta) & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mathbf{e}_1 \\ \mathbf{e}_2 \\ \mathbf{e}_3 \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mathbf{e}_1 \\ \mathbf{e}_2 \\ \mathbf{e}_3 \end{bmatrix}$$

- Linear operators.

$$\mathbf{v} = \boldsymbol{\lambda}(\mathbf{u}) = \boldsymbol{\lambda} \cdot \mathbf{u} (\text{tensor notation}) = \boldsymbol{\lambda} \mathbf{u} (\text{matrix notation})$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} \lambda_{11} & \lambda_{12} & \lambda_{13} \\ \lambda_{21} & \lambda_{22} & \lambda_{23} \\ \lambda_{31} & \lambda_{32} & \lambda_{33} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} \lambda_{11}u_1 + \lambda_{12}u_2 + \lambda_{13}u_3 \\ \lambda_{21}u_1 + \lambda_{22}u_2 + \lambda_{23}u_3 \\ \lambda_{31}u_1 + \lambda_{32}u_2 + \lambda_{33}u_3 \end{bmatrix}$$

$$\boldsymbol{\lambda}(a\mathbf{u} + b\mathbf{v}) = a\boldsymbol{\lambda}(\mathbf{u}) + b\boldsymbol{\lambda}(\mathbf{v}), \quad a, b: \text{scalar}$$

$$v_i = \mathbf{e}_i \cdot \boldsymbol{\lambda}(\mathbf{e}_j u_j) = \sum_j \lambda_{ij} u_j \equiv \mathbf{e}_i \cdot \boldsymbol{\lambda}(\mathbf{e}_j) u_j, \quad \sum_j \lambda_{ij} \equiv \mathbf{e}_i \cdot \boldsymbol{\lambda}(\mathbf{e}_j), \quad \boldsymbol{\lambda} = [\lambda_{ij}]$$

- $\{x_1 \ x_2 \ x_3\}$ 에서 정의된  $\boldsymbol{\lambda}$ 를  $\{x'_1 \ x'_2 \ x'_3\}$ 에 적용할 경우.

$$\mathbf{v}' = \boldsymbol{\lambda}'(\mathbf{u}') = \boldsymbol{\lambda}' \cdot \mathbf{u}' = \boldsymbol{\lambda}' \mathbf{u}' \text{를 만족하는 } \boldsymbol{\lambda}' \text{를 구한다.}$$

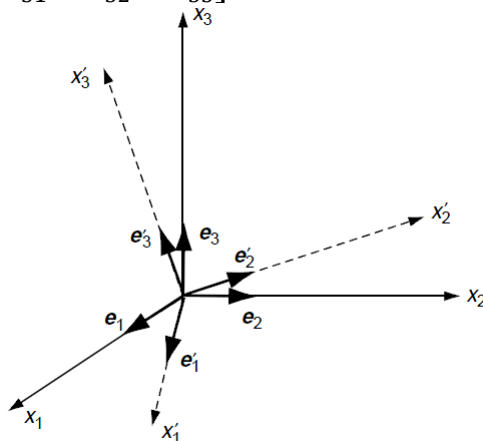
$$v'_i = \sum_j \beta_{ij} v_j, \quad v_j = \sum_k \lambda_{jk} u_k, \quad u_k = \sum_l \beta_{kl} u'_l$$

$$v'_i = \sum_j \beta_{ij} \sum_k \lambda_{jk} \sum_l \beta_{kl} u'_l,$$

$$\sum_l \lambda'_{il} = \sum_j \beta_{ij} \sum_k \lambda_{jk} \sum_l \beta_{kl}, \quad \boldsymbol{\lambda}' = \boldsymbol{\beta} \boldsymbol{\lambda} \boldsymbol{\beta}^T (\text{matrix notation})$$

$$il: \{x'_1 \ x'_2 \ x'_3\} \text{system indices}, \quad jk: \{x_1 \ x_2 \ x_3\} \text{system indices}$$

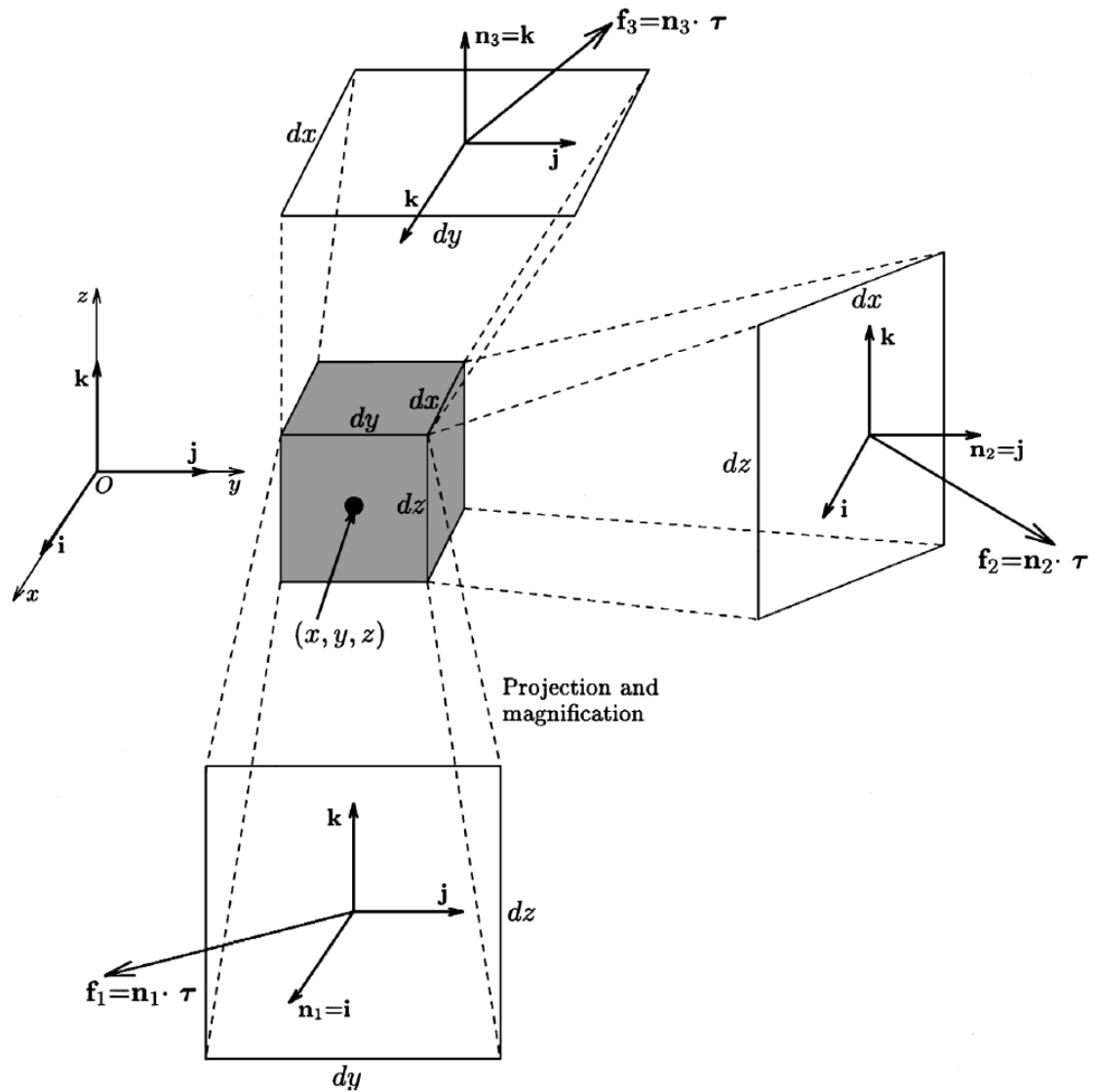
$$\begin{bmatrix} \lambda'_{11} & \lambda'_{12} & \lambda'_{13} \\ \lambda'_{21} & \lambda'_{22} & \lambda'_{23} \\ \lambda'_{31} & \lambda'_{32} & \lambda'_{33} \end{bmatrix} = \begin{bmatrix} \beta_{11} & \beta_{12} & \beta_{13} \\ \beta_{21} & \beta_{22} & \beta_{23} \\ \beta_{31} & \beta_{32} & \beta_{33} \end{bmatrix} \begin{bmatrix} \lambda_{11} & \lambda_{12} & \lambda_{13} \\ \lambda_{21} & \lambda_{22} & \lambda_{23} \\ \lambda_{31} & \lambda_{32} & \lambda_{33} \end{bmatrix} \begin{bmatrix} \beta_{11} & \beta_{21} & \beta_{31} \\ \beta_{12} & \beta_{22} & \beta_{32} \\ \beta_{13} & \beta_{23} & \beta_{33} \end{bmatrix}$$



- Invariant.

The property is shared by  $\boldsymbol{\lambda}$  and  $\boldsymbol{\lambda}'$  (for any  $\boldsymbol{\beta}$ ).

■ Stress tensor.



$$\mathbf{a} \cdot \boldsymbol{\sigma} = \sum_{i=1}^3 \left( \sum_{j=1}^3 a_j \sigma_{ji} \right) \mathbf{n}_i, \quad \boldsymbol{\sigma} \cdot \mathbf{a} = \sum_{i=1}^3 \left( \sum_{j=1}^3 \sigma_{ij} a_j \right) \mathbf{n}_i \text{ (tensor algebra)}$$

$$\mathbf{f}_1 = \mathbf{n}_1 \cdot \boldsymbol{\tau}, \quad \mathbf{f}_2 = \mathbf{n}_2 \cdot \boldsymbol{\tau}, \quad \mathbf{f}_3 = \mathbf{n}_3 \cdot \boldsymbol{\tau}$$

$$\mathbf{f}_1 = \mathbf{n}_1 \cdot \boldsymbol{\tau} = [\tau_{11} \quad \tau_{12} \quad \tau_{13}] = [\mathbf{1} \quad 0 \quad 0] \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix}$$

$$\mathbf{f}_2 = \mathbf{n}_2 \cdot \boldsymbol{\tau} = [\tau_{21} \quad \tau_{22} \quad \tau_{23}] = [0 \quad \mathbf{1} \quad 0] \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix}$$

$$\mathbf{f}_3 = \mathbf{n}_3 \cdot \boldsymbol{\tau} = [\tau_{31} \quad \tau_{32} \quad \tau_{33}] = [0 \quad 0 \quad \mathbf{1}] \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix}$$

$$\begin{aligned}
\boldsymbol{\tau} &= \mathbf{n}_1 \mathbf{f}_1 + \mathbf{n}_2 \mathbf{f}_2 + \mathbf{n}_3 \mathbf{f}_3 (\text{tensor notation}) \\
&= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} \tau_{21} & \tau_{22} & \tau_{23} \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} \\
&= \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ \tau_{21} & \tau_{22} & \tau_{23} \\ 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} = \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix}
\end{aligned}$$

$$\begin{aligned}
\mathbf{f}_1 &= \tau_{11} \mathbf{n}_1 + \tau_{12} \mathbf{n}_2 + \tau_{13} \mathbf{n}_3 \\
\mathbf{f}_2 &= \tau_{21} \mathbf{n}_1 + \tau_{22} \mathbf{n}_2 + \tau_{23} \mathbf{n}_3 \\
\mathbf{f}_3 &= \tau_{31} \mathbf{n}_1 + \tau_{32} \mathbf{n}_2 + \tau_{33} \mathbf{n}_3
\end{aligned}
\quad \Rightarrow \quad
\begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} = \boldsymbol{\tau}$$

$$\begin{aligned}
\mathbf{f} &= \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix}^T = \mathbf{n} \cdot \boldsymbol{\tau} = \begin{bmatrix} n_1 & n_2 & n_3 \end{bmatrix} \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} = \begin{bmatrix} n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31} \\ n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32} \\ n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33} \end{bmatrix}^T \\
(|\mathbf{n}| &= \sqrt{n_1^2 + n_2^2 + n_3^2} = 1)
\end{aligned}$$

$$\mathbf{f} = \mathbf{f}_N + \mathbf{f}_T$$

$$\mathbf{f}_N = (\mathbf{n} \cdot \mathbf{f}) \mathbf{n} = \mathbf{n} \cdot (\mathbf{n} \cdot \boldsymbol{\tau}) \mathbf{n} = (\mathbf{nn} : \boldsymbol{\tau}) \mathbf{n}$$

$$\begin{aligned}
\mathbf{n} \cdot \mathbf{f} &= \begin{bmatrix} n_1 & n_2 & n_3 \end{bmatrix} \begin{bmatrix} n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31} \\ n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32} \\ n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33} \end{bmatrix} \\
&= n_1(n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31}) + n_2(n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32}) + n_3(n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33})
\end{aligned}$$

$$\begin{aligned}
\mathbf{nn} : \boldsymbol{\tau} &= \sum_{i=1}^3 \{[\mathbf{nn}] \quad [\boldsymbol{\tau}]\}_{ii} = \sum_{i=1}^3 \left\{ \begin{bmatrix} \mathbf{n}_1 \mathbf{n}_1 & \mathbf{n}_1 \mathbf{n}_2 & \mathbf{n}_1 \mathbf{n}_3 \\ \mathbf{n}_2 \mathbf{n}_1 & \mathbf{n}_2 \mathbf{n}_2 & \mathbf{n}_2 \mathbf{n}_3 \\ \mathbf{n}_3 \mathbf{n}_1 & \mathbf{n}_3 \mathbf{n}_2 & \mathbf{n}_3 \mathbf{n}_3 \end{bmatrix} \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} \right\}_{ii} \\
&= (\mathbf{n}_1 \mathbf{n}_1 \tau_{11} + \mathbf{n}_1 \mathbf{n}_2 \tau_{21} + \mathbf{n}_1 \mathbf{n}_3 \tau_{31}) + (\mathbf{n}_2 \mathbf{n}_1 \tau_{12} + \mathbf{n}_2 \mathbf{n}_2 \tau_{22} + \mathbf{n}_2 \mathbf{n}_3 \tau_{32}) + (\mathbf{n}_3 \mathbf{n}_1 \tau_{13} + \mathbf{n}_3 \mathbf{n}_2 \tau_{23} + \mathbf{n}_3 \mathbf{n}_3 \tau_{33}) \\
&= n_1(n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31}) + n_2(n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32}) + n_3(n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33}) = |\mathbf{f}_N|
\end{aligned}$$

$$\begin{aligned}
\mathbf{f}_T &= \mathbf{f} - \mathbf{f}_N = \mathbf{n} \cdot \boldsymbol{\tau} - (\mathbf{nn} : \boldsymbol{\tau}) \mathbf{n} \\
&= \begin{bmatrix} n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31} - \mathbf{n}_1(n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31}) + n_2(n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32}) + n_3(n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33}) \\ n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32} - \mathbf{n}_2(n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31}) + n_2(n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32}) + n_3(n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33}) \\ n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33} - \mathbf{n}_3(n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31}) + n_2(n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32}) + n_3(n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33}) \end{bmatrix}
\end{aligned}$$

$$\mathbf{f}_T = \mathbf{n} \times (\mathbf{f} \times \mathbf{n}) = \mathbf{f} \cdot (\mathbf{I} - \mathbf{nn})$$

$$\mathbf{f} \times \mathbf{n} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ f_1 & f_2 & f_3 \\ n_1 & n_2 & n_3 \end{vmatrix} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31} & n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32} & n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33} \\ n_1 & n_2 & n_3 \end{vmatrix}$$

$$\mathbf{n} \times (\mathbf{f} \times \mathbf{n}) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ n_1 & n_2 & n_3 \\ f_2 n_3 - f_3 n_2 & f_3 n_1 - f_1 n_3 & f_1 n_2 - f_2 n_1 \end{vmatrix} = \begin{bmatrix} n_2(f_1 n_2 - f_2 n_1) - n_3(f_3 n_1 - f_1 n_3) \\ n_3(f_2 n_3 - f_3 n_2) - n_1(f_1 n_2 - f_2 n_1) \\ n_1(f_3 n_1 - f_1 n_3) - n_2(f_2 n_3 - f_3 n_2) \end{bmatrix}$$

$$\begin{aligned}
n_2(f_1 n_2 - f_2 n_1) - n_3(f_3 n_1 - f_1 n_3) &= f_1(\mathbf{n}_1 \mathbf{n}_1 + \mathbf{n}_2 \mathbf{n}_2 + \mathbf{n}_3 \mathbf{n}_3) - n_1(\mathbf{n}_1 \mathbf{f}_1 + \mathbf{n}_2 \mathbf{f}_2 + \mathbf{n}_3 \mathbf{f}_3) \\
&= n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31} - \mathbf{n}_1(n_1 \tau_{11} + n_2 \tau_{21} + n_3 \tau_{31}) + n_2(n_1 \tau_{12} + n_2 \tau_{22} + n_3 \tau_{32}) + n_3(n_1 \tau_{13} + n_2 \tau_{23} + n_3 \tau_{33})
\end{aligned}$$

$$\mathbf{f} \cdot (\mathbf{I} - \mathbf{nn}) = \begin{bmatrix} f_1 & f_2 & f_3 \end{bmatrix} \begin{bmatrix} 1 - n_1 n_1 & -n_1 n_2 & -n_1 n_3 \\ -n_2 n_1 & 1 - n_2 n_2 & -n_2 n_3 \\ -n_3 n_1 & -n_3 n_2 & 1 - n_3 n_3 \end{bmatrix} = \begin{bmatrix} f_1 - n_1(n_1 f_1 + n_2 f_2 + n_3 f_3) \\ f_2 - n_2(n_1 f_1 + n_2 f_2 + n_3 f_3) \\ f_3 - n_3(n_1 f_1 + n_2 f_2 + n_3 f_3) \end{bmatrix}$$

● Invariants.

$$\begin{vmatrix} \tau_{11} - \lambda & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} - \lambda & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} - \lambda \end{vmatrix}$$

$$= (\tau_{11} - \lambda)(\tau_{22} - \lambda)(\tau_{33} - \lambda) - \tau_{23}\tau_{32}(\tau_{11} - \lambda) + \tau_{12}\tau_{23}\tau_{31} - \tau_{12}\tau_{21}(\tau_{33} - \lambda) + \tau_{13}\tau_{21}\tau_{32} - \tau_{13}(\tau_{22} - \lambda)\tau_{31}$$

$$= -\{\lambda^3 - (\tau_{11} + \tau_{22} + \tau_{33})\lambda^2 + (\tau_{11}\tau_{22} + \tau_{11}\tau_{33} + \tau_{22}\tau_{33} - \tau_{12}\tau_{21} - \tau_{13}\tau_{31} - \tau_{23}\tau_{32})\lambda - (\tau_{11}\tau_{22}\tau_{33} - \tau_{11}\tau_{23}\tau_{32} + \tau_{12}\tau_{23}\tau_{31} - \tau_{12}\tau_{21}\tau_{33} + \tau_{13}\tau_{21}\tau_{32} - \tau_{13}\tau_{22}\tau_{31})\}$$

$$= -\{\lambda^3 - J_1\lambda^2 + J_2\lambda - J_3\} = 0$$

$$\begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} \quad \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

$$J_1 = \tau_{11} + \tau_{22} + \tau_{33} = \lambda_1 + \lambda_2 + \lambda_3$$

$$J_2 = \begin{vmatrix} \tau_{22} & \tau_{23} \\ \tau_{32} & \tau_{33} \end{vmatrix} + \begin{vmatrix} \tau_{11} & \tau_{13} \\ \tau_{31} & \tau_{33} \end{vmatrix} + \begin{vmatrix} \tau_{11} & \tau_{12} \\ \tau_{21} & \tau_{22} \end{vmatrix} = \lambda_1 \lambda_2 + \lambda_1 \lambda_3 + \lambda_2 \lambda_3 \text{ (cofactor)}$$

$$J_3 = \begin{vmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{vmatrix} = \lambda_1 \lambda_2 \lambda_3$$

$$(\lambda - \lambda_1)(\lambda - \lambda_2)(\lambda - \lambda_3)$$

$$= \lambda^3 - (\lambda_1 + \lambda_2 + \lambda_3)\lambda^2 + (\lambda_1 \lambda_2 + \lambda_1 \lambda_3 + \lambda_2 \lambda_3)\lambda - \lambda_1 \lambda_2 \lambda_3$$

■ Maximum shear stress.

$$\mathbf{f} = \mathbf{f}_N + \mathbf{f}_T$$

$$\mathbf{f}_N = (\mathbf{n} \cdot \mathbf{f}) \mathbf{n} = \mathbf{n} \cdot (\mathbf{n} \cdot \boldsymbol{\tau}) \mathbf{n} = (\mathbf{nn} : \boldsymbol{\tau}) \mathbf{n}$$

$\mathbf{n} \rightarrow$  principal direction

$$\mathbf{f} = \mathbf{n} \cdot \boldsymbol{\tau} = \begin{bmatrix} n_1 & n_2 & n_3 \end{bmatrix} \begin{bmatrix} \sigma_{11} & 0 & 0 \\ 0 & \sigma_{22} & 0 \\ 0 & 0 & \sigma_{33} \end{bmatrix} = \begin{bmatrix} n_1 \sigma_{11} \\ n_2 \sigma_{22} \\ n_3 \sigma_{33} \end{bmatrix}^T \rightarrow |\mathbf{f}|^2 = n_1^2 \sigma_{11}^2 + n_2^2 \sigma_{22}^2 + n_3^2 \sigma_{33}^2$$

$$|\mathbf{f}_N| = \mathbf{n} \cdot \mathbf{f} = \begin{bmatrix} n_1 & n_2 & n_3 \end{bmatrix} \begin{bmatrix} n_1 \sigma_{11} \\ n_2 \sigma_{22} \\ n_3 \sigma_{33} \end{bmatrix} = n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + n_3^2 \sigma_{33}$$

$$|\mathbf{f}_T|^2 = |\mathbf{f}|^2 - |\mathbf{f}_N|^2 = n_1^2 \sigma_{11}^2 + n_2^2 \sigma_{22}^2 + n_3^2 \sigma_{33}^2 - (n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + n_3^2 \sigma_{33})^2$$

$$n_3^2 = 1 - n_1^2 - n_2^2$$

$$|\mathbf{f}_T|^2 = n_1^2 \sigma_{11}^2 + n_2^2 \sigma_{22}^2 + (1 - n_1^2 - n_2^2) \sigma_{33}^2 - (n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + (1 - n_1^2 - n_2^2) \sigma_{33})^2$$

$$\frac{\partial |\mathbf{f}_T|^2}{\partial n_1} = 0, \quad \frac{\partial |\mathbf{f}_T|^2}{\partial n_2} = 0$$

$$\frac{\partial |\mathbf{f}_T|^2}{\partial n_1} = 2n_1\sigma_{11}^2 - 2n_1\sigma_{33}^2 - 2(n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33})(2n_1\sigma_{11} - 2n_1\sigma_{33}) = 0$$

$$n_1(\sigma_{11}^2 - \sigma_{33}^2) = 2(n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33})n_1(\sigma_{11} - \sigma_{33})$$

$$(\sigma_{11} + \sigma_{33})n_1 = 2(n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33})n_1$$

$$(\sigma_{22} + \sigma_{33})n_2 = 2(n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33})n_2$$

Case1)  $\sigma_{11} \neq \sigma_{22} \neq \sigma_{33}$

$$n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33} - \frac{\sigma_{11} + \sigma_{33}}{2} = 0$$

$$n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33} - \frac{\sigma_{22} + \sigma_{33}}{2} = 0$$

$$\sigma_{11} \neq \sigma_{22} \quad \therefore n_1 = 0 \text{ or } n_2 = 0$$

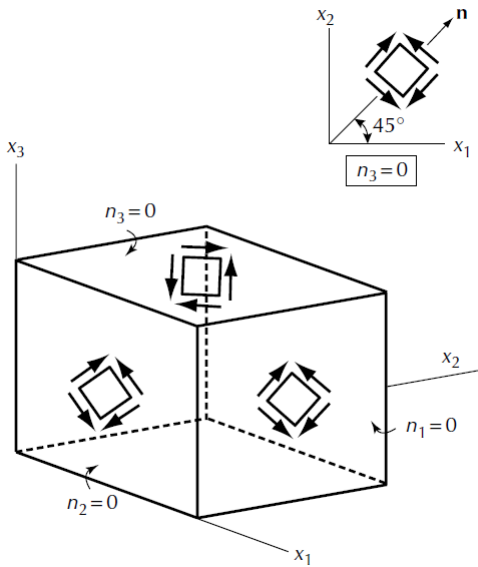
if  $n_1 = 0$

$$n_1^2\sigma_{11} + n_2^2\sigma_{22} + (1 - n_1^2 - n_2^2)\sigma_{33} - \frac{\sigma_{22} + \sigma_{33}}{2} = \left(n_2^2 - \frac{1}{2}\right)(\sigma_{22} - \sigma_{33}) = 0$$

$$\therefore n_1 = 0, \quad n_2 = \pm \frac{1}{\sqrt{2}}, \quad n_3 = \pm \frac{1}{\sqrt{2}}, \quad |\mathbf{f}_T|^2 = \left(\frac{\sigma_{22} - \sigma_{33}}{2}\right)^2 \rightarrow |\mathbf{f}_T| = \left|\frac{\sigma_{22} - \sigma_{33}}{2}\right|$$

$$n_1 = \pm \frac{1}{\sqrt{2}}, \quad n_2 = 0, \quad n_3 = \pm \frac{1}{\sqrt{2}}, \quad |\mathbf{f}_T| = \left|\frac{\sigma_{11} - \sigma_{33}}{2}\right|$$

$$n_1 = \pm \frac{1}{\sqrt{2}}, \quad n_2 = \pm \frac{1}{\sqrt{2}}, \quad n_3 = 0, \quad |\mathbf{f}_T| = \left|\frac{\sigma_{11} - \sigma_{22}}{2}\right|$$



Case2)  $\sigma_{11} = \sigma_{22} \neq \sigma_{33}$

$$n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + (1 - n_1^2 - n_2^2) \sigma_{33} - \frac{\sigma_{11} + \sigma_{33}}{2} = 0$$

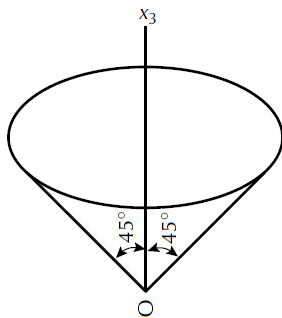
$$n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + (1 - n_1^2 - n_2^2) \sigma_{33} - \frac{\sigma_{22} + \sigma_{33}}{2} = 0$$

$$\sigma_{11} = \sigma_{22}$$

$$\left(n_1^2 + n_2^2 - \frac{1}{2}\right) \sigma_{11} + \left(\frac{1}{2} - n_1^2 - n_2^2\right) \sigma_{33} = 0$$

$$n_1^2 + n_2^2 = \frac{1}{2}, \quad n_3^2 = \frac{1}{2}, \quad n_3 = \pm \frac{1}{\sqrt{2}}$$

$$|\mathbf{f}_T|^2 = \left(\frac{\sigma_{22} - \sigma_{33}}{2}\right)^2 \rightarrow |\mathbf{f}_T| = \left|\frac{\sigma_{22} - \sigma_{33}}{2}\right| = \left|\frac{\sigma_{11} - \sigma_{33}}{2}\right|$$



Case3)  $\sigma_{11} = \sigma_{22} = \sigma_{33} = \sigma$  (hydrostatic pressure)

$$|\mathbf{f}_T|^2 = n_1^2 \sigma_{11}^2 + n_2^2 \sigma_{22}^2 + (1 - n_1^2 - n_2^2) \sigma_{33}^2 - (n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + (1 - n_1^2 - n_2^2) \sigma_{33})^2$$

$$= \sigma^2 - \sigma^2 = 0$$

■ **Hydrostatic** and **deviatoric** stress.

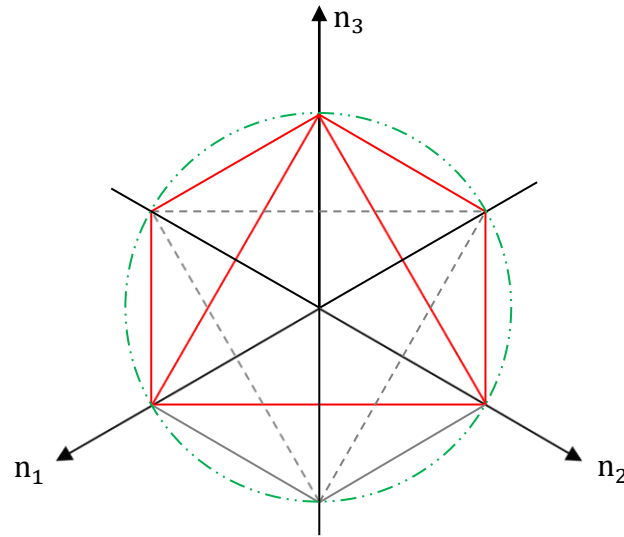
$$\begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} = \begin{bmatrix} \frac{\tau_{11} + \tau_{22} + \tau_{33}}{3} & 0 & 0 \\ 0 & \frac{\tau_{11} + \tau_{22} + \tau_{33}}{3} & 0 \\ 0 & 0 & \frac{\tau_{11} + \tau_{22} + \tau_{33}}{3} \end{bmatrix}$$

$$+ \begin{bmatrix} \tau_{11} - \frac{\tau_{11} + \tau_{22} + \tau_{33}}{3} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} - \frac{\tau_{11} + \tau_{22} + \tau_{33}}{3} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} - \frac{\tau_{11} + \tau_{22} + \tau_{33}}{3} \end{bmatrix}$$

deviatoric stress



■ Octahedral shear stress.



$\mathbf{n} \rightarrow$  principal direction

$$n_1^2 = n_2^2 = n_3^2 = \frac{1}{3}, \quad (\text{octahedral planes})$$

$$\begin{aligned} |\mathbf{f}_T|^2 &= |\mathbf{f}|^2 - |\mathbf{f}_N|^2 = n_1^2 \sigma_{11}^2 + n_2^2 \sigma_{22}^2 + n_3^2 \sigma_{33}^2 - (n_1^2 \sigma_{11} + n_2^2 \sigma_{22} + n_3^2 \sigma_{33})^2 \\ &= \frac{1}{3} (\sigma_{11}^2 + \sigma_{22}^2 + \sigma_{33}^2) - \frac{1}{9} (\sigma_{11} + \sigma_{22} + \sigma_{33})^2 \\ &= \frac{1}{9} (2\sigma_{11}^2 + 2\sigma_{22}^2 + 2\sigma_{33}^2 - 2\sigma_{11}\sigma_{22} - 2\sigma_{22}\sigma_{33} - 2\sigma_{33}\sigma_{11}) \\ &= \frac{1}{9} \{(\sigma_{11} - \sigma_{22})^2 + (\sigma_{22} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{11})^2\} \end{aligned}$$

or

$$\begin{aligned} &= \frac{2}{9} \{(\sigma_{11} + \sigma_{22} + \sigma_{33})^2 - 3(\sigma_{11}\sigma_{22} + \sigma_{22}\sigma_{33} + \sigma_{33}\sigma_{11})\} = \frac{2}{9} (I_1^2 - 3I_2) \\ &= \frac{2}{9} \{(\tau_{11} + \tau_{22} + \tau_{33})^2 - 3(\tau_{11}\tau_{22} + \tau_{11}\tau_{33} + \tau_{22}\tau_{33} - \tau_{12}\tau_{21} - \tau_{13}\tau_{31} - \tau_{23}\tau_{32})\} \\ &= \frac{1}{9} \{(\tau_{11} - \tau_{22})^2 + (\tau_{22} - \tau_{33})^2 + (\tau_{33} - \tau_{11})^2 + 6(\tau_{12}^2 + \tau_{13}^2 + \tau_{23}^2)\} \end{aligned}$$

$$J_1 = \tau_{11} + \tau_{22} + \tau_{33} = \lambda_1 + \lambda_2 + \lambda_3$$

$$J_2 = \begin{vmatrix} \tau_{22} & \tau_{23} \\ \tau_{32} & \tau_{33} \end{vmatrix} + \begin{vmatrix} \tau_{11} & \tau_{13} \\ \tau_{31} & \tau_{33} \end{vmatrix} + \begin{vmatrix} \tau_{11} & \tau_{12} \\ \tau_{21} & \tau_{22} \end{vmatrix} = \lambda_1 \lambda_2 + \lambda_1 \lambda_3 + \lambda_2 \lambda_3$$

■ Effective stress: tensile test  $(\sigma_{11} = \sigma_{yield}, \sigma_{22} = \sigma_{33} = 0, |\tau_{oct}| < \frac{\sqrt{2}}{3} \sigma_{yield})$ .

$$\begin{aligned} \sigma_{eff} &= \frac{3}{\sqrt{2}} |\tau_{oct}| = \frac{1}{\sqrt{2}} \sqrt{(\sigma_{11} - \sigma_{22})^2 + (\sigma_{22} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{11})^2} \\ &= \frac{1}{\sqrt{2}} \sqrt{(\tau_{11} - \tau_{22})^2 + (\tau_{22} - \tau_{33})^2 + (\tau_{33} - \tau_{11})^2 + 6(\tau_{12}^2 + \tau_{13}^2 + \tau_{23}^2)} < \sigma_{yield} \end{aligned}$$

■ Graph of octahedral shear stress.

$$|\tau_{oct}|^2 < \left( \frac{\sqrt{2}}{3} \sigma_{yield} \right)^2 = \frac{1}{9} \{ (\sigma_{11} - \sigma_{22})^2 + (\sigma_{22} - \sigma_{33})^2 + (\sigma_{33} - \sigma_{11})^2 \}$$

$$\sigma_{33} = 0 \rightarrow \sigma_{yield}^2 = \sigma_{11}^2 + \sigma_{22}^2 - \sigma_{11}\sigma_{22}$$

$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$ ,  $B \neq 0$  의 경우  $xy$  항을 제거하기 위한 좌표 계의 회전각  $\theta$ 는  $\cot 2\theta = \frac{A-C}{B}$ ,  $0 < 2\theta < 180^\circ$

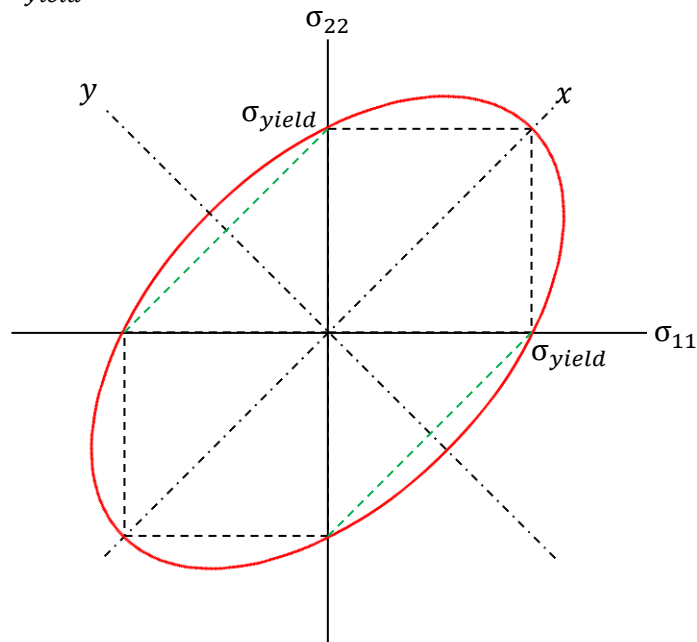
$$\sigma_{11}^2 - \sigma_{11}\sigma_{22} + \sigma_{22}^2 = \sigma_{yield}^2$$

$$\cot 2\theta = \frac{1}{\tan 2\theta} = \frac{A-C}{B} = 0 \rightarrow \theta = 45^\circ$$

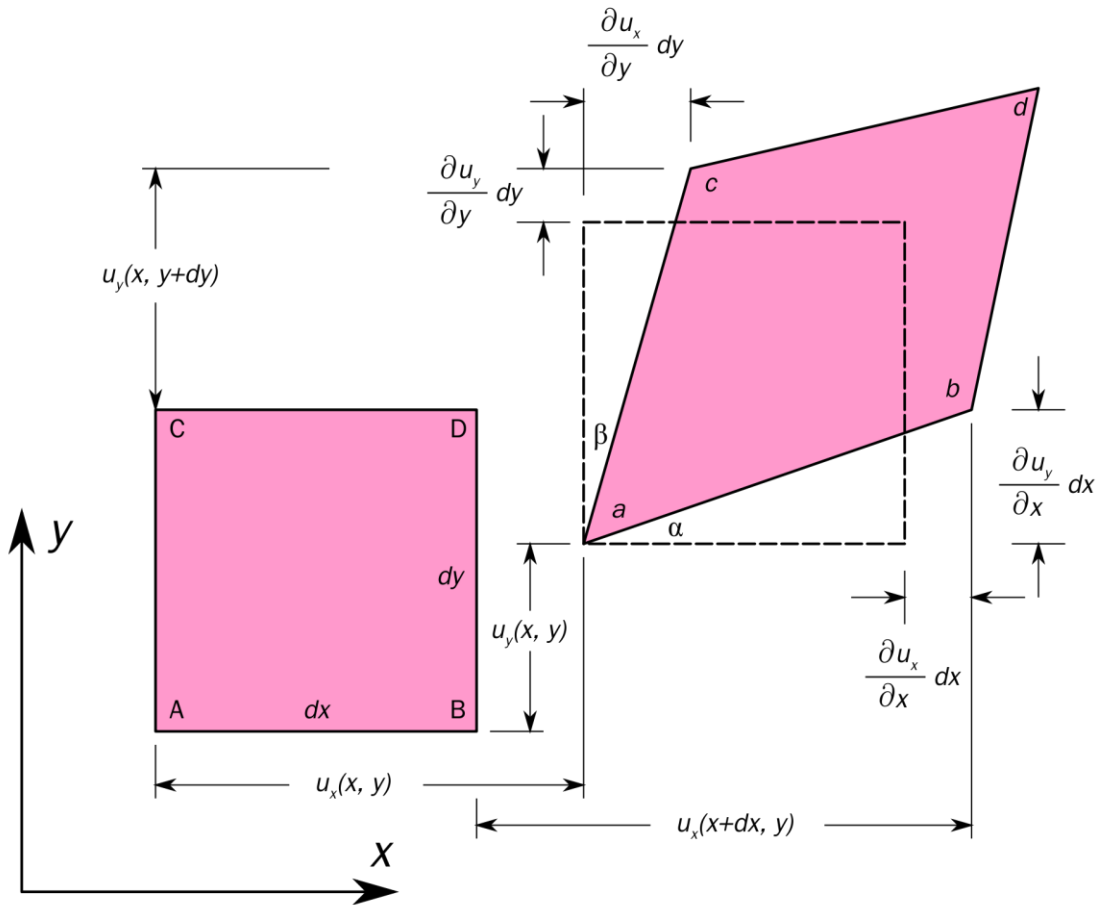
$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \end{bmatrix} = \begin{bmatrix} \cos(-\theta) & \sin(-\theta) \\ -\sin(-\theta) & \cos(-\theta) \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos\theta x - \sin\theta y \\ \sin\theta x + \cos\theta y \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}}x - \frac{1}{\sqrt{2}}y \\ \frac{1}{\sqrt{2}}x + \frac{1}{\sqrt{2}}y \end{bmatrix}$$

$$\left( \frac{1}{\sqrt{2}}x - \frac{1}{\sqrt{2}}y \right)^2 - \left( \frac{1}{\sqrt{2}}x - \frac{1}{\sqrt{2}}y \right) \left( \frac{1}{\sqrt{2}}x + \frac{1}{\sqrt{2}}y \right) + \left( \frac{1}{\sqrt{2}}x + \frac{1}{\sqrt{2}}y \right)^2 = \sigma_{yield}^2$$

$$\left( \frac{1}{\sqrt{2}}x \right)^2 + \left( \frac{\sqrt{3}}{\sqrt{2}}y \right)^2 = \sigma_{yield}^2$$



■ Strain tensor.



● Displacement gradient tensor.

$$\nabla \mathbf{u} = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} u_x & u_y & u_z \end{bmatrix} = \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_y}{\partial x} & \frac{\partial u_z}{\partial x} \\ \frac{\partial u_x}{\partial y} & \frac{\partial u_y}{\partial y} & \frac{\partial u_z}{\partial y} \\ \frac{\partial u_x}{\partial z} & \frac{\partial u_y}{\partial z} & \frac{\partial u_z}{\partial z} \end{bmatrix}$$

● Normal strain.

$$\epsilon_x = \frac{\overline{ab} - \overline{AB}}{\overline{AB}} = \frac{\overline{ab} - dx}{dx}$$

$$\overline{ab} = \sqrt{\left(dx + \frac{\partial u_x}{\partial x} dx\right)^2 + \left(\frac{\partial u_y}{\partial x} dx\right)^2} \cong \left(1 + \frac{\partial u_x}{\partial x}\right) dx \quad \left[\left(\frac{\partial u_y}{\partial x} dx\right)^2 \rightarrow 0\right]$$

$$\epsilon_x \cong \frac{\partial u_x}{\partial x} \quad (\text{small strain} < 0.01)$$

- Shear strain.

$$\gamma_{xy} = \alpha + \beta = \tan^{-1} \left( \frac{\frac{\partial u_y}{\partial x} dx}{dx + \frac{\partial u_x}{\partial x} dx} \right) + \tan^{-1} \left( \frac{\frac{\partial u_x}{\partial y} dy}{dy + \frac{\partial u_y}{\partial y} dy} \right)$$

$$\gamma_{xy} \cong \frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y} \quad (\text{small normal and shear strain})$$

- Tensor decomposition (deformation and rigid body rotation).

$$\nabla \mathbf{u} = \frac{1}{2} (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) + \frac{1}{2} (\nabla \mathbf{u} - (\nabla \mathbf{u})^T) \quad (\nabla \mathbf{u})^T = \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_x}{\partial y} & \frac{\partial u_x}{\partial z} \\ \frac{\partial u_y}{\partial x} & \frac{\partial u_y}{\partial y} & \frac{\partial u_y}{\partial z} \\ \frac{\partial u_z}{\partial x} & \frac{\partial u_z}{\partial y} & \frac{\partial u_z}{\partial z} \end{bmatrix}$$

$$\text{Symmetric tensor} \quad e_{ij} = \frac{1}{2} (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) = \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y}}{2} & \frac{\frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z}}{2} \\ \frac{\frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y}}{2} & \frac{\partial u_y}{\partial y} & \frac{\frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z}}{2} \\ \frac{\frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z}}{2} & \frac{\frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z}}{2} & \frac{\partial u_z}{\partial z} \end{bmatrix} = \begin{bmatrix} \epsilon_x & \frac{\gamma_{xy}}{2} & \frac{\gamma_{xz}}{2} \\ \frac{\gamma_{xy}}{2} & \epsilon_y & \frac{\gamma_{yz}}{2} \\ \frac{\gamma_{xz}}{2} & \frac{\gamma_{yz}}{2} & \epsilon_z \end{bmatrix}$$

- Large strain (ex: Green strain).

$$\mathbf{G} = \frac{1}{2} (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) + \frac{1}{2} \nabla \mathbf{u} (\nabla \mathbf{u})^T = \begin{bmatrix} e_{xx} & e_{xy} & e_{xz} \\ e_{xy} & e_{yy} & e_{yz} \\ e_{xz} & e_{yz} & e_{zz} \end{bmatrix}$$

$$\nabla \mathbf{u} (\nabla \mathbf{u})^T = \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_y}{\partial x} & \frac{\partial u_z}{\partial x} \\ \frac{\partial u_x}{\partial y} & \frac{\partial u_y}{\partial y} & \frac{\partial u_z}{\partial y} \\ \frac{\partial u_x}{\partial z} & \frac{\partial u_y}{\partial z} & \frac{\partial u_z}{\partial z} \end{bmatrix} \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_x}{\partial y} & \frac{\partial u_x}{\partial z} \\ \frac{\partial u_y}{\partial x} & \frac{\partial u_y}{\partial y} & \frac{\partial u_y}{\partial z} \\ \frac{\partial u_z}{\partial x} & \frac{\partial u_z}{\partial y} & \frac{\partial u_z}{\partial z} \end{bmatrix} = \begin{bmatrix} \left( \frac{\partial u_x}{\partial x} \right)^2 + \left( \frac{\partial u_y}{\partial x} \right)^2 + \left( \frac{\partial u_z}{\partial x} \right)^2 & \frac{\partial u_x}{\partial x} \frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial x} \frac{\partial u_z}{\partial y} & \frac{\partial u_x}{\partial x} \frac{\partial u_x}{\partial z} + \frac{\partial u_y}{\partial x} \frac{\partial u_y}{\partial z} + \frac{\partial u_z}{\partial x} \frac{\partial u_z}{\partial z} \\ \frac{\partial u_x}{\partial x} \frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial x} \frac{\partial u_z}{\partial y} & \left( \frac{\partial u_x}{\partial y} \right)^2 + \left( \frac{\partial u_y}{\partial y} \right)^2 + \left( \frac{\partial u_z}{\partial y} \right)^2 & \frac{\partial u_x}{\partial y} \frac{\partial u_x}{\partial z} + \frac{\partial u_y}{\partial y} \frac{\partial u_y}{\partial z} + \frac{\partial u_z}{\partial y} \frac{\partial u_z}{\partial z} \\ \frac{\partial u_x}{\partial x} \frac{\partial u_x}{\partial z} + \frac{\partial u_y}{\partial x} \frac{\partial u_y}{\partial z} + \frac{\partial u_z}{\partial x} \frac{\partial u_z}{\partial z} & \frac{\partial u_x}{\partial y} \frac{\partial u_x}{\partial z} + \frac{\partial u_y}{\partial y} \frac{\partial u_y}{\partial z} + \frac{\partial u_z}{\partial y} \frac{\partial u_z}{\partial z} & \left( \frac{\partial u_x}{\partial z} \right)^2 + \left( \frac{\partial u_y}{\partial z} \right)^2 + \left( \frac{\partial u_z}{\partial z} \right)^2 \end{bmatrix}$$

$$e_{xx} = \frac{\partial u_x}{\partial x} + \frac{1}{2} \left[ \left( \frac{\partial u_x}{\partial x} \right)^2 + \left( \frac{\partial u_y}{\partial x} \right)^2 + \left( \frac{\partial u_z}{\partial x} \right)^2 \right], \quad e_{yy} = \frac{\partial u_y}{\partial y} + \frac{1}{2} \left[ \left( \frac{\partial u_x}{\partial y} \right)^2 + \left( \frac{\partial u_y}{\partial y} \right)^2 + \left( \frac{\partial u_z}{\partial y} \right)^2 \right], \quad e_{zz} = \frac{\partial u_z}{\partial z} + \frac{1}{2} \left[ \left( \frac{\partial u_x}{\partial z} \right)^2 + \left( \frac{\partial u_y}{\partial z} \right)^2 + \left( \frac{\partial u_z}{\partial z} \right)^2 \right]$$

$$e_{xy} = \frac{1}{2} \left( \frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y} \right) + \frac{1}{2} \left( \frac{\partial u_x}{\partial x} \frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial x} \frac{\partial u_z}{\partial y} \right), \quad e_{xz} = \frac{1}{2} \left( \frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z} \right) + \frac{1}{2} \left( \frac{\partial u_x}{\partial x} \frac{\partial u_x}{\partial z} + \frac{\partial u_y}{\partial x} \frac{\partial u_y}{\partial z} + \frac{\partial u_z}{\partial x} \frac{\partial u_z}{\partial z} \right)$$

$$e_{yz} = \frac{1}{2} \left( \frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z} \right) + \frac{1}{2} \left( \frac{\partial u_x}{\partial y} \frac{\partial u_x}{\partial z} + \frac{\partial u_y}{\partial y} \frac{\partial u_y}{\partial z} + \frac{\partial u_z}{\partial y} \frac{\partial u_z}{\partial z} \right)$$

Why?

Polar decomposition=> eigenvalue problem 의 연산 어려움.

- Strain transformation.

$$\sum_l \lambda'_{il} = \sum_j \beta_{ij} \sum_k \lambda_{jk} \sum_l \beta_{kl}, \quad \lambda' = \beta \lambda \beta^T \text{ (matrix notation)}$$

$il: \{x'_1 \quad x'_2 \quad x'_3\} \text{system indices}, \quad jk: \{x_1 \quad x_2 \quad x_3\} \text{system indices}$

$$\begin{bmatrix} \lambda'_{11} & \lambda'_{12} & \lambda'_{13} \\ \lambda'_{21} & \lambda'_{22} & \lambda'_{23} \\ \lambda'_{31} & \lambda'_{32} & \lambda'_{33} \end{bmatrix} = \begin{bmatrix} \beta_{11} & \beta_{12} & \beta_{13} \\ \beta_{21} & \beta_{22} & \beta_{23} \\ \beta_{31} & \beta_{32} & \beta_{33} \end{bmatrix} \begin{bmatrix} \lambda_{11} & \lambda_{12} & \lambda_{13} \\ \lambda_{21} & \lambda_{22} & \lambda_{23} \\ \lambda_{31} & \lambda_{32} & \lambda_{33} \end{bmatrix} \begin{bmatrix} \beta_{11} & \beta_{21} & \beta_{31} \\ \beta_{12} & \beta_{22} & \beta_{32} \\ \beta_{13} & \beta_{23} & \beta_{33} \end{bmatrix}$$

예제)

$$\begin{bmatrix} e'_{11} & e'_{12} \\ e'_{21} & e'_{22} \end{bmatrix} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} e_{11} & e_{12} \\ e_{21} & e_{22} \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} e_{11}\cos\theta + e_{12}\sin\theta & -e_{11}\sin\theta + e_{12}\cos\theta \\ e_{21}\cos\theta + e_{22}\sin\theta & -e_{21}\sin\theta + e_{22}\cos\theta \end{bmatrix}$$

$$e'_{11} = e_{11}\cos^2\theta + e_{22}\sin^2\theta + 2e_{12}\sin\theta\cos\theta$$

$$e'_{22} = e_{11}\sin^2\theta + e_{22}\cos^2\theta - 2e_{12}\sin\theta\cos\theta$$

$$e'_{12} = e'_{21} = e_{12}(\cos^2\theta - \sin^2\theta) - e_{11}\sin\theta\cos\theta + e_{22}\sin\theta\cos\theta$$

- Principal strain.

$$\det(\mathbf{e} - \lambda \mathbf{I}) = 0 \Rightarrow \text{Characteristic equation.}$$

- Generalized Hooke's law for linear isotropic elastic solids.

$$e_{11} = \frac{1}{E}(\sigma_{11} - \nu(\sigma_{22} + \sigma_{33}))$$

$$e_{22} = \frac{1}{E}(\sigma_{22} - \nu(\sigma_{11} + \sigma_{33}))$$

$$e_{33} = \frac{1}{E}(\sigma_{33} - \nu(\sigma_{11} + \sigma_{22}))$$

$$\left( E: \text{Young's modulus}, \nu: \text{Poisson's ratio} = \frac{e_{\text{lateral}}}{e_{\text{longitudinal}}} \right)$$

$$e_{12} = \frac{1+\nu}{E}\tau_{12} = \frac{1}{2\mu}\tau_{12} = \frac{1}{2G}\tau_{12} = \frac{\gamma_{12}}{2}$$

$$e_{13} = \frac{1+\nu}{E}\tau_{13}$$

$$e_{23} = \frac{1+\nu}{E}\tau_{23}$$

2D principal stress  $\sigma_{11} = -\sigma_{22}, \sigma_{33} = 0$

$$e_{11} = \frac{1}{E}(\sigma_{11} - \nu(\sigma_{22} + \sigma_{33})) \rightarrow e_{11} = \frac{1 + \nu}{E}\sigma_{11}$$

Maximum shear stress  $\tau_{12} = \sigma_{11}$ , Maximum shear strain  $e_{12} = e_{11}$

$$\therefore e_{12} = \frac{1 + \nu}{E}\tau_{12} = \frac{1}{2G}\tau_{12} \rightarrow G = \mu = \frac{E}{2(1 + \nu)}$$

■ Volumetric strain, bulk modulus, hydrostatic stress.

$$e(\text{volumetric strain}) = (1 + e_{11})(1 + e_{22})(1 + e_{33}) - 1$$

$$= e_{11} + e_{22} + e_{33} + e_{11}e_{22} + e_{11}e_{33} + e_{22}e_{33} + e_{11}e_{22}e_{33} \cong e_{11} + e_{22} + e_{33}$$

$$= \frac{1}{E}(\sigma_{11} + \sigma_{22} + \sigma_{33} - 2\nu(\sigma_{11} + \sigma_{22} + \sigma_{33})) = \frac{1 - 2\nu}{E}(\sigma_{11} + \sigma_{22} + \sigma_{33})$$

$$k(\text{bulk modulus}) = \frac{\sigma_{hyd}}{e} = \frac{\left(\frac{\sigma_{11} + \sigma_{22} + \sigma_{33}}{3}\right)}{e} = \frac{E}{3(1 - 2\nu)}$$

■ Lamé's constant ( $\lambda$ ).

$$\sigma_{11} = \lambda(e_{11} + e_{22} + e_{33}) + 2\mu e_{11}$$

$$= \frac{\lambda(1 - 2\nu)}{E}(\sigma_{11} + \sigma_{22} + \sigma_{33}) + \frac{2\mu}{E}(\sigma_{11} + \nu\sigma_{11} - \nu(\sigma_{11} + \sigma_{22} + \sigma_{33}))$$

$$= \frac{2\mu(1 + \nu)}{E}\sigma_{11} + \frac{\lambda(1 - 2\nu) - 2\mu\nu}{E}(\sigma_{11} + \sigma_{22} + \sigma_{33})$$

$$\frac{2\mu(1 + \nu)}{E} = 1 \rightarrow \lambda(1 - 2\nu) - 2\mu\nu = 0 \rightarrow \nu = \frac{\lambda}{2(\lambda + \mu)}$$

$$\nu = \frac{E}{2\mu} - 1 \rightarrow E = \frac{\mu(3\lambda + 2\mu)}{(\lambda + \mu)}$$

■ Equilibrium equation.

운동량 보존:  $\int_S \mathbf{n} \cdot \mathbf{T} dS + \int_V \rho \mathbf{g} dV = 0 \rightarrow \nabla \cdot \mathbf{T} + \mathbf{F} = 0$  (divergence theorem)

● Stress formulation.

$$\nabla \cdot \mathbf{T} = \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} \sigma_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \sigma_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \sigma_{33} \end{bmatrix} = \begin{bmatrix} \frac{\partial \sigma_{11}}{\partial x} + \frac{\partial \tau_{21}}{\partial y} + \frac{\partial \tau_{31}}{\partial z} \\ \frac{\partial \tau_{12}}{\partial x} + \frac{\partial \sigma_{22}}{\partial y} + \frac{\partial \tau_{32}}{\partial z} \\ \frac{\partial \tau_{13}}{\partial x} + \frac{\partial \tau_{23}}{\partial y} + \frac{\partial \sigma_{33}}{\partial z} \end{bmatrix}^T$$

$$\frac{\partial \sigma_{11}}{\partial x} + \frac{\partial \tau_{21}}{\partial y} + \frac{\partial \tau_{31}}{\partial z} + F_x = 0$$

$$\frac{\partial \tau_{12}}{\partial x} + \frac{\partial \sigma_{22}}{\partial y} + \frac{\partial \tau_{32}}{\partial z} + F_y = 0$$

$$\frac{\partial \tau_{13}}{\partial x} + \frac{\partial \tau_{23}}{\partial y} + \frac{\partial \sigma_{33}}{\partial z} + F_z = 0$$

● Displacement formulation.

$$(\lambda + \mu) \nabla (\nabla \cdot \mathbf{u}) + \mu \nabla^2 \mathbf{u} + \mathbf{F} = 0$$

$$e_{ij} = \frac{1}{2} (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) = \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y}}{2} & \frac{\frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z}}{2} \\ \frac{\frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y}}{2} & \frac{\partial u_y}{\partial y} & \frac{\frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z}}{2} \\ \frac{\frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z}}{2} & \frac{\frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z}}{2} & \frac{\partial u_z}{\partial z} \end{bmatrix} = \begin{bmatrix} \epsilon_x & \frac{\gamma_{xy}}{2} & \frac{\gamma_{xz}}{2} \\ \frac{\gamma_{xy}}{2} & \epsilon_y & \frac{\gamma_{yz}}{2} \\ \frac{\gamma_{xz}}{2} & \frac{\gamma_{yz}}{2} & \epsilon_z \end{bmatrix}$$

$$\mathbf{T} = \lambda (\nabla \cdot \mathbf{u}) \mathbf{I} + \mu [\nabla \mathbf{u} + (\nabla \mathbf{u})^T]$$

$$= \begin{bmatrix} \lambda \left( \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + 2\mu \frac{\partial u_x}{\partial x} & \mu \left( \frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y} \right) & \mu \left( \frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z} \right) \\ \mu \left( \frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y} \right) & \lambda \left( \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + 2\mu \frac{\partial u_y}{\partial y} & \mu \left( \frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z} \right) \\ \mu \left( \frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z} \right) & \mu \left( \frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z} \right) & \lambda \left( \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + 2\mu \frac{\partial u_z}{\partial z} \end{bmatrix}$$

$$\nabla \cdot \mathbf{T} = (\lambda + \mu)\nabla(\nabla \cdot \mathbf{u}) + \mu\nabla^2 \mathbf{u}$$

$$\begin{aligned} \nabla \cdot (\nabla \cdot \mathbf{u})\mathbf{I} &= \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}\right) & 0 & 0 \\ 0 & \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}\right) & 0 \\ 0 & 0 & \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}\right) \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}\right) = \nabla(\nabla \cdot \mathbf{u}) \end{aligned}$$

$$\begin{aligned} \nabla \cdot (\nabla \mathbf{u})^T &= \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_x}{\partial y} & \frac{\partial u_x}{\partial z} \\ \frac{\partial u_y}{\partial x} & \frac{\partial u_y}{\partial y} & \frac{\partial u_y}{\partial z} \\ \frac{\partial u_z}{\partial x} & \frac{\partial u_z}{\partial y} & \frac{\partial u_z}{\partial z} \end{bmatrix} = \begin{bmatrix} \frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_y}{\partial x \partial y} + \frac{\partial^2 u_z}{\partial x \partial z} \\ \frac{\partial^2 u_x}{\partial x \partial y} + \frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_z}{\partial y \partial z} \\ \frac{\partial^2 u_x}{\partial x \partial z} + \frac{\partial^2 u_y}{\partial y \partial z} + \frac{\partial^2 u_z}{\partial z^2} \end{bmatrix}^T \\ &= \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}\right) = \nabla(\nabla \cdot \mathbf{u}) \end{aligned}$$

$$\nabla \cdot \nabla \mathbf{u} = \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_y}{\partial x} & \frac{\partial u_z}{\partial x} \\ \frac{\partial u_x}{\partial y} & \frac{\partial u_y}{\partial y} & \frac{\partial u_z}{\partial y} \\ \frac{\partial u_x}{\partial z} & \frac{\partial u_y}{\partial z} & \frac{\partial u_z}{\partial z} \end{bmatrix} = \begin{bmatrix} \frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} + \frac{\partial^2 u_x}{\partial z^2} \\ \frac{\partial^2 u_y}{\partial x^2} + \frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_y}{\partial z^2} \\ \frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial y^2} + \frac{\partial^2 u_z}{\partial z^2} \end{bmatrix}^T = \nabla^2 \mathbf{u}$$

$$(\lambda + \mu) \frac{\partial}{\partial x} \left( \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + \mu \left( \frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} + \frac{\partial^2 u_x}{\partial z^2} \right) + F_x = 0$$

$$(\lambda + \mu) \frac{\partial}{\partial y} \left( \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + \mu \left( \frac{\partial^2 u_y}{\partial x^2} + \frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_y}{\partial z^2} \right) + F_y = 0$$

$$(\lambda + \mu) \frac{\partial}{\partial z} \left( \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + \mu \left( \frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial y^2} + \frac{\partial^2 u_z}{\partial z^2} \right) + F_z = 0$$