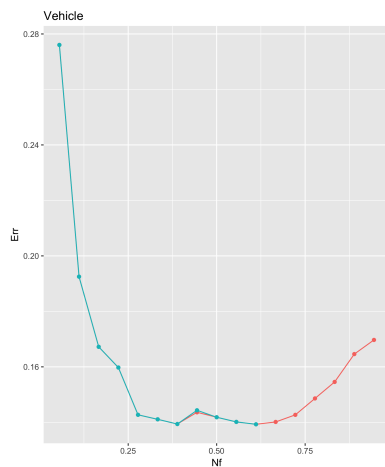
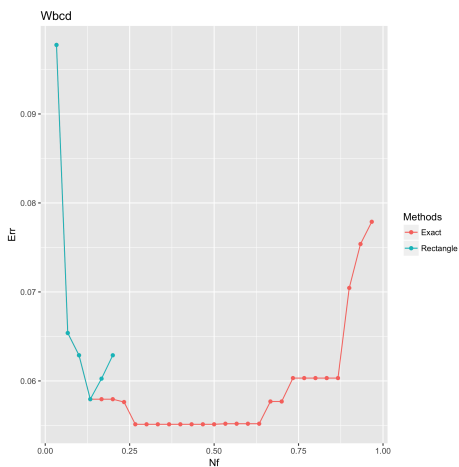


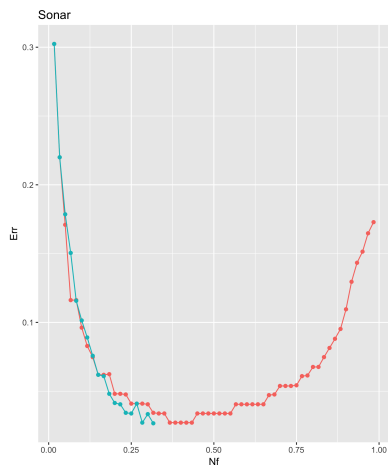
(a) Australian



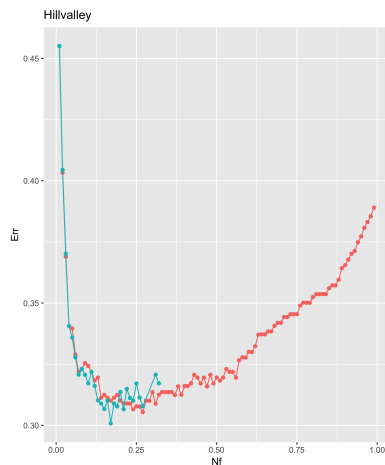
(b) Vehicle



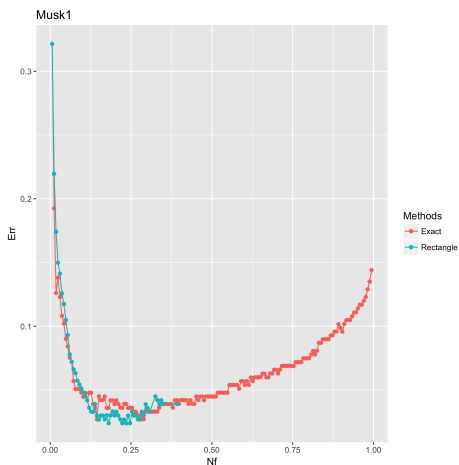
(c) WBCD



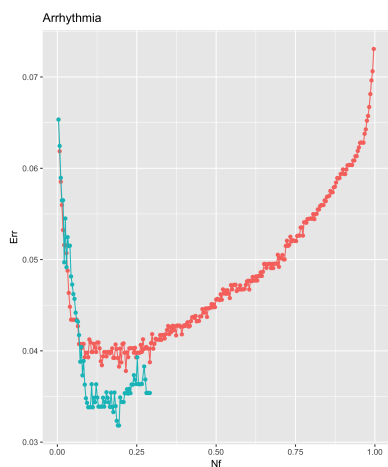
(d) Sonar



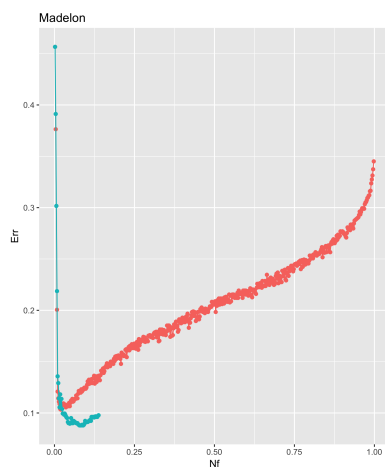
(e) Hillvalley



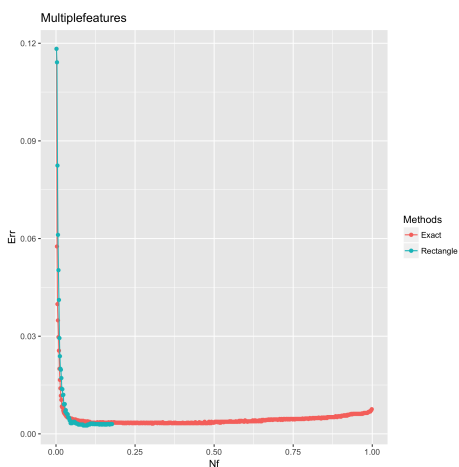
(f) Musk1



(g) Arrhythmia

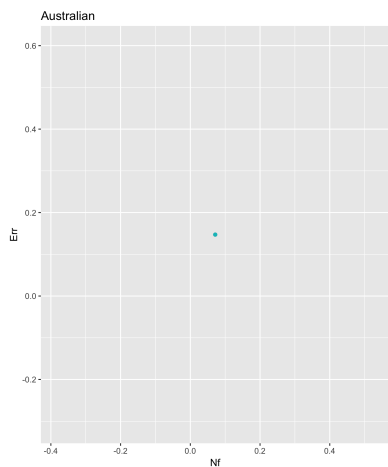


(h) Madelon

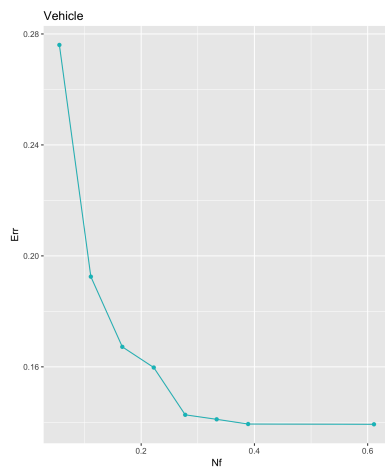


(i) Multiple Features

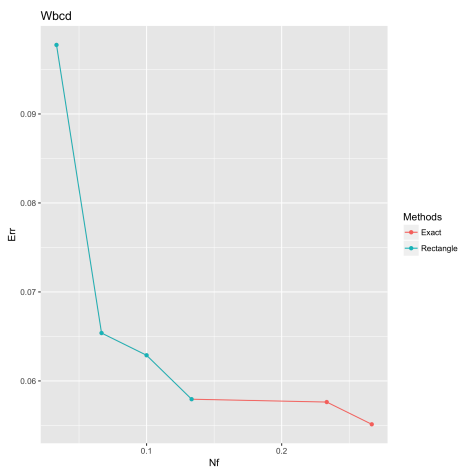
Figure 1: Full



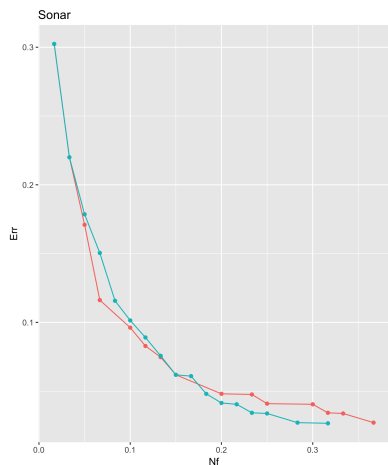
(a) Australian



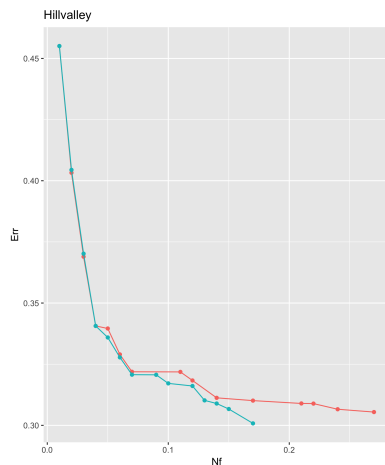
(b) Vehicle



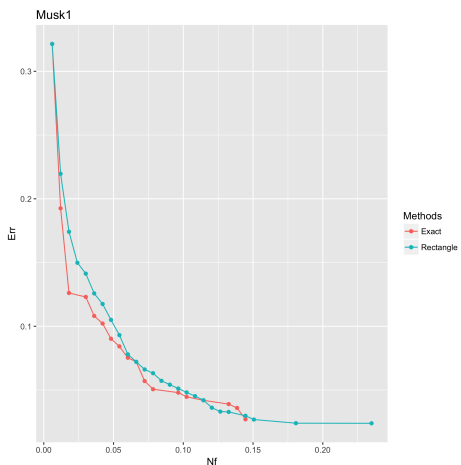
(c) WBCD



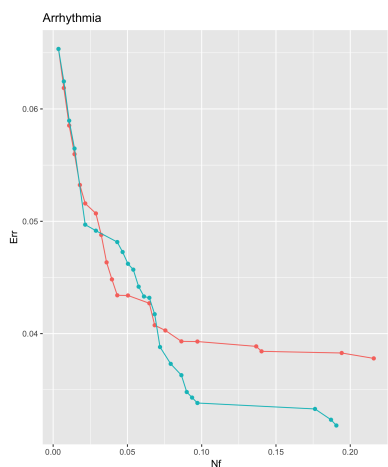
(d) Sonar



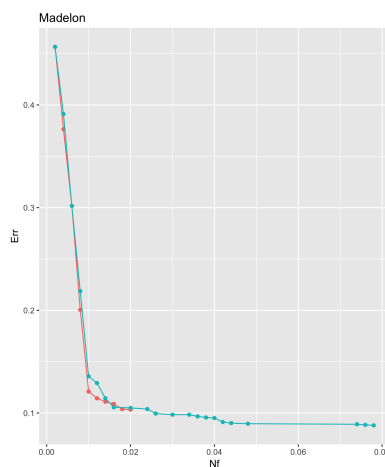
(e) Hillvalley



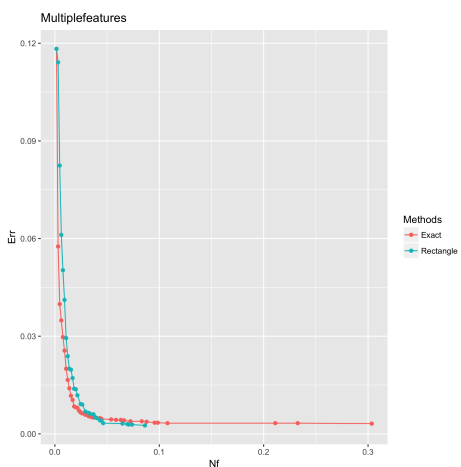
(f) Musk1



(g) Arrhythmia



(h) Madelon



(i) Multiple Features

Figure 2: Non-dominated solutions