## **B-Tree**

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2021



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1. B-tree

2. Basic operations on B-trees

3. Applications

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## Introduction



**Assumption.** So far, search trees were limited to main memory structures  $\rightarrow$  the dataset organized in a search tree fits in main memory (internal memory)

**Problem.** Transaction data of a bank > 1 TB per day  $\rightarrow$  use secondary storage media (HDD, SSD, etc.) (external memory)

Goal. Make a search tree structure secondary-storage-enabled



# File system model



Page. Contiguous block of data (e.g., a file or 4,096-byte chunk).

**Probe.** First access to a page (e.g., from disk to memory).

Property. Time required for a probe is much larger than time to access data within a page.

**Cost.** Number of probes.

Goal. Access data using minimum number of probes.





## Concept 1

A B-tree of order M (M > 2) invented by Rudolf Bayer and Edward M.McCreight is an M-ary tree with the following properties:

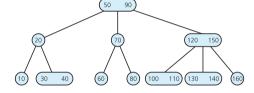
- 1. The root is either a leaf or has between 2 and M children
- 2. All nonleaf nodes (except the root) have between  $\lfloor \frac{M+1}{2} \rfloor$  and M children.
  - minimum degree  $m = \lfloor \frac{M+1}{2} \rfloor$
  - maximum degree M
- **3.** All leaves are at the same depth h.
- 4. All nodes store **keys** to guide the searching.

Indexing

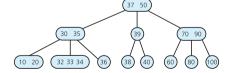
B-tree variants

# B-tree (cont.)

• 2-3 tree



• 2-3-4 tree



### Bas

operations

B-trees Searching

> Creation Single-pass Insert

Insertion
Deletion

Application

Indexing

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Worksho

## The height of a B-tree



### Theorem 1

If  $n \ge 1$ , then for any n-key B-tree T of height h and minimum degree m,

$$h \le \log_m \frac{n+1}{2} \tag{1}$$

**In practice.** Number of probes is at most 4.

**Optimization.** Always keep root page in memory.

### Structure of Node



- 1. Every node x has the following fields:
  - x.n, the number of keys currently stored in node x.
  - the x.n keys themselves,  $x.key_1, x.key_2, ..., x.key_{x,n}$  stored in nondecreasing order, so that

$$x.key_1 \le x.key_2 \le \dots \le x.key_{x.n} \tag{2}$$

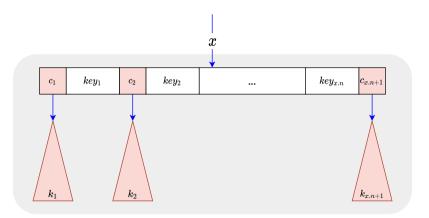
- x.leaf. a boolean value that is true if x is a leaf and false if x is an internal node.
- **2.** Each internal node x also contains x.n+1 pointers  $x.c_1, x.c_2, ..., x_{c_{v,n+1}}$  to its children
- **3.** The keys  $x.key_i$  separate the ranges of keys stored in each subtree: if  $k_i$  is any key stored in the subtree with root  $x.c_i$ , then

$$k_1 \le x. key_1 \le k_2 \le x. key_2 \le \dots \le x. key_{x.n} \le k_{x.n+1}$$
 (3)

Indexing B-tree variants

# **Structure of Node (cont.)**





## **Basic operations on B-trees**

- Searching
- Creation
- Single-pass Insertion
- Insertion
- Deletion

Application Indexing

B-tree varian

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### Introduction



### We adopt two conventions:

- The root of the B-tree is always in main memory, so that a DISK-READ on the root is never required; a DISK-WRITE of the root is required, however, whenever the root node is changed.
- Any nodes that are passed as parameters must already have had a DISK-READ operation performed on them.

### There are two kinds of algorithms:

- "Single pass down" algorithms that proceed downward from the root of the tree, without having to back up (pre-processing)
- "Two-pass" algorithms (post-processing)

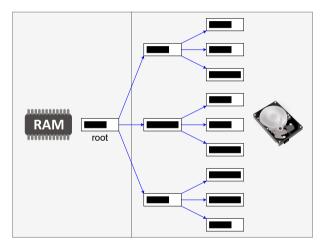
### Basic operations on

**B**-trees

Indexing B-tree variants

# Introduction (cont.)





# Searching

## **Searching a B-tree**



```
B-Tree-Search(x, k)
     if x.leaf return null
     i \leftarrow 1
     while i < x.n and k > x.key_i
          i \leftarrow i + 1
    if i \le x.n and k = x.key_i
          return (x, i)
     else
          DISK-READ(x.c_i)
          return B-Tree-Search(x.c_i, k)
```

• Challenge: Can we make any improvement?

## **Creating an empty B-tree**

Creation

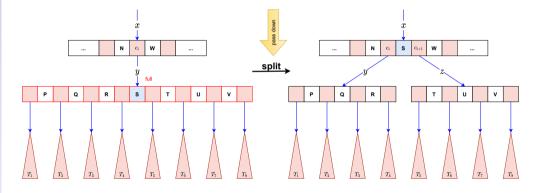
```
B-Tree-Create(T)
     x \leftarrow \text{Allocate-Node()}
      x.leaf \leftarrow true
      x.n \leftarrow 0
```

# Splitting a node in a B-tree

```
B-Tree-Split-Child(x, i)
      z \leftarrow \text{Allocate-Node()}
      v \leftarrow x.ci
      z.leaf \leftarrow v.leaf
      z n \leftarrow m - 1
      for j \leftarrow [1, ..., m-1]
            z.key_i \leftarrow y.key_{i+m}
      if not y.leaf
            for j \leftarrow [1, ..., m]
                  z.c_i \leftarrow y.c_{i+m}
      y.n \leftarrow m-1
      for j \leftarrow [x.n + 1, ..., i + 1]
            x.c_{i+1} \leftarrow x.c_i
      x.c_{i+1} \leftarrow z
      for j \leftarrow [x.n, ..., i]
            x.key_{i+1} \leftarrow x.key_i
      x.kev_i \leftarrow y.kev_m
      x.n \leftarrow x.n + 1
      DISK-WRITE(y)
      DISK-WRITE(z)
      DISK-WRITE(x)
```

# Splitting a node in a B-tree (cont.)

• B-tree(m = 4, M = 8): split



## Inserting a key into a B-tree

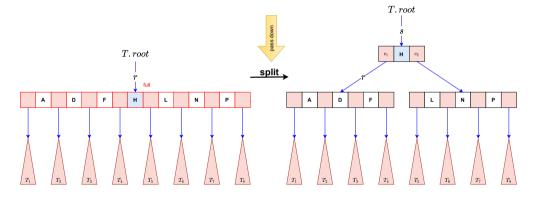


```
B-Tree-Insert(T, k)
     r \leftarrow T.root
     if r.n = 2m - 1
          s \leftarrow \text{Allocate-Node()}
           T.root \leftarrow s
           s.leaf \leftarrow false
          s.n \leftarrow 0
           s.c_1 \leftarrow r
          B-Tree-Split-Child(s, 1)
          B-Tree-Insert-Nonfull(s, k)
     else
          B-Tree-Insert-Nonfull(r, k)
```

Splitting a node in a B-tree (cont.)



• B-tree(m = 4, M = 8): split at root



## Inserting a key into a B-tree



```
B-Tree-Insert-Nonfull(x, k)
     i \leftarrow x.n
     if x leaf
          while i \ge 1 and k < x.key_i
                x.kev_{i+1} \leftarrow x.kev_i
                i \leftarrow i - 1
          x.key_{i+1} \leftarrow k
          x.n \leftarrow x.n + 1
          DISK-WRITE(x)
     else
          while i \ge 1 and k < x.key_i
                i \leftarrow i - 1
          i \leftarrow i + 1
          DISK-READ(x.c_i)
          if x.c_i.n = 2m - 1
                B-Tree-Split-Child(x, i)
                if k > x.key_i
                     i \leftarrow i + 1
          B-Tree-Insert-Nonfull(x.c_i, k)
```

## **Example of Insertion**

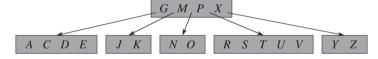


Single-pass Insertion

B-tree variants

Consider B-tree(m = 3, M = 6)

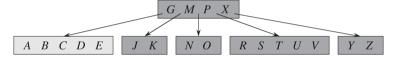
1 Initial tree



## **Example of Insertion (cont.)**

Consider B-tree(m = 3, M = 6)

2 B inserted

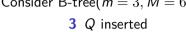


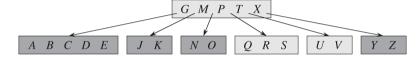


## **Example of Insertion (cont.)**

Single-pass Insertion

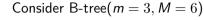
Consider B-tree(m = 3, M = 6)



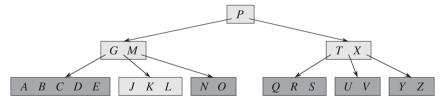


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# **Example of Insertion (cont.)**



4 L inserted

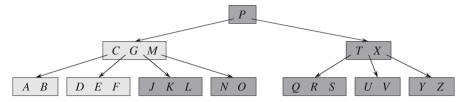




Consider B-tree(m = 3, M = 6)

**5** *F* inserted

**Example of Insertion (cont.)** 



B-tree Basic

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Searching

Single-pass Inse

Insertion

Deletion

Application Indexing

Indexing B-tree variant

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Workshop

## **Bottom-up Insertion**



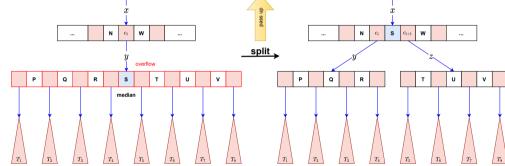
- 1. All insertions start at a leaf node.
- 2. If the node contains more than the maximum allowed number of keys, then the node is overflow:
  - A single median key is chosen from among the node's keys
  - Keys less than the median are put in **the new left node** and keys greater than the median are put in **the new right node**.
  - The median is inserted in **the node's parent**, which may cause it to be split, and so on. If the node has no parent (i.e., the node was the root), create a new root above this node.

B-tree variants

• B-tree(m = 4, M = 7)

Insertion

**Bottom-up Insertion (cont.)** 

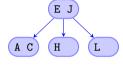


B-tree variants

## **Example of Insertion**



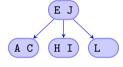
Consider B-tree(m = 2, M = 3) 1 Initial tree



Insertion

## **Example of Insertion (cont.)**

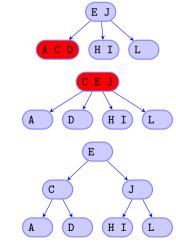
Consider B-tree(m = 2, M = 3) 2 I inserted



Insertion

**Example of Insertion (cont.)** 

Consider B-tree(m = 2, M = 3) 3 D inserted



### **Deletion**



### Deletion from a leaf node

- Delete it from the node.
- If underflow happens, rebalance the tree.

Deletion from an internal node: Each key in an internal node acts as a separation value for two subtrees

• Choose a new separator (either the largest key in the left subtree or the smallest key in the right subtree), remove it from the leaf node it is in, and replace the **key** to be deleted with the new separator.

# **Deletion** (cont.)



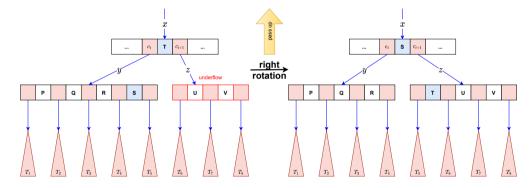
### Rebalancing after deletion

- 1. If the deficient node's right sibling exists and has more than the minimum number of elements, then rotate left
- 2. Otherwise, if the deficient node's left sibling exists and has more than the minimum number of elements, then rotate right
- 3. Otherwise, if both immediate siblings have only the minimum number of elements, then merge with a sibling sandwiching their separator taken off from their parent.

B-tree variants

# **Right rotation**

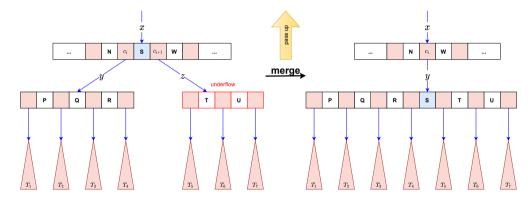
• B-tree(m = 4, M = 7)



B-tree variants

# Merge

• B-tree(m = 4, M = 7)



B-tree variants

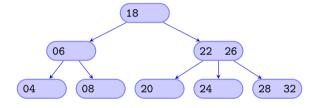
# **Example of Deletion**





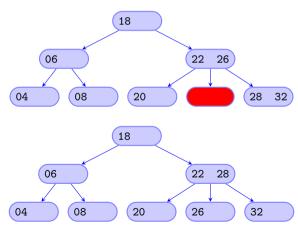
Consider B-tree(
$$m = 2, M = 3$$
)

1 Initial tree



# **Example of Deletion (cont.)**

Consider B-tree(m = 2, M = 3) 2 24 deleted

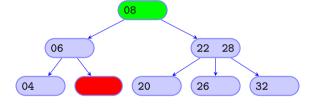


# **Example of Deletion (cont.)**



Consider B-tree(
$$m = 2, M = 3$$
)

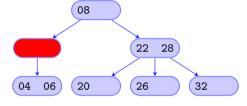
3 18 deleted



# **Example of Deletion (cont.)**



Consider B-tree(
$$m = 2, M = 3$$
)
3 18 deleted ...

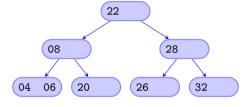


# **Example of Deletion (cont.)**



Consider B-tree(
$$m = 2, M = 3$$
)

**3** 18 deleted ...



# **Applications**

- Indexing
- B-tree variants



Indexing

# Indexing



### Concept 2

**Indexing** is a data structure technique to efficiently retrieve records from the database files based on some attributes on which the indexing has been done.

### Indexing can be

Primary Index: primary key

Secondary Index: candidate key

Clustering Index: non-key

DepartmentName	BudgetCode	OfficeNumber	Phone
Administration	BC-100-10	BLDG01-300	360-285-8100
Legal	BC-200-10	BLDG01-200	360-285-8200
Accounting	BC-300-10	BLDG01-100	360-285-8300
Finance	BC-400-10	BLDG01-140	360-285-8400
Human Resources	BC-500-10	BLDG01-180	360-285-8500
Production	BC-600-10	BLDG02-100	360-287-8600
Marketing	BC-700-10	BLDG02-200	360-287-8700
InfoSystems	BC-800-10	BLDG02-270	360-287-8800

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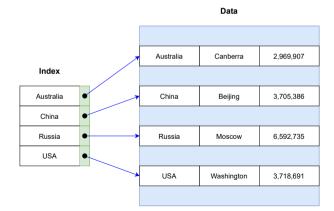
Applications

Indexing

### **Dense Index**



 In dense index, there is an index record for every search key value in the database. This makes searching faster but requires more space to store index records itself. Index records contain search key value and a pointer to the actual record on the disk



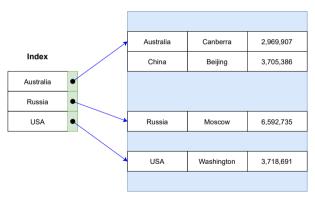
Indexing

# **Sparse Index**



• In sparse index, index records are not created for every search key.

### Data



Basic

operations o
B-trees

Searching Creation

Single-pass Ins

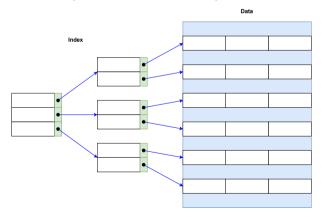
Applications

Indexing

## **Multilevel Index**



 Multi-level Index helps in breaking down the index into several smaller indices in order to make the top level so small that it can be saved in a single disk block, which can easily be accommodated anywhere in the main memory.



### **B-tree variants**



## Concept 3

B+ tree is a B-tree

- Copies of the keys are stored in the internal nodes.
- The keys and records are stored in leaves.
- In addition, a leaf node may include a pointer to the next leaf node to speed sequential access.

### Concept 4

 $B^*$  tree is a B-tree that ensures non-root nodes are at least 2/3 full instead of 1/2.

# Searching a B+ Tree



Table people

ID	name	age
1	Peter	20
2	Mary	30
3	John	25

Queries

SELECT name FROM people

WHERE age = 25

SELECT name FROM people WHERE 20<=age AND age<=30

### Exact key values:

- Start at the root
- Proceed down, to the leaf

### Range queries:

- As above
- Then sequential traversal

# **Applications**



B-trees (and variants) are widely used for file systems and databases.

- Windows: NTFS.
- Mac: HFS. HFS+.
- Linux: ReiserFS, XFS, Ext3FS, JFS.
- Databases: ORACLE, DB2, INGRES, SQL, PostgreSQL.

# Workshop





1. What is a B-tree?





Indexing

B-tree variants

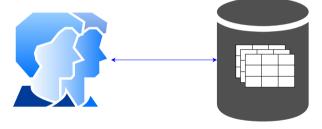
### Workshop

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Workshop

**Projects** 

1. (Big project) Design and implement a tiny relational database project using B+ tree.



### References



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