

Convolutional Neural network

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Outline

- ❑ Convolutional neural network
- ❑ Practice with Google Colab

Problems in computer vision

Classification



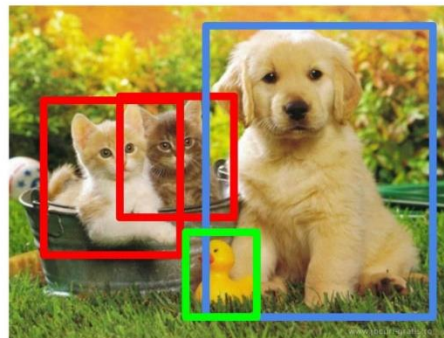
CAT

**Classification
+ Localization**



CAT

Object Detection



CAT, DOG, DUCK

**Instance
Segmentation**



CAT, DOG, DUCK

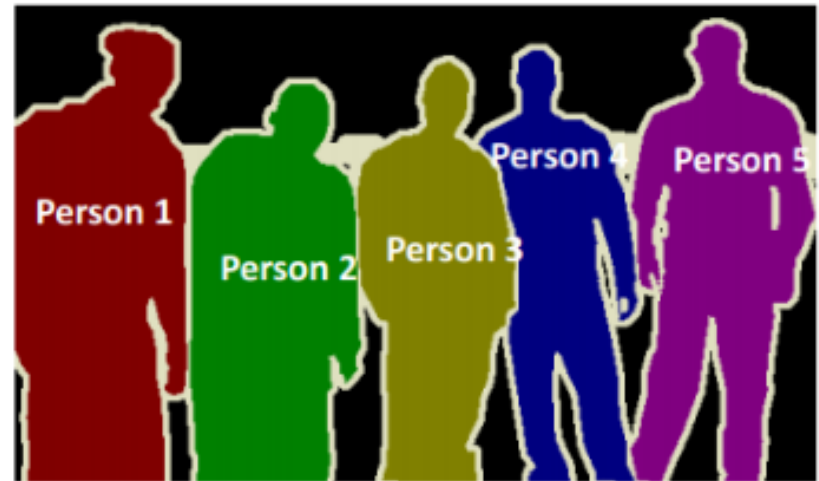
Single object

Multiple objects

Image segmentation



Semantic Segmentation



Instance Segmentation

Segmentation techniques

- ❑ The pixel values will be different for the objects and the image's background → **Threshold Segmentation**
- ❑ **Edge Detection Segmentation** - There is always an edge between two adjacent regions with different grayscale values.
- ❑ **Image Segmentation based on Clustering**

Convolutional neural network

- ❑ High resolution images contains $O(\text{millions})$ of pixels
- ❑ A neural network which can handle that kind of images would also have $O(\text{millions})$ of weight



Convolutional filter

Convolutional neural network

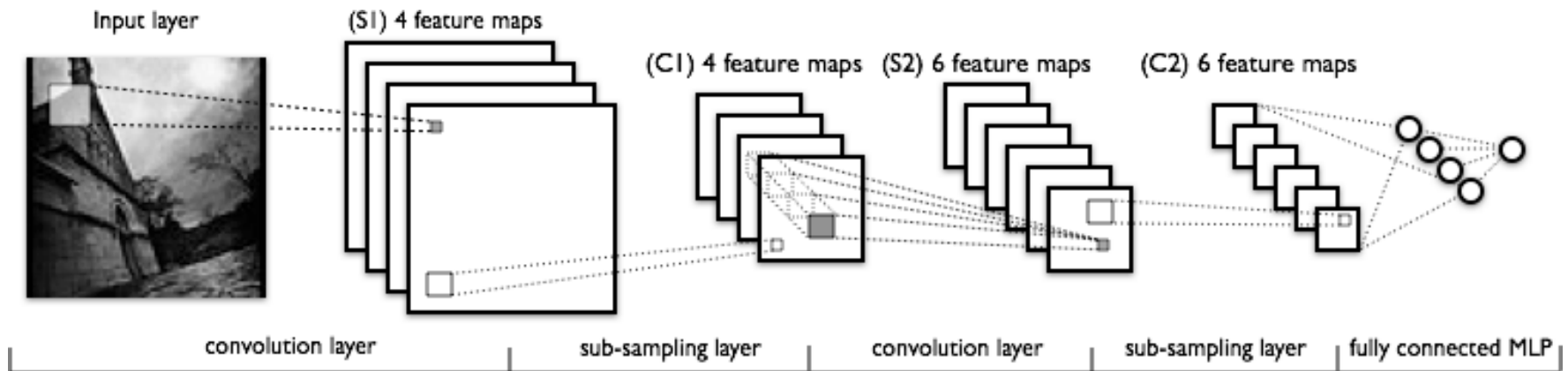


Illustration: Theano documentation

This kind of architecture will learn filters and build an internal representation of the input data using many stacked layers and finally use this representation on a classification task.

Convolutional neural network

□ Filters

| | | | | |
|-----------------|-----------------|-----------------|---|---|
| 1 _{x1} | 1 _{x0} | 1 _{x1} | 0 | 0 |
| 0 _{x0} | 1 _{x1} | 1 _{x0} | 1 | 0 |
| 0 _{x1} | 0 _{x0} | 1 _{x1} | 1 | 1 |
| 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 |

Image

| | | |
|---|--|--|
| 4 | | |
| | | |
| | | |

Convolved
Feature

Convolutional neural network

□ Filters

| | | | | |
|-----------------|-----------------|-----------------|---|---|
| 1 _{x1} | 1 _{x0} | 1 _{x1} | 0 | 0 |
| 0 _{x0} | 1 _{x1} | 1 _{x0} | 1 | 0 |
| 0 _{x1} | 0 _{x0} | 1 _{x1} | 1 | 1 |
| 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 |

Image

| | | |
|---|--|--|
| 4 | | |
| | | |
| | | |

Convolved
Feature

Convolutional neural network

□ Pooling (Ma trận con)

| | | |
|-----|-----|-----|
| 3.0 | 3.0 | 3.0 |
| 3.0 | 3.0 | 3.0 |
| 3.0 | 2.0 | 3.0 |

| | | | | |
|---|---|---|---|---|
| 3 | 3 | 2 | 1 | 0 |
| 0 | 0 | 1 | 3 | 1 |
| 3 | 1 | 2 | 2 | 3 |
| 2 | 0 | 0 | 2 | 2 |
| 2 | 0 | 0 | 0 | 1 |

Convolutional neural network

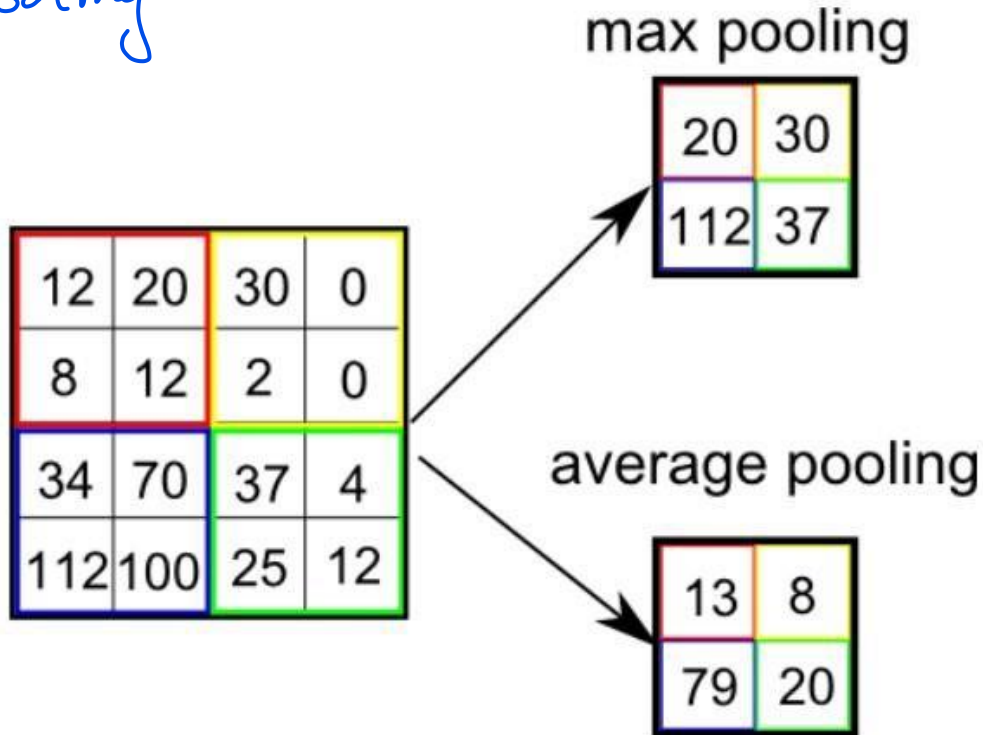
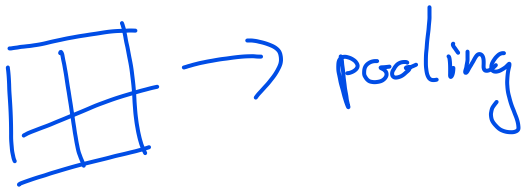
□ Pooling

| | | |
|-----|-----|-----|
| 3.0 | 3.0 | 3.0 |
| 3.0 | 3.0 | 3.0 |
| 3.0 | 2.0 | 3.0 |

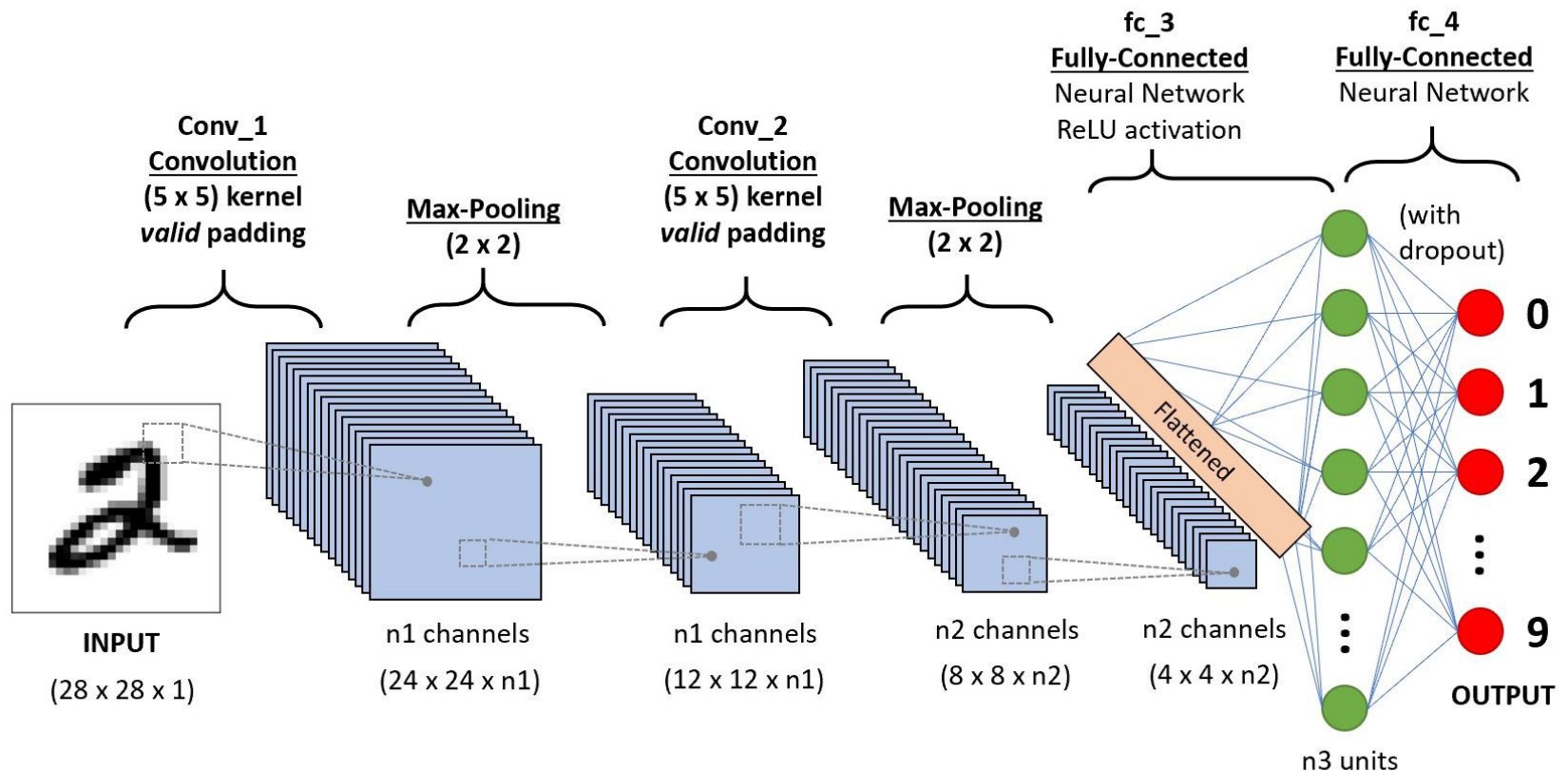
| | | | | |
|---|---|---|---|---|
| 3 | 3 | 2 | 1 | 0 |
| 0 | 0 | 1 | 3 | 1 |
| 3 | 1 | 2 | 2 | 3 |
| 2 | 0 | 0 | 2 | 2 |
| 2 | 0 | 0 | 0 | 1 |

Convolutional neural network

□ Max pooling vs Average pooling



Convolutional neural network

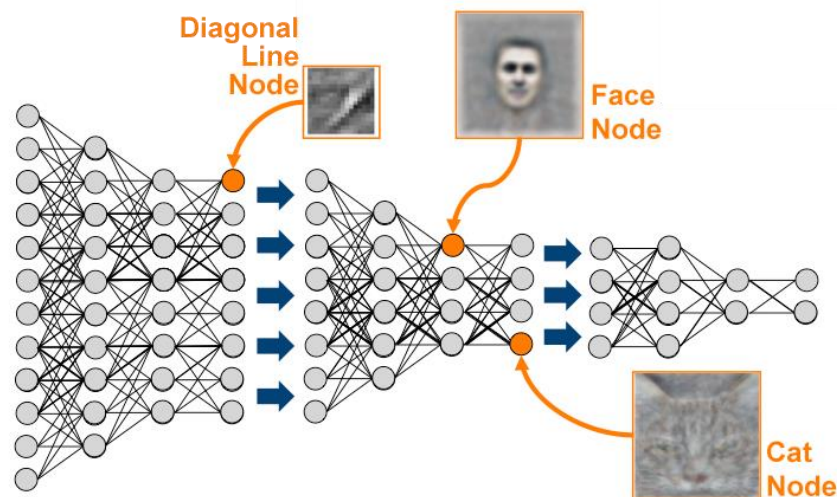


Learn high level features of a cat



“Best neuron” activation heat map

- ❑ Training: 16.000 CPU during 3 days
- ❑ Learned high levels features of cats, human faces by watching Youtube videos
- ❑ Totally unsupervised : unlabeled data



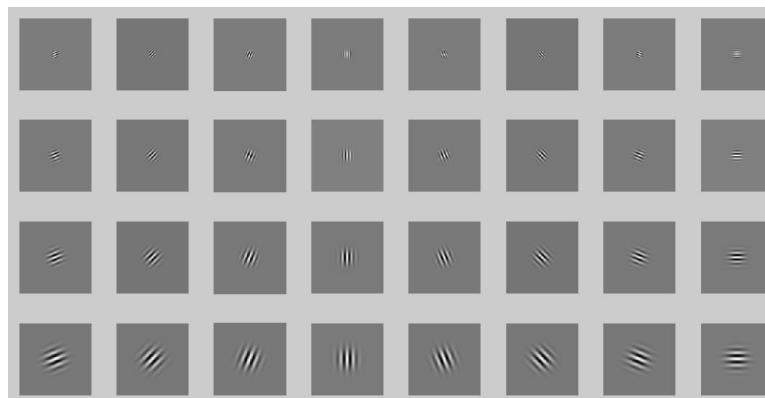
High level feature learning



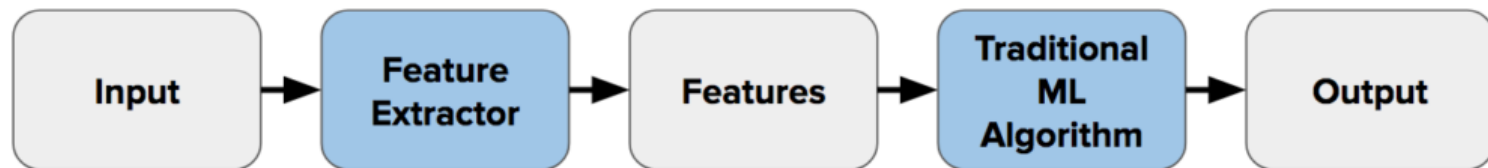
Figure 3: 96 convolutional kernels of size $11 \times 11 \times 3$ learned by the first convolutional layer on the $224 \times 224 \times 3$ input images. The top 48 kernels were learned on GPU 1 while the bottom 48 kernels were learned on GPU 2. See Section 6.1 for details.

The model learns some edge detection filter. We find a similar process in the cells of the primary visual cortex of the human brain

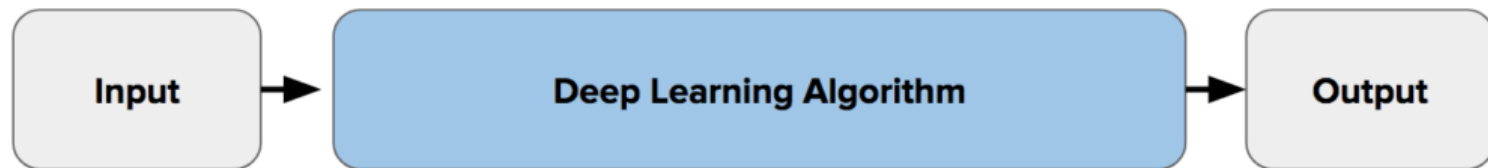
Edge detectors filters :



Traditional ML vs Deep learning



Traditional Machine Learning Flow



Deep Learning Flow

Practice with Google Colab

<https://colab.research.google.com/drive/1UA-wUXx2QziKgZXTDLVo1gn0xImIwj2H>

Model evaluation

- ❑ Measurements
 - Precision, recall
 - Accuracy
 - F1-score
- ❑ Depending on problems, we need some suitable measures

Model evaluation

predict

| | | |
|---|----|----|
| | P | N |
| P | TP | FP |
| N | FN | TN |

$$\square \text{ Precision} = \frac{\text{True positive}}{\text{Predicted positive}}$$

$$= \frac{TP}{TP + FP}$$

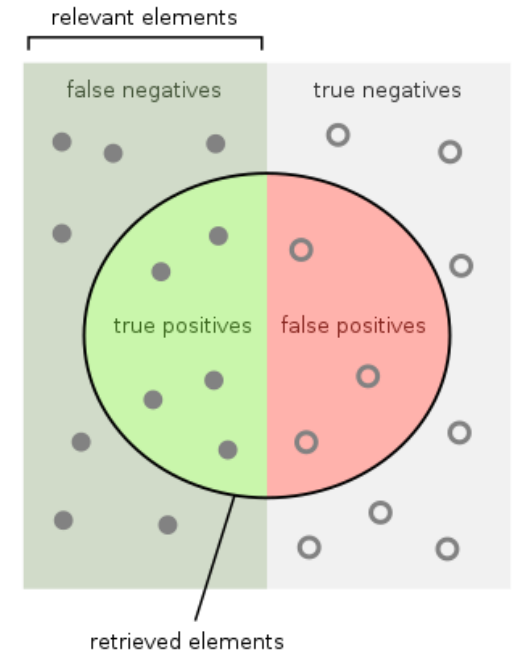
$$\square \text{ Recall} = \frac{\text{True positive}}{\text{Positive}}$$

$$= \frac{TP}{TP + FN}$$

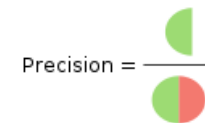
$$\square \text{ F1 - score} = \frac{2 \times \text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}$$

$$\square \text{ Accuracy} = \frac{\text{True positive} + \text{True negative}}{\text{Positive} + \text{Negative}}$$

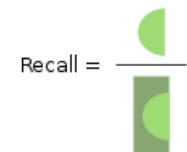
$$= \frac{TP + TN}{TP + FN + TP + TN}$$



How many retrieved items are relevant?



How many relevant items are retrieved?



Source: Wikipedia

Confusion matrix

| | | Predicted | | | | Total |
|--------|-------|-----------|-----|-------|------|-------|
| | | Cat | Dog | Tiger | Wolf | |
| Actual | Cat | 6 | 0 | 3 | 1 | 10 |
| | Dog | 2 | 4 | 0 | 4 | 10 |
| | Tiger | 3 | 3 | 3 | 0 | 9 |
| | Wolf | 1 | 4 | 1 | 2 | 8 |
| Total | | 12 | 11 | 7 | 7 | |

```
>>> sklearn.metrics.classification_report
```

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| Cat | 0.500 | 0.600 | 0.545 | 10 |
| Dog | 0.364 | 0.400 | 0.381 | 10 |
| Tiger | 0.429 | 0.333 | 0.375 | 9 |
| Wolf | 0.286 | 0.250 | 0.267 | 8 |
| accuracy | | | 0.405 | 37 |
| macro avg | 0.394 | 0.396 | 0.392 | 37 |
| weighted avg | 0.399 | 0.405 | 0.399 | 37 |

```
>>> y_true = [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, ...]
>>> y_pred = [0, 0, 0, 0, 0, 0, 2, 2, 2, 3, ...]
>>> target_names = ['Cat', 'Dog', 'Tiger', 'Wolf']
```

Thank you for your attention
