

1. direct communication	<p>processes must call each other clearly EX: send (P, message) - send a message to process P recieve(Q, message) - receive a message from process Q</p> <p>each pair has one link! link made automatically! hard coded - which can be undesirable :(</p>	12. remote procedure calls	...
2. indirect communication	<p>messages are directed and received from MAILBOXES. each mailbox has an id, processes can communicate only if they SHARE a mailbox . send(A, message) - send a message to mailbox A</p> <p>each pair can have multiple links!</p>	13. sockets	...
3. IPC system - Mach	<p>communications are messaged based! Each task gets two mailboxes (kernel and notify),</p> <p>send() recieve() rpc (remote procedure call) allocate()</p>	14. synchronization	<p>1) blocking or 2)non-blocking</p> <p>1) synchronous: (dependent) (send) cant send until message received (recieve) cant recieve until message available</p> <p>2)asynchronous (FREEEEEEEE) (send) sender sends (receive)reciver recieves</p>
4. IPC system - Windows	...		
5. local calls	...		
6. message passing	<p>way for processes to communicate and synchronize their actions.</p> <p>1. send(message) 2. receive(message) there needs to be a link between 1 and 2 (communication link)...links can be complicated to implement (slide 3) Links: direct or indirect synchronus or asynchronus automatic or explicit buffering</p> <p>message size: fixed or variable</p>		
7. message system	processes communicate without using shared variables		
8. named pipes	...		
9. ordinary pipes	...		
10. POSIX	Portable Operating System Interface for Unix		
11. producer and consumer	cant fill last spot, producer puts stuff in buffer and consumer gets stuff from buffer.		