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| 1. <b>4 Conditions for deadlock</b>                  | Mutual Exclusion, Hold and wait, No preemption, Circular wait                                                                                                                                                                                                                                                                                                                                                                            | 12. <b>Disadvantages of Allowing Preemption</b>          | When conflict, process releases everything it owns and re-requests it, causing inefficiency. Also will not work if any processes share a priority level as the CPU won't know who to give the desired resource to. |
| 2. <b>Best option for Recovery</b>                   | Combine them all (Trick question :P)                                                                                                                                                                                                                                                                                                                                                                                                     | 13. <b>Disadvantages of Disallowing Hold and Wait</b>    | Inefficient, long waits occur, resources may remain allocated and unused for a long time, processes might not know what they need ahead of time                                                                    |
| 3. <b>Best way to Avoid Deadlock</b>                 | Allow conditions 1-3 and make sure condition 4 can never happen. OS is responsible for checking to make sure deadlock can't happen before granting resource access                                                                                                                                                                                                                                                                       | 14. <b>Disadvantages of Disallowing Mutual Exclusion</b> | Simply infeasible in modern systems                                                                                                                                                                                |
| 4. <b>Circular Wait</b>                              | Yielding to person to right at an intersection (rule of the road)                                                                                                                                                                                                                                                                                                                                                                        | 15. <b>Finding process that can run to completion</b>    | 1. Subtract each row of [C-A] from the available vector.<br>2. Any process whose result row has values $\geq 0$ can run to completion                                                                              |
| 5. <b>Circular wait</b>                              | a chain of processes exists such that each process holds one or more resources needed by the next process in the chain                                                                                                                                                                                                                                                                                                                   | 16. <b>Hold and Wait</b>                                 | a process can hold a resource and enter a wait state                                                                                                                                                               |
| 6. <b>Common detection algorithm</b>                 | Uses same matrix A and vector V. Adds new matrix Q that is how much each process is requesting.<br><br>Initially consider all processes deadlocked, mark processes in A with all zeros (those can't deadlock, they aren't requesting anything)<br><br>Find processes that are not requesting more than available, those are not deadlocked. Add these values to the allocated vector to keep track of what used and move to next process | 17. <b>Indirect Deadlock Prevention</b>                  | Prevents conditions 1-3 (Mutual Exclusion, Hold and Wait, No Preemption).                                                                                                                                          |
| 7. <b>Consumable Resources</b>                       | Resources that are created and destroyed by one or more processes (e.g. producer consumer problem, interrupts, signals, messages, etc.)                                                                                                                                                                                                                                                                                                  | 18. <b>Methods of dealing with Deadlock</b>              | Prevention, Avoidance, Detection, & Recovery                                                                                                                                                                       |
| 8. <b>Deadlock</b>                                   | permanent blocking of a set of processes that either compete for system resources or communicate with each other                                                                                                                                                                                                                                                                                                                         | 19. <b>Mutual Exclusion</b>                              | Only one process may use a resource at a time, other processes must wait                                                                                                                                           |
| 9. <b>Deadlock Detection</b>                         | The OS periodically performs an algorithm that allows it to detect condition 4 (Circular Wait). This can be run every time a resource is requested, but tradeoff is more overhead                                                                                                                                                                                                                                                        | 20. <b>No Preemption</b>                                 | resources can not be forcibly taken from a process                                                                                                                                                                 |
| 10. <b>Direct Deadlock Prevention</b>                | Prevents Condition 4 (Circular Wait)                                                                                                                                                                                                                                                                                                                                                                                                     | 21. <b>Options for Recovery</b>                          | Abort all deadlocked processes.<br><br>Backup deadlocked processes to a previously defined checkpoint, then restart them all<br><br>Start aborting deadlocked processes one by one until one is released           |
| 11. <b>Disadvantage of Process initiation denial</b> | not optimal, not efficient. Assumes all processes will make max resource claims all at once                                                                                                                                                                                                                                                                                                                                              | 22. <b>Process initiation denial</b>                     | (requires all information known ahead of time) Puts resources into 2 matrix, available or allocated. No process is allowed more than it needs and may only take as much as the total available for each resource   |
|                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                          | 23. <b>Process initiation denial</b>                     | Don't start a process if its demands might lead to a deadlock                                                                                                                                                      |

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| 24. <b>Resource allocation denial</b>                             | (aka banker's algorithm) define set of system states that the OS can use to determine what allocations are safe (not result in deadlock)               |
| 25. <b>Resource allocation denial</b>                             | Don't grant a resource to a process if doing so could lead to deadlock.                                                                                |
| 26. <b>Reusable Resources</b>                                     | Used by one process at a time and not depleted by use (e.g. processor, I/O channel, main & secondary memory, files, etc.)                              |
| 27. <b>Safe state</b>                                             | state in which there is at least one sequence of resource allocation to process that does not result in deadlock (all processes can run to completion) |
| 28. <b>Two categories of resources that processes compete for</b> | Reusable and Consumable                                                                                                                                |