

Chapter 5 - Concurrency: Mutual Exclusion and Synchronization

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1. atomic operation	a function or action that cannot be interrupted or preempted while running	15. monitor characteristics	- local data vars are accessible only by the monitor's procedures and not by any external procedure - process enters monitor by invoking one of its procedures - only one process may be executing in the monitor at a time
2. basic requirement for the execution of concurrent processes	the ability to enforce mutual exclusion	16. multiprocessing	the management of multiple processes within a multiprocessor
3. blocking send, blocking receive	both the sender and receiver are blocked until the message is delivered	17. multiprogramming	the management of multiple processes within a uniprocessor system
4. the central themes of OS design	- multiprogramming - multiprocessing - distributed processing	18. mutual exclusion	the requirement that when one process is in a critical section that accesses shared resources, no other process can be as well
5. critical section	a section of code within a process that requires access to shared resources	19. nonblocking send, blocking receive	although the sender may continue on, the receiver is blocked until the requested message arrives (most useful combo)
6. deadlock	a situation in which two or more processes are unable to proceed because each is waiting for one of the others to do something	20. nonblocking send, nonblocking receive	neither party is required to wait
7. direct addressing	send primitive includes a specific identifier of the destination process (using either explicit or implicit addressing)	21. OS Concerns (the OS must...)	- be able to keep track of various processes - allocate and de-allocate resources for each active process - protect the data and physical resources of each process against interference by other processes - ensure that the processes and outputs are independent of the processing speed
8. distributed processing	the management of multiple processes executing on multiple, distributed computer systems	22. overlapping	processes running separately
9. implementation of semaphores	- semWait and semSignal be implemented as atomic primitives - can be implemented in hardware or firmware - software schemes or algorithms can be used	23. producer/consumer (reader/writer) problem	- ensure that the producer can't add data into full buffer and consumer can't remove data from an empty buffer * semaphore is not good for P/C problem, consumer can get ahead, leads to deadlock * - any number of readers may simultaneously read, one writer at a time may write to the file, if a writer is writing, no reader may read it
10. indirect addressing	messages are sent to a shared data structure consisting of queues (mailboxes) that can temporarily hold messages	24. race condition	a situation in which multiple threads or processes read and write a shared data item and the final result depends on the relative timing of their execution (think of class example)
11. interleaving	interleaving instructions from code from different processes		
12. message passing	when processes interact with one another, these requirements must be satisfied: - synchronization to enforce mutual exclusion - communication to exchange information		
13. message passing primitives	- send (destination, message) - receive (source, message)		
14. monitor	a software module consisting of one or more procedures, an initialization sequence, and local data		

25. requirements for mutual exclusion	<ul style="list-style-type: none"> - must be enforced - a process that halts must do so without interfering with others - no deadlock or starvation - a process must not be denied access to a critical section when no other process is using it - no assumptions - remain in critical section for a finite time only
26. resource competition	<p>concurrent processes come into conflict when competing for use of the same resource, three control problems must be faced:</p> <ul style="list-style-type: none"> - need for mutual exclusion - deadlock - starvation
27. semaphore	<p>an integer value used for signaling among processes</p> <ul style="list-style-type: none"> - initialized to a nonnegative int value - semWait operation decrements value (sends processes to blocked queue) - semSignal operation increments value (unblocks processes)
28. starvation	<p>a situation in which a runnable process is overlooked indefinitely by the schedule</p>
29. strong semaphore	<p>includes the removal policy of FIFO, the process that has been blocked the longest is released first from the queue</p>
30. synchronization	<p>(same concept at semaphores) achieved by the use of condition variables that are contained within the monitor and accessible only within the monitor (cWait, cSignal)</p>
31. three contexts in which concurrency arises	<ul style="list-style-type: none"> - multiple applications - structured applications - operating system structure
32. three degrees of awareness between processes	<ul style="list-style-type: none"> - unaware of each other (competition) - indirectly aware of each other (cooperation, may share I/O buffer) - directly aware of each other (cooperation, can communicate by process ID, work together)
33. weak semaphore	<p>a semaphore that does not specify the order in which processes are removed from the queue</p>