



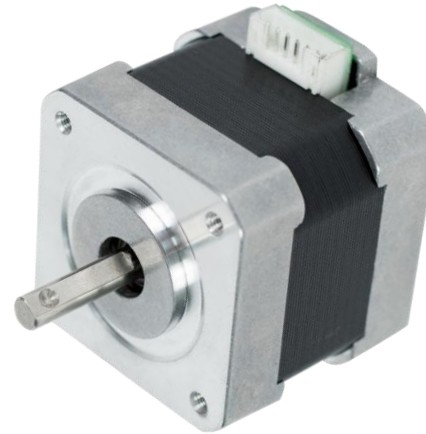
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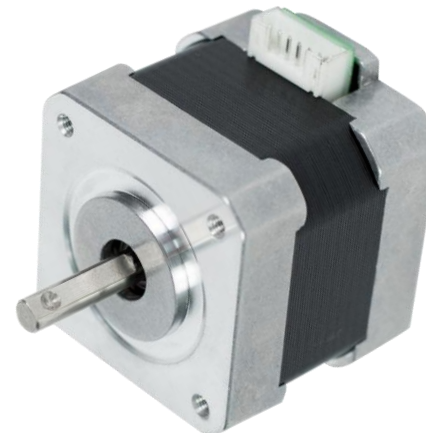
Robô Omnidirecional para estudar ROS

Proposta

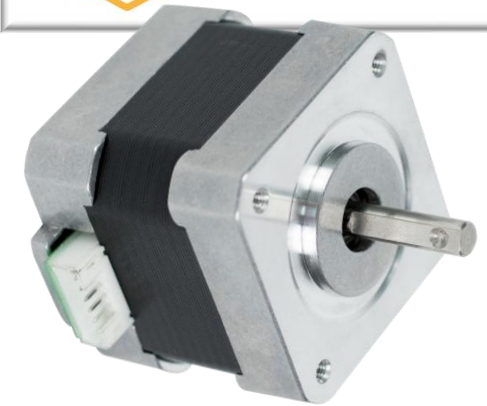
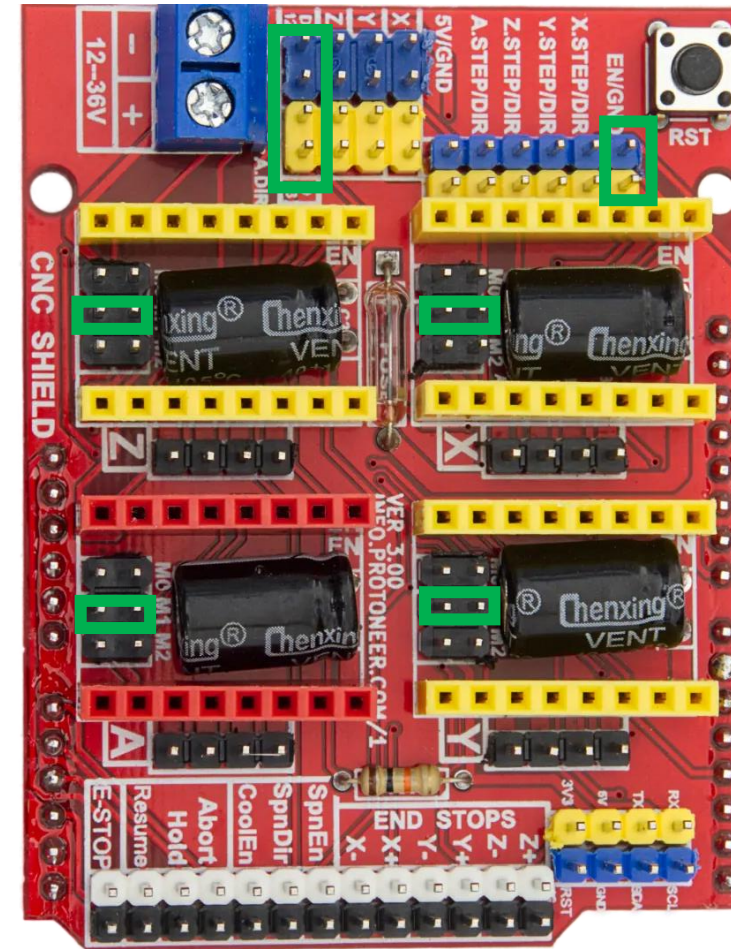
Pinos			Resolução micropassos
MS1	MS2	MS3	
Low	Low	Low	Full step
High	Low	Low	Half step
Low	High	Low	Quarter step (1/4)
High	High	Low	Eighth step (1/8)
High	High	High	Sixteenth step (1/16)



TD
Driver Z



FD
Driver A



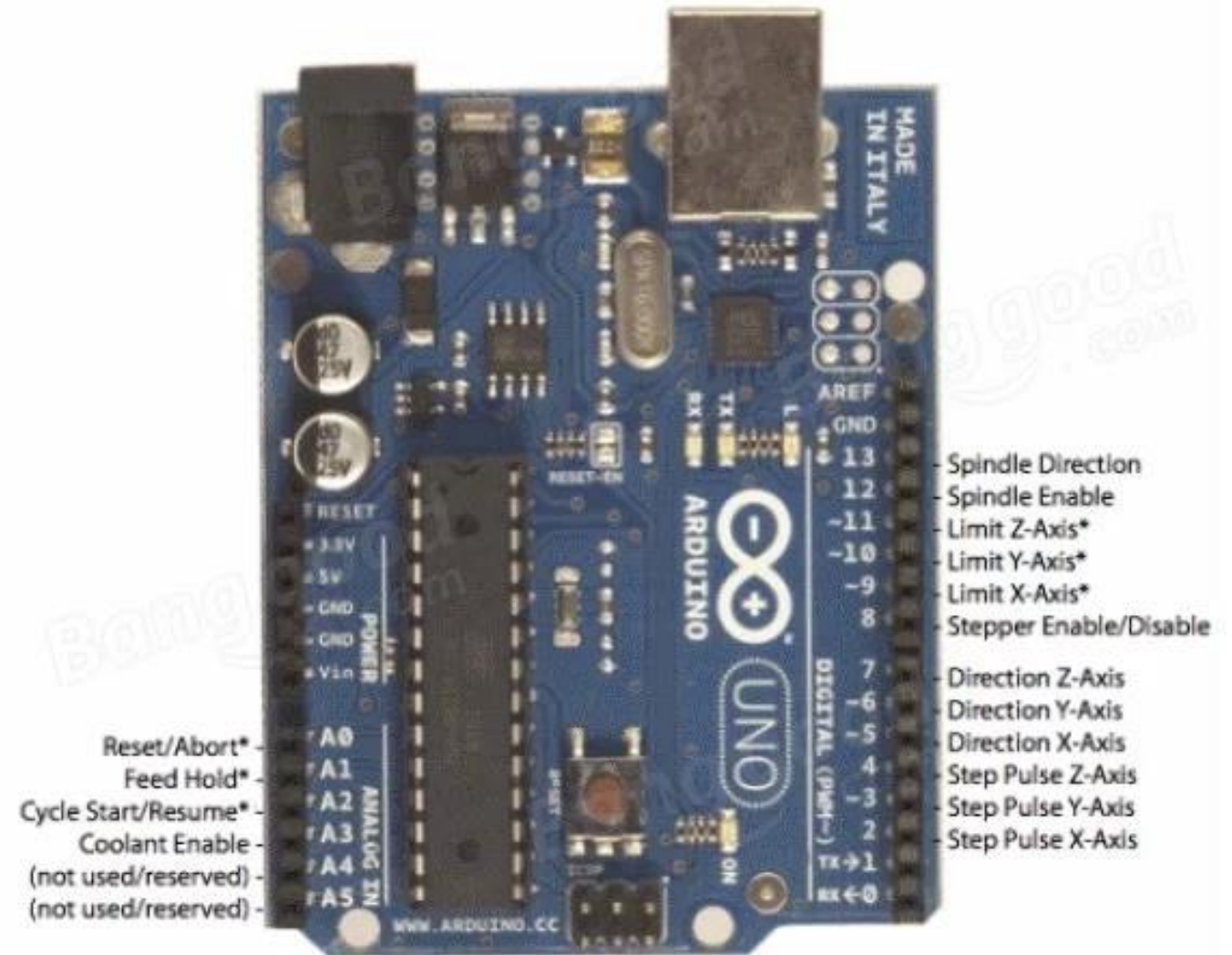
TE
Driver X



FE
Driver Y



- `#include <AccelStepper.h>`
- `#include<ros.h>`
- `#include <geometry_msgs/Twist.h>`



- Próximos vídeos
- Parcerias





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