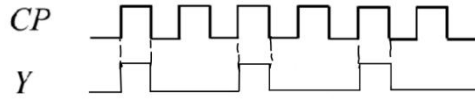


作业 4

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1.



2.

$$(1) Q_0^{n+1} = \overline{Q_0^n}$$

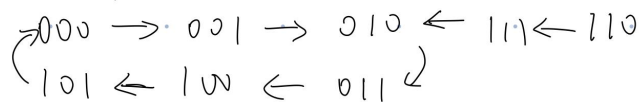
$$\begin{aligned} Q_1^{n+1} &= J_1 \overline{Q_1^n} + \overline{K_1} Q_1^n = Q_0^n \overline{Q_2^n} \overline{Q_1^n} + \overline{Q_0^n \overline{Q_2^n}} Q_1^n \\ &= Q_0^n \overline{Q_2^n} \overline{Q_1^n} + (\overline{Q_0^n} + Q_2^n) Q_1^n \\ &= Q_0^n \overline{Q_2^n} \overline{Q_1^n} + \overline{Q_0^n} Q_1^n + Q_2^n Q_1^n \end{aligned}$$

$$Q_2^{n+1} = J_2 \overline{Q_2^n} + \overline{K_2} Q_2^n = Q_0^n Q_1^n \overline{Q_2^n} + \overline{Q_0^n} Q_2^n$$

状态转换表

现态 $Q_2^n Q_1^n Q_0^n$	次态 $Q_2^{n+1} Q_1^{n+1} Q_0^{n+1}$	时钟 CP
0 0 0	0 0 1	↓
0 0 1	0 1 0	↓
0 1 0	0 1 1	↓
0 1 1	1 0 0	↓
1 0 0	1 0 1	↓
1 0 1	0 0 0	↓
1 1 0	1 1 1	↓
1 1 1	0 1 0	↓

状态转换图



(2) 该电路为一同步模6加法计数器

3.

输入	现态	次态	输出	触发器状态
x	$Y_3 Y_2 Y_1$	$Y_3^+ Y_2^+ Y_1^+$	z	$D_3 D_2 D_1$
0	000	000	0	0 0 0
1	000	001	0	0 0 1
0	001	000	0	0 0 0
1	001	010	0	0 1 0
0	010	000	0	0 0 0
1	010	011	0	0 1 1
0	011	000	0	0 0 0
1	011	100	1	1 0 0
0	100	000	0	0 0 0
1	100	100	1	1 0 0
0	101	xxx	x	xxx
1	101	xxx	x	xxx
0	110	xxx	x	xxx
1	110	xxx	x	xxx
0	111	xxx	x	xxx
1	111	xxx	x	xxx

对于触发器 D_3 :

$x Y_3 \backslash Y_2 Y_1$	00	01	11	10
00	0	0	0	0
01	0	x	x	x
11	1	x	x	x
10	0	0	1	0

$$D_3 = x Y_3 + x Y_2 Y_1$$

对于触发器 D_2 :

$x Y_3 \backslash Y_2 Y_1$	00	01	11	10
00	0	0	0	0
01	0	x	x	x
11	0	x	x	x
10	0	1	0	1

$$D_2 = x \bar{Y}_2 \bar{Y}_1 + x Y_2 \bar{Y}_1$$

$$= x (Y_2 \oplus Y_1)$$

对于触发器 D_1 :

$x Y_3 \backslash Y_2 Y_1$	00	01	11	10
00	0	0	0	0
01	0	x	x	x
11	0	x	x	x
10	1	0	0	1

$$D_1 = x \bar{Y}_3 \bar{Y}_1$$

对于输出 Z:

$x \backslash Y_2 Y_1$	00	01	11	10
00	0	0	0	0
01	0	X	X	X
11	X	X	X	X
10	0	0	0	0

$$Z = xY_3 + xY_2Y_1$$

电路设计如下:

