

Introduce.

a spline-based multilevel approach for effectively analyzing complex data.

developed is estimation procedure combining Expectation-Maximization algorithm & non-param. reg approach.

Key word : Expectation-Maximization

Hurdle model

Nonparametric regression

latent variable.

large-scaled data

linear smoother

smoothing spline.

Using data collected from various sources, however, pose few challenges.

① data structure is often complex.

② traditional assumptions on the sampling process are difficult to justify

③ the volume of data is larger than the data collected by traditional method.

\* In this work

we propose a statistical framework to analyze the data merged from various sources.

The proposed model uses a "multilevel model" under non-param functional structural model assumption.

add modeling layer.

Nonparametric modeling approach provides

a useful extension of parametric models for hierarchical structure, by allowing an additional, flexible smoothness of para.

\* Our aim

to develop a statistical procedure for nonpara modeling approach. on the underlying reg fnc under the multilevel model structure, as well as deriving the theoretical properties of such procedure.

## 2. Model Methodology.

the location and date of each event of a group of musicians are observed over the entire USA for a given time period.

number of event,  $i = 1, \dots, n$

month,  $j = 1, \dots, J$

number of concert events in the  $j$ th month,

$$\mathbf{y}_{\cdot j} = (y_{1j}, \dots, y_{nj})^T$$

with expectation vector

$$\begin{aligned} \boldsymbol{\eta}_{\cdot j} &= (\eta(x_{1j}; \beta_{\cdot j}), \dots, \eta(x_{nj}; \beta_{\cdot j}))^T \\ &= (\eta_{1j}, \dots, \eta_{nj})^T \end{aligned}$$

$\eta$  is known link fnc.

$\beta_{\cdot j} = (\beta_{\cdot j1}, \dots, \beta_{\cdot jp})^T$  is unknown time-varying para to be esti

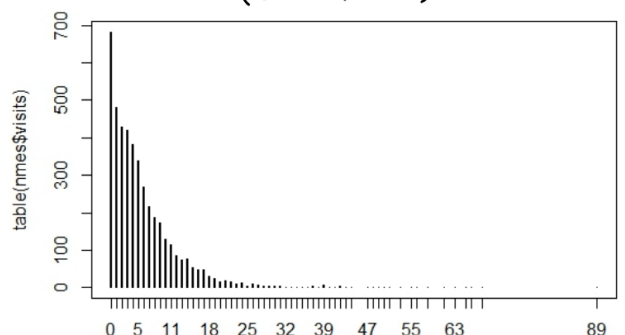
$\mathbf{x}_i = (x_{i1}, \dots, x_{ip})^T$  is CBSA specific regional covariates.

assume

$$y_{i \cdot j} \sim f(y_{i \cdot j}; \mathbf{x}_i, \beta_{\cdot j}) \dots \textcircled{1}$$

where  $f$  is a parametric model (hurdle model)

✓  $y_{i \cdot j}$  값이 0이 아니거나 0인 값만 가지는 데이터 (0 or positive)



The time varying para  $\beta_j$ 's are assume

$$\beta_{jk} = \mu_k(z_j) + \varepsilon_{jk}, \quad k=1, \dots, p$$

$\downarrow p=1$  to 간략하게 한다.

$$\beta_j = \mu(z_j) + \varepsilon_j \quad \dots \textcircled{2}$$

where months are re-scaled to  $z_1, \dots, z_J \in [0, 1]$ ,

?  $\mu(z_j)$  is mean fnc of  $\beta_j$  that belong to a class of smooth fnc with respect to  $z_j$ .

$\varepsilon_j$  is random error  $\sim N(0, \sigma^2)$ ,  $\sigma^2 > 0$

\* main interest.

to investigate how the relationship between

$y_{ij}$  and  $x_i$  changes over time,

$\uparrow \downarrow$

This can be achieved by finding the 2nd level model which capture the temporal change of  $\beta_j$ .

\* The main challenge in this approach

there is no direct measurement of  $\beta_j$

the smoothing splines approach & EM algorithm

## 2.2 Estimation

$\beta_j = \mu(z_j) + \varepsilon_j \Rightarrow$  consider the smoothing spline estimation!

$$\sum_{j=1}^J (\beta_j - \mu(z_j))^2 + \lambda \int_0^1 (\mu'')^2 \quad \dots \textcircled{3}$$

$\mu \in W^{(2,2)}$ , where  $W^{(2,2)} = \{m \in L_2 : \int (m'')^2 < \infty\}$

Sobolev class of twice differentiable fnc

&  $\lambda$  is penalty constant

③ rewritten as

$$\min_{\theta \in \mathbb{R}^J} g(\theta; \beta) = (\beta - N\theta)^T (\beta - N\theta) + \lambda \theta^T W \theta \quad \dots \textcircled{4}$$

where  $\beta = (\beta_1, \dots, \beta_J)$ ,  $\theta = (\theta_1, \dots, \theta_J)$

$$N_{j,j}^T = (N_{i,j}), \quad N_{i,j} = N_i(z_j)$$

$W = (W_{i,j})$ ,  $W_{i,j} = \int N_i'' N_j''$  with natural cubic spline  $N_j$  having  $z_1, \dots, z_J$  knots

Power Basis for space

$$1, \quad x, \quad d_i(x) = d_{n-1}(x), \quad i=1, \dots, k-1$$

$$\text{where } d_i(x) = \frac{(x - X_i)^3 - (x - X_n)^3}{X_n - X_i}$$

$$\boxed{\begin{matrix} \text{matrix} \\ B \end{matrix}}_{n \times k+1} = \begin{pmatrix} 1 & x_1 & d_1(x_1) - d_{k-1}(x_1) & \dots & d_{k-2}(x_1) - d_{k-1}(x_1) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & d_1(x_n) - d_{k-1}(x_n) & \dots & d_{k-2}(x_n) - d_{k-1}(x_n) \end{pmatrix}$$

$$N_{J \times J} = \begin{pmatrix} N_1(z_1) & \dots & N_1(z_J) \\ \vdots & \ddots & \vdots \\ N_J(z_1) & \dots & N_J(z_J) \end{pmatrix} \quad \text{why } J \times J$$

- The joint pdf of  $(X_1, \dots, X_n, \theta)$

$$\begin{aligned} g(X_1, \dots, X_n; \theta) &= \prod_{i=1}^n f(x_i; \theta) h(\theta) \\ &= L(\theta | x) h(\theta) \end{aligned}$$

- Marginal pdf of  $X_1, \dots, X_n$

$$g_X(x) = \int_{\Omega} g(x_1, \dots, x_n; \theta) d\theta$$

- Posterior <sup>Target.</sup> distribution of  $\theta$ .

given  $x_1, \dots, x_n$

$$k(\theta | x) = \frac{g(x_1, \dots, x_n; \theta)}{g_X(x_1, \dots, x_n)}$$

information related to  $\beta_{\bar{j}}$

can be obtained from the obs  $(y_{\bar{j}}, X)$

$y_{\bar{j}} = (y_{1\bar{j}}, \dots, y_{n\bar{j}})$ ,  $\bar{j}$ th month event count.

$X = (x_1, \dots, x_n)$  CBSA specific information.

<Two step>

① obtain  $\hat{\beta} = (\hat{\beta}_1, \dots, \hat{\beta}_J)^T$  by individually fitting the model in  $f(y_{i\bar{j}}; x_{i\bar{j}}, \beta_{\bar{j}})$  for each  $\bar{j}$ ,  $\bar{j} = 1, \dots, J$

\* Since  $\beta$  is not observable,

it is treated as a latent variable, where  $\hat{\beta}$  is treated as an observation for  $\beta = (\beta_1, \dots, \beta_J)^T$

Once all  $\hat{\beta}_1, \dots, \hat{\beta}_J$  are obtained, define  $\mathcal{L}(\hat{\beta}_{\bar{j}} | \beta_{\bar{j}})$

$\Rightarrow$  the prob density of the sampling dist of  $\hat{\beta}_{\bar{j}}$ .

Maximum likelihood is used to obtain  $\hat{\beta}_{\bar{j}}$

$\mathcal{L}(\hat{\beta}_{\bar{j}} | \beta_{\bar{j}})$  can assume  $N(\beta_{\bar{j}}, V_{\bar{j}}^{-1})$

$V_{\bar{j}}^{-1}$  is inverse of Fisher information matrix.

② we estimate  $\theta$  using EM, by minimizing

$$\sum_{\bar{j}=1}^J (\beta_{\bar{j}} - \mu(z_{\bar{j}}))^2 + \lambda \int_0^1 (\mu'')^2$$

with a consideration of the  $\mathcal{L}(\hat{\beta}_{\bar{j}} | \beta_{\bar{j}})$

Specifically, the smoothing spline criterion in

$$\min_{\theta \in \mathbb{R}^J} g(\theta; \beta) = (\beta - N\theta)^T (\beta - N\theta) + \lambda \theta^T W \theta$$

can be viewed as the negative complete

loglikelihood with  $(\beta | \theta, \sigma^2) \sim N(N\theta, \Sigma)$

$$(\theta | \sigma^2) \sim N(0, \sigma^2 \lambda^{-1} W^{-1})$$

where  $\Sigma = \sigma^2 I_J$ .

$$\max_{\theta \in \mathbb{R}^J} \int \mathcal{L}(\hat{\beta} | \beta) \exp(-\frac{g(\theta; \beta)}{2}) d\beta \quad \dots ⑤$$

⑤ 증명 - Line 1  $\rightarrow$  2

$$\hat{\theta} = \arg \min E[(\hat{\beta} - \beta)^T V^{-1} (\hat{\beta} - \beta) + (\beta - N\theta)^T (\beta - N\theta) + \lambda \theta^T W \theta | \hat{\beta}; \hat{\theta}^{(m)}, \sigma] \quad \dots ⑥$$

It is straight-forward to derive (유도하기 쉽다)

$$(\beta | \hat{\beta}; \theta, \sigma) \sim N \left( (V^{-1} + \Sigma^{-1})^{-1} (V^{-1} \hat{\beta} + \Sigma^{-1} N\theta), (V^{-1} + \Sigma^{-1})^{-1} \right) = N(\beta^*, V^*)$$

$$\frac{\partial}{\partial \theta} E[\cdot] = E \left[ \frac{\partial}{\partial \theta} (\beta - N\theta)^T (\beta - N\theta) + \lambda \frac{\partial}{\partial \theta} \theta^T W \theta | \hat{\beta}; \hat{\theta}^{(m)}, \sigma \right] = E[-2N^T \beta + 2N^T N \hat{\theta} + 2\lambda W \hat{\theta} | \hat{\beta}; \hat{\theta}^{(m)}, \sigma] \stackrel{\text{let}}{=} 0$$

$$\begin{aligned} \hat{\theta}^{(m+1)} \cdot (N^T N + \lambda W) &= N^T N \hat{\theta}^{(m+1)} + \lambda W \hat{\theta}^{(m+1)} \\ &= N^T E[\beta | \hat{\beta}; \hat{\theta}^{(m)}, \sigma] = N^T \beta^* \\ &= N^T (V^{-1} + \Sigma^{-1})^{-1} (V^{-1} \hat{\beta} + \Sigma^{-1} N \hat{\theta}^{(m)}) \quad \dots ⑦ \end{aligned}$$

$$\therefore \hat{\theta}^{(m+1)} = (N^T N + \lambda W)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} (V^{-1} \hat{\beta} + \Sigma^{-1} N \hat{\theta}^{(m)})$$

$m \rightarrow \infty, \hat{\theta}$

$$\begin{aligned} \hat{\theta} &= (N^T N + \lambda W)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} V^{-1} \hat{\beta} \\ &\quad + (N^T N + \lambda W)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} \Sigma^{-1} N \hat{\theta} \end{aligned}$$

$$\begin{aligned} (I - (N^T N + \lambda W)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} \Sigma^{-1} N) \hat{\theta} \\ = (N^T N + \lambda W)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} V^{-1} \hat{\beta} \end{aligned}$$

$$\begin{aligned} (N^T N + \lambda W) (I - (N^T N + \lambda W)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} \Sigma^{-1} N) \hat{\theta} \\ = N^T (V^{-1} + \Sigma^{-1})^{-1} V^{-1} \hat{\beta} \end{aligned}$$

$$\therefore \hat{\theta} = (N^T N + \lambda W - N^T (V^{-1} + \Sigma^{-1})^{-1} \Sigma^{-1} N)^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} V^{-1} \hat{\beta}$$

$$= [N^T (I - (V^{-1} + \Sigma^{-1})^{-1} \Sigma^{-1} N) + \lambda W]^{-1} N^T (V^{-1} + \Sigma^{-1})^{-1} V^{-1} \hat{\beta}$$

$$= [N^T D N + \lambda W]^{-1} N^T D \hat{\beta}$$

$$(\because D = I - V^* \Sigma^{-1} = V^* V^{-1})$$

$$\hat{\mu}(z) = \sum_{j=1}^J \hat{\theta}_{\hat{f}} N_{\hat{f}}(z) \quad \dots \textcircled{9}$$

for smooth mean fnc.

$$\hat{\mu}(z) = \sum_{j=1}^J l_{\lambda, j}(z) \hat{\beta}_{\hat{f}}$$

$\hat{\mu}(\cdot)$  is a linear smoother for  $\hat{\beta}$

$$l_{\lambda}(z) = (l_{\lambda, 1}(z), \dots, l_{\lambda, J}(z))$$

Thus, the fitted response is

$$\hat{\mu} = (\hat{\mu}(z_1), \dots, \hat{\mu}(z_J))^T = S_{\lambda} \hat{\beta}$$

with smoothing matrix  $S_{\lambda} = (l_{\lambda}(z_1), \dots, l_{\lambda}(z_J))^T$

To choose the value of  $\lambda$ ,

calculate Generalized Cross Validation (GCV)

$$GCV(\lambda) = J^{-1} \sum_{j=1}^J \left( \frac{\hat{\beta}_{\hat{f}} - \hat{\mu}(z_{\hat{f}})}{1 - \text{tr}(S_{\lambda})/J} \right)^2$$

effective degree of freedom is  $df_{\lambda} = \text{tr}(S_{\lambda})$   
for a linear smoother.

where  $h(\hat{\beta}_{\hat{f}} | \beta_{\hat{f}}) \sim \text{AN}(\beta_{\hat{f}}, V_{\hat{f}})$

or  $E(\beta | \hat{\beta}, \hat{\theta}^{(m)}, \sigma)$

$\beta_1^{(m)}, \dots, \beta_B^{(m)}$  generated from dist.

$$\begin{aligned} (\beta | \hat{\beta}; \theta, \sigma) &\sim \mathcal{N} \left( (V^{-1} + \Sigma^{-1})^{-1} (V^{-1} \hat{\beta} + \Sigma^{-1} N \theta), (V^{-1} + \Sigma^{-1})^{-1} \right) \\ &= \mathcal{N}(\beta^*, V^*) \end{aligned}$$

can be estimated by

$$\frac{\sum_{b=1}^B w_b \beta_b^{(m)}}{\sum_{b=1}^B w_b}$$

where  $w_b$  is weight for the  $\beta_b^{(m)}$

$w_b = h(\hat{\beta} | \beta_b)$ , straightforward choice

$$\begin{aligned} E(\beta | \hat{\beta}; \hat{\theta}^{(m)}, \sigma) &= \int \beta h(\beta | \hat{\beta}; \hat{\theta}^{(m)}, \sigma) d\beta \\ &= \int \beta \frac{h(\hat{\beta}, \beta | \hat{\theta}^{(m)}, \sigma)}{\int h(\hat{\beta}, \beta | \hat{\theta}^{(m)}, \sigma) d\beta} d\beta \\ &= \frac{\int \beta h(\hat{\beta} | \beta) h(\beta | \hat{\theta}^{(m)}, \sigma) d\beta}{\int h(\hat{\beta}, \beta | \hat{\theta}^{(m)}, \sigma) d\beta} \\ &= \frac{E_{\beta | \hat{\theta}^{(m)}, \sigma}[\beta h(\hat{\beta} | \beta)]}{E_{\beta | \hat{\theta}^{(m)}, \sigma}[h(\hat{\beta} | \beta)]} \quad \dots \textcircled{11} \end{aligned}$$

Thus, once a form of  $h(\hat{\beta} | \beta)$  is given,

generate MC sample  $\beta_b \sim (\beta_b | \hat{\theta}^{(m)}, \sigma)$

$$E[\beta | \hat{\beta}, \hat{\theta}^{(m)}, \sigma] \approx \frac{\sum_{b=1}^B \beta_b h(\hat{\beta} | \beta_b)}{\sum_{b=1}^B h(\hat{\beta} | \beta_b)}$$

by WLLN large B ..