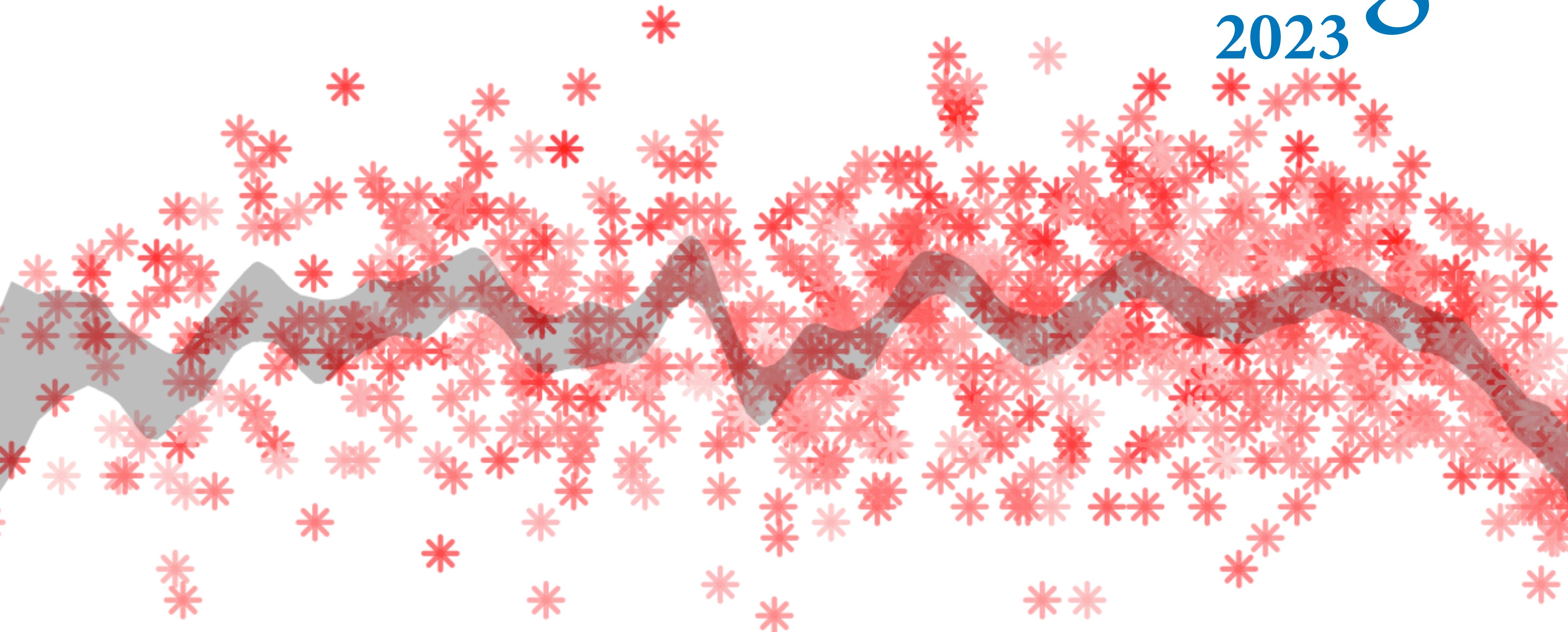


# Statistical Rethinking

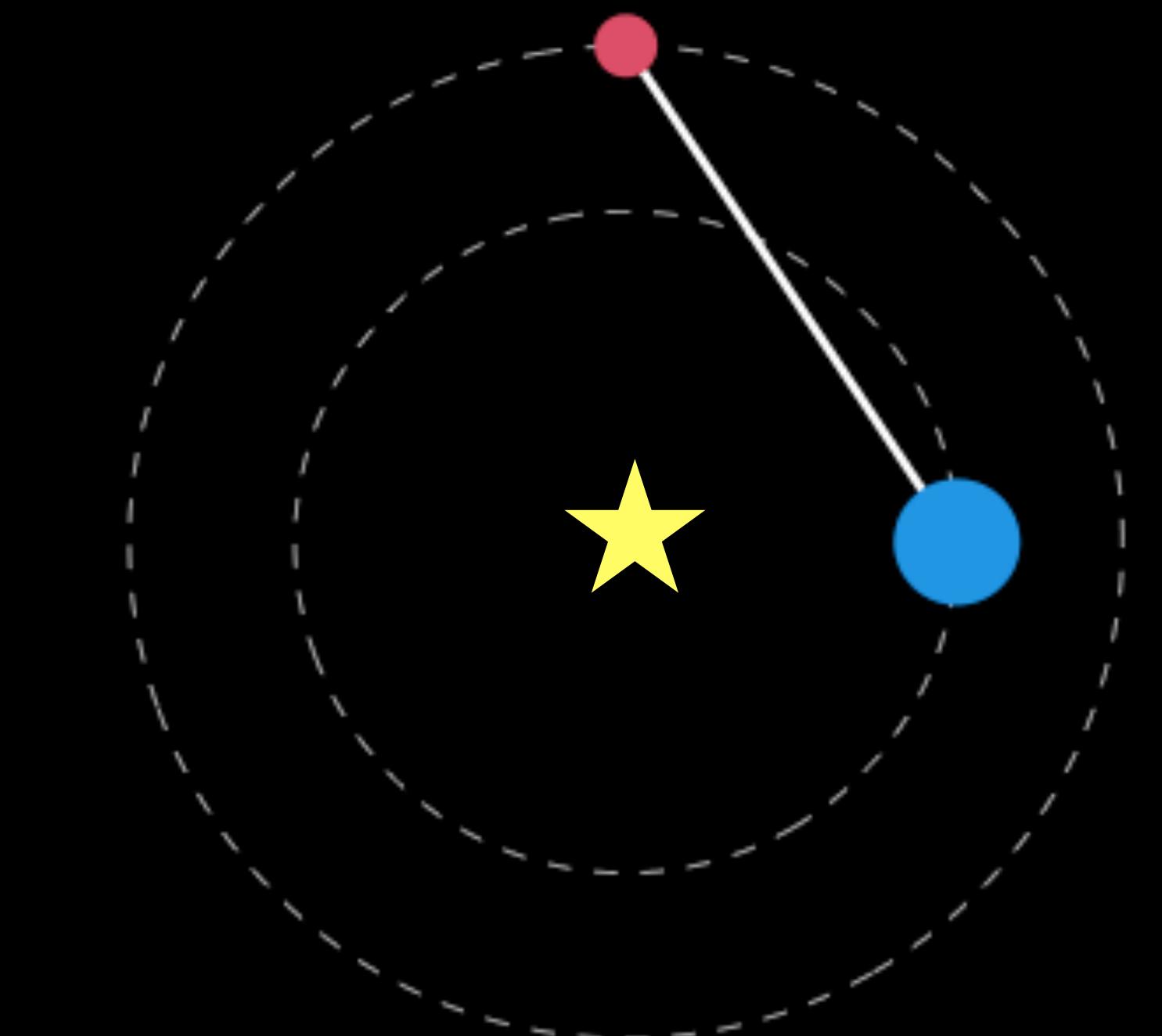
2023



7. Fitting Over & Under



Mikołaj Kopernik (1473–1543)

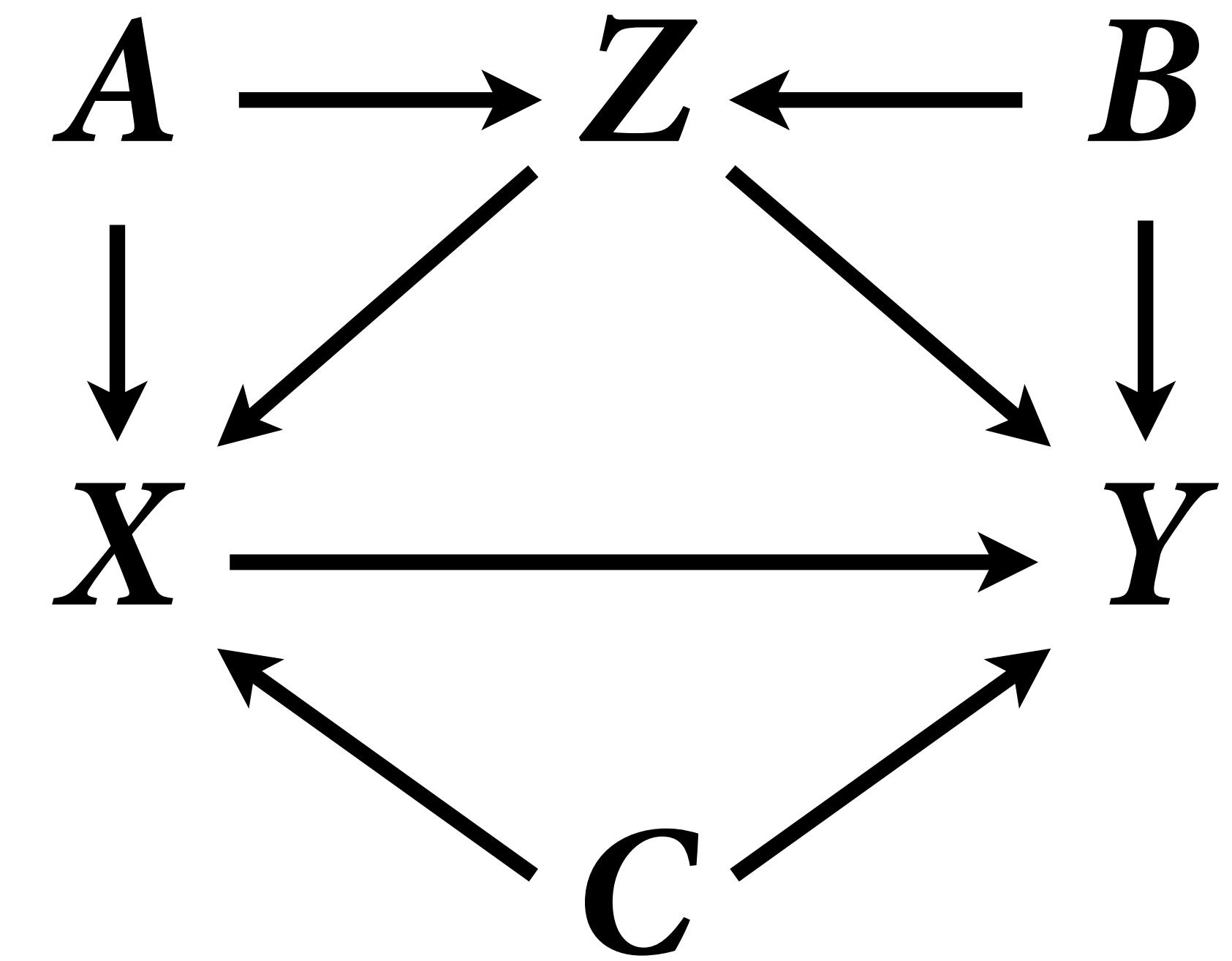


# Infinite causes, finite data

Estimator might **exist**, but not be **useful**

Struggle against causation: How to use causal assumptions to design estimators, contrast alternative models

Struggle against data: How to make the estimators work



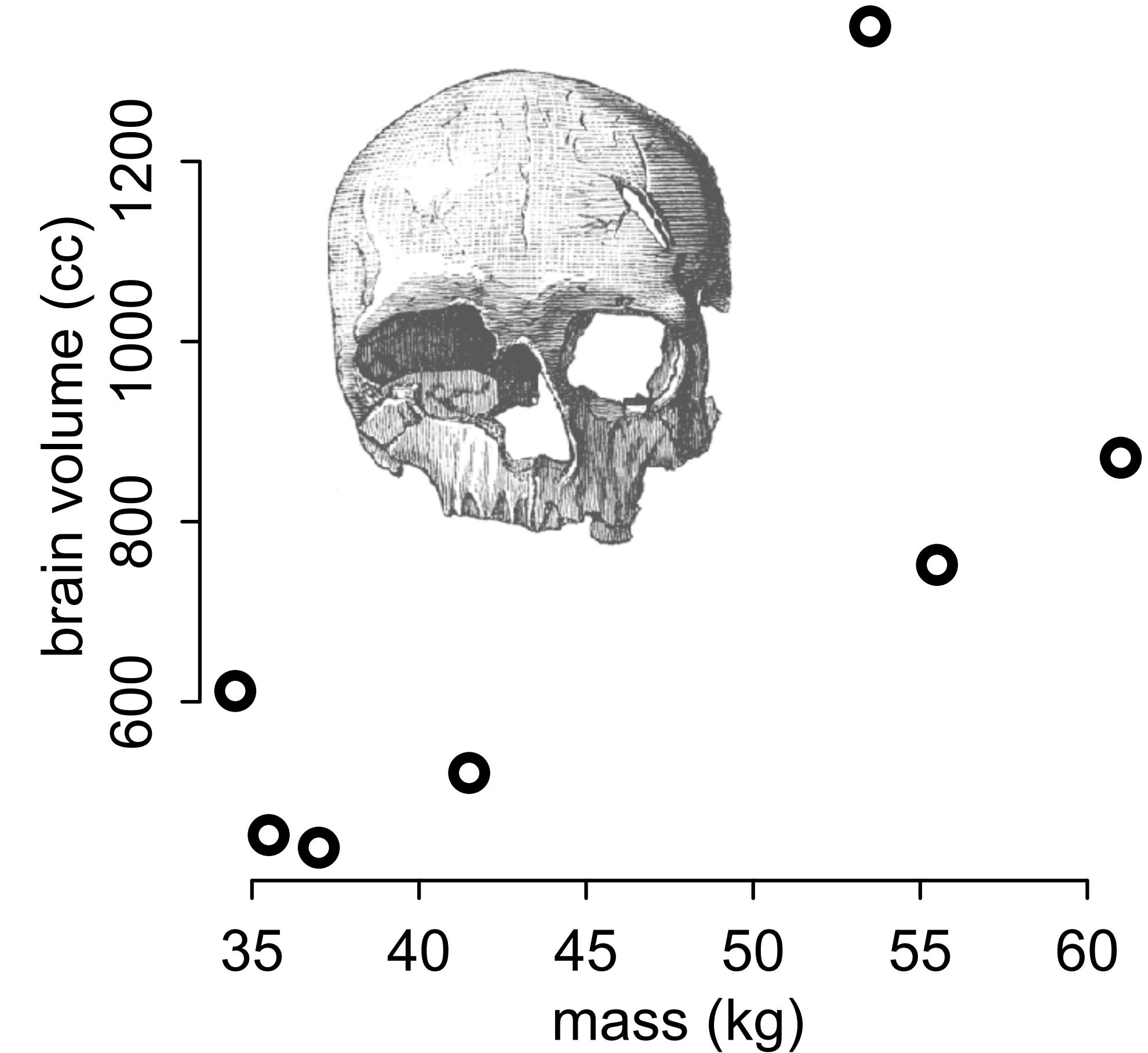
# Problems of Prediction

What function describes these points?  
(fitting, compression)

What function explains these points?  
(causal inference)

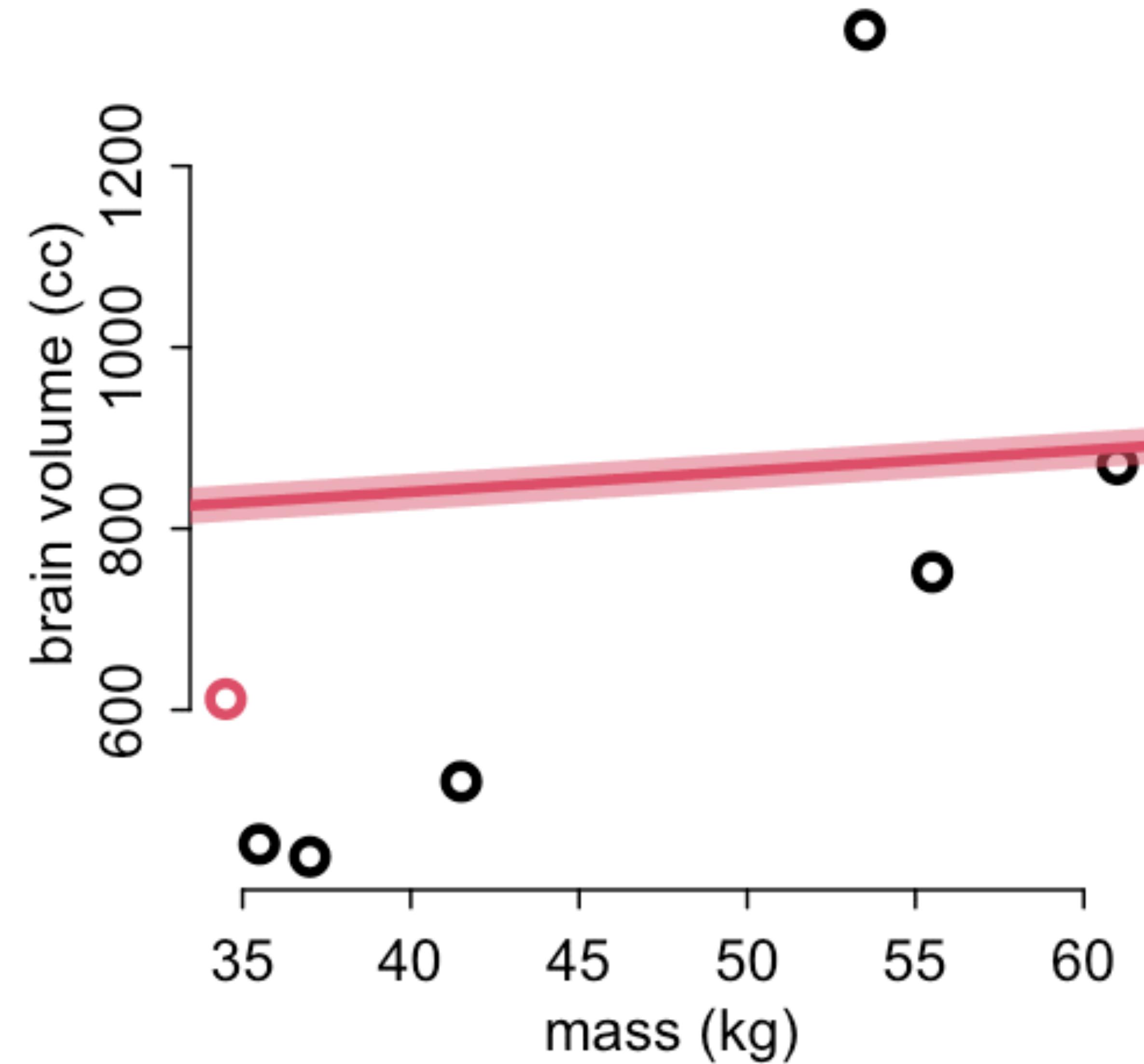
What would happen if we changed a point's mass? (intervention)

What is the next observation from the same process? (prediction)



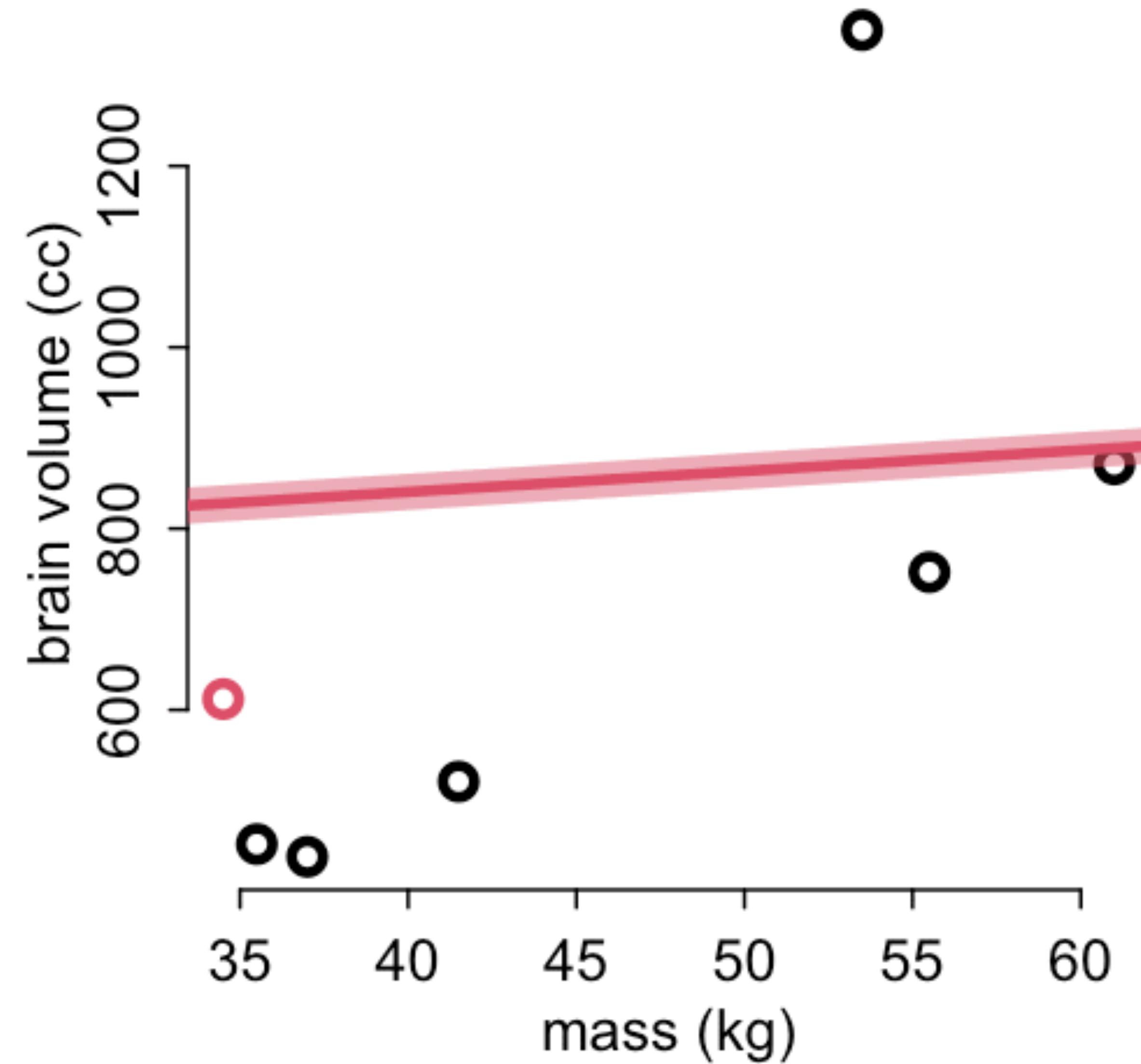
# Leave-one-out cross-validation

- (1) Drop one point
- (2) Fit line to remaining
- (3) Predict dropped point
- (4) Repeat (1) with next point
- (5) Score is error on dropped



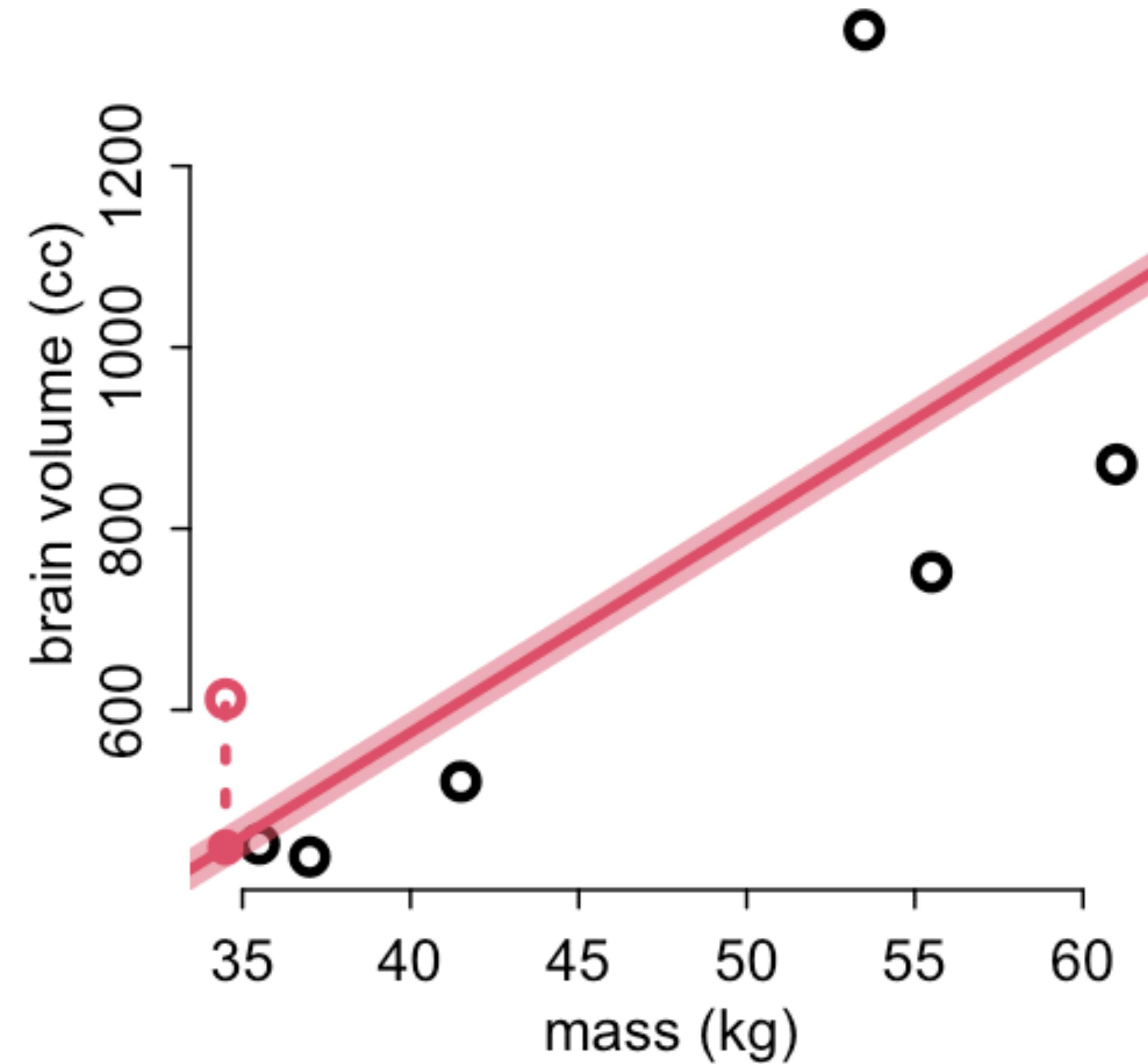
## Leave-one-out cross-validation

- (1) Drop one point
- (2) Fit line to remaining
- (3) Predict dropped point
- (4) Repeat (1) with next point
- (5) Score is error on dropped



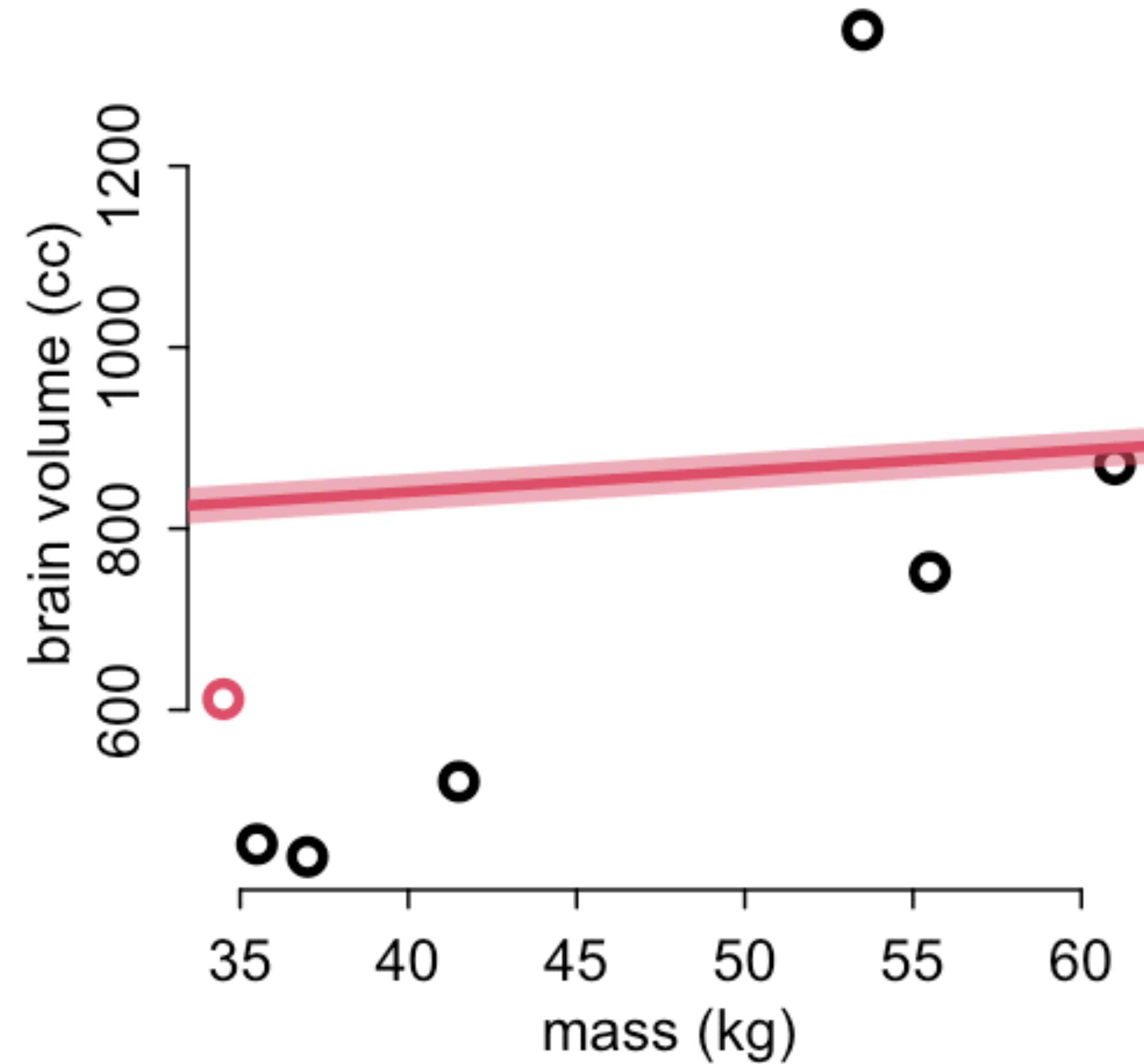
# Leave-one-out cross-validation

- (1) Drop one point
- (2) Fit line to remaining
- (3) Predict dropped point
- (4) Repeat (1) with next point
- (5) Score is error on dropped



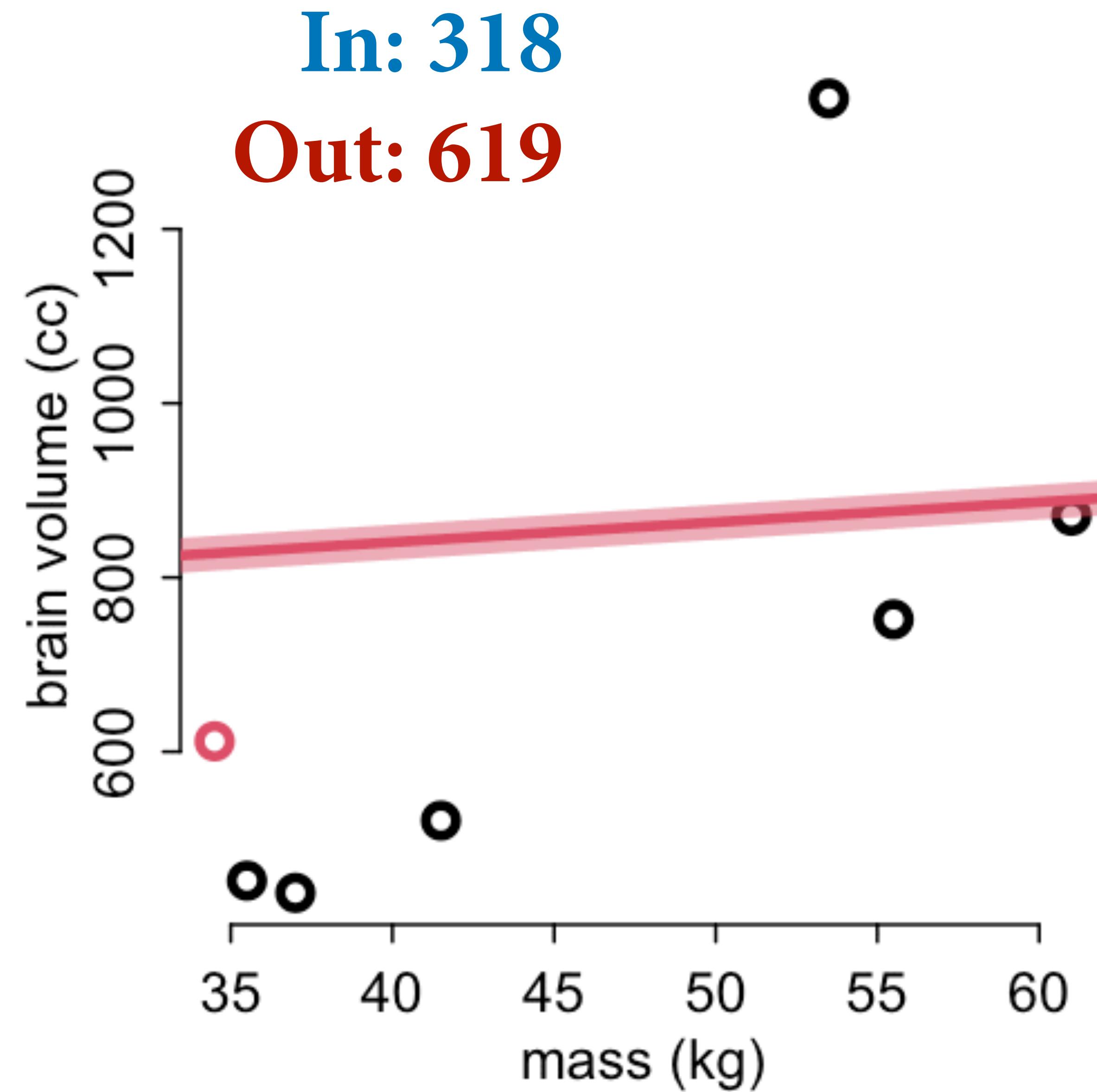
# Leave-one-out cross-validation

- (1) Drop one point
- (2) Fit line to remaining
- (3) Predict dropped point
- (4) Repeat (1) with next point
- (5) Score is error on dropped



## Leave-one-out cross-validation

- (1) Drop one point
- (2) Fit line to remaining
- (3) Predict dropped point
- (4) Repeat (1) with next point
- (5) Score is error on dropped

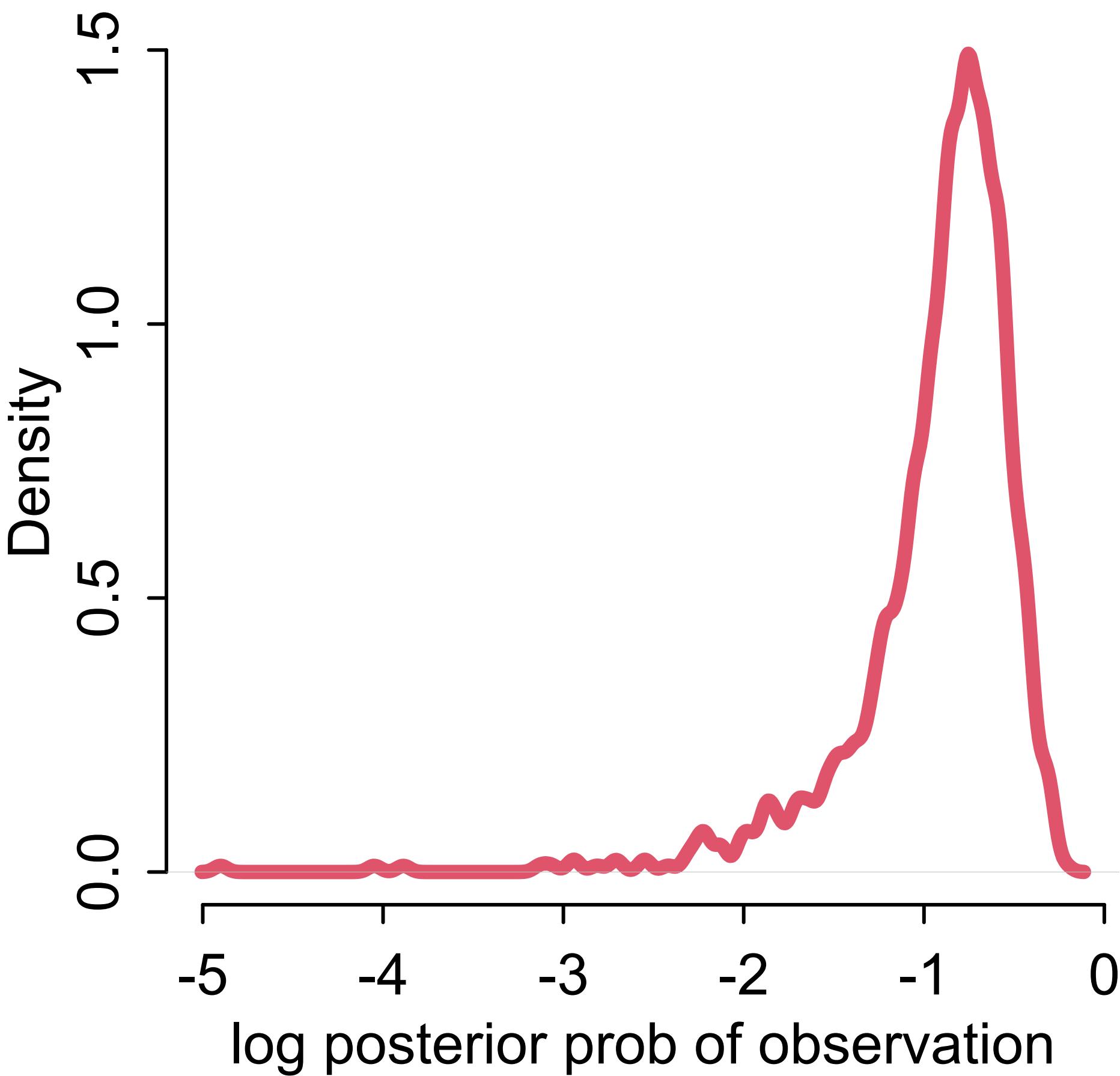


# Bayesian Cross-Validation

We use the entire posterior, not just a point prediction

Cross-validation score is:

$$\text{lppd}_{\text{CV}} = \sum_{i=1}^N \frac{1}{S} \sum_{s=1}^S \log \Pr(y_i | \theta_{-i,s})$$



# Bayesian Cross-Validation

$$\text{lppd}_{\text{CV}} = \sum_{i=1}^N \frac{1}{S} \sum_{s=1}^S \overbrace{\log \Pr(y_i | \theta_{-i,s})}^{\substack{\text{log probability of each point } i, \\ \text{computed with posterior that} \\ \text{omits point } i}}$$

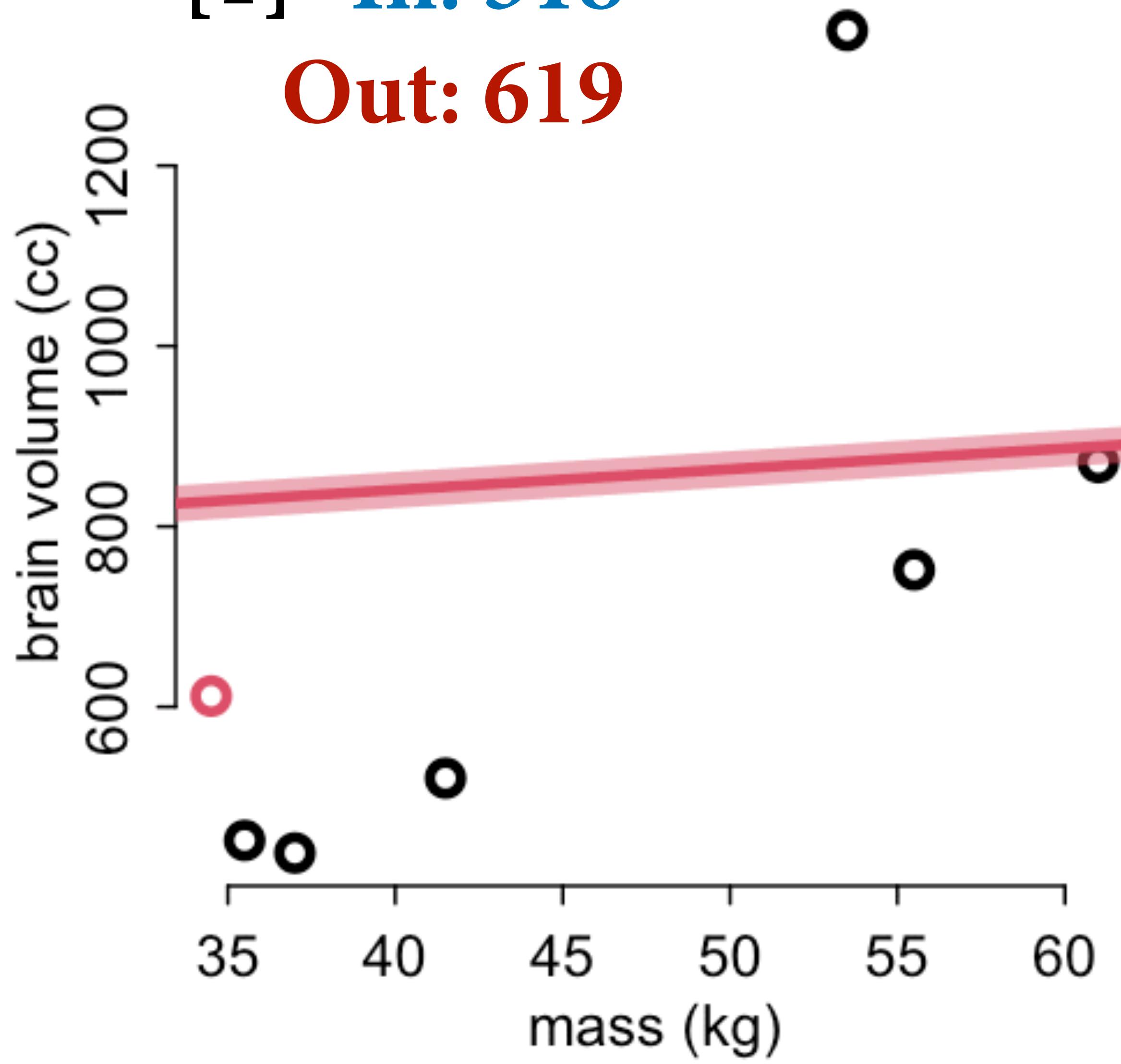
*log pointwise  
predictive density*

*N data points*

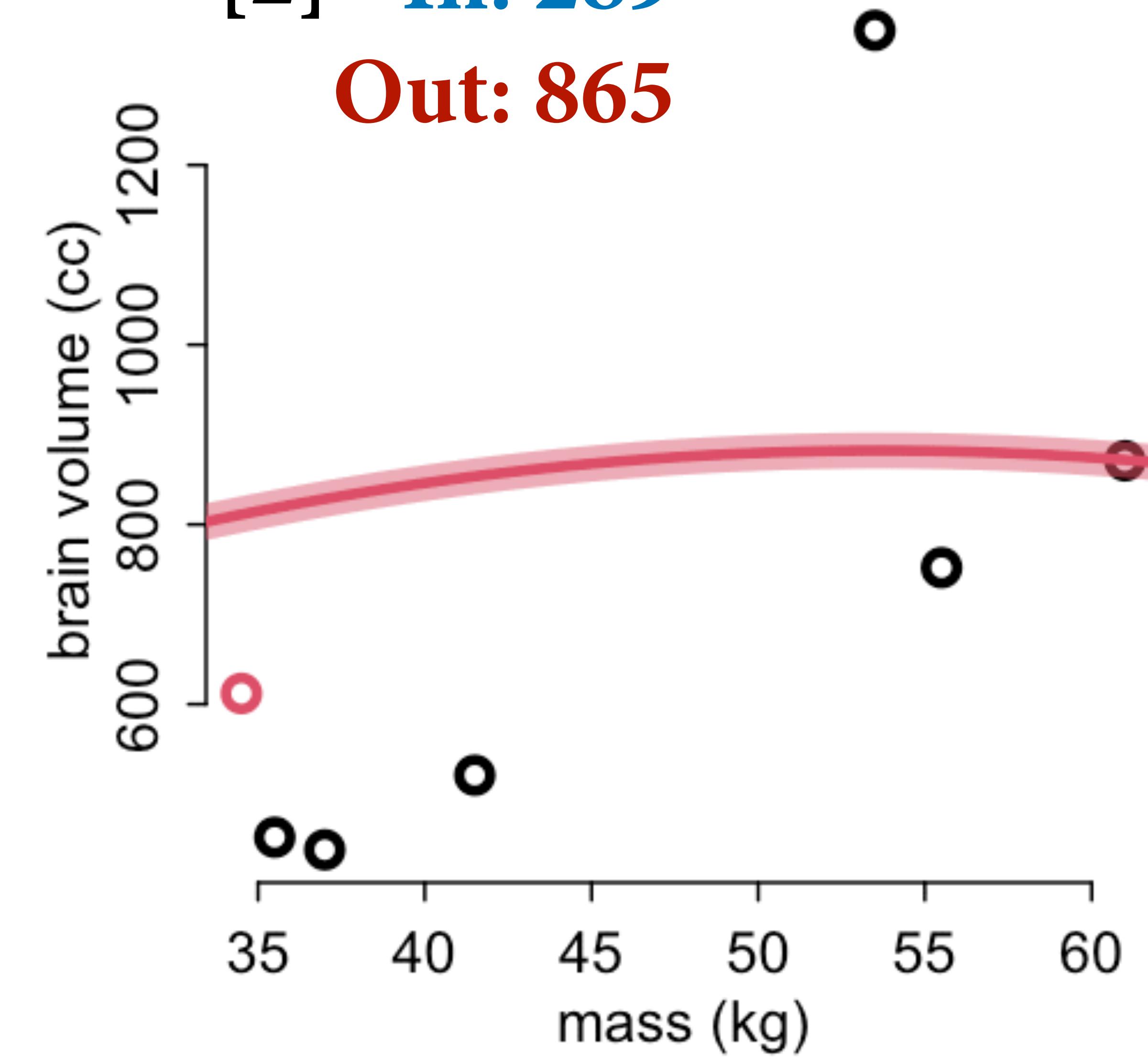
*S samples  
from posterior*

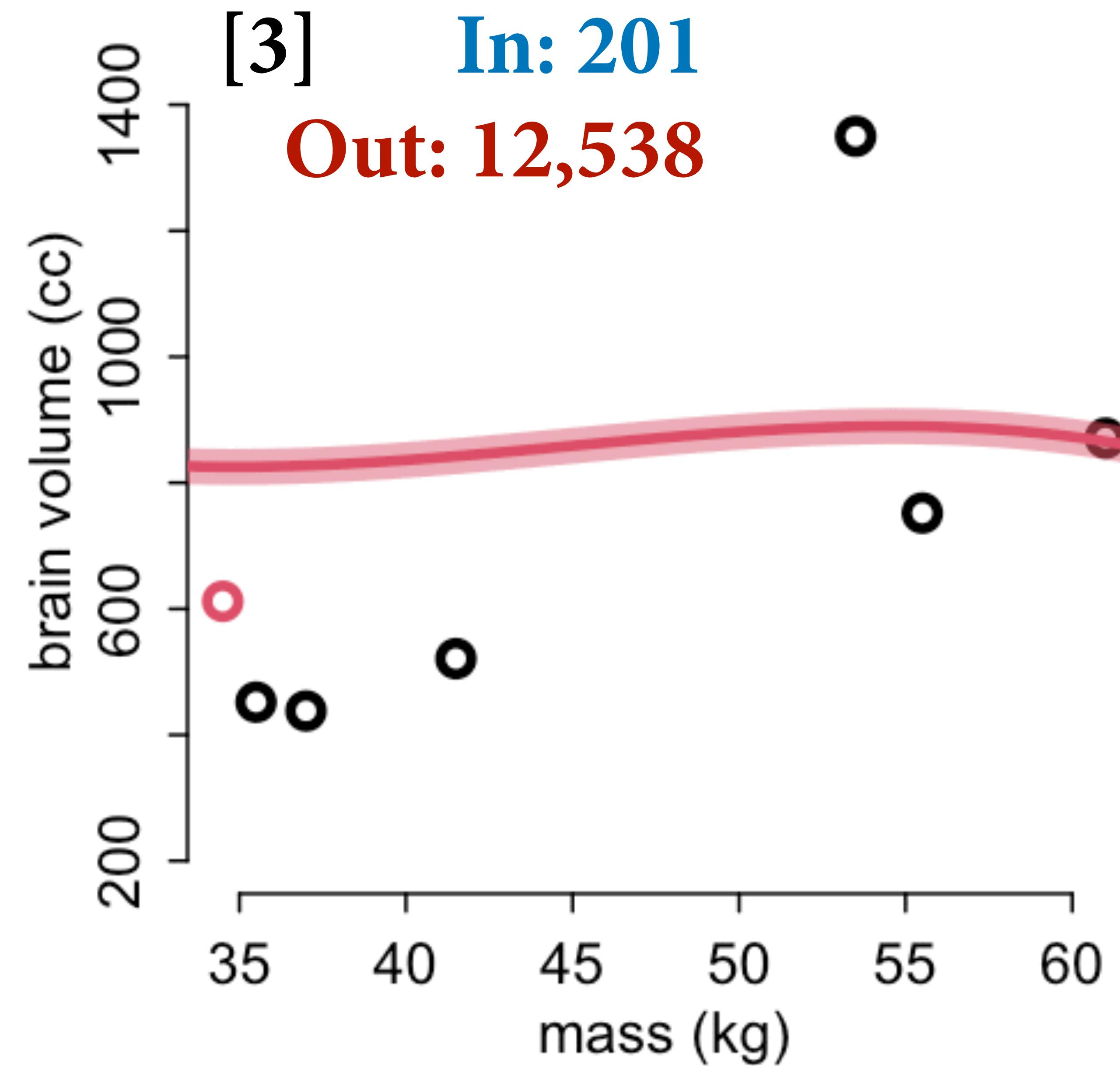
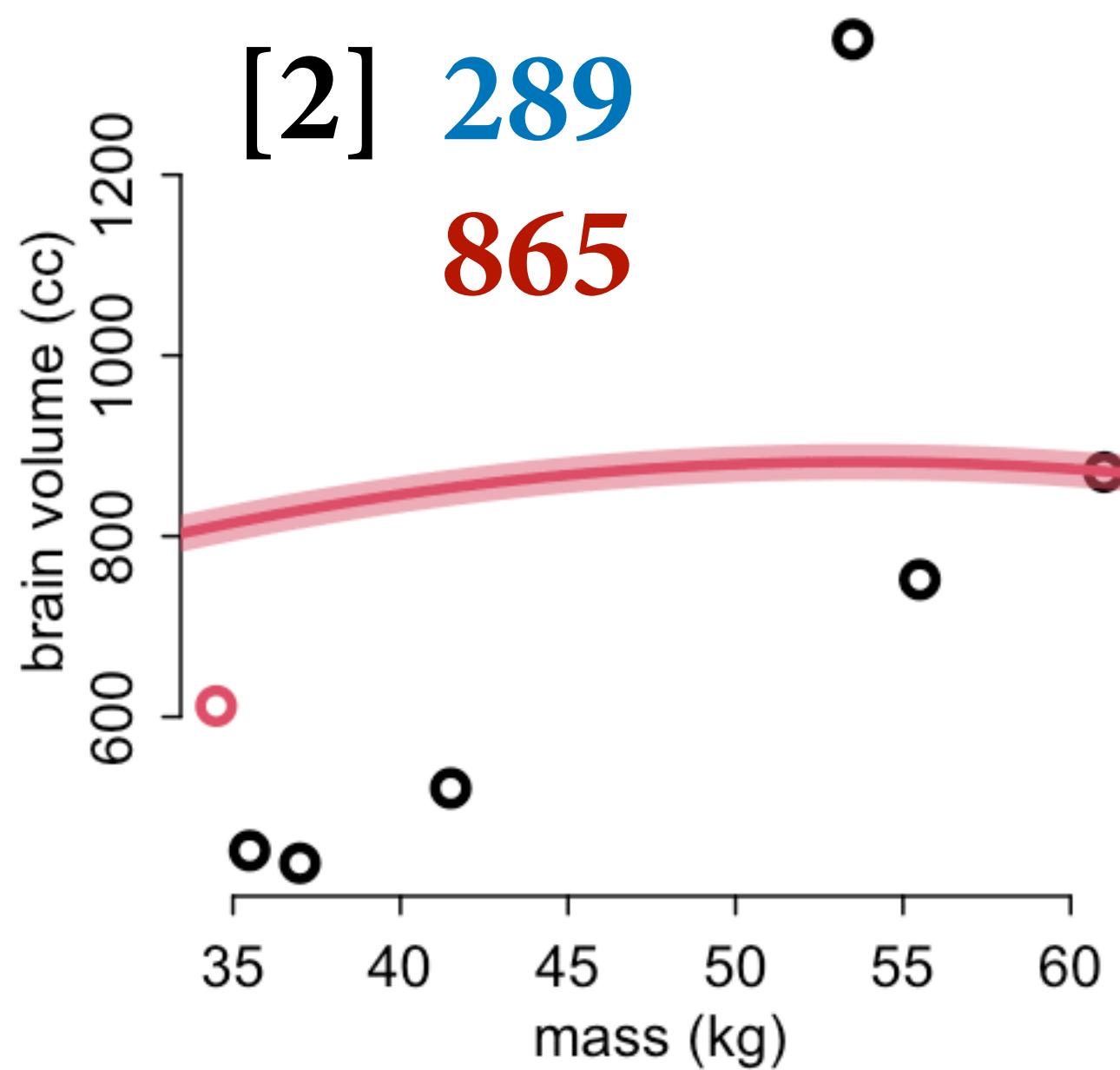
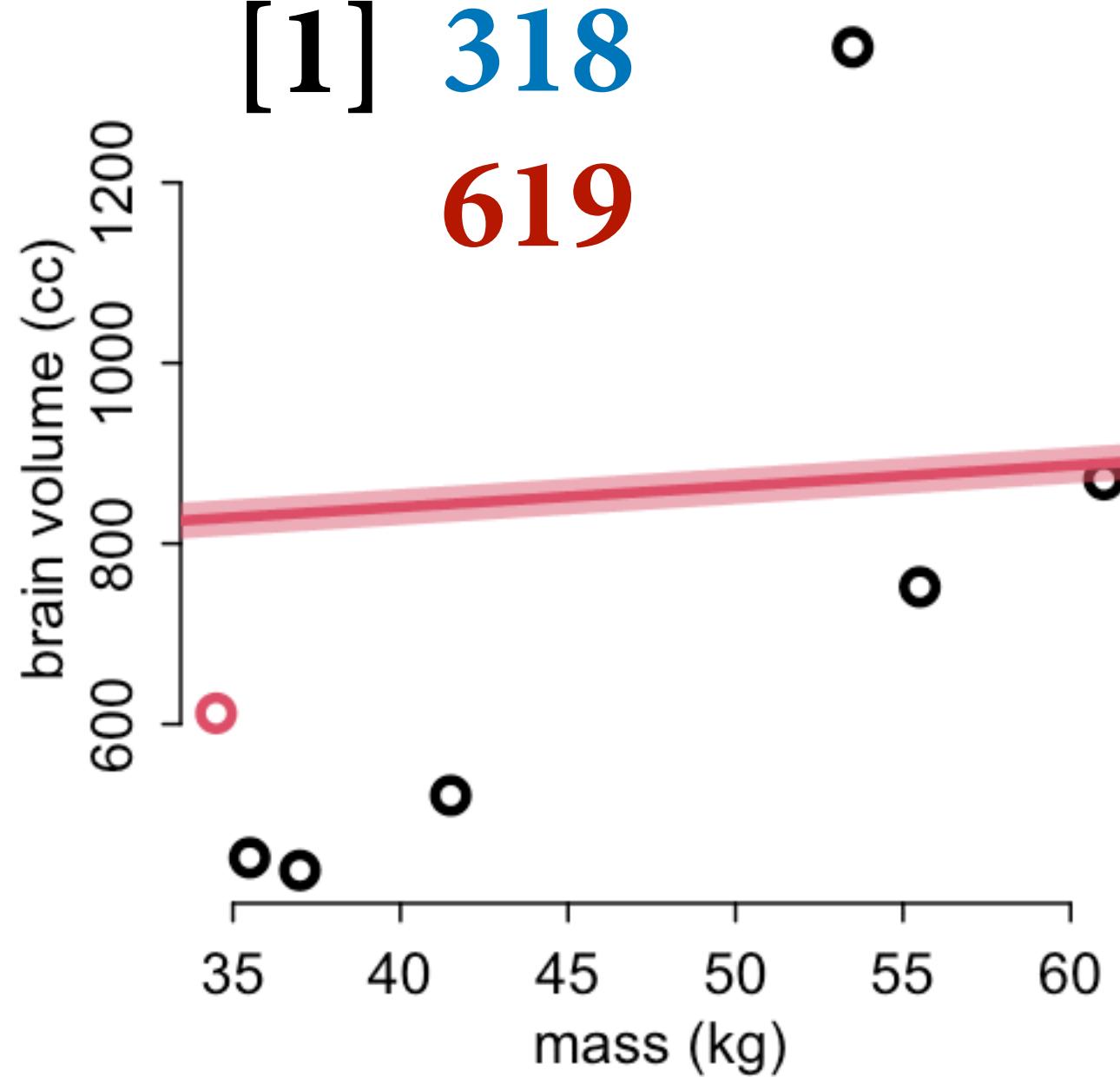
*average log probability  
for point i*

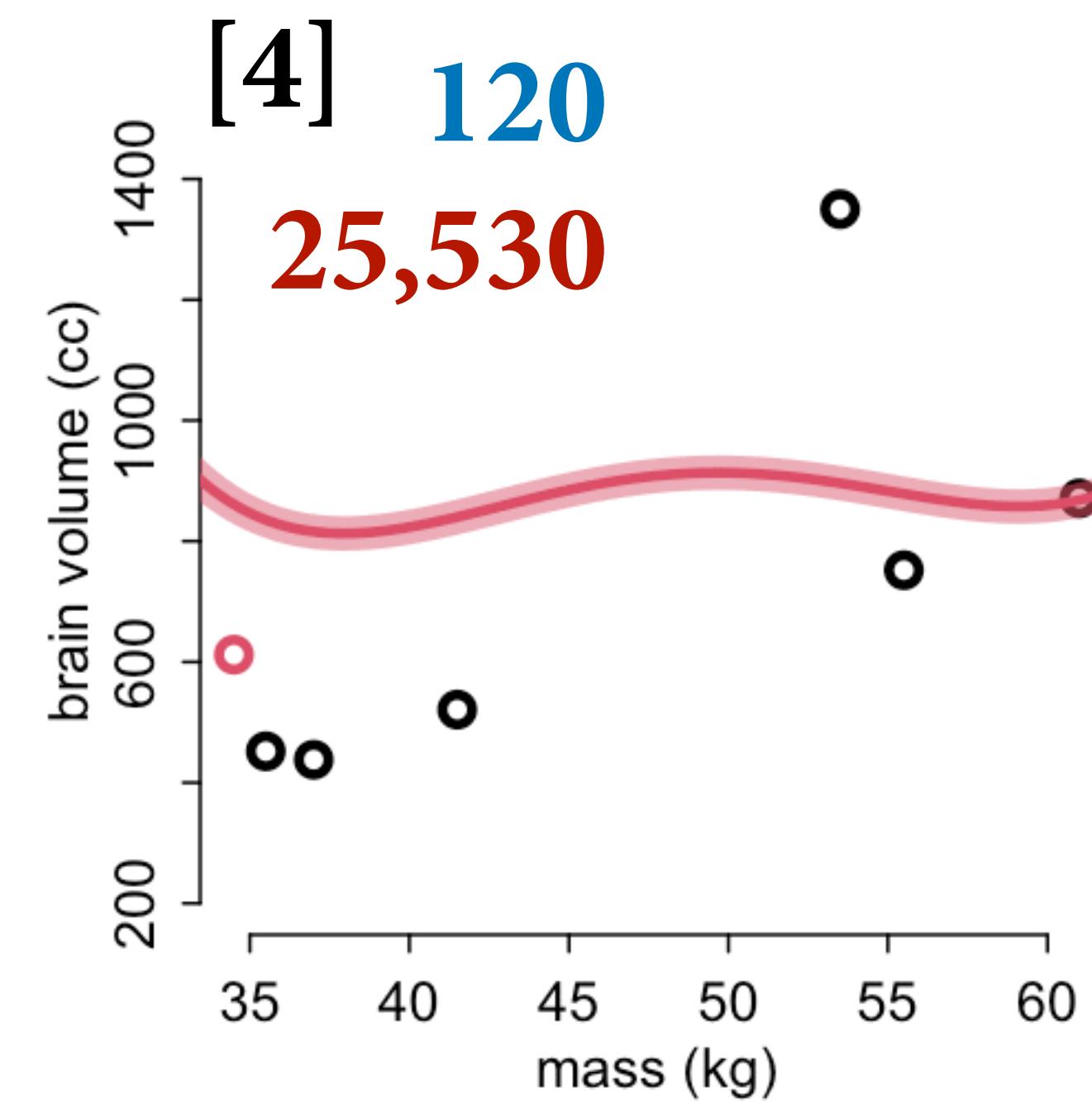
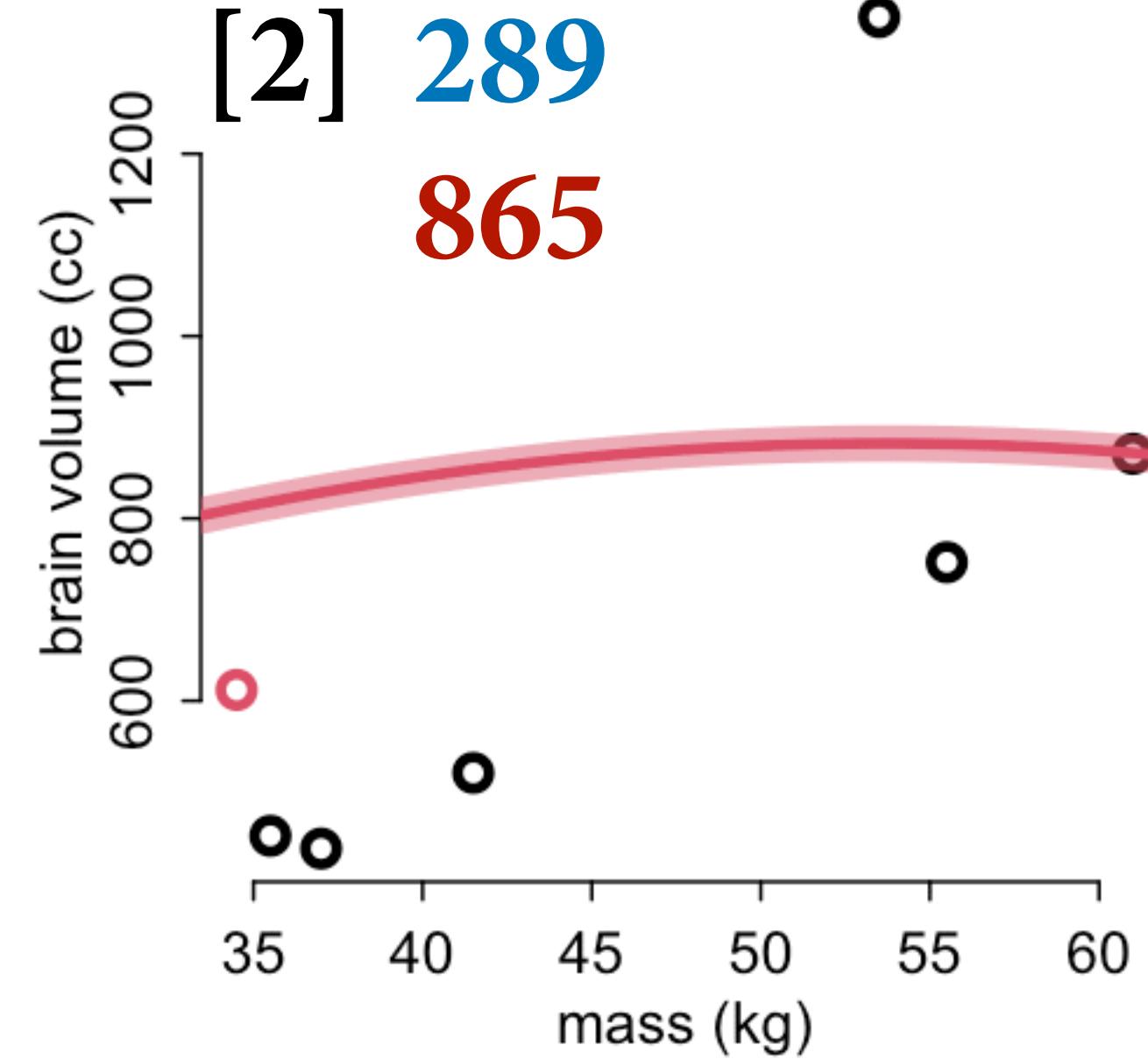
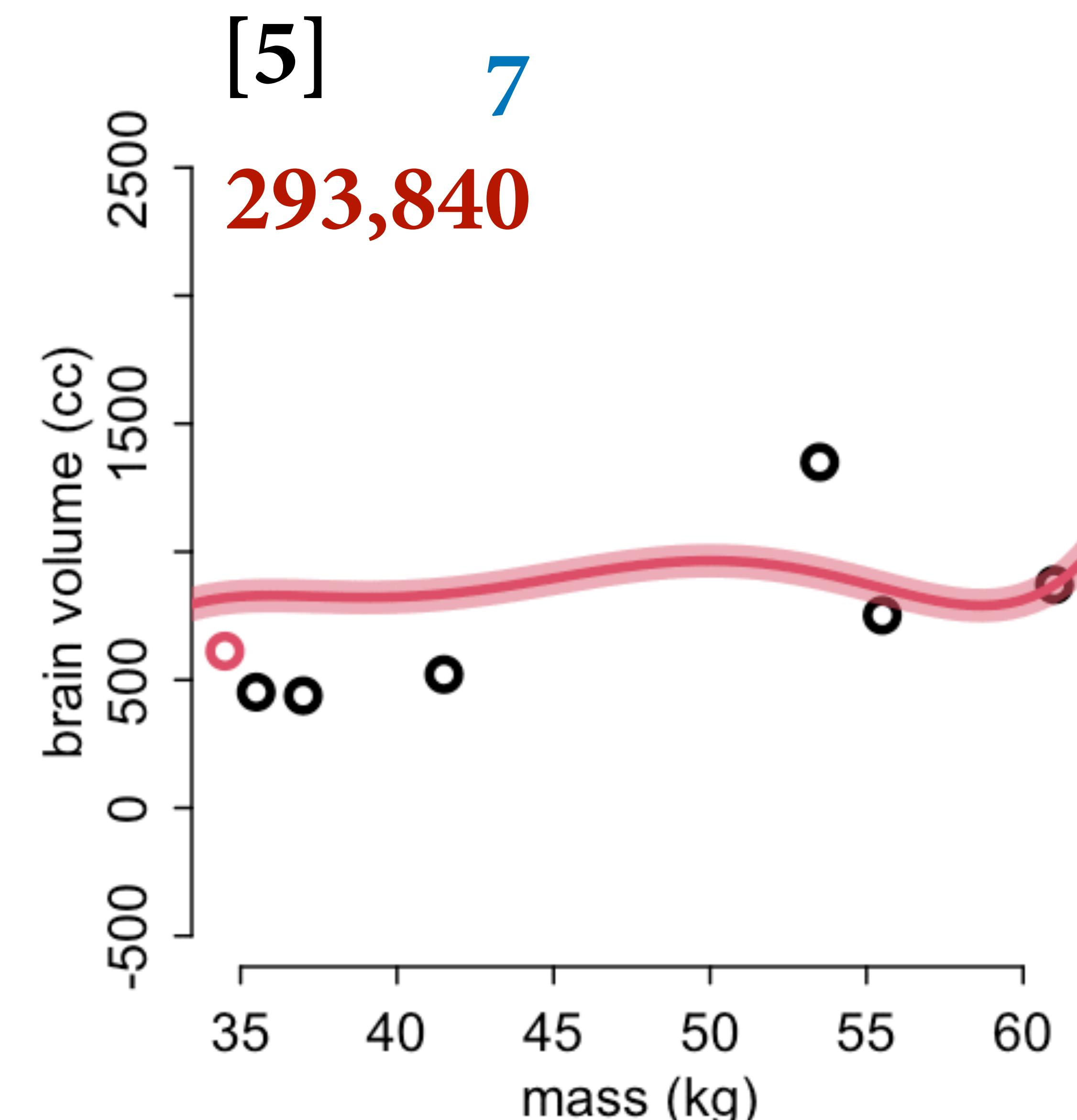
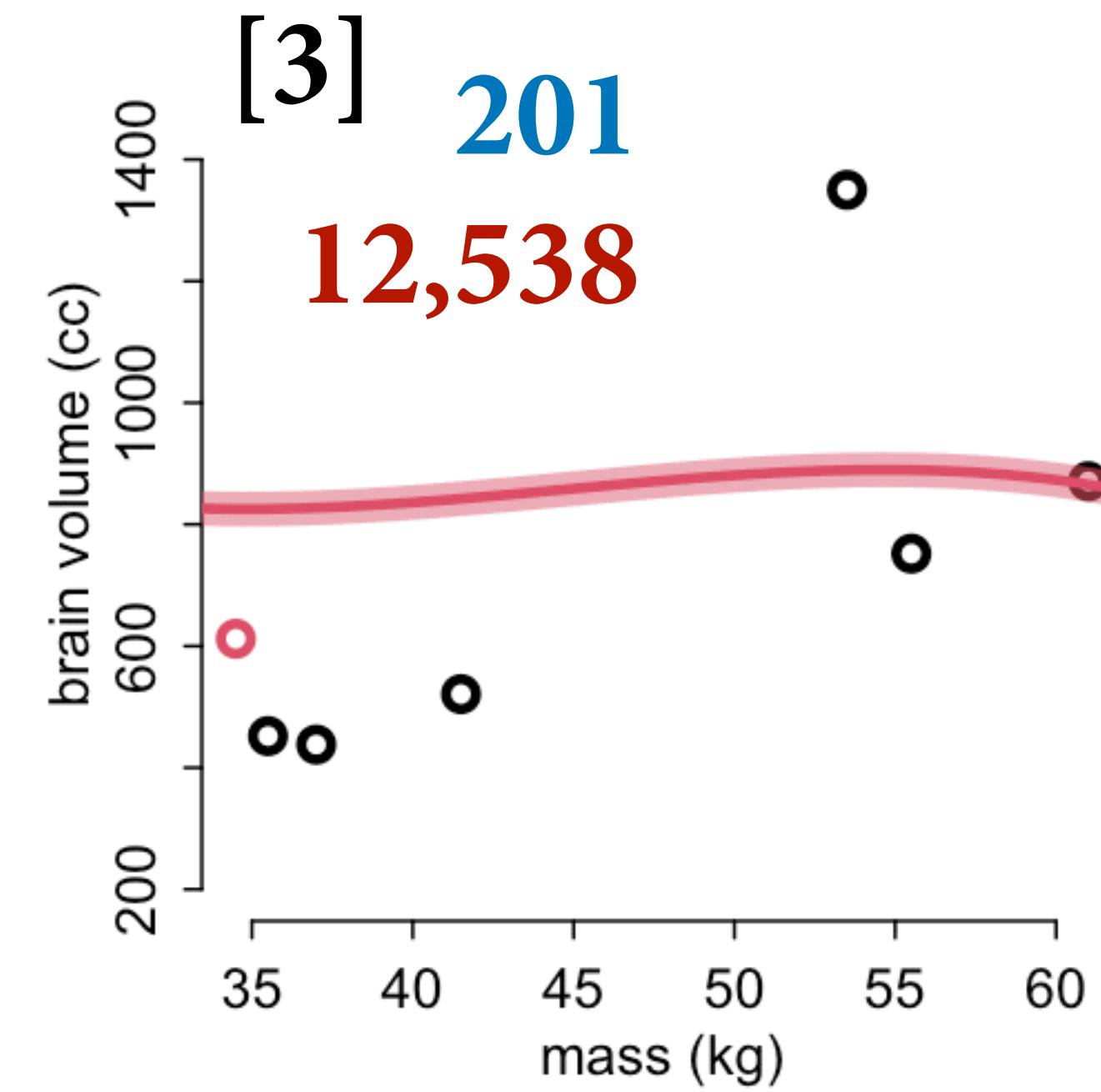
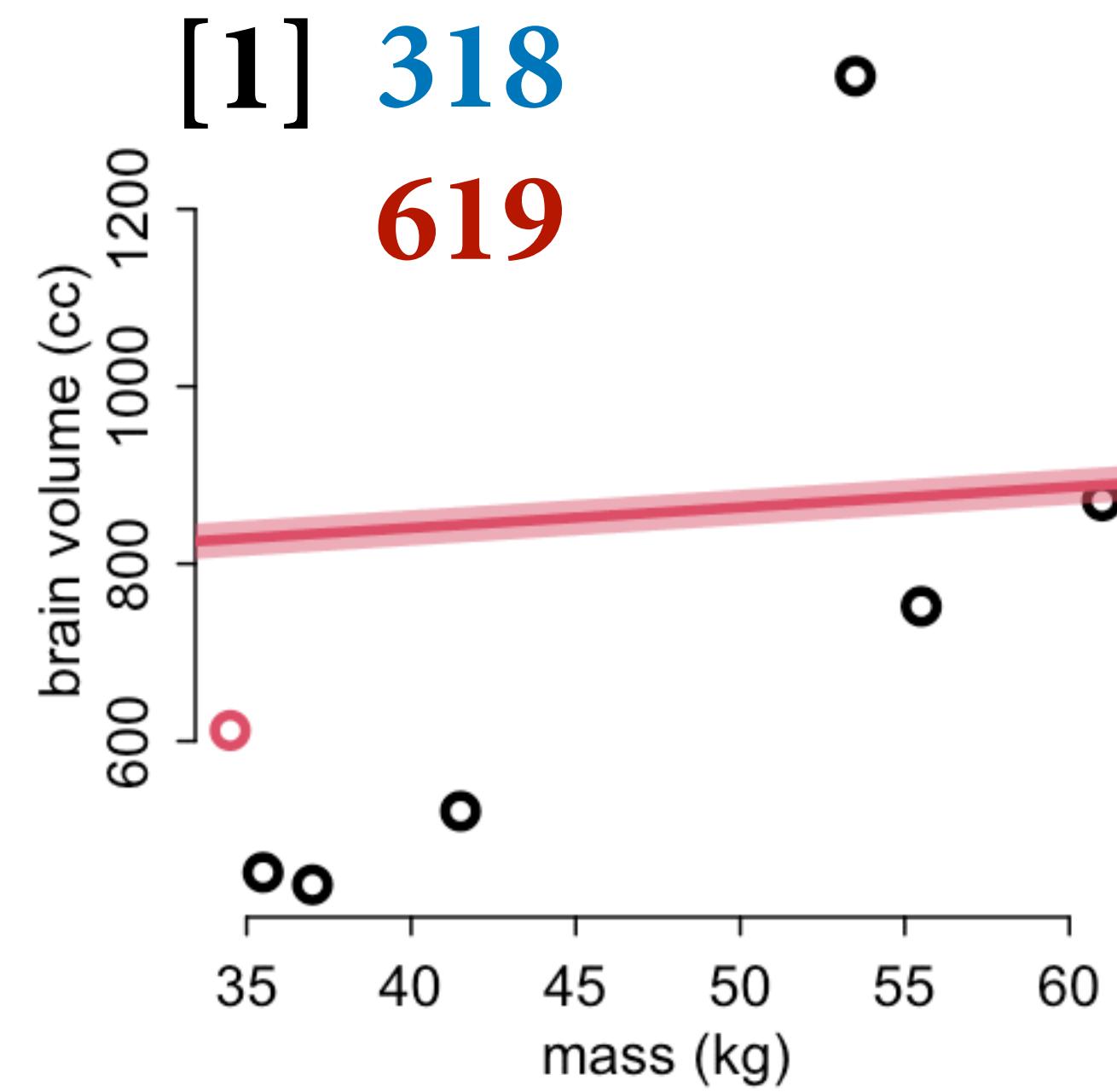
[1] In: 318  
Out: 619



[2] In: 289  
Out: 865





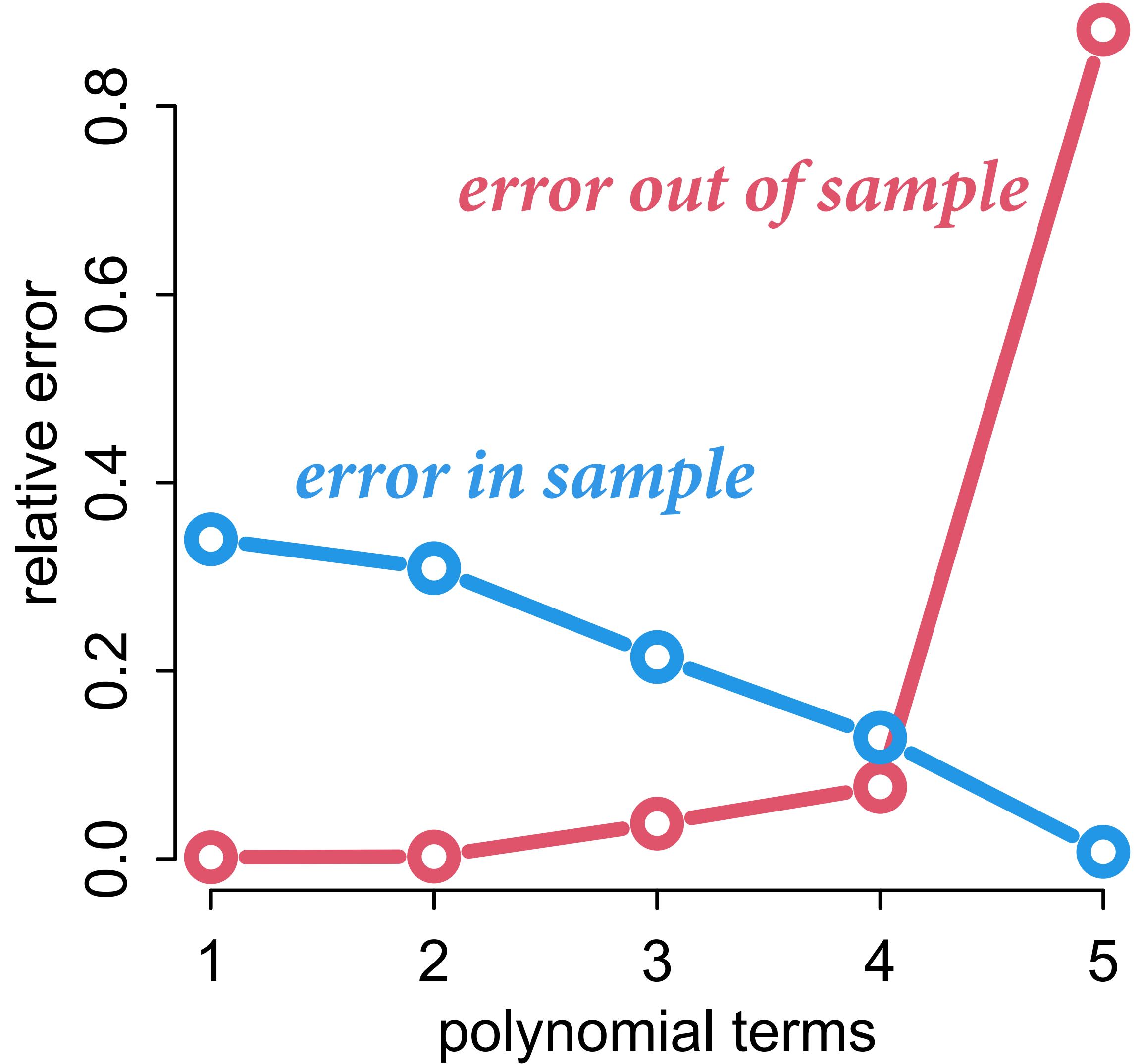


# Cross-validation

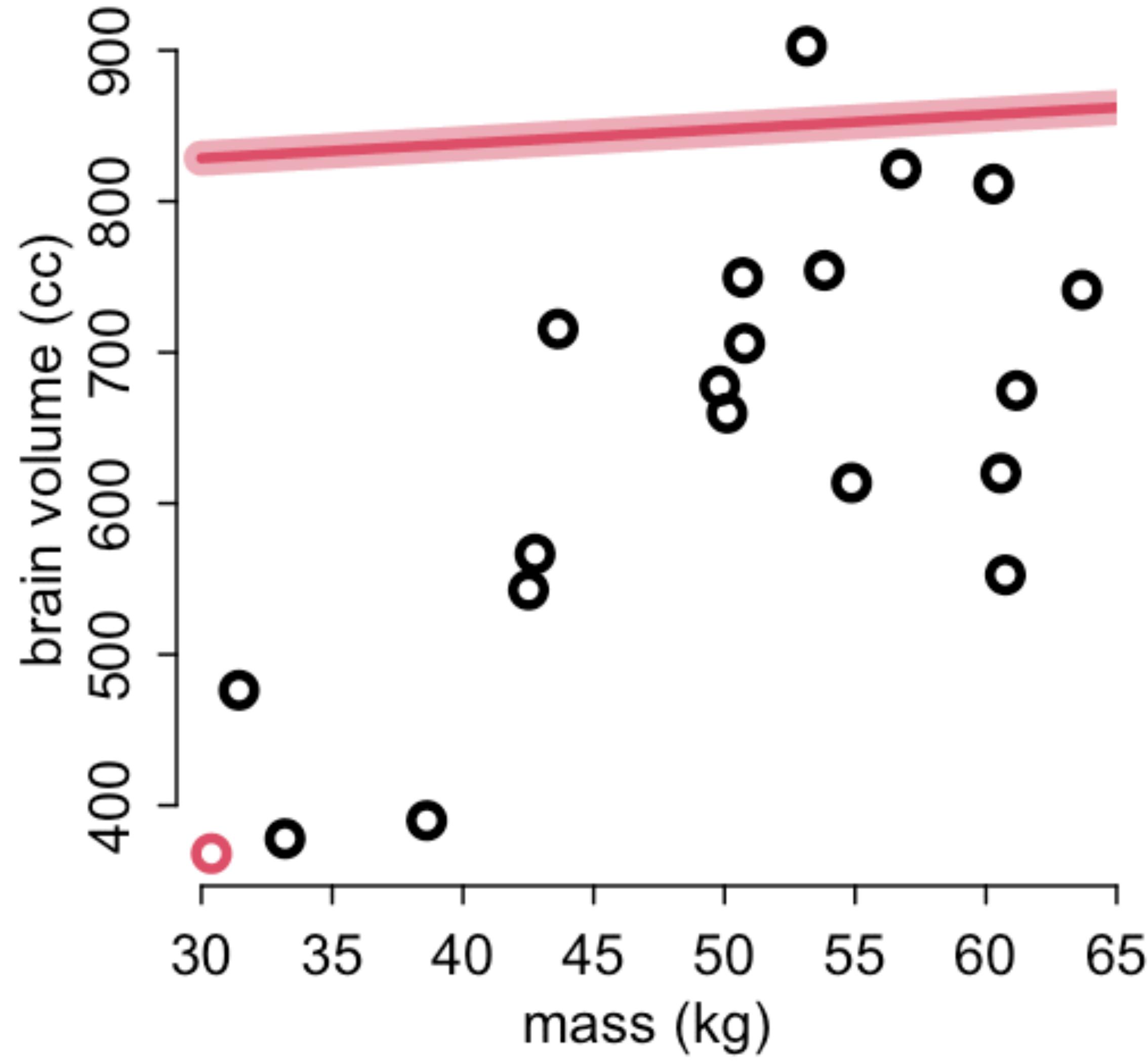
For **simple** models, more parameters improves fit to sample

But may reduce accuracy of predictions out of sample

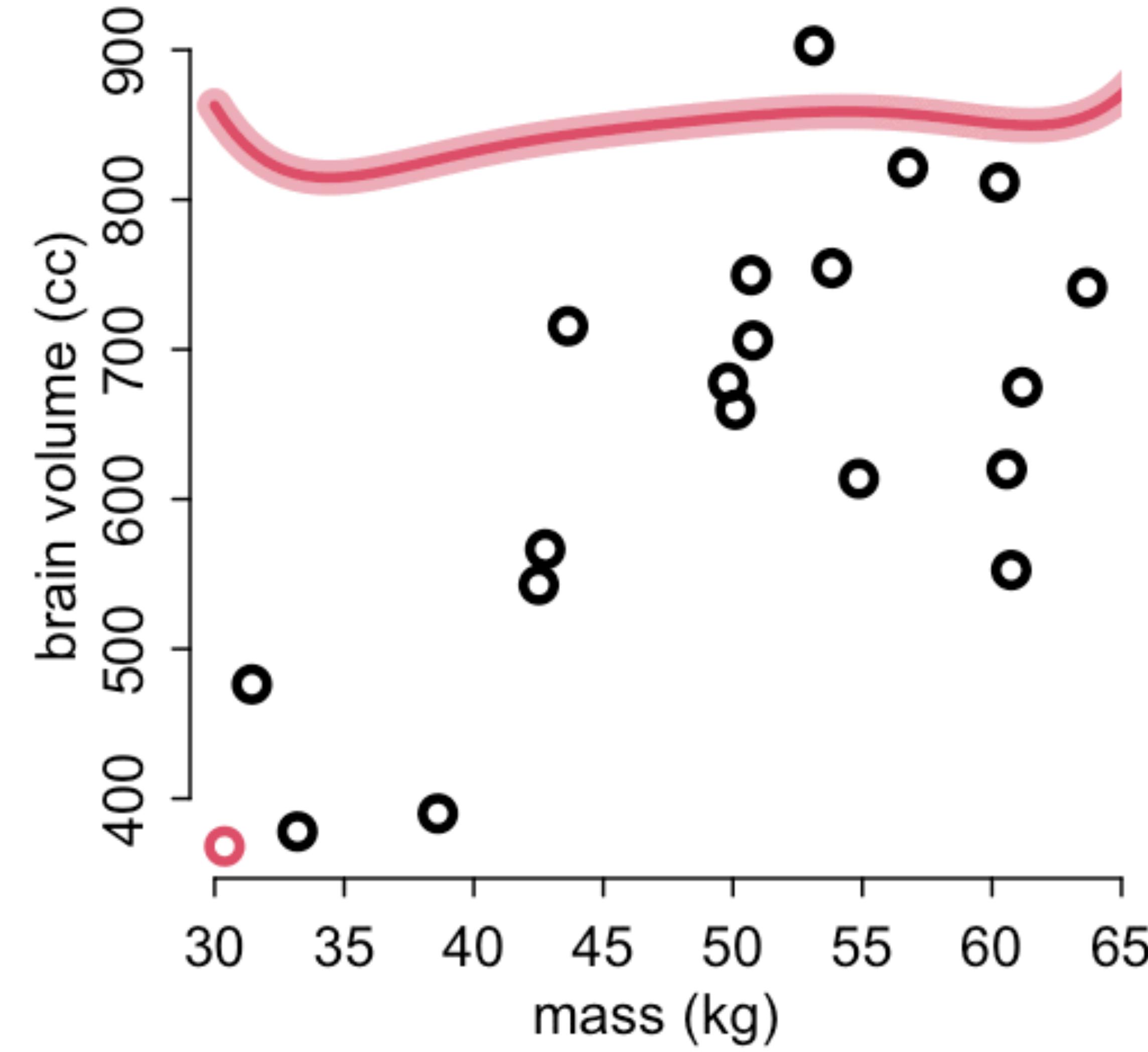
Most accurate model trades off flexibility with **overfitting**



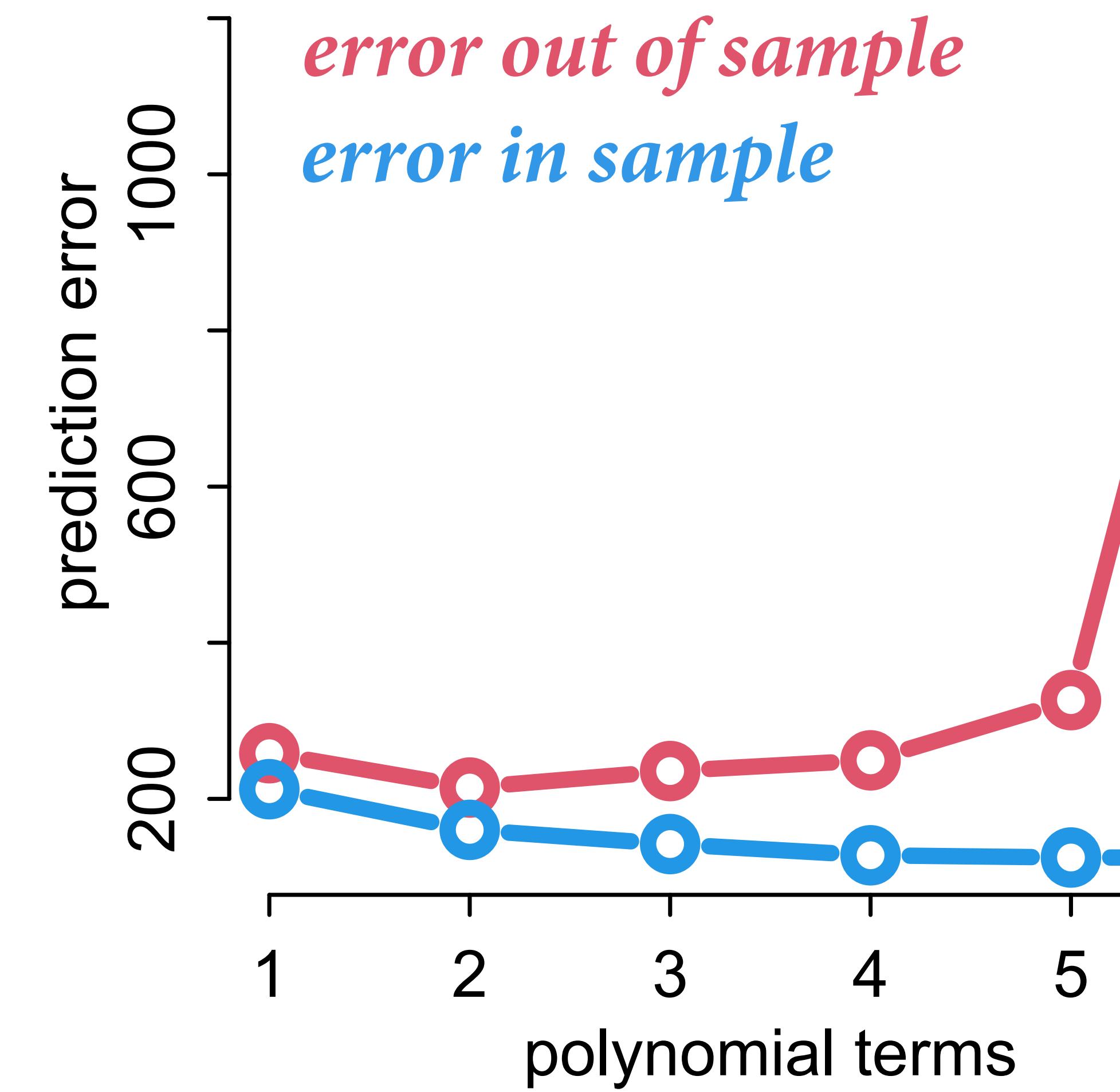
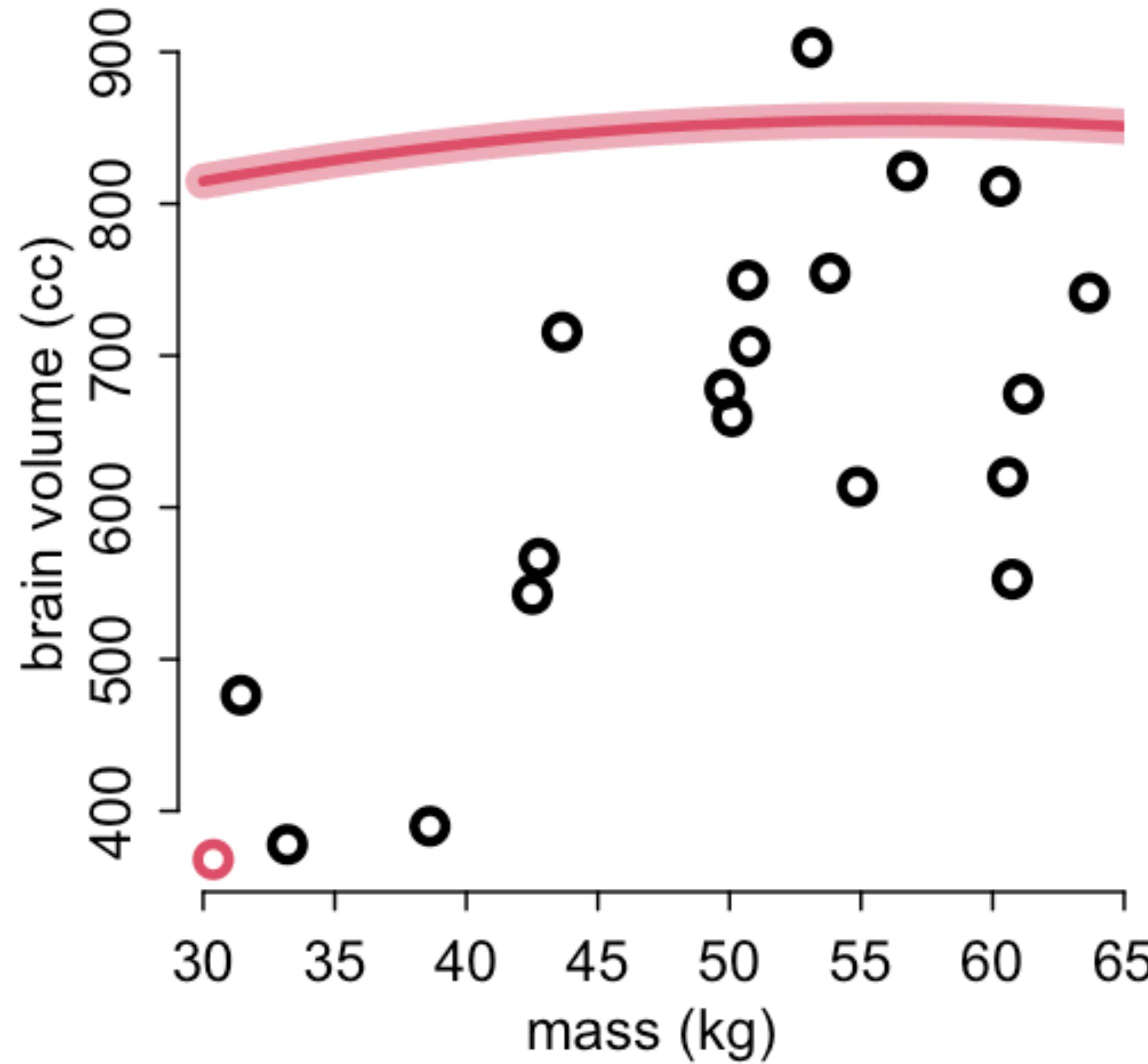
1st degree polynomial



6th degree polynomial

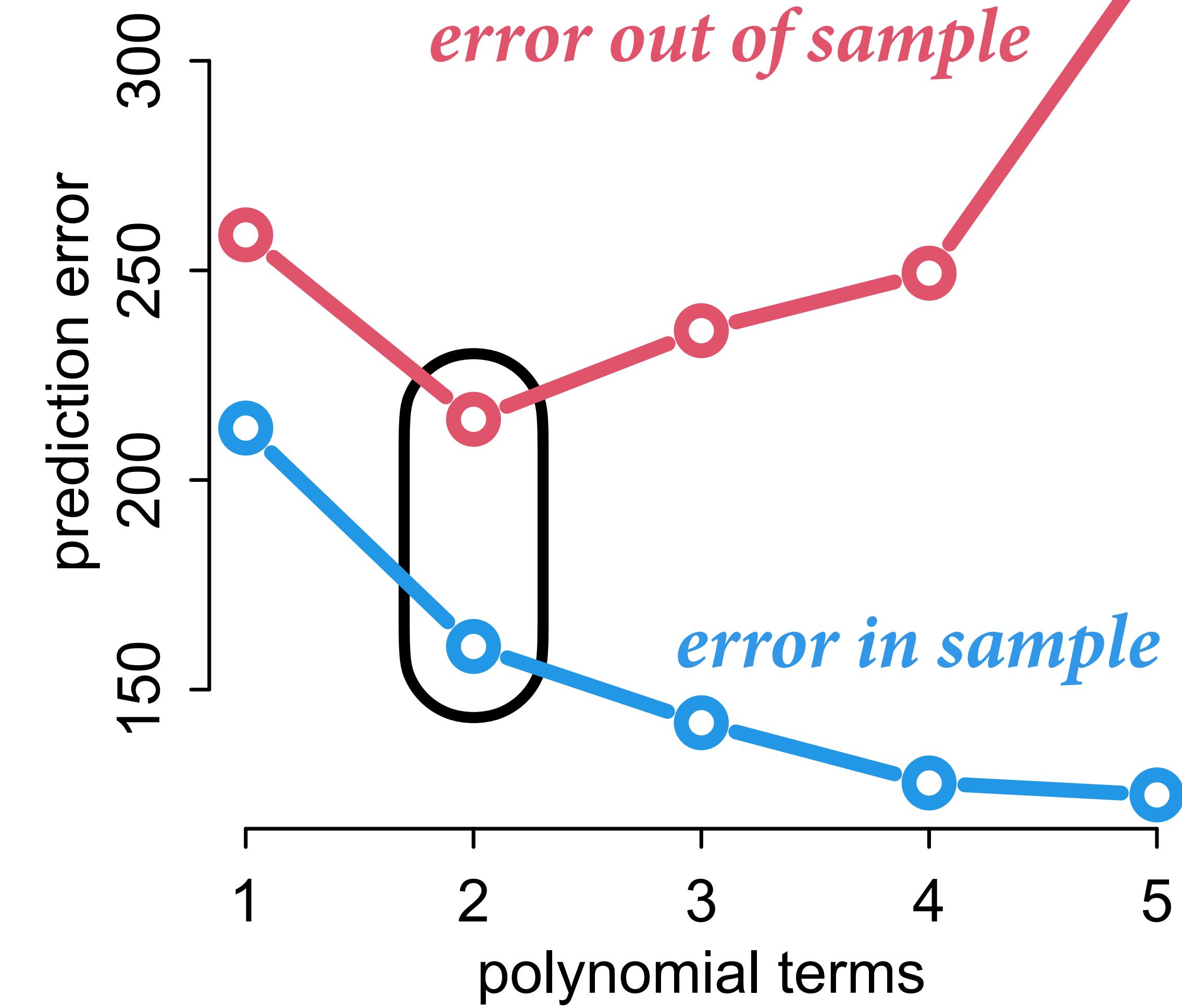
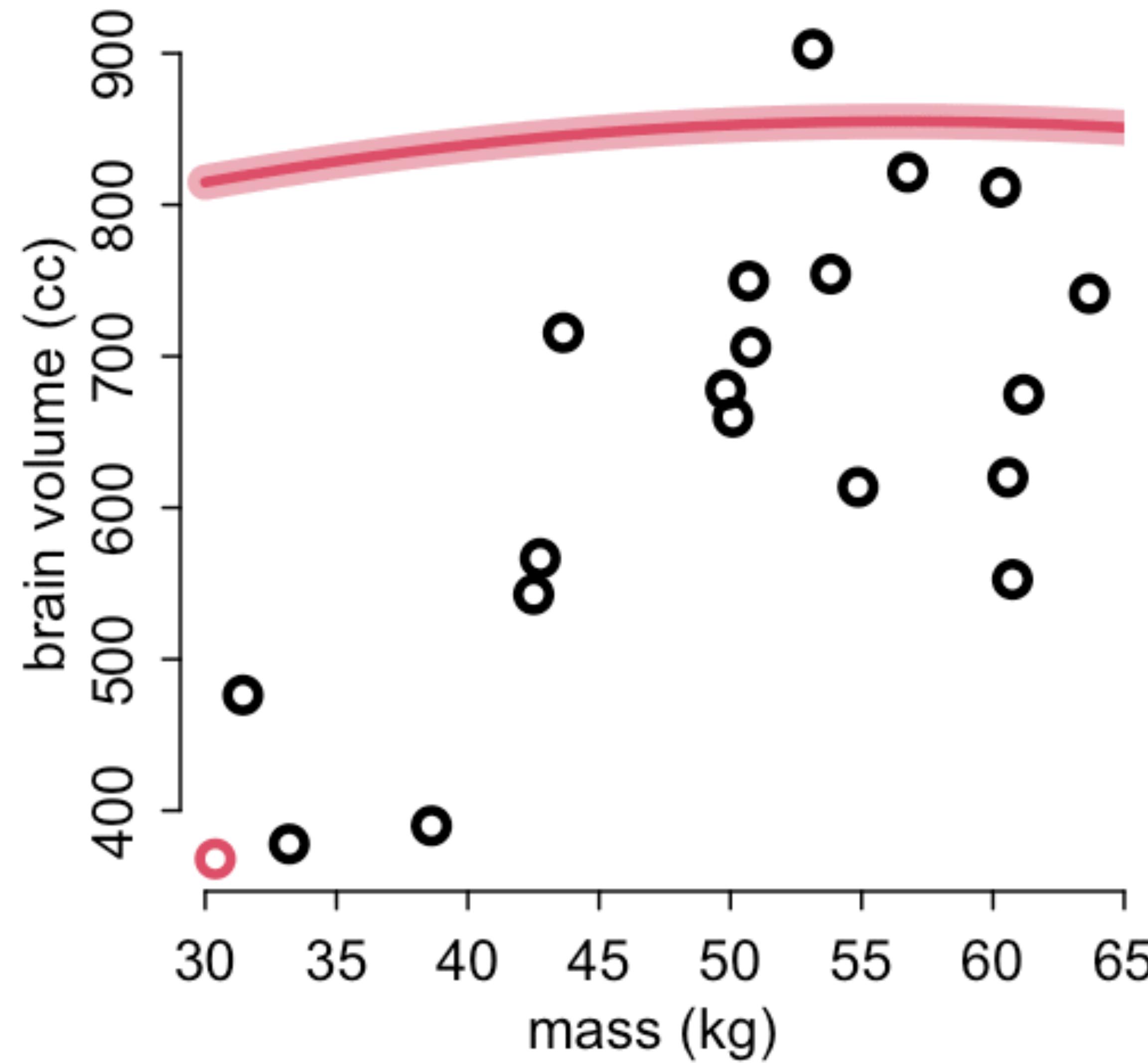


## 2nd degree polynomial



*error out of sample*  
*error in sample*

## 2nd degree polynomial



# Regularization

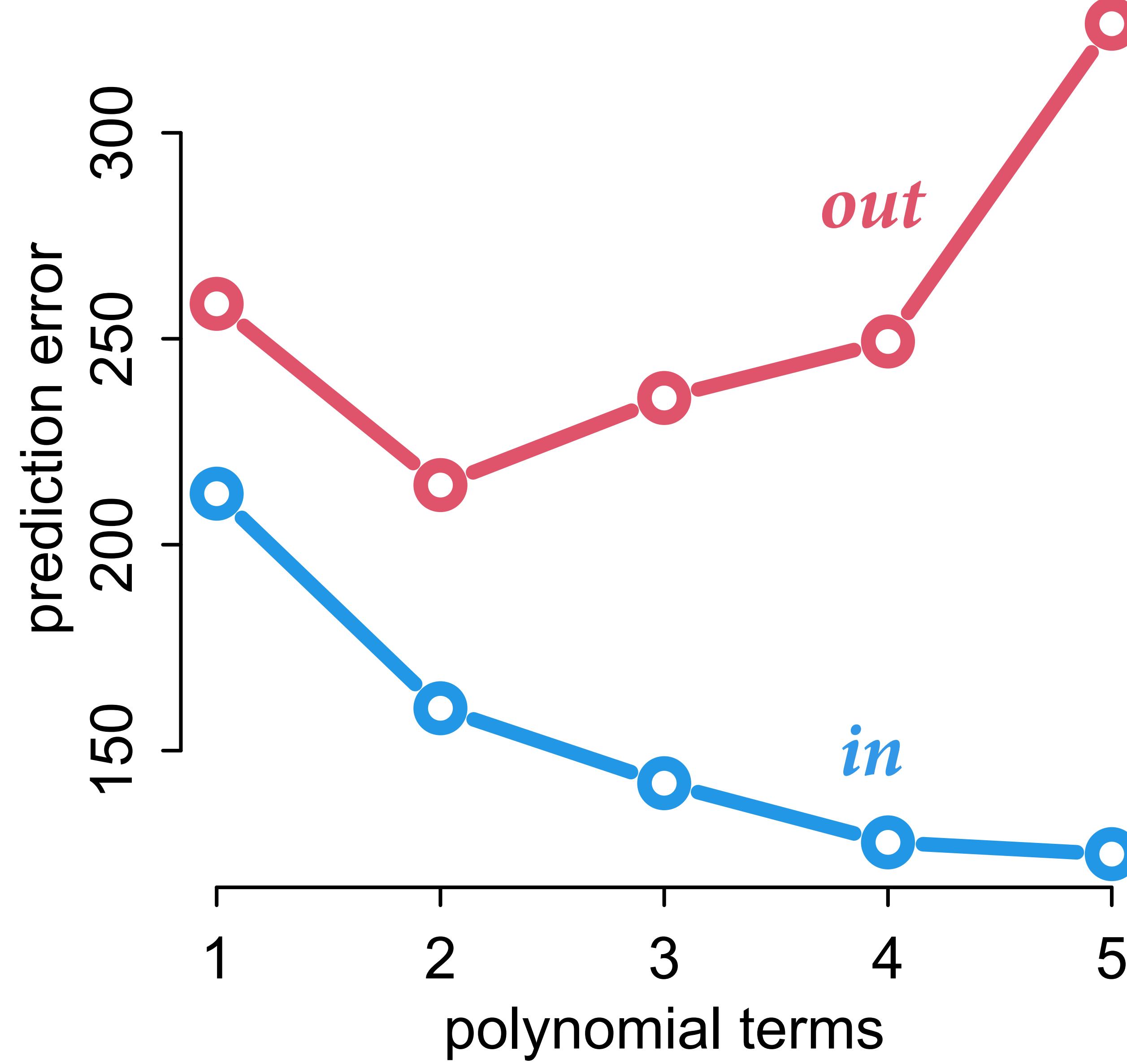
Overfitting depends upon the priors

Skeptical priors have tighter variance, reduce flexibility

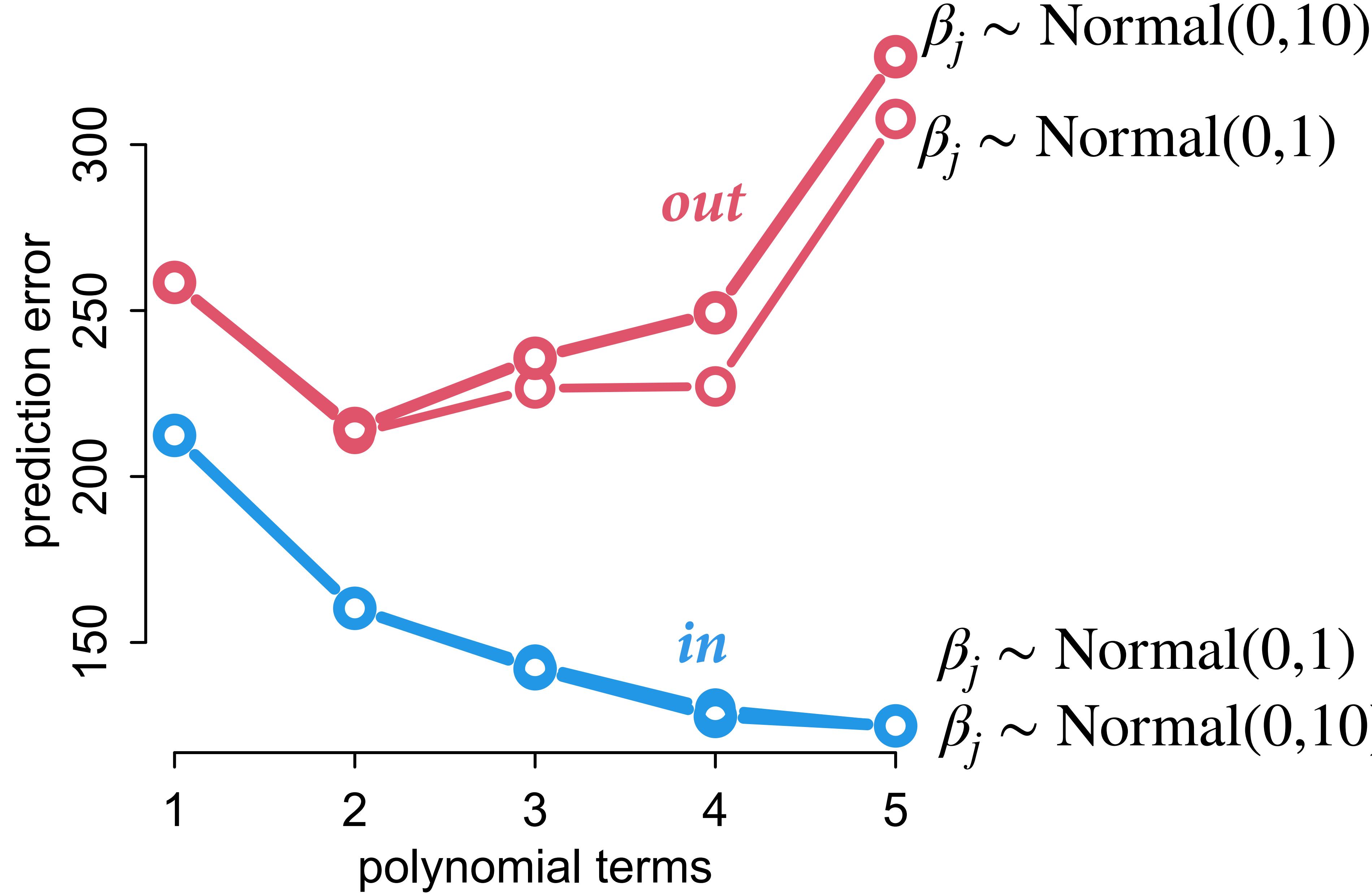
***Regularization***: Function finds regular features of process

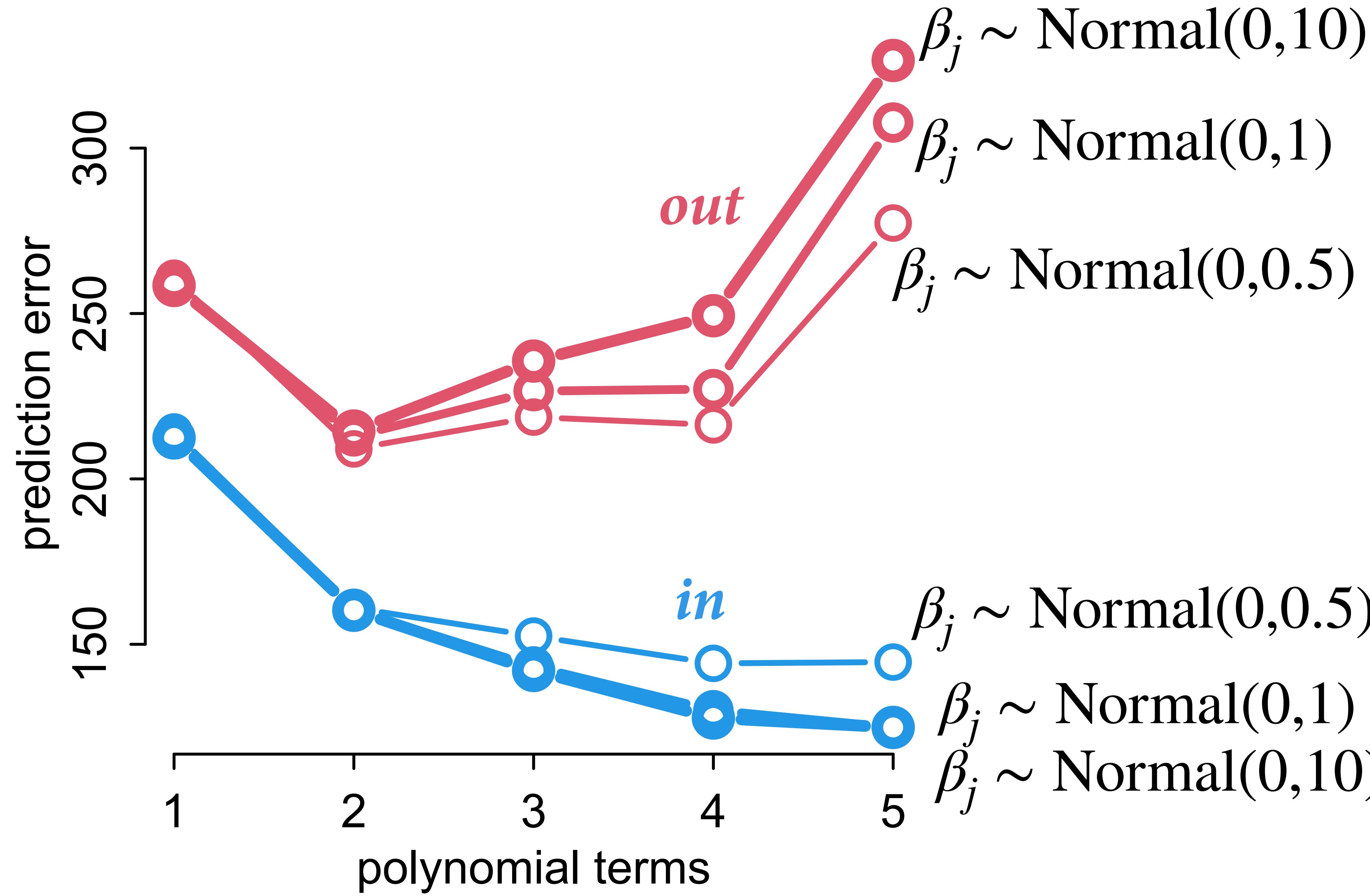
Good priors are often tighter than you think!

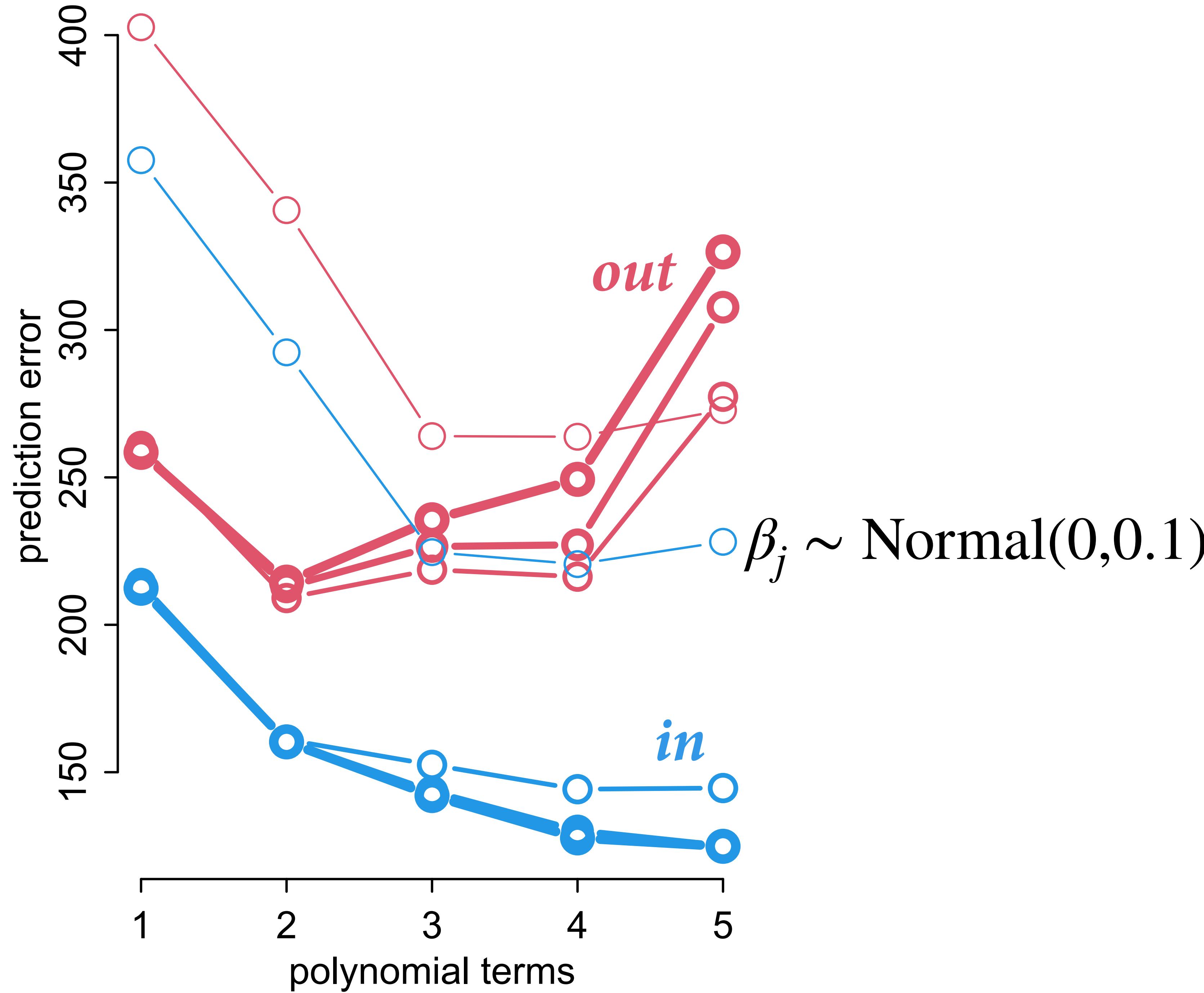




$$\mu_i = \alpha + \sum_{j=1}^m \beta_j x_i^j$$
$$\beta_j \sim \text{Normal}(0, 10)$$







# Regularizing priors

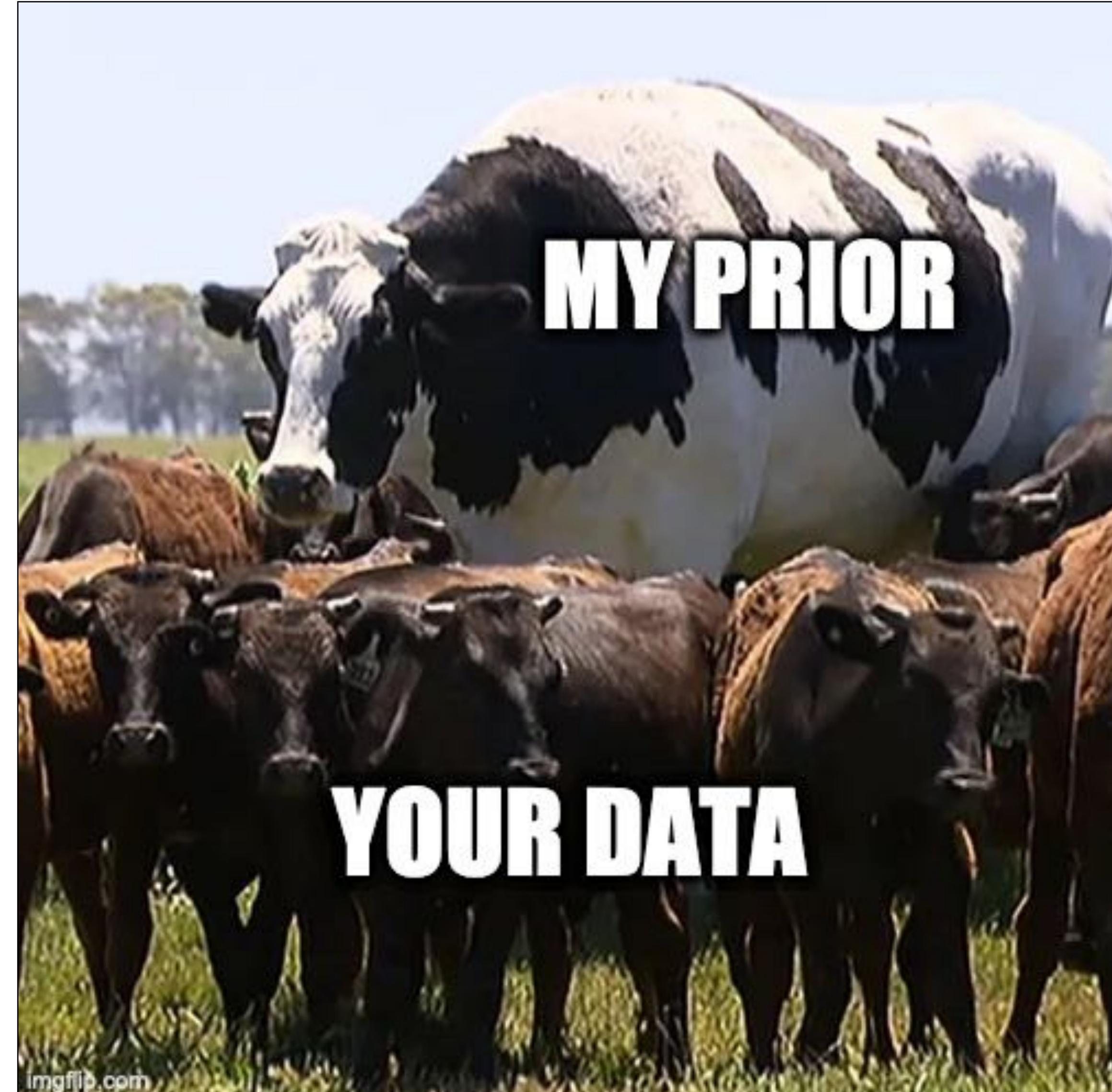
How to choose width of prior?

For causal inference, use science

For pure prediction, can tune the prior using cross-validation

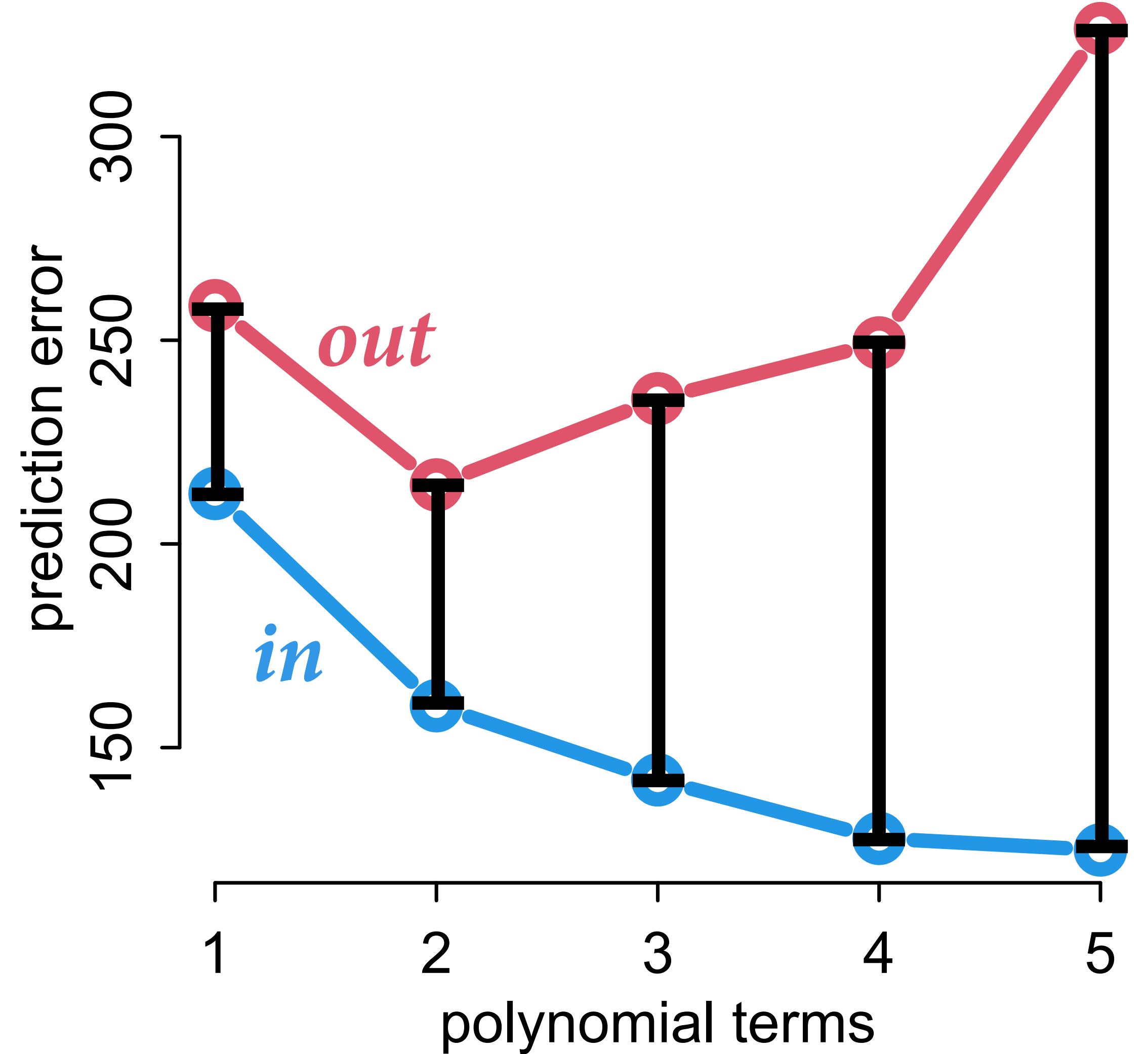
Many tasks are a mix of inference and prediction

No need to be perfect, just better

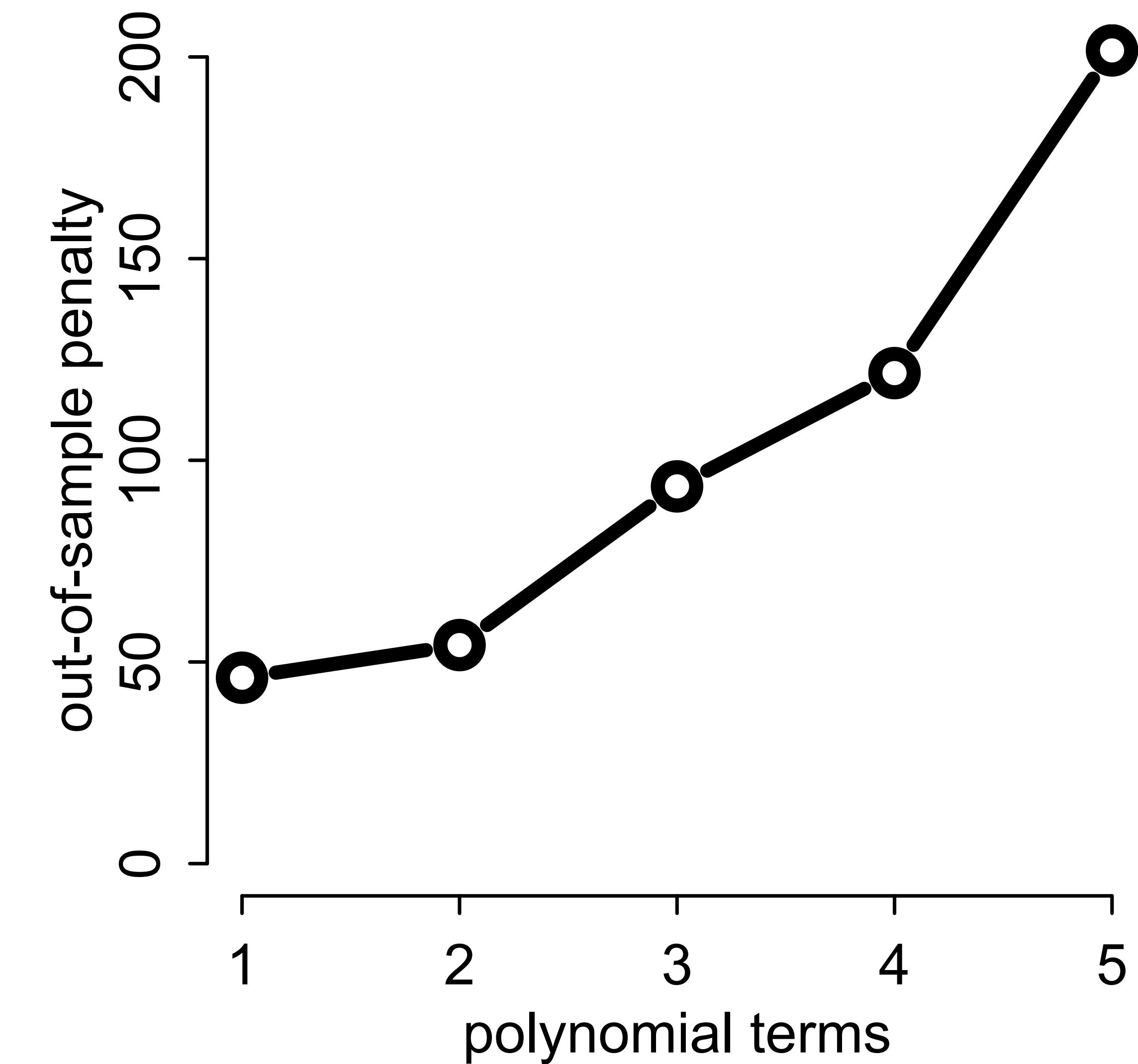
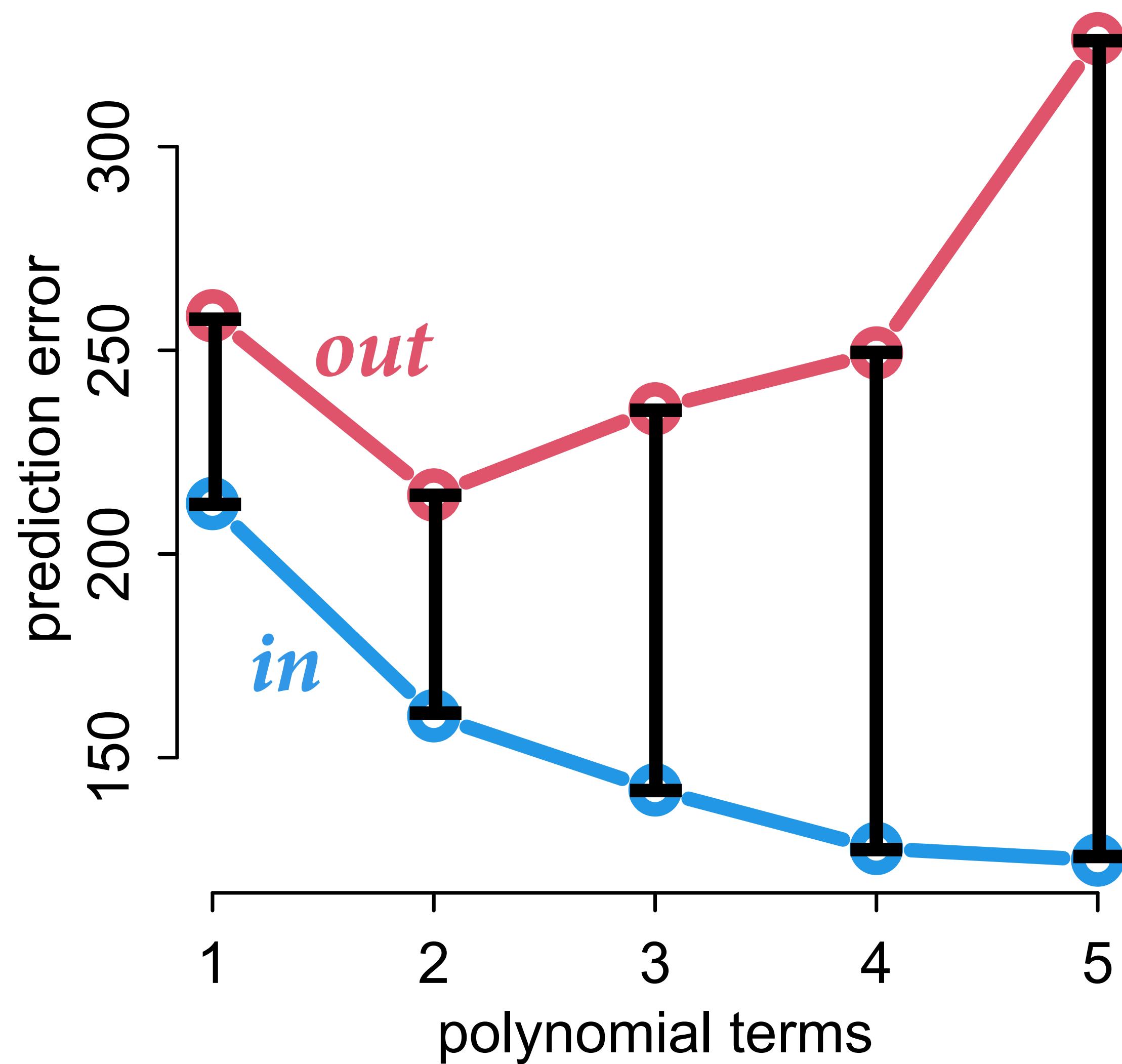


**PAUSE**

# Prediction penalty



# Prediction penalty



# Penalty prediction

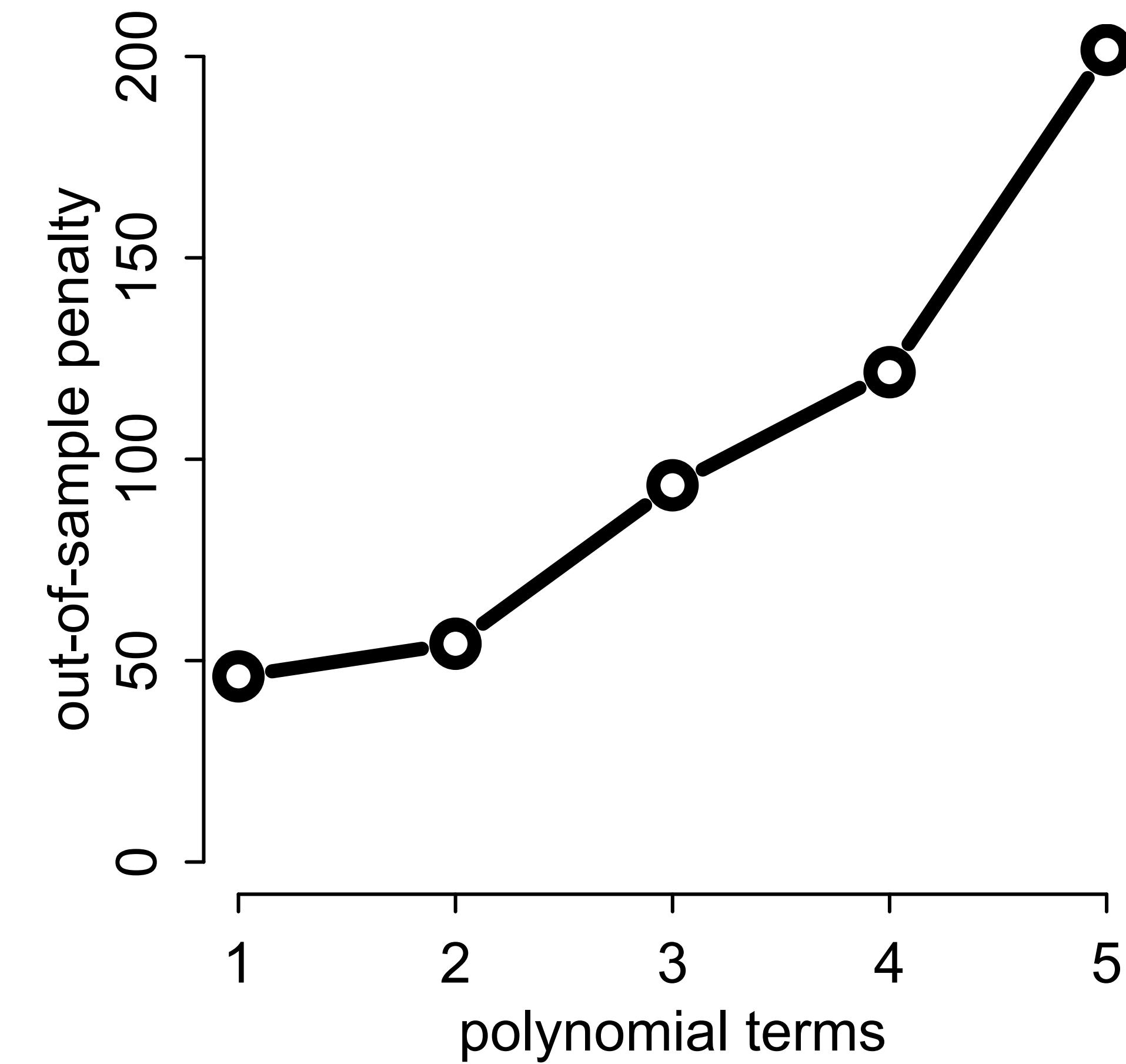
For  $N$  points, cross-validation  
requires fitting  $N$  models

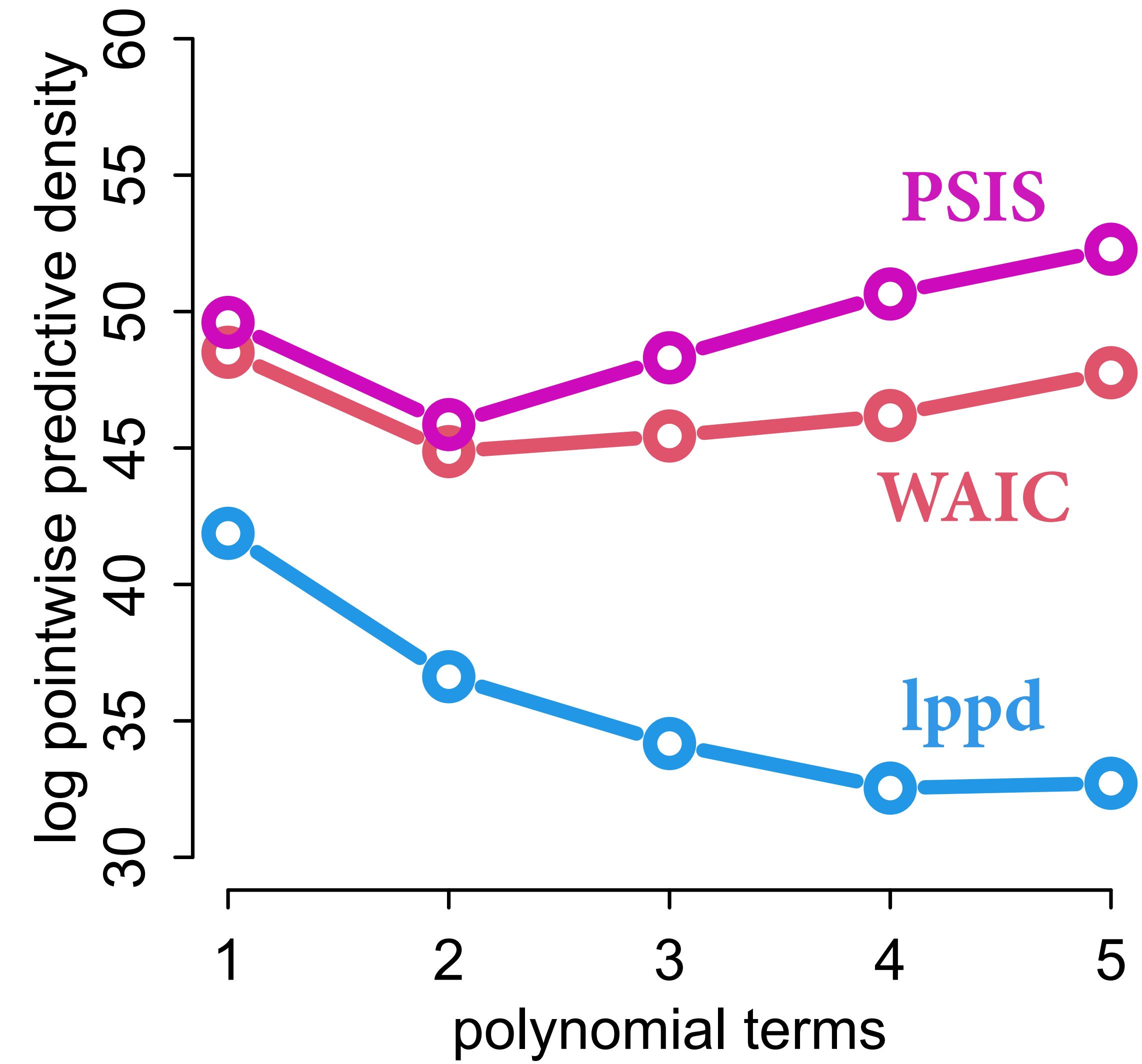
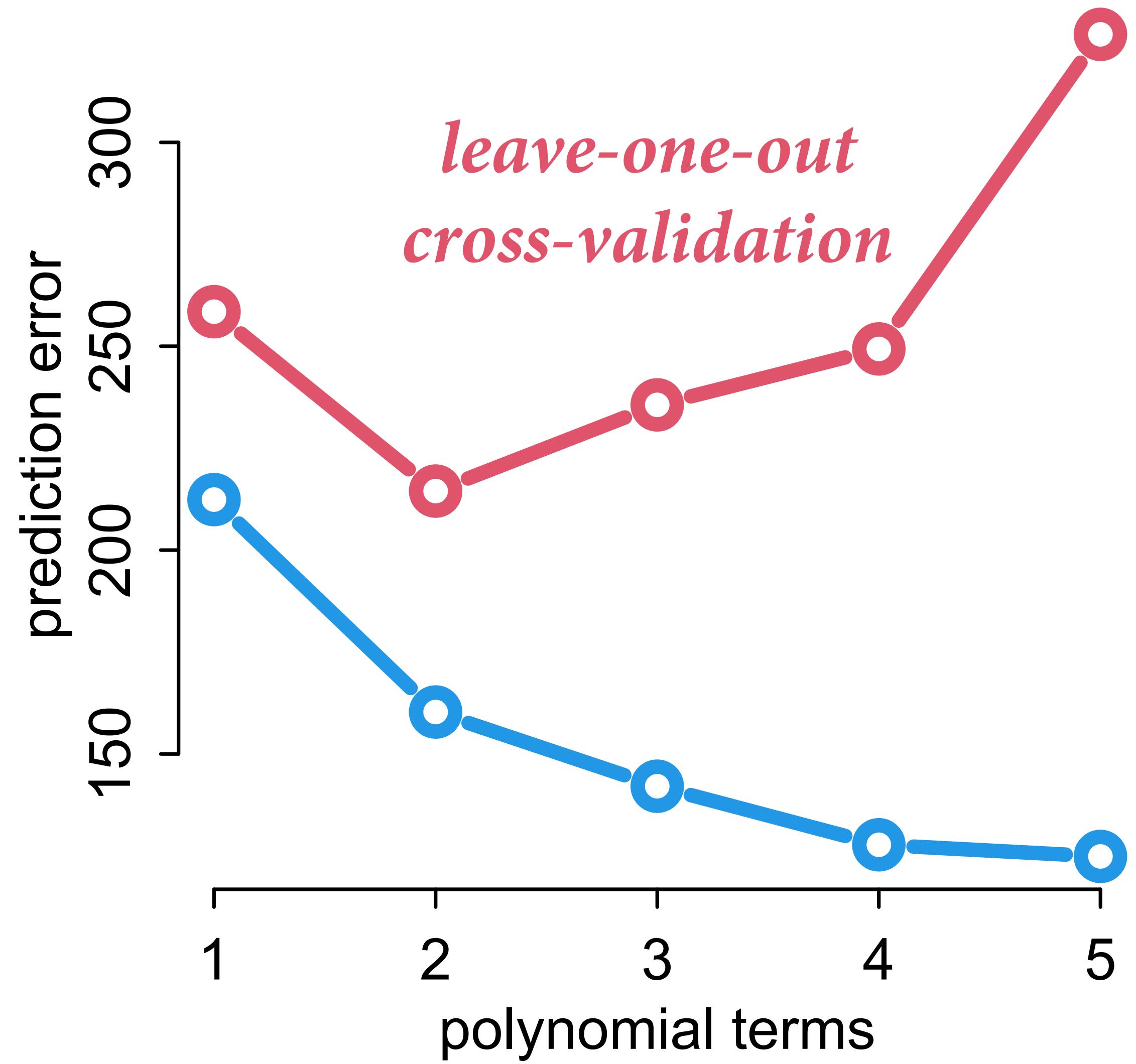
What if you could estimate the  
penalty from a single model fit?

Good news! You can:

Importance sampling (PSIS)

Information criteria (WAIC)





WAIC,PSIS,CV measure overfitting

Regularization manages overfitting

None directly address causal  
inference

Important for  
understanding  
statistical inference

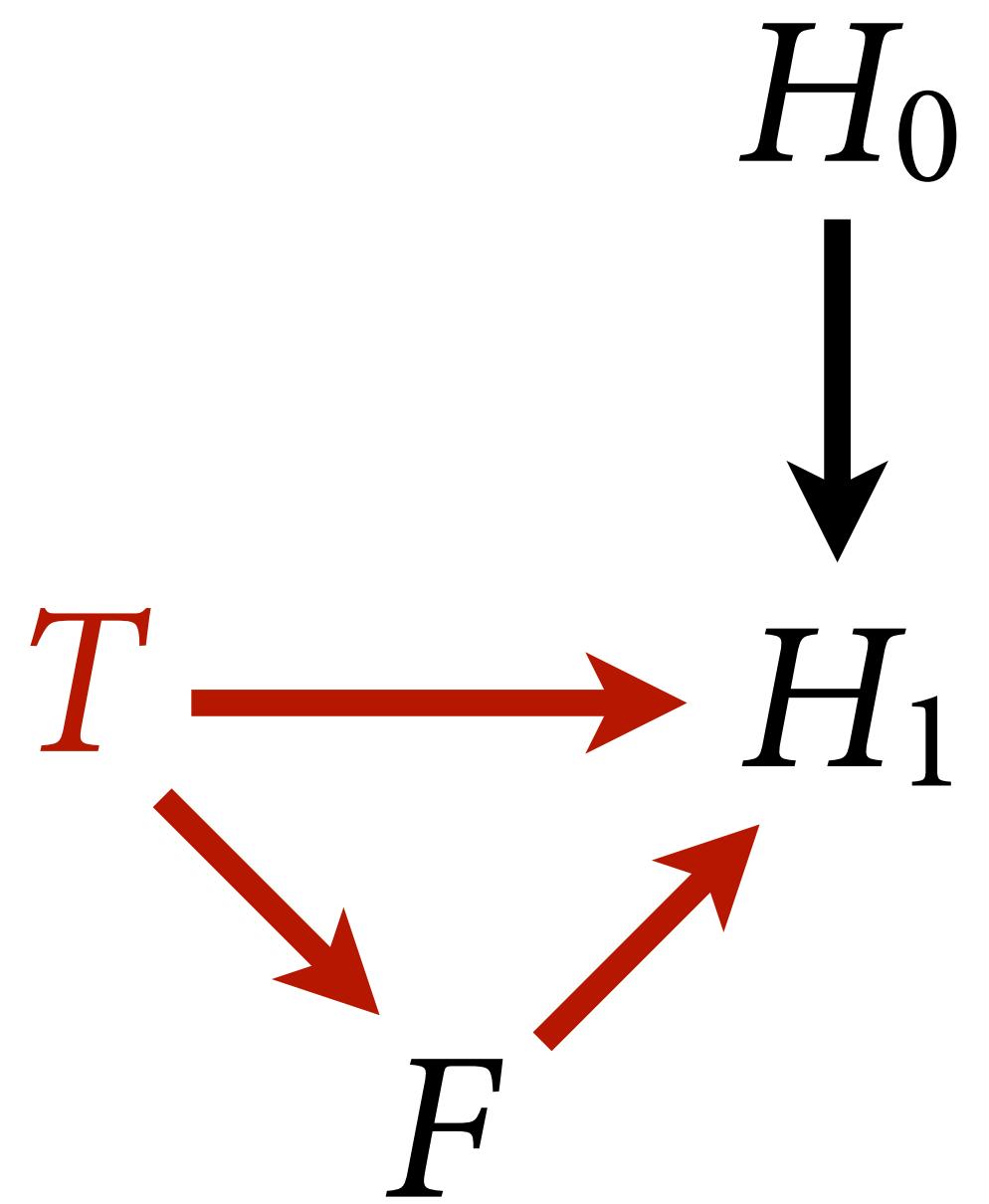


# Model Mis-selection

Do not use predictive criteria (WAIC, PSIS, CV) to choose a causal estimate

Predictive criteria actually prefer confounds & colliders

Example: Plant growth experiment

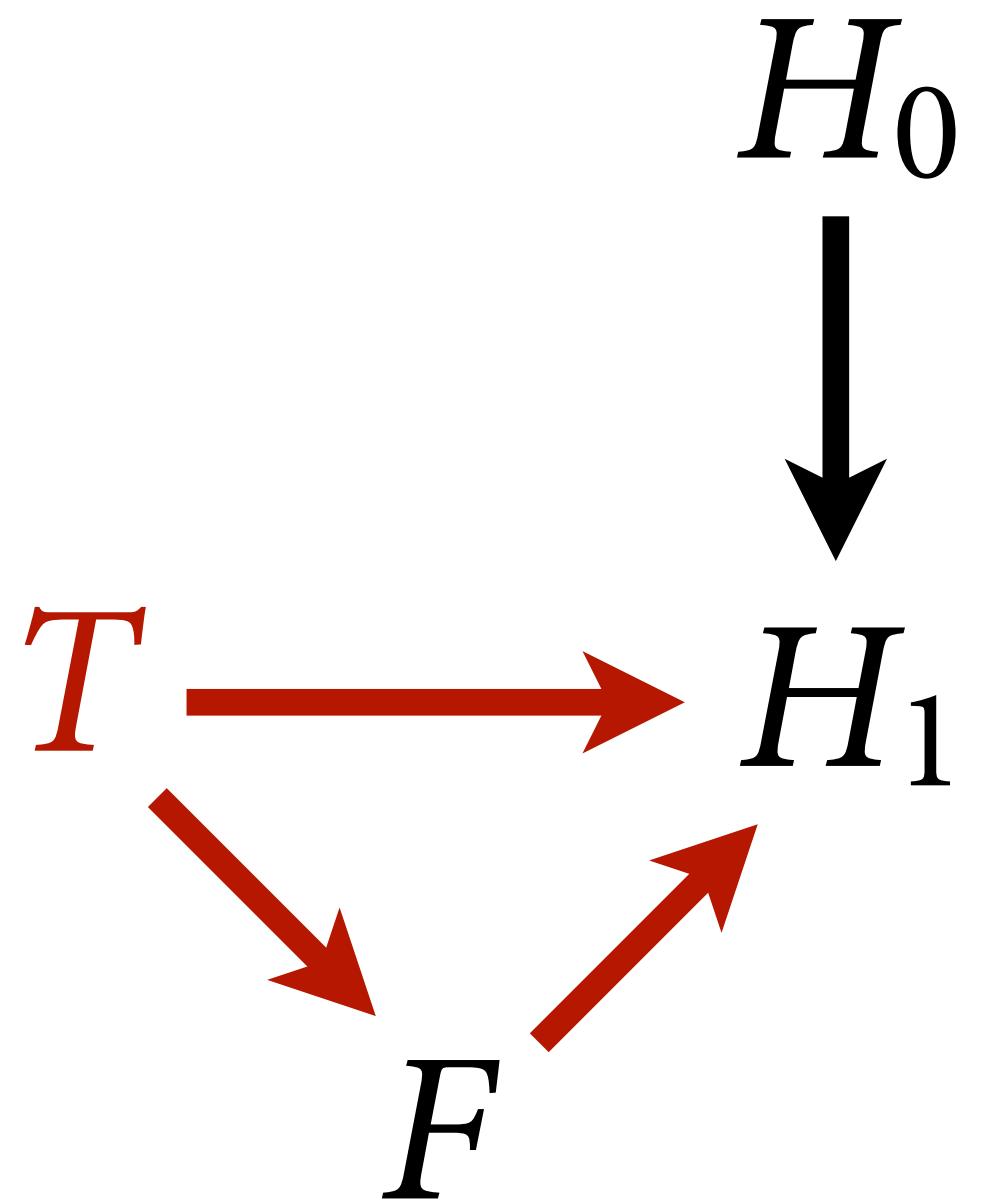


$$H_1 \sim \text{Normal}(\mu_i, \sigma)$$

$$\mu_i = H_0 \times p_i$$

$$p_i = \alpha + \beta_T T_i + \beta_F F_i$$

*Wrong adjustment set  
for total causal effect of  
treatment (blocks  
mediating path)*



$$H_1 \sim \text{Normal}(\mu_i, \sigma)$$

$$\mu_i = H_0 \times p_i$$

$$p_i = \alpha + \beta_T T_i$$

*Correct adjustment set for  
total causal effect of  
treatment*

$$H_1 \sim \text{Normal}(\mu_i, \sigma)$$

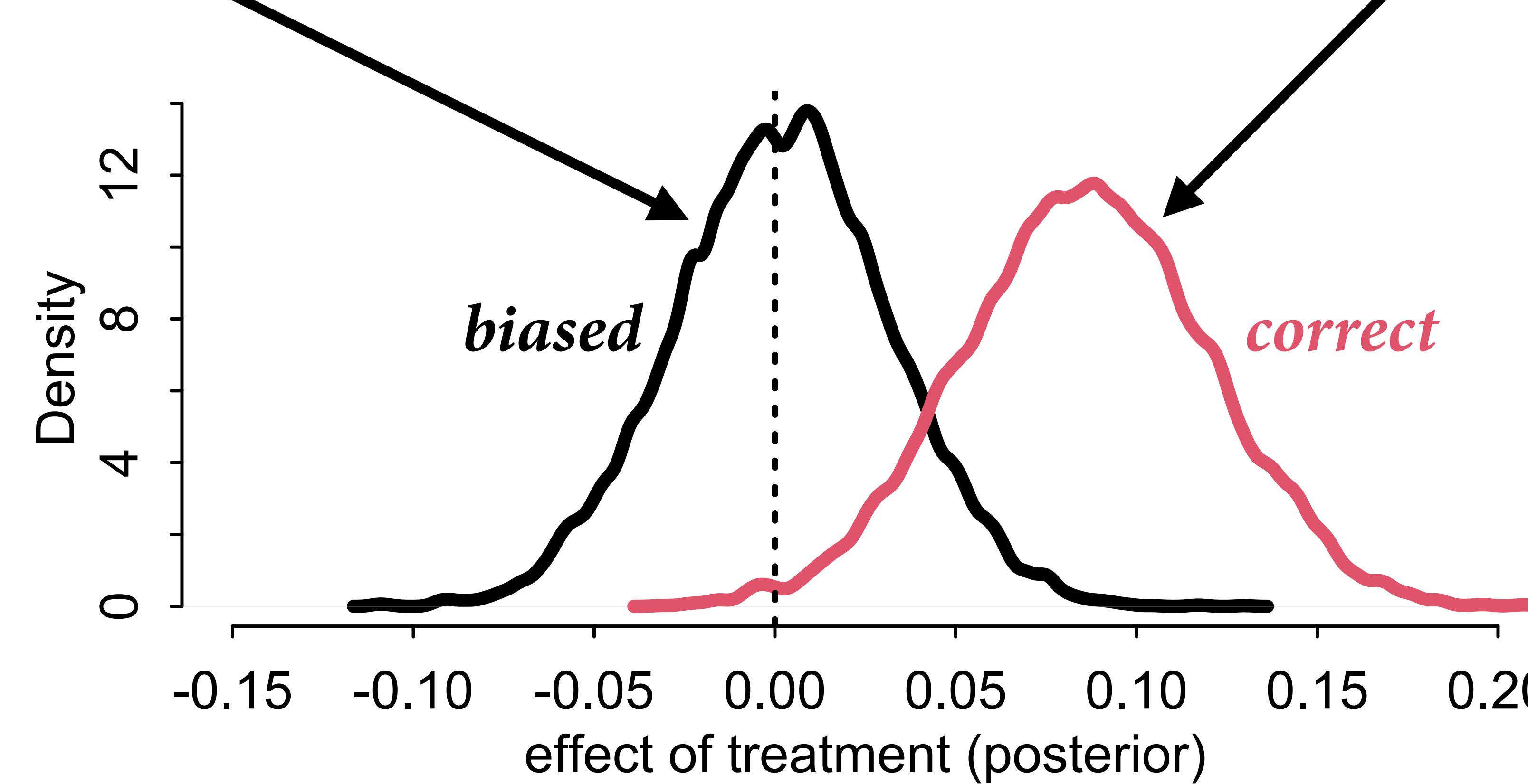
$$\mu_i = H_0 \times p_i$$

$$p_i = \alpha + \beta_T T_i + \beta_F F_i$$

$$H_1 \sim \text{Normal}(\mu_i, \sigma)$$

$$\mu_i = H_0 \times p_i$$

$$p_i = \alpha + \beta_T T_i$$



$$H_1 \sim \text{Normal}(\mu_i, \sigma)$$

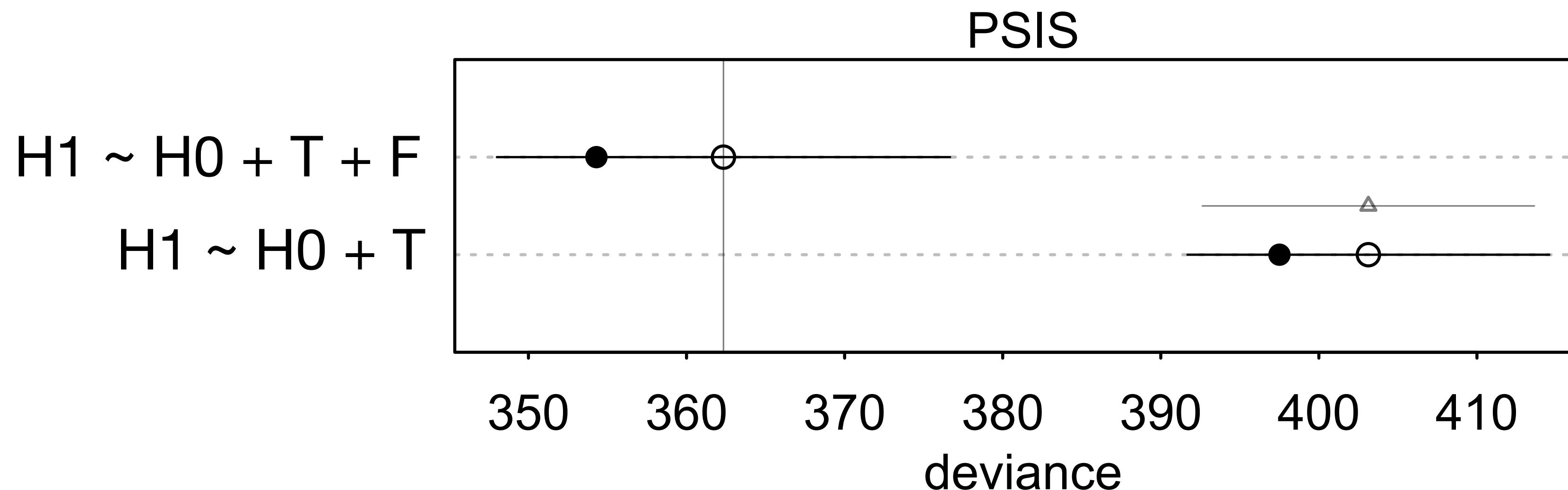
$$\mu_i = H_0 \times p_i$$

$$p_i = \alpha + \beta_T T_i + \beta_F F_i$$

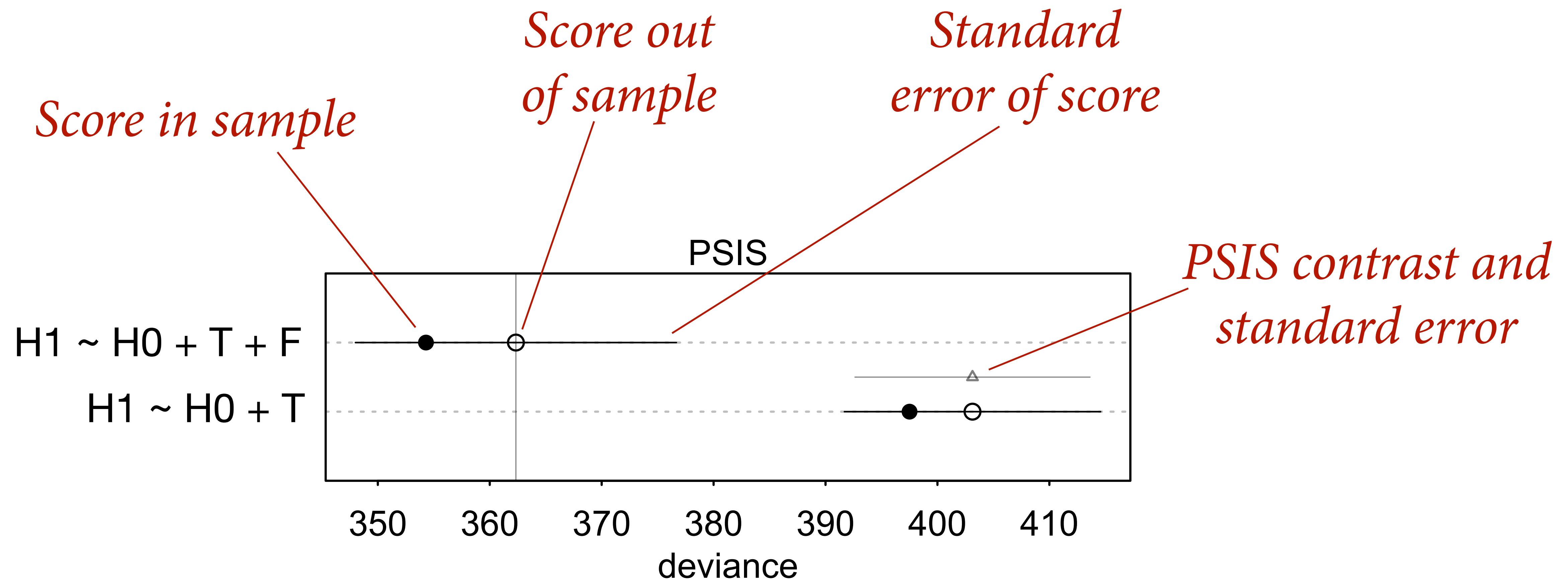
$$H_1 \sim \text{Normal}(\mu_i, \sigma)$$

$$\mu_i = H_0 \times p_i$$

$$p_i = \alpha + \beta_T T_i$$

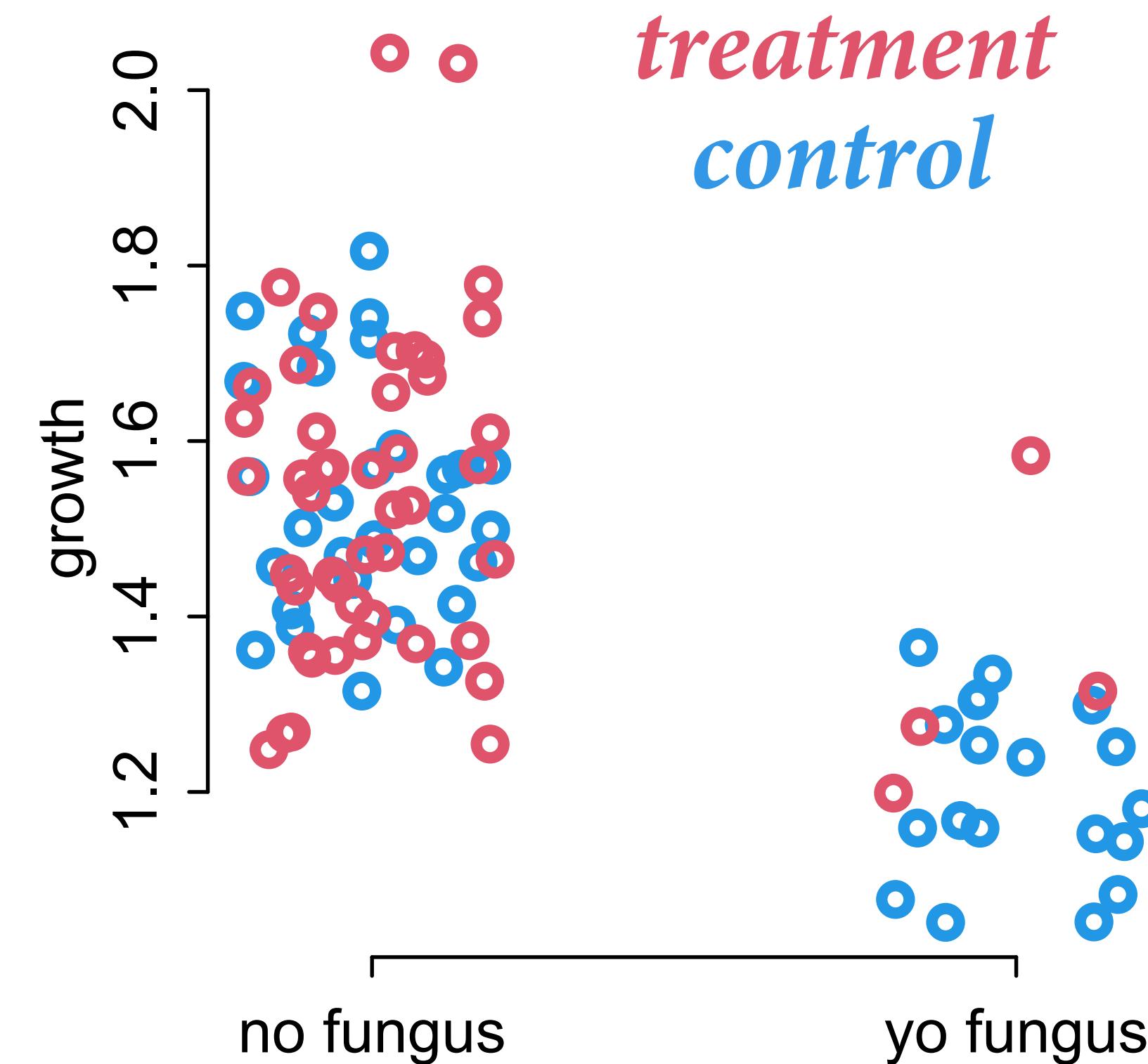
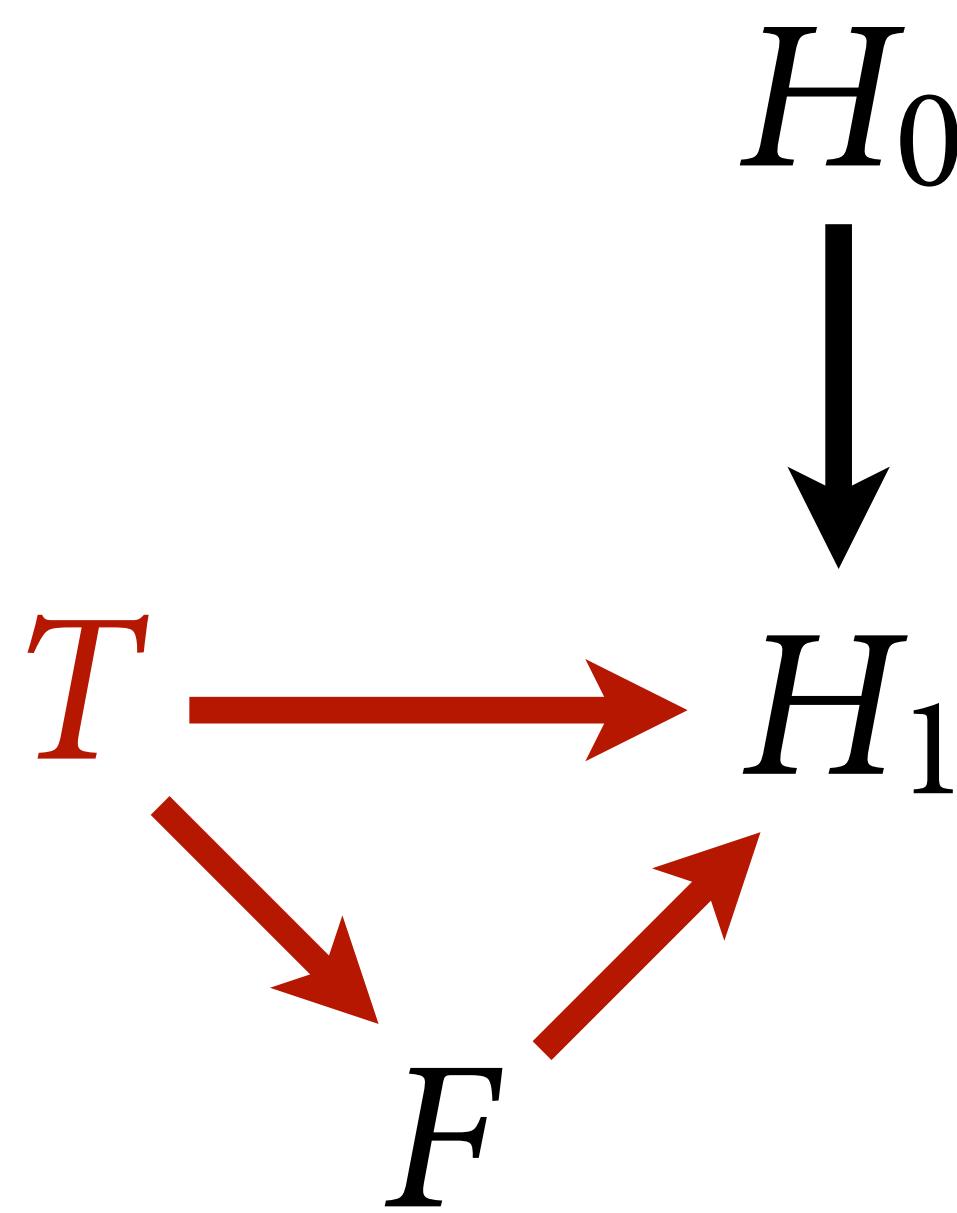


*Wrong model wins at prediction*

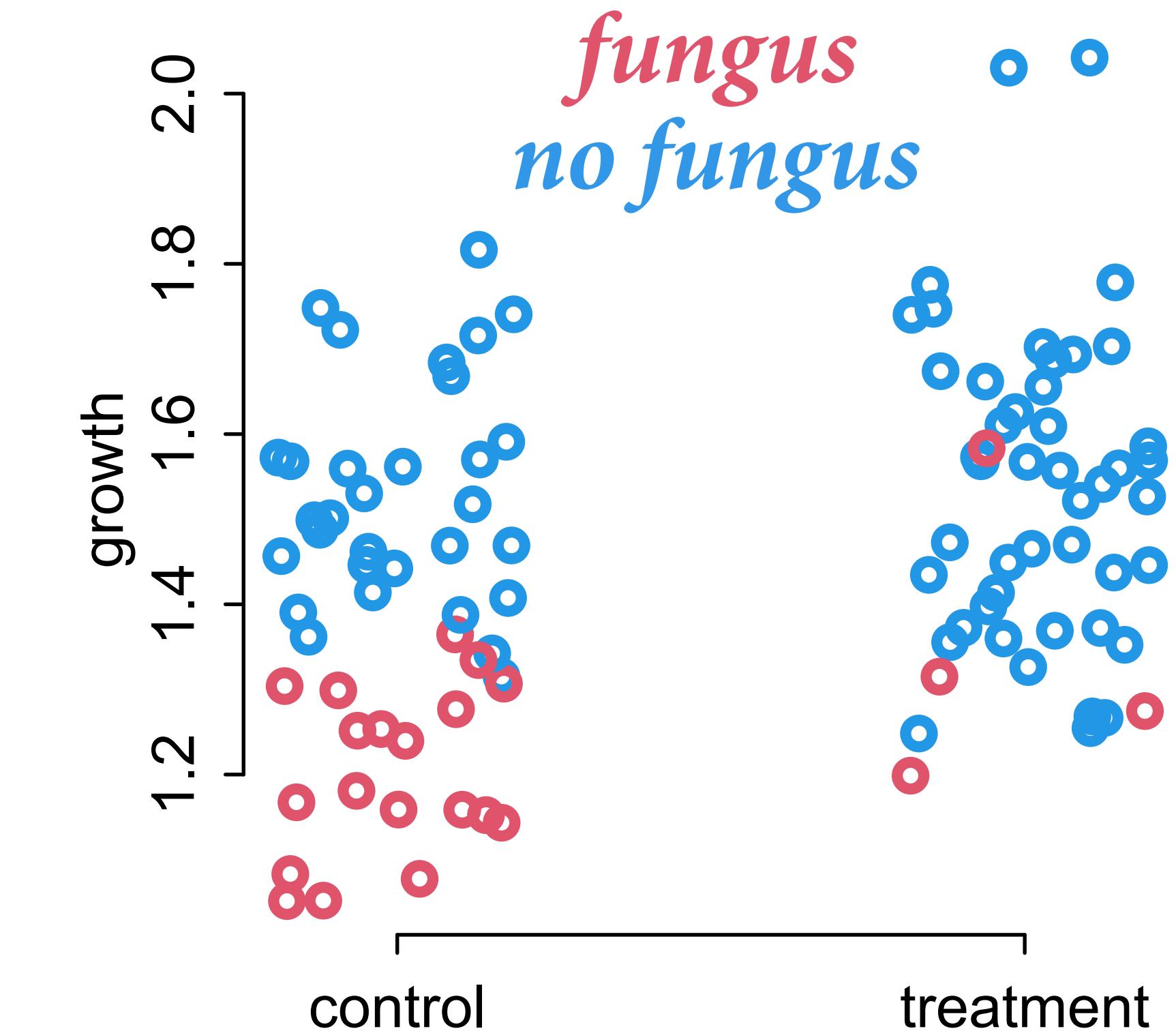
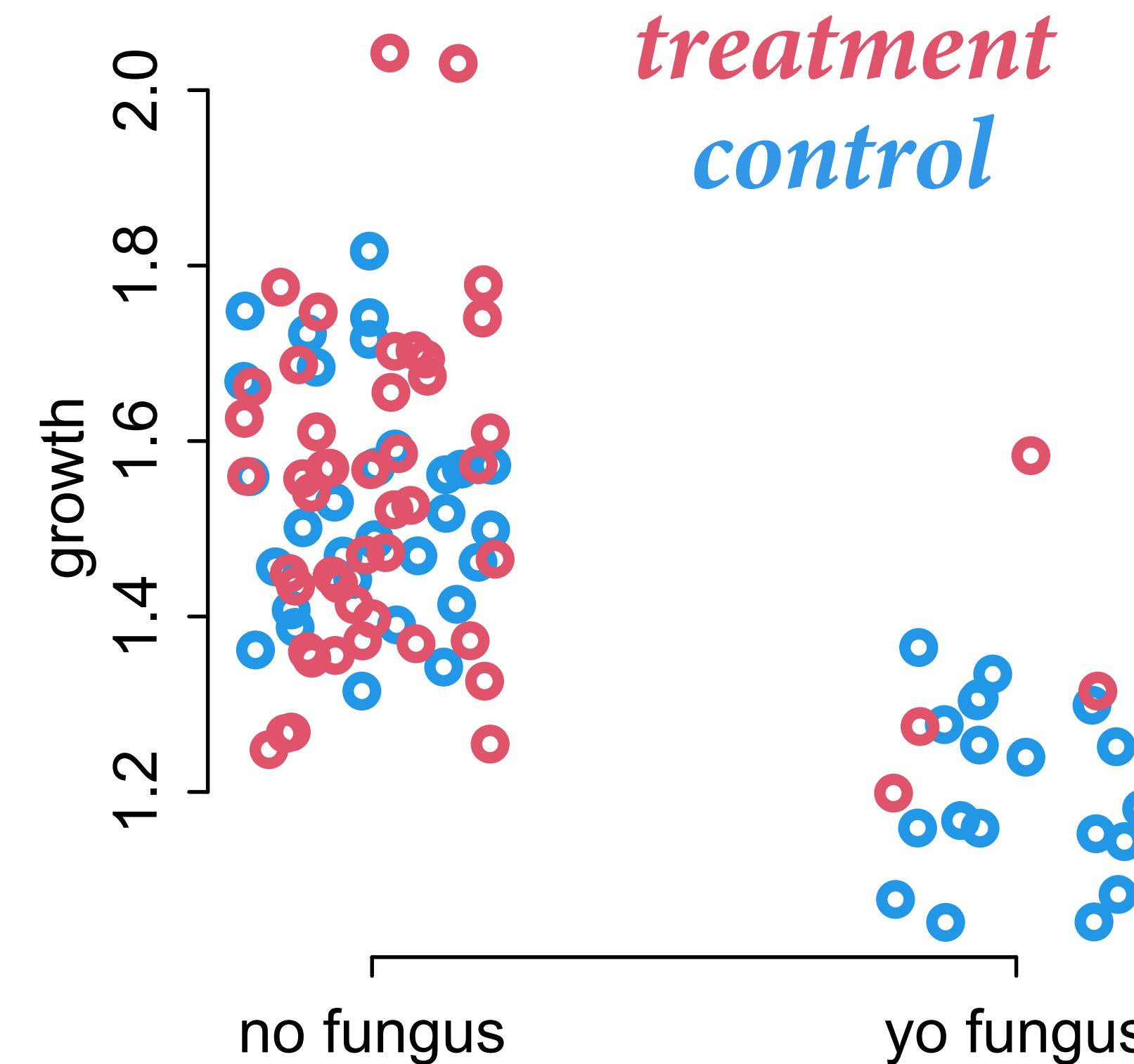
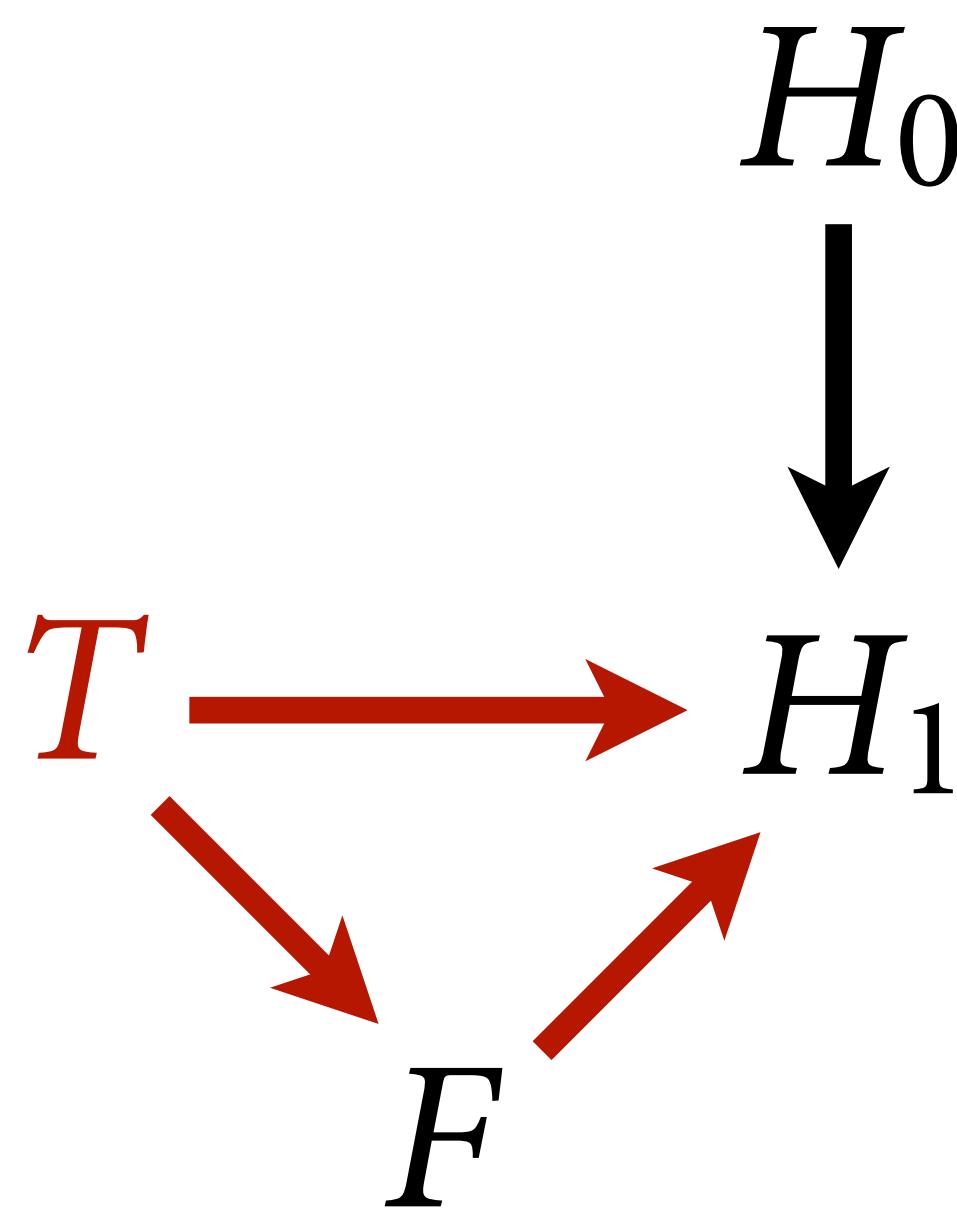


*Wrong model wins at prediction*

# Why does the wrong model win at prediction?



# Why does the wrong model win at prediction?



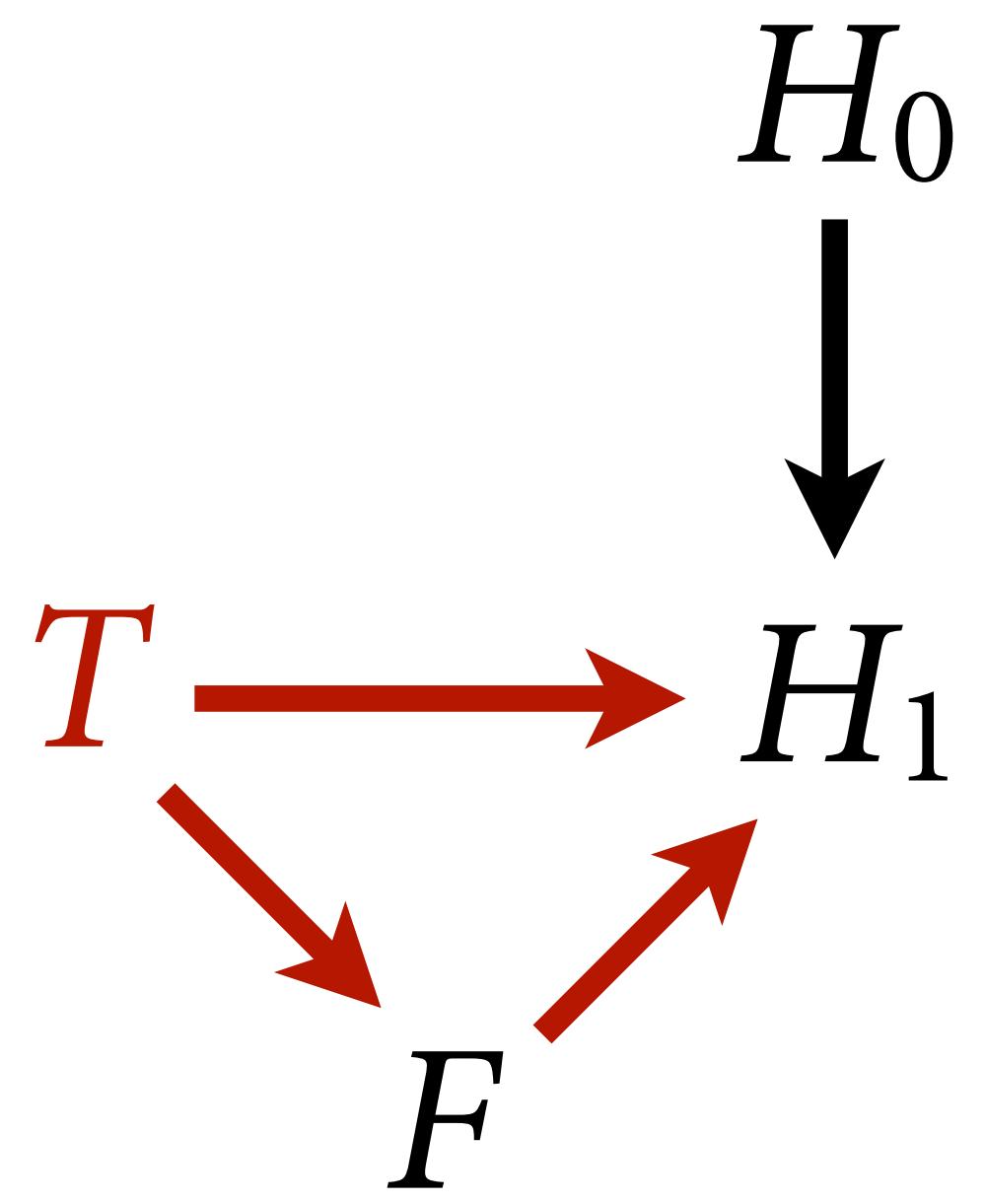
*Fungus is in fact a better predictor than treatment*

# Model Mis-selection

Do not use predictive criteria (WAIC, PSIS, CV) to choose a causal estimate

However, many analyses are mixes of inferential and predictive chores

Still need help finding good functional descriptions while avoiding overfitting



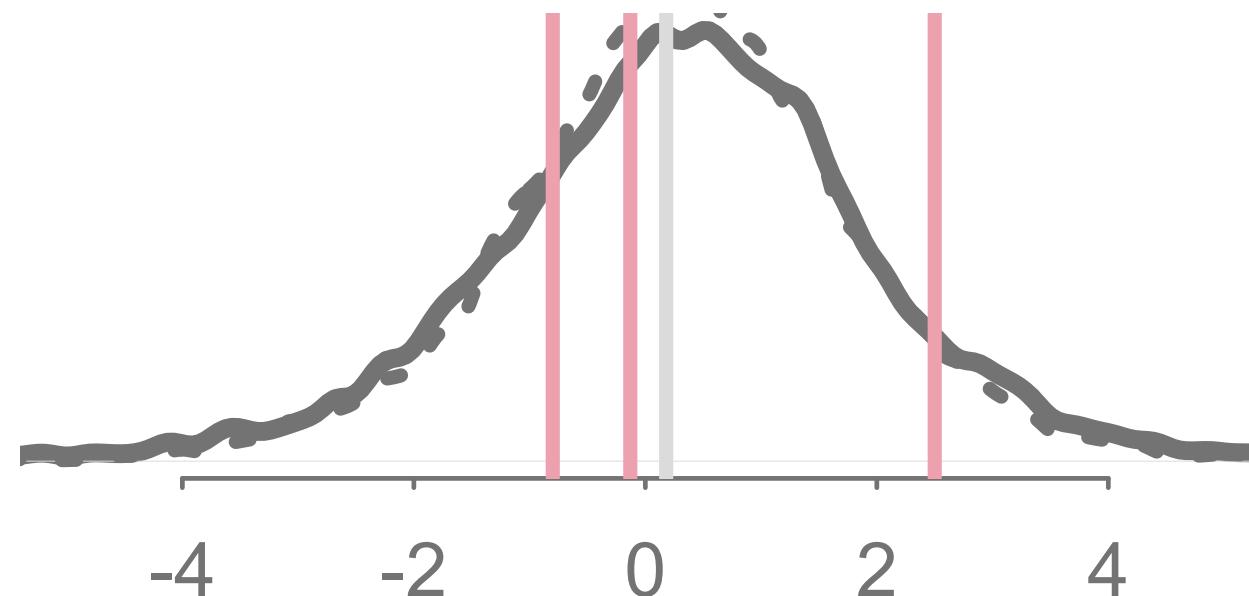
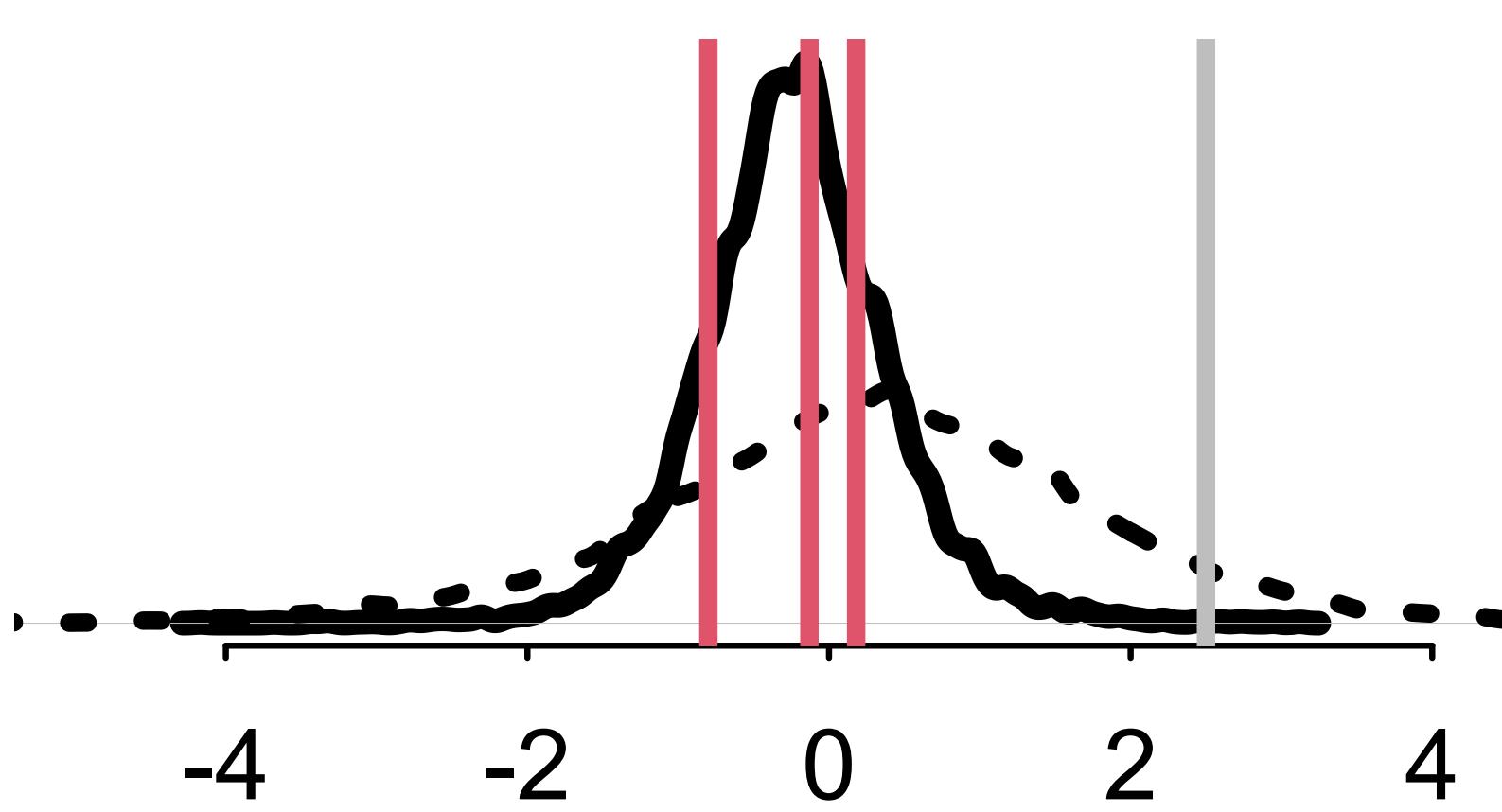
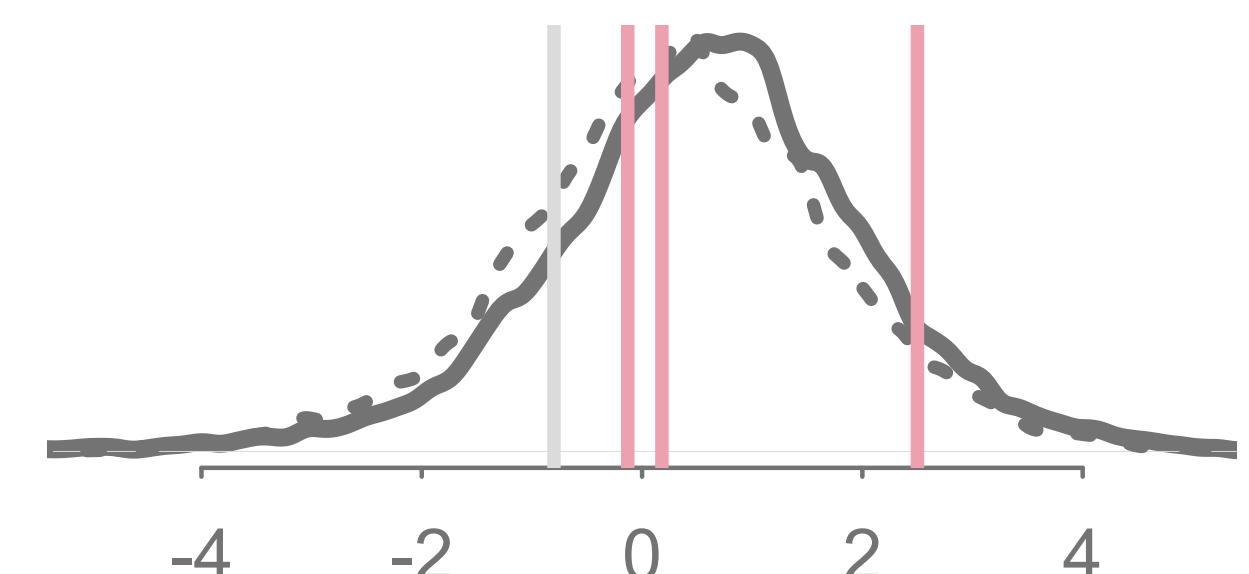
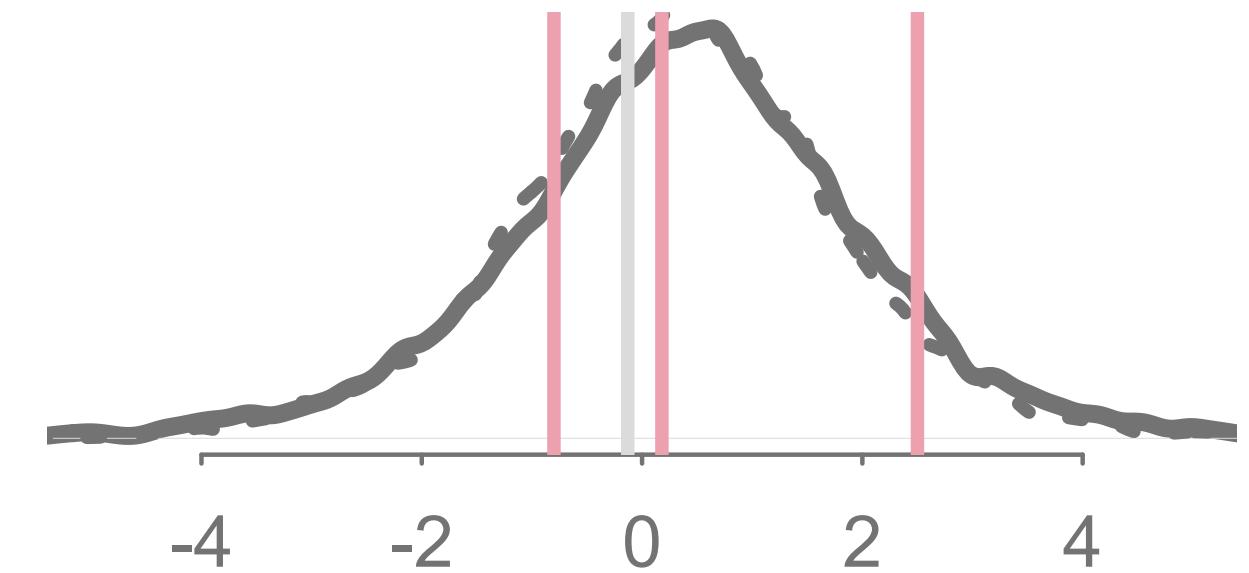
# Outliers & Robust Regression

Some points are more influential than others

“Outliers”: Observations in the tails of predictive distribution

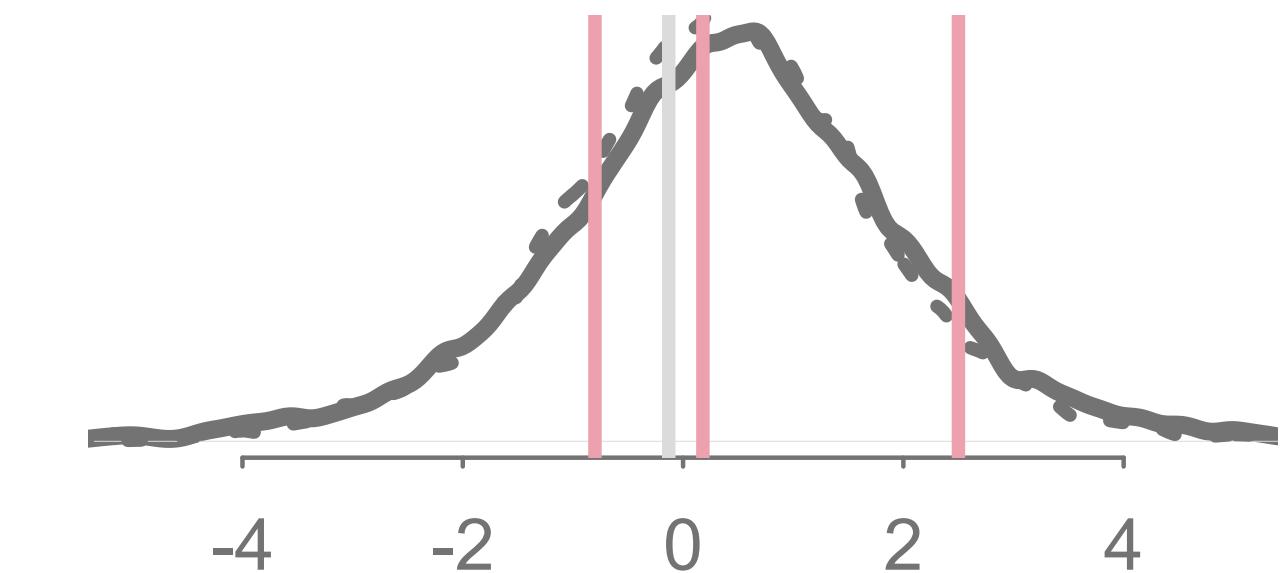
Outliers indicate predictions are possibly overconfident, unreliable

The model doesn’t expect enough variation



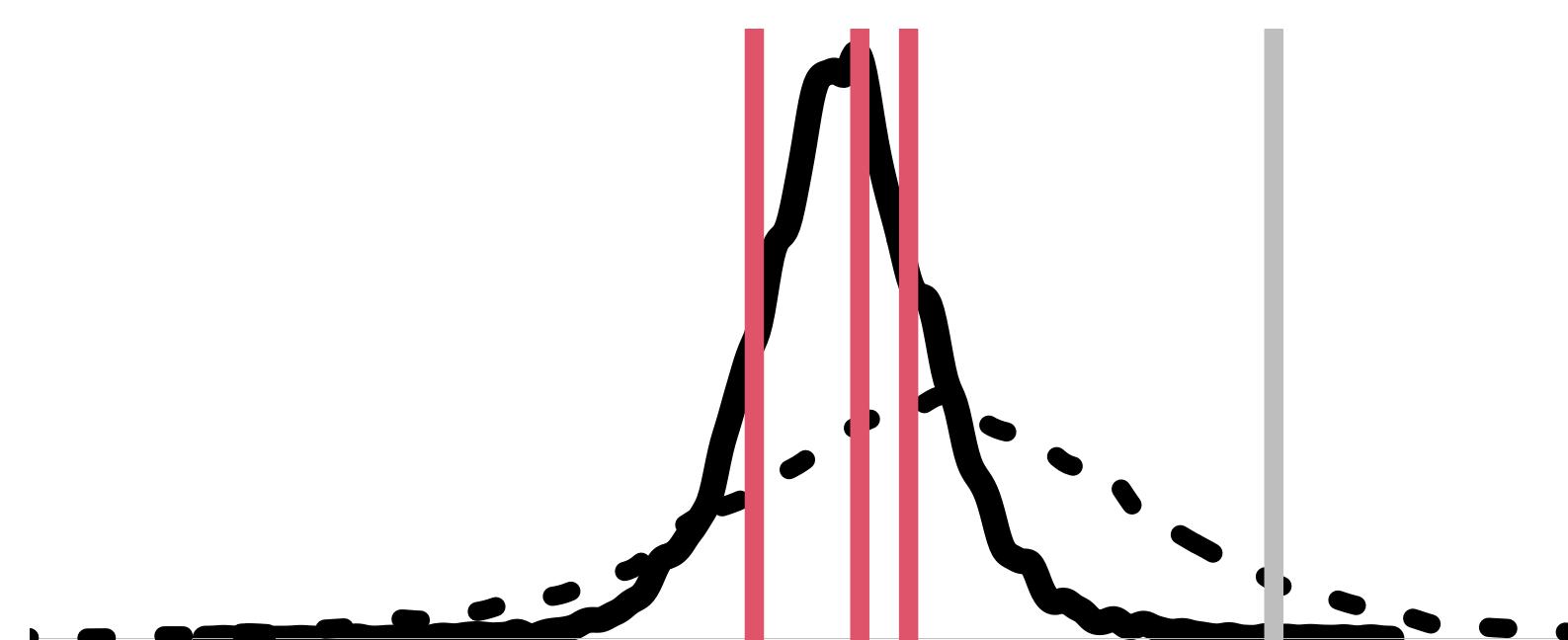
# Outliers & Robust Regression

Dropping outliers is bad: Just ignores the problem; predictions are still bad!

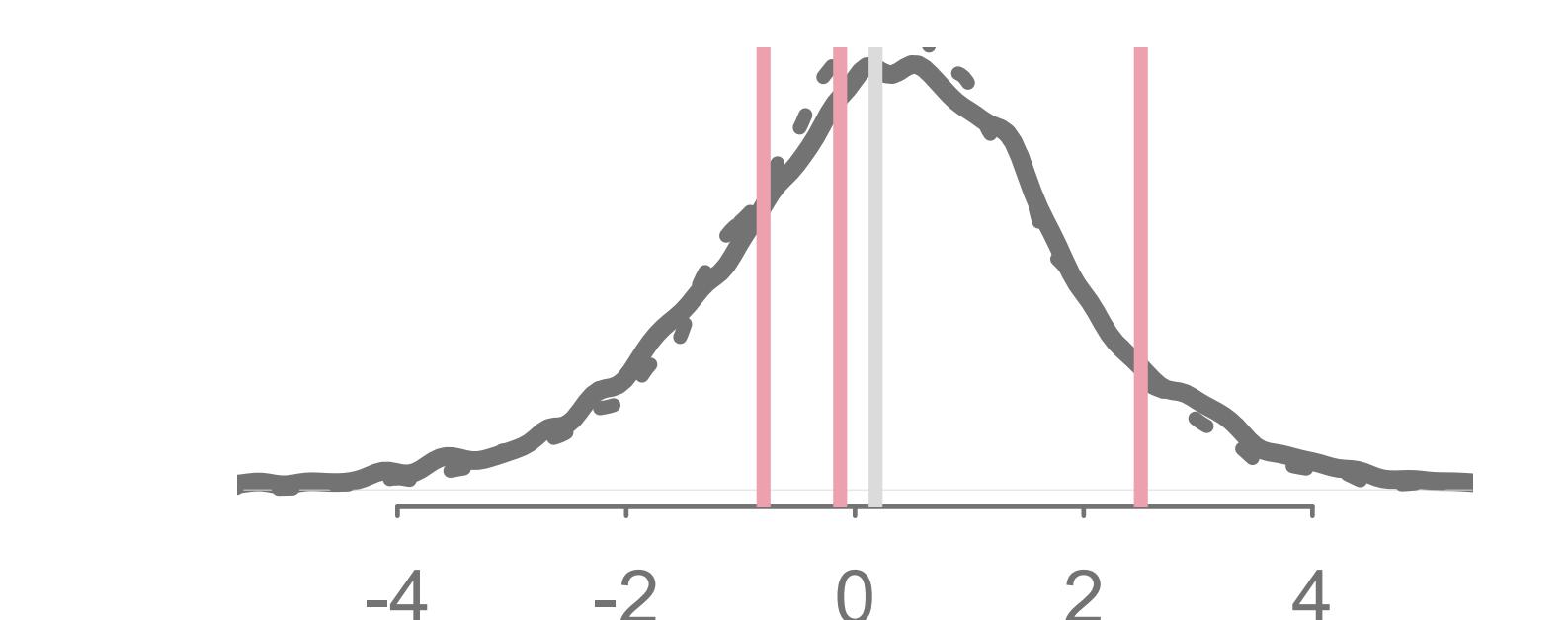


It's the model that's wrong, not the data

First, quantify influence of each point



Second, use a mixture model (robust regression)



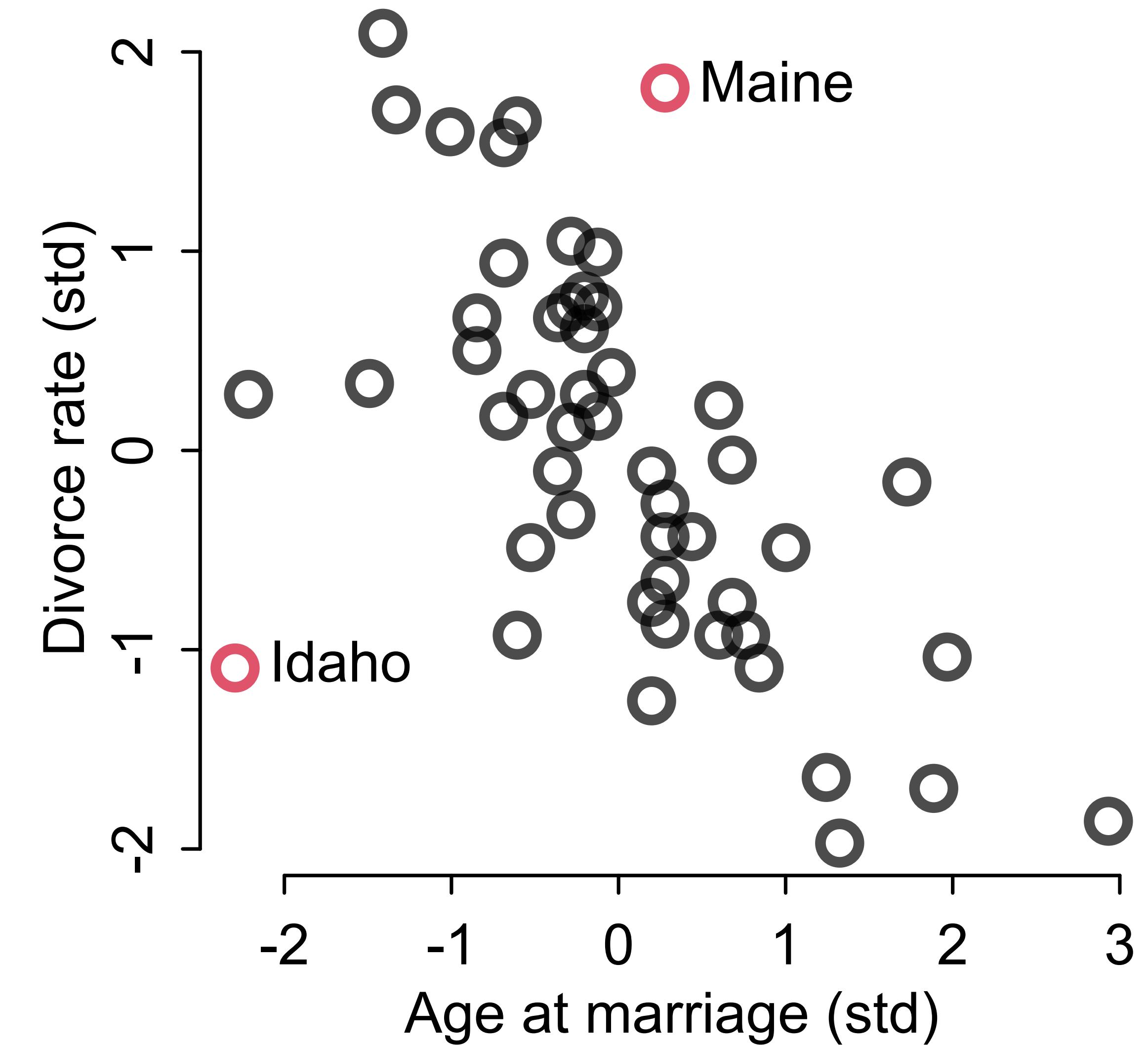
# Outliers & Robust Regression

Divorce rate example

Maine and Idaho both unusual

Maine: high divorce for trend

Idaho: low divorce for trend

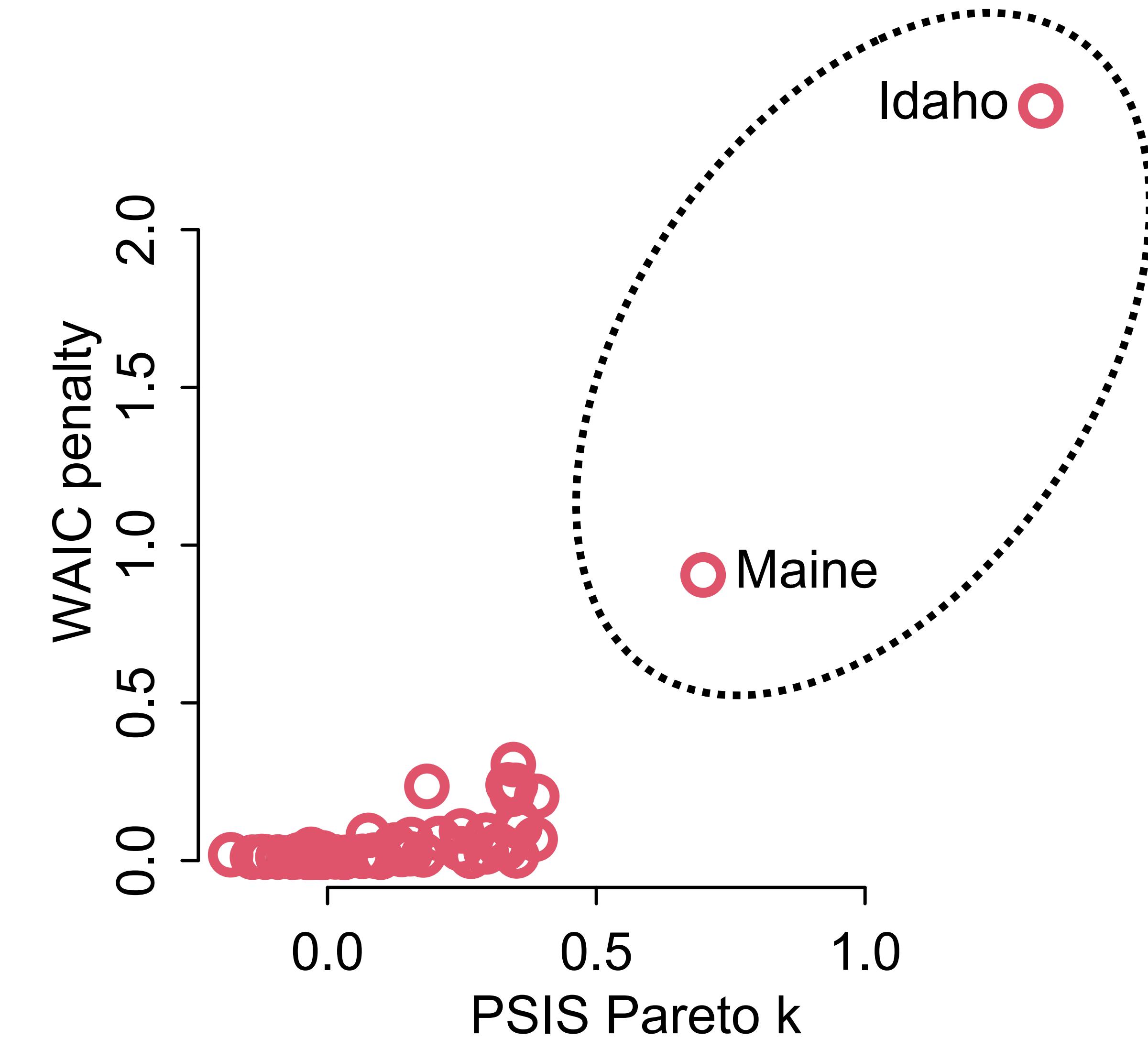


# Outliers & Robust Regression

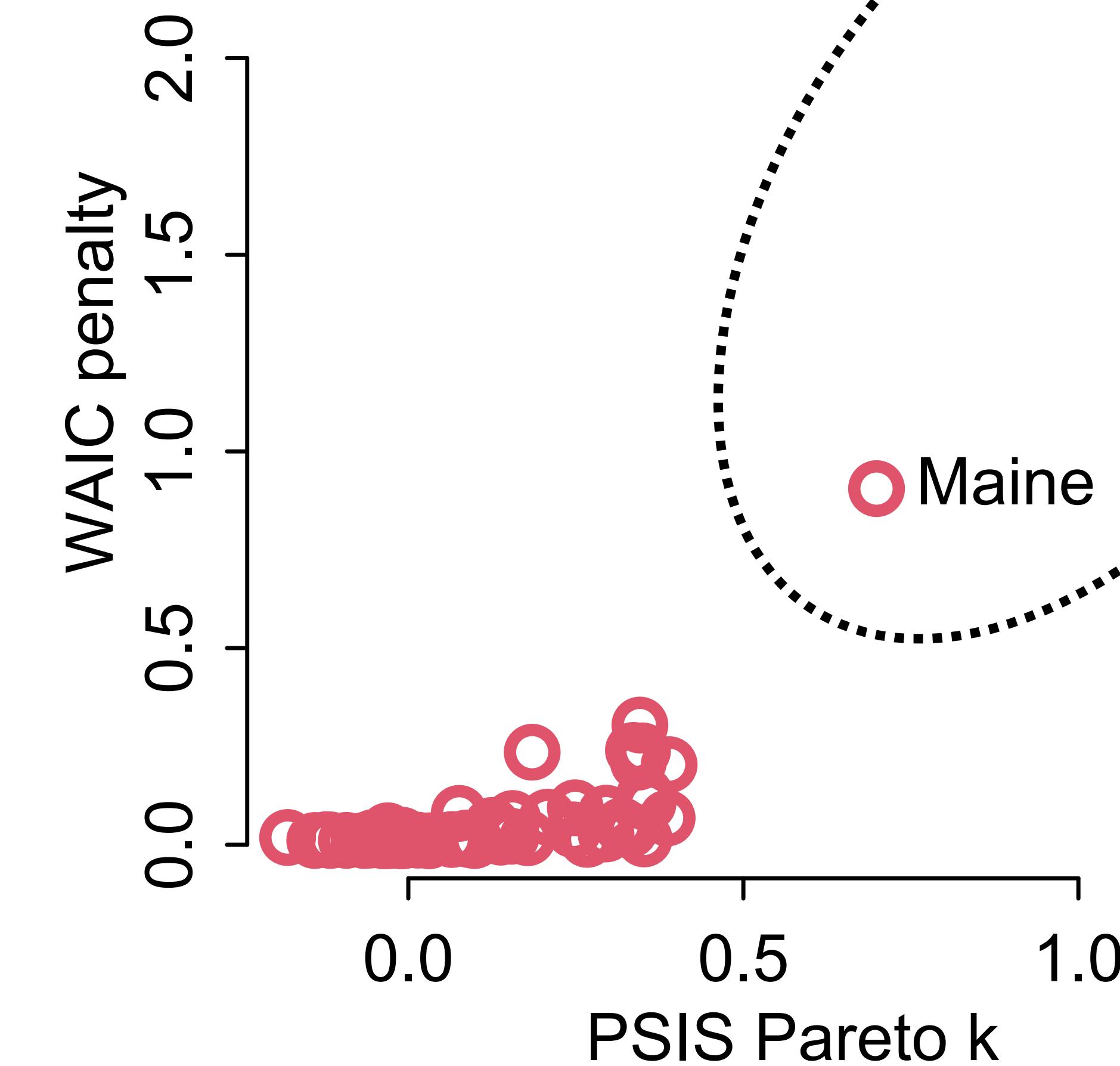
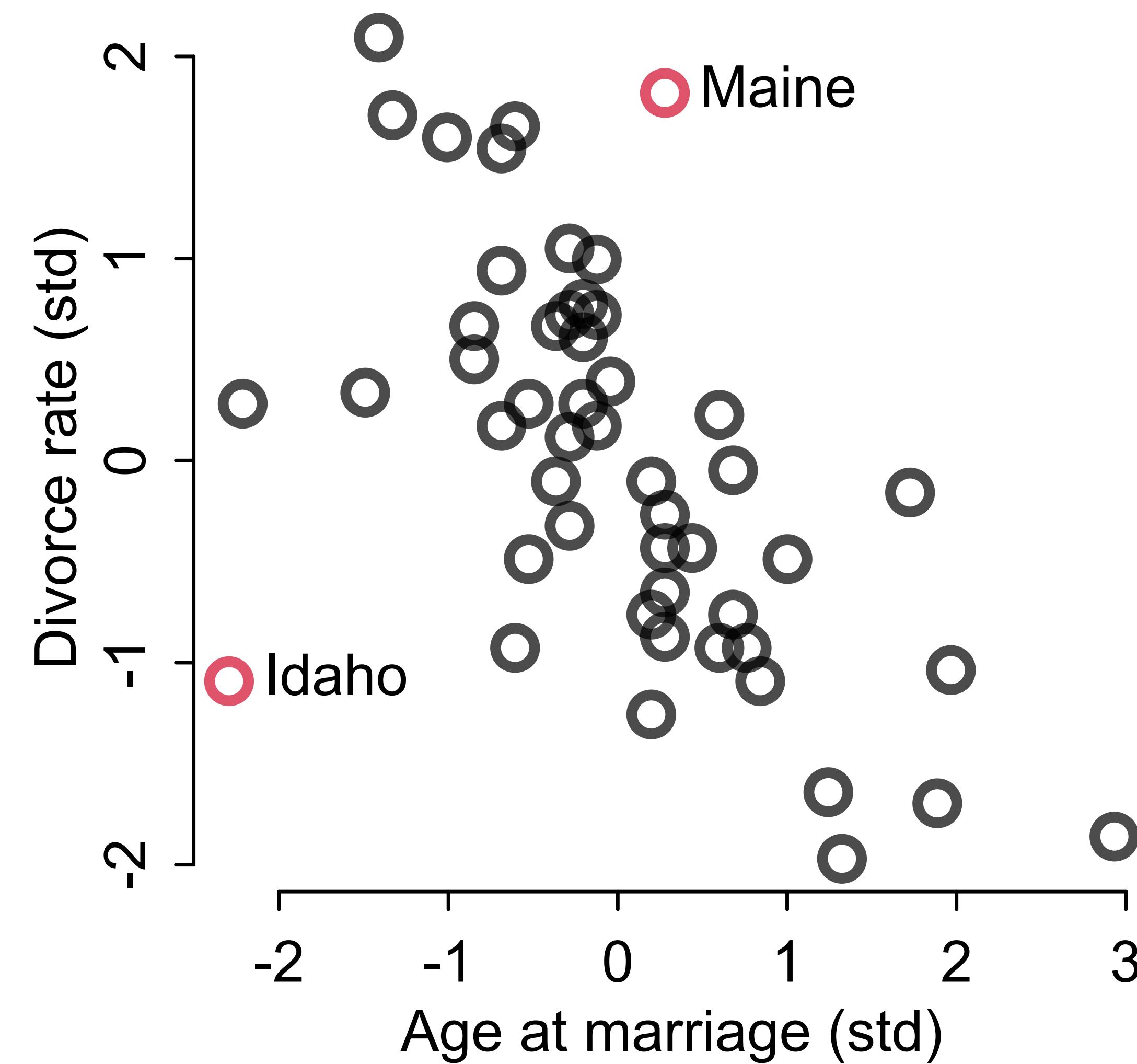
Quantify influence:

PSIS  $k$  statistic

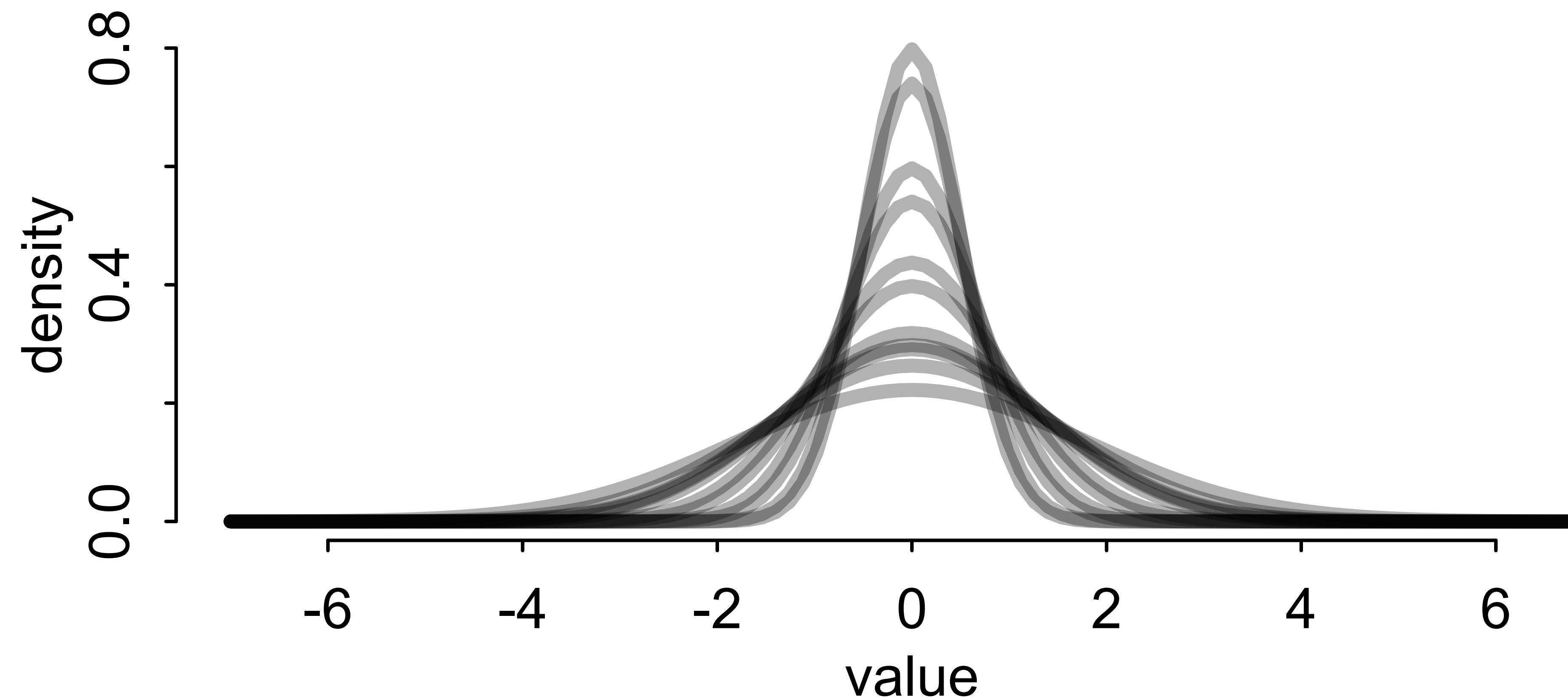
WAIC penalty term (“effective number of parameters”)



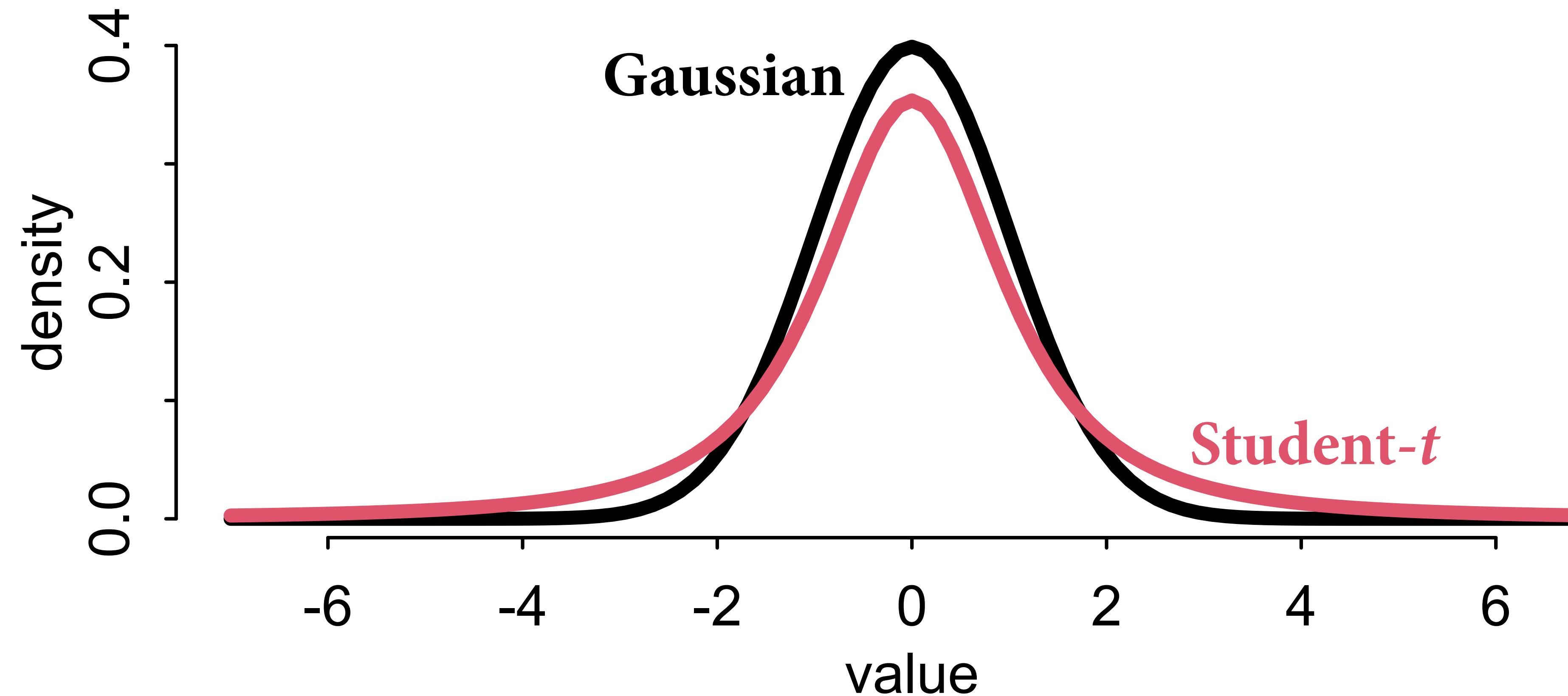
# Outliers & Robust Regression



# Mixing Gaussians



# Mixing Gaussians



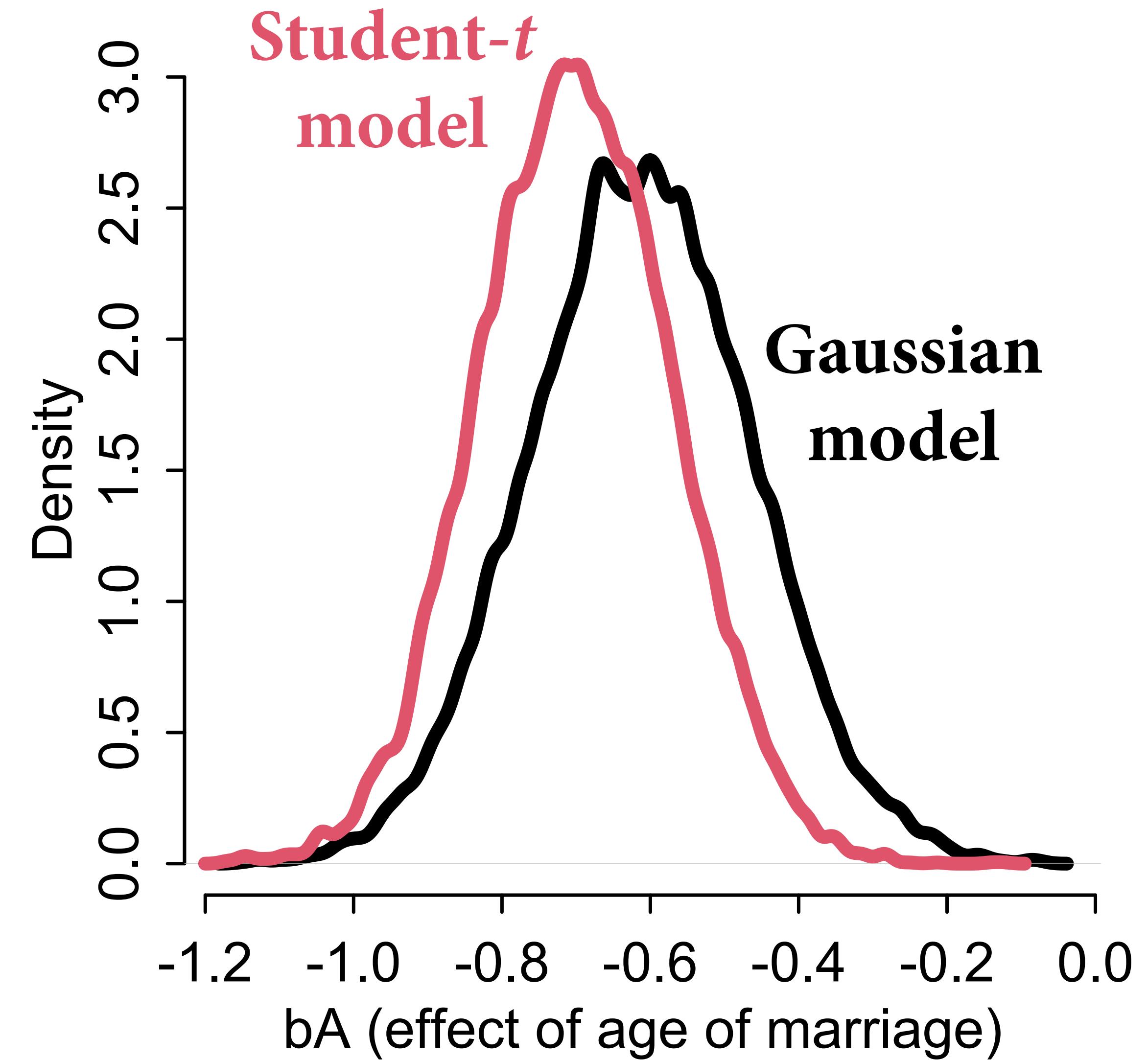
```
m5.3 <- quap(  
  alist(  
    D ~ dnorm( mu , sigma ) ,  
    mu <- a + bM*M + bA*A ,  
    a ~ dnorm( 0 , 0.2 ) ,  
    bM ~ dnorm( 0 , 0.5 ) ,  
    bA ~ dnorm( 0 , 0.5 ) ,  
    sigma ~ dexp( 1 )  
  ) , data = dat )  
  
m5.3t <- quap(  
  alist(  
    D ~ dstudent( 2 , mu , sigma ) ,  
    mu <- a + bM*M + bA*A ,  
    a ~ dnorm( 0 , 0.2 ) ,  
    bM ~ dnorm( 0 , 0.5 ) ,  
    bA ~ dnorm( 0 , 0.5 ) ,  
    sigma ~ dexp( 1 )  
  ) , data = dat )
```

```

m5.3 <- quap(
  alist(
    D ~ dnorm( mu , sigma ) ,
    mu <- a + bM*M + bA*A ,
    a ~ dnorm( 0 , 0.2 ) ,
    bM ~ dnorm( 0 , 0.5 ) ,
    bA ~ dnorm( 0 , 0.5 ) ,
    sigma ~ dexp( 1 )
  ) , data = dat )

m5.3t <- quap(
  alist(
    D ~ dstudent( 2 , mu , sigma ) ,
    mu <- a + bM*M + bA*A ,
    a ~ dnorm( 0 , 0.2 ) ,
    bM ~ dnorm( 0 , 0.5 ) ,
    bA ~ dnorm( 0 , 0.5 ) ,
    sigma ~ dexp( 1 )
  ) , data = dat )

```



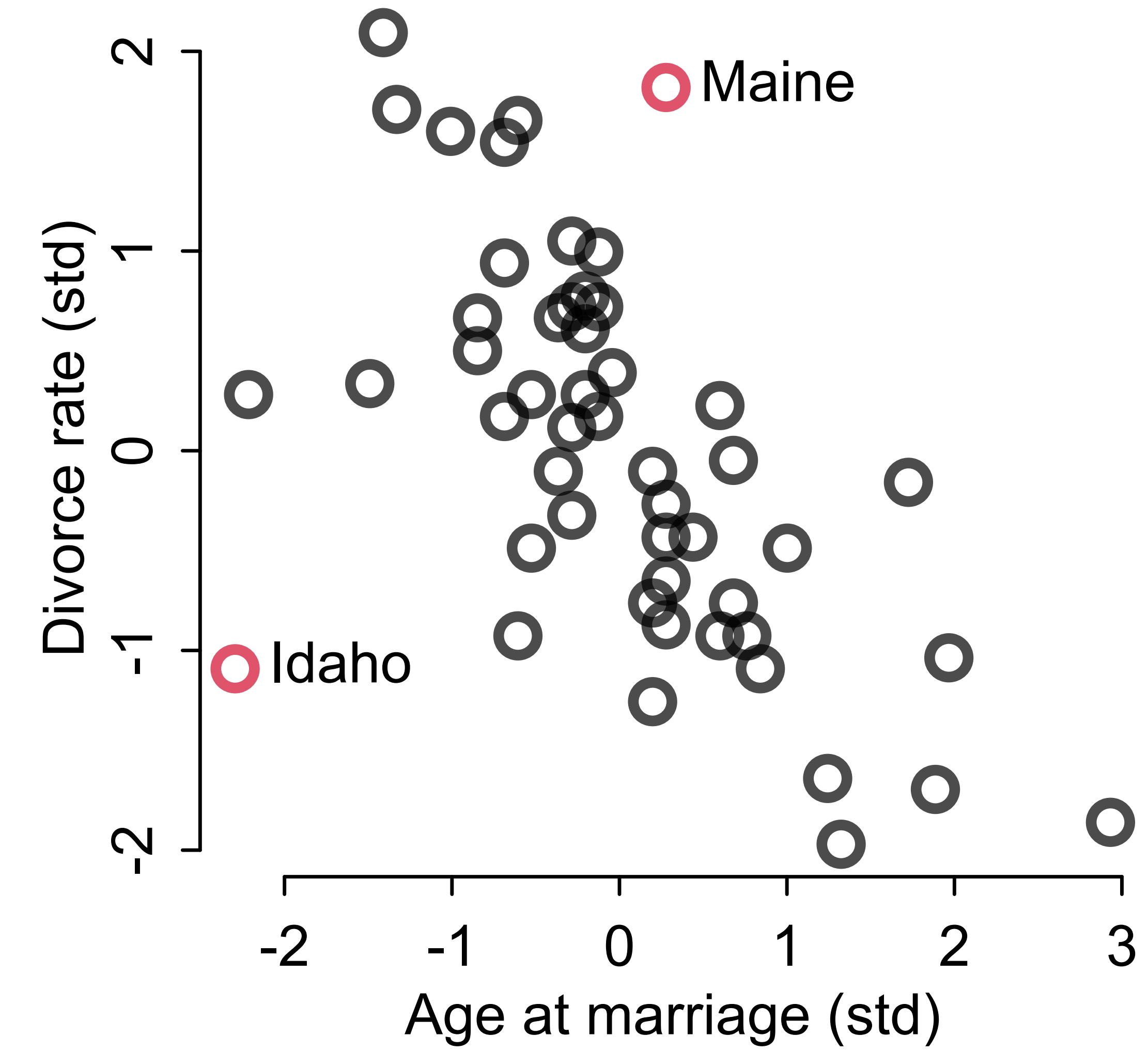
# Robust Regressions

Unobserved heterogeneity =>  
mixture of Gaussians

Thick tails means model is less  
surprised by extreme values

Usually impossible to estimate  
distribution of extreme values

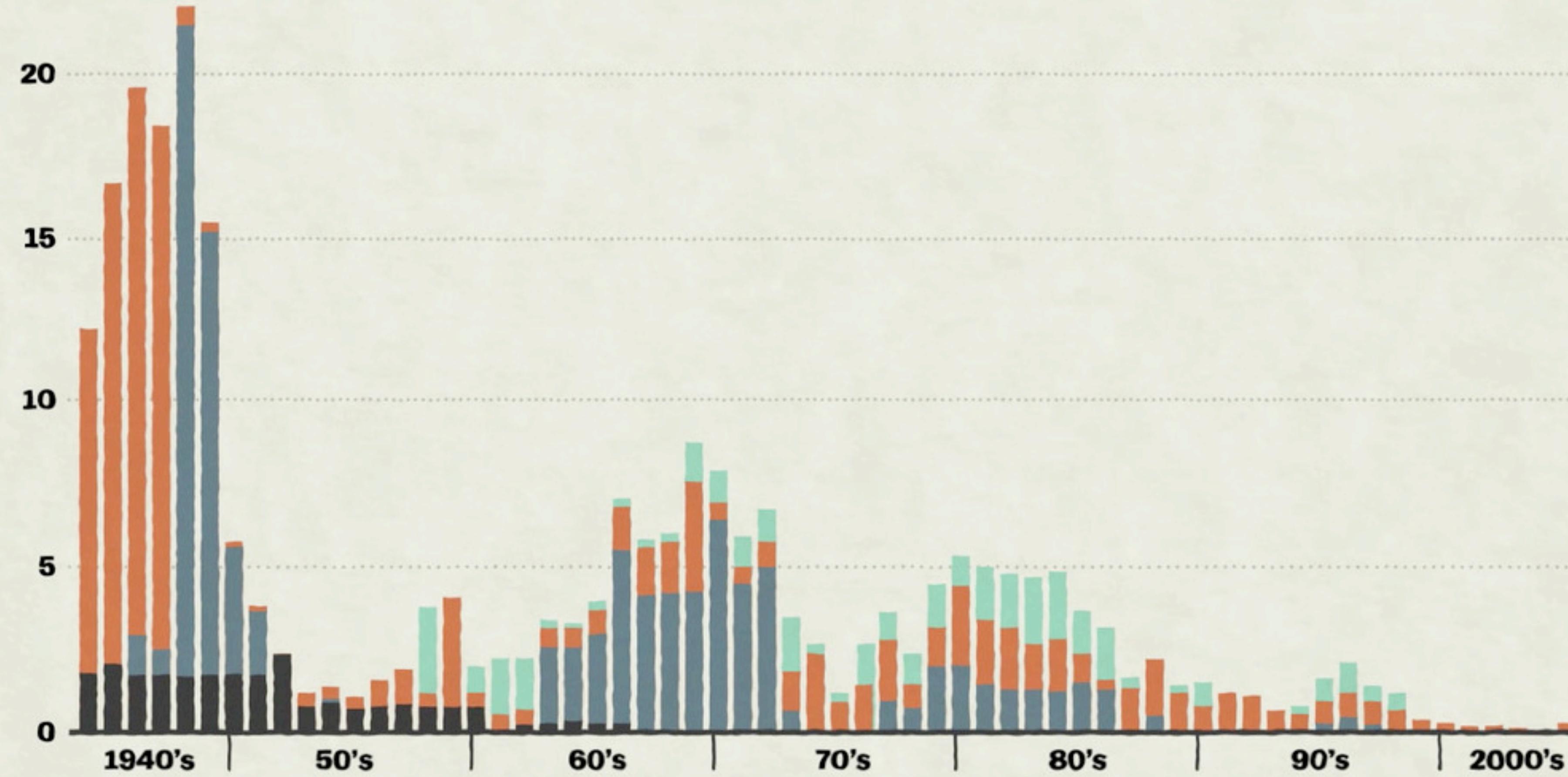
Student-*t* regression as default?



# World-wide battle deaths per 100,000 people

■ Colonial ■ Interstate ■ Civil ■ Civil with foreign interaction

Human Security Report Project, Uppsala Conflict Data Project, Peace Research Institute of Oslo, via WSJ



V

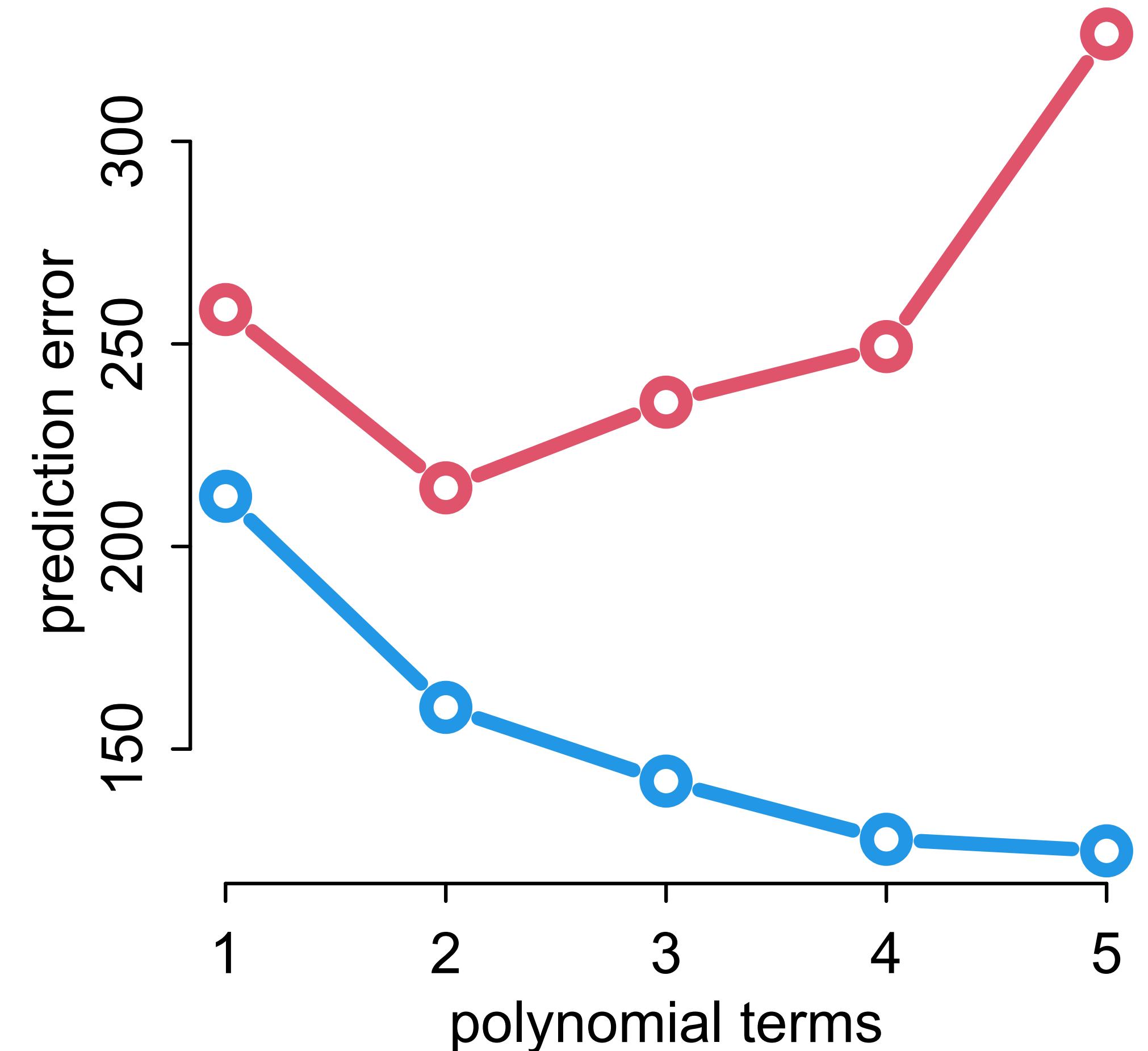
# Problems of Prediction

What is the next observation from the same process? (prediction)

Possible to make very good predictions without knowing causes

Optimizing prediction does not reliably reveal causes

Powerful tools (PSIS, regularization) for measuring and managing accuracy



# Course Schedule

Week 1	Bayesian inference	Chapters 1, 2, 3
Week 2	Linear models & Causal Inference	Chapter 4
Week 3	Causes, Confounds & Colliders	Chapters 5 & 6
Week 4	Overfitting / MCMC	Chapters 7, 8, 9
Week 5	Generalized Linear Models	Chapters 10, 11
Week 6	Integers & Other Monsters	Chapters 11 & 12
Week 7	Multilevel models I	Chapter 13
Week 8	Multilevel models II	Chapter 14
Week 9	Measurement & Missingness	Chapter 15
Week 10	Generalized Linear Madness	Chapter 16

[https://github.com/rmcelreath/stat\\_rethinking\\_2023](https://github.com/rmcelreath/stat_rethinking_2023)

