EEP 2.5 Specification © EnOcean Alliance



EnOcean Equipment Profiles (EEP)

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 - A5-09-07: Particles
- 7. A5-10: Room Operating Panel

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- A5-10-03: Temperature Sensor, Set Point Control
- A5-10-04: Temperature Sensor, Set Point and Fan Speed Control
- A5-10-05: Temperature Sensor, Set Point and Occupancy Control
- A5-10-06: Temperature Sensor, Set Point and Day/Night Control
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- A5-10-10: Temperature and Humidity Sensor, Set Point and Occupancy Control
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 D2-01-02: Type 0x02 (description: see table) ■ D2-01-03: Type 0x03 (description: see table) D2-01-04: Type 0x04 (description: see table)
D2-01-05: Type 0x05 (description: see table) ■ D2-01-06: Type 0x06 (description: see table) ■ D2-01-07: Type 0x07 (description: see table) D2-01-08: Type 0x08 (description: see table)
D2-01-09: Type 0x09 (description: see table) ■ D2-01-10: Type 0x10 (description: see table) ■ D2-01-11: Type 0x11 (description: see table) 3. D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke ■ D2-02-00: Type 0x00 ■ D2-02-01: Type 0x01 (description: see table) ■ D2-02-02: Type 0x02 (description: see table) 4. D2-03: Light, Switching + Blind Control ■ D2-03-00: Type 0x00 5. D2-20: Fan Control D2-20-00: Type 0x00D2-20-01: Type 0x01 ■ D2-20-02: Type 0x02 RPS Teach-in
 1BS Teach-in 3. 4BS Teach-in Smart Ack Teach-in (without repeater)
 Smart Ack Teach-in (with repeater)
 UTE - Universal Uni- and Bidirectional Teach-in 7. Smart Ack: functional principle (without repeater)
8. Smart Ack: functional principle (with repeater)
9. Remote Management / RPC
10. Interoperability with Security of EnOcean Networks 11. Existing 'bidirectional' profile structures 12. MSC telegram - Manufacturer Specific Communication
13. Use Cases for profile 2D-00-01 (self powered RCP for 2way operation) 14. Manufacturer ID's **15.** XML + DOC Maintenance process 1. General

1) Introduction

1.1) Terms, Abbreviations

13 14 15	J. MSC telegram - Manufacturer Specific Communication Use Cases for profile 2D-00-01 (self powered RCP for 2way operation) Manufacturer ID's XML + DOC Maintenance process 1. General 2. XML file Revision
1) Introd	
1.1) Terr	ms, Abbreviations EnOcean 1 Byte Communication
1BS	EnOcean 1 Byte Communication
4BS	EnOcean 4 Byte Communication
BAS	Building Automation System
Choice	Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG
Client	Bidirectional Smart Ack Device
Data	Payload of ERP telegrams or ESP packets
EEP	EnOcean Equipment Profiles
ERP	EnOcean Radio Protocol
ESP	EnOcean Serial Protocol
HTML	Hyper Text Markup Language; HTML can be displayed using a internet browser
MSC	Manufacturer Specific Communication
N/A	Not applicable
ORG	Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface)
RORG	Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice'
RMCC	Remote Management Control Commands
RPC	Remote Procedure Calls
RPS	EnOcean telegram type for Repeated Switch Communication

Smart Ack	Smart Acknowledge EnOcean standard for energy-optimized bidirectional transmission
UART	Universal Asynchronous Receiver Transmitter
VLD	EnOcean Variable Length Data telegram
XML	Extensible Markup Language; designed to transport and store data
XSL	Extensible Stylesheet Language; XML based language to visualize XML (data)



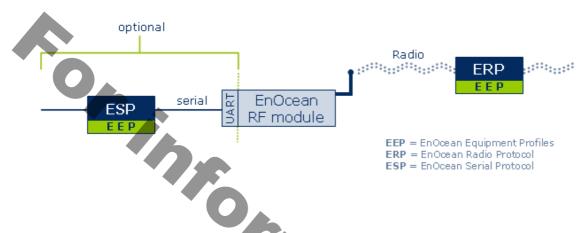
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1.2) General

The EnOcean radio protocol (ERP) is optimized to transmit information with utmost reliability using extremely little power while ensuring that the products of customers applying EnOcean technology are compatible with each other. Only the very shortest transmission period (< 1ms) for an EnOcean telegram allows the design of, for example, a battery-free radio switch, which can produce a full radio command with just approx. 50 μ Ws (50 μ J) of energy. At the same time, the reliability of the system increases, as the possibility of data collision is strongly reduced. Every data bit in the radio telegram is essential. For each '0' or '1' state, content descriptions are definied, which must be followed by the sender and the receiver likewise. Depending on the telegram type and the function of the device the user data (payload) is defined in:

EEP (EnOcean Equipment Profiles)



The ERP specification defines the structure of the entire radio telegram. The user data embedded in this structure is defined by the EEP.

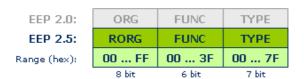
The objective of interoperability is easier to reach with as less profiles as required. Therefore, it is EnOcean Alliance's goal to configure each profile as universally as possible, to target a spectrum of devices in the building automation sector for all manufacturers.

It is of high interest to the EnOcean Alliance that Alliance members verify new devices or newly joined companies verify their products against the existing EEP Profiles and adopt these during testing. Every newly defined EEP would increase diversity and therefore decrease interoperability.

The technical characteristics of a device define three profile elements, which make up the organizational description of all profiles:

- 1. The ERP radio telegram type (RORG)
- 2. Basic functionality of the data content (FUNC)
- 3. Type of device in its individual characteristics (TYPE)

Therefore, every EEP profile has a number, reflecting these three components:



Every field is represented by a hexadecimal number, where the maximum value is limited by the available bits.

Before the definition of a new profile existing profiles should be checked first for suitability. A new profile is to be defined only if the existing profiles would not be adequate.

Once a new profile is to be developed it should be submitted to the TWG of the EnOcean Alliance. The information to be provided is

• the XML-data, plus

 $\bullet\,$ the profile as text in a pdf-file (the .pdf-data is to be generated from the XML-data)

The TWG will review and ratify the profile. Following the recommendation by the TWG the BoD will disapprove or approve the profile.

When defining a new profile rules, abbreviations and terms as per this document have to be applied.

To maintain the XML-data and the linked pdf-document in a proper way a document maintenance process is defined. For details refer to appendix 3.14 Data + document maintenance process.



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1.3) What's new in EEP 2.5?

New RPS profile

• F6-02-03: Light Control - Application Style 1

New 4 BS profiles

- A5-06-03: 10-bit measurement (1-Lux resolution) with range 0lx to 1000lx
- A5-07-02: Occupancy with Supply voltage monitor
- A5-07-03: Occupancy with Supply voltage monitor and 10-bit illumination measurement
- A5-09-02: CO Sensor (0-1020 ppm)
- A5-09-05: VOC Sensor
- A5-09-06: Radon
- A5-09-07: Particles
- A5-10-1F: Temperature Sensor, Set Point, Fan Speed, Occupancy and Unoccupancy control
- A5-11-03: Blind Status
- A5-11-04: Extended lighting status
- A5-13-10: Sun position and radiation
- A5-14-01: Single Input Contact (Window/Door), Supply voltage monitor
- A5-14-02: Single Input Contact (Window/Door), Supply voltage monitor and Illumination
- A5-14-03: Single Input Contact (Window/Door), Supply voltage monitor and Vibration
 A5-14-04: Single Input Contact (Window/Door), Supply voltage monitor, Vibration and Illumination
 A5-14-05: Vibration/Tilt, Supply voltage monitor
 A5-14-06: Vibration/Tilt, Illumination and Supply voltage monitor

- A5-38-08: Gateway / Command 0x07 (Blind Central Command)
 A5-38-09: Extended Lighting-Control

New VLD profiles D2-01: Electronic switches and dimmer (actuators, continuously powered)

- D2-01-00: Type 00 (see table)
- D2-01-01: Type 01 (see table)
- D2-01-02: Type 02 (see table)
- D2-01-03: Type 03 (see table)
- D2-01-04: Type 04 (see table)
- D2-01-05: Type 05 (see table)D2-01-06: Type 06 (see table)
- D2-01-07: Type 07 (see table)
- D2-01-08: Type 08 (see table)
- D2-01-09: Type 09 (see table)
- D2-01-10: Type 10 (see table)
- D2-01-11: Type 11 (see table)

New VLD profiles D2-02: Environmental Sensors

- • D2-02-00: Temperature and Illumination Sensor, Occupany and Smoke Detector
- D2-02-01: Temperature and Illumination Sensor, Smoke Detector
- D2-02-02: Temperature Sensor, Smoke Detector

New VLD profile D2-03: Light, Switching + Blind Control

• D2-03-00: 2 Rocker Switch

New VLD profiles D2-20: Fan Control

- D2-20-00: Fan Control Message Type 01 (see table)
- D2-20-01: Fan Control Message Type 02 (see table)
- D2-20-02: Fan Control Message Type 03 (see table)

Updated profiles

- A5-07-01: Occupancy with Supply voltage monitor
- A5-09-01: CO Sensor (not in use)
- A5-09-04: CO2 Sensor
- A5-13-01: Weather Station
- A5-13-02: Sun Intensity (3x Scale 0...150), Bit 29

Deleted profile

• A5-10-1E: identical to A5-10-1B

New + updated chapters

- 1.8: Viewing XML-data / conversion formula
- 3.6: UTE Universal Uni- and Bidirectional Teach-in
- 3.9: Remote Management / RPC function no. added, reference source: specification
- 3.10: Interoperability with Security of EnOcean Networks
- 3.14: Manufacturer ID's / only with a cross reference to an external document

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1.4) Telegram types (RORG)

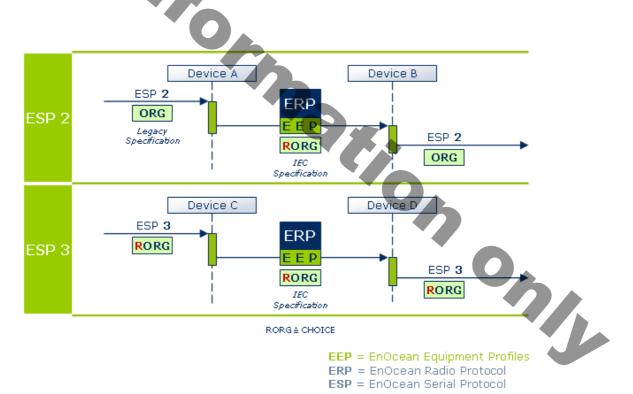
The various ${f R}$ adio-Telegram types are grouped ${f org}$ anizationally.

The specifications of ERP (EnOcean Radio Protocol) and of ESP (EnOcean Serial Protocol) group telegram types by 'CHOICE' number. 'RORG' at EEP 2.1(2.5) corresponds to 'CHOICE'.

The following RORG are used in EEP 2.5:

Telegram	RORG	ORG	
RPS	F6	05	Repeated Switch Communication
1BS	D5	06	1 Byte Communication
4BS	A5	07	4 Byte Communication
VLD	D2	=RORG	Variable Length Data
MSC	D1	=RORG	Manufacturer Specific Communication
ADT	A6	=RORG	Adressing Destination Telegram
SM_LRN_REQ	C6	=RORG	Smart Ack Learn Request
SM_LRN_ANS	C7	=RORG	Smart Ack Learn Answer
SM_REC	A7	=RORG	Smart Ack Reclaim
SYS_EX	C5	=RORG	Remote Management
SEC	30	∍RORG	Secure telegram
SEC_ENCAPS	31	=RORG	Secure telegram with R-ORG encapsulation

For compatibility reasons, the old ORG values on the serial ESP2 interfaces remain valid. However, on the air interface, each ESP2 telegram is transported with the appropriate RORG (= CHOICE).

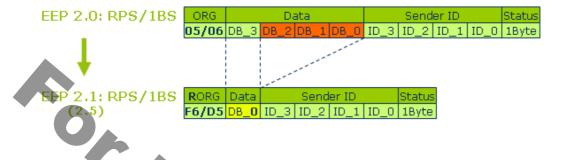


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1.5) EEP modifications at RPS and 1BS data telegram

Both telegram types carry a one byte payload (DB_0) on the wireless interface (ERP).

EEP 2.0 follows the specification of the serial interface / ESP2, which defines the payload to be carried in DB_3 (see succeeding figure). The trailing bytes, DB_2, DB_1 and DB_0 are marked as `unused'.



For orthogonal data structural reasons, this deviation will be avoided with EPP 2.1, 2.5 and future versions. The new ESP3 serial interface already respects this.

For reasons of compatibility of end devices, the ESP2 interface remains unaltered, i.e. the DB_0 byte (radio) will continue to be transferred as a DB_3 byte (serial) (including the 3 unused bytes). The conversation has to happen on the application layer as the XML-data structure of EEP 2.1 / 2.5 only refers to the DB_0 byte.

DB_0 byte.

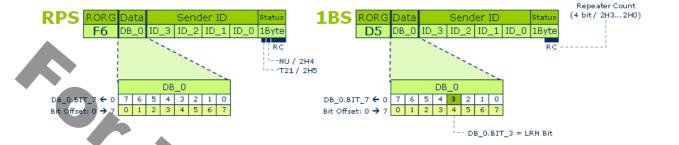
As a consequence of this modification the LRN bit is now described in a row for the 1BS and 4BS telegram types as standardized with the DB_0.BIT_3 position.

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1.6) Structure and addressing of the telegram types

1.6.1) RPS / 1BS



The RPS and the 1BS telegrams offer only 1 byte user data. These two telegrams differ in the respective learning operations (the 1BS has a LRN bit), and in the way the status byte is used. Comment for RPS status bits:

T21 = 0 = PTM switch module of type 1 / synonymous for module PTM1xx T21 = 1 = PTM switch module of type 2 / synonymous for module PTM2xx

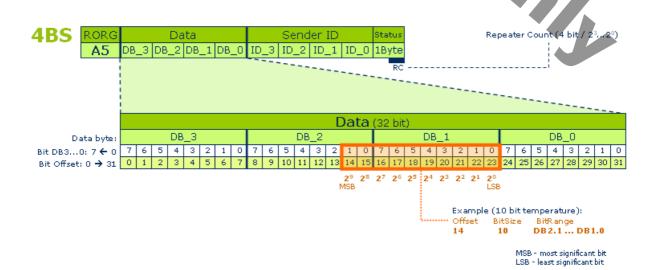
NU = 1 = N-message (N = normal)

NU = 0 = U-message (U = unassigned)

1.6.2) 4BS

A 4BS telegram carries a payload of 4 bytes. The sequence of the 4 data bytes is historically reversed, so that DB_3 appears first and DB_0 last on the radio interface. The bits are addressed in the sequence of the data flow, however (offset). Hence, DB_3.BIT_7 has the offset position 0 and DB_0.BIT_3 (LRN bit) has the offset position 28. The actual content-bits in a byte are not affected by this, i.e., they are described from right (2H0) to left (2H7) in the ascending order.

The example of a 10-bit temperature profile (see below) illustrates the binary valuation of the individual bits, so that a number range from 0 ... 1023 can be addressed.

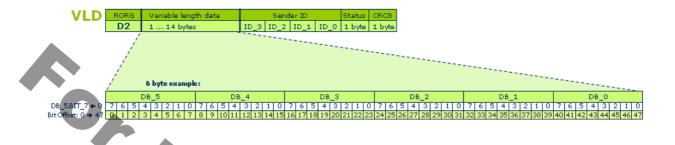


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1.6.3) VLD

VLD telegrams carry a variable payload between one and 14 bytes, depending on their design. The teach-in process applies the Smart Ack procedure (see appendices 3.4 and 3.5).

The example following displays a VLD telegram with 6 bytes user data. DB_5.BIT_7 is the first transmitted bit with offset 0.



1.7) Teach-in procedures

The 'Teach-in' defines the mutual communication between wireless devices in an 868 (315) MHz radio network. The 'Teach-in' defines to which transmitter(s) a receiver needs to listen to.

For this purpose of a determined relationship between transmitter and receiver each transmitting device has a unique Sender-ID which is part of each radio telegram. The receiving device detects from the Sender-ID whether the device is known, i.e., was already learned, or unknown.

A telegram with unknown Sender-ID is disregarded.

The 'teach-in' process is different for each telegram type (RPS, 1BS, 4BS, Smart Ack), but the following points are valid for all telegrams:

- First, the receiver must be switched into learning mode. Now, the Sender-ID of an arriving telegram is interpreted as an authorized information source and will be stored at the receiver. The further steps of 'teach-in' are defined by the device type or the telegram type. Thus, normal data telegrams or special teach-in telegrams can be used. Frequently, a learn button triggers the teach-in process.
- The telegram of the respective transmitter should be triggered at least once (by pressing the desired switch rocker or triggering a sensor).
- The bits of the payload (data bytes) can have multiple functions depending on the interpretation set by
 identification or status bits. Only in the 1BS and 4BS telegram the 'LRN BIT' DB_0.BIT_3 is reserved exclusively
 and must not be used elsewhere.

The following issues are relevant for a number of application but not mandatory for specification perspective:

- To prevent unwanted devices from being learned the input sensitivity of the receiver is often restricted, and thus an IN-ROOM operation is created. Typically, the device to be learned is placed close by the receiver.
- Dolphin-based transmitters (e.g. TCM 300 or TCM 2x with Dolphin library) can also be switched into the learn-mode via a remote management command. This remote 'teach-in' mode can only be activated within the first 30 min after receiver power-up. To avoid inadvertent learning the transmitter telegrams have to be triggered 3 times within 2 seconds.

For further details on the 'Teach-in' processes refer to appendices 3.1 to 3.6.

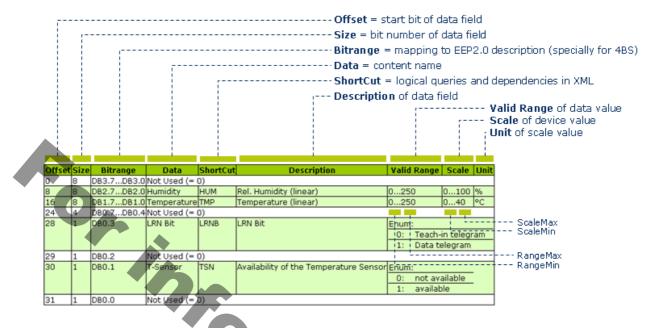
1.8) Viewing XML-data

 The XML-file and all the associated files (CSS, DTD, XSL) and the 'graphics' folder must be stored in the same directory.

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- The XML-file is best opened using an Internet browser, generating an HTML-view which displays the describing chapters, graphics and data tables.
- Mozilla Firefox V3.6 or upwards is recommended for optimum screen and print view.

The following example illustrates the HTML-view of the XML-data of a 4BS telegram (= payload of 32 bits).

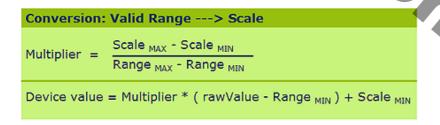


Data ranges unused are displayed in the table as white rows.

The 'Bit range' column displays the starting-point and the end-point of the respective data.

The 'Valid range', 'Scale' and 'Unit' columns are displayed separately only for measurement values. However, these 3 columns are merged into one if the data comes from an enumeration (enum).

Assuming a linear conversion between the value to be measured and the 'valid range' of data the resolution can be calculated as follows:



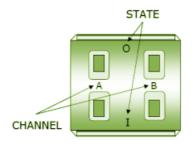
F6: RPS Telegram

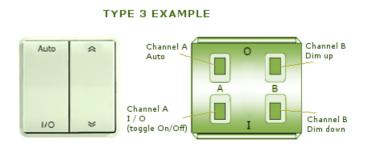
Repeated Switch Communication

F6-02: Rocker Switch, 2 Rocker

For clarification reasons the following picture shows a PTM200 transmitter module from EnOcean GmbH which transmits RPS telegrams and is one possibility to be used in applications that require an EEP F6-02-xx. Please note that PTM200 does not support transmission of teach-in telegrams.

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The button naming used below is referring to CHANNEL and STATE of the PTM200. Thus "Button AI" means STATE "I" on CHANNEL "A".

There are two different message types, the N-message and the U-message, which need to be identified from the Status Field of an EnOcean RPS telegram. For that reason not only the data bytes are given for each EEP but the T21 and NU bits of the Status Field are listed as well.

RORG	F 6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

position	position! Application Style 1 is widely used in EU but may be found in other markets as well.								
Statusfield: Offset Size Data Value									
Offset		Bitrange	Data		Description		Valid Range	Scale	Unit
	3	DB0.7DB0.5		R1		1: 2:		"Dim light dow "Dim light up" "Dim light dow	n" or or "Move n" or
3	1	DB0.4	Energy Bow	EB		Enum: 0: 1:	•		
4	3	DB0.3DB0.1	Rocker 2nd action	R2		Enum: 0: 1: 2:	· · · · · · · · · · · · · · · · · · ·	"Dim light up" "Dim light dow	or "Move n" or
7	1	DB0.0	2nd Action	SA		Enum: 0: 1:	•		

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		3: 3	button or 4 attons	
3	1	DB0.4	Energy Bow	EB			leased essed	_
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	02	Light and Blind Control - Application Style 2

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in an I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Off	set	Size	Data	Value
2		1	T21	1
3		1	NU	1

position	position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.										
Statusfi Offset 2 3		Data Value T21 1 NU 1			Description						
	Datafield:										
Offset		•	Data	ShortCut	Description	Valid Range Scale Unit					
0	3	DB0.7DB0.5	Rocker 1st action	R1		Enum: 0: Button AI: "Switch light on" or "Dim light up" or "Move blind open " 1: Button A0: "switch light off" or "Dim light down" or "Move blind closed " 2: Button BI: "Switch light on" or "Dim light up" or "Move blind open" 3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"					
3	1	DB0.4	Energy Bow	ЕВ		Enum: 0: released 1: pressed					
4	3	DB0.3DB0.1	Rocker 2nd action	R2		Enum: 0: Button AI: "Switch light on" or "Dim light up" or "Move blind open " 1: Button A0: "switch light off" or "Dim light down" or "Move blind closed " 2: Button BI: "Switch light on" or "Dim light up" or "Move blind open" 3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"					
7	1	DB0.0	2nd Action	SA		Enum: 0: No 2nd action 1: 2nd action valid					

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	N		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		3: 3:	button or 4 ttons	
3	1	DB0.4	Energy Bow	EB			leased essed	- -
4	4	DB0.3DB0.0	Not Used (= 0)					

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	03	Light Control - Application Style 1

Submitter: Servodan

Definition of Auto, I/O for Rocker switch, Dim control (PTM200)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Definit	Definition of Auto, I/O for Rocker switch, Dim control (PTM200)								
Statusfield: Offset Size Data Value 2 1 T21 1 3 1 NU 1 Datafield:									
	t Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0		DB0.7DB0.0		RA		0x30: 0x10: 0x70: 0x50:	Button A0: Set the controller in a Button A1:	utomatic mode	nd

F6-03: Rocker Switch, 4 Rocker

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

lown" or Ip" or "Move lown" or Ip" or "Move
lp" or "Move lown" or lp" or "Move
lown" or up" or "Move
ıp" or "Move
own" or
ıp" or "Move
lown" or
ıp" or "Move
lown" or
ıp" or "Move
lown" or
ıp" or "Move
lown" or
ıp" or "Move
lown" or
ip" or "Move

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	0

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	3			R1		Enum	:		
			simultaneously			0:	no Butt pressed		
						1:	2 butto pressec		

					2:	3 buttons pressed
					3:	4 buttons pressed
					4:	5 buttons pressed
					5:	6 buttons pressed
					6:	7 buttons pressed
					7:	8 buttons pressed
3	1	DB0.4	Energy Bow	EB	 Enum	:
					0:	released
					1:	pressed
4	4	DB0.3DB0.0	Not Used (= 0)			

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	02	Light and Blind Control - Application Style 2

A This EEP definition is based on the assumption that a RPS switch module is installed in a I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

A This I Applica	EEP d tion S	efinition is base Style 2 is typica	ed on the assun lly used in US a	nption that and CAN bu	a RPS switch ut may be fou	h module is installed in a I-STATE up position! und in other markets as well.
Statusf Offset 2 3		Data Value T21 0 NU 1				
Datafie		_	1			
Offset			Data		Description	
0	3	DB0.7DB0.5	Rocker 1st action	R1	G	Enum: 0: Button AI: "Switch light on" or "Dim light up" or "Move blind open"
						1: Button A0: "Switch light off" or "Dim light down" or "Move blind closed"
						2: Button B1: "Switch light on" or "Dim light up" or "Move blind open"
						3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
						4: Button CI: "Switch light on" or "Dim light up" or "Move blind open"
						5: Button CO: "Switch light off" or "Dim light døwn" or "Move blind closed"
						6: Button DI: "Switch light on" or "Dim light up" or "Move blind open"
						7: Button D0: "Switch light off" or "Dim light down" or "Move blind closed"
3	1	DB0.4	Energy Bow	EB		Enum:
						0: released
4	2	DB0 3 DB0 1	Docker 2nd	R2		1: pressed
4	3	DB0.3DB0.1	action	KZ		Enum: 0: Button AI: "Switch light on" or "Dim light up" or "Move blind open"
						1: Button A0: "Switch light off" or "Dim light down" or "Move blind closed"
					,	

					2: Button BI: "Switch light on" or "Dim light up" or "Move blind open"
					3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed"
					4: Button CI: "Switch light on" or "Dim light up" or "Move blind open"
					5: Button C0: "Switch light off" or "Dim light down" or "Move blind closed"
					6: Button DI: "Switch light on" or "Dim light up" or "Move blind open"
					7: Button D0: "Switch light off" or "Dim light down" or "Move blind closed"
7	1	DB0.0	2nd Action	SA	 Enum:
					0: No 2nd action
					1: 2nd action valid

Statusfield:

Offset Size Data Value

1 T21 0

NU 0

Datafield:

Dataile						
Offset			Data	ShortCut	Description	Valid Range Scale Unit
0	3			R1		Enum:
			simultaneously			0: no button pressed
			2			1: 2 buttons pressed
			70			2: 3 buttons pressed
				3		3: 4 buttons pressed
						4: 5 buttons pressed
						5: 6 buttons pressed
						6: 7 buttons pressed
						7: 8 buttons pressed
3	1	DB0.4	Energy Bow	EB		Enum:
						0: released
						1: pressed
4	4	DB0.3DB0.0	Not Used (= 0)			

F6-04: Position Switch, Home and Office Application

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	01	Key Card Activated Switch

Insertion of Key Card generates an N-Message, take-out a U-Message

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Key Card	KC		Enum:		
						112: inserte	d (0x70	0)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB0.7DB0.0	Key Card	KC		Enum:
						0: taken out

echanical Handle

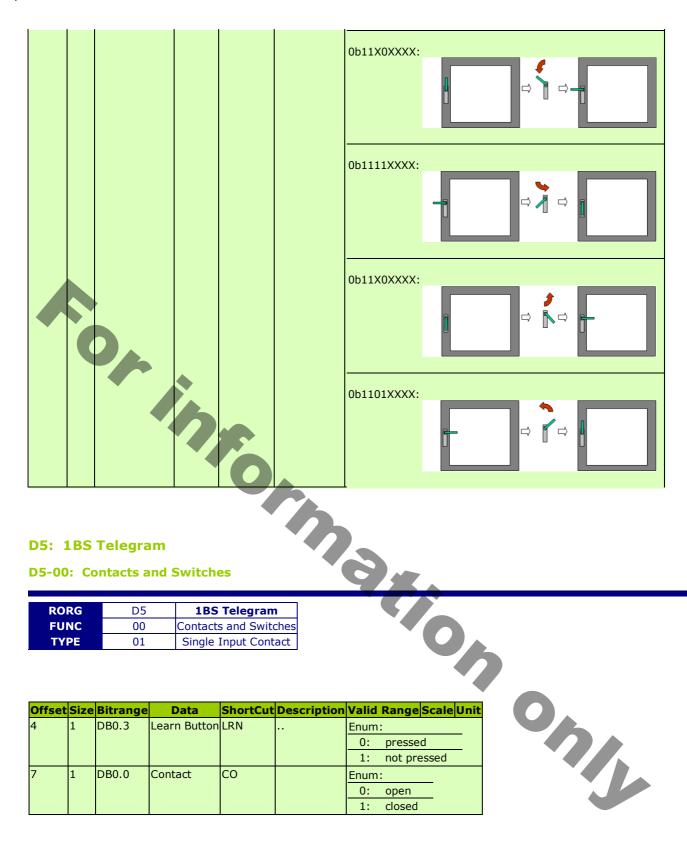
RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
TYPE	00	Window Handle

The bits marked with 'X' in DB_0 should not be checked. These bits can be '1' or '0' and should not be assumed to be a defined value, because both of them are allowed and not predictable!

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

(defined	valu	e, because both	of them	are allow	ed and not pr	edictable!
	Statusfi Offset 2 3	Size 1	Data Value T21 1 NU 0		0		
[Datafie	d:					
	Offset	Size				Description	
	0	8 DB0.7DB0.0 Window handle	WIN		Ob1111XXXX:		
							Ob11X0XXXX: Ob1101XXXX:



D5: 1BS Telegram

D5-00: Contacts and Switches

RORG	D5	1BS Telegram
FUNC	00	Contacts and Switches
TYPE	01	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
4	1	DB0.3	Learn Button	LRN		Enum:
						0: pressed
						1: not pressed
7	1	DB0.0	Contact	СО		Enum:
						0: open
						1: closed



A5-02: Temperature Sensors

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	01	Temperature Sensor Range -40°C to 0°C

Offset Size Bitrange Data ShortCut De	escription Valid Range Scale Unit
---------------------------------------	---

0	16	DB3.7DB2.0	Not Used (= 0)						
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550)	-400	°C
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-i	n telegr	am
						1:	Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	02	Temperature Sensor Range -30°C to +10°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+10	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	03	Temperature Sensor Range -20°C to +20°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+20	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)	•			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	04	Temperature Sensor Range -10°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-10+30	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram

FUNC	02	Temperature Sensors
TYPE	05	Temperature Sensor Range 0°C to +40°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rang	e Scale	Unit
0	16	DB3.7DB2.0	Not Used (=)	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= (0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teacl	n-in telegr	am
						1: Data	telegram	
29	3	DB0.2DB0.0	Not Used (= (0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	06	Temperature Sensor Range +10°C to +50°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+10+50	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	า
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)	5			

RORG	A5	4BS Telegram	
FUNC	02	Temperature Sensors	4
TYPE	07	Temperature Sensor Range +20°C to +60°C	

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+60	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegran	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	08	Temperature Sensor Range +30°C to +70°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)		-		
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+30+70	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (=	0)		•	

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	09	Temperature Sensor Range +40°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=)	0)				
16	œ	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+80	°C
24	4	DB0.7DB0.4	Not Used (=)	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= (0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	0A	Temperature Sensor Range +50°C to +90°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+50+90	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	<u></u>
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	0B	Temperature Sensor Range +60°C to +100°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+60+100	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)		_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	10	Temperature Sensor Range -60°C to +20°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-60+20	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	11	Temperature Sensor Range -50°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-50+30	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrai	m
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (= (0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	12	Temperature Sensor Range -40°C to +40°C

Size	Bitrange	Data	ShortCut	Description	Valid Rang	e Scale	Unit
16	DB3.7DB2.0	Not Used (= (0)				
8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-40+40	°C
4	DB0.7DB0.4	Not Used (= (0)				
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach	n-in telegra	m
					1: Data	telegram	
3	DB0.2DB0.0	Not Used (= (0)				77
	16 8 4 1	16 DB3.7DB2.0 8 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3	16 DB3.7DB2.0 Not Used (= 0 8 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 0 1 DB0.3 LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit Enum: 0: Teach 1: Data	16 DB3.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 2550 -40+40 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit LRNB LRN Bit 0: Teach-in telegrant: Data telegram

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	13	Temperature Sensor Range -30°C to +50°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Ra	nge	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=)	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-3	30+50	°C
24	4	DB0.7DB0.4	Not Used (= (0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Te	each-in	telegrar	n
						1: Da	ata tel	egram	
29	3	DB0.2DB0.0	Not Used (= (0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	14	Temperature Sensor Range -20°C to +60°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+60	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)		_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	15	Temperature Sensor Range -10°C to +70°C

			<u> </u>					
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-10+70	°C
24	4	DB0.7DB0.4	Not Used (=)	0)				
28	1	DB0.3	LRN Bit	LRNB 💮	LRN Bit	Enum:		
				*		0: Teach-	in telegra	m
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= (0)		7		

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	16	Temperature Sensor Range 0°C to +80°C

		2201711122011		7) -					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	Teach-	in telegram elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)	6	>			
	•								-
RC	RG	A5		4BS Tele	gram				
FU	INC	02	Ter	nperature	Sensors				
TY	PE	16	Temperature	Sensor Ra	ange 0°C to +80°C	·	Y /		
								0	
Offse	tSize	Bitrange	Data	ShortCut	Description	Valid	Range	Scale Unit	
0	16	DB3.7DB2.0	Not Used (= 0))					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550)	0+80 °C	
24	4	DB0.7DB0.4	Not Used (= 0	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-	in telegram	
						1:	Data te	elegram	
29	3	DB0.2DB0.0	Not Used (= ())		•			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	17	Temperature Sensor Range +10°C to +90°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				

16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255(+10+90 °C
24	4	DB0.7DB0.4	Not Used (=	0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (=	0)			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	18	Temperature Sensor Range +20°C to +100°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+100	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	19	Temperature Sensor Range +30°C to +110°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0	0)	73			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	25 50	+30+110	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	_
29	3	DB0.2DB0.0	Not Used (= 0	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	1A	Temperature Sensor Range +40°C to +120°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= (0)			_	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+120	°C
24	4	DB0.7DB0.4	Not Used (= (Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data te	elegram	_
29	3	DB0.2DB0.0	Not Used (= (0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors

TYPE 1B	Temperature Sens	sor Range +50°C to +130°C
---------	------------------	---------------------------

Offset	Size	Bitrange	Data	ShortCut	Description	Valid I	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= (0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550)	+50+130	°C
24	4	DB0.7DB0.4	Not Used (=)	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-	in telegram	
						1:	Data te	elegram	
29	3	DB0.2DB0.0	Not Used (= (0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	20	10 Bit Temperature Sensor Range -10°C to +41.2°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegram	_
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	30	10 Bit Temperature Sensor Range -40°C to +62.3°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (= 0	0)					
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	1023.	0	-40+62.3	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:		
						0:	Teach-	in telegram	7/4
						1:	Data t	elegram	
29	3	DB0.2DB0.0	Not Used (= 0	0)					

A5-04: Temperature and Humidity Sensor

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
TYPE	01	Range 0°C to +40°C and 0% to 100%

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)			•	

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum		
						0:	Teach-in telegram	
						1:	Data telegram	
29	1	DB0.2	Not Used (=	ot Used (= 0)				
30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum		
						0:	not available	
						4.	available	
						1:	available	

A5-06: Light Sensor

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	01	Range 300lx to 60.000lx

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	30030000	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	60060000	lx
24	4	DB0.7DB0.4	Not Used $(= 0)$	_				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegram	
						1: Data tel	egram	
29	2	DB0.2DB0.1	Not Used $(= 0)$					
31	1	DB0.0	Range select	RS	Range	Enum:		
					0: Range acc. to DB_1 (ILL1)			
						1: Range acc. to DB_2 (ILL2)		
					6)-			
RO	RG	A5	4BS Telegr	am				
FU	NC	06	Light Sense	or				
TY	PE	02	Range 0lx to 1	.020lx				
						7		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
Ω	Q	DB2 7 DB2 0	Supply voltage	SVC	Supply voltage (linear)	0 255	0 5 1	\/

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	02	Range 0lx to 1.020lx

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	01020	lx
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in to	elegram	
						1: Data teleg	ram	
29	2	DB0.2DB0.1	Not Used (= 0)	_				
31	1	DB0.0	Range select	RS	Range	Enum:		
						0: Range acc.	to DB_1 (ILL1)
						1: Range acc.	to DB_2 (ILL2)

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	03	10-bit measurement (1-Lux resolution) with range 0lx to 1000lx

Submitter: Lutuo Technology

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage (linear) 251255: reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear) DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx
18	10	DB1.5DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telegr 1: Data		
29	3	DB0.2DB0.0	Not Used (= 0))		•		

A5-07: Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	01	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage (OPTIONAL)	SVC	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	PIR Status	PIRS	PIR Status	Enum: 0127: PI 128255: PI	R off R on	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Supply voltage availability	SVA	Supply voltage availability at DB_3	0: Supply v	oltage is	not

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	02	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offse	tSize	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Supply voltage (REQUIRED)		Supply voltage / super cap. (linear); 251 - 255 reserved for error code	0250	05.0	V
8	16	DB2.7DB1.0	Not Used (= 0)					

24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum:
						0: Uncertain of
						occupancy status
						1: Motion detected
25	3	DB0.6DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	03	Occupancy with Supply voltage monitor and 10-bit illumination measurement

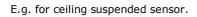
Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8	DB3.7DB3.0	Supply voltage (REQUIRED)	SVC	Supply voltage (linear); 251 – 255 reserved for error code	0250	05.0	V		
8	10	DB2.7DB1.6	Illumination	ILL	Illumination (linear); DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx		
18	6	DB1.5DB1.0	Not Used (= 0)							
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum:				
			•			1: Motion	detected			
						0: Uncerta	ain of occup	ancy		
25	3	DB0.6DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-	: Teach-in telegram			
						1: Data te	elegram			
29	3	DB0.2DB0.0	Not Used (= 0)							
A5-08	B: Li	ght, Temper	ature and Occup	ancy Sens	sor)				
RO	RG	A5		4BS Teleg	ram		5 .			
FUI	NC	08	Light, Tempe	erature and	Occupancy Sensor			•		
TY	PE	01	Range 0lx to 510lx,	0°C to +51	°C and Occupancy Button					
E.g. for	RORG A5 FUNC 08 Light, Temperature and Occupancy Sensor TYPE 01 Range 0lx to 510lx, 0°C to +51°C and Occupancy Button E.g. for ceiling suspended sensor.									
Offset	Size	Bitrange	Data S	hortCut	Description Vali	d Range Scale	Unit			
0	0	DB2 7 DB2 0	Cupply voltage C	VC C	anly voltage (linear) 0	FF 0 F 1	\/			

A5-08: Light, Temperature and Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	01	Range Olx to 510lx, 0°C to +51°C and Occupancy Button



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on	 '	
						1: PIR off		

31	1	DB0.0	Occupancy Button	OCC	 Enum:	
					0:	Button pressed
					1:	Button released

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	02	Range Olx to 1020lx, 0°C to +51°C and Occupancy Button

E.g. for wall mounted sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01020	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	am
						1: Data t	elegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on	<u> </u>	
						1: PIR of	f	
31	1	DB0.0	Occupancy Button	OCC		Enum:		
						0: Button	pressed	
			76			1: Button	released	Γ

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	03	Range Olx to 1530lx, -30°C to +50°C and Occupancy Button

E.g. for outdoor sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01530	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-30+50	°C
24	4	DB0.7DB0.4	Not Used (= 0)	_				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	m
						1: Data to	elegram	
29	1	DB0.2	Not Used (= 0)	•				
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on	1	
						1: PIR off	f	
31	1	DB0.0	Occupancy Button	occ		Enum:		
						0: Button	pressed	_
						1: Button	released	_

A5-09: Gas Sensor

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	01	CO Sensor (not in use)

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Concentration	Conc	Concentration	0255	0255	ppm
8	8	DB2.7DB2.0	Concentration	Conc	Concentration (tbd!)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+255	°C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in teleg	ram	
						1: Data telegram	<u> </u>	
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	T-Sensor	TSN		Enum:		
						0: Temperature	Sensor not ava	ailable
						1: Temperature	Sensor availab	ole
31	1	DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	02	CO-Sensor 0 ppm to 1020 ppm

Submitter: Unitronic AG

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Concentration	Conc	Gas concentration	0255	01020	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used $(=0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in teleg 1: Data telegran		
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	T-Sensor	TSN	6	Enum: 0: Temperature available 1: Temperature		able
31	1	DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	04	CO2 Sensor

						avaliable		
					1:	Temperature Se	ensor availab	ole
31	1	DB0.0	Not Used (= 0)				
					10	b		
RC	ORG	A5	4BS Telegra	m	•			
FL	JNC	09	Gas Sensor					
T	YPE	04	CO2 Sensor					
Offse	t Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear), 0.5 %	0200	0100	%
			,		= 1 bit			
8	8	DB2.7DB2.0	Concentration	Conc	Concentration (linear), increment = 10 ppm	0255	02550	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear), increment = 0.2 °C	0255	0+51.0	°C
24	4	DB0.7DB0.4	Not Used (= 0)		•		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegram	_
						1: Data te	legram	_
29	1	DB0.2	H-Sensor	HSN		Enum:		
						0: Humidit availabl	y Sensor not e	t
						1: Humidit	y Sensor	

30	1	DB0.1	T-Sensor	TSN	 Enum	:
					0:	Temperature Sensor not available
					1:	Temperature Sensor available
31	1	DB0.0	Not Used (= 0))		

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	05	VOC Sensor

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	VOC	Conc	VOC Concentration	065535	065535	ppb
16	8	DB1.7DB1.0	VOC ID	VOC_ID	VOC identification	Enum:		
						0: VOCT (to	tal)	
						1: Formalde		
						2: Benzene		
						3: Styrene		
						4: Toluene		
						5: Tetrachlo	proethylene	
						6: Xylene		
						7: n-Hexan	e	
						8: n-Octane	2	
						9: Cycloper		
						10: Methano	l	
					_	11: Ethanol		
						12: 1-Pentar	ol	
						13: Acetone		
						14: ethylene		
					Y (63)	15: Acetalde		
						16: Acetic Ac		
						17: Propionio		
						18: Valeric A		
						19: Butyric A		
						20: Ammonia		
						22: Hydroge		
						23: Dimethy		. I IX
						24: 2-Butano		noi)
						25: 2-Methyl		
						26: Diethyl e	culer	
24	4	DD0 7 DD0 4	Not Head (O)			255: ozone		
24 28	4	DB0.7DB0.4 DB0.3	Not Used (= 0)	LRNB	LRN Bit	F		7/
20	1	כ.טמע	LRN Bit	LKIND	LKIN DIL	Enum:	tologram	
							telegram	
20	1	DD0 3	Not Hond (O)			1: Data tele	egram	
29	1	DB0.2	Not Used (= 0)		Coole Multiplian	-		
30	2	DR0.1DR0.0	Scale Multiplier	SCM	Scale Multiplier	Enum:		
						0: 0.01		
						1: 0.1		
						2: 1		
						3: 10		

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	06	Radon

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Va Rar		Scale	Unit
0	10	DB3.7DB2.6	Radon	Act	Radon activity (regulation is an average of 100 Bq/m3/24h)	010	23	01023	Bq/m3
10	18	DB2.5DB0.4	Not Use	ed (= 0)					
28	1	DB0.3	LRN	LRNB	LRN Bit	Enum	:		
			Bit			0:	Teac	h-in teleg	ıram
						1:	Data	telegran	1
29	3	DB0.2DB0.0	Not Use	ed (= 0)					

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	07	Particles

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	9	DB3.7DB2.7	Particles_10	PM10	Dust less than 10 µm (PM10)	0511	1	0511	µg/m3
9	9	DB2.6DB1.6	Particles_2.5	PM2.5	Dust less than 2.5 µm (PM2.5)	0511	1	0511	µg/m3
18	9	DB1.5DB0.5	Particles_1	PM1	Dust less than 1 µm (PM1)	0511	1	0511	µg/m3
27	1	DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	Teach-	in teleg	
29	1	DB0.2	PM10 active	PM10a		Enum: 0: 1:		not activ	
30	1	DB0.1	PM2.5 active	PM2.5a	2	Enum: 0: 1:		not active	/e
31	1	DB0.0	PM1 active	PM1a	94	Enum: 0: 1:		ot active	_
A5-10	A5-10: Room Operating Panel								
RO	RG	A5			4BS Telegram				

A5-10: Room Operating Panel

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	01	Temperature Sensor, Set Point, Fan Speed and Occupancy Control

Submitter: Kieback + Peter GmbH

RO	RG	A5		4BS Tel	egram					
FU	NC	10	R	oom Opera	ating Panel					
TY	PE	01	Temperature Sensor, Set Point, Fan Speed and Occupancy Control							
Submit	ter: K	(ieback + Peter	CGMbH							
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit			
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:				
			speed			210255: Stage Auto				
						190209: Stage 0				
						165189:	Stage 1			
						145164:	Stage 2			
						0144:	Stage 3			
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C			
24	4	DB0.7DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-in				
						telegr				
						1: Data	telegram			
29	2	DB0.2DB0.1	Not Used (= 0)							

 31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:	
						1:	Button released
						0:	Button pressed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	02	Temperature Sensor, Set Point, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCu	t Description	Valid Range	Scale Unit		
0	8	DB3.7DB3.0	Turn-switch for	fan FAN	Turn-switch for fan speed	Enum:			
			speed			21025	5: Stage Auto		
		+					9: Stage 0		
						16518	9: Stage 1		
							4: Stage 2		
	L					0144:	Stage 3		
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A		
16	8	DB1.7DB1.0		TMP	Temperature (linear)	2550	0+40 °C		
24	4		Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Tea	ch-in telegram		
						1: Data	a telegram		
29	2		Not Used (= 0)						
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch Day/Night	Enum:	Enum:		
						0: Position I / Night / Off			
							ition O / Day /		
						On	ition 0 / Day /		
					6) % ,				
RO	RG	A5	4B5	S Telegram					
FU	NC	10	Room (Operating Panel	`(),				
TY	PE	03	Temperature S	ensor, Set Point	Control				
					Control				
Offset	_			hortCut	Description Val	lid Range Sc	ale Unit		
0	8		Not Used (= 0)						
8	8	DB2.7DB2.0	Set point SI	Set poi	nt (linear) Min Max+ 0	255 0	.255 N/A		

RORG	A5	4BS Telegram		
FUNC	10	Room Operating Panel		
TYPE	03	Temperature Sensor, Set Point Control		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Not Used (= (0)			
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= (0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-	in telegram
						1: Data te	elegram
29	3	DB0.2DB0.0	Not Used (= (0)			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	04	Temperature Sensor, Set Point and Fan Speed Control

Offset Size Bitrange Data ShortCut Description Range Scale Uni	Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
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0	8		Turn-switch for fan	FAN		Enum:				
			speed			210255:	Stage Auto			
						190209:	Stage 0			
						165189:	Stage 1			
						145164:	Stage 2			
						0144:	Stage 3			
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C			
24	4	DB0.7DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-in telegram 1: Data telegram				
29	3	DB0.2DB0.0	DB0.2DB0.0 Not Used (= 0)							

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	05	Temperature Sensor, Set Point and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data to	elegram	
29	2	DB0.2DB0.1	Not Used (= (0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	<u> </u>
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	06	Temperature Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)					
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegrar legram	<u>n</u>
29	2	DB0.2DB0.1	Not Used $(= 0)$					
31	1		Slide switch 0/I		Slide switch or Slide switch Day/Night	Enum: 0: Position I / Nigh Off 1: Position O / Day On		

FUNC	10	Room Operating Panel
TYPE	07	Temperature Sensor, Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:		
						210255:	Stage Aut	to
						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegra	am
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (= 0)					

			_
RORG	A5		4BS Telegram
FUNC	10		Room Operating Panel
TYPE	08	Ten	perature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:	
						210255: S	tage Auto
						190209: S	tage 0
						165189: S	tage 1
				747	145164: S	tage 2	
						0144: S	tage 3
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-i	n telegram
						1: Data te	legram
29	2	DB0.2DB0.1	Not Used (= 0)	_			
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:	
						1: Button	released
						0: Button	pressed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	09	Temperature Sensor, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8			FAN		Enum:		
			speed			210255: Stage Aut 190209: Stage 0 165189: Stage 1		to
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Not Used (= 0)					

16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255	0 0+40 °C	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0:	Teach-in telegram	
						1:	Data telegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum		
				Day/Night	0:	Position I / Night / Off		
						1:	Position O / Day / On	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0A	Temperature Sensor, Set Point Adjust and Single Input Contact
		·

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0))				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0	()				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegr	am
29	2	DB0.2DB0.1	Not Used (= 0	1)				
31	1	DB0.0	Contact State	СТЅТ	Contact state	Enum: 0: closed 1: open	-	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0B	Temperature Sensor and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Uni
0	16	DB3.7DB2.0	Not Used (= 0))			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0))			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
							in telegram
						1: Data te	elegram
29	2	DB0.2DB0.1	Not Used $(= 0)$))			
31	1	DB0.0	Contact State	CTST	Contact state	Enum:	
						0: closed	_
						1: open	_

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0C	Temperature Sensor and Occupancy Control

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0	16	DB3.7DB2.0	Not Used (=	0)		
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550 0+40 °C
24	4	DB0.7DB0.4	Not Used (=	0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	2	DB0.2DB0.1	Not Used (=	0)		
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:
						1: Button released
						0: Button pressed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0D	Temperature Sensor and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= (0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	255(0	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:		n telegra legram	m_
29	2	DB0.2DB0.1	Not Used (=	0)					
31	1	DB0.0	Slide switch		Slide switch 0/I or Slide switch Day/Night	Enum: 0: 1:	Position Off	I / Night	,

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	10	Temperature and Humidity Sensor, Set Point and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Ra	nge Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C \
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Te	each-in telegi	ram
						1: Da	ata telegram	
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
						1: Bu	utton release	d
						0: Bu	utton pressed	i

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	11	Temperature and Humidity Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (= (0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegrai	m_
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=)	0)				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:		
					Day/Night	0: Position	I / Night	:/
						Off		
							O / Day	/
						On		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	12	Temperature and Humidity Sensor and Set Point

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
				Y		1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	13	Temperature and Humidity Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit			
0	8	DB3.7DB3.0	Not Used (=)	0)						
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100 %			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40 °C			
24	4	DB0.7DB0.4	Not Used (= (ot Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach-	in telegram			
						1: Data te	elegram			
29	2	DB0.2DB0.1	Not Used (= (0)						
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:				
						1: Button	released			
						0: Button	pressed			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	14	Temperature and Humidity Sensor, Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=)	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=)	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegrai	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (= (0)				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:		
					Day/Night	0: Position	I / Night	: /
						Off		
							O / Day	/
						On		

RORG	A5	4BS Telegram			
FUNC	10	Room Operating Panel			
TYPE	15	10 Bit Temperature Sensor, 6 bit Set Point Control			

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	6	DB2.7DB2.2	Set point		Set point (6 bit, linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP 📐	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (= (0)				

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	16	10 Bit Temperature Sensor, 6 bit Set Point Control; Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0	0)				
8	6	DB2.7DB2.2	Set point	SP	Set point (linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (= 0	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegram	
						1: Data	telegram	_
29	2	DB0.2DB0.1	Not Used (= 0	0)				
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
						1: Butto	n released	
						0: Butto	n pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	17	10 Bit Temperature Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=)	0)					
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	1023.	0	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=)	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:		
						0:	Teach-	in telegram	
						1:	Data te	elegram	
29	2	DB0.2DB0.1	Not Used (= (0)					
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum	:		
						1:	Button	released	
						0:	Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TŶPE	18	Illumination, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8	DB2.7DB2.0	Temp Setpoint	TMPSP	Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25		DB0.6DB0.4	Fan Speed LRN Bit	LRNB	Fan Speed LRN Bit	1: S 2: S 3: S 4: S 5: S 6: S 7: O	opeed 0 opeed 1 opeed 2 opeed 3 opeed 4 opeed 5 ff	
						te	elegram ata telegra	am
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED	Occupancy enable/disable; if occupancy is disabled ignore DB0.0 (occu. button)	1: O	ccupancy nabled ccupancy sabled	
31	1	DB0.0	Occupancy button	ОВ		1: B	utton ressed utton eleased	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	19	Humidity, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%

8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 2: Speed 3: Speed 4: Speed 5: Speed 6: Speed 7: Off	d 1 d 2 d 3 d 4	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		n-in telegr telegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy button	ОВ		-	n pressed n released	_
31	1	DB0.0	Occupancy enable/disable	OED		enabl	oancy	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1A	Supply voltage monitor, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

TY	PE	IA	Supply voltage 11	iouitor, re	Occupancy Control	sensor, rai	i Speeu a	iiiu
	-				6),	1		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	SV	0 5.0 V linear (super cap); 251-255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set Point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25		DB0.6DB0.4	Fan speed	FAN	Fan Speed LRN Bit	2: Sp 3: Sp 4: Sp 5: Sp 6: Sp 7: Off Enum: 0: Te	eed 0 eed 1 eed 2 eed 3 eed 4 eed 5	am
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		1: Oc	cupancy abled cupancy abled	
31	1	DB0.0	Occupancy button	ОВ		1: Bu	tton press tton eased	sed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1B	Supply Voltage Monitor, Illumination, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	SV	(super cap) 251 – 255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4		FAN	Fan Speed	2: Sp 3: Sp 4: Sp 5: Sp	eed 0 eed 1 eed 2 eed 3 eed 4 eed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tel	ach-in egram ta telegra	m
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED	92.	1: Oc	cupancy abled cupancy abled	
31	1	DB0.0	Occupancy button	ОВ	70	Enum: 0: Bu 1: Bu	tton press tton eased	ed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1C	Illumination, Illumination Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit			
0	8	DB3.7DB3.0	Illumination		Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx			
8	8	DB2.7DB2.0	Illumination Set Point	ILLSP		0250	01000	lx			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C			
24	1	DB0.7	Not Used (= 0)	ot Used (= 0)							
25	3	DB0.6DB0.4	Fan speed	FAN		2: Spe 3: Spe 4: Spe	eed 0 eed 1 eed 2 eed 3 eed 4				

						6: 7:	Speed 5 Off
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Not Used (= 0)				
30 1 DB	DB0.1		OED		Enum:		
	30 1		enable/disable			0:	Occupancy enabled
						1:	Occupancy disabled
31	1	DB0.0	Occupancy button	ОВ		Enum	:
						0:	Button pressed
					1:	Button released	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1D	Humidity, Humidity Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Humidity Set Point	HUMSP	Humidity Set Point (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 2: Speed 3: Speed 4: Speed 5: Speed 6: Speed 7: Off	1 2 3 4	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegra	am_
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy enable/disable	OED		0: Occupa enable 1: Occupa disable	d	>
31	1	DB0.0	Occupancy button	ОВ			pressed released	_

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1E	see A5-10-1B

RORG A5 4BS Telegram	RORG	A5	4BS Telegram
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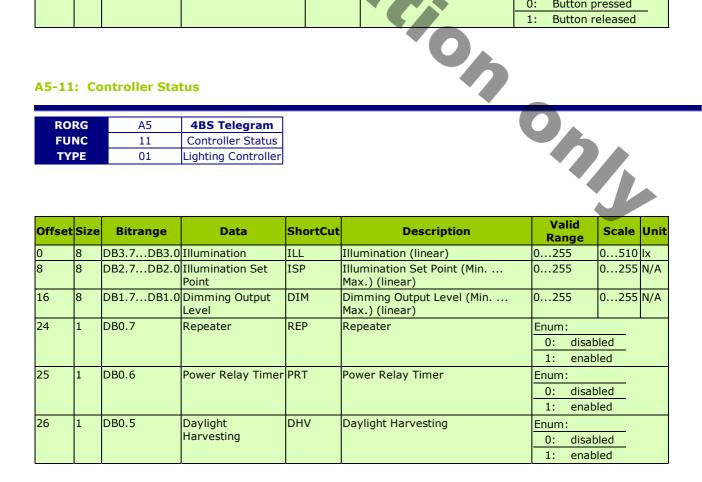
FUNC	10	Room Operating Panel
TYPE	1F	Temperature Sensor, Set Point, Fan Speed, Occupancy and Unoccupancy Control

Submitter: Distech Controls

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN	Turn-switch for fan speed	Enum: 210255: 9	0	
						190209: Stage 165189: Stage 145164: Stage		<u> </u>
							Stage 3	
8	8	DB2.7DB2.0	Set Point	SP	Set point (linear) Min Max+	0255		N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25		DB0.6	Temperature flag	TMP_F	Temperature flag	1: Tempe presen 0: Tempe absent	t rature	
26	1	DB0.5	Set point flag	SP_F	Set point flag	Enum: 1: Set point present 0: Set point absent		
27	1	DB0.4	Fan speed flag	FAN_F	Fan speed flag	Enum: 1: Fan speed presen		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Fan speed absent Enum: 0: Teach-in telegram 1: Data telegram		ım_
29	1	DB0.2	Not Used (= 0)	3		•		
30	1	DB0.1	Unoccupancy	UNOCC	Unoccupancy button	-	pressed	_
24	_			000			released	
31	1	DB0.0	Occupancy	occ	Occupancy button		pressed released	_

A5-11: Controller Status

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	01	Lighting Controller



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27	1	DB0.4	Dimming	EDIM	Dimming	Enum 0: 1:	switching load dimming load
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum 0: 1:	: Teach-in telegram Data telegram
29	1	DB0.2	Magnet Contact	MGC	Magnet Contact	Enum: 0: open 1: closed	
30	1	DB0.1	Occupancy	occ	Occupancy	Enum: 0: unoccupied 1: occupied	
31	1	DB0.0	Power Relay	PWR	Power Relay	Enum 0: 1:	off on

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	02	Temperature Controller Output
ITPE	02	remperature Controller Output

Submitter: Thermokon Sensortechnik GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Control Variable	CVAR	Actual value of controller	0255	0100	%
8	8	DB2.7DB2.0	FanStage	FAN	Actual value of fan	1: Stage 2: Stage 3: Stage 16: Stage 17: Stage 18: Stage	o Manual o 1 Manual o 2 Manual o 3 Manual o 0 Automat o 1 Automat o 2 Automat o 3 Automat o 3 Automat	ic ic
16	8	DB1.7DB1.0	Actual Setpoint	ASP	Occupied: Basic setpoint occupied + Setpoint shift + Sensor offset StandBy: Basic setpoint standBy + Setpoint shift Unoccupied: Basic setpoint unoccupied + setpoint shift	0255	0+51.2	°C
24	1	DB0.7	Alarm	ALR	In case of internal error alarm is set	Enum: 0: No ala 1: Alarm	arm	
25	2	DB0.6DB0.5	Controller mode	СТМ	Actual state of controller	Enum: 1: Heati 2: Coolii 3: Off		
27	1	DB0.4	Controller state	CST	Automatic control, or is controlled from another device	Enum: 0: Autor 1: Overr		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ı-in telegrar telegram	<u>n</u>
29	1	DB0.2	Energy hold-off	ERH	Stop control if window is opened	Enum: 0: Norm		

						1:	Energy hold-off/ Dew point
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum:	Occupied
			, , ,			1:	Unoccupied
						2:	StandBy
						3:	Frost

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	03	Blind Status

Submitter: PEHA / infratec

This controller status is specific for blinds, awning and shutter modules. All modules can use this 4BS telegram to send all information about the status, the position and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Blind/shutter	BSP		0100	0100	%
			pos.					
8	1	DB2.7	Angle sign	AS		Enum:		
						0: Positive sign		
						1: Negative sig	n	
9	7	DB2.6DB2.0		AN	Angle in 2° steps (e.g. 0 = 0°, 90 = 180°)	0180	0360	0
16	1	DB1.7	·	PVF		Enum:		
			flag			0: No Position	value availat	ole
						1: Position valu	ie available	
17	1	DB1.6	Angle value	AVF		Enum:		
			flag			0: No Angle va	lue available	
						1: Angle value	available	
18	2	DB1.5DB1.4	Error state	ES		Enum:		
					6	0: No error pre	sent	
						1: End-position	s are not	
						configured		
						2: Internal failu	ıre	
						3: Not used		
20	2	DB1.3DB1.2	End-position	EP		Enum:		
						0: No End-posit		<u> </u>
						1: No End-posit		
						2: Blind fully or		
						3: Blind fully cl	osed	
22	2	DB1.1DB1.0	Status	ST		Enum:		
						0: No Status av	vailable	
						1: Blind is stop	ped	
						2: Blind opens		
						3: Blind closes		
24	1	DB0.7	Service Mode	SM		Enum:		
						0: Normal mod		
						1: Service mod		
						example for	maintenanc	e)
25	1	DB0.6	Mode of the	MOTP		Enum:		
			position			0: Normal mod		20/
						0% Blind full Blind fully cl		J%
						1: Inverse mod		
						100% Blind)%
						Blind fully cl		
26	2	DB0.5DB0.4	Not Used (= 0)					
28		DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in tele	egram	
						1: Data telegra		
29	3	DB0.2DB0.0	Not Used (= 0)					
	1							

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	04	Extended Lighting Status

Submitter: PEHA / infratec

This status is an extended answer of new lighting-controllers. All modules can use this 4BS telegram to send all information about the status and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	'	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Parameter 1	P1		Enum:			
							Mode 0: Dimm-Va Mode 1: R - Red (I Mode 2: Energy m 15 8) Mode 3: Not used	0 255)	(MSB
8	8	DB2.7DB2.0	Parameter 2	P2		Enum:			
							Mode 0: Lamp ope 8) Mode 1: G - Greer Mode 2: Energy m LSB) Mode 3: Not used	ı (0 255)	
16	8	DB1.7DB1.0	Parameter 3	P3		Enum:			
							Mode 0: Lamp oper LSB) Mode 1: B - Blue (Mode 2: Unit for e Enum: 0 = mW 1 = W 2 = kW 3 = MW 4 = Wh 5 = kWh 6 = MWh 7 = GWh 8 = mA 9 = 1/10 A 10 = mV 11 = 1/10 V 12 15 Not used Mode 3: Not used	0 255)	70
24	1	DB0.7	Service Mode	SM		Enum: 0: 1:			-
25	1	DB0.6	Operating hours	OHF	For Mode 0	Enum:		indirection (cc)	
			flag		, , , , , , ,	0:	No lamp operating	hours availab	ole
						1:	Lamp operating ho		
26	2	DB0.5DB0.4	Error state	ES		Enum:			
						0:	No error present		
						1:	Lamp-failure		
						2:	Internal failure		
						3:	Failure on the exte	ernal peripher	y
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-in telegram	_	
						1:	Data telegram	_	
29	2	DB0.2DB0.1	Parameter Mode	PM		Enum:			
							8 Bit Dimmer Valu	e and Lamp	
						1:	RGB Value		
						2:	Energy metering v	alue	
							Not used		

31	1	DB0.0	Status	ST	Enum	:
					0:	Lighting off
					1:	Lighting on

A5-12: Automated meter reading (AMR)

The meter reading is represented by 3 data bytes, a divisor and a flag that indicates it as a cumulative or a current value. A 4 bit info field gives additional information and is TYPE specific.

RORG	A5	4BS Telegram
FUNC	12	Automated meter reading (AMR)
TYPE	00	Counter

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading	MR	Current value or cumulative counter value	016777215		according to DT
24	4	DB0.7DB0.4	Measurement channel	СН		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	in telegram elegram	- -
29	1	DB0.2	Data type (unit)	DT	Current value or cumulative counter value		ative value	1 1/s
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for counter value	Enum: 0: x/1 1: x/10 2: x/100 3: x/1000		

RORG	A5	4BS Telegram
FUNC	12	Automated meter reading (AMR)
TYPE	01	Electricity

						2: x/1 3: x/1	
RC	RG	A5	48	S Telegra	m		
FU	INC	12	Automated				
T۱	/PE	01		Electricity			
<u>Submi</u>	tter: E	nOcean GmbH		ı		Valid	0
Offse	tSize	Bitrange	Data	ShortCut	Description	Range	Scale Unit
0	24	DB3.7DB1.0	Meter reading	MR	current value in W or cumulative value in kWh	01677721	.5 according to according to DIV
24		DB0.7DB0.4	Tariff info	TI		015	015
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		h-in telegram telegram
29	1	DB0.2	Data type (unit)	DT	Current value or cumulative value	0: Cum	ulative value kWh ent value W
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	Enum: 0: x/1 1: x/10 2: x/10 3: x/10	0

RORG A5 4BS Telegram

FUNC	12	Automated meter reading (AMR)
TYPE	02	Gas

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	meter reading	MR	Cumulative value in m³ or Current value in liter/s	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	1	DB0.2	data type	DT	Current value or cumulative	Enum:		
			(unit)		value	0: Cumul	ative value	m³
						1: Currer	nt value	liter/s
30	2	DB0.1DB0.0	divisor	DIV	Divisor for value	Enum:		
			(scale)			0: x/1	_	
						1: x/10	_	
						2: x/100		
						3: x/1000)	

RORG	A5	4BS Telegram
FUNC		Automated meter reading (AMR)
TYPE	03	Water

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading		Cumulative value in m ³ or Current value in liter/s	016777215		according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram elegram	-
29	1	DB0.2	Data type (unit)	DT	Current value or cumulative value		ative value r	n³ .iter/s
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	Enum: 0: x/1 1: x/10 2: x/100 3: x/1000	9	

A5-13: Environmental Applications

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	01	Weather Station

A receiver that accepts EEP A5-13-01 at teach-in automatically needs to accept telegrams from the same ID that comply to the definitions of EEP A5-13-02 thru EEP A5-13-06. Different telegrams received from that ID need to be distinguished by their 4 bit identifiers.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Dawn sensor	DWS	Dawn sensor	0255	0999	lx
8	8	DB2.7DB2.0	Temperature	TMP	Outdoor Temp	0255	-40+80	°C
16	8	DB1.7DB1.0	Wind speed	WND	Wind speed	0255	070	m/s

24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x1:
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Day / Night	D/N	Day / Night	Enum:
						0: Day
						1: Night
30	1	DB0.1	Rain Indication	RAN	Rain Indication	Enum:
						0: No Rain
						1: Rain
31	1	DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	02	Sun Intensity

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCu	t Do	escription	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Sun – West	SNW	Sun - West,linear		0255	0150	klx
8	8	DB2.7DB2.0	Sun – Soutl	SNS	Sun - South,linear	•	0255	0150	klx
16	8	DB1.7DB1.0	Sun – East	SNE	Sun - East,linear		0255	0150	klx
24	4	DB0.7DB0.4	Identifier	ID	Identifier		Enum: 0x2:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		1: Da	each-in legram ata legram	
29	1	DB0.2	Hemisphere	HEM		uth, then swith Sun south n in southern hemisphere	0: No	orth outh	
30	2	DB0.1DB0.0	Not Used (=	= 0)		10 ₀			
RO	RG	A5	4RS	Telegram			_		
FU		13	Environme						
TY		03	.	Exchange	GETOTIS				
Submit	ter: E	Elsner electronic	<u>cs</u>				Scale		
Offset	Size	Bitrange	Data S	hortCut	Description	Valid Range	Scale	Un	it
0	3	DB3.7DB3.5	Not Used (=	= 0)		<u> </u>			
3	5	DB3.4DB3.0	Day D	Y D	ay	131	31	N/A	

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	03	Date Exchange

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Not Used	(= 0)				
3	5	DB3.4DB3.0	Day	DY	Day	131	131	N/A
8	4	DB2.7DB2.4	Not Used	(= 0)				
12	4	DB2.3DB2.0	Month	MTH	Month (1->January)	112	112	N/A
16	1	DB1.7	Not Used	(= 0)				
17	7	DB1.6DB1.0	Year	YR	Year (0->Year 2000)	099	20002099	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x3:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in teleg	jram	
						1: Data telegran	า	
29	2	DB0.2DB0.1	Not Used	(= 0)				
31	1	DB0.0	Source	SRC	Source	Enum:		
						0: Real Time Clo	ck	
						1: GPS or equiva	lent (e.g. DCF77,	WWV)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	04	Time and Day Exchange

Submitter: Elsner electronics

Recommendation: always transmit time in 24 hrs format

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	e Unit
0	3	DB3.7DB3.5	Weekday	WDY	Weekday (1 ->	Enum:		
					Monday)	1: Monday		
						2: Tuesday		
						3: Wednesday		
						4: Thursday		
						5: Friday		
						6: Saturday		
						7: Sunday		
3	5	DB3.4DB3.0	Hour	HR	Hour	023	023	N/A
8	2	DB2.7DB2.6	Not Used (=	: 0)				•
10	6	DB2.5DB2.0	Minute	MIN	Minute	059	059	N/A
16	2	DB1.7DB1.6	Not Used (=	: 0)				·
18	6	DB1.5DB1,0		SEC	Second	059	059	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:		
						0x4:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in teleg	ram	
						1: Data telegram		
29	1	DB0.2	Time	TMF	Time Format	Enum:		
			Format			0: 24 hours		
						1: 12 hours		
30	1	DB0.1	AM/PM	A/PM	AM or PM	Enum:		
					(C)	0: AM		
						1: PM		
31	1	DB0.0	Source	SRC	Source	Enum:		
						0: Real Time Clo	ck	
						1: GPS or equiva	lent (e.g. l	DCF77,
						WWV)		
RO	RG	A5	4BS 1	elegram				
	NC	13	Environmen		tions			
	PE	05		n Exchange				<u></u>
					_			
Offset				nortCut	Descriptio	n Valid	Range	Scale Unit
Λ.	10	DD2 7 DD2 0	Elavation El	\/	ovation ("OO > borizon"	0 10	0	$\alpha + \alpha \alpha \alpha$

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	05	Direction Exchange

Offset	Si-o	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
Oliset					Description	vallu Kaliye		
0	8	DB3.7DB3.0	Elevation	ELV	Elevation ("0° -> horizon")	0180	-90+90	0
8	7	DB2.7DB2.1	Not Used	(= 0)				
15	9	DB2.0DB1.0	Azimut	AZM	Azimuth ("0° -> True north"; "clockwise")	0359	0359	0
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x5:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegrai elegram	m_
29	3	DB0.2DB0.0	Not Used	(= 0)			•	

RORG	A5	4BS Telegram

FUNC	13	Environmental Applications		
TYPE	06	Geographic Position Exchange		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	4	DB3.7DB3.4	Latitude(MSB)	LAT(MSB)	Latitude MSB	according to LAT(LSB)	according to LAT(LSB)	according to LAT(LSB)		
4	4	DB3.3DB3.0	Longitude(MSB)	` ,		according to LOT(LSB)	according to LOT(LSB)	according to LOT(LSB)		
8	8	DB2.7DB2.0	Latitude(LSB)	LAT(LSB)	Latitude LSB	04095	-90+90	0		
16	8	DB1.7DB1.0	Longitude(LSB)	` ,	Longitude LSB	04095	-180+180	٥		
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x6:				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram				
29	3	DB0.2DB0.0 Not Used (= 0)								

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	10	Sun position and radiation

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	DB3.7DB3.1	Sun Elevation	SNE	Sun Elevation (linear); 91 - 127: reserved	090	090	0
7	1	DB3.0	Day / Night	D/N	Day / Night	Enum: 0: Day 1: Night		
8	8	DB2.7DB2.0	Sun Azimuth	SNA	Sun Azimuth 181 - 255: reserved	0180	-90+90	0
16	8			SRA (MSB)		according to SRA (LSB)	according to SRA (LSB)	according to SRA (LSB)
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x7:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-ir 1: Data tel	n telegram egram	
29	3	DB0.2DB0.0	Solar Radiation (LSB)	SRA (LSB)	Solar Radiation (LSB) (Linear); 20012048: reserved	02000	02000	W/m2

A5-14: Multi-Func Sensor

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	01	Single Input Contact (Window/Door), Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset Size Bitr	ange Data	ShortCut	Description	Valid Range So	cale Unit
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0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250 05.0 V
8	20	DB2.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0)			
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact closed 0b1: Contact open

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	02	Single Input Contact (Window/Door), Supply voltage monitor and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used $(=0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach- telegra 1: Data t		
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contac 0b1: Contac		_

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	03	Single Input Contact (Window/Door), Supply voltage monitor and Vibration

Submitter: Lutuo Technology

					Traite Famo Concor			
TY	PE	03	Single Input Co	ontact (Wi	ndow/Door), Supply voltage monito	r and Vibration		
		<u>.utuo Technolo</u> g): Ventilation, L		. Intrusion	(breakage of glass), Calling system		//	
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Uni
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		n_
29	1	DB0.2	Not Used (= 0))				
30	1	DB0.1	Vibration	VIB		Enum: 0b0: No vibration detected 0b1: Vibration detected		d
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact 0b1: Contact		

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	04	Single Input Contact (Window/Door), Supply voltage monitor, Vibration and Illumination

Submitter: Lutuo Technology

 $\hbox{Purpose (eg): Ventilation, Lighting, Alarm , Intrusion (breakage of glass), Calling \ system}$

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegran	n
						1: Data te	legram	
29	1	DB0.2	Not Used (= 0))				
30	1	DB0.1	Vibration	VIB		Enum:		
						0b0: No vibr detecte		
						0b1: Vibratio	n detecte	d
31	1	DB0.0	Contact	СТ		Enum:		
						0b0: Contact	closed	
						0b1: Contact	open	

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	05	Vibration/Tilt, Supply voltage monitor

Submitter: Lutuo Technology

		_									
RO	RG	A5	4B	S Telegra	m						
FU	NC	14	Multi	Multi-Func Sensor							
TY	TYPE 05 Vibration/Tilt, Supply voltage monitor										
Submitter: Lutuo Technology Purpose (eg): Intrusion (breakage of glass), Calling system											
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit			
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V			
8	20	DB2.7DB0.4	Not Used (= 0))							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele		n			
29	1	DB0.2	Not Used (= 0))			-				
30	1	DB0.1	Vibration	VIB		Enum: 0b0: No vibra detected 0b1: Vibration		d			
31	1	DB0.0	Not Used (= 0))			-				

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	06	Vibration/Tilt, Illumination and Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	٧
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegran legram	<u>n</u>
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Vibration	VIB		Enum: 0b0: No vibr detecte 0b1: Vibratio	d	d
31	1	DB0.0	Not Used (= 0)					

VAC Components

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	01	Battery Powered Actuator (BI-DIR)

DIRECTION-1 = Transmit mode: Message from the actuator to the controller DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB3.7DB3.0	Current Value	CV	Current value	0100 0100 %
8	1	DB2.7	Service On	SO	Service On	Enum:
						1: on
9	1	DB2.6	Energy input enabled	ENIE	Energy input enabled	Enum: 1: true
10	1	DB2.5	Energy Storage	ES	Energy storage sufficiently charged	Enum: 1: true
11	1	DB2.4	Battery capacity	BCAP	Battery capacity; change battery next days	Enum: 0: true
12	1	DB2.3	Contact, cover open	ССО	Contact, cover open	Enum: 1: true
13	1	DB2.2	Failure temperature sensor, out off range	FTS	Failure Temperature sensor, out off range	Enum: 1: true
14	1	DB2.1	Detection, window open	DWO	Detection, window open	Enum: 1: true
15	1	DB2.0	Actuator obstructed	ACO	Actuator obstructed	Enum: 1: true
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255 0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

Offset Size Bitrange Data ShortCut Description	Valid Range	Scale	Unit	
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		i	I					
0	8	DB3.7DB3.0	or	SP	Valve position or Temperature set point (linear); selection with DB1.2	0100 or 255	0100 or +40	% or °C
			Temperature Setpoint		Valve position 0100% in combination with compatible classic controllers the actuator used DB_3;			
					Temperature set point: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).			
8	8	DB2.7DB2.0	Temperature from RCU	TMP	Temperature actual from RCU = 0b0 (Room controller-unit), see DB1.0	2550	0+40	°C
					Maintenance mode ("service on"): DB_2.BIT_5: energy memory sufficiently charged =1			
		*	>		DB_2.BIT_4: battery capacity changing battery in the next days, need changing batteries = 0			
			<u></u>		Status feedback signal (service on, DB_2.BIT_7			
16	1	DB1.7	Run'init sequence	RIN	The limit switching measures the travel and signals when an end position has been reached. This end position (valve zero point) in the actuator is stored.	Enum: 1: tr	ue	
17	1	DB1.6	Lift set	LFS	Initialization, adjustment to the valve stroke. The Initialization is switched after receiving the command. The valve is completely opened and closed during initialization.	Enum: 1: true		
18	1	DB1.5	Valve open / maintenance	VO	After receiving an operation command, the actuator moves the valve in direction open or close. when reaching the end position, an automatic switch-off procedure is started. In service mode the valve can be set to open or closed always.	Enum: 1: tr	ue	
19	1	DB1.4	Valve closed	VC	valve closed	Enum:	ue	
20	1	DB1.3	Summer bit, Reduction of energy consumption	SB	The radio communication between the actuator and the controller is restricted, sleep mode is extended. This functionality can be used for battery powered actuators.	Enum:		
21	1	DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	(C	alve position 0-100%). Un espond to ontroller.	iit
						po Ui ro us	emperature pint 040°C nit respond to com sensor a se internal Pop.	c. to and
22	1	DB1.1	Set point inverse	SPN	Valve set point can be sent to the actuator normal or inverted. The selection is done by DB_1.Bit1. The implementation is done and is controlled in the actuator with DB_3. This function is used in dependence on the type of valve.	Enum: 1: tr	ue	
23	1	DB1.0	Select function	RCU	RCU or "Service on": After transmitting the command to the actuator, it can be send from the		CU ervice on	

					controller or a service device, the actuator sends a status feedback signal (service on, DB_2.BIT_7).	
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			•

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	02	Basic Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

Basic Actuator can be used by any manufacturer for linear or rotary actuator.

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator. To use with a BAS/Gateway system; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual Value	~	Actual value (linear); can be a linear or rotation motion.	0100	0100	%
8	14	DB2.7DB1.2	Not Used	(=0)				
22	1	DB1.1	Set point inverse		Set point inverse (Needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer	Enum: 1: t	rue	
24	4	DB0.7DB0.4	Not Used	(= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: [each-in elegram Data elegram	
29	3	DB0.2DB0.0	Not Used	(= 0)				

						Valid		
Offset	Size	Bitrange	Data	ShortCut	Description	Range	Scale	Unit
0	8	DB3.7DB3.0		VSP	Valve set Point (linear)	0100	0100	%
			Set					
_	_		point					
8		DB2.7DB2.0		` ,				
16	6	DB1.7DB1.2	Not Used	d (= 0)				
22	1		Set point inverse	VSP	"Set point inverse " needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer. It can send a command to invert functionality of the unit. In some instance some equipment might need 100% to represent fully extracted, in other fully retracted.	Enum: 1: t	rue	
23	5	DB1.0DB0.4	Not Used	d (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: 7	each-in	
						t	elegram	
						1: [Data	
						t	elegram	
29	3	DB0.2DB0.0	Not Used	d (= 0)				

RORG	A5	4BS Telegram

FUNC	FUNC 20 HVAC Components					
TYPE	03	Line powered Actuator (BI-DIR)				

Submitter: Spartan Peripheral Devices

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual valve	AV	Actual valve	0100	0100	%
8	8	DB2.7DB2.0	Not Used (=)	0)		_	ā.	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+40	°C
24	4	DB0.7DB0.4	Not Used (=)	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegr	am
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used (= (0)				

DIRECTION-2

DIKECI	TON	_							
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Actuator or Temperature Setpoint	ATS	Actuator Setpoint: in combination with BAS/Gateway controllers. Temperature Setpoint: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU).	0100 or 255	0100 or +40	% or °C	
8	8	DB2.7DB2.0	from RCU	· ·	Temperature actual from RCU = 0b0 (Room controller-unit)	2550	0+40	°C	
16	5	DB1.7DB1.3	Not Used $(= 0)$		· (C)				
21		DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	Enum: 0: Actuator Setpoint (0-100%); Unit respond to controller. 1: Temperature Setpoint 0+40°C; Unit respond to room sensor and use internal PI loop.			
22		DB1.1	Set Point Inverse		Valve set point can be sent to the actuator normal or inverted through BAS/Gateway controller. The selection is done by DB_1.Bit1. in the actuator with DB_3. This function is used in dependence on the type of valve.	Enum: 1: tru			
23	5	DB1.0DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
							ch-in teleg a telegram	_	
29	3	DB0.2DB0.0	Not Used $(= 0)$						

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	10	Generic HVAC Interface (BI-DIR)

Submitter: Intesis Software SL

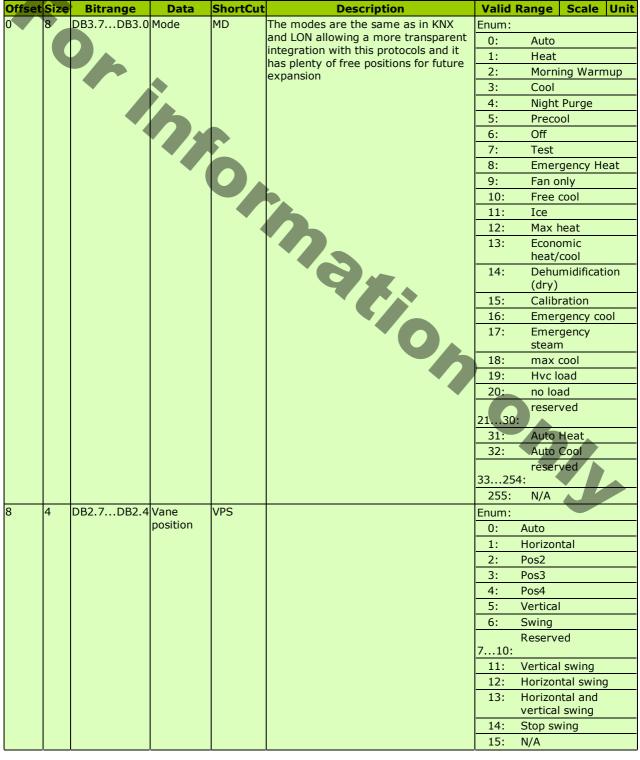
Functions: Mode, Vane Position, Fan Speed, Sensors and On/Off: With this EEP plus the already existing EEP A5-10-03

and A5-20-11 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

Offset	_		Data	ShortCut	Description	Valid I	Range	Scale	Unit
0		DB3.7DB3.0		MD	The modes are the same as in KNX and				
					LON allowing a more transparent	0:	Auto)	
					integration with this protocols and it	1:	Hea		
					has plenty of free positions for future	2:		ning Warr	mun
					expansion	3:	Coo		пир
						4:			
								t Purge	
						5:	Prec	001	
						6:	Off		
						7:	Test		
						8:		rgency H	eat
	•					9:		only	
						10:	Free	cool	
						11:	Ice		
						12:	Max	heat	
						13:		nomic	
							heat	:/cool	
						14:	Deh	umidificat	ion
							(dry		
						15:		oration	
						16:	Eme	rgency co	ool
						17:		rgency	
							stea	m	
						18:	max	cool	
						19:	Hvc	load	
				(20:	no lo	oad	
							rese	rved	
						2130	:		
					163	31:	Auto	Heat	
						32:	Auto	Cool	
								rved	
						3325	4:		
						255:	N/A		
8	4	DB2.7DB2.4	Vane	VPS		Enum:			
			position			0:	Auto		
						1:	Horizo	ntal	
						2:	Pos2		
						3:	Pos3		
						4:	Pos4		
						5:	Vertic	al	
						6:	Swing		
						0.	Reser		,
						710:	itesei	Ved	
						11:	Vertic	al swing	
						12:		ntal swin	a
						13:		ntal and	3
						13.		al swing	
						14:	Stop s		
						15:	N/A		
12	4	DB2.3DB2.0	Fan Sneed	FANSP	fan speed value goes from 1 to 14. 1 is		-,		
12	'	552.5552.0	an Speed		the lowest fan speed allowed by the AC	0:	Auto		
					and from there it increments with the	U:		1.4 for on	oods
					value of this variable. Typically AC	1 14:		14 fan spe 1 the low	
					units have up to 5-6 speeds. Any speed	15:	N/A	I the low	CSC
					higher than the maximum the AC	15:	IV/A		
					allows would set it to the higher speed.				
16	0	DD1 7 DD1 0	Control	CVAD	0 is auto and 15 is N/A	0 100	255	0 100	0/
16	8	DB1.7DB1.0	Control variable	CVAR	Control variable; value 255 = auto	0100,	255	0100	70
24	4	DB0.7DB0.4		= O)					
24	7	טטט.,	ivor osea (<u> </u>					

28		1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
							0:	Teach-in telegram
							1:	Data telegram
29		2	DB0.2DB0.1	Room	RO	The interfaces can automatically	Enum:	
	оссир	occupancy		control the behaviour of the AC without	0:	Occupied		
					integration in automation systems when linked to presence/movement sensors.	1:	StandBy (waiting to perform action)	
						SCHS013.	2:	Unoccupied (action performed)
							3:	Off (no occupancy and no action)
31		1	DB0.0	On/Off	O/I	On/Off	Enum:	
					0:	off (the unit is not running)		
							1:	on



12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1 is the lowest fan speed allowed by the AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A	Enum: 0: 114: 15:	Auto Up to 1	.4 fan spe . the lowe	eds
16	8	DB1.7DB1.0	Control variable	CVAR	Control variable (linear); value 255 = auto	0100), 255	0100	%
24	4	DB0.7DB0.4	Not Used (:	= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	D: Teach-in telegram		
29	2	DB0.2DB0.1	Room occupancy	RO	Room occupancy	Enum: 0: 1: 2: 3:	Occupie StandBy perform Unoccup perform	(waiting action) wied (action) ed) occupancy	n
31	1	DB0.0	On/Off	O/I	On/Off	Enum: 0: 1:	off on		

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	11	Generic HVAC Interface - Error Control (BI-DIR)

Submitter: Intesis Software SL

Error Control: AC Error Code, Error States and Disablements. With this EEP plus the already existing EEP A5-10-03 and A5-20-10 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rang	Scale	Unit
0	23	DB3.7DB1.1	Not Used (= 0)					
23	1	DB1.0	External disablement	EXDS	External disablement		Not disable Disabled	d_
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1	Teach-in celegram Data telegr	am
29	1	DB0.2	Disable remote controller	DRC	Disable remote controller (When in receive mode it controls if the interface overwrites the remote controller commands.)	1:	Enable Ren controller Disable Remote controller	note
30	1	DB0.1	Window contact	WC	Window contact	1:	Windows opened Windows closed	
31	1	DB0.0	Not Used (= 0)					

Offset Size Bitrange Data ShortCut Description Valid Scale Uni	Offset Size	Bitrange	Data	ShortCut	Description	Valid	Scale	Unit
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						Range		
0	16	DB3.7DB2.0	Error Code	ERR	Error Code (DB3 HI,DB2 LO); generated by A.C.		5 065535	N/A
16	4	DB1.7DB1.4	Reserved	RES	Reserved (0b0000)	Enum: : R	eserved	
20	1	DB1.3	Other disablement	OD	Manufacturer defined. It is just to provide an extra "disablement signal" that could be used for other devices. People would not have to change anything then as this is already an established "signal"		ot disabled isabled	-
21	1	DB1.2	Window contact disablement	WCD	Window contact disablement		ot disabled isabled	- -
22	1	DB1.1	Key card disablement	KCD	Key carddisablement		ot disabled isabled	-
23	1	DB1.0	External disablement	ED	External disablement		ot disabled isabled	-
24	4	DB0.7DB0.4	Not Used $(= 0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	te	each-in elegram ata telegram	n
29	1	DB0.2	Remote controller Disablement	RCD	Remote controller Disablement (In transmit it sends the status of this parameter. If the manufacturer doesn't support this option, it will send allways 0, no matter what it receives.)	0: R c e 1: R	emote ontroller nabled emote ontroller sabled	
30	1	DB0.1	Window contact	WC	Window contact		indows oper	
31	1	DB0.0	Alarm State	AS	Alarm State	Enum: 0: C 1: E	k	

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	12	Temperature Controller Input

					Y (),					
RO	RG	A5	4BS Telegrar	n						
FU	NC	20	HVAC Compone	nts						
TY	PE	12	Temperature Control	ler Input						
	_		sortechnik GmbH			9	2/2			
Offset	_		Data	ShortCut	Description	Valid Range	Scale	Unit		
0	8		Control Variable override	CV	Actual value for controller	0255	0100	%		
8	8	DB2.7DB2.0	FanStage override	FANOR	FanStage override	Enum: 0: Stage 0 1: Stage 1 2: Stage 2 3: Stage 3 31: auto 255: not ava				
16	8	DB1.7DB1.0	Setpoint shift	SPS	Actual set point could be shifted	0255	-10+10	°K		
24	1	DB0.7	Fan override	FANOR		Enum: 0: Automa 1: Overrid	tic e Fan DB2	-		
25	2	DB0.6DB0.5	Controller mode	СТМ		Enum: 0: Auto model 1: Heating 2: Cooling	<u> </u>			

						3:	Off	
27	1	DB0.4	Controller state	CST	Controller state	Enum	:	
						0:	Automatic	
						1:	Override control variable DB3	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0:	Teach-in telegram	
						1:	Data telegram	
29	1	DB0.2 Energy hold-off / ERH Energy hold-off /		Energy hold-off / Dew	Enum	Enum:		
			Dew point		point	0:	Normal	
						1:	Energy hold-off/ Dew	
							point	
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	y Enum:		
						0:	Occupied	
						1:	Unoccupied	
						2:	StandBy	
						3:	Frost	

A5-30: Digital Input

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	01	Single Input Contact, Battery Monitor

Offset	Size	Bitrange	Data	ShortCut	Description	n	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)						
8	8	DB2.7DB2.0	Supply voltage	SVC	Supply voltage ((linear)		ttery LO ttery Ok	
16	8	DB1.7DB1.0	Input State	IPS	Input State		Enum: 0195: Co 196255: Co	ntact clo	
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum: 0: Teach-in 1: Data tele		m_
29	3	DB0.2DB0.0	Not Used (= 0)						

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	02	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	28	DB3.7DB0.4	Not Used (=	= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-ir	n telegr	am
						1:	Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	= 0)					
31	1	DB0.0	Input State	IPS	Input State	Enum:			
						0:	Contact	closed	
						1:	Contact	open	

A5-37: Energy Management

RORG	A5	4BS Telegram
FUNC	37	Energy Management
TYPE	01	Demand Response

Submitter: Echoflex Solutions Inc.

Purpose of EEP:

Demand Response is a developing standard to allow utility companies to send requests for reduction in power consumption during peak usage times. It is also used as a means to allow users to reduce overall power consumption as energy prices increase. Having an EEP for this will allow ease of integration with EnOcean products to this standard. The EEP was designed with a very flexible setting for the level (0-15) as well as a default level whereby the transmitter can specify a specific level for all controllers to use (0-100% of either maximum or current power output, depending on the load type). This EEP also includes a timeout setting to indicate how long the DR event should last if the DR transmitting device does not send heartbeats or subsequent new DR levels.

Description

This EEP is included under a new function of Energy Management. Additional types could be added in future for power, voltage, and current data. The proposed EEP type 01 only deals with demand response activation at this point. Data Byte 3 is the default DR value for devices that implement a control algorithm that uses a set-point. It will be used for any controllers not supporting the current DR Level in the message and having an adjustable set-point.

Data Byte 2 is the default DR Level for any controllers not supporting the current DR Level in the message and having an adjustable control. It can be defined as either a percentage of the maximum power or a percentage of the current power, depending on the value of bit 7 in Data Byte 2. Bits 0 through 6 contain the percentage of power (either relative or absolute) that should be used. A value of 0 corresponds to 0% and a value of 100 corresponds to 100%. Any value higher that n100 should be interpreted as 100%. For example, if the current DR level is not supported by the controller and Data Byte 2 bit 7 is 0 and Data Byte 2 bits 0 through 6 are set to 55, then the controller should try to use 55% of its maximum power usage. In the case of a lighting load with 0-10V dimming, this would correspond to 5.5V on the dimming line. In the case of a heating controller with a maximum set back of 5 degrees C, this would correspond to a set back of 2.75 degrees C (this would most likely be rounded to 3).

Data Byte 1 is the timeout for this DR event. After this command is sent the controller will stay at the DR level for Data Byte 1 multiplied by 15 minutes. Once this time has elapsed the controller will return to normal operation. If Data Byte 1 is 0 then the controller will remain in the DR event until the next DR command is received. This timeout allows DR devices to leave or turn off after setting controllers into a DR state, thus the DR transmitter is not needed to take the devices out of the DR state and the controllers will automatically recover. For example a DR transmitter that only sends messages when a DR event is active could be used with the timeout to create a successful DR system.

Data Byte 0, Bits 7 through 4 make up a nibble that will be used as the DR level. Levels 0 through 15 will be possible using these bits. Bit 4 will be the lowest bit in this nibble and bit 7 will be the highest. If any level is not supported by a controller then that controller should use the default settings sent in this message or map the level to one that it supports.

Data Byte 0 Bits 2 and 1 indicate whether the power adjustment at start and end of the DR event should be randomized or not. This feature is intended to minimize rapid changes on the power distribution equipment by delaying each controller's response. If random start or end is enabled, each controller will delay starting or ending the DR event by a random time that will vary uniformly over a specific time period (for example, 5 seconds, 60 seconds, or 15 minutes).. The maximum length of these random delays will depend on the implementation in the controller.

Data Byte 0, Bit 0 is the state for loads that are not adjustable for the default DR level. If a controller does not support the current DR level and does not have adjustable control then it should use this bit. The two states of this bit are defined as follows: 1 = maximum power usage by controller, 0 = minimum power usage by the controller. If for example lights are being controlled, then a setting of 1 will mean the lights should be ON, where as a setting of 0 will mean the lights should be OFF. For a thermostat application with non adjustable set back, a setting of 1 will mean that no set back should be applied, whereas a setting of 0 will mean that the full set back should be applied. This setting only applies to the maximum power usage of the controller, if for example the lights are currently off and the controller receives a DR event with this bit set, then the lights should not turn ON as the DR event has only set the maximum power usage for the device.

Offset	Size	Bitrange	Data	ShortCut	Description	Val	id Range	Scale	Unit
0	8	DB3.7DB3.0	Temporary default		New Temporary default DR set point Min Max. (linear)	025	5	0255	N/A
8	1	DB2.7	Absolute/relative	SPWRU		Enum			
			power usage			0:		ver usage. DB_2.BIT_0 of the maximu	
						1:		ver usage. DB_2.BIT_0 of the current	as a

9	7	DB2.6DB2.0	Power Usage	PWRU	0% to 100% power usage in 1% increments; 101127 = interpreted as 100%	0100	0100	N/A
16	8	DB1.7DB1.0	Timeout Setting	TMOS	Time in 15 min. intervals; 0 = No time specified; 1255 = increasing 15 min. intervals. Max value: 3825 = 255*15	1255	153825	min
24	4	DB0.7DB0.4	DR Level	DRL	DR Level	015	015	N/A
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in to 1: Data teleg		
29	1	DB0.2	Random start delay	RSD		Enum: 0: False 1: True		
30	1	DB0.1	Randomized end delay	RED		Enum: 0: False 1: True		
31	1	DB0.0	Max/Min Power Usage for Default DR State	MPWRU			Power usage Power usage	

A5-38: Central Command

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	08	Gateway

Communication between gateway and actuator uses byte DB_3 to identify Commands. Commands 0x01 to 0x7F shall be common to all types belonging to this profile. Commands 0x80 to 0xFE can be defined individually for each device type.

0x01 Switching

	imon	to all types bel			s byte DB_3 to identify Commands. Commands 0x80 to 0xFE can be defined in	individually for each device
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x01:
8	16	DB2.7DB1.0	Time	TIM	Time in $1/10$ seconds. $0 = no$ time specifed	165535 0.16553.5 s
24	4	DB0.7DB0.4	Not Used (=)	0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Lock/Unlock	LCK	Lock for duration time if time >0, unlimited time of no time specified. Locking may be cleared with "unlock". During lock phase no other commands will be accepted or executed	Enum: 0: Unlock 1: Lock
30	1	DB0.1	Delay or duration	DEL	Delay or duration (if Time > 0); 0 = Duration (Execute switching command immediately and switch back after duration) 1 = Delay (Execute switching command after delay)	Enum: 0: Duration 1: Delay

31	1	DB0.0	Switching	SW	Switching Command ON/OFF	Enum:	
			Command			0:	Off
						1:	On

0x02 Dimming

REMARK:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:	_	
						0x02:		
8	8		Dimming value	EDIM	Dimming value (absolute [0255] or relative [0100])	0255	0100	%
16	8		, p 3	RMP	Ramping time in seconds, $0 = no$ ramping, $1 255 = seconds$ to 100%	0255	0255	S
24	4		Not Used (= 0)			•		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tele 1: Da	ach-in egram ta egram	
29	1	DB0.2	Dimming Range	EDIM R	Dimming Range	val	solute ue lative va	lue
30	1	DB0.1	Store final value	STR	Store final value	Enum: 0: No 1: Yes	<u>—</u>	
31	1	DB0.0	Switching Command	SW	Switching Command ON/OFF	Enum: 0: Off 1: On	_	
	_	oint shift <u>'hermokon Sen</u>	sortechnik Gmb	<mark>H</mark>	inter compensation			
			, for example su	ımmer / w	inter compensation			
Offset 0	Size 8		Data Sho Command COM		cription Valid Range Scale Unit			

0x03 Setpoint shift

Submitter: Thermokon Sensortechnik GmbH

Used fo	r chai	nging set point	, for exam	ole summe	er / winter com	pensation		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x03:		-
8	8	DB2.7DB2.0	Not Used ((= 0)		_	-	
16	8	DB1.7DB1.0	Setpoint	SP	Setpoint shift	0255	-12.712.8	8 K
24	4	DB0.7DB0.4	Not Used ((= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	_
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used ((= 0)				

0x04 Basic Setpoint

Submitter: Thermokon Sensortechnik GmbH

Send a new basic set point via DDC to an actuator

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x04:		
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Basic Setpoint	BSP	Basic Setpoint	0255	0+51.2	2°C

24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

0x05 Control variable

Submitter: Thermokon Sensortechnik GmbH

Set occupancy, energy holdoff and control directly actuator

Offset	Size		Data	ShortC	ut Descrip	tion Vali	id Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum 0x0			
8	8	DB2 7 DB2 0	Not Used (= 0)			0.00	J.		
16	8		Control variable override	CVOV	Control variab	ole 025	55	0100	%
24	1	DB0.7	Not Used (= 0)		override				
25	2		Controller mode	СМ	Controller Mod	de <u>Enum</u> 0: 1: 2: 3:	Automatic selection Heating Cooling	mode	
27	1	DB0.4	Controller state	CS	Controller stat				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum 0: 1:	: Teach-in to Data teleg		_
29	1	DB0.2	Energy hold off	ENHO	Energy Hold C	0: 1:	Normal Energy holpoint	Idoff/ Dev	W
30	2	DB0.1DB0.0	Room occupancy	RMOCC	Room occupar	0: 1: 2:	: Occupied Unoccupied Standby	<u>d</u>	
<u>Submit</u>	tter: 7	stage <u>Thermokon Sen</u> fan stage	sortechnik GmbH				Scale Unit		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit		
0	8	DB3.7DB3.0			ommand ID	Enum: 0x06:			

0x06 Fan stage

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:
						0x06:
8	8	DB2.7DB2.0	Not Used (= 0)			
16	8	DB1.7DB1.0	FanStage override	FO	FanStage override	Enum:
						0: Stage 0
						1: Stage 1
						2: Stage 2
						3: Stage 3
						255: Auto
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)	•		

0x07 Blind Central Command

Submitter: PEHA / infrated

With this central command all blinds, awnings and shutters can be manipulated.

Remarks for data table:

REMARK 1:

The angle is usually available in blinds and awning modules.

Normally, in shutter modules the angle value is ignored.

The angle value can be set from -180° (e.g. maximum slat angle at the fully SHUT position) to 180° (e.g. maximum slat angle at the fully OPEN position).

© EnOcean Alliance

The byte is set with following rule:

Bit7: Sign of the slat angle (0 = positive value, 1 = negative value)

Bit6..0: Slat angle value in 2° steps (e.g. 50 = 100°)

REMARK 2:

If this function (Blind drives to position with angle value) is not supported or not configured, use following rule:

- Position is 0 to 49% -> The blind opens
- Position is 50 to 100% -> The blind closes.

REMARK 3:

Conventional blinds and shutters can be configured with these 3 parameters to calculate the sufficiently accurate position and angle of the blind.

RFMARK 4

With this command you can adjust the minimal and maximal position of the blinds. So it's possible to override the running-range of blinds via a central control unit. Local operations are restricted and increase safety (e.g. to open blinds in case of wind or fire).

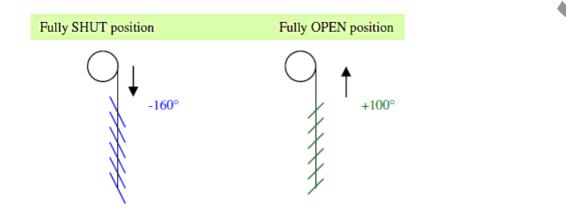
Condition: The Minimal value must be smaller or equal the maximal value.



Example to lock the local functionality: Drive the shutters to a define position and set the minimal and maximal values to this position.

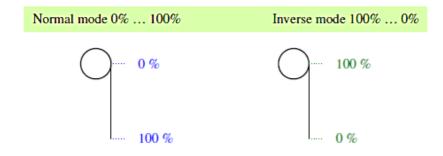
REMARK 5:

These to angle values describe the maximum slat angle at the fully SHUT position and the maximal slat angle at the fully OPEN position. With the time parameter, e.g.:



REMARK 6:

Set the position logic for the blind control and visualization.



Note: If the mode is changed, the minimum and maximal values (function 9) are converted as well!

REMARK 7:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

Offset				ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x07: Shutters / Blinds		
8	8	DB2.7DB2.0	Parameter 1	P1	Function defined	Enum:		
					parameter value	Func. 00: not use	d	
						Func. 01: not use	d	
						Func. 02: not use	d	
						Tune. 02 not use	u -	
					30	Func. 03: not use	d	
						* • • • • • • • • • • • • • • • • • • •	001	
						Func. 04: 0% 10 e.g.: 0% = Blind ful		no/- -
						Blind fully closed	ny open / 100	J70 —
						Contract of the contract of th		
						Func. 05: 0 255 s	seconds	
						Func. 06; 0 255 s	sacando	
						Turic. 00. 0 255 s	seconds	
						Func. 07: Runtime	value to close	the
						blind		
						0 255 seconds		
						Func. 08: Runtime	value for the	sunblind
						reversion time		
						This is the time to r	evolve the su	ınblind
						from one slat angle end posit	ion to the oth	or and
						position:	ion to the oti	iei eilu
						0.0 25.5 seconds	(0.1s steps)	
						Func. 09: Set minim 0 100%	nal position v	alue
						0 100 70		
						Func. 10: Angle at t	he fully SHU	Г
						position		
						Bit7 0 = positive sig		
						Bit7 1 = negative si Bit60 0 90	gii	
						Angle in 2° steps (e	.g. $0 = 0^{\circ}, 9$	0 =
						180°)		
						Funo 11, Docition Is	naio	
						Func. 11: Position lo 0 = Highest position		est
						position = 100%	1 – 070 / LOW	CSC
						1 = Highest position	n = 100% / L	owest
						position = 0%		

16	8	DB1.7DB1.0	Parameter 2	D2	Function defined	Enum:
10	0	DD1.7DD1.0	Parameter 2	P2	parameter value	Func. 00: not used
						Func. 01: not used
						Func. 02: not used
						Func. 03: not used
						Func. 04: Angel (see remark 1)
						Bit7 0 = positive sign
						Bit7 1 = negative sign Bit60 0 90
						Angle in 2° steps (e.g. 0 = 0°, 90 = 180°)
						Func. 05: 0.0 25.5 seconds
						Func. 06: 0.0 25.5 seconds
						Func. 07: Runtime value to open the blind
						0 255 seconds
						Func. 08: not used
						Func. 09: Set maximal position value
			\times			0 100%
			5			Func. 10: Angle at the fully OPEN
						position Bit7 0 = positive sign
						Bit7 1 = negative sign Bit60 0 90
						Angle in 2° steps (e.g. 0 = 0°, 90 =
						180°)
2.6		DD0 7 550	E	FILINIC		Func. 11: not used
24	4	DB0.7DB0.4	Function	FUNC		Enum: 0: Do nothing, status request
						1: Blind stops
						2: Blind opens
						3: Blind closes
						4: Blind drives to position with angle value (see remark 2)
						5: Blind opens for time (position value) and
						angle (angle value) 6: Blind closes for time (position value) and
						angle (angle value)
						7: Set Runtime parameters (see remark 3)
						8: Set angle configuration (see remark 3)
						9: Set Min, Max values (see remark 4)
						10: Set slat angle for SHUT and OPEN position (see remark 5)
						11: Set position logic (see remark 6)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
29	1	DB0.2	Send status	SSF	see remark 7	1: Data telegram Enum:
			flag			0: Send new status of device
						Send no status (e.g. Global central commands)
30	1	DB0.1	Pos. and	PAF		Enum:
			Angle flag			0: No Angle and position value available
- (1: Angle and position value available
31	1	DB0.0	Service Mode Flag	SMF		Enum:
						0: Normal operation 1: Service mode: The module disables all
						senders, except this sender, which has
						set the service mode. (For example for maintenance)
						,

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	09	Extended Lighting-Control

Submitter: PEHA / infrated

With this central command all lighting actors can be manipulated.

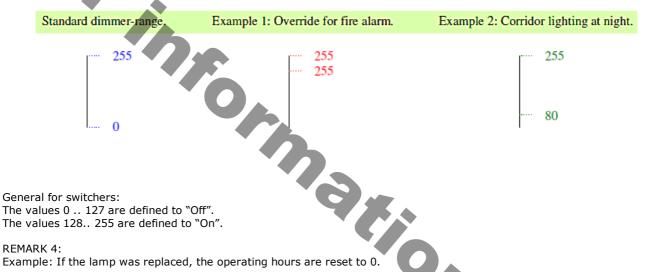
Remarks for data table:

REMARK 1:

Set the RGB level for corresponding lighting-control. Devices without this feature ignore this command.

Up to 16 different scenes can be selected and configured.

Change the minimal and maximal dimmer-value. Example:



General for switchers:

The values 0 .. 127 are defined to "Off". The values 128.. 255 are defined to "On".

REMARK 4:

Example: If the lamp was replaced, the operating hours are reset to 0.

This function blocks all other commands from the other taught-in transmitters. The transmitter, which has called this function, must delete the blocking state, before the other transmitters can use the device again.

REMARK 6:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

REMARK 7:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Parameter			Enum:			
			1		parameter value	Func. 00: not used Func. 01: not used			
					Func. 02: not used				
						Func. 03: not used			
						Func. 04: not use	ed		
						Func. 05: not use	ed		
						Func. 06: Dimm-Va	lue (0 255)	
						Func. 07: R - Red (0 255)		

						Func. 08: not used
						Func. 09: Dimm-Value (0 255)
						Func. 10: Lamp operating hours (MSB 158)
						Func. 11: not used
0	0	DD2 7 DD2 0		D 2		Func. 12: Energy metering value (MSB 158)
8	8	DB2.7DB2.0	Parameter 2	P2	Function defined parameter value	Enum: Func. 00: not used
						Func. 01: not used
						Func. 02: not used
						Func. 03: Ramping time (MSB 158) (65535 s)
						Func. 04: Ramping time (MSB 158) (65535 s)
						Func. 05: not used
						Func. 06: Ramping time (MSB 158) (65535 s)
						Func. 07: G - Green (0 255)
						Func. 08: not used
						Func. 09: Dimm-Value (0 255)
						Func. 10: Lamp operating hours (70 LSB)
				·		Func. 11: not used
					(5)	Func. 12: Energy metering value (70 LSB)
16	8	DB1.7DB1.0	Parameter 3	P3	Function defined parameter value	
						Func. 01: not used Func. 02: not used
						Func. 03: Ramping time (70 LSB) (65535 s)
						Func. 04: Ramping time (70 LSB) (65535 s)
						Func. 05: not used
						Func. 06: Ramping time (70 LSB) (65535 s)
						Func. 07: B - Blue(0 255)
						Func. 08: Bit7: 0 = Drive to scene-value
						Bit7: 0 = Drive to scene-value Bit7: 1 = Stores actual value in the scene
						Bit30: Scene number 0 15
						Func. 09: not used
						Func. 10: not used
						Func. 11: Blocks the local operations Enum:
						0 = Unlock local operations 1 = Locking switch on commands
						2 = Locking switch off commands

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A5-3F: Universal

RORG	A5	4BS Telegram		
FUNC	3F	Universal		
TYPE	00	Radio Link Test (BI-DIR)		

Submitter: PROBARE

Units supporting the EEP Radio Link Test shall offer a functionality that allows for radio link testing between them (Position A to Position B, point-to-point only). Testing shall be possible without the need for prior teach-in and as an option it shall cover two way communications.

Further, testing shall be backward compatible to existing EnOcean installations that support at least 1BS (RORG=0xD5) and 4BS (RORG=0xA5) EnOcean messages.

The main area of RLT application are in-field testing of radio links between portable test equipment placed at different

locations as well as between portable test equipment and fixed installation, e.g. an EnOcean Gateway.

Functional description of RLT:

When two units perform radio link testing one unit needs to act in a mode called RLT Master and the other unit needs to act in a mode called RLT Slave. On a RLT enabled unit one or both modes may be supported. The mode(s) supported shall require explicitly activation at run time.

After activation a RLT Master listens for RLT_Query messages. On reception of at least one RLT_Query message a RLT Master responds with an RLT_Response message. Following that it starts transmission of RLT_MasterTest messages within a maximum time frame of 250ms and awaits the response from the RLT Slave for each RLT_MasterTest message sent. A radio link test communication consists of a minimum of 16 and a maximum of 256 RLT_MasterTest messages. Timing distance between individual RLT_MasterTest messages shall not exceed 250ms. When the radio link test communication is completed the RLT Master gets deactivated automatically.

After activation a RLT Slave periodically transmits RLT_Query messages (1 message / 2s). It stops transmission of RLT_Query messages as soon as it has received at least one RLT_Response message. It then waits for RLT_MasterTest messages from the same EnOcean ID and replies to them within a maximum delay of 100ms thru RLT_SlaveTest messages. If it does not receive RLT_MasterTest messages from the same EnOcean ID for a time period of 5s, the RLT Slave restarts periodic transmission of RLT_Query messages. The RLT Slave requires explicit deactivation.

RLT_Query Message

This Message is a "4BS Teach-In Query" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process.

RLT_Response Message

This Message is a "4BS Teach-In Response" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process. As a RLT Master does accept teach-in of a RLT Slave only for the time period required by a single RLT communication it shall indicate the EEP to be supported but the EnOcean ID of the RLT Slave not to be stored permanently.

RLT MasterTest 4BS

This is the 4BS message sent by the RLT Master during a radio link test communication **DIRECTION-1**

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	28	DB3.7DB0.4	Not Used (=	0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	MSG_ID	MSGID	Message ID	Enum: 2:
31	1	DB0.0	MSG-Source	MSGS	Message Source	Enum: 0: RLT-Master

RLT_SlaveTest_4BS

							0:	RLT-Mast	ter			
This is	RLT_SlaveTest_4BS This is the 4BS message sent by the RLT Slave in reply to an RLT_MasterTest_4BS message. DIRECTION- 2											
Offse	tSize	Bitrange	Data	Sho	ortCut		Des	scription		Va Rar	5	cale Unit
0	2	DB3.7DB3.6	Sub-Telegram Counter	n STO				MasterTes ved Repeat		0: 1: 2: 3:	not supp 1 sub tel 2 sub tel ≥ 3 sub telegran	legram legram
2	6	DB3.5DB3.0	RSSI Level in	dBm RSI				MasterTes ved Repeat	er level 1	0x00: 0x01: 0x02:	not supporte ≥-31	ed dBm

					0.05	≤-93	dBm
8	DB2 7 DB2 0	Sub-Telegram	RSLV	Related to RLT MasterTest 4BS			
ŭ	5521711155210	Counter/RSSI Level in dBm		message received Repeater level 1 (for details see DB3)		See prev	
8	DB1.7DB1.0		RSLV	Related to RLT_MasterTest_4BS	Enum:		
		Level in dBm			:	See prev	
4	DB0.7DB0.4	RSSI Level in dBm	RSLV		Enum:		
				Level with 6dB quantization steps	0×00:		
						≥ -31	dBm
					0x02:		dBm
					0x03:		dBm
					0x04:		dBm
					0x05:		dBm
					0x06:		dBm
					0x07:		dBm
					0x08:		dBm
					0x09:		dBm
					0x0A:		dBm
					0x0B:	≤ -92	dBm
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						Teach-in telegram	
					1:	Data telegr	am
2	DB0.2DB0.1	MSG_ID	MSGID	94.	Enum: 2:	_	
1	DB0.0	MSG-Source	MSGS	7/	Enum:		_
	1 1 2	B DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3 2 DB0.2DB0.1	Counter/RSSI Level in dBm 8 DB1.7DB1.0 Sub-Telegram Counter/RSSI Level in dBm 4 DB0.7DB0.4 RSSI Level in dBm 1 DB0.3 LRN Bit	Counter/RSSI Level in dBm 8 DB1.7DB1.0 Sub-Telegram Counter/RSSI Level in dBm 4 DB0.7DB0.4 RSSI Level in dBm RSLV 1 DB0.3 LRN Bit LRNB 2 DB0.2DB0.1 MSG_ID MSGID	Counter/RSSI Level in dBm B DB1.7DB1.0 Sub-Telegram Counter/RSSI Level in dBm Counter/RSSI Level in dBm DB0.7DB0.4 RSSI Level in dBm RSLV Related to RLT_MasterTest_4BS message received direct link Non-EnOcean signal detection since last RLT_MasterTest message RSSI Level with 6dB quantization steps Level with 6dB quantization steps LRN Bit LRN Bit LRN Bit LRN Bit LRN Bit	Counter/RSSI Level in dBm (for details see DB3) Enum: (for details see DB3) (for d	B DB2.7DB2.0 Sub-Telegram Counter/RSSI Level in dBm Counter/RSSI Level in dBm RSLV Related to RLT_MasterTest_4BS message received Repeater level 1 : See prev

RLT_MasterTest_1BS

This is the 1BS message sent by the RLT Master during a radio link test communication.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting, AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION- 1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4		RLT MSG-Counter MSB		Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum:		
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram 1: Data telegram		
5	2	DB3.2DB3.1	RLT MSG-Counter LSB		Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum:		
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum:		
						0: RLT	Master	

EEP 2.5 Specification © EnOcean Alliance

RLT_SlaveTest_1BS

This is the 1BS message sent by the RLT Slave in reply to an RLT_MasterTest_1BS message.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION- 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4		RLT MSG-Counter MSB		Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :		
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Dat	a telegra	am
5	2	DB3.2DB3.1	RLT MSG-Counter LSB		Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :		
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum:		_
						1: RL7	-Slave	

D2-00: Room Control Panel (RCP

The Communication is based on the Smart Ack concept. Some basics related hereto are included in this document for convenience but for details please consult the Smart Ack specification.

A Room Control Panel (RCP) compliant to this EEP offers the following features:

- Multi symbol, multi segment LC display (or equivalent)
- 1 temperature measurement channel, remote configurable
 1 temperature set point control (e.g. key pad based)
- 1 fan speed control (e.g. key pad based)
- 1 presence control (e.g. key pad based)

Repeater operation shall work in compliance with the Smart Ack specification

RORG	D2	VLD Telegram
FUNC	00	Room Control Panel (RCP)
TYPE	01	RCP with Temperature Measurement and Display (BI-DIR)

Submitter: PROBARE

Message type A / ID 01 (First User Action on RCP)

Direction: Sensor -> Gateway

Transaction Response: Message Type B or Type E

Chaining: No

Timing: T1+ = 170ms

Message A / ID 01 DB_1 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 $DB_1.BIT_7 \leftarrow 0$ Bit Offset: 0 → 15

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Offset	Size	Data	ShortCut	Description		Valid Range	Scale	Unit
0	1	ConfigValid	CV		Enum			
					0:	Configuration data not valid (message of type E)	e.g. never receive	d
					1:	Configuration data valid		
1	2	Not Used (=	= 0)					
3	5	User	KP		Enum			
		Action			0:	not used		
					1:	Presence		
					2:	Temperature Set Poi	nt "down" or "—"	_
					3:	not used		
					4:	not used		_
					5:	Temperature Set Poi	nt "up" or "+"	_
					6:	Fan		_
					0x0	70x1F: Not Used		
8	5	Not Used (=	= 0)					
13	3	MsgId		Message Id;	Enum			
				0×01	1:	Message Id		

Message Type B / ID 02 (Display Content)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms

Message B / ID 02

The symbols Sa, Sb, Sc, Sd, Se are optional. One or more of those symbols are available on the display only if the manufacturer of a RCP implements them in a specific design. Thus, they are NOT mandatory for a RCP in order to comply with this EEP.

comply	WILLI	this EEP.					
Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Not Used (= 0)					
3	1	User Notification	Se	optional	Enum: 0x00: Off 0x01: On	4	>
4	1	Window	Sd	optional	Enum: 0x00: Closed 0x01: Opened		
5	1	Dew-Point	Sc	optional	Enum: 0x00: Warning 0x01: No warning		
6	1	Cooling	Sb	optional	Enum: 0x00: Off 0x01: On		
7	1	Heating	Sa	optional	Enum: 0x00: Off 0x01: On		
8	16	Figure A Value	ZA	Format according to TA:	Enum: 0x010x07: 0 4000 0x080x0A: Time 0000 . 0x0B0x0C: Date 0101 . 0x0D: 0 9999 0x0E0x10: 0 10000		

					0x0F:	0 999 ppm	
24	3	Presence	PR		Enum:		
					0x00:	Do not display	
					0x01:	Present	
					0x02:	Not present	
					0x02:	Night time reduction	
					0x040x07		
27	5	Figure A Type	TA			. Hot useu	
21	5	Figure A Type	IA		Enum:	De net dienless	
					0×00:	Do not display	0.0
					0x01:	Room Temperature	°C
					0x02:	Room Temperature	°F
					0x03:	Nominal Temperature	°C
					0x04:	Nominal Temperature	°F
					0x05:	Delta Temperature Set Point	°C
					0x06:	Delta Temperature Set Point	°F
					0x07:	Delta Temperature Set Point(graphic)	
					0x08:	Time 00:00 to 23:59 [24h]	
					0x09:	Time 00:00 to 11:59 [AM]	
					0x0A:	Time 00:00 to 11:59 [PM]	
					0x0B:	Date 01.01 to 31.12 [DD.MM]	
					0x0C:	Date 01.01 to 12.31 [MM.DD]	
					0x0D:	Illumination (linear) 0 to 9999	lx
					0x0E:	Percentage 0 to 100	
					0x0F:	Parts per Million 0 to 9999	ppm
					0x10:	Relative Humidity 0 to 100	% rH
					0x110x1F:	not used	
32	1	Fan manual	М				
32	1	i ali ilialiuai	IMI		Enum: 0: Auto	<u> </u>	
					0: Auto 1: Fan ma		
33	3	Fan	F		Enum:	ludi	
					0: Do no	t display	
						Level 0	
						Level 1	
						Level 2	
						Level 3	
					57: not us		
36	1	MoreData	MD		Enum:		
	_	. ioi cData			0: no mor	re data	
						lata will follow after T2+	
27	2	Mostd	MI	Massas Id. 0.402		ata will follow after 12+	
37	3	MsgId	IMIT	Message Id;0x02	Enum:	o Id	
					2: Messag	je Iu	

Message Type C / ID 03 (Repeated User Action on RCP)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No

Timing: may only be sent within 5s from latest receipt of a Message Type B

Message C / ID 03

				DΒ	_3							DB	_2							DΒ	_1							DΒ	_0			
DB_3.BIT_7 ← 0								0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 31									8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	15	5 Z/													- 1	. 0		PR				TΑ					F				MI	

Offset Size Data ShortCut Description Valid Range Scale	Unit
---	------

0	16	Set Point A Value	ZA	Format according to TA: 0x05 [0.01°]	-1270+1270	-12.70+12.70	0
16	3	Presence	PR		Enum:		
					0x00: n	o change	
					0x01: P	resent	_
						ot present	_
						ight time reduction	_
					0x040x07: n	ot used	
19	5	Set Point A	TA		Enum:		
		Туре			0x00: no	o change	
						ot used	
					0x010x04:		
					0x05: Te	emperature Set Poir	nt
					0x060x1F: no		
24	1	Not Used (= 0)			T OXOGITIOX 21 TIN	or abea	
25	3.	Fan	F		Enum:		
					0: no chang	<u> </u>	
					1: Speed Le		
					2: Speed Le		
					3: Speed Le	evel 2	
					4: Speed Le	evel 3	
					5: Speed Le	evel Auto	
					67: not used		
28	1	Not Used (= 0)					
29	3	MsgId	MI	Message Id; 0x03	Enum:		
					3: Message I	d	

Message Type D / ID 04 (Measurement Result)

	Me	55	ag	e [7	IC	0	4																
	DB_2																4							
	DB_3.BIT_7 + 0 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 7 6 5 4 3														3	2	1	Ō						
Bit Offset: 0 → 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
		Т	Ά		11					- 1	/A				- 0	. 0							MI	

Messa	nge T	ype D / ID 0	4 (Measu	rement Result)			
Direction Fire and Respond Chaining Timing	d Forg ise: N ig: No	one O	У				
		Messa	ge D / ID	04			
			DB_2	DB_1	DB_0		
	BitO	3.BIT_7 ← 0 7 6 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	2 3 4 5 I	VA C	7 6 5 4 3 2 1 V 5 16 17 18 19 20 21 22 23 MI	0,	
Offset			ShortCut	Description	Valid Range	Scale	Unit
0	4	Channel A Type	TA		Enum:		
					-	rature [°C]	
					0x010x0E: not use		
						rement result n	_
4		Channel A Value	VA	Format according to TA:	04000	040.00	0
16		Not Used (= 0)	l				
21	3	MsgId	MI	Message Id;0x04	Enum:		
					4: Message Id		

Message Type E / ID 05 (Sensor Configuration)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms

	Me	5 S a	ge	E/	ID	0.	5																																						
			D	B_5							B_	4						DB.	_3			Т)B_	2			П			DB	_1							DΒ	_0			1
DB_5.BIT_7 ← 0	7	6 !	5 4	3	2	1	0	7	6	5 4	4 3	3 2	1	0	7	6	5	4	3	2	1	0	7	5 5	5 4	4	3 :	2	1 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1 0	П
Bit Offset: 0 → 47	0	1 :	2 3	4	5	6	7	8	9	10 1	1 1	2 13	14	15	16	17	18	19	20 :	21 :	22 2	23 2	24 2	5 2	6 2	7 2	28 2	9 3	0 3:	1 32	2 33	34	35	36	37	38	39	40	41	42	43	44	45 4	6 47	7
	ST KA				KA			PR		F				T	Т										SI	os i							SPI	2							MD.		ΜI	1	

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Significant Temperature Difference	ST	Difference between two subsequent temperature measurements to trigger a Message Type D [0.2°]	0x00xF	0.03.0	o
4	1	Not Used (= 0)					
5	3	Keep Alive Timing	KA	Number of measurements between two subsequent "Keep Alive messages"	each Tem measure	ment result wit	:h
8	3		PR	Number of Presence Levels available to user	0: Presence 0x10x7: Presence 0x10x7	te disabled te avaibles	
11	3	Fan		Number of Fan Speed Levels available to user:	0: Fan Spe 0x10x7: Fan Spe	eed disabled eeds	
14	6	Temperature Measurement Timing	П	Time between two subsequent Temperature measurements	Enum: Tempo 0x010x3C: measo	erature urement disabl	s eds
20	5	Not Used (= 0)	_				
25	7	Set PointSteps	SPS	Number of Set Point Steps:	Enum: 0: Set P 0x010x7F: Set p	oint disabled oint	
32	1	Not Used (= 0)					
33	7	Set Point Range Limit	SPR	Limit of Set Point Range, absolute value:	0: Set P 0x010x7F: Set p	oint disabled oint	_
40	4	Not Used (= 0)					
44			MD		Enum: 0: no more data 1: more data wil	II follow after 3	00ms
45	3	MsgId	MI	Message Id; 0x05	Enum: 5: Message Id	6	

D2-01: Electronic switches and dimmers with Energy Measurement and Local Control

This EEP family shall be used for bidirectional actuators that control electric loads, e.g. for lightning purposes. Switching and dimming is controlled and high-resolution energy measurement is supported. Local Control, either thru a user interface or thru other measures shall be supported on the actuator. This may include other EnOcean enabled devices taught-in to a device belonging to the EEP family, e.g. a simple rocker switch or more sophisticated devices like occupancy sensors with timing control. The proposed EEP family serves up to 30 output channels and allows controlling them either individually or as a bulk. Extension of this EEP family is possible in different ways:

- 1. A new device with a different feature mix creates a new TYPE within this EEP family
- -> new column in following table
- $\ensuremath{\mathsf{2}}.$ An additional feature is added and a new device with a new TYPE is created
- -> new column and new line in following table
- 3. Like 2, but ${\sf EnOcean}$ communication of the ${\sf EEP}$ family needs to be extended
- -> new column and new line in following table
- -> one or more additional messages need to be defined

For teach-in and teach-out UTE (Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication) shall be used.

Supported function	Type 0x00	Type 0x01	Type 0x02	Type 0x03	Type 0x04	Type 0x05	Type 0x06	Type 0x07	Type 0x08	Type 0x09	Type 0x10	Type 0x11
No. of output channels	1	1	1	1	1	1	1	1	1	1	2	2
Switching	Χ	X	X	X	X	X	X	Χ	Χ	X	X	X
Dimming	-	-	X	X	X	Χ	-	-	-	X	-	-
Dimming configurable	-	_	-	_	X	Х	-	_	-	X	-	_
Local control	X	X	X	X	X	X	-	-	Χ	X	X	X
Local control enable/disable	-	-	-	-	X	X	-	-	Х	-	-	-
Taught-in devices enable/disable 2)	-	-	-	-	X	Х	-	-	Х	X	-	-
User interface day/night mode	-	-	-	-	-	Х	-	-	Х	-	-	-
Over current reporting	-	-	-	-	Х	Х	-	-	Х	Х	-	-
Over current configurable	-	-	-	-	Х	Х	-	-	Х	-	-	-
Energy measurement	Х	-	Х	-	Х	Х	Х	-	Х	Х	Х	-
Power measurement		F	-	-	X	Х	-	-	Х	Х	-	-
Measurement Roll Over 1)	Х	-	Х	-	-	-	Х	-	-	-	Х	-
Measurement Auto Scaling 1)	-	7)		-	Х	Х	-	-	Х	Х	-	-
Measurement configurable	-			-	-	Х	-	-	Х	Х	-	-
Measurement report on query	Х	-	X	-	Х	Х	Х	-	Х	Х	Х	-
Measurement auto reporting	-	-	-		X	Х	-	-	Х	Х	-	-
Default state configurable	-	-	-	-	7	Х	-	-	Х	Х	-	-
Error level reporting	-	-	-	-	- 0	X		-	Х	X	-	-

- 1) A device may either support Measurement Roll Over or Measurement Auto Scaling.
- 2) Enable / disable only effects devices that are taught-in to a device belonging to this EEP family; it does not effect communication between a device belonging to this EEP family and any other entity where this device has been taught-in by itself.

RORG	D2	VLD Telegram	
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Con	itrol
TYPE	00	Type 0x00	

Submitter: Team

CMD 0x1 - Actuator Set Output

This message is sent to an actuator. It controls switching / dimming of one or all channels of an actuator.

0

Command ID 01 (CMD)

				DΒ	_2							DΒ	_1							DB	_0			
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
						a,	ИD		dim) Va	ue		1/0	cha	nne				0	тфu	t Va	lue	96	

REMARK:

In case an Actuator Set Output message specifies a parameter that is not supported by the device being addresses, such device shall react as following:

- channel not supported by device -> ignore message
- dimming command to switching device -> no change of status
- dimming command with non supported speed -> dim with regular speed

RECOMMENDATION:

Dimmers should take things like phase shifting into account to provide dimming based on power consumption (results in brightness for lamps) rather than interpreting percentage values as phase angle only.

Offset	Size	Data	ShortCut	Description	Valid	d Range	Scale	Unit
0	4	Not Used (= 0	0)	•				
4	4	Command ID	CMD	command identifier	Enum:			
					0x01: ID 01	_		
8	3	Dim value	DV		Enum:			
		· ·			0x00:	Switch to new out	put value	
					0x01:	Dim to new outpu	t value – dim tim	ner 1
					0x02:	Dim to new outpu	t value – dim tim	ner 2
			Ť		0x03:	Dim to new outpu	t value – dim tim	ner 3
					0x04:	Stop dimming		
					0x050x07:	: not used		
11	5	I/O channel	I/O		Enum:			
					0x000x1D	: Output channel (t	o load)	
					0x1E:	All output channe	s supported by t	he device
					0x1F:	Input channel (fro	m mains supply)
16	1	Not Used (= 0	0)					
17	7	Output value	OV		Enum:			
					0x00:	Output value 0%	or OFF	
					0x010x64:	Output value 1%	to 100% or ON	
					0x650x7E:	: Not used		
					0x7F:	Output value not	valid / not application	able

CMD 0x2 - Actuator Set Local

This message is sent to an actuator. It configures one or all channels of an actuator.

Response Timing: None

RECOMMENDATION:

In case the device implements an internal order for dim timers, this order should be from "dim timer 1" (fast) to "dim timer 3" (slow). The configured time shall always be interpreted for a full range (0 to 100%) dimming.

Command ID 02 (CMD)



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Offset	Size	Data	ShortCut	Description	Valid I	Range	Scale	Unit
0	1	Taught-in devices	d/e		Enum:			
					0b0: Disable EEP)	taught-in dev	ices (with diff	erent
					0b1: Enable EEP)	taught-in devi	ces (with diffe	erent
1	3	Not Used (= 0)						
4	4	Command ID	CMD	Command	Enum:	_		
				identifier	0x02: ID 02			
8	1	Over current shut down	oc		Enum:			
						irrent shut dov		
					0b1: Over cu	ırrent shut dov	vn: automatic	restart
9	1	reset over current shut	RO		Enum:			
		down			0b0: Reset o	ver current sh	ut down: not	active
					0b1: Reset o signal	ver current sh	ut down: trig	ger
10	1	Local control	LC		Enum:			
					0b0: Disable	local control		
					0b1: Enable	local control		
11	5	I/O channel	I/O		Enum:			
						Output chann	el (to load)	
					0x000x1D:			
					0x1E:	All output cha	annels support	ted by
					0x1F:	Input channe	l (from mains	supply)
16	4	Dim timer 2	DT2		Enum:			
					0x00:	Not used		
					0x010x0F:	Dim timer 2 [0,5s]	[0,5 7,5s / s	steps
20	4	Dim timer 3	DT3		Enum:			
					0x00:	Not used		
						Dim timer 3 [[0,5 7,5s / s	steps
					0x010x0F:	0,5s]		
24	1	User interface indication	d/n		Enum:			
						terface indicati		
	1.				0b1: User in	terface indicati	ion: night ope	ration
25		Not Used (= 0)	D.C.	•				
26	2	Default state	DS		Enum:	h	055	
						t state: 0% or		
						t state: 100%		ctate
					0b10: Derau	t state: remer	inder previous	state
28	4	Dim timer 1	DT1		Enum:	cu		
20	T	Dill diller 1	D11		0x00:	Not used		
					0.000.	Dim timer 1	0 5 7 5c / c	stens
					0x010x0F:	0,5s]	0,0 1,33 / 5	ACP3

CMD 0x3 - Actuator Status Query

This message is sent to an actuator. It requests the status of one or all channels of an actuator.

Response Timing:

An Actuator Status Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.

Command ID 03 (CMD)

				DΒ	_1							DB	_0			
DB_1.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
						a	1D						Į/O	cha	nne	

Of	fset	Size	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0		4	Not Used (= 0))					
4		4	Command ID	CMD	Command identifier	Enum:			
						0x03: ID 03	_		
8		3	Not Used (= 0))					
11		5	I/O channel	I/O		Enum:			
Z						0x000x1D	: Output channel (t	o load)	
						0x1E:	All output channe	ls supported by t	he device
						0x1F:	Input channel (fro	m mains supply)

CMD 0x4 - Actuator Status Response

This message is sent by an actuator if one of the following events occurs:

- Status of one channel has been changed locallyMessage Actuator Status Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Status Query message.

Command ID 04 (CMD)

ge.	Co	mr	na	nd	ID	0.0	4 ((CN	чD)					?				8		>			
				DΒ	_2							DΒ	_1							DÉ	_0			
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	2 2	23
						a,	/ID		∞	E	L		(O	char	nnel		LC		O	υφι	it Va	lue	%	2

In case an Actuator Status Query message specifies a parameter that is not supported by the device being addresses, such device shall ignore the message and shall not answer using the Actuator Status Response message.

In case an Actuator Status Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04		
8		Over current switch	OC		Enum:		
		off			0b0: Over current switch of supported	f: ready / not	
					0b1: Over current switch of	f: executed	
9	2	Error level	EL		Enum:		
					0b00: Error level 0: hardwa	re OK	
					0b01: Error level 1: hardwa	re warning	
					0b10: Error level 2: hardwa	re failure	
					0b11: Error level not suppo	rted	

11	5	I/O channel	I/O	Enum:	
				0x000x1	D: Output channel (to load)
				0x1E:	Not applicable, do not use
				0x1F:	Input channel (from mains supply)
16	1	Local control	LC	Enum:	
				0b0: Local	control disabled / not supported
				0b1: Local	control enabled
17	7	Output value	OV	Enum:	
				0x00:	Output value 0% or OFF
				0x010x6	64: Output value 1% to 100% or ON
				0x650x7	'E: Not used
				0x7F:	output value not valid / not set

CMD 0x5 - Actuator Set Measurement

This message is sent to an actuator. It configures the energy and power measurement of one or all channels of an actuator.

Response Timing: None



Offse	t Size	Data	ShortCut	Description	Valid Rang	e Scale	Unit
0	4	Not Used (= 0)			•		
4	4	Command ID	CMD	Command identifier	Enum:	_	
					0x05: ID 05		
8	1	Report measurement	RM		Enum:		
					only	measurement: q	
					0b1: Report auto re	measurement: q porting	luery /
9	1	Reset measurement	RE		Enum:		
					active	neasurement: no	
					0b1: Reset r signal	neasurement: tri	gger
10	1	Measurement mode	e/p		Enum:		
						measurement	
					0b1: Power	measurement	
11	5	I/O channel	I/O		Enum:		
					0x000x1D:		
					0x1E:	All output chann supported by the device	
					0x1F:	Input channel (fi mains supply)	rom
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN		Enum:		=
					0x00:	Energy [Ws]	_
					0x01:	Energy [Wh]	-
					0x02:	Energy [KWh]	-
					0x03:	Power [W]	-
					0x04:	Power [KW]	

					0x050x07: No	t used	
24	_	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32	_	Maximum time between two subsequent Actuator		Measurement Response messages [10s]	0255	102550	S
40		Minimum time between two subsequent Actuator		Measurement Response messages [s]	0255	0255	S

CMD 0x6 - Actuator Measurement Query

This message is sent to an actuator. The actuator replies with an Actuator Measurement Response message.

Response Timing:

An Actuator Message Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0	0)				
4	4	Command ID	CMD	Command identifier	Enum:		
					0x06: ID 06		
8	2	Not Used (= 0	0)				
10	1	Query	qu		Enum:		
					0b0: Query energy		
					0b1: Query power		
11	5	I/O channel	I/O		Enum:		
					0x000x1D: Output channel (to load)	
					0x1E: All output channe	ls supported by t	he device
					0x1F: Input channel (fr	om mains supply)

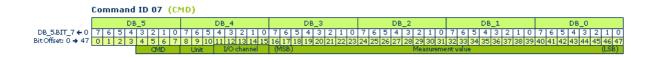
CMD 0x7 - Actuator Measurement Response

This message is sent by an actuator if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Measurement Query message.



REMARK 1:

In case an Actuator Measurement Query message specifies a parameter that is not supported by the device addressed, such device shall ignore the message and shall not answer using the Actuator Measurement Response message. REMARK 2:

In case an Actuator Measurement Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid R	ange	Scale	Unit
0	4	Not Used (= 0)	_					
4	4	Command ID	CMD	Command identifier	Enum:			
					0x07: ID 07			
8	3	Unit	UN		Enum:			
					0x00:	Energy [Ws]		
					0x01:	Energy [Wh]	<u> </u>	
					0x02:	Energy [KW	h]	
					0x03:	Power [W]		
					0x04:	Power [KW]		
					0x050x07	: Not used		
11	5	I/O channel	I/O		Enum:			
					0x000x1D:	Output chan	nel (to loa	d)
					0x1E:	Not applicab	le, do not	use
					0x1F:	Input channe supply)	el (from m	ains
16	32	Measurement value (4 bytes)	MV	DB3 = MSB / DB0 = LSB	0429496729	5		N/A

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	01	Type 0x01 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	02	Type 0x02 (description; see table)

See profile: D2-01-00

RORG	D2	VLD Telegram	
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local (Control
TYPE	03	Type 0x03 (description: see table)	

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	04	Type 0x04 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	05	Type 0x05 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	06	Type 0x06 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	07	Type 0x07 (description: see table)

See profile: D2-01-00

RORG	D2 VLD Telegram
FUNC	01 Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	08 Type 0x08 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	09	Type 0x09 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	10	Type 0x10 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	11	Type 0x11 (description: see table)

See profile: D2-01-00

D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke

This EEP family shall be used for bidirectional sensors that measure temperature, illumination, and detect room occupancy and smoke presence.

The EEP may be used in conjunction with the Smart Acknowledge protocol.

For teach-in and teach-out the "Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication"

EEP 2.5 Specification © EnOcean Alliance

shall be used. Alternatively the Smart Acknowledge Teach-In Procedure is used for those sensors supporting Smart $\ \ \, Acknowledge.$

Supported function	Type 0x00	Type 0x01	Type 0x02
Temperature Sensor	X	X	X
Illumination Sensor	X	X	-
Occupancy Detector	X	-	-
Smoke Detector	X	X	X

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	00	Type 0x00

Submitter: MSR-Office

CMD 0x1 - Sensor Measurement

This message is sent by a sensor if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing: None

		Cor	mm	and	ID	0:	1 (CN	10)																						
				DB	_3							DB,	_2							DВ	_1						DB.	0			ı
	BIT_7 ← 0		6 5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2 1	0	7	6	5	4		2 1	0]
BitOffs	et: 0 → 31	0	1 2	3	4	5	6	7	8	9 :	10	11	12	18	14	15	16	17	18	19	20	21 2	2 23	3 24	25	26	27	28 2	_	0 31	_
						_ a₁	/ID		- ty	/pe							MB	В				me as	sure	men	tva	lue				LSB	
																							<u></u>								
Size		Dat	ta			Sł	or	tCı	ut		D	es	cri	pt	ioi	1				٧	ali	d Ra	ang	je				Sc	ale		l

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	command identifier	Enum: 0x01: ID 01		
8	3	Measurement type	type		Enum: Temperature (065 0x00: Illumination (065 0x01: Occupancy (0: not of otel of otel otel otel otel otel otel otel otel	detected; 1: nt applies for DB_1: etected cted via ionizated	the ation
11	5	Not Used (= 0)					
16	16	Measurement value (2 bytes)	MV	DB_0 = LSB / DB_1 = MSB	065.535		N/A

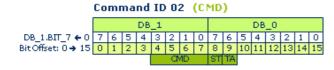
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EEP 2.5 Specification © EnOcean Alliance

CMD 0x2 - Sensor Test/Trigger

This message is sent to a sensor. It causes the sensor to enter self-test mode or trigger an alarm (if supported).

Response Timing: None



Offset	Size		Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not	Used (= 0)				
4	4	Con	nmand ID	CMD	Command identifier	Enum:		
						0x02: ID 02	_	
8	1	Self	-test	ST		Enum:		
						0b0: Self-tes	st mode)
						0b1: Normal	operat	ion
9	1	Trig	ger alarm	TA		Enum:		
						0b0: Trigger	alarm	
						0b1: Normal	operat	ion
10	6	Not	Used (= 0)				

CMD 0x3 - Actuator Set Measurement

This message is sent to a sensor. It configures the measurement behaviour of the sensor.

Response Timing: None



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x03: ID 03		
8	1	Report measurement	RM		Enum:		
					0b0: Report mea	surement: qu	iery
					0b1: Report mea auto report		iery /
9	7	Not Used (= 0)					
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN		Enum:		
					0x00: Ter	nperature (°C	<u> </u>
					0x01: Illu	mination (lx)	

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					0x020x07: No	t used	
24	8	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32	8	Maximum time between two subsequent Actuator		Measurement Response messages [10s]	0255	102550	S
40	8	Minimum time between two subsequent Actuator	MIT	Measurement Response messages [s]	0255	0255	S

CMD 0x4 - Sensor Measurement Query

This message is sent to a sensor. The sensor replies with an Sensor Measurement message.

Response Timing:

A Sensor Measurement message shall be received within a maximum of 300ms from the time of transmission of this message.

In case no such response is received within this time frame the action shall be treated as completed without result.

Q _A	Co	mr	na	nd	ID	0	4	(CI	MD)						
				DB	_1							DΒ	_0			
$DB_1.B\Pi_7 \leftarrow 0$	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	7	7	\overline{Z}			a	ИD			qu						
			9	9		_										

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	4	Not Used (= 0))			
4	4	Command ID	CMD	Command identifier	Enum: 0x04: ID 04	
8	3	Query	qu		0x1: Quer 0x2: Quer	y temperature y illumination y occupancy y smoke used
11	5	Not Used (= 0))			

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	01	Type 0x01 (description: see table)

See profile: D2-02-00

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	02	Type 0x02 (description: see table)

See profile: D2-02-00

D2-03: Light, Switching + Blind Control

The EEP family D2-03-xx provides different telegram types for switches, light and blind control. The purpose is to support secure communication and other functional aspects of applications extending the possibilities given by existing profiles (1BS, RPS, 4BS). Transmitting information in the status field of a telegram is not necessary with this EEP family.

EEP Properties:

DATA EXCHANGE
Direction: unidirectional
Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: N/A Tx delay: N/A Rx timeout : N/A

TEACH-IN

Teach-in method: Universal teach-in (UTE) + Secure Teach-in (for secure communication)

SECURITY

Encryption supported: yes

EEP Family Table:

(Only for VLD EEP families)

Supported function	Type 00
2 Rocker Switch	X

Each TYPE has to support every parameter that is marked in its column!

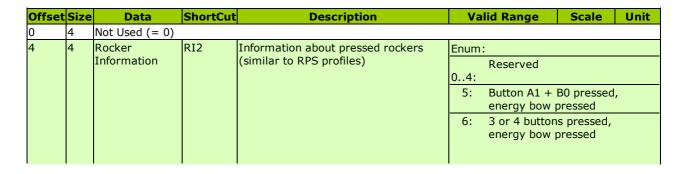
RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

The encrypted telegram has the R-ORG 0x30. The payload (4 bits) is encrypted. That telegram can be repeated. After decryption and the authentication of the CMAC, the telegram turns into a non-encrypted EnOcean telegram with the R-ORG 0x32. The payload will be expanded to 8 bits (4 MSB set to zero) and can then be interpreted as described in the telegram definition table.

The decrypted telegram may not be repeated as the information is not secure anymore. The following table provides information about the conversion between the profiles D2-03-00 and F6-02-01:

D2-03-00 DATA	F6-02-01 DATA	F6-02-01 STATUS
04	-	-
5	0x17	0x30
6	0x70	0x20
7	0x37	0x30
8	0x10	0x20
9	0x15	0x30
10	0x35	0x30
11	0x50	0x30
12	0x70	0x30
13	0x10	0x30
14	0x30	0x30
15	bxxx0xxxx	0x20



		7:	Button A0 + B0 pressed, energy bow pressed
		8:	No buttons pressed, energy bow pressed
		9:	Button A1 + B1 pressed, energy bow pressed
		10:	Button A0 + B1 pressed, energy bow pressed
		11:	Button B1 pressed, energy bow pressed
		12:	Button B0 pressed, energy bow pressed
		13:	Button A1 pressed, energy bow pressed
		14:	Button A0 pressed, energy bow pressed
		15:	Energy bow released

D2-20: Fan Control

The EEP family D2-20-xx provides different telegram types for fan control and fan supervision messages using various parameters and variables.

Devices using this EEP family may include a master-slave function (for further description see subheading 'Master-slave function')

EEP Properties:

DATA EXCHANGE Direction: bidirectional

EEP Family Table:

Addressing: unicast (ADT) + Communication trigger: ever Communication interval: N/A Trigger event: query / polling Tx delay: N/A Rx timeout: N/A TEACH-IN Teach-in method: Universal to SECURITY Encryption supported: no Security level: none EEP Family Table: (Only for VLD EEP families)	nt-triggere N	ed UTE)		
Supported function	Type 00	Type 01	Type 02	
Fan Speed	X	X	X	
Fan Speed Status	Х	X	Х	
Humidity	Х	-	-	
Humidity Control	Х	_	-	
	\/			
Humidity Control Status	X	-	X	
Humidity Control Status Humidity Threshold	X		X -	
•		- - X	X - X	
Humidity Threshold	Х	- - X -	-	
Humidity Threshold Message Type	X X	- X - X	-	
Humidity Threshold Message Type Operating Mode	X X X	-	-	
Humidity Threshold Message Type Operating Mode Operating Mode Status	X X X	- X	- X -	
Humidity Threshold Message Type Operating Mode Operating Mode Status Room Size	X X X X X	- X X	- X - - X	
Humidity Threshold Message Type Operating Mode Operating Mode Status Room Size Room Size Reference	X X X X X	- X X X	- X - - X X	
Humidity Threshold Message Type Operating Mode Operating Mode Status Room Size Room Size Reference Room Size Reference Status	X X X X X X	- X X X X	- X - - X X	

Each TYPE has to support every parameter that is marked in its column!

Master-slave function:

A device using this EEP may be able to work as a master or a slave fan. Master fans control slave fans. Slave fans are controlled by master fans. These roles are defined during the teach-in process. A slave fan will always be taught-in to a master. A master fan will accept teach-in requests from slave fans. A fan that is taught-in to another device will from now on work as a slave. A fan that accepted the teach-in of another device will go on working as a master. Combining master fans is not possible. Not every device is able to work as a master and a slave. Certain fans might only be able to be used as slaves.

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	00	Type 0x00

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Ui	nit
0	4	Operating Mode	ОМ	Sets the operating mode	Enum:	
					0: Disabled	
					1: Standard	
					compliant	
					Reserved	
					214:	
4	-	Net Lleed (C)			15: No change	
4 5	2	Not Used (= 0) Temperature Level	τı	Status of the temperature supervision	F	
3	2	l'emperature Level		Status of the temperature supervision	Enum: 0: Too low	
					1: Normal	
					2: Too high	
					3: No change	
7	1	Message Type	MT	Defines the message type	Enum:	
,	-	ressage Type		beinies the message type	0: Fan control	
8	2	Humidity Control	HC	Activates the humidity control	Enum:	
3	_	Trainialty Control		Acceptates the humbley control	0: Disabled	
					1: Enabled	
					2: Default	
					3: No change	
10	2	Room Size	RSR	Defines if the provided room size has to be	Enum:	
		Reference		considered	0: Used	
					1: Not used	
					2: Default	
				*	3: No change	
12	4	Room Size	RS	Defines the room size	Enum:	
					0: < 25 m ²	
					1: 2550 m ²	
					2: 5075 m ²	
					3: 75100 m ²	
					4: 100125 m ²	
					5: 125150 m ²	
					6: 150175 m ²	
					7: 175200 m ²	
					8: 200225 m ²	
					9: 225250 m ²	
					10: 250275 m ²	
					11: 275300 m ²	
					12: 300325 m ²	
					13: 325350 m ²	
					14: > 350 m ² 15: No change	
16	8	Humidity Threshold	μт	Sets the humidity threshold	_	
10	0	Turniuity Threshold	111	Sets the number threshold	Enum: 0100%	
					101252: Reserved	
					253: Auto	
					254: Default	

					255:	No change
24	8	Fan Speed *	FS	Sets the fan speed	Enum:	
					0100:	0100%
					101252	: Reserved
					253:	Auto
					254:	Default
					255:	No change

Telegram Definition: 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Operating Mode	OMS	Provides the recent operating mode	Enum:
		Status			0: Disabled
					1: Standard
					compliant
					Reserved
					214:
4	2	Cardina Tafanna atian	CI	Complete information	15: Not supported
4	3	Service Information	SI	Service information	Enum:
					0: Nothing to report 1: Air filter error
					1: Air filter error 2: Hardware error
					36: Reserved
		Y			7: Not supported
7	1	Message Type	MT	Defines the message type	
,	-	riessage Type		Defines the message type	Enum: 1: Fan status
0	2	Humaiditus Cambual	HCS	Chabasif the houseidity control is a stive	
8	2	Humidity Control Status	пс	States if the humidity control is active	Enum:
		Status			0: Disabled
					1: Enabled 2: Reserved
10	2	Room Size	RSR	States if the provided room size has to be	• • • • • • • • • • • • • • • • • • • •
10	2	Reference	KSK	considered	Enum:
		reference		considered	0: Used
					1: Not used 2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Doom size status	' '
12	4	Room Size Status	K55	Room size status	Enum: 0: < 25 m ²
					1: 2550 m ²
				•	2: 5075 m ²
					3: 75100 m ²
					4: 100,125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
					15: Not supported
16	8	Humidity	HUM	Humidity measurement	Enum:
					0100: 0100%
					Reserved
					101254:
					255: Not
2.4		- 0 / C: :	500		supported
24	8	Fan Speed Status	FSS	Fan speed	Enum:
					0100: 0100%
•					

		101254:	Reserved
		255:	Not supported

RORG	D2	VLD Telegram	
FUNC	20	Fan Control	
TYPE	01	Type 0x01	

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

and ma	itch v	alues beside those d	iscrete lev	els to the next lower fan speed level.		
Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	7	Not Used (= 0)	ı			
7	1	Message Type	MT	Defines the message type	Enum: 0: Fan	control
8	2	Not Used (= 0)				
10	2	Room Size Reference	RSR	Defines if the provided room size has to be considered	Enum: 0: Used 1: Not u 2: Defa 3: No c	used
12	4	Room Size	RS	Defines the room size	10: 250.	50 m ² 75 m ² 100 m ² 125 m ² 150 m ² 200 m ² 225 m ² 250 m ² 275 m ² 300 m ² 350 m ² 350 m ²
16	8	Not Used (= 0)			•	
24	8	Fan Speed *	FS	Sets the fan speed	Enum: 0100: 101252: 253: 254: 255:	0100% Reserved Auto Default No change

 $\label{temperature} \textbf{Telegram Definition: `Fan Status Message'}$

	Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit
--	-------------	------	----------	-------------	-------------	-------	------

0

0	4	Operating Mode Status	OMS	Provides the recent operating mode	Enum: 0: Disabled 1: Standard compliant Reserved 214: 15: Not supported
4	3	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum: 1: Fan status
8	2	Not Used (= 0)			
10	2	Room Size Reference	RSR	States if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Reserved 3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum: 0: < 25 m² 1: 2550 m² 2: 5075 m² 3: 75100 m² 4: 100125 m² 5: 125150 m² 6: 150175 m² 7: 175200 m² 8: 200225 m² 9: 225250 m² 10: 250275 m² 11: 275300 m² 12: 300325 m² 13: 325350 m² 14: > 350 m² 15: Not supported
16	8	Not Used (= 0)			
24	8	Fan Speed Status	FSS	Fan speed	Enum: 0100: 0100% 101254: Reserved 255: Not supported

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	02	Type 0x02

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	Not Used (= 0)					
7	1	Message Type	MT	Defines the message type	Enum: 0: Fan co	ontrol	
8	2	Not Used (= 0)					
10		Room Size Reference		Defines if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Defau 3: No cha	lt	

12	4	Room Size	RS	Defines the room size	2: 50 3: 75 4: 100. 5: 125. 6: 150. 7: 175. 8: 200. 9: 225. 10: 250. 11: 275. 12: 300. 13: 325. 14: > 35	50 m ² 75 m ² 100 m ² 125 m ² 150 m ² 200 m ² 225 m ² 250 m ² 275 m ² 300 m ² 350 m ² 350 m ²
					15: No c	hange
16		Not Used (= 0)		T		
24	8	Fan Speed *	FS	Sets the fan speed	Enum:	
					0100:	0100%
	-				101252:	Reserved
					253:	Auto
					254:	Default
					255:	No change

Telegram Definition : `Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range Scale Uni
0	7	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum:
					1: Fan status
3	2	Humidity Control	HCS	States if the humidity control is active	Enum:
		Status			0: Disabled
					1: Enabled
					2: Reserved
					3: Not supported
10		Room Size Reference	RSR	States if the provided room size has to be considered	Enum:
		Reference		Considered	0: Used
					1: Not used 2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum:
12	_	Room Size Status	IX33	Noon size status	0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ² 13: 325350 m ²
					14: > 350 m ²
					15: Not supported
16	8	Not Used (= 0)			13. Not supported
.0	<u> </u>	1401 0360 (- 0)			

EEP 2.5 Specification © EnOcean Alliance

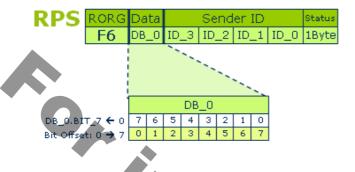
24	8	Fan Speed Status	FSS	Fan speed	Enum:	
					0100:	0100%
						Reserved
					101254:	
					255:	Not
						supported



EEP 2.5 Specification © EnOcean Alliance

3) Appendix

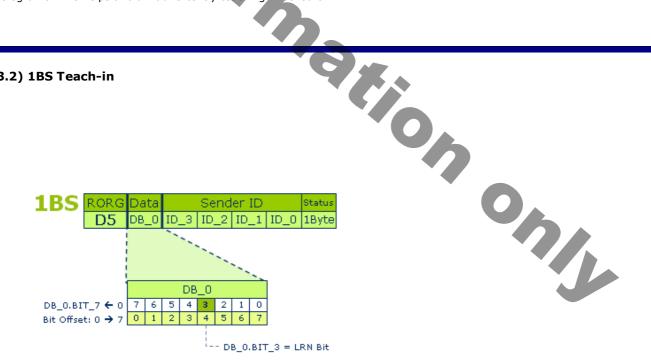
3.1) RPS Teach-in



The RPS telegram can only send data and has no special telegram modification to teach-in the device. Therefore, the teach-in procedure takes place manually on the actuator/controller through a normal data telegram. The EEP profile must be manually supplied to the controller per sender ID.

In learn mode, the receiving actuator reduces the input sensitivity in order to fade out weakly received data telegrams. This helps avoid inadvertently teaching-in sensors.

3.2) 1BS Teach-in



The 1BS telegram has its own teach-in telegram, which can signal the teach-in command through the DB_0.BIT_3 data hit.

	Offset	Size	Bitrange	Data	Valid	Range	Scale	Unit
	4	1	DB0.3	LRN Bit	Enum:			
ı					0:	Teach-ir	n telegr	am
					1:	Data tel	egram	

Here, an EEP profile must also be manually allocated per sender ID.

3.3) 4BS Teach-in



The 4BS telegram also has its own teach-in telegram, however with more teach-in variations:

Variation 1

The profile-less unidirectional teach-in procedure functions according to the same principle as the 1BS telegram: if the data bit is $DB_0.BIT_3 = 0$, then a teach-in telegram is sent. This includes the 'LRN TYPE' $DB_0.BIT_7 = 0$ data bit. Then no EEP profile identifier and no manufacturer ID are transferred.

Offset	Size	Bitrange	Data		Valid Range	Scale Unit
24	1	DB0.7	LRN Type	Enum:		
				0:	telegram without EEF	P and Manufacturer ID
28	1	DB0.3	LRN Bit	Enum:		
				0:	Teach-in telegram	
				1:	Data telegram	

Variation 2

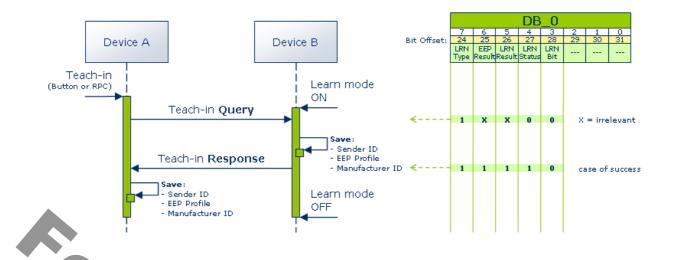
For the unidirectional profile teach-in procedure, it is preferred in opposite to variation 1), as the teach-in telegram contains both the complete EEP number and the manufacturer ID. The device is therefore clearly identifiable as ready-to-use and can be securely executed in a complex system environment or by foreign systems. In this case, the 'LRN TYPE' data bit is $DB_0.BIT_7 = 1$.

Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum	:		
				1:	telegram with EEP nur	mber and Manufa	cturer ID
28	1	DB0.3	LRN Bit	Enum	:		
				0:	Teach-in telegram		
				1:	Data telegram		

Variation 3

During the bidirectional teach-in procedure, further bits are required from the DB_0, in order to develop the mutual teach-in between two communication partners. For this, the procedure is made up of 2 teach-in telegrams, which are exchanged on both sides. The following UML diagram is used to illustrate this:

EEP 2.5 Specification © EnOcean Alliance



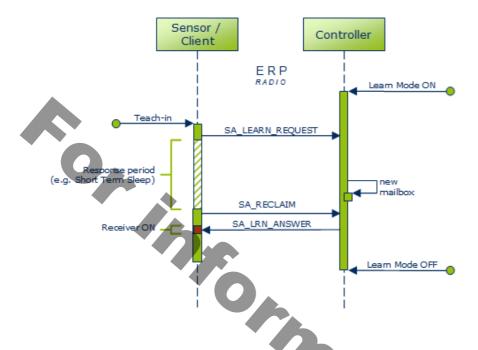
Offset	Size	Bitrange	Data	Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum:		
				0: telegram without EEP a	nd Manufacture	r ID
				1: telegram with EEP num		
25	1	DB0.6	EEP Result	Enum:		
			Y	0: EEP not supported		
				1: EEP supported		
26	1	DB0.5	LRN Result	Enum:		
				0: Sender ID deleted/not s	stored	
				1: Sender ID stored		
27	1	DB0.4	LRN Status	Enum:		
				0: Query		
				1: Response		
28	1	DB0.3	LRN Bit	Enum:		
				0: Teach-in telegram	5/	
				1: Data telegram		
						4

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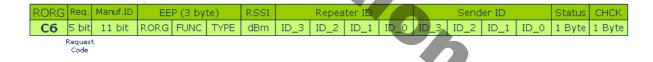
EEP 2.5 Specification © EnOcean Alliance

3.4) Smart Ack Teach-in (without repeater)

Under Smart Ack (SA), the teach-in procedure is more complex as, alongside the SA client and SA controller, a Postmaster must also be established to prepare a mailbox for each taught-in SA client. The Postmaster is normally found in the controller. If a repeater is installed, then a postmaster is set up there.



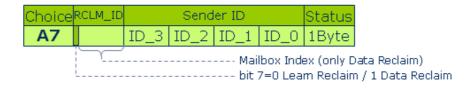
After the learn mode is activated on the controller, the teach-in procedure can be started on the client. The client sends an SA_LEARN_REQUEST telegram:



0

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0x00	0 = Without repeater
Repeater ID	0x00000000	0 = Without repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

During the 'response period' in the SA client, which is always 550 ms during the teach-in, the controller creates a new mailbox in its postmaster and leaves its first message there with an OK receipt. This entry is requested from the postmaster by the SA client with an SA_RECLAIM 'Learn' telegram:



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Data	Value	Description
Message Index	0b0	Bit 7: 0 = Learn Reclaim
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-ir
Status	0x0F	0F = no repeating desired
CHCK	0xnn	Checksum

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

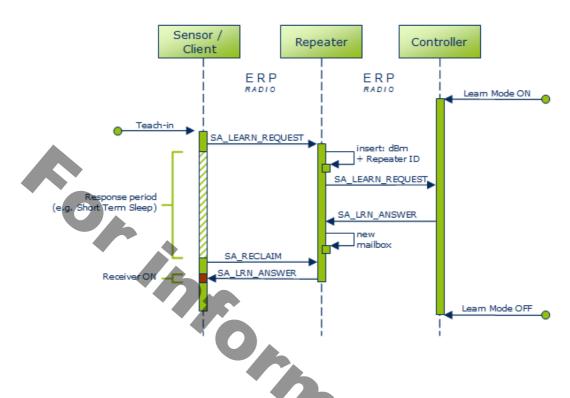
Smart Ack Learn Answer (Learn Acknowledge)

RORG	RORG-EN	Index	Respor	se time	Ack C.	Mailbox		not used	i		Postma	ster ID			Contro	ller ID		Status	CHCK
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
A6	C7	02					-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data		
	Value	Description
RORG 0)xA6	A6 = ADR Telegram
RORG-EN 0	xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
ndex 0	x02	Message Index; 02 = Learn Acknowledge
Response time 0		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)
ode 0	0x00	First Learn In successful
Mailbox index 0	xnn 🔍	Index no. of the assigned mailbox
ostmaster ID 0)xnnnnnnn	Device ID of the Post master candidate
Controller ID 0)xnnnnnnnn	Device ID of the assigned controller
Status 0	x0F	0F = no repeating permitted
CHCK 0)xnn	Checksum
		Device ID of the assigned controller OF = no repeating permitted Checksum

EEP 2.5 Specification © EnOcean Alliance

3.5) Smart Ack Teach-in (with repeater)



If a repeater comes into operation, the SA_LEARN_REQUEST telegram sent by the SA client (with an EEP No., Manufacturer ID, Sender ID) is completed on the repeater with the RSSI value (in dBm) and the Repeater ID, and sent to the controller.

	RORG F	Req.	Manuf.ID	EE	EP (3 byte)		RSSI	I Repeater ID						Send	Sender ID		Status	CHCK
	C6 5	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_	3 / J	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
		eques Code	t															
Data Value				Description														
uest Code 0b11111				Default value – send by sensor														
ufacturer ID Obnnnnnnnnnn				Corresponding to the teach-in sensor										4				
No. 0xnnnnn			RORG, FUNC, TYPE											` 🐬				
0xnn			Value added from repeater											~ ~	7/	7		
eater ID 0xnnnnnnn				Device ID repeater														
ler ID 0xnnnnnnn 0				Chip ID of sensor for teach-in														
0x0F $0F = no r$					o rene	ating r	ermitt	ed										

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0xnn	Value added from repeater
Repeater ID	0xnnnnnnn	Device ID repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

From the reception strength of the RSSI, the controller can recognise which repeater is best for the task of postmaster. In the meantime, the SA client will be in its 'response period'.

The sent addressed telegram SA_LRN_ANSWER with the message 'Learn Reply' by the controller to the repeater ensures that the postmaster is activated and a mailbox is created.

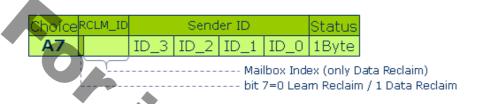
RORG	Req.	Manuf.ID	EEP (3 byte)			RSSI	Repeater ID				Sender ID				Status	CHCK
C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
	Request Code	t														

Data	Value	Description
		-

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RORG	0xA6	A6 = ADR Telegram			
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER			
Index	0x01	Message Index; 01 = Learn Reply			
Response time	0xnnnn	Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value $550 \text{ ms} = 0x0226$)			
Acknowledge code	0x00	First Learn In successful			
Sender ID	0xnnnnnnn	Chip ID of sensor to be teach-in			
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate			
Controller ID	0xnnnnnnnn	Device ID of the assigned controller			
Status	0x0F	0F = no repeating permitted			
CHCK	0xnn	Checksum			

Also, a mailbox is created for the SA client, where an initial entry with an OK message is left. This information is requested by the SA client from the repeater's postmaster with the SA_RECLAIM 'Learn' telegram.



Data	Value	Description
Message Index	0b0	Bit 7: 0 = Learn Reclaim
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating desired
CHCK	0xnn	Checksum

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

	RORG	RORG-EN	Index	Respor	nse time	Ack C.	Mailbox		not usec			Postma	ster ID			Contro	ller ID		Status	CHCK
П	0	1	2	3	4	5	6	7	8	9	10	41	12	13	14	15	16	17	18	19
	A6	C7	02					-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value 550 ms = 0x0226)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

3.6) UTE - Universal Uni- and Bidirectional Teach-in

General

Up to now there are teach-in procedures available for:

- RPS communication (EnOcean ID + rocker/channel information, unidirectional)
- 1BS communication (LRN telegram, w/o EEP and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, bidirectional)
- SmartACK communication (self powered devices, bidirectional)

For uni- and bidirectional EEP communication that does not fit into SmartACK communication principles but is based on e.g. MSC and VLD messages no teach-in procedure is defined so far.

Therefore, this document proposes a universal teach-in procedure that allows handling of teach-in and teach-out requirements for EEP based communication of all different RORG. This proposal shall be understood as an alternative to SmartACK teach-in for devices where SmartACK is not applicable.

RORG to be used: 0xD4 Universal Teach-in, EEP based (UTE)

FUNC and TYPE shall be represented as 8bit parameters, both with a value range from 0x00 ... 0xFF. This aligns UTE with the EEP representation defined for SmartACK teach-in.

REMARK 1

Even though the proposed Universal Tech-In Procedure is able to cover EEPs based on RPS, 1BS and 4BS messages as well, it is not intended to replace the existing RPS, 1BS and 4BS teach-in / teach-out procedures for unidirectional and the existing 4BS teach-in / teach-out procedures for bidirectional communication.

However, it is recommended that with the acceptance of the proposed Universal Tech-In Procedure all new bidirectional 4BS applications shall use it for teach-in and teach-out as well.

RFMARK 2:

The proposed Universal Tech-In Procedure is dedicated to EEP based EnOcean communication. It does neither compete with nor shall it interfere with the tech-in process of the Generic EnOcean Communication.

Communication - Principles and Definitions

BIDIRECTIONAL EEP-BASED COMMUNICATION

Bidirectional EnOcean communication means a point-to-point communication relationship between two enabled EnOcean devices. It requires all parties involved to know the unique EnOcean ID of their partners. Such point-to-point communication relationship is established with the completion of a successful teach-in process and it is deleted with the completion of a successful teach-out process.

To get a maximum reliable teach-in process with a minimum consumption of energy and resources, a simple query - response mechanism is used: the device that is intended to be taught-in broadcasts a query message and gets back an addresses response message, containing its own EnOcean ID as the transmission target address.

In case there is more than one device ready to accept teach-in query messages at the same time and within the same radio range, the device with the quickest response time will be accepted by the device to be taught-in. Second and further devices will respond as well but they will not be accepted by the device to be taught-in. This will result in a configuration situation that is common to today's EEP based unidirectional teach-in processes.

UNIDIRECTIONAL EEP-BASED COMMUNICATION

Unidirectional EnOcean communication means a point-to-multipoint communication relationship between enabled EnOcean devices. In this case of broadcasting the device to be taught-in to other devices does not know the unique EnOcean ID of those communication partners.

The proposed Universal Teach-In Procedure supports unidirectional EnOcean communication thru related configuration bits in the query message.

However, for specific applications – e.g. configuration feedback – it is also possible to combine a bidirectional teach-in process with a unidirectional EEP based communication during the regular operation of a device.

EEP Teach-In Query - UTE Message (Broadcast / CMD: 0x0)

This message is sent by the EEP based EnOcean device that is intended to be taught-in to another device (which has been set into LRN-mode before either manually or thru a ReMan command).

Response Timing

If a response is expected it shall be received within a maximum of 700ms from the time of transmission of this message. In case no such response is received within this time frame the query action shall be treated as completed with negative result. If no response is expected, each query action has to be treated as completed with positive result.

TABLE OF 7 BYTE PAYLOAD:

Data	Value	Description
DB_0	RORG	RORG of EEP [0x00 0xFF]
DB_1	FUNC	FUNC of EEP [0x00 0xFF]
DB_2	TYPE	TYPE of EEP [0x00 0xFF]
DB_3.BIT_73	-	Do not use
DB_3.BIT_20	MID (3MSB)	Manufacturer-ID (3MSB)
DB_4	MID (8LSB)	Manufacturer-ID (8LSB)
DB_5	0x00 0xFE	Number of individual channel to be taught in
"	0xFF	Teach-in of all channels supported by the device
DB_6.BIT_7	0b0	Unidirectional communication (EEP operation)
"	0b1	Bidirectional communication (EEP operation)
DB_6.BIT_6	0b0	EEP Teach-In-Response message expected
"	0b1	No EEP Teach-In-Response message expected
DB_6.BIT_54	0b00	Teach-in request
"	0b01	Teach-in deletion request
"	0b10	Teach-in or deletion of teach-in, not specified
"	0b11	Not used
DB_6.BIT_30	0x0	Command identifier (CMD): EEP Teach-In Query

EEP Teach-In Response - UTE Message (Addressed / CMD: 0x1)

This message is the reply to an EEP Teach-In Query message. It is sent by the EEP based EnOcean device that has been set into LRN-mode before (either manually by HMI or thru a ReMan command).

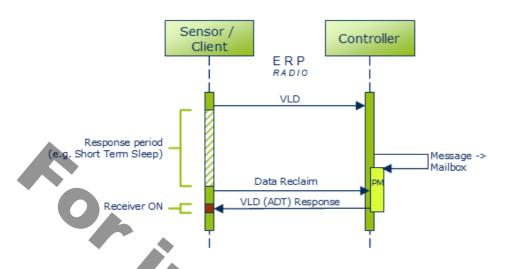
Response Timing:

If a response is requested this message shall be sent within a maximum of 500ms from the time of reception of the EEP Teach-In Query message. This limit shall give sufficient time to decide on the teach-in request and answer accordingly (e.g. when requests need to be processes by data base systems connected asynchronously).

TABLE OF 7 BYTE PAYLOAD:

Data	Value	Description
DB_0DB_5		Same structure as Teach-In Query message (EEP, MID and channel of requesting device is echoed back)
DB_6.BIT_7	0b0	Unidirectional communication (EEP operation)
"	0b1	Bidirectional communication (EEP operation)
DB_6.BIT_6	-	Not used
DB_6.BIT_54	0b00	Request not accepted, general reason
II .	0b01	Request accepted, teach-in successful
"	0b10	Request accepted, deletion of teach-in successful
"	0b11	Request not accepted, EEP not supported
DB_6.BIT_30	0x1	Command identifier (CMD): EEP Teach-In Response

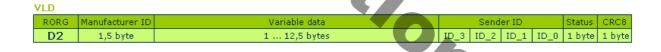
3.7) Smart Ack: functional principle (without repeater)



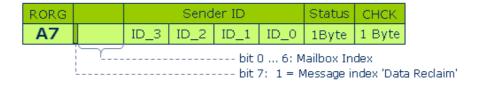
Smart Ack is a bidirectional communication protocol between a self-powered device and a line-powered controller. Data transmission in both directions is controlled by the sensor/client, as the limited energy budget requires an exact synchronization of the sent and the received messages. This pre-defined time interval allows a very short activation of the energy-intensive receiver electronics on the client.

If the teach-in procedure has already taken place as in Chapter 'Smart Ack Teach-in procedure' and the two devices already 'know each other', communication always takes place as following under Smart Ack:

The client sends its message over a VLD telegram to the controller (Manufacturer ID = optional).



Finally, the message is processed in the controller, or forwarded to an external micro-controller over the serial interface for each use case. During the intervening period, the client is in the 'response period', which is frequently connected to an energy saving measure (like 'Short Term Sleep'). The length of this time period is agreed during the teach-in procedure between the devices as 'response time'. The feedback defined for the client is deposited in the mailbox of the postmaster (PM). When the client is active again, it requests this message containing the Smart Ack telegram DATA_RECLAIM from the responsible postmaster.



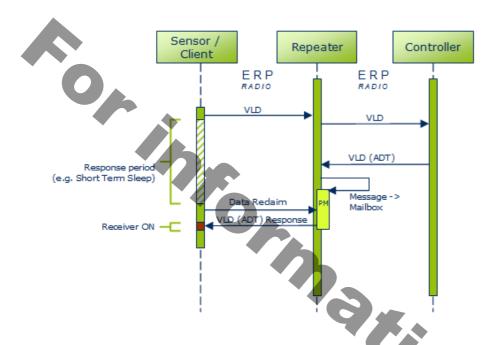
Finally, the receiver part of the client is activated and the message sent by the postmaster is accepted. In this case the VLD telegram is sent encapsulated as ADT telegram (= addressed).

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ADT / VLD

RORG	RORG-EN	Manufacturer ID	Variable data		Destina	tion ID			Send	er ID		Status	CRC8
A6	D2	1,5 byte	1 7,5 bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

3.8) Smart Ack: functional principle (with repeater)



If a repeater is used, it takes over the task of the postmaster after the teach-in procedure. Hence, the client cannot view under operating conditions whether it is communicating directly with a controller or with a repeater.

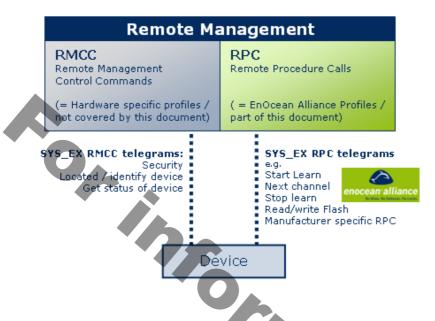
The VLD telegram of the client is forwarded by the repeater 1:1 in the direction of the controller. The feedback is transferred in the form of an addressed telegram (containing Repeater ID) to the postmaster of the repeater and stored in the mailbox.

The client then turns to the repeater with its 'Data Reclaim', instead of turning to the controller, and requests the response message from the postmaster.

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3.9) Remote Management / RPC

Remote Management allows EnOcean devices to be configured and maintained over the air or via a serial interface. For instance sensor or switch IDs can be stored or deleted from already installed actuators or gateways that are hard to access. There is a remote management library available for Dolphin based products.



Remote management is divided into two function groups:

RMCCs are mandatory features; they are permanently defined and they have overlapping tasks. They cannot be modified devicespecifically and are therefore, not an integral part of this description.

RPCs cover optional and manufacturer-specific features, and they have a flexible number of functionalities that can be used for numerous devices. If new device properties are mapped, RPCs can be extended correspondingly. To keep the RPCs interoperable, it is in the interest of the EnOcean Alliance to standardize these procedures.

The RPCs available today with their SYS_EX structures do not have any data-technical commonalities with EEP, but are to be handled the same way in future within the framework of coordination measures.

Structure of SYS_EX for RPC

SYS_EX telegrams for RPCs are generally encapsulated in an ADT telegram (RORG = A6) and are sent addressed as such.



RORG	RORG-EN	SYS-EX data		Destina	tion ID			Send	er ID		Status	CRC8
A6	C5	x bytes	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

In the following section the SYS_EX data is described in detail. Note that Remote Management RPC commands are composed of several telegrams. That means SYS_EX data is than merged in one data block. The next section describes this datablock in detail.

For further details refer to the specification Remote Management, V1.7, Dec 16, 2010, released by EnOcean GmbH www.enocean.com/fileadmin/redaktion/pdf/tec_docs/RemoteManagement.pdf , please.

Title	RPC - Remote learn
Function code	0x201
Manufacturerid	0x7FF
Datalength	0x04

Broadcast	YES
Addressable	YES
Answer	NO

Offset	Size	Data	Description	Valid	Range	Scale	Unit
0	24	EEP (ORG-FUNC-TYPE)	Determines the device type to learn in, all other devices learn telegrams are ignored. To ignore EEP controll the mask bits has to be set to 0)				
24	8	Flag	procedure	Enum: 0×00: 0×01:	RESER\	earn	
					Next ch		
				0x04:		ACK - Sta learn mo	
	Y			0x05:		ACK - Sta ed learn	rt
				0x06:		ACK - Sto	p

<u> </u>	
Title	RPC - Remote flash write
Function code	0x203
Manufacturerid	0x7FF
Datalength	0x04 + N
Broadcast	YES
Addressable	YES
Answer	NO

1	itle	RPC - Remote fla	sh write		
Funct	ion c	ode 0x203			
Manuf	actui	rerid 0x7FF			
Data	leng	th 0x04 + N			
Bro	adca	st YES			
Addr	essa	ble YES			
An	swei	NO			
Using tl	nis co	mmand the flash of a d	levice can be written.		
Offset	Size	Data	Description		
0	16	Flash Memory Address	Destination where the data should be stored		
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash		
32	N*8	Data	data to be transfered and written to the flash		

Title	RPC - Remote flash read
Function code	0x204
Manufacturerid	0x7FF
Datalength	0x04
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the flash can be read from the application. The data requested data area transmitted in RPC telegrams.

Offset Size		Data	Description		
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash		

Title	RPC - Remote flash read answer		
Function code	0x804		
Manufacturerid	0x7FF		
Datalength	N		
Broadcast	NO		

Addressable	YES	
Answer	NO	

Offset			
0	N*8	Data	data read from flash

Title	RPC - SmartACK read settings
Function code	0x205
Manufacturerid	0x7FF
Datalength	1
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the SmartACK settings and learn tables can be read from the device. The Setting type filled determines what type of data is requested. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description		Valid Range	Scale	Unit
0	8	>Setting	type of settings to	Enum:			
		type	read		RESERVED		
				0x00:			
		4			Mailbox settings		
				0x01:			
			70		Learned sensor - read the ID	table of sensors i	n the
				0x02:	Controller		

Title	RPC - SmartACK read settings - I	Mailbox settings answer
Function code	0x805	
Manufacturerid	0x7FF	
Datalength	4	
Broadcast	NO	
Addressable	YES	
Answer	NO	

Offset	Size	Data	Description
0	16	SmartACK flash address	Address where the SmartACK settings are stored
16	16	SmartACK mailbox count	number of mailboxes stored in flash

Title	DDC CoordACK and antique Language
Title	RPC - SmartACK read settings - Learned sensor answer
Function code	0x806
Manufacturerid	0x7FF
Datalength	N*9
Broadcast	NO
Addressable	YES
Answer	NO

 $\ensuremath{\mathsf{N}}$ - is the number of entries: SensorID, ControllerID, LearnCount

Offset	Size	Data
N*0	32	SensorID
N*32	32	ControllerID
N*64	8	Learned Count

Title	RPC - SmartACK write settings

Function code	0x206
Manufacturerid	0x7FF
Datalength	10
Broadcast	NO
Addressable	YES
Answer	YES

Using this command different type of data can be transmitted to the SmartACK devices. This command is useful when the SmartACK device has to be configured remotely. The structure of the data transmitted is depends on the Operation Type field.

Operation Type = 0x01: Add mailbox (only controller)

Offset	Size	Data	Value	Description
0	8	Operatian Type	0x01	Add mailbox (only controller)
8	8	Mailbox Index		
16	32	SensorID		
48	32	PostmasterID		

Operation Type = 0x02: Delete mailbox

Offset	Size	Data	Value	Desci	ription
0	8	Operation Type	0x02	Delete	mailbox
8	8	Mailbox Index			
16	64	Not Used (= 0)			

Operation Type = 0x03: LearnIn - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x03	LearnIn - only controller
8	8	Learn Count		
16	32	SensorID		
48	32	ControllerID		

Operation Type = 0x04: LearnOut - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x04	LearnOut - only controller
8	8	Learn Count		
16	32	SensorID		
48	32	ControllerID		

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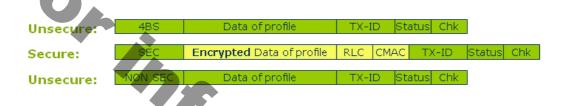
3.10) Interoperability with Security of EnOcean Networks

The Specification "Security of EnOcean Networks" defines two new telegram types for secure EnOcean telegrams in operational mode:

- R-ORG = 0x30 = SEC <u>Secure telegram</u>
- R-ORG = 0x31 = SEC_ENCAPS Secure telegram with R-ORG encapsulation

To make sure that interoperability is warranted, both telegrams may used for telegram transmission with existing EEP's. Because the profile of the device is known, the data of the SEC or SEC_ENCAPS telegram contains the same information as described in the profile, but it may be encrypted defined by the SLF (Security level format) of the device. When the device uses more than one R-ORG's in operational mode, the SEC_ENCAPS telegram has to be applied to ensure the correct original R-ORG after converting from secure to unsecure telegram. At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

Example for converting a telegram from unsecure to secure and back:



The data of the known profile will be applied in the unsecure telegram after the conversion from secure to unsecure telegram.

Example for converting a telegram from unsecure to secure and back with encapsulated R-ORG:



After conversion from secure to unsecure telegram, the encapsulated R-ORG will be applied in the telegram. The data of the profile of the encapsulated R-ORG will be applied.

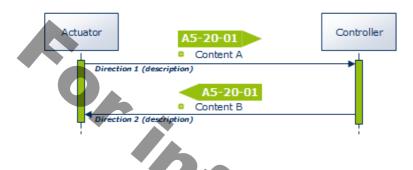
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3.11) Existing 'bidirectional' profile structures

At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

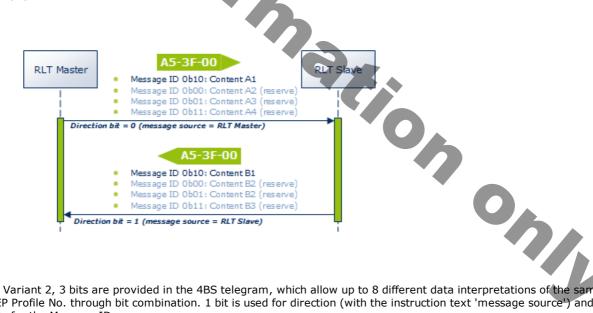
The original terminology 'transmit mode / receive mode' was not taken over, as no unique assignment to device type and hence to transmission direction can be derived there from. A neutral number (Direction 1 / 2) or the state of a bit should allow the required free space to the individual application.

Variant 1:



In Variant 1, there is no data-technical differentiation option in the 4BS telegram between Direction 1 and Direction 2, but only a documentation-related direction specification. No transmission direction can be detected if the telegrams are monitored on the radio stretch.

Variant 2:



In Variant 2, 3 bits are provided in the 4BS telegram, which allow up to 8 different data interpretations of the same EEP Profile No. through bit combination. 1 bit is used for direction (with the instruction text 'message source') and 2 bits for the Message ID.

Variant 3:



In Variant 3, the Smart Ack technology normally offers multiple use options of bidirectional data transmission. Smart Ack clients can therefore be energy self-sufficient devices. The used VLD telegrams allow a payload of up to 14 bytes (12.5 bytes with Manufacturer ID). Contents can thus be structured more individually.



3.12) MSC telegram - Manufacturer Specific Communication

Communication over MSC telegrams can always be used when bigger data volumes are to be transmitted, and at the same time, a closed system structure is to be created. This can be the case if e.g., the controller system backbone is expanded to include radio components, or if safety-related controls require proprietary data structures.

Such communication must not affect any interoperable EEP-based communication and should be identifiable as MSC by any Dolphin-based hardware.

Interoperability Conditions:

A device using MSC in addition to other EEPs may be marked with the EnOcean ingredient logo, as long as it complies with the rules defined by the EnOcean alliance for such markings. A device using MSC may be marked with the EnOcean ingredient logo even though the manufacturer does not disclose any or all information regarding the MSC payload. However, all other functionality of such a device shall comply with the latest EEP specification and such a device shall support at least one additional EEP. The manufacturer must clearly state which EEP(s) the device complies with. To safeguard interoperability, if there is sufficient justified doubt within the EnOcean Alliance TWG, a specific unit using MSC can be assessed by the TWG and if found to breach the interoperability intentions, the TWG may then decide (majority vote) to adapt the rules for the usage of the interoperability logo.

The MSC telegram has the same structure as a VLD telegram. The only difference is that the RORG Number is different and the payload specification is missing.

MSC		A								
RORG	Manufacturer ID	7		Variable data		Send	er ID		Status	CRC8
D1	1,5 byte		\nearrow	1 12,5 bytes	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte
		_								

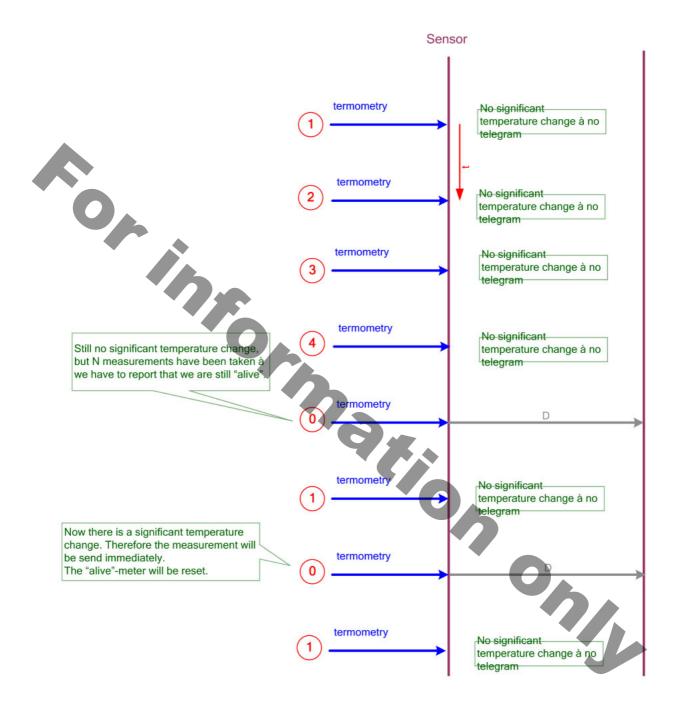
The following points are to be noted:

- 1. The usage of the Multi User Manufacturer ID (0x7FF) shall not be allowed.
- shall no. anufacture. 2. Each user may send MSC telegrams under his own Manufacturer ID. The Manufacturer ID should not be left out.

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3.13) Use Cases for profile 2D-00-01 (self powered RCP for 2way operation)

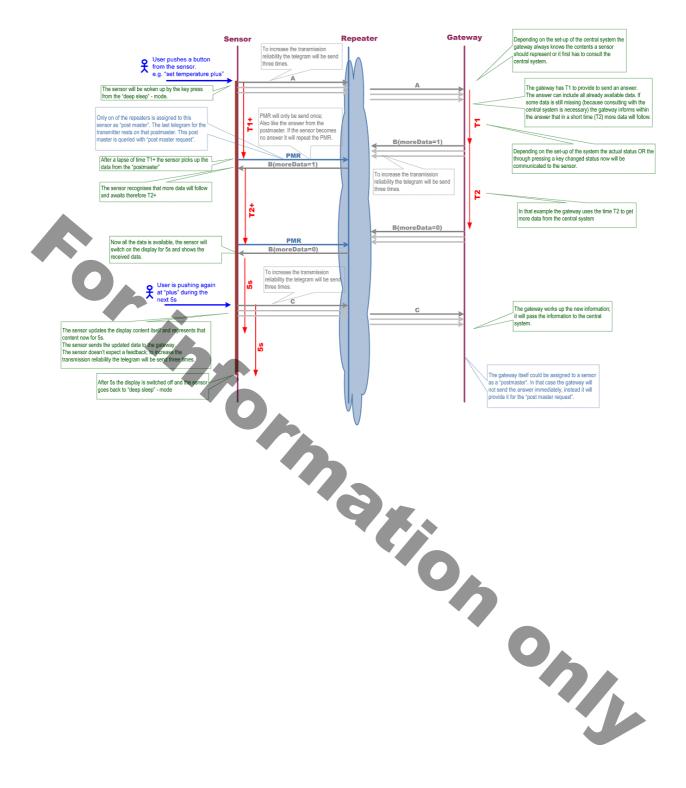
Use Case: Temperature Measurement



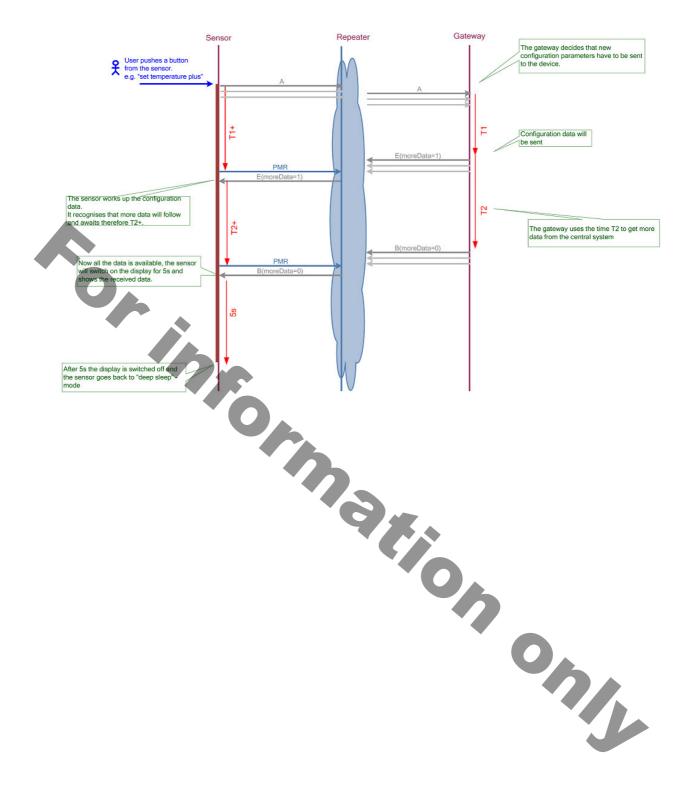
REMARK:

Temperature measurement may be configured by the Gateway, see chapter "Message Type E - RCP Configuration".

Use Case: User Interaction



Use Case: User Interaction including transfer of configuration data



3.14) Manufacturer ID's

This chapter was transferred into a separate document entitled **EnOcean Manufacturer Identification (ManID)**. This document will be updated as soon as a new ManID will be allocated to a member of the EnOcean Alliance. The document **EnOcean Manufacturer Identification (ManID)** is stored in the webspace of the TWG on http://portal.enocean-alliance.org/MyWorkGroups/Documents.aspx (access only for registered members of the TWG).

3.15) XML + DOC Maintenance process

3.15.1) General

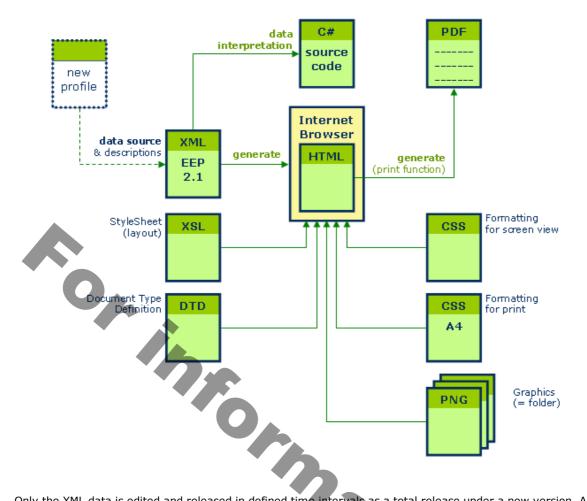
The maintenance process is descripted separately in the document: EEP2x_Maintenance_Process.pdf.

3.15.2) XML file

With EEP 2.1, a new type of documentation is introduced, which can also display logical structures next to the described contents. These can be adapted by developers into their programming environment.

XML is fully compatible with applications like C# or JAVA, and it can be combined with any application which is capable of processing XML irrespective of the platform it is being used on. If the application can work alongside XML, then XML can work on any platform and has no boundaries. It is also vendor independent and system independent.

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Only the XML data is edited and released in defined time intervals as a total release under a new version. A styles sheet file (XSL) and formatting specifications (CSS) ensure that an attractive HTML representation is possible in an internet browser. The author of the new version also creates a final PDF file.

This method ensures that the document view, as well as the software environment, remain synchronized. Errors are strongly reduced and data maintenance is optimized.

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3.16) Revision

Rev.	Date	Editor	Major Changes
0.10	Dute	GT	Initial EnOcean Alliance Version created, based on the EnOcean GmbH document
5.10		31	"Standardization EnOcean Communication Profiles v1.04"
0.90		TR	EEP for ORG = 0x05 added
			EEP for $ORG = 0x06$ added
			Headlines and Text formatted
0.91		TR	FUNC = 11 "Controller Status" added
			Proposals added:
			EEP 07-11-01 "Lightning Controller" (EchoFlex) EEP 07-02-0C "Temp.Sensor, Window Contact" (EchoFlex)
			EEP 07-10-0A "Temp. Sensor, Set-Point Adj., Window Contact" (EchoFlex)
			EEP 07-30-02 "Window Contact, Single Input" (EchoFlex)
0.92		TR	Manufacturer ID: Guidelines added. Definitions updated
			Revision History moved to a separate document chapter
			INPUT document for Berlin Meeting April 2009
2.0R		TR	EEP 07-02-0C shifted to Room Operating Panels -> EEP 07-10-0B
			EEP 06-00-00 renamed to 06-00-01 EEP 05-xx-xx (PRS telegram / PTM200) updated with results of latest discussions
			EEP 05-04-01 (Key Card Activated Switch) updated
			Proposals Added:
			EEP 07-10-0C "Temp. Sensor, Occupancy Control" (Termokon)
			EEP 07-10-0D "Temp. Sensor, Day/Night Control" (Termokon)
2.0	July		Ratification info and period added Creation of final Version V2.0
	July 2009		EEP 05-03-02 added
			EEP 05-04-01 corrected
			EEP 06-00-01 renamed Single Input Contact
			EEP 07-10-0A and EEP 07-10-0B updated Single Input Contact
			EEP 07-30-01 and EEP 07-30-02 updated Single Input Contact 4BS teach in Telegram updated FUNC /TYPE
			Editorial corrections
2.1	Nov.	Ор	The EEP 2.0 document as well as all 2.1 single documents were transferred to an XML data
	12,	O P	structure and standardized. The following chapters were re-written: Introduction, Teach-in,
	2010		Bi-directional profiles, Smart Ack, RPC and MSC. Profiles that are still being coordinated were
			also accepted. These are characterized as 'Not approved' in the document. Bidirectional profiles
			are labeled with 'BI-DIR'. RPS ORG 05 = RORG F6; 1BS ORG 06 = RORG D5; 4BS ORG 07 = RORG A5
2.1	Dec.	Ор	2th review
	31,	"	
	2010		
	Jan.	Ор	Creation of final Version V2.1
	20, 2011		Y A
2.5		Ор	Review version 1
	20,	ОР	Added profiles:
	2012		- 1 RPS: F6-02-03
			- 16 4BS: A5-07-02, A5-09-02, A5-09-05, A5-09-06, A5-09-07, A5-10-1F, A5-11-03, A5-11-04,
			A5-14-01, A5-14-02, A5-14-03, A5-14-04, A5-14-05, A5-14-06, A5-38-08 CMD 0x07, A5-38-09
			- 15 VLD: D2-01-0011, D2-01-0002 Updated profiles: A5-07-01, A5-09-01, A5-09-04
			Further:
			- Description: UTE – Universal Uni- and Bidirectional Teach-in
			- RPC function no. added
2.5	Nex	0=	- Manufacturer ID's added
	Nov. 08,	Ор	Review version 2 Significant changes:
112	2012		- Chapter 1.3
			- Add new profiles: A5-06-03, A5-07-03, A5-13-07
			- Update of profiles: A5-10-15, A5-10-16, A5-10-17, A5-13-01, A5-13-05
	Feb.	Ор	Significant changes:
	03,		- Add new profiles: D2-03-00, D2-20-00, D2-20-01, D2-20-02
	2013		- Update of profiles: A5-07-02, A5-13-02, D2-01-00 - Deleted Chapter 'Manufacturer ID's'
2.5	March	Ор	Creation of final Version V2.5
	04,	Ob	- Add chapter 3.14 "Manufacturer ID's" with a cross reference only
	2013		- Add chapter 3.10 "Interoperability with Security"
			- Update profiles: A5-13-02 (name), A5-20-01 (first phrase), A5-38-08 / 0x02 Dimming (remark
			/ ramp time), A5-38-09 (remark 7 / ramp time)